Multi-loop Feynman integrals with masses

Li Lin Yang Zhejiang University



In recent years we have seen enormous progresses in the analytic understanding of multi-loop integrals in massless theories



multi-loop integrals in massless theories



Two-loop five-point integrals and amplitudes



Chicherin et al.: 1812.11160; Yang Zhang, ...



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Luo et al.: 1912.05778; Hua Xing Zhu, ...

Henn et al.: 1911.10174; Gang Yang, ...



We are also interested in loop integrals with massive particles, especially in electroweak physics







The analytic structure quickly becomes complicated when mass scales are introduced





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Simplest non-polylogarithmic massless integral

Bourjaily et al.: 1712.02785



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 $m_1 = m_2 = 0$: polylogarithmic



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: polylogarithmic
 $m_1 \neq 0, m_2 = 0$: elliptic



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 $m_1 \neq 0, m_2 = 0$: elliptic
 $m_1, m_2 \neq 0$: ???



May be computed numerically (sector decomposition, auxiliary mass flow, ...) See talk by Y. Q. Ma







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But we'd like to push the analytic method to its limit. And there are many questions: ► Given an integral family, how do we know which classes of functions will appear in the

- results?
- > What is a good functional basis (with nice analytic/algebraic/geometric/numeric properties) to represent the results?
- > How to organize the calculation procedure to naturally reflect these properties?
- > After obtaining an analytic expression, how to efficiently evaluated it numerically?



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Let's look at the simplest example: MPLs





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Multiple polylogarithms (MPLs)

Generalization of logarithms and polylogarithms

 $G(a_1, ..., a_n; z) =$

Well-defined "transcendental weights" or "transcendentality"



$$\int_{0}^{z} \frac{dt}{t - a_{1}} G(a_{2}, \dots, a_{n}; t)$$

Goncharov (1998)



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$$dG(a_1, \dots, a_n; z) = \sum_{i=1}^n G(a_1, \dots, \hat{a}_i, \dots, a_n; z) d\log \frac{a_{i-1} - a_i}{a_{i+1} - a_i}$$



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- different kinematic regions
- compact representation See talk by Gang Yang
- Efficient numeric evaluation: helps to make phenomenological predictions



$$\int_{0}^{z} \frac{dt}{t - a_{1}} G(a_{2}, \dots, a_{n}; t)$$
Goncharov (1998)

> Well-understood analytic structure (branch cuts): helps the analytic continuation to

► Many algebraic properties (shuffle, stuffle, symbols, Hopf, ...): helps to find the most



MPLs from canonical differential equations



$$g_1 = c(-s)^{\epsilon} t G_{0,1,0}$$
$$g_2 = c(-s)^{\epsilon} s G_{1,0,2}$$
$$g_3 = c \epsilon (-s)^{\epsilon} s t G_{1,2}$$

"canonical basis"

Henn: 1304.1806, 1412.2296





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MPLs from canonical DEs

Expansion coefficients in ϵ consist of iterated integrals

$$\vec{f}^{(n)}(z) \supset \int_{z_0}^z d\log(\alpha_n(z_n)) \cdots \int_{z_0}^{z_3} d\log(\alpha_2(z_2)) \int_{z_0}^{z_2} d\log(\alpha_1(z_1))$$

"Uniform transcendentality (UT)"

Therefore also the terms "UT integrals" and "UT basis"



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"Uniform transcendentality (UT)"

(either by direct integration or by "bootstrapping")

- Therefore also the terms "UT integrals" and "UT basis"
- In many cases can be converted to combinations of MPLs



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"Uniform transcendentality (UT)"

(either by direct integration or by "bootstrapping")

Other benefits of having a UT basis:

- > Even if no explicit form as MPLs, can be efficiently evaluated numerically Hidding: 2006.05510 Amplitude coefficients often take a simpler form Boehm et al.: 2008.13194

- Therefore also the terms "UT integrals" and "UT basis"
- In many cases can be converted to combinations of MPLs





How to find a canonical basis?

