

μ TPC status

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BES III

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Outline

- **Time calibration**

time-walk, time-reference, time-propagation

- **Systematic effects**

tracking system, environment conditions

- **After calibrations**

broken cluster, capacitive corrections, tracking improvement



Time calibration

Time calibrations

time-walk

The shape of the signal affects the measured time.

The correlation between time and charge is studied.

time-reference

The TIGER chips are synchronized but the time measurement of the same event can differ due to geometrical differences (i.e. routing, strip length, etc).

time-propagation

The signal propagation from the induction place on the strip and the chip affects the time measurement.

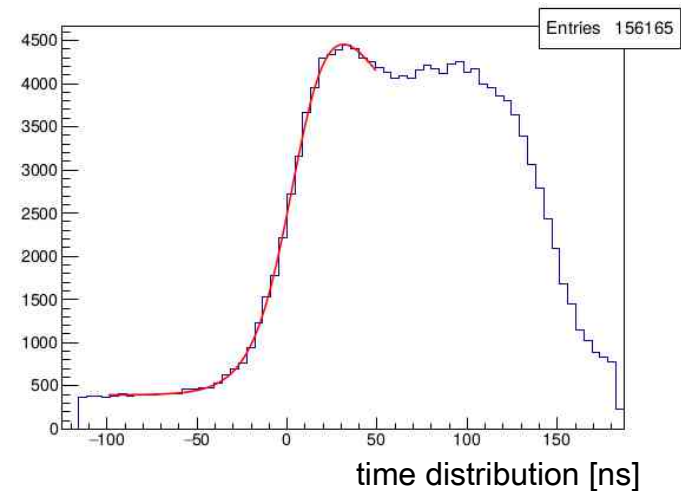


How to measure the time

The time distribution of the hits can be studied to extract the starting time of a certain group of recorded signal (i.e. all the hits of a TIGER or all the hits measured by a channel with a certain threshold).

The function used to fit the rising edge is:

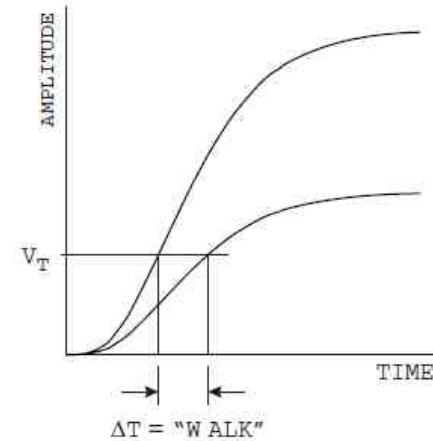
$$[0] + \frac{[1] e^{-[2] (x - [3])}}{1 + e^{-\frac{(x - [4])}{[5]}}}$$



Time calibration -> time-walk

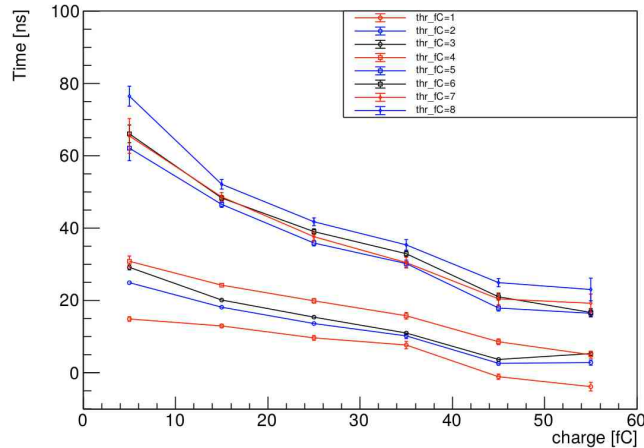
The shape of the signal affects the measured time.
The correlation between time and charge is studied
in two different environments: experimental and
simulation data.

The effect is threshold depends.

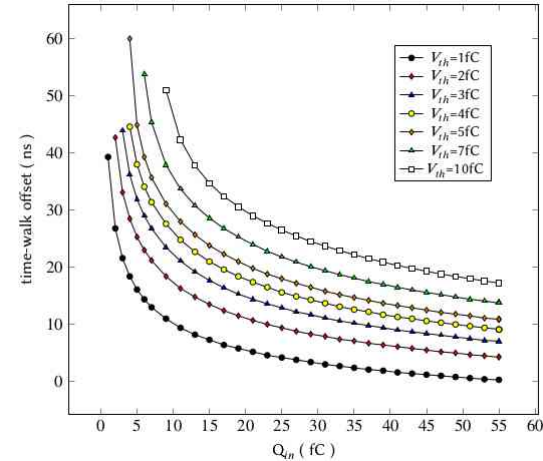


Time calibration -> time-walk

experimental data



simulation data



Experimental data are evaluated for different charge intervals and channel thresholds [run 11-16] using the

