

2022年第二季度考核

Zeng Hao

Advisor: Joao Guimaraes da Costa

September 2, 2022

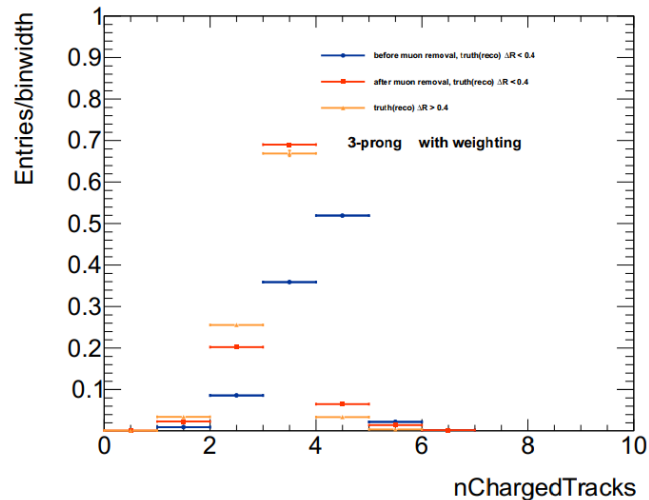
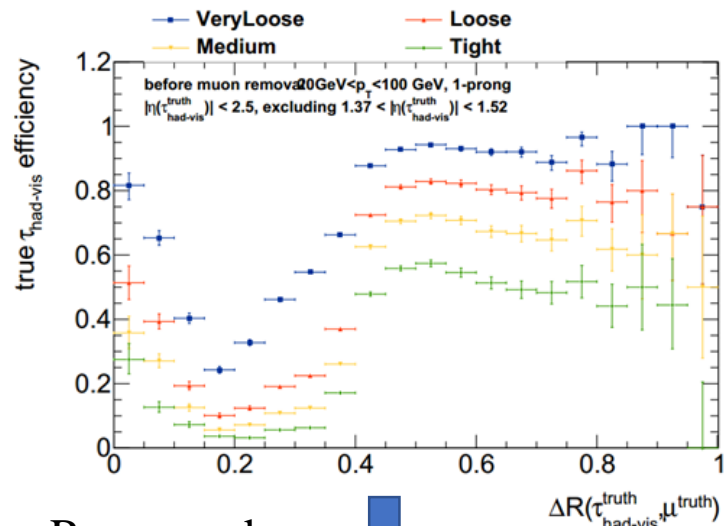
Content

- $H \rightarrow 2a \rightarrow 4\tau$ merged analysis:
 - Validation of the new derivation TAUP6
 - The RNN variables and the tau reco and id efficiency of the muon removal algorithm.
 - TAUP6 DAOD checking in SUSYTool
- Qualification task: HGTD module automation assembly
 - Glue study and assembly exercise
 - Assembled several modules
 - Wrote QT note
- CEPC vertex detector simulation
 - Merged the MOST2 vertex code into official CEPCSW github repository

