

roofit tutorial

references

<http://roofit.sourceforge.net/quicktour/first.html>

<https://www.slideserve.com/denna/statistical-methods-for-data-analysis-parameter-estimates-with-roofit>

<https://www.slideserve.com/gomer/deviations-from-exponential-decay>

RooFit: Your toolkit for data modeling

What is it?

- A powerful toolkit for modeling the expected distribution(s) of events in a physics analysis
- Primarily targeted to high-energy physicists using ROOT
- Originally developed for the BaBar collaboration by Wouter Verkerke and David Kirkby.
- Included with ROOT v5.xx

Documentation:

- <http://root.cern.ch/root/Reference.html> – for latest class descriptions. RooFit classes start with “Roo”.
- <http://roofit.sourceforge.net> – for documentation and tutorials

Tutorials:

- `Dig $ROOTSYS/tutorials/rootfit`

Math – The Likelihood estimator

- **Definition** of Likelihood
 - given $\mathbf{D}(\vec{x})$ and $\mathbf{F}(\vec{x}; \vec{p})$

Functions used in likelihoods must be Probability Density Functions:

$$\int F(\vec{x}; \vec{p}) d\vec{x} \equiv 1, \quad F(\vec{x}; \vec{p}) > 0$$

$$L(\vec{p}) = \prod_i F(\vec{x}_i; \vec{p}), \quad \text{i.e. } L(\vec{p}) = F(x_0; \vec{p}) \cdot F(x_1; \vec{p}) \cdot F(x_2; \vec{p}) \dots$$

- For convenience the **negative log of the Likelihood** is often used

$$-\ln L(\vec{p}) = -\sum_i \ln F(\vec{x}_i; \vec{p})$$

- Parameters are estimated by maximizing the Likelihood, or equivalently minimizing $-\log(L)$

$$\left. \frac{d \ln L(\vec{p})}{d \vec{p}} \right|_{p_i = \hat{p}_i} = 0$$

Wouter Verkerke, NIKHEF

Math – Variance on ML parameter estimates

- **Estimator** for the **parameter variance** is

$$\hat{\sigma}(p)^2 = \hat{V}(p) = \left(\frac{d^2 \ln L}{dp^2} \right)^{-1}$$

- I.e. variance is estimated from 2nd derivative of $-\log(L)$ at minimum
- Valid if estimator is **efficient** and **unbiased!**

From Rao-Cramer-Frechet inequality

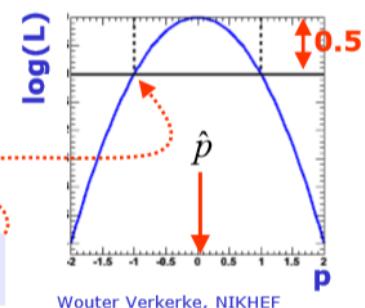
$$V(\hat{p}) \geq 1 + \frac{\frac{db}{dp}}{\left(\frac{d^2 \ln L}{dp^2} \right)}$$

b = bias as function of p , inequality becomes equality in limit of efficient estimator

- **Visual interpretation** of variance estimate

- Taylor expand $-\log(L)$ around minimum

$$\begin{aligned} \ln L(p) &= \ln L(\hat{p}) + \left. \frac{d \ln L}{dp} \right|_{p=\hat{p}} (p - \hat{p}) + \frac{1}{2} \left. \frac{d^2 \ln L}{dp^2} \right|_{p=\hat{p}} (p - \hat{p})^2 \\ &= \ln L_{\max} + \left. \frac{d^2 \ln L}{dp^2} \right|_{p=\hat{p}} \frac{(p - \hat{p})^2}{2} \\ &= \ln L_{\max} + \frac{(p - \hat{p})^2}{2\hat{\sigma}_p^2} \Rightarrow \ln L(p \pm \sigma) = \ln L_{\max} - \frac{1}{2} \end{aligned}$$



