

τ decay mode classification

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Introduction

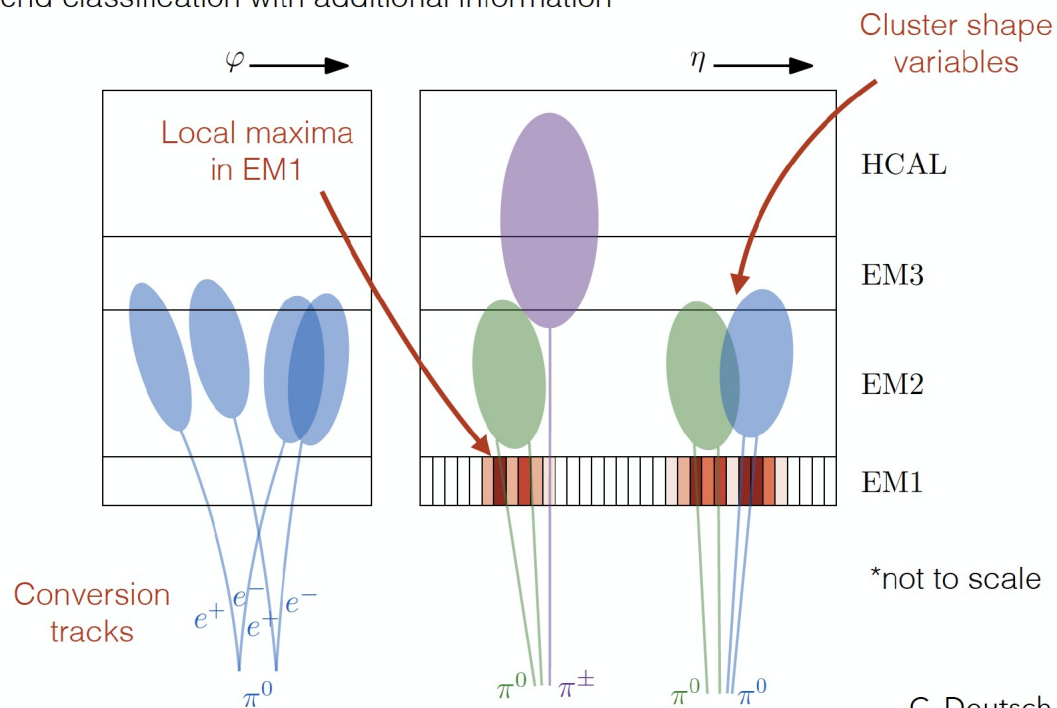
- Improve the five-way τ decay mode classification using machine learning techniques:
- Categorized by the number of charged and neutral products
- Previously use kinematics of the decay products, the identification score of π^0 and the number of photons

Decay mode test	$N(\pi_{\text{cand}}^0)$	$N(\pi_{\text{ID}}^0)$	Variables
$h^\pm \{0, 1\}\pi^0$	≥ 1 1	0 1	$S_1^{\text{BDT}}, f_{\pi^0,1}, \Delta R(h^\pm, \pi^0), D_{h^\pm}, N_\gamma$
$h^\pm \{1, \geq 2\}\pi^0$	≥ 2 ≥ 2	1 ≥ 2	$S_2^{\text{BDT}}, f_{\pi^0}, m_{\pi^0}, N_{\pi^0}, N_\gamma$
$3h^\pm \{0, \geq 1\}\pi^0$	≥ 1 ≥ 1	0 ≥ 1	$S_1^{\text{BDT}}, f_{\pi^0}, \sigma_{E_T, h^\pm}, m_{h^\pm}, N_\gamma$

Introduction

- The algorithm will be upgraded to neural network version in Run3
- RNN study by Christopher : [link](#)
- Use information from:
 - Charged PFO, Neutral PFO, Photon Shots and Conversion Tracks

- Extend classification with additional information



10/02/2020

C. Deutsch

Input variables

- Last presentation repeated the machinery and studied the high level inputs
 - Conclusion: PanTau BDT inputs doesn't improve the results. See
- Continue on study input variables
 - Kinematics of each object
 - Replace $\text{Pi}0$ BDT score by the $\text{Pi}0$ BDT ID inputs

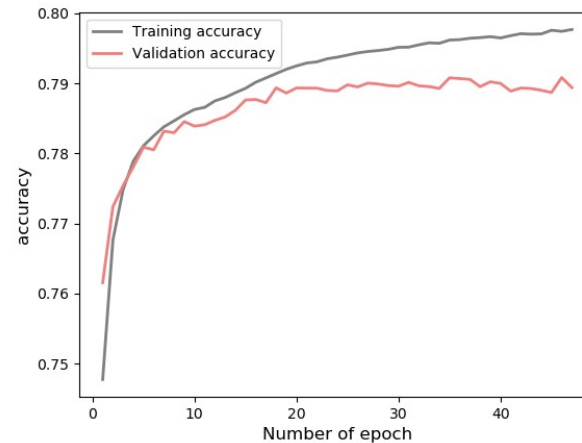
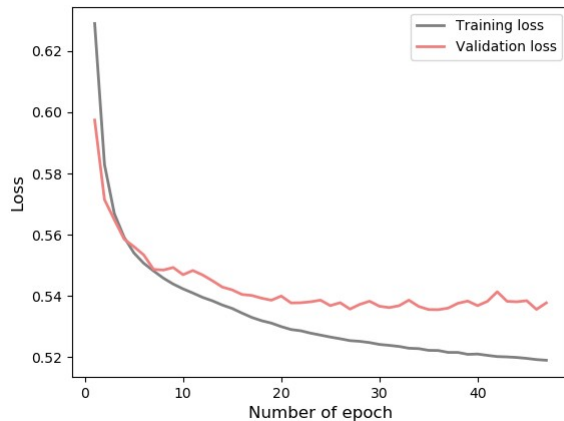
Baseline

- The training sample is mc16d Gammatautau
 - mc16_13TeV:mc16_13TeV.425200.Pythia8EvtGen_A14NNPDF23LO_Gammatautau_MassWeight.merge.AOD.e5468_s3126_r10201_r10210
 - ~12M taus after baseline selection (backup)
- Subset is used: 4M for training (20% of it for validation) 1M for testing

Baseline

- Slightly change the implementation of the model
 - Implemented using PyTorch framework so far.
 - Remove the TimeDistributed+Dense layer before the LSTM – Training becomes much faster on GPUs.
 - Use bidirectional RNN – hope it can learn both the forward and the backward relation
 - Use the RNN output of the full sequence – pass more information to the final dense layers. (need to check if this is really helpful)
 - Use two layers of RNN – proved to be better than just one.