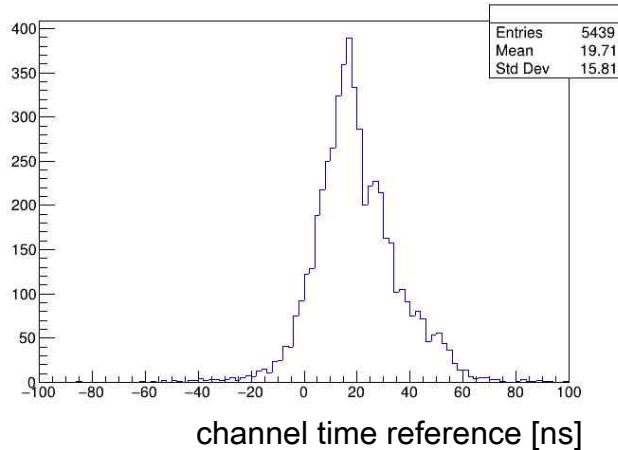
method shown in slide 4. Simulation data are evaluated from squared waves injected in the TIGER ASIC.

A strong dependency of the time-walk as a function of the charge is evident. The discrepancy between the two

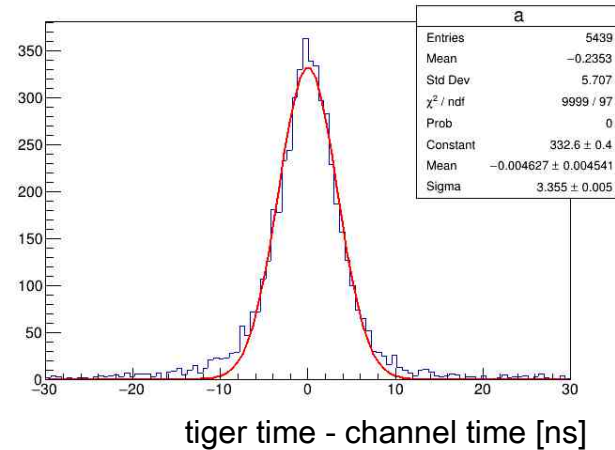
methods is given by the different signal shapes considered. Experimental results will be used.

Time calibration -> time-reference

experimental data



experimental data



Time reference is measured for each channel or for each TIGER chip (~60 channels) using the method of slide 4. A spread from -20 to 80 ns has been observed comparing the different channels, while a difference of about 10-20 ns has been observed between a channels and the others of the same chip.



Time calibration -> time-propagation

direct measurements and simulations

	Strip X	Strip V
Layer 2	$0.51 \pm 0.05 c$	$0.59 \pm 0.05 c$
Layer 3	$0.35 \pm 0.04 c$	$0.57 \pm 0.05 c$
Simulation	$0.36c$	$0.57c$

experimental data

	Strip X
Layer 1	$0.83 \pm 0.30 c$
Layer 2	$0.25 \pm 0.03 c$

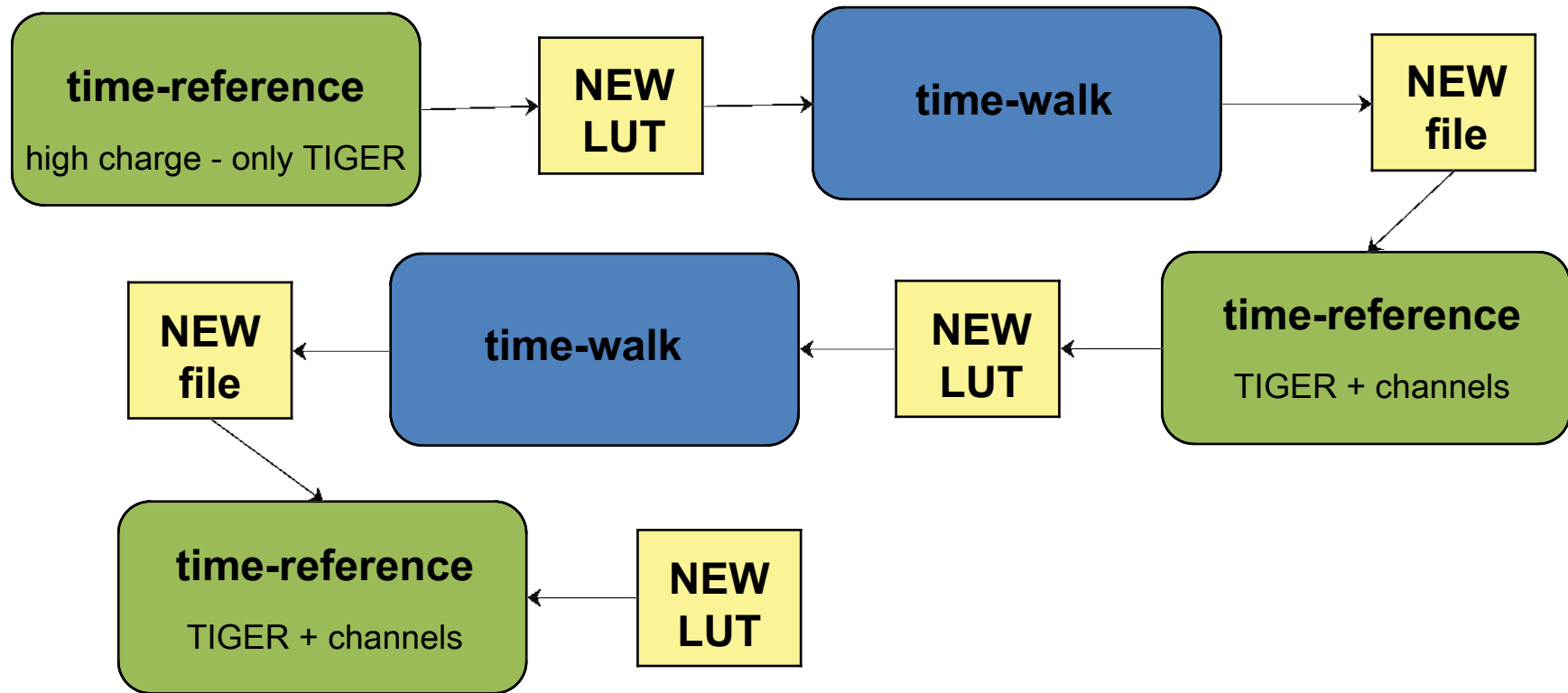
Simulations and direct measurements report a propagation velocity between 0.35-0.6 c.