Wouter Verkerke, NIKHEF

RooFit core design philosophy

- Mathematical objects are represented as C++ objects

Mathematical concept		RooFit class
variable	x	<code>RooRealVar</code>
function	$f(x)$	<code>RooAbsReal</code>
PDF	$f(x)$	<code>RooAbsPdf</code>
space point	\vec{x}	<code>RooArgSet</code>
integral	$\int_{x_{\min}}^{x_{\max}} f(x) dx$	<code>RooRealIntegral</code>
list of space points		<code>RooAbsData</code>

Likelihood function



- Given a sample of N events each with variables (x_1, \dots, x_n) , the likelihood function expresses the probability density of the sample, as a function of the unknown parameters:

$$L = \prod_{i=1}^N f(x_1^i, \dots, x_n^i; \theta_1, \dots, \theta_m)$$

- Sometimes the used notation for parameters is the same as for conditional probability:

$$f(x_1, \dots, x_n | \theta_1, \dots, \theta_m)$$

- If the size N of the sample is also a random variable, the extended likelihood function is also used:

$$L = p(N; \theta_1, \dots, \theta_m) \prod_{i=1}^N f(x_1^i, \dots, x_n^i; \theta_1, \dots, \theta_m)$$

- Where p is most of the times a Poisson distribution whose average is a function of the unknown parameters

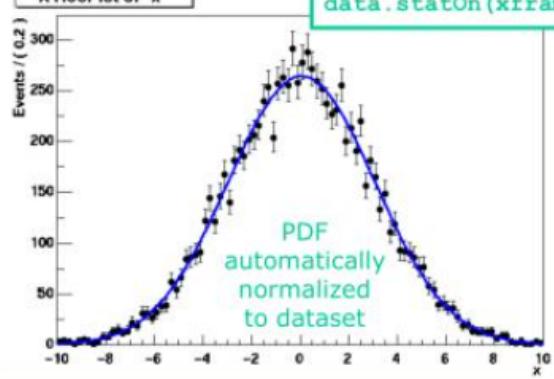
- In many cases it is convenient to use $-\ln L$ or $-2\ln L$: $\prod_i \rightarrow \sum_i$

Example

INN
Download

```
RooRealVar x("x","x",-10,10) ;  
RooRealVar mean("mean","mean of gaussian",0,-10,10);  
RooRealVar sigma("sigma","width of gaussian",3);  
  
RooGaussian gauss("gauss","gaussian PDF",x,mean,sigma);  
  
RooDataSet* data = gauss.generate(x,10000);  
  
// ML fit is the default  
gauss.fitTo(*data);  
  
mean.Print();  
// RooRealVar::mean =  
// 0.0172335 +/- 0.0299542  
sigma.Print();  
// RooRealVar::sigma =  
// 2.98094 +/- 0.0217306  
  
RooPlot* xframe = x.frame();  
data->plotOn(xframe);  
gauss.plotOn(xframe);  
xframe->Draw();
```

Further drawing options:
pdf.paramOn(xframe,data);
data.statOn(xframe);



Extended ML fits

INN
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- Specify extended ML fit adding one extra parameter:

```
pdf.fitTo(*data,  
          RooFit::Extended(kTRUE));
```

Import external data sets



- Read a ROOT tree:

```
RooRealVar x("x","x",-10,10);  
RooRealVar c("c","c",0,30);  
RooDataSet data("data","data",inputTree,  
RooArgSet(x,c));
```

- Automatic removal of entries out of variable range

- Read an ASCII file:

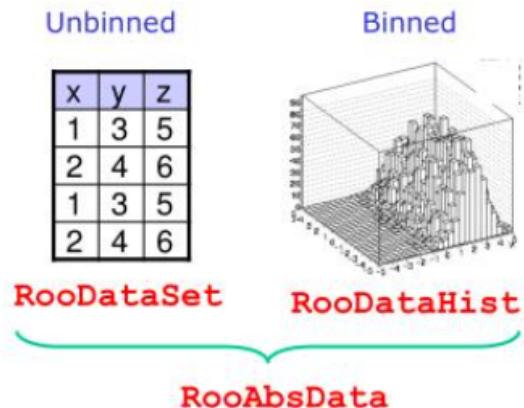
```
RooDataSet* data =  
RooDataSet::read("ascii.file",  
RooArgList(x,c));
```