The traditional way: starting from the DEs

which means



$\frac{\partial}{\partial x}\vec{f}(x,\epsilon) = A(x,\epsilon)\vec{f}(x,\epsilon)$

Try to find a transformation matrix $T(x, \epsilon)$ such that $\vec{f}'(x, \epsilon) = T\vec{f}$ is a canonical basis,

 $T^{-1}AT - T^{-1}\partial_{x}T = \epsilon \tilde{A}(x)$



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Algorithmic approach: Lee: 1411.0911

Program packages:

Prausa: 1701.00725; Gituliar, Magerya: 1701.04269; Meyer: 1705.06252



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$$= A(x,\epsilon) \vec{f}(x,\epsilon)$$

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However, does not work well for irrational systems (e.g., with algebraic extensions like square-roots)



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UT integrals and d-log integrands

It is believed that integrals with d-log integrands are canonical

$$\int_{\mathscr{C}} \left[G(z) \right]^{\epsilon} \bigwedge_{j=1}^{n} d \log f_j(z)$$
Studie
Arkan

• 1 . 0

An example

weight 0

$$4\epsilon^{2} \int_{0}^{x} \frac{dz_{2}}{z_{2}} \int_{0}^{z_{2}} \frac{dz_{1}}{z_{2} - z_{1}} \left[\frac{z_{2}(x - z_{2})(1 + z_{1})}{z_{1}(z_{1} - z_{2})^{2}} \right]^{\epsilon} = 1 - \epsilon \log x + \epsilon^{2} \left(\frac{1}{2} \log^{2} x + 2\text{Li}_{2}(-x) \right) + \cdots$$
weight 2

ed a lot in the context of $\mathcal{N} = 4$ SYM ni-Hamed et al., Bern et al., Drummond et al., Gehrmann et al., ...



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We'd like to find d-log integrands which can be interpreted as Feynman integrals

ed a lot in the context of $\mathcal{N} = 4$ SYM ni-Hamed et al., Bern et al., Drummond et al., Gehrmann et al., ...

Need to choose a concrete representation...



Baikov representation

Baikov: hep-ph/9611449

Change of integration variables from momenta to propagators

$$\int \left[\prod_{i=1}^{L} \frac{d^{d}k_{i}}{i\pi^{d/2}}\right] \frac{1}{z_{1}^{a_{1}} z_{2}^{a_{2}} \cdots z_{N}^{a_{N}}} \propto \int_{\mathscr{C}} \left[\prod_{n=1}^{N} dz_{n}\right] \frac{\left[G(z)\right]}{q_{n}}$$
Gram
Gram
$$det \begin{pmatrix} -q_{1} \cdot q_{1} & -q_{1} \\ -q_{2} \cdot q_{1} & -q_{2} \\ \vdots \\ -q_{N} \cdot q_{1} & \cdot \end{pmatrix}$$



determinant

 $\begin{array}{cccc} q_1 \cdot q_2 & \cdots & -q_1 \cdot q_N \\ q_2 \cdot q_2 & & \vdots \end{array}$

Other uses of Baikov rep.: IBP reduction, deriving differential equations, ...

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Baikov representation

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Change of integration variables from momenta to propagators



Looks d-log if $d - L - E = 1 - 2\epsilon$ and all $a_n = 1$, but this does not cover all situations!

$$[1, \ldots, z_N) \Big]^{(d-L-E-1)/2}$$

Gram determinant

Other uses of Baikov rep.: IBP reduction, deriving differential equations, ...



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Other uses of Baikov rep.: IBP reduction, deriving differential equations, ...

We need a more generic form...

Generalized loop-by-loop Baikov representation



representation, e.g.:

$$[a_1, \dots, z_N)]^{(d-L-E-1)/2}$$

→ irreducible scalar product (ISP) If some z_i does not appear in the denominator, we can integrate over it to obtain a new

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Generalized loop-by-loop Baikov representation

$$\int \left[\prod_{i=1}^{L} \frac{d^{d}k_{i}}{i\pi^{d/2}}\right] \frac{1}{z_{1}^{a_{1}} z_{2}^{a_{2}} \cdots z_{N}^{a_{N}}} \propto \int_{\mathcal{C}} \left[\prod_{n=1}^{N} dz_{n}\right] \frac{\left[G(z_{1}, \dots, z_{N})\right]^{(d-L-E-1)/2}}{z_{1}^{a_{1}} \cdots z_{N}^{a_{N}}}$$

If some z_i does not appear in the denomination representation, e.g.:

$$\int_{z_{-}}^{z_{+}} (az^{2} + bz + c)^{-1-\epsilon} dz \sim a^{\epsilon} (b^{2} - 4ac)^{-1/2-\epsilon}$$

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> Equivalent to the loop-by-loop (LBL) Baikov representation

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We will use this generalized form to look for d-log integrands, but how can we convert them back to Feynman integrals?