Experimental measurements suffer the low statistic that limits the precision of this evaluation.

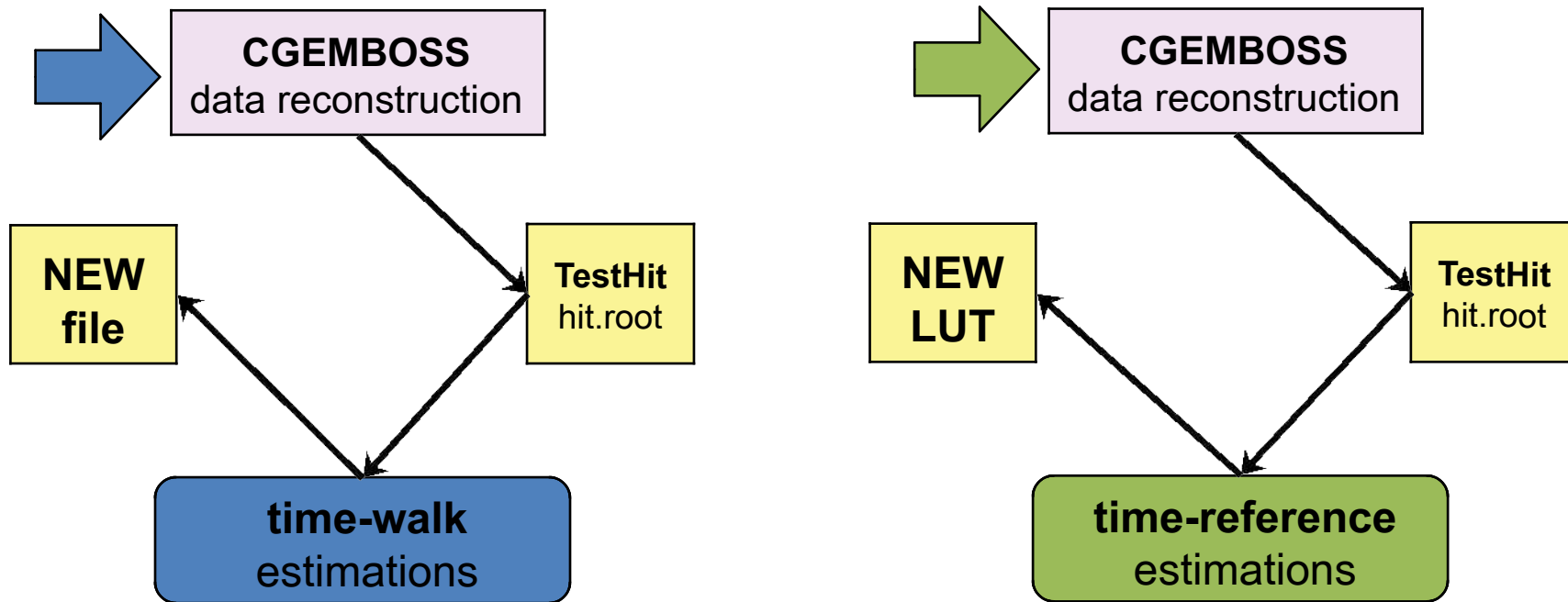
The measures are not compatible then up to now this correction is not taken into account.