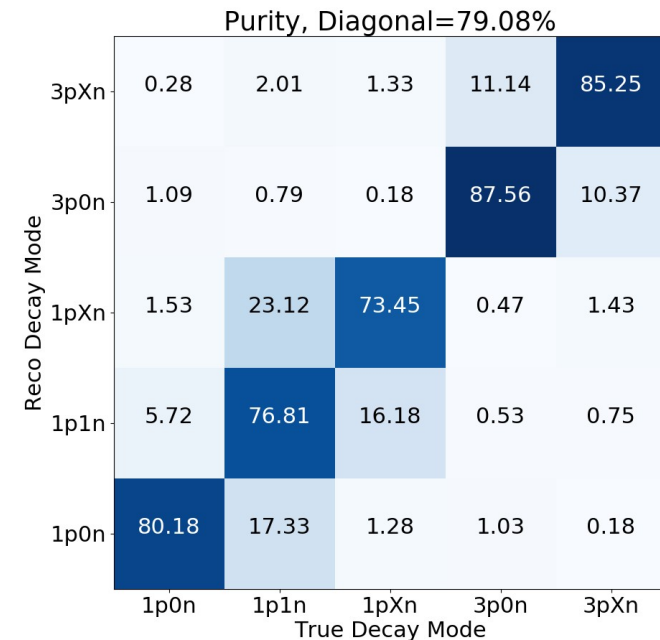
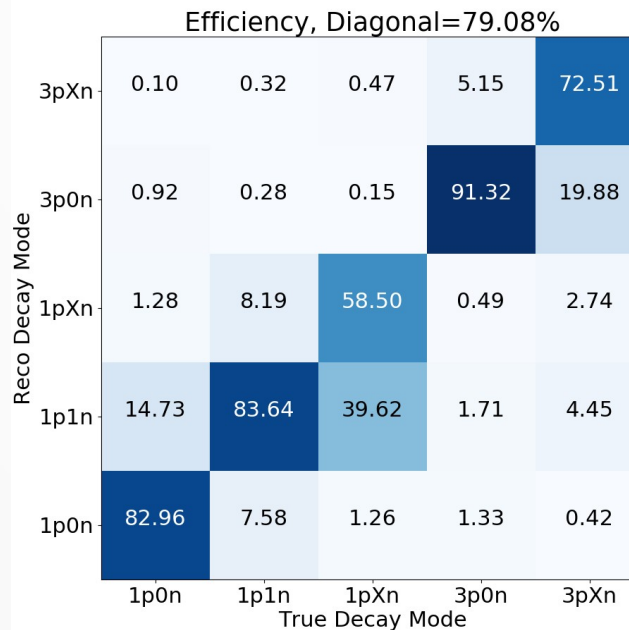
Baseline performance



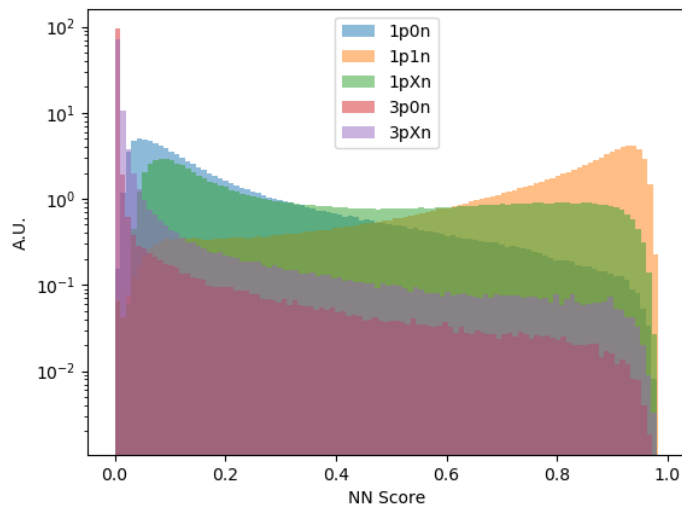
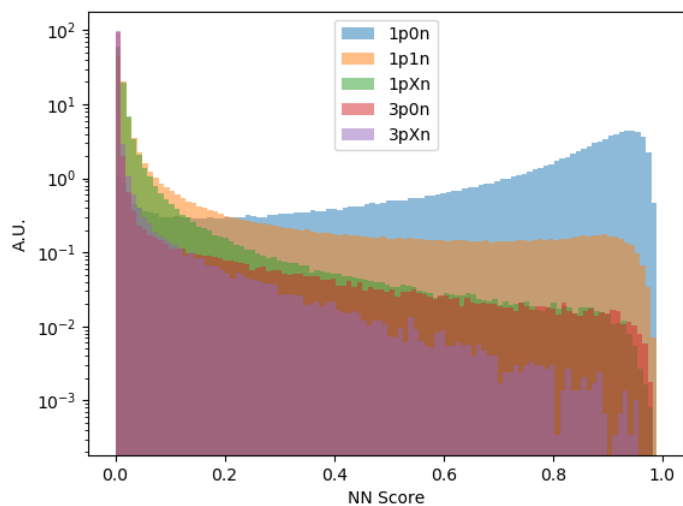
Next step needs to deal with the overtraining

A little bit worse than the previous run (80.4 diagonal). But here the dataset is smaller. And the model is different.

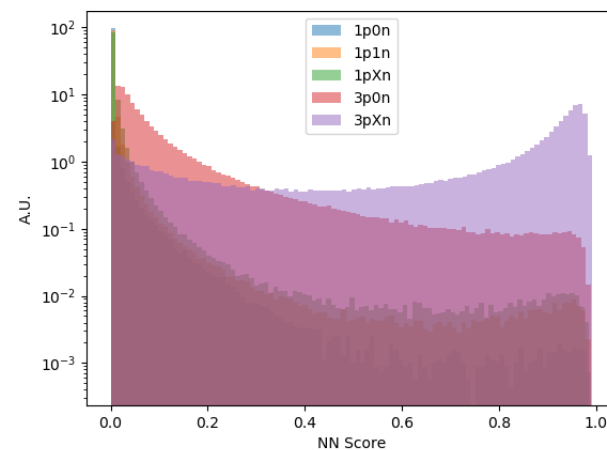
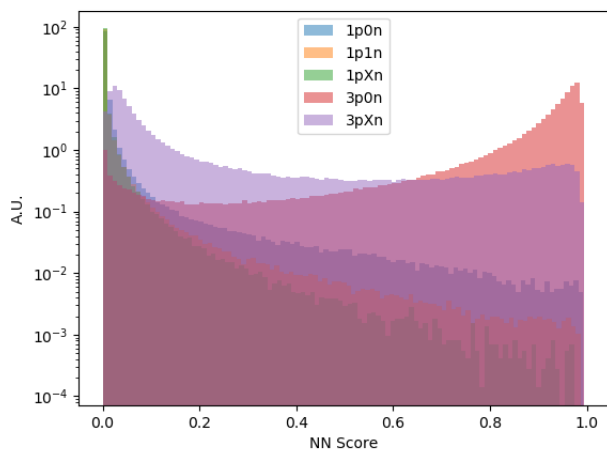
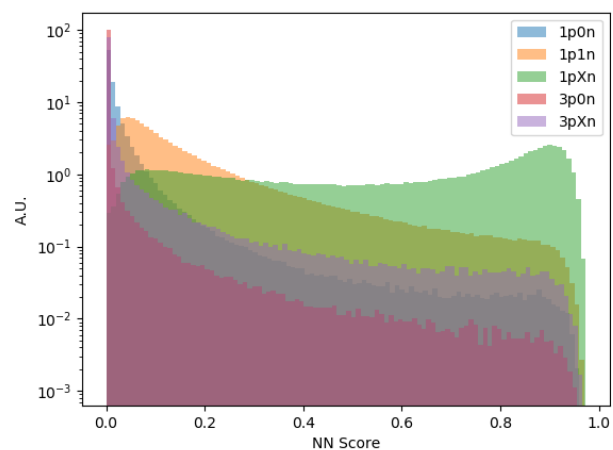
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Baseline performance