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> Equivalent to the loop-by-loop (LBL) Baikov representation

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Geometric formulation of IBP equivalence

Frellesvig et al.: 1901.11510, 1907.02000, 2008.04823 Baikov integrals are special cases of generalized hypergeometric integrals

> $I = \int_{\mathscr{C}} u(z) \, \varphi(z)$ multivalued function vanishing on the boundary $\partial \mathscr{C}$

single-valued differential *n*-form



Geometric formulation of IBP equivalence

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> multivalued function vanishing on the boundary $\partial \mathscr{C}$

$$0 = \int_{\mathscr{C}} d(u(z)\xi(z)) = \int_{\mathscr{C}} u(z) \nabla_{\omega}\xi(z)$$

(*n* - 1)-form

 $I = \int_{\mathscr{C}} u(z) \, \varphi(z)$

single-valued differential *n*-form

$$\nabla_{\omega} \equiv d + \omega \wedge \qquad \begin{array}{l} \text{covariant} \\ \text{derivative} \end{array}$$

$$\omega \equiv d \log u \qquad \begin{array}{l} \text{connection} \end{array}$$



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$$0 = \int_{\mathscr{C}} d(u(z)\xi(z)) = \int_{\mathscr{C}} u(z)\nabla_{\omega}\xi$$

$$(n-1)\text{-form}$$

 $I = \int_{\mathscr{C}} u(z) \, \varphi(z)$

single-valued differential *n*-form



 $\varphi(z)$ and $\varphi(z) + \nabla_{\omega}\xi(z)$ are equivalent (in the sense of integration)



Twisted cohomology

The covariant derivative ∇_{ω} creates a cochain complex of differential forms $\Omega^0(M) \xrightarrow{\nabla_{\omega}} \Omega^1(M)$

> Closed forms φ : $\nabla_{\omega} \varphi = 0$ Exact forms $\varphi: \varphi = \nabla_{\omega} \xi$

$$M) \xrightarrow{\nabla_{\omega}} \cdots \Omega^{n-1}(M) \xrightarrow{\nabla_{\omega}} \Omega^{n}(M) \xrightarrow{\nabla_{\omega}} 0$$



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Exact forms $\varphi: \varphi = \nabla_{\omega} \xi$

The *k*-th twisted cohomology group

$$H^k_{\omega} = \frac{\ker(\nabla_{\omega} : \Omega^k(M) \to \Omega^{k+1}(M))}{\operatorname{im}(\nabla_{\omega} : \Omega^{k-1}(M) \to \Omega^k(M))} = \frac{\{\text{closed } k\text{-forms}\}}{\{\text{exact } k\text{-forms}\}}$$

$$M) \xrightarrow{\nabla_{\omega}} \cdots \Omega^{n-1}(M) \xrightarrow{\nabla_{\omega}} \Omega^{n}(M) \xrightarrow{\nabla_{\omega}} 0$$

Closed forms φ : $\nabla_{\omega} \varphi = 0$



Twisted cohomology

- The covariant derivative ∇_{ω} creates a cochain complex of differential forms $\Omega^0(M) \xrightarrow{\nabla_{\omega}} \Omega^1(M)$
 - Exact forms $\varphi: \varphi = \nabla_{\omega} \xi$
- The *k*-th twisted cohomology group $H_{\omega}^{k} = \frac{\ker(\nabla_{\omega} : \Omega^{k}(M))}{\operatorname{im}(\nabla_{\omega} : \Omega^{k-1}(M))}$
 - H_{ω}^{k} is a vector space whose elements (cocycles) are equivalence classes



$$M) \xrightarrow{\nabla_{\omega}} \cdots \Omega^{n-1}(M) \xrightarrow{\nabla_{\omega}} \Omega^{n}(M) \xrightarrow{\nabla_{\omega}} 0$$

Closed forms φ : $\nabla_{\omega} \varphi = 0$

$$\frac{M}{M} \to \Omega^{k+1}(M)) = \frac{\{\text{closed } k\text{-forms}\}}{\{\text{exact } k\text{-forms}\}}$$

$$\varphi : \varphi \sim \varphi + \nabla_{\omega} \xi$$

The same as IBP!