- One line per entry; variable order given by argument list

Histogram fits



- Use a binned data set:
 - **RooDataHist** instead of **RooDataSet**
- Fit with binned model



Minuit function MIGRAD



- Purpose: find minimum

```
*****
** 13 **MIGRAD      1000      1
*****
(some output omitted)
MIGRAD MINIMIZATION HAS CONVERGED.
MIGRAD WILL VERIFY CONVERGENCE AND ERROR MATRIX
COVARIANCE MATRIX CALCULATED SUCCESSFULLY
FCN=257.304 FROM MIGRAD   STATUS=CONVERGED
                           EDM=2.36773e-06  STRATEGY= 31 CALLS      32 TOTAL
EXT PARAMETER              1           ERROR MATRIX ACCURATE
NO.  NAME        VALUE          ERROR
  1  mean        8.84225e-02  3.23862e-01
  2  sigma       3.20763e+00  2.39540e-01
                           STEP      FIRST
                           SIZE      DERIVATIVE
                           3.58344e-04 -2.24755e-02
                           2.78628e-04 -5.34724e-02
ERR DEF= 0.5
EXTERNAL ERROR MATRIX.     NDIM= 25   NPAR= 2   ERR DEF=0.5
 1.049e-01  3.338e-04
 3.338e-04  5.739e-02
PARAMETER  CORRELATION COEFFICIENTS
 NO.  GLOBAL      1      2
  1  0.00430    1.000  0.004
  2  0.00430    0.004  1.000
```

Luca Lista Statistical Methods

Progress information,
watch for errors here

Parameter values and approximate
errors reported by MINUIT

Error definition (in this case 0.5 for
a likelihood fit)

Minuit function MIGRAD



- Purpose: find minimum

```
*****
** 13 **MIGRAD      1000      1
*****
(some output omitted)
MIGRAD MINIMIZATION HAS CONVERGED.
MIGRAD WILL VERIFY CONVERGENCE AND ERROR MATRIX.
COVARIANCE MATRIX CALCULATED SUCCESSFULLY
FCN=257.304 FROM MIGRAD   STATUS=CONVERGED      31 CALLS      32 TOTAL
                           EDM=2.36773e-06  STRATEGY= 1           ERROR MATRIX ACCURATE
EXT PARAMETER              1           ERROR MATRIX ACCURATE
NO.  NAME        VALUE          ERROR
  1  mean        8.84225e-02  3.23862e-01
  2  sigma       3.20763e+00  2.39540e-01
                           STEP      FIRST
                           SIZE      DERIVATIVE
                           3.58344e-04 -2.24755e-02
                           2.78628e-04 -5.34724e-02
ERR DEF= 0.5
EXTERNAL ERROR MATRIX.     NDIM= 25   NPAR= 2   ERR DEF=0.5
 1.049e-01  3.338e-04
 3.338e-04  5.739e-02
PARAMETER  CORRELATION COEFFICIENTS
 NO.  GLOBAL      1      2
  1  0.00430    1.000  0.004
  2  0.00430    0.004  1.000
```

Value of χ^2 or likelihood at
minimum

(NB: χ^2 values are not divided
by N_{d.o.f.})

Approximate
Error matrix
And covariance matrix

Minuit function MIGRAD



- Purpose: find minimum

```
*****
** 13 **MIGRAD      1000
*****
(some output omitted)
MIGRAD MINIMIZATION HAS CONVERGED
MIGRAD WILL VERIFY CONVERGENCE AND EXIT MATRIX.
COVARIANCE MATRIX CALCULATED SUCCESSFULLY
FCN=257.304 FROM MIGRAD   STATUS=CONVERGED    31 CALLS    32 TOTAL
                           EDM=2.36773e-06  STRATEGY= 1    ERROR MATRIX ACCURATE
EXT PARAMETER              STEP          FIRST
NO.  NAME      VALUE       ERROR      SIZE      DERIVATIVE
  1  mean      8.84225e-02  3.23862e-01  3.58344e-04 -2.24755e-02
  2  sigma     3.20763e+00  2.39540e-01  2.78628e-04 -5.34724e-02
                           ERR DEF= 0.5
EXTERNAL ERROR MATRIX.   NDIM=  25   NPAR=  2   ERR DEF=0.5
 1.049e-01  3.338e-04
 3.338e-04  5.739e-02
PARAMETER  CORRELATION COEFFICIENTS
 NO.  GLOBAL      1      2
  1  0.00430    1.000  0.004
  2  0.00430    0.004  1.000
```