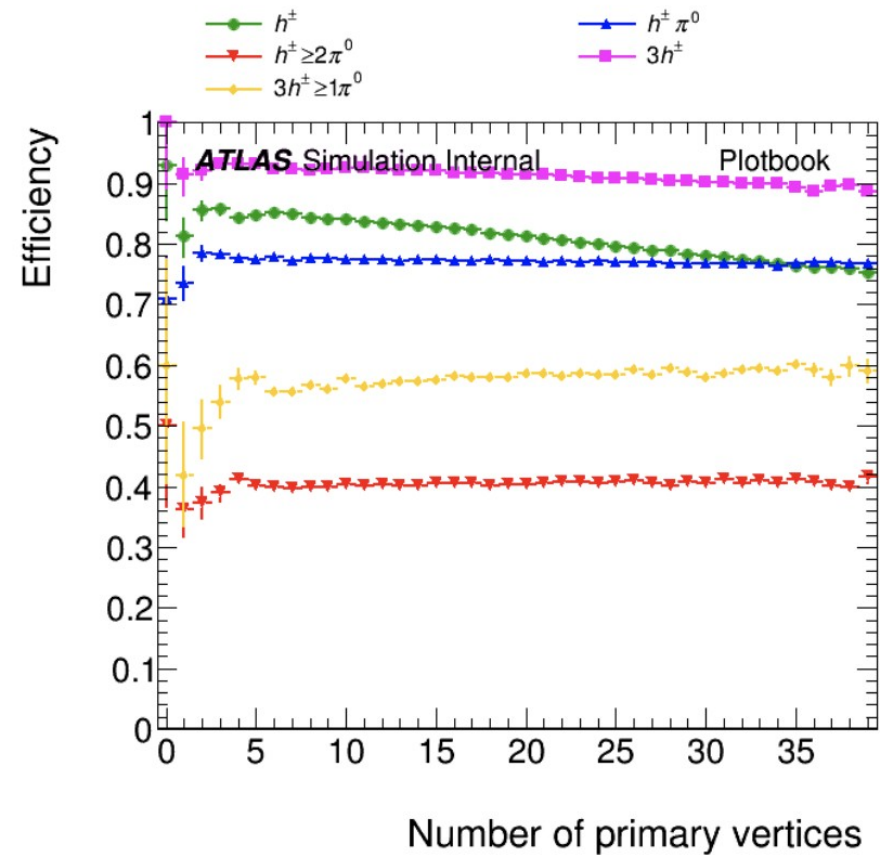
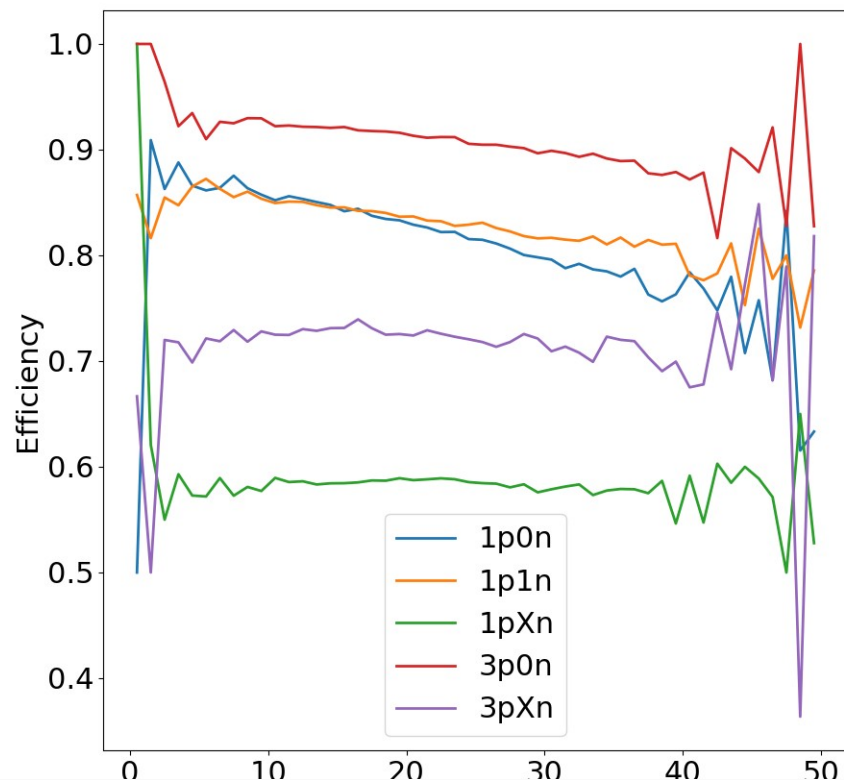