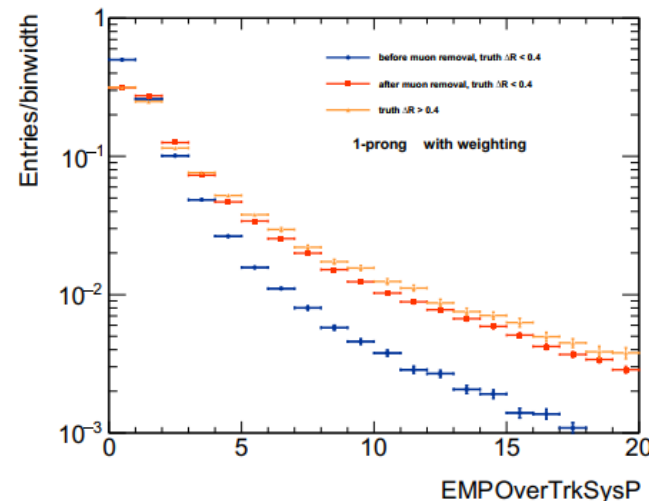
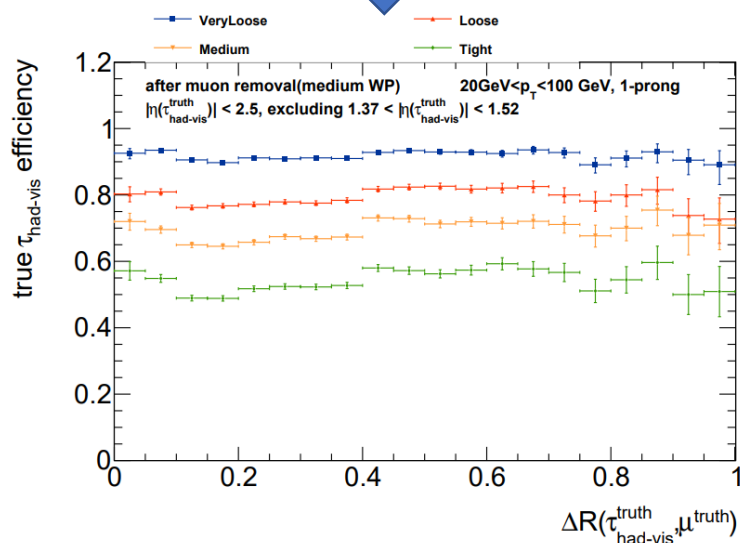
H → 2a → 4tau merged analysis

Identification efficiency study

