

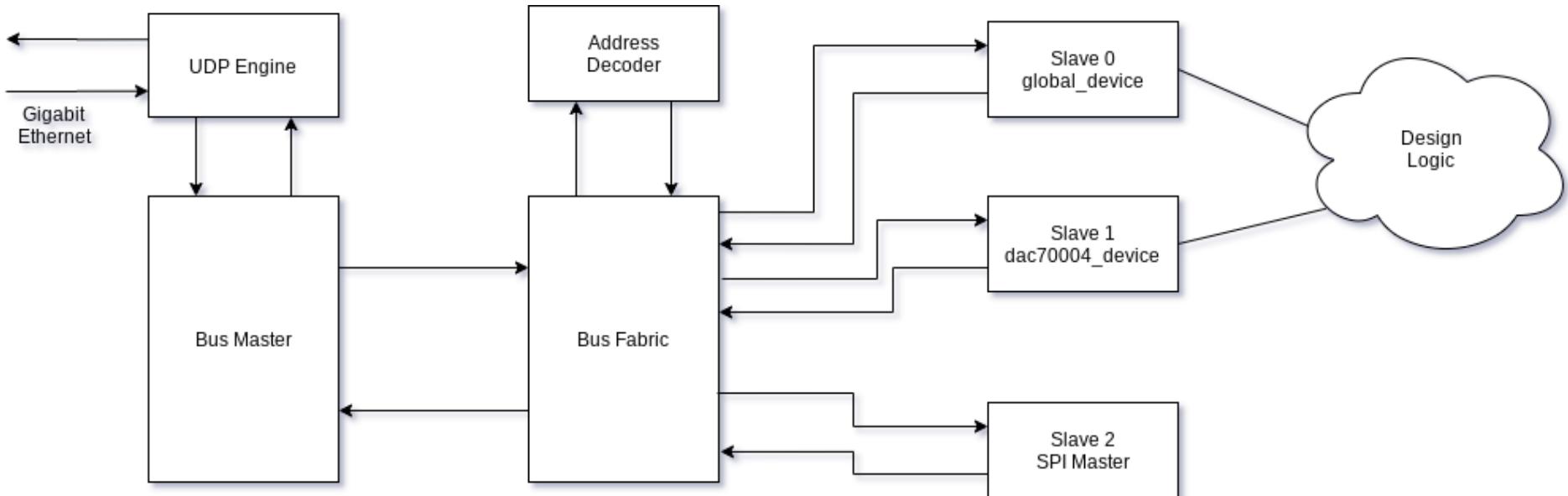
# Firmware Status

7/20/2020  
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# Implement

- Firmware:
  - IPbus Infrastructure(Master/Ethernet/Fabric)
  - IPbus slaves: DAC70004, SPI master, global
- Software:
  - Address tables
  - Python Scripts

# Firmware Structure



# Software

## Address tables:

- Connection/address
- Device

## Python scripts:

- JadePixCtrl.py

## lib

- dac70004\_defs.py
- dac70004\_device.py
- global\_device.py
- spi\_device.py

```
<?xml version="1.0" encoding="ISO-8859-1"?>
<node id="JadePix0 udp.0">
    <node id="global_dev" module="file:///dev/global_dev.xml" address="0x00000000" tags="slave" />
    <node id="dac70004_dev" module="file:///dev/dac70004_dev.xml" address="0x40000000" tags="slave" />
    <node id="spi_dev" module="file:///dev/opencores_spi.xml" address="0x80000000" tags="slave" />
</node>
```

```
1 #!/usr/bin/env python
2
3 #####
4 import time
5 import uhal
6 import logging
7
8 from lib.global_device import GlobalDevice
9 from lib.dac70004_device import Dac70004Device
10 from lib.dac70004_defs import *
11
12 #####
13
14 logging.basicConfig(level=logging.DEBUG, format='%(asctime)s - %(name)s - %(levelname)s - %(message)s')
15 log = logging.getLogger(__name__)
16 log.setLevel(logging.DEBUG)
17
18 __author__ = "Sheng Dong"
19 __email__ = "s.dong@mails.ccnu.edu.cn"
20
21 if __name__ == '__main__':
22     # if len(sys.argv) < 3:
23     #     log.info("Please specify the device IP address and the top-level address table file to use")
24     #     sys.exit(1)
25     device_ip = "192.168.3.16"
26     device_uri = "ipbusudp-2.0:///" + device_ip + ":50001"
27     # address_table_name = sys.argv[2]
28     address_table_name = "../etc/address.xml"
29     address_table_uri = "file://" + address_table_name
30
31     uhal.setLevelTo(uhal.LogLevel.WARNING)
32     hw = uhal.getDevice("HappyDaq.udp.0", device_uri, address_table_uri)
33
34     global_dev = GlobalDevice(hw)
35     dac70004_dev = Dac70004Device(hw)
36
37     ## Soft global reset
38     global_dev.set_soft_rst()
39
40     ## SET DAC70004
41     dac70004_dev.soft_reset()
42     dac70004_dev.soft_clr()
43     dac70004_dev.w_power_chn(DAC70004_PW_UP, 0xf) # Power up all channels
44     dac70004_dev.w_chn_update_chn(DAC70004_CHN_A, dac70004_dev.out_to_din(1.5)) # Set channe A to 1.5V
45     dac70004_dev.w_chn_update_chn(DAC70004_CHN_B, dac70004_dev.out_to_din(2.0)) # Set channe B to 2.0V
```

# Plan

- More control modules and data link implement in firmware
- Run software as server mode

# Code Repository

[https://github.com/habrade/JadePix3\\_Readout](https://github.com/habrade/JadePix3_Readout)

The screenshot shows a GitHub repository page for 'JadePix3\_Readout'. At the top, there are buttons for 'master' (selected), '1 branch', '0 tags', 'Go to file', 'Add file', and 'Code'. Below this is a commit history table:

habrade	Remove files which copied from other project by accident	707a8cc 8 hours ago	4 commits
constrains	Implement IPBus Spi Master and dac70004 slaves, address tables an...	8 hours ago	
etc	Implement IPBus Spi Master and dac70004 slaves, address tables an...	8 hours ago	
ipcores	Implement IPBus Spi Master and dac70004 slaves, address tables an...	8 hours ago	
scripts	Implement IPBus Spi Master and dac70004 slaves, address tables an...	8 hours ago	
src	Remove files which copied from other project by accident	8 hours ago	
JadePixReadout.xpr	Implement IPBus Spi Master and dac70004 slaves, address tables an...	8 hours ago	
LICENSE	add License	8 hours ago	
README.md	add README	8 hours ago	

The screenshot shows the 'README.md' file content:

```
README.md
```

**JadePix3 Readout**

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The readout system is developed and tested on:

- Ubuntu 20.04 LTS
- Xilinx Vivado 2019.2
- Python 3.8.2
- IPbus Software: master branch
- IPbus Firmware: master branch

## To be done:

- Script/Makefile to auto build project
- Release bit/mcs files

# Backup

- Pin issue: DAC70004 can't be connected to KC705 via FMC(HPC400)?