NN output from
left to right:
1p0n 1p1n
1pXn 3p0n 3pXn



Baseline performance

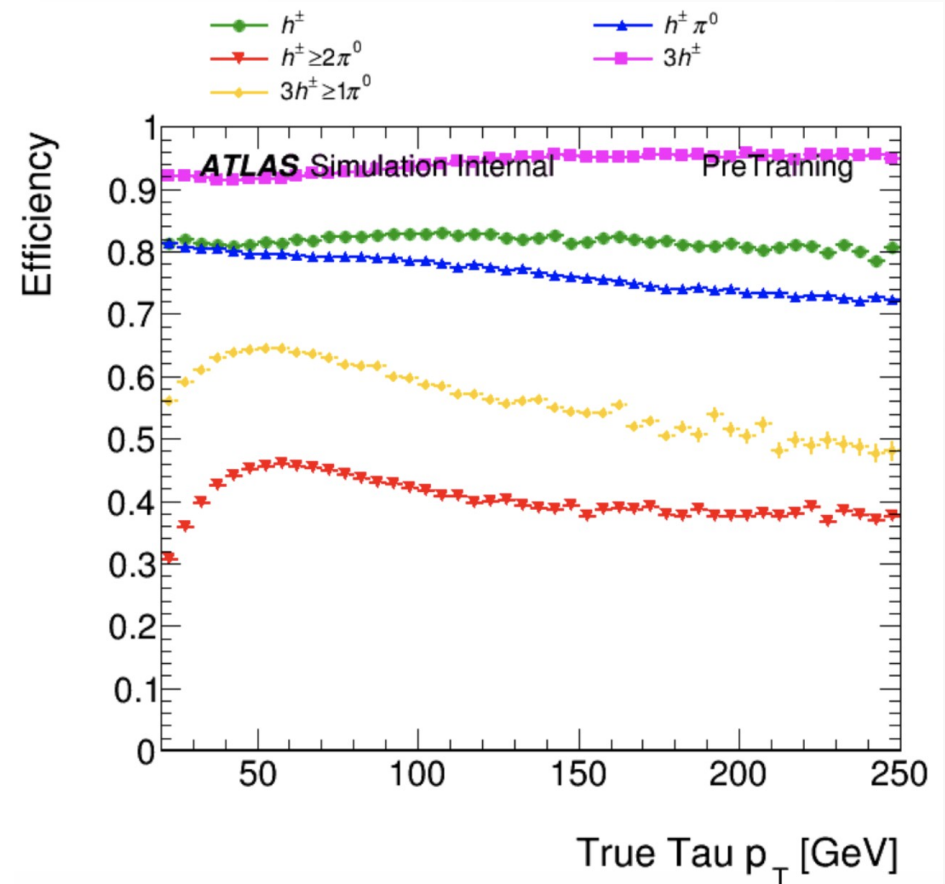
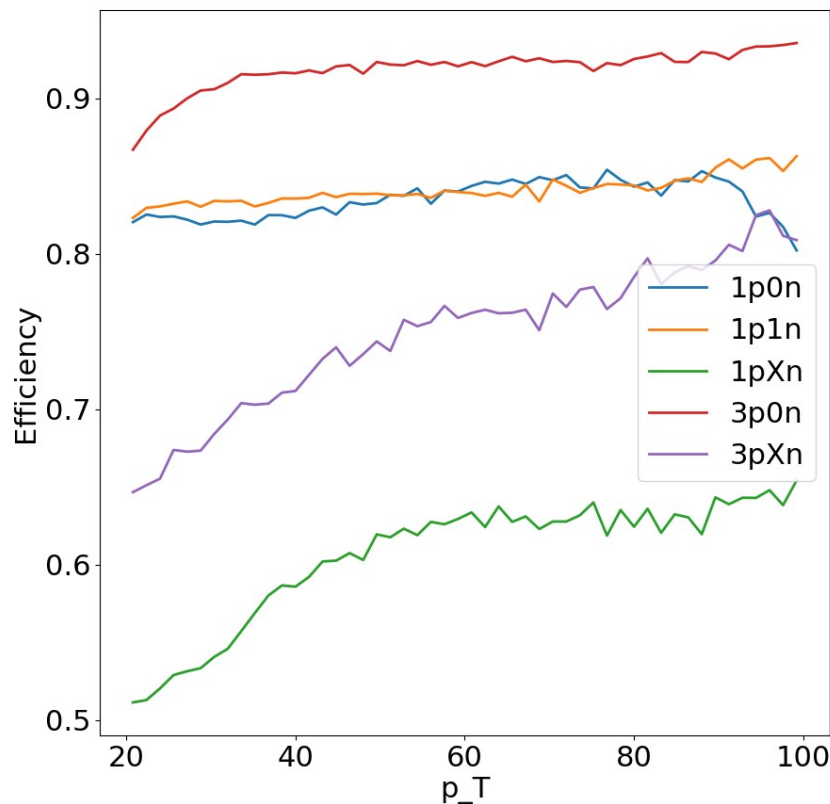
Efficiency dependences on number of primary vertices



- Especially 1p1n drops at high pile up → Left orange,
Right blue

Baseline performance

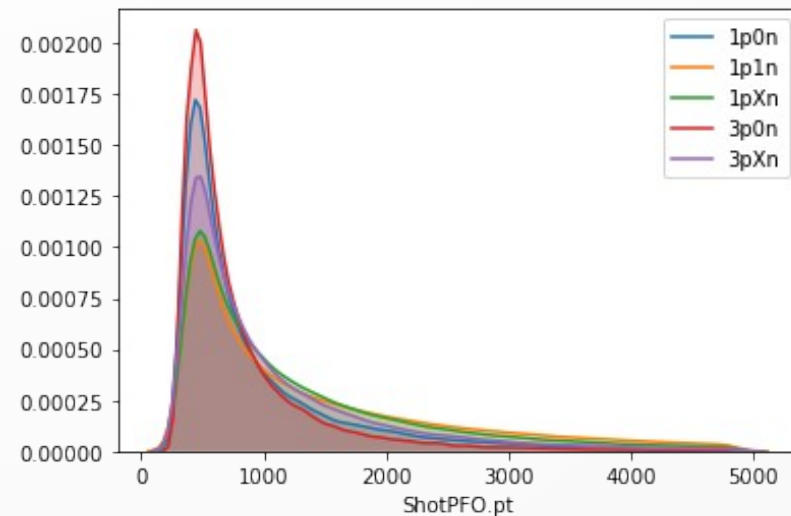
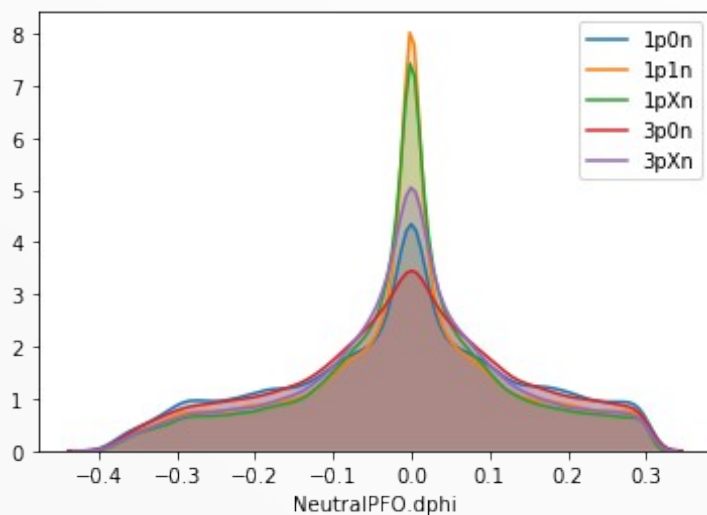
Efficiency dependences on tau pT



- RNN (Left) only trained on tau with $p_T < 100 \text{ GeV}$ and doesn't require medium tau ID.
- Trend is different.

Kinematics (4-vectors)

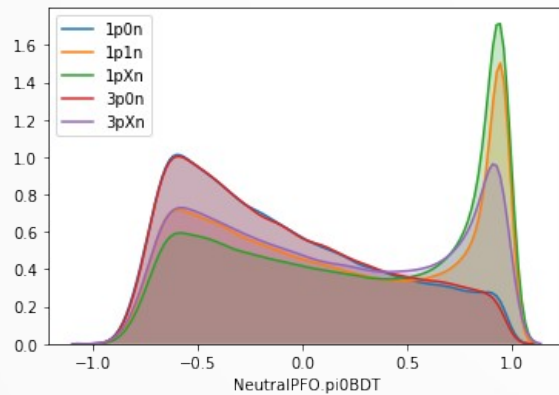
- Only keep pt of the object, pt , eta, phi of tau and the relative eta, phi between the object and the tau axis in the input.
- The length of the sequence, the pt (relative) of the object, and the relative eta, phi are crucial to the classification. e.g.
 - N Charged PFO = 1, 3



- Result shows ~76.9% diagonal efficiency.