Status:
Should be 'converged' but can be 'failed'

Estimated Distance to Minimum
should be small $O(10^{-6})$

Error Matrix Quality
should be 'accurate', but can be
'approximate' in case of trouble

Minuit function HESSE



- Purpose: calculate error matrix from $\frac{d^2L}{dp^2}$

```
*****
** 18 **HESSE      1000
*****
COVARIANCE MATRIX CALCULATED SUCCESSFULLY
FCN=257.304 FROM HESSE   STATUS=OK
                           EDM=2.36534e-06  STRAT=1
EXT PARAMETER              INTERNAL      INTERNAL
NO.  NAME      VALUE      ERROR      STEP SIZE      VALUE
  1  mean      8.84225e-02  3.23861e-01  7.16689e-05  8.84237e-03
  2  sigma     3.20763e+00  2.39539e-01  5.57256e-05  3.26535e-01
                           ERR DEF= 0.5
EXTERNAL ERROR MATRIX.   NDIM=  25   NPAR=  2   ERR DEF=0.5
 1.049e-01  2.780e-04
 2.780e-04  5.739e-02
PARAMETER  CORRELATION COEFFICIENTS
 NO.  GLOBAL      1      2
  1  0.00358    1.000  0.004
  2  0.00358    0.004  1.000
```

Symmetric errors
calculated from 2nd
derivative of $-\ln(L)$ or χ^2

Minuit function HESSE



- Purpose: calculate error matrix from $\frac{d^2L}{dp^2}$

```
*****
** Error matrix
*** (Covariance Matrix)
COV calculated from
FCN
EX
NO
1
2
  sic
  3.20763e+00
EXTERNAL ERROR MATRIX.
  1.049e-01  2.780e-04
  2.780e-04  5.739e-02
PARAMETER CORRELATION COEFFICIENTS
 NO. GLOBAL      1      2
 1 0.00358    1.000  0.004
 2 0.00358    0.004  1.000
```

$V_{ij} = \left(\frac{d^2(-\ln L)}{dp_i dp_j} \right)^{-1}$

Minuit function HESSE



- Purpose: calculate error matrix from $\frac{d^2L}{dp^2}$

```
*****
** 18 **HESSE      1000
*****
COVARIANCE MATRIX CALCULATED SUCCESSFULLY
FCN=257.304 FROM HESSE   STATUS=OK      10 CALLS      42 TOTAL
                           EDM=2.36534e-06  STRATEGY= 1  ERROR MATRIX ACCURATE
EXT PARAMETER
NO. NAME      VALUE
 1 mean      8.84225e-02
 2 sigma     3.20763e+00
EXTERNAL ERROR MATRIX. NDIM= 25      NPAR= 2      ERR DEF=0.5
 1.049e-01  2.780e-04
 2.780e-04  5.739e-02
PARAMETER CORRELATION COEFFICIENT
 NO. GLOBAL      1      2
 1 0.00358    1.000  0.004
 2 0.00358    0.004  1.000
```

$V_{ij} = \sigma_i \sigma_j \rho_{ij}$

Minuit function HESSE



- Purpose: calculate error matrix from $\frac{d^2L}{dp^2}$

```
*****
** 18 **HESSE      1000
*****
COVARIANCE MATRIX CALCULATED SUCCESSFULLY
FCN=257.304 FROM HESSE      STATUS=OK          10 CALLS      42 TOTAL
                           EDM=2.36534e-06   STRATEGY= 1    ERROR MATRIX ACCURATE
EXT PARAMETER              INTERNAL      INTERNAL
NO.  NAME        VALUE       ERROR
  1  mean         7.16689e-05  8.84237e-03
  2  sigma        5.57256e-05  3.26535e-01
STEP SIZE                  INTERNAL      INTERNAL
                           VALUE
  1  1.049e-01   2.780e-04  5.739e-01
EXTERNAL ERROR
  1.049e-01  2.780e-04  5.739e-01
PARAMETER CORRELATION COEFFICIENTS
NO.  GLOBAL      1     2
  1  0.00358    1.000  0.004
  2  0.00358    0.004  1.000
```