Id variables distribution



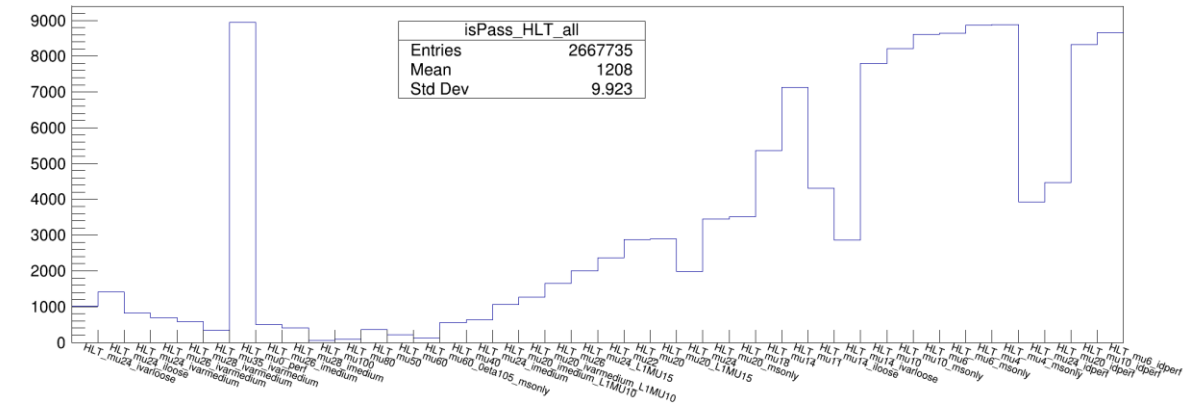
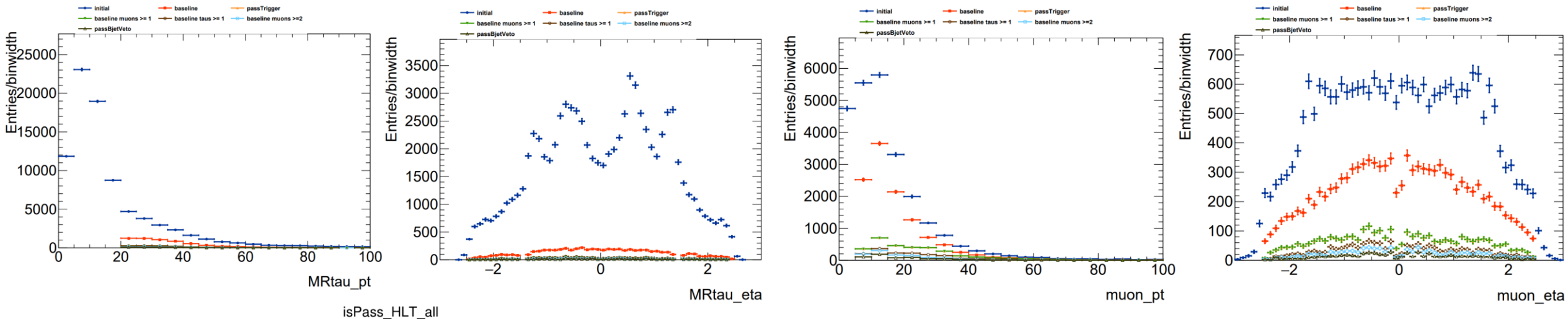
Recovered