Pi0 BDT ID score and the inputs

- Pi0 BDT score is a powerful discriminant:



- The BDT input variables are cluster properties of the pi0 candidates:
- *Path to Pi0 BDT weight file

Cluster pseudorapidity, $|\eta^{\text{clus}}|$

Magnitude of the energy-weighted η position of the cluster

Cluster width, $\langle r^2 \rangle^{\text{clus}}$

Second moment in distance to the shower axis

Cluster η width in EM1, $\langle \eta_{\text{EM1}}^2 \rangle^{\text{clus}}$

Second moment in η in EM1

Cluster η width in EM2, $\langle \eta_{\text{EM2}}^2 \rangle^{\text{clus}}$

Second moment in η in EM2

Cluster depth, $\lambda_{\text{centre}}^{\text{clus}}$

Distance of the shower centre from the calorimeter front face measured along the shower axis

Cluster PS energy fraction, $f_{\text{PS}}^{\text{clus}}$

Fraction of energy in the PS

Cluster core energy fraction, $f_{\text{core}}^{\text{clus}}$

Sum of the highest cell energy in PS, EM1 and EM2 divided by the total energy

Cluster logarithm of energy variance, $\log \langle \rho^2 \rangle^{\text{clus}}$

Logarithm of the second moment in energy density

Cluster EM1 core energy fraction, $f_{\text{core,EM1}}^{\text{clus}}$

Energy in the three innermost EM1 cells divided by the total energy in EM1

Cluster asymmetry with respect to track, $\mathcal{A}_{\text{track}}^{\text{clus}}$

Asymmetry in η - ϕ space of the energy distribution in EM1 with respect to the extrapolated track position

Cluster EM1 cells, $N_{\text{EM1}}^{\text{clus}}$

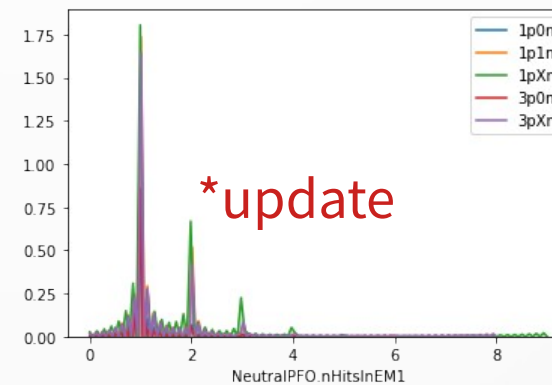
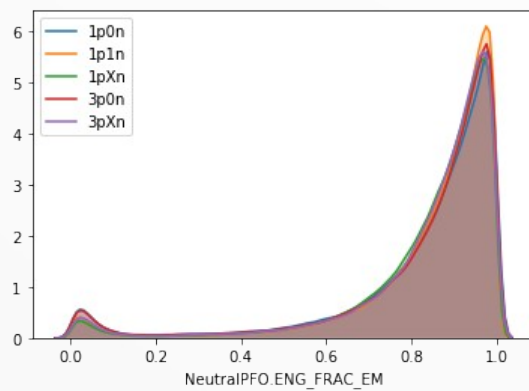
Number of cells in EM1 with positive energy

Cluster EM2 cells, $N_{\text{EM2}}^{\text{clus}}$

Number of cells in EM2 with positive energy

Pi0 BDT ID score and the inputs

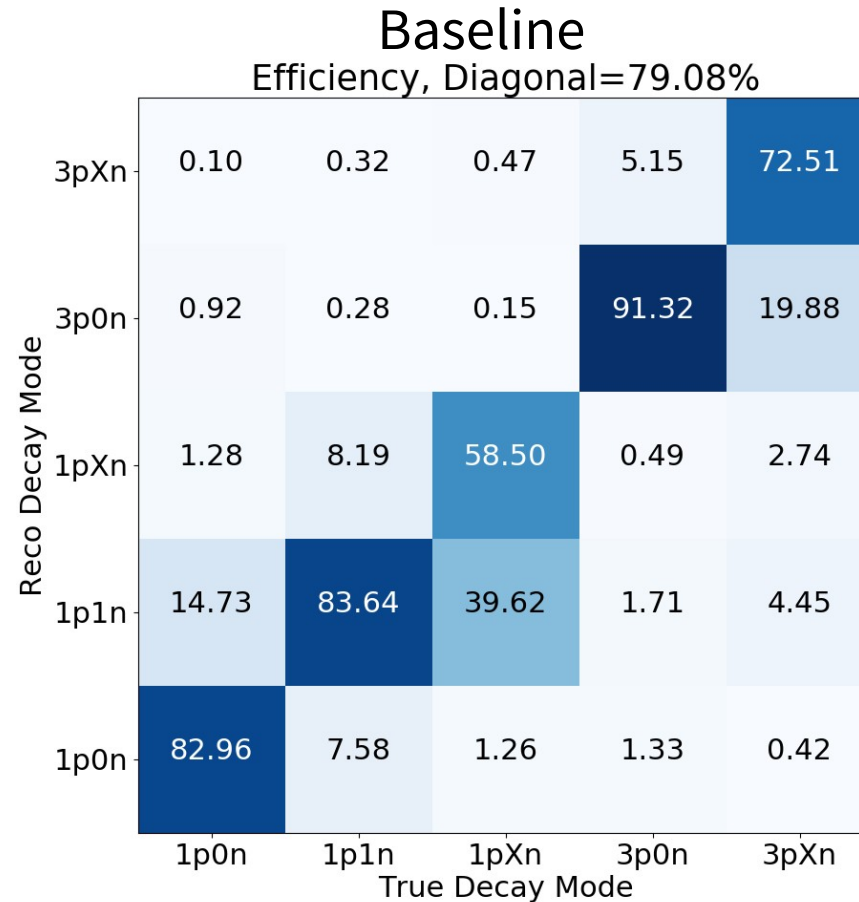
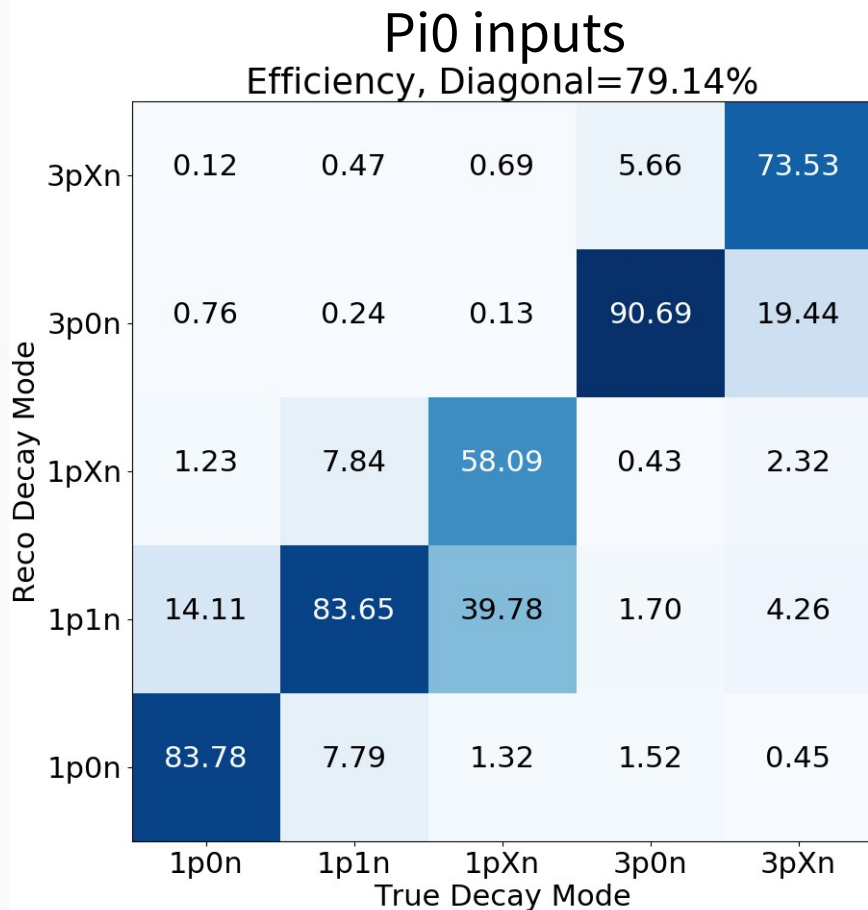
- Replace the pi0 score with the BDT inputs
- Select the important variables of Neutral PFO:
 - Using “Boruta” feature selection techniques (scikit-learn)
 - Compare the performance of the ensemble ML algorithms (like BDT or Random Forest) running on the original dataset and the dataset with one variable shuffled.
 - Details: [paper](#), [python version](#)
- "NeutralPFO.ENG_FRAC_EM" and "NeutralPFO.nHitsInEM1" are rejected