Global correlation vector:
correlation of each parameter with all other parameters

Minuit function MINOS



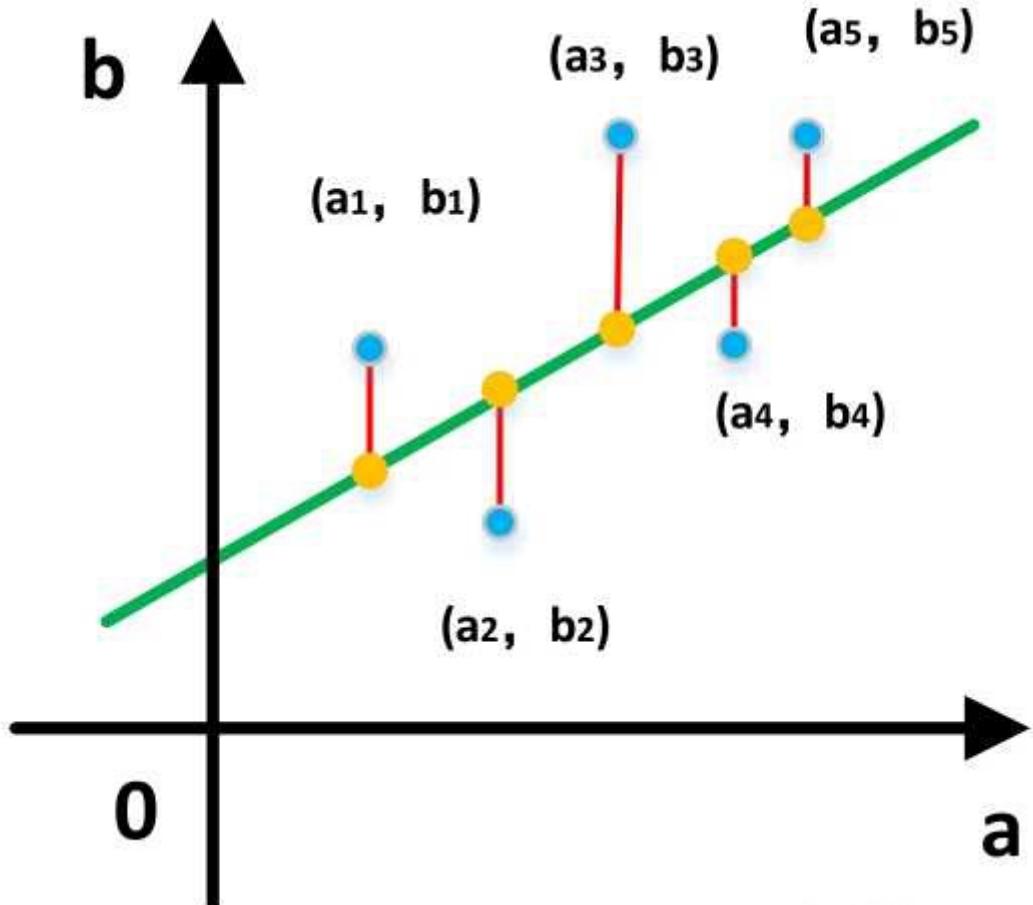
- Error analysis through $\Delta\chi^2$ contour finding

```
*****
** 23 **MINOS      1000
*****
FCN=257.304 FROM MINOS      STATUS=SUCCESSFUL      52 CALLS      94 TOTAL
                           EDM=2.36534e-06   STRATEGY= 1    ERROR MATRIX ACCURATE
EXT PARAMETER              PARABOLIC      MINOS ERRORS
NO.  NAME        VALUE       ERROR           NEGATIVE      POSITIVE
  1  mean         8.84225e-02  3.23861e-01  -3.24688e-01  3.25391e-01
  2  sigma        3.20763e+00  2.39539e-01  -2.23321e-01  2.58893e-01
ERR DEF= 0.5
```