Procedure to evaluate the time calibrations



Procedure to evaluate the time calibrations



Why don't we implement the codes to estimate these corrections inside CGEMBOSS?



Limits of this procedure

The corrections we want to implement **need time and high statistic**. The procedure is **iterative** and it can reduce the time spread due to the charge and the geometry of the strip or the routing.

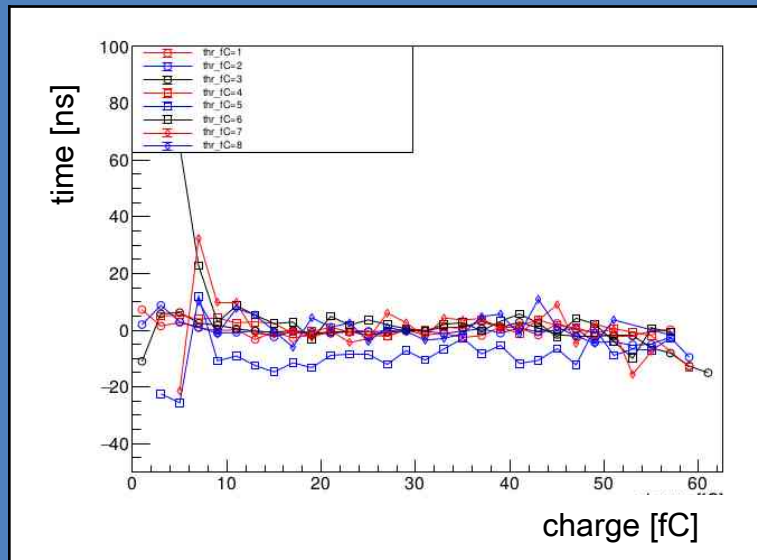
The time extraction from the procedure shown in slide 4 requires a high statistic to reduce as much as possible the error. **This is not guaranteed for all the channels** or some charge/threshold configurations.

The number of channels is more than 5000 then it is **important** to constrain correctly the **fitting procedure** to automatize it.