- Remove them in the input.

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Pi0 ID inputs performance vs baseline **check more plots later*



No obvious difference

Current setup

- Training/Testing with ML packages: JupyterLab provided by <https://www.atlas-ml.org/>
- * ...

Summary

- Start to look at the performance of the RNN classifier
- Checked the impact of input variables:
 - 4-vectors are important
 - Can use pi0 ID inputs instead of pi0 BDT score → might avoid re-training of pi0 BDT
- To-do:
 - Finalize the current study
 - Deal with overtraining, improve baseline model, decide tau pt cut, ...
 - Start to implement in C++ and evaluate performance in THOR
 - convert the model to lwttn format(?)

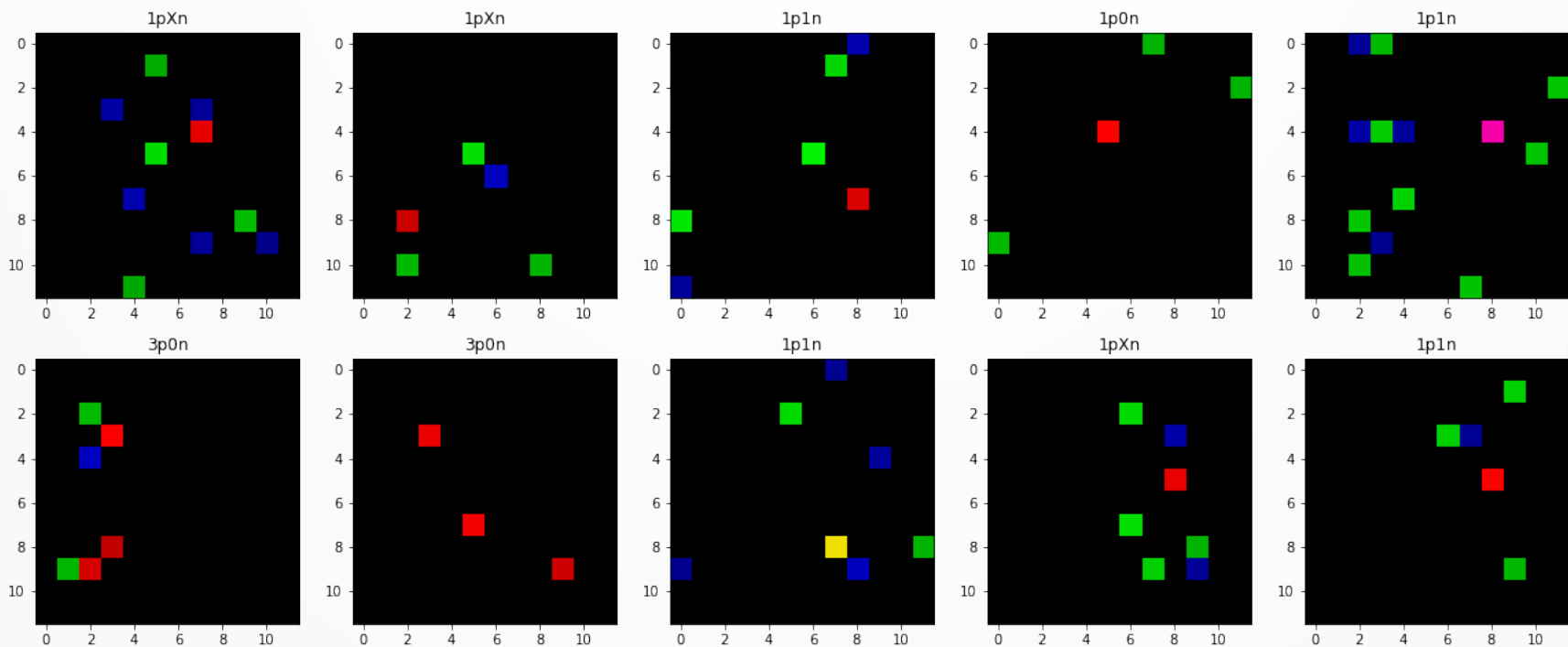
Backup

Selection

```
removed_indices = df[(df["TauJets.truthDecayMode"] > 4) | (df["TauJets.IsTruthMatched"] != 1) |  
    (df["TauJets.pt"] < 20000) | (df["TauJets.truthPtVis"] < 20000) |  
    (df["TauJets.pt"] > 100000) | (df["TauJets.truthPtVis"] > 100000) |  
    (df["TauJets.eta"] > 2.5) | (df["TauJets.truthEtaVis"] > 2.5) |  
    ((df["TauJets.eta"] > 1.37) & (df["TauJets.eta"] < 1.52)) |  
    ((df["TauJets.truthEtaVis"] > 1.37) & (df["TauJets.truthEtaVis"] < 1.52)) |  
    ((df["TauJets.nTracks"] != 1) & (df["TauJets.nTracks"] != 3)) |  
    ((df["TauJets.truthProng"] != 1) & (df["TauJets.truthProng"] != 3))].index
```

Kinematics (4-vectors)