Symmetric error
(repeated result from HESSE)

MINOS error
Can be asymmetric
(in this example the 'sigma' error is slightly asymmetric)

最小二乘法和最大似然法



代表: hist->Fit(f1);

最大似然法

Likelihood function



- Given a sample of N events each with variables (x_1, \dots, x_n) , the likelihood function expresses the probability density of the sample, as a function of the unknown parameters:

$$L = \prod_{i=1}^N f(x_1^i, \dots, x_n^i; \theta_1, \dots, \theta_m)$$

- Sometimes the used notation for parameters is the same as for conditional probability:

$$f(x_1, \dots, x_n | \theta_1, \dots, \theta_m)$$

- If the size N of the sample is also a random variable, the extended likelihood function is also used:

$$L = p(N; \theta_1, \dots, \theta_m) \prod_{i=1}^N f(x_1^i, \dots, x_n^i; \theta_1, \dots, \theta_m)$$

- Where p is most of the times a Poisson distribution whose average is a function of the unknown parameters

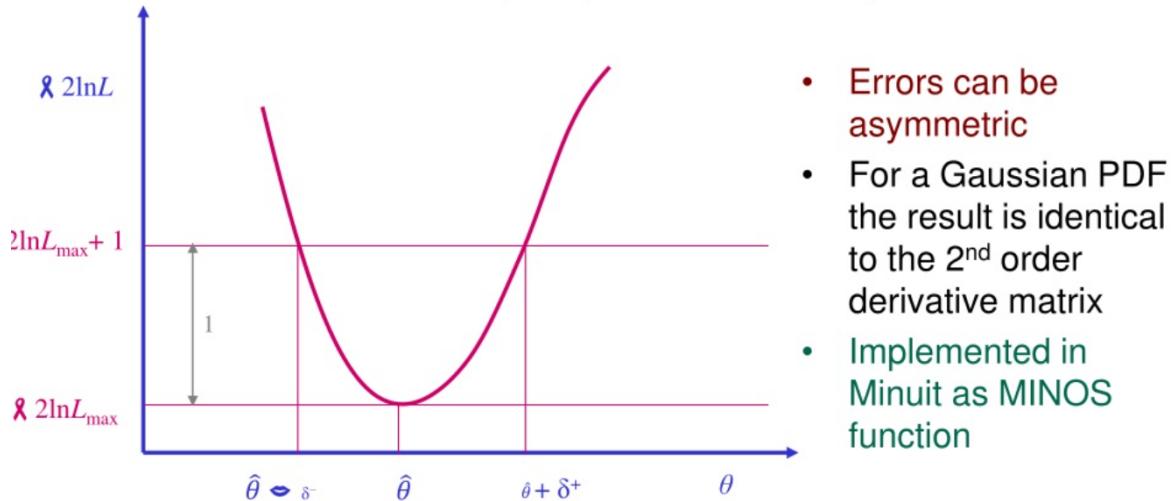
- In many cases it is convenient to use $-\ln L$ or $-2\ln L$: $\prod_i \rightarrow \sum_i$

Asymmetric errors

按 Esc 即可退出全屏模式



- Another approximation alternative to the parabolic one may be to evaluate the excursion range of $\sqrt{2 \ln L}$.
- Error ($n\sigma$) determined by the range around the maximum for which $\sqrt{2 \ln L}$ increases by +1 (+ n^2 for $n\sigma$ intervals)



roofit是一个容易进行最大似然拟合的框架

roofit也可以进行最小二乘拟合 (rf602_chi2fit.C)

```
66
67 // Construct a chi^2 of the data and the model.
68 // When a p.d.f. is used in a chi^2 fit, the probability density scaled
69 // by the number of events in the dataset to obtain the fit function
70 // If model is an extended p.d.f, the expected number events is used
71 // instead of the observed number of events.
72 model.chi2FitTo(*dh) ;
73 return;
```

root 的Fit是常用的最小二乘拟合手段,

但是调用minuit方法, 也可以进行最大似然拟合