Decomposition in cohomology group

The dimension of the vector space H_{ω}^{n} is

We may find a basis with ν vectors $\{\langle e_1 |$

All vectors can be written as a linear combination

$$\langle \varphi | = \sum_{i=1}^{\nu} c_i \langle e_i |$$



$\dim(H_{\omega}^n) = \nu = \#$ of master integrals with a given ω

$$\langle e_2 | , \dots, \langle e_{\nu} | \}$$

Decomposition in cohomology group

The dimension of the vector space H_{ω}^{n} is

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How



- $\dim(H_{\omega}^n) = \nu = \#$ of master integrals with a given ω

- v to project out these coefficients?
- We need something like an "inner-product"

Intersection numbers

To define an inner-product, introduce a dual vector space $H_{\omega}^{n^*}$ with elements $|\varphi_R\rangle$

The intersection numbers Cho, Matsumoto (1995)

$$\left\langle \varphi_{L} | \varphi_{R} \right\rangle_{\omega} = \frac{1}{(2\pi i)^{n}} \int \iota_{\omega}(\varphi_{L}) \wedge \varphi_{R} = \frac{1}{(2\pi i)^{n}} \int \varphi_{L} \wedge \iota_{-\omega}(\varphi_{R})$$

Equivalence classes $|\varphi_R\rangle$: $\varphi_R \sim \varphi_R + \nabla_{-\omega} \xi_R$

map to an equivalent, but compactly supported form



Decomposition via intersection numbers

$$\langle \varphi | = \sum_{i=1}^{\nu} c_i \langle e_i |$$

Construct a dual basis of $\langle e_i |$

$$\langle e_i | d_j \rangle = \delta_{ij} \quad -$$

Frellesvig et al.: 1901.11510, 1907.02000, 2008.04823

$$c_i = \langle \varphi | d_i \rangle$$

or
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Just like the decomposition in a usual vector space...



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Computing these inner-products is still a non-trivial task (skipped in this talk)

Frellesvig et al.: 1901.11510, 1907.02000, 2008.04823

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Application to generalized Baikov integrals

We identify

$$\omega = d \log u$$
$$u(z) = \prod_{i} \left[G_{i}(z) \right]^{-\gamma_{i} - \beta_{i} \epsilon}$$

polynomials resulting from integrating over some ISPs

Given a candidate $\varphi(z)$, we can convert it to Feynman integrals using intersection theory, or by generalized IBP relations

 $\varphi(z) = \frac{f(z)}{z_1^{a_1} \cdots z_n^{a_n} G_1^{b_1} \cdots G_m^{b_m}} \bigwedge_{j=1}^n dz_j$

candidates for d-log integrands

Dlapa, Li, Zhang: 2103.04638

The remaining task is to construct enough *n*-forms belonging to H_{ω}^{n} which lead to d-log integrals...



One-loop integrals



$$E \text{ even: } \varphi(z) \sim \left[G(z)\right]^{(E-2)/2} \bigwedge_{i=1}^{E+1} d \log(z_i)$$
$$E \text{ odd: } \varphi(z) \sim \sqrt{G(\mathbf{0})} \left[G(z)\right]^{(E-3)/2} \bigwedge_{i=1}^{E+1} \frac{dz_i}{z_i}$$

Easy to verify that $u(z)\varphi(z)$ takes d-log form

An arbitrary one-loop topology

of independent external momenta: E = n - 1

$$\overline{E})/2-\epsilon$$

A useful relation:

$$\frac{\partial}{\partial x} \log \frac{1 - \sqrt{\frac{x_2(x_1 - x)}{x_1(x_2 - x)}}}{1 + \sqrt{\frac{x_2(x_1 - x)}{x_1(x_2 - x)}}} = \frac{\sqrt{x_1 x_2}}{x\sqrt{(x_1 - x)(x_2 - x)}}$$

i=1



We now turn to multi-loop Baikov integrals

$$F_{a_1,\dots,a_m,0,\dots,0} = \int_{\mathcal{C}} \left[\prod_i \left[G_i(\boldsymbol{z}) \right]^{-\gamma_i - \beta_i \epsilon} \right] \left[\prod_{j=1}^m \frac{dz_j}{z_j^{a_j}} \right] \prod_k dz_k$$