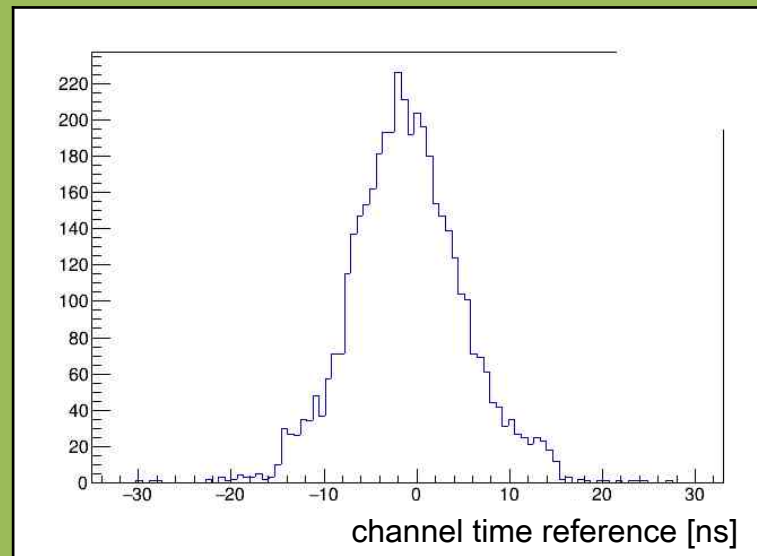


Results of the time calibrations

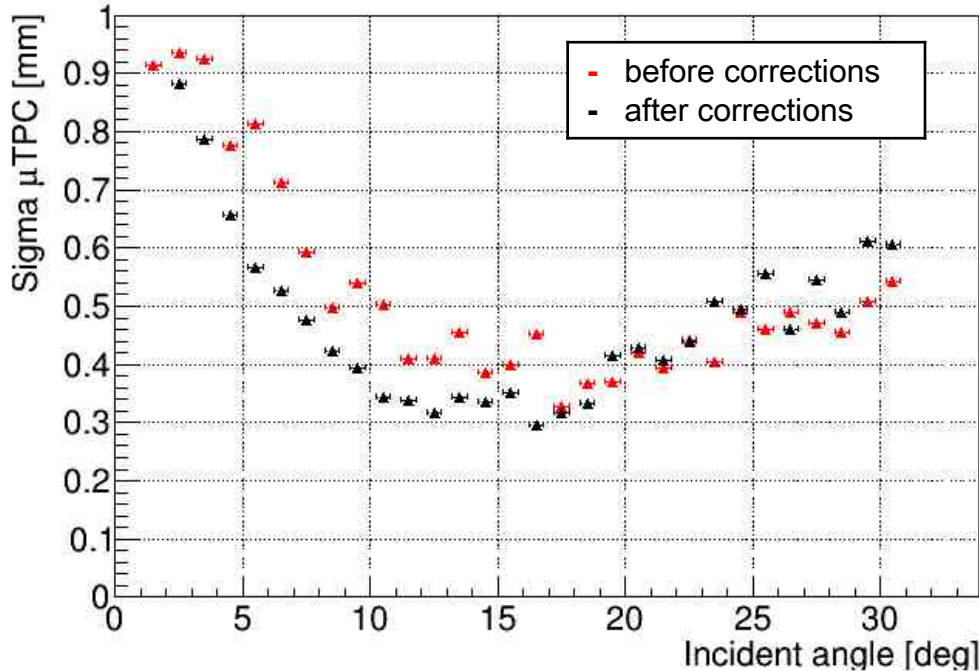
time-walk



time-reference



Results of the time calibrations → Layer1



The time calibrations introduce an improvement of the **sigma μ TPC** in the region below 20° incident angle. The time calibrations are successful.

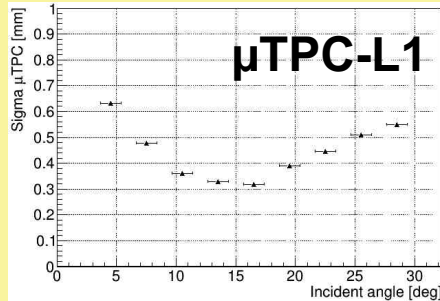
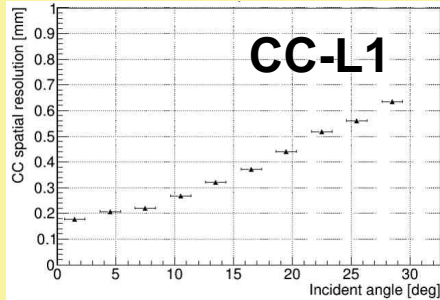
The fluctuations above 20° are due to low statistic in the sigma evaluation. In this range the μ TPC should be flat.



Systematic effects

Systematic effects

Tracking system



Environment

$$t'_{hit} = t_{hit} - t_0$$

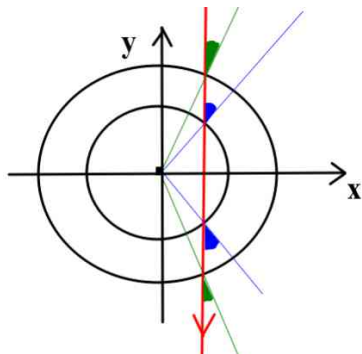
$$z_{hit} = t'_{hit} \cdot v_{drift}$$

$$x_{\mu TPC} = \frac{gap/2 - b}{a}$$

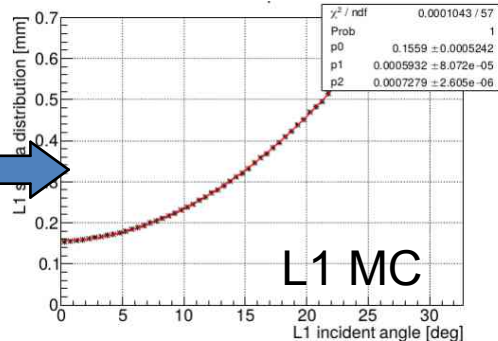
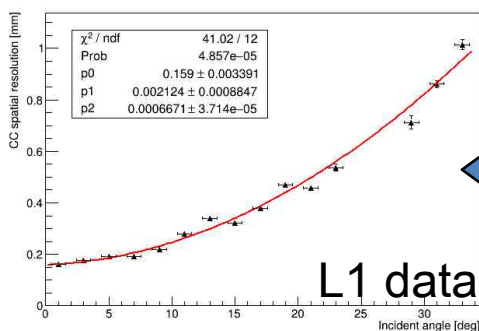
Time and drift velocity
can be affected by
temperature, pressure
and humidity of the
gas mixture



Tracking system → toy MC



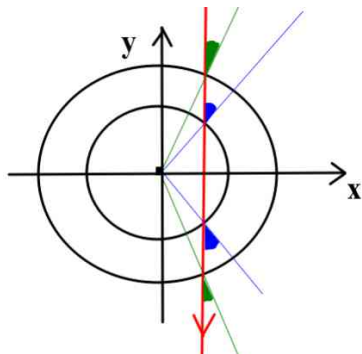
1. Randomize the position of the cosmic ray [0, R_L1]
2. Smear the track incident angle of 0.36 deg (from Marco's calculation) for L1down and L2down
3. Evaluate the **expected CC resolution** at the impact point using the function
$$\text{CC_res} = 80 \mu\text{m} + 3.0 \mu\text{m/deg} * \text{angle} + 0.65 \mu\text{m/deg}^2 * \text{angle}^2$$