- The identification efficiency is not perfect but it is the best we can do and much better than the standard tau algorithm.
- The id variables were back to the good shape as the un-overlapped tau.

H → 2a → 4tau merged analysis

➤ Baseline Objects checking with SUSYTool



TAUP6 as MuHad tau recon & ID

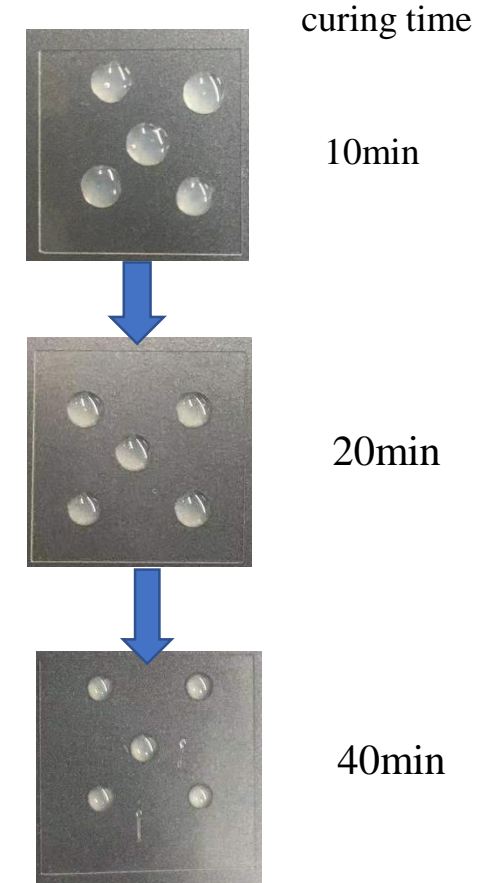
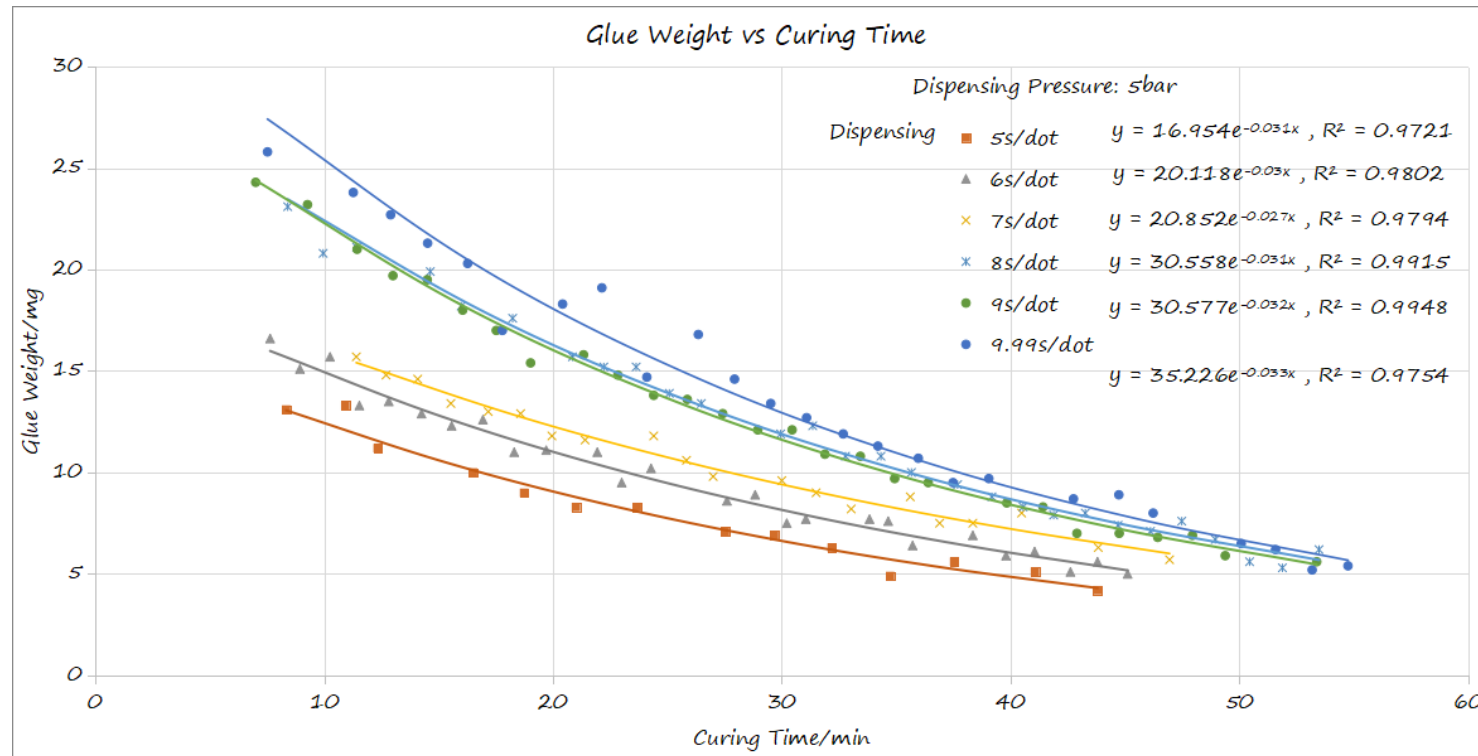
[Open](#) Lianyou Shan requested to merge [lshan/muHadTauDeriv:21.2](#) into [21.2](#) 2 weeks ago