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For simplicity, we first consider maximal cuts

$$F_{a_1,\ldots,a_m,0,\ldots,0}^{m-\text{cut}} = \int_{\mathcal{C}'} \left[\prod_k dz_k \right] \left[\prod_{j=1}^m \oint_{z_j=0} \frac{dz_j}{z_j^{a_j}} \right] \times \prod_i \left[G_i(\boldsymbol{z}) \right]^{-\gamma_i - \beta_i \epsilon}$$



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$$\operatorname{cut} = \operatorname{integrate} \operatorname{out} \operatorname{using} \operatorname{residue}$$

es

We now turn to multi-loop Baikov integrals

$$F_{a_1,\dots,a_m,0,\dots,0} = \int_{\mathcal{C}} \left[\prod_i \left[G_i(\boldsymbol{z}) \right]^{-\gamma_i - \beta_i \epsilon} \right] \left[\prod_{j=1}^m \frac{dz_j}{z_j^{a_j}} \right] \prod_k dz_k$$

For simplicity, we first consider maximal cuts

$$F_{a_1,\ldots,a_m,0,\ldots,0}^{m\text{-cut}} = \int_{\mathcal{C}'} \left[\prod_k dz_k \right] \left[\prod_{j=1}^m \oint_{z_j=0} \frac{dz_j}{z_j^{a_j}} \right] \times \prod_i \left[G_i(\boldsymbol{z}) \right]^{-\gamma_i - \beta_i \epsilon}$$

$$\operatorname{cut} = \operatorname{integrate} \operatorname{out} \operatorname{using} \operatorname{residue}$$

Good things about maximal cuts: > Determines the differential equations up to sub-topologies > Helps to identify whether the integral family involves elliptic integrals

2S

In the simplest cases, only one variable remains under maximal cuts

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$$\frac{1}{c_{i}} \prod_{j=0}^{\nu} (z - c_{j})^{\gamma'_{j}}, \ (i = 1, \dots, \nu)$$

If one of the γ_i 's is a half-integer

$$u(z) = \frac{\mathcal{K}_1^{\epsilon}}{\mathcal{K}_0} \left[(z - c_0)(z - c_0) \right]$$

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 $-c_1)]^{-\gamma_1-\beta_1\epsilon}\prod_{j=1}^{\nu}(z-c_j)^{-\gamma_j'-\beta_j'\epsilon}$ j=2

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 $\hat{\phi}_i(z) = \frac{\mathcal{K}_0}{z - c_i}$

needs to construct ν d-log integrals

$$\hat{\phi}_1(z) = \frac{\mathcal{K}_0}{\left[(z-c_0)(z-c_1)\right]^{1/2-\gamma_1}} \prod_{j=2}^{\nu} (z-c_j)^{\gamma'_j}$$
$$\hat{\phi}_i(z) = \frac{\mathcal{K}_0}{z-c_i} \frac{\sqrt{(c_0-c_i)(c_1-c_i)}}{\left[(z-c_0)(z-c_1)\right]^{1/2-\gamma_1}} \prod_{j=2}^{\nu} (z-c_j)^{\gamma'_j}$$

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It is easy to verify that $u(z)\phi_i(z)$ are d-log integrands

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Beyond these two cases, one expect appearance of elliptic integrals! 22

needs to construct ν d-log integrals

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 $\dim(H_{\omega}) = 2$

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 $\dim(H_a)$

No half-integer powers: ϕ Chen, Jiang, Xu, LLY: 2008.03045

$$\frac{1}{s^2} \left(\frac{t(s+t)}{s^2} \right)^{\epsilon} z^{-1-\epsilon} (s+z)^{\epsilon} (t-z)^{-1-2\epsilon}$$

$$\log(u) = \left(\frac{\epsilon}{s+z} + \frac{1+2\epsilon}{t-z} - \frac{1+\epsilon}{z}\right) dz$$

$$_{\omega}) = 2$$

$$_1 = s^2 z dz$$
, $\phi_2 = s^2 (t - z) dz$



 $\dim(H_a)$

No half-integer powers: ϕ Pick two arbitrary master integ

$$E_1 = F_{1,1,1,1,1,1,0,0}, \quad E_2 = F_{1,2,1,1,1,1,1,0,0}$$



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$$= dz, \quad \langle e_2 | = \frac{1 + 2\varepsilon}{z} dz$$



