Track Parameter Resolution

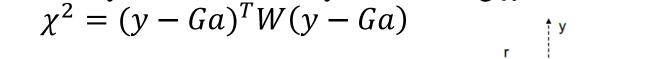
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General formulas

Track function:

$$f(x) = \sum_{i=0}^{M} a_i g_i(x)$$

 a_i are unknown parameters. They are estimated by minimizing χ^2 defined as:



In which:

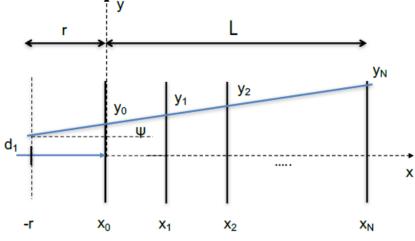
y: measured values.

G: $g_m(x_n)$ W: weight matrix To minimize χ^2 , we have

$$a = (G^T W G)^{-1} G^T W y$$

Now we have relation between a and y. What we want is the relation between covariance matrices C_a and C_y . After some calculation and applying the generalized Gauss-Markov theorem, we have

$$C_a = (G^T C_y^{-1} G)^{-1}$$



Covariance matrix C_y

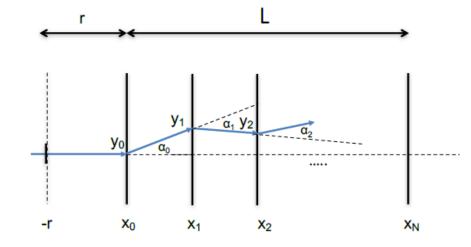
In general, C_y has the form

$$(C_y)_{mn} = \sigma_n^2 \delta_{mn} + \sum_{j=0}^{Min[m,n]-1} \sigma_{\alpha_j}^2 (x_m - x_j) (x_n - x_j)$$

- First term: intrinsic detector resolution, not correlated
- Second term: multiple scattering, highly correlated and energy dependent

We consider them separately for simplicity, and use R_{mn} to denote the first term and M_{mn} to denote the second term. The total resolution is

$$\sigma_{total} = \sigma_{intrinsic} \oplus \sigma_{ms}$$



Calculating σ_{z0}

For simplicity, let's assume the incident angle of the particle is almost perpendicular to the measurement surface. The fitting function is

$$f(x) = a_0 + a_1 x$$

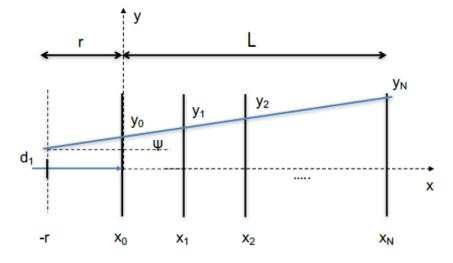
The G matrix is

$$G^{T} = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ x_{0} & x_{1} & x_{2} & x_{3} & \cdots & x_{n} \end{pmatrix}$$

$$C_{a,intrinsic} = (G^T R^{-1} G)^{-1}$$

$$\sigma_{z0,intrinsic} = (\Delta f(0))^2 = g(0)^T C_{a,intrinsic} g(0)^T$$

in which $g(x) = (1 \ x)$. We can do similar calculation for $\sigma_{z0.ms}$.



Calculating σ_{1/p_T}

The circle is approximated by f(x) = a

The G matrix is

$$p_{T}$$
ated by
$$f(x) = a_{0} + a_{1}x + a_{2}x^{2}/2$$

$$\int_{q_{0}}^{r} \int_{x_{1}}^{y_{1}} \int_{x_{2}}^{y_{2}} \odot B$$

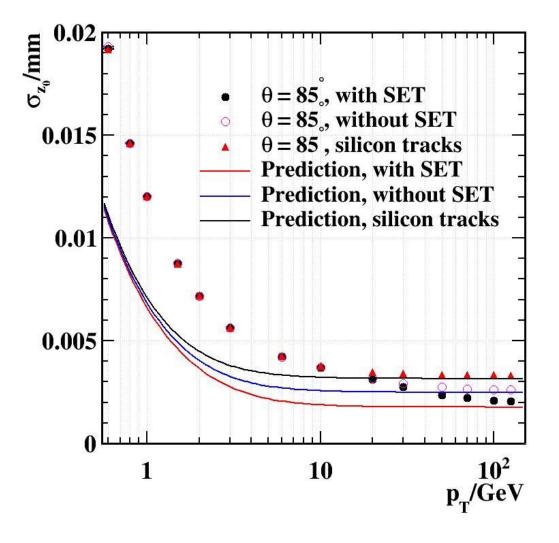
$$\int_{x_{1}}^{y_{N}} \int_{x_{2}}^{y_{N}} \int_{x_{1}}^{y_{N}} \int_{x_{2}}^{y_{N}} \int_{x_{1}}^{y_{2}} \int_{x_{2}}^{y_{N}} \int_{x_{1}}^{y_{N}} \int_{x_{1$$

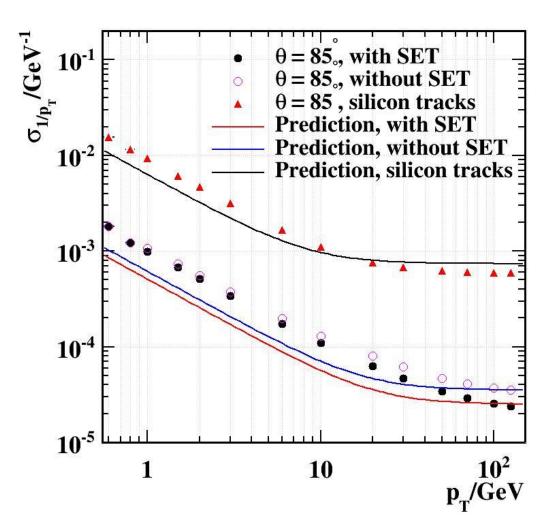
$$C_{a,intrinsic} = (G^T R^{-1} G)^{-1}$$

$$\sigma_{1/p_T,intrinsic} = \frac{\Delta a_2}{0.3B} = \frac{\sqrt{(C_a)_{22}}}{0.3B}$$

We can do similar calculation for $\sigma_{1/p_T,ms}$.

Results





 σ_{1/p_T}

 σ_{z0}