CC L1 + tracking system



Tracking system → toy MC



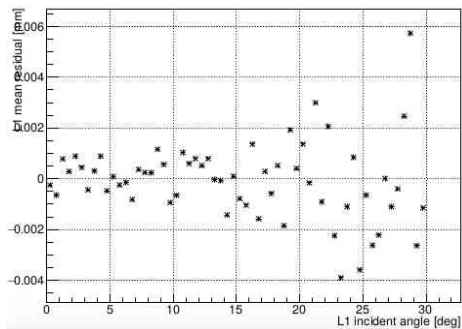
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$$CC_res = 80 \mu\text{m} + 3.0 \mu\text{m}/\text{deg} * \text{angle} + 0.65 \mu\text{m}/\text{deg}^2 * \text{angle}^2$$
4. Smear the four point on the X direction and extract the corresponding Y
5. Use three point to reconstruct the track and measure the residual distribution and the contribution of the tracking system = $\text{sqrt}(\text{sigma_recon}^2 - \text{sigma_true}^2)$

The function used to evaluate the CC_res has been calculated in order to match the reconstructed CC_res in the MC data with the experimental data below $20\mu\text{m}$



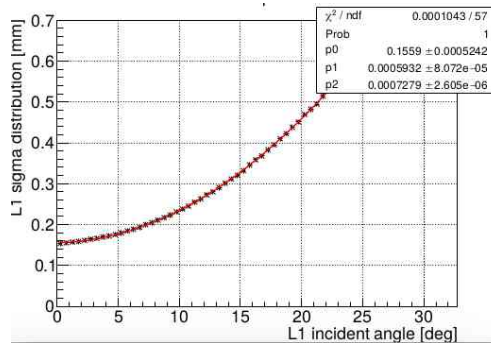
Tracking system → toy MC

Residual Mean value

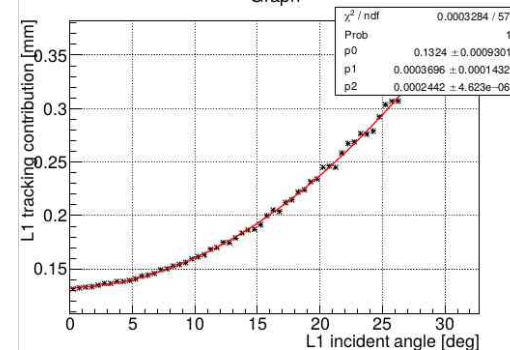


L1

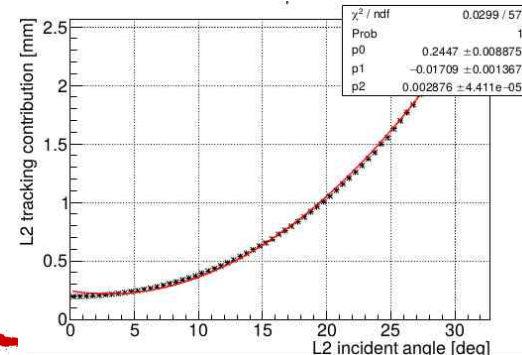
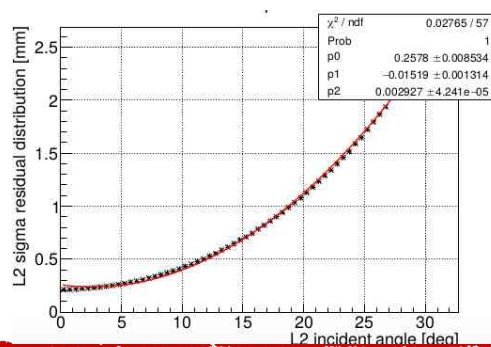
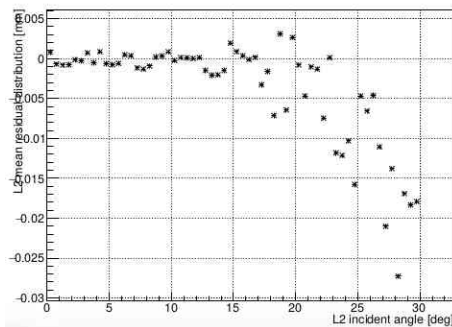
Residual sigma