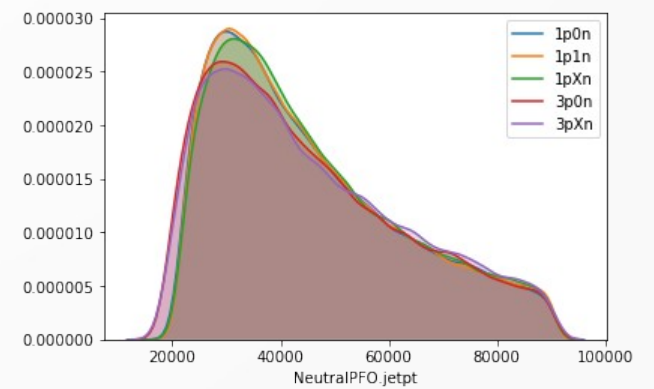
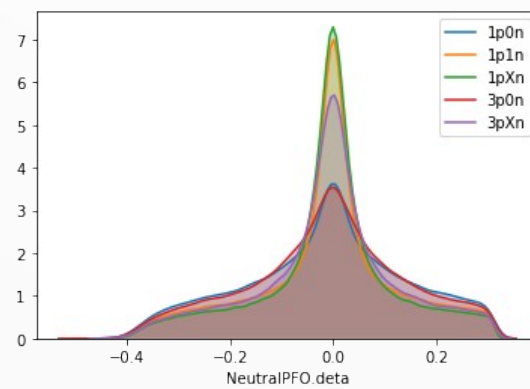
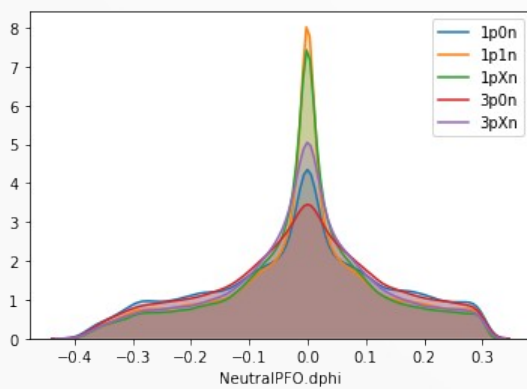
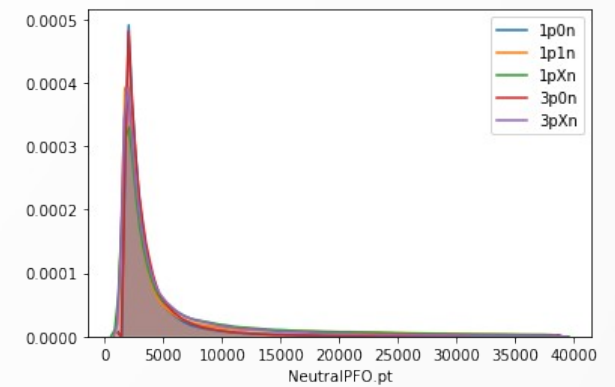
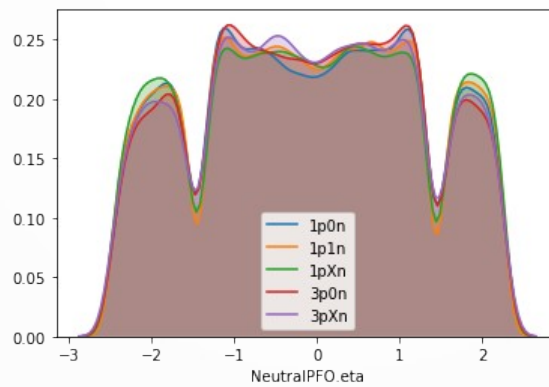
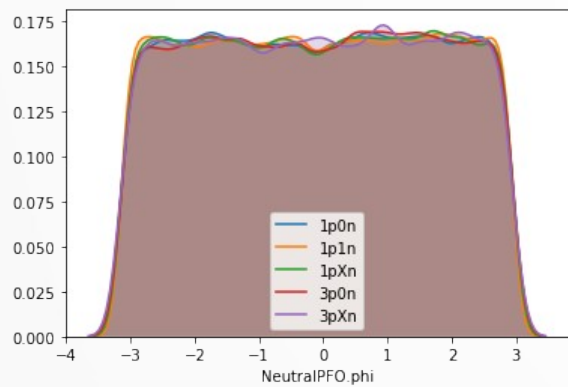
- Or to visualize what the neural network would see (the relative positions in tau axis)



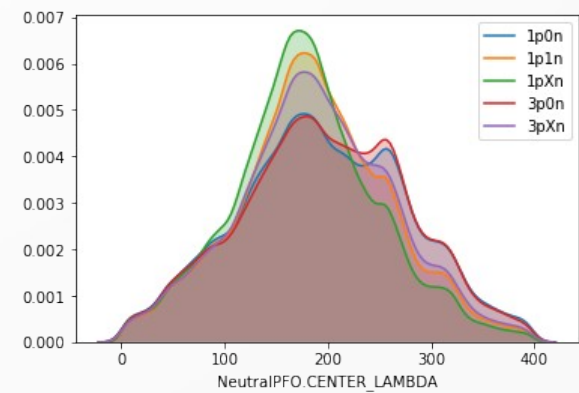
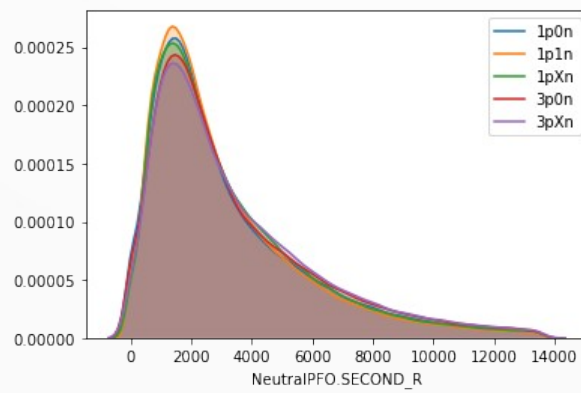
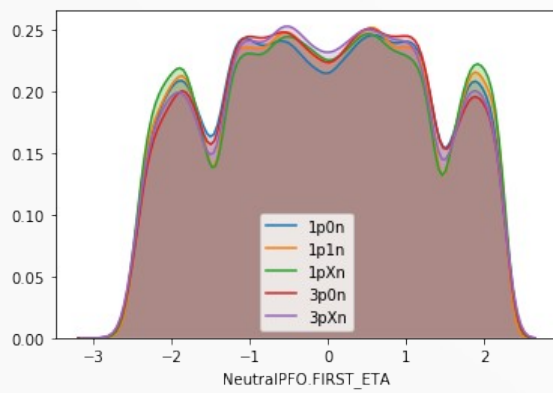
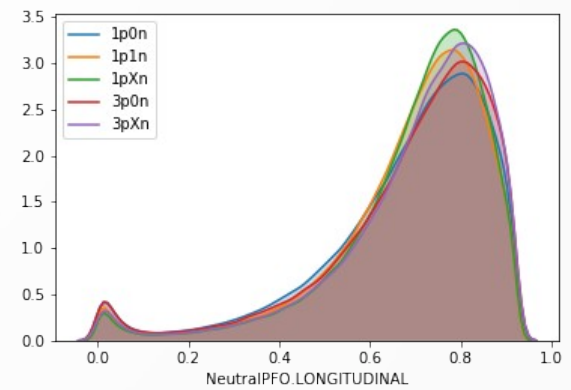
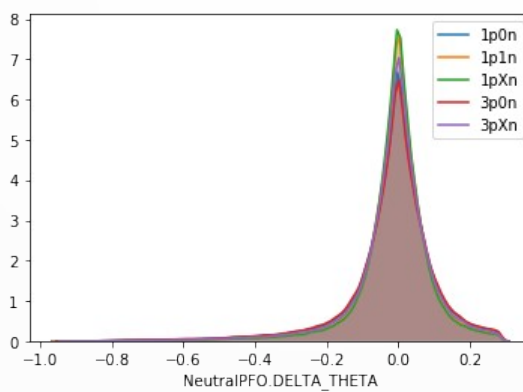
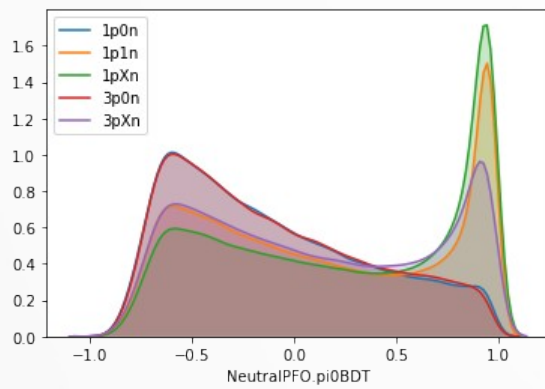
Neutral PFO vars