Overview 466 Commits 15 Pipelines 21 Changes 36

- Baseline objects selection and event selection works very well in SUSYTool
- Trigger information was stored in the TAUP6 derivation
- The TAUP6 merging into official repository is on-going by Lianyou.

Qualification task: HGTD module automation assembly

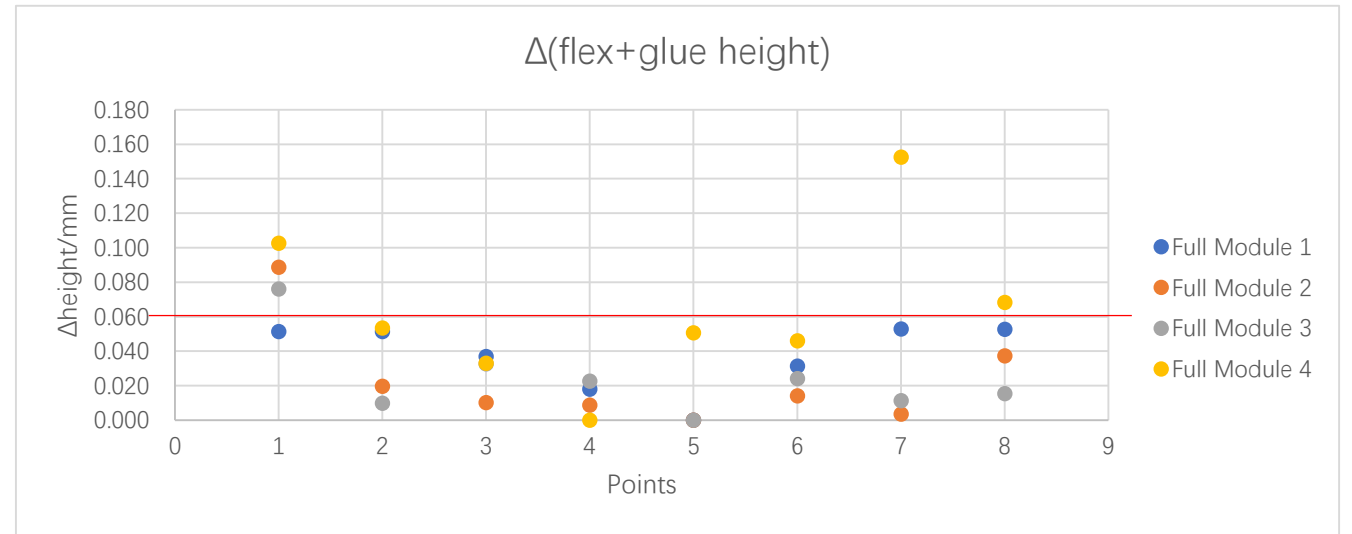
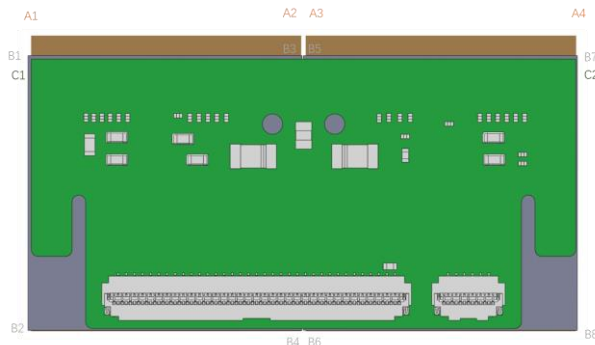
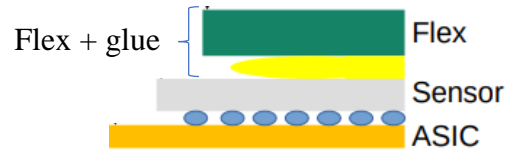
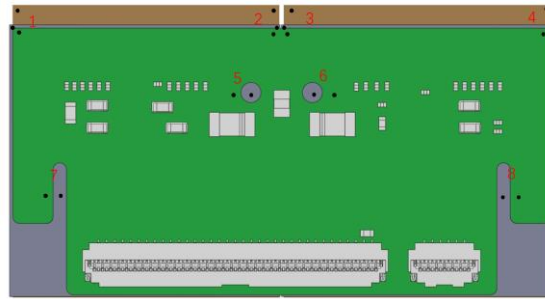
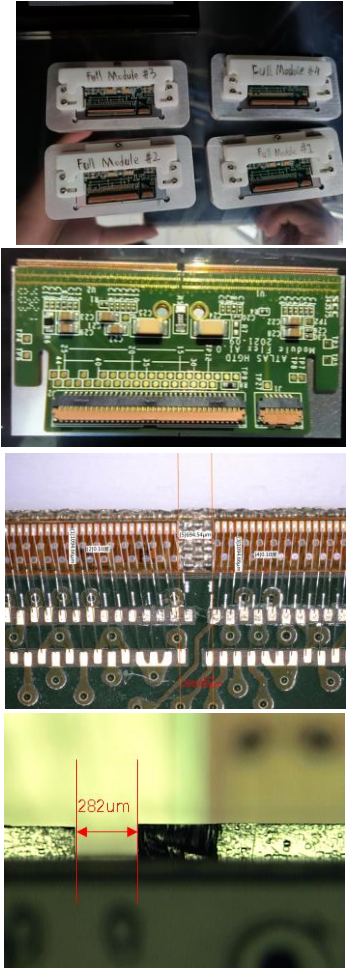
- Glue weight measurement depending on the pressure and curing time has been done using the integration software



- ✓ The glue weight exponentially decreases.
- ✓ We can get the dispensing time for a given curing time, which can be used for glue weight calibration.