Contribution of the tracking system

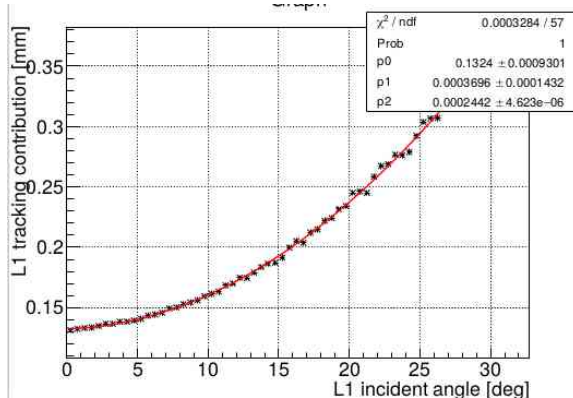


L2



Tracking system → toy MC

Contribution of the tracking system on L1



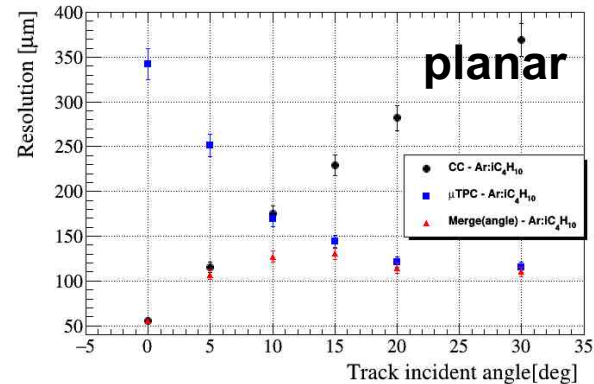
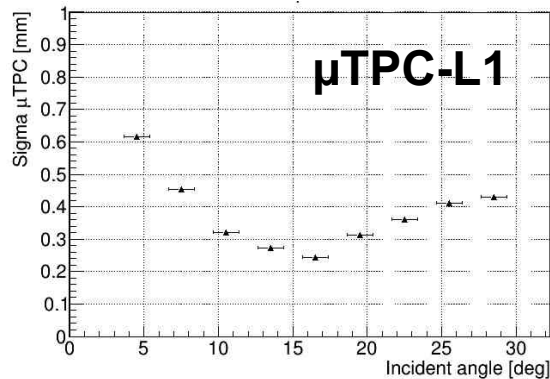
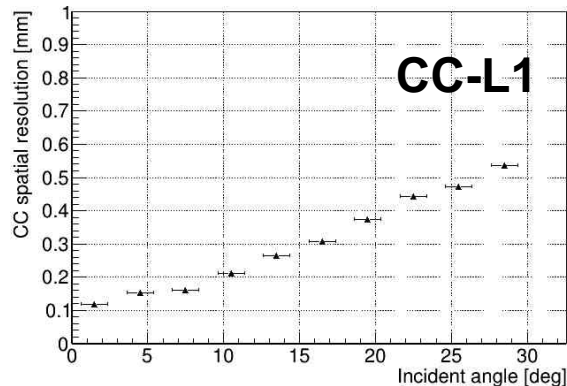
1. The trend of the contribution of the tracking system now is reasonable with respect to the one shown on April

2. This result is important to understand the behavior of the μ TPC once the incident angle is larger than 15° but it does not explain the difference between μ TPC resolution of the CGEM and the planar GEM.

3. The MC resolution for L1 matches the experimental data but the MC resolution of L2 does not. L2 seems to be different from L1 or the systematics are not measured properly. A different function could be used to estimate the CC resolution as a function of the angle for L2.



Tracking system \rightarrow toy MC



Even if we subtract the contribution of the tracking system from the CC and μ TPC sigma measurements, the performance measured in the CGEM is different from the one measured on the planar.

This means that there are other systematics that we have to take into account.



Enviroments systematics → Magboltz simulations

Temperature, pressure, gas mixture contaminations can affect the drift properties of the electrons, such as longitudinal diffusion (time resolution) and drift velocity.

Some Magboltz simulations have been performed to evaluate if the variations of these environment variables can affects the μ TPC parameters then its resolution.

We consider a gas mixture Argon:isobutane (90:10) + $15 \cdot 10^{-3}$ O₂ and $15 \cdot 10^{-3}$ H₂O in agreement with the article linked there (these values are an overestimation)

<https://www.sciencedirect.com/science/article/pii/S016890021931544X>



Enviroments systematics → Magboltz simulations

Drift velocity [$\mu\text{m}/\text{ns}$]	P = 1003 mbar	P = 1013 mbar	P = 1023 mbar
T = 10 °C	37.12	37.20	37.27
T = 20 °C	36.89	36.97	37.02
T = 30 °C	36.70	36.77	36.80

Longitudnal diffusion [cm^2/s]	P = 1003 mbar	P = 1013 mbar	P = 1023 mbar
T = 10 °C	5398	5375	4920
T = 20 °C	5234	5800	5351
T = 30 °C	5755	5649	5502

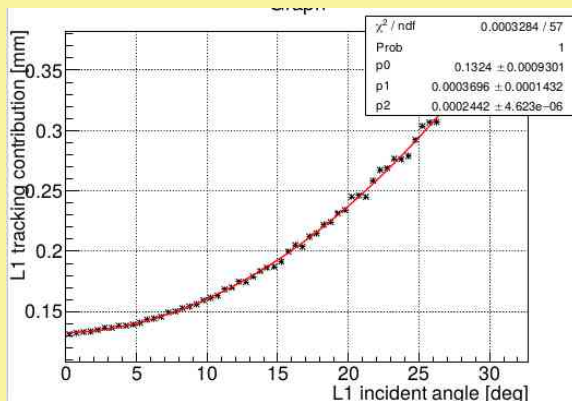
Variations below 1% in drift velocity and about 7% (max) in the longitudinal diffusion are found for large variations of T and P