"NeutralPFO.FIRST_ETA",
"NeutralPFO.SECOND_R",
"NeutralPFO.DELTA_THETA",
"NeutralPFO.CENTER_LAMBDA",
"NeutralPFO.LONGITUDINAL",
"NeutralPFO.SECOND_ENG_DENS",
"NeutralPFO.ENG_FRAC_EM",
"NeutralPFO.ENG_FRAC_CORE",
"NeutralPFO.NPosECells_EM1",
"NeutralPFO.NPosECells_EM2",
"NeutralPFO.nHitsInEM1",
"NeutralPFO.ptSubRatio",
"NeutralPFO.energyfrac_EM2",
"NeutralPFO.EM1CoreFrac",
"NeutralPFO.secondEtaWRTClusterPosition_EM1",
"NeutralPFO.firstEtaWRTClusterPosition_EM1",
"NeutralPFO.secondEtaWRTClusterPosition_EM2",

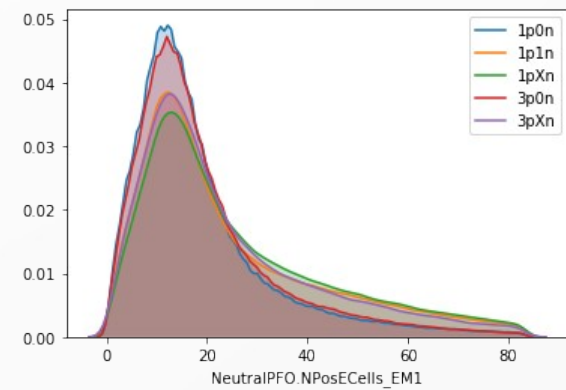
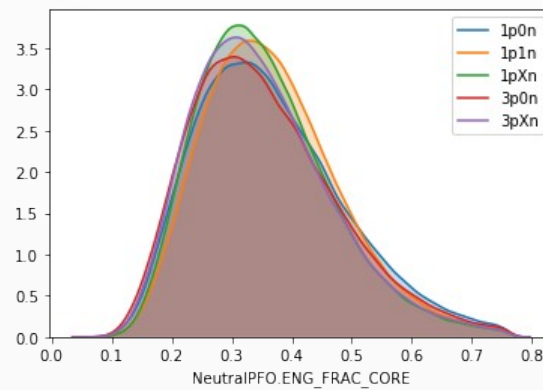
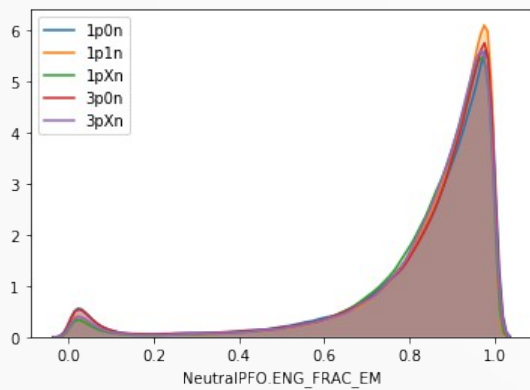
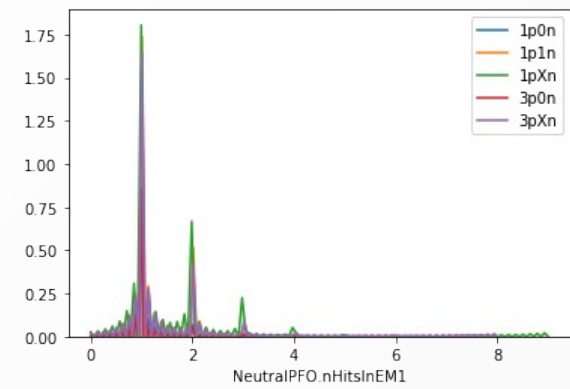
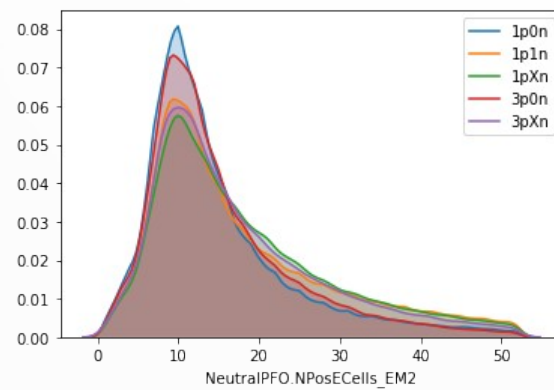
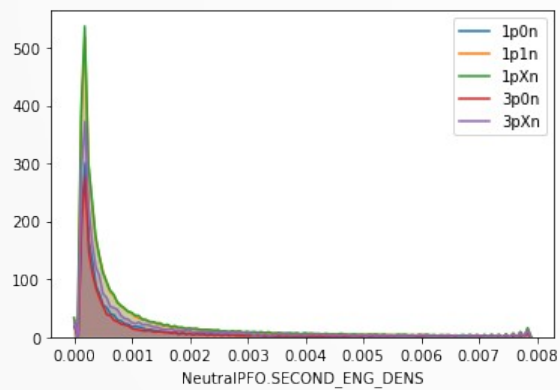
Input vars



Input vars



Input vars



Pi0 ID inputs performance