Check the DEs (on maximal cuts)

$$\frac{\partial}{\partial s} \begin{pmatrix} I_1 \\ I_2 \end{pmatrix} = \epsilon \begin{pmatrix} -\frac{2}{s} & \frac{1}{s+t} \\ \frac{2}{s} & -\frac{s+t}{s+2t} \\ \frac{2}{s} & \frac{s+2t}{s(s+t)} \end{pmatrix} \begin{pmatrix} I_1 \\ I_2 \end{pmatrix}, \quad \frac{\partial}{\partial t} \begin{pmatrix} I_1 \\ I_2 \end{pmatrix} = \epsilon \begin{pmatrix} 0 & -\frac{s}{t(s+t)} \\ -\frac{2}{t} & -\frac{s}{t(s+t)} \end{pmatrix} \begin{pmatrix} I_1 \\ I_2 \end{pmatrix}$$

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Performing the decomposition gives

$$= -\frac{s(1+3\epsilon)}{2\epsilon}E_1 + \frac{st(1+\epsilon)}{2\epsilon(1+2\epsilon)}E_2$$
$$= \frac{s(1+3\epsilon) + 2\epsilon t}{2\epsilon}E_1 - \frac{st(1+\epsilon)}{2\epsilon(1+2\epsilon)}E_2$$

Multivariate construction

In the generic multivariate case, we perform the construction variable-by-variable

Many examples worked out:



But there are still questions to be answered...







 $A^{(1),N_l}$

$$F(x;k) = \int_0^x \frac{dt}{\sqrt{(1-t^2)(1-k^2t^2)}}$$
$$E(x;k) = \int_0^x \frac{\sqrt{1-k^2t^2}}{\sqrt{1-t^2}}$$

What is a good functional basis and how do we organize the calculation?







Elliptic MPLs

A class of functions containing (integrals) of elliptic integrals, and sharing many important features of ordinary MPLs

$$\mathcal{E}_4(\begin{smallmatrix}n_1 \ \dots \ n_k\\ c_1 \ \dots \ c_k\\ ; x, \vec{a}) = \int_0^x$$

Pure functions

$$d\mathscr{E}_4 \sim \sum$$
 (functions wit

Shuffle algebra

 $\mathcal{E}_4(A_1\cdots A_k; x, \vec{a}) \mathcal{E}_4(A_{k+1}\cdots A_{k+1})$

And many more...

How do these functions arise from differential equations?

Broedel et al.: 1809.10698; and many more references

 $dt \Psi_{n_1}(c_1, t, \vec{a}) \mathcal{E}_4(\begin{smallmatrix} n_2 & \dots & n_k \\ c_2 & \dots & c_k \end{smallmatrix}; t, \vec{a})$

th lower weights) \times (one-forms)

$$A_l; x, \vec{a}) = \sum_{\sigma \in \Sigma(k,l)} \mathcal{E}_4(A_{\sigma(1)} \cdots A_{\sigma(k+l)}; x, \vec{a})$$





Elliptic canonical basis

In the elliptic cases, one may still find a basis which satisfy

$$d\vec{f}(z,\epsilon) = \epsilon d$$

See, e.g., Weinzierl: 1912.02578 $dA(z)\vec{f}(z,\epsilon)$ and references therein

where $f(z, \epsilon)$ are non-algebraic combinations of Feynman integrals





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How can we construct such a basis? Our attempt: elliptic d-log forms

Look for combinations of $dK(f_1(z)) \wedge d\log(f_2(z)) \wedge \cdots$ and $dE(f_1(z)) \wedge d\log(f_2(z)) \wedge \cdots$




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Preliminary results for the kite integral



Stay tuned...





Summary and outlook

- Constructive approach to find canonical roots)
- ► Future generalization to elliptic sectors

Constructive approach to find canonical bases for massive integrals (with many square-



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