Systematic effects results

Tracking system

L1 tracking contribution has been evaluated but it doesn't explain the planar difference



Environment

Variations of temperature, pressure and humidity have a small contribution

$$t'_{hit} = t_{hit} - t_0$$
$$z_{hit} = t'_{hit} \cdot v_{drift}$$
$$x_{\mu\text{TPC}} = \frac{\text{gap}/2 - b}{a}$$



After calibrations

After calibrations

Broken clusters

Microsectors
introduce some
broke-cluster on
the readout.
Larger cluster
may improve the
 μ TPC
reconstruction

Capacitive effects

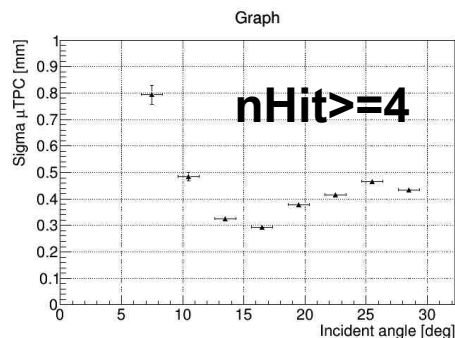
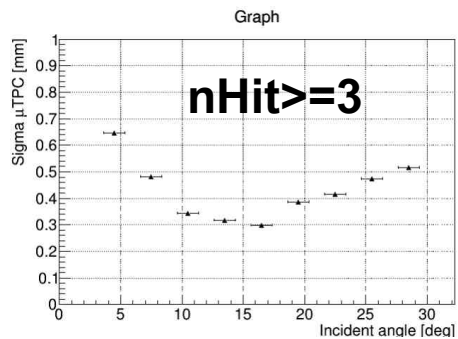
From studies on
the planar GEM,
some algorithms
can improve the
 μ TPC using the
charge
information

Tracking improvements

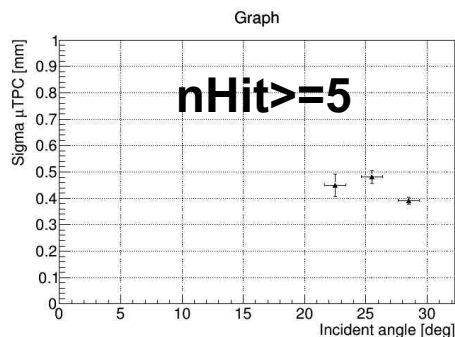
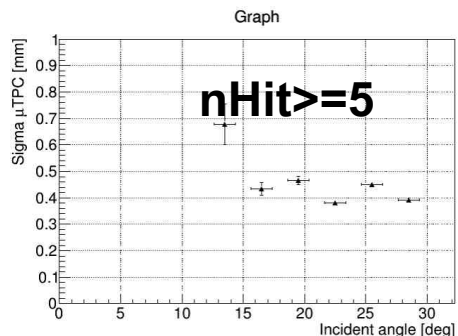
The code for the
2D tracking in
CGEMBOSS can
improve the
results and
increase the
statistic



Broken clusters \rightarrow μ TPC vs cluster size



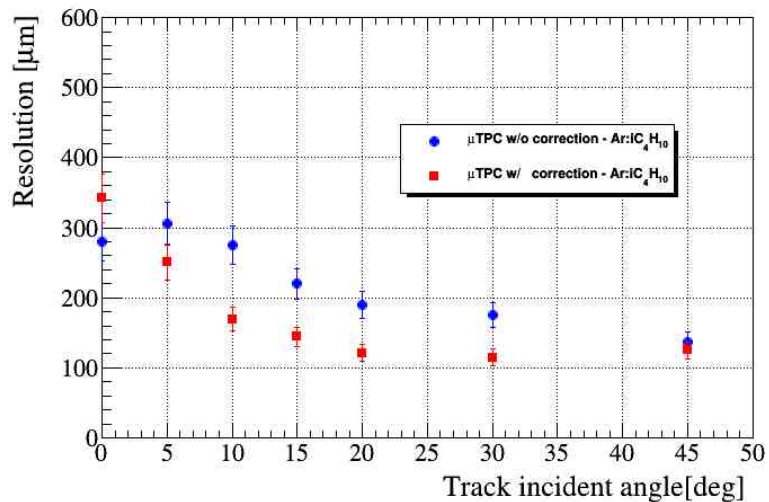
μ TPC sigma is shown for some constraints on the number of hit in the cluster.



No significant improvement are observed if only large cluster size is considered



Capacitive effects



The charge information can be used to improve the μ TPC resolution.



After calibrations → To Do

Broken clusters

Not needed

Capacitive effects

To be implemented once all the other contributions are understood

Tracking improvements

To be tested with the new code in CGEMBOSS