Qualification task: HGTD module automation assembly

- Several digital module and full module has been assembled using the gantry and custom tooling
 - Wire-bonding was performed successful
 - The metrology results are very close the specifications



	B3B5(mm)	B4B6(mm)	Nominal gap(um)	Average Δ nominal(um)
Full Module 1	0.215	0.200	280	-72
Full Module 2	0.235	0.311	280	-7
Full Module 3	0.157	0.196	280	-104
Full Module 4	0.282	0.285	280	3

	Full Module 1	Full Module 2	Full Module 3	Full Module 4
Average rotation angle[°]	-0.067	0.128	0.070	-0.182

Qualification task: HGTD module automation assembly

- The qt note draft has been finished
- Summarized almost all HGTD module assembly work at IHEP
 - Hardware and software of the gantry system
 - Module assembly details
 - Preliminary metrology results

Automation Assembly of ATLAS HGTD Modules with Gantry System

Hao Zeng^a, Zhijun Liang^a, Chuanye Wang^b, Xinhui Huang^a, Joao Guimaraes Costa^a

^aInstitute of High Energy Physics, Chinese Academy of Sciences, Beijing, China, ^bNanjing University

This note is the summary of the QT task developing the procedures of positioning and gluing steps in HGTD module assembly. This note also summaries the hardware and software of the automation HGTD module assembly at IHEP. The gantry system, the custom tools and the C++ Qt program to control the gantry system is introduced in this note. The automation HGTD module assembly procedures and the semi-automated HGTD module assembly trials are presented in this note. Several digital modules and real modules were assembled with this gantry system and those custom tools. The metrology results of those modules is shown in this note.

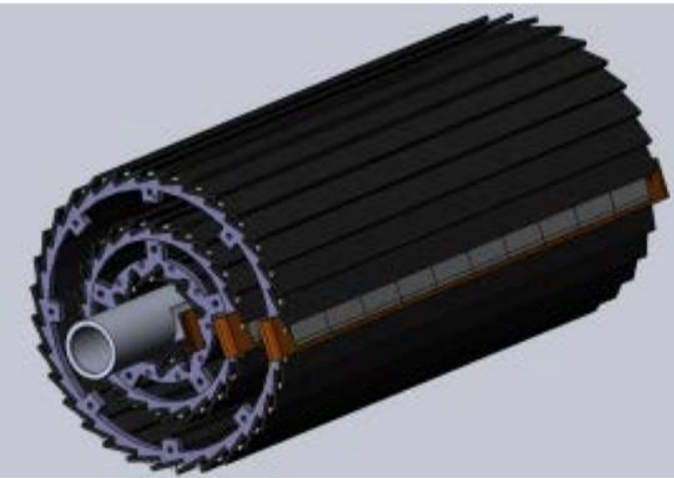
17 Contents

18	1 Introduction	3
19	2 Hardware for ATLAS HGTD Automated Module Assembly	6
20	2.1 Coretech Gantry Positioning System	6
21	2.2 Keyence vision system	8
22	2.3 Nordson EFD Glue Dispensing controller	9
23	2.4 Customized tools	9
24	3 Software for ATLAS HGTD Automated Module Assembly	15
25	3.1 Main GUI of Gantry System Controller	15
26	3.2 Camera coordinate calibration	16
27	3.3 Pick and release parameters	16
28	3.4 Dispensing settings	18
29	3.5 Module assembly workflow setting	20
30	4 ATLAS HGTD Module Assembly Procedures	21
31	4.1 Automation HGTD module assembly procedure concept	21
32	4.2 Semi-automation HGTD module assembly procedures	22
33	4.2.1 Manual alignment	23
34	4.2.2 Gluing calibration	23
35	4.2.3 Automation glue dispensing and module components pick-and-place	25
36	4.2.4 Study on glue pattern and glue weight	25
37	5 The modules assembled using gantry system at IHEP	31
38	5.1 The assembled digital modules	31
39	5.2 The assembled full modules	32
40	5.2.1 The result of module dimension	33
41	5.2.2 The gap between two bare modules	35
42	5.2.3 The rotation between module flex and bare modules	36
43	5.2.4 The module planarity	36
44	6 Summary and Outlook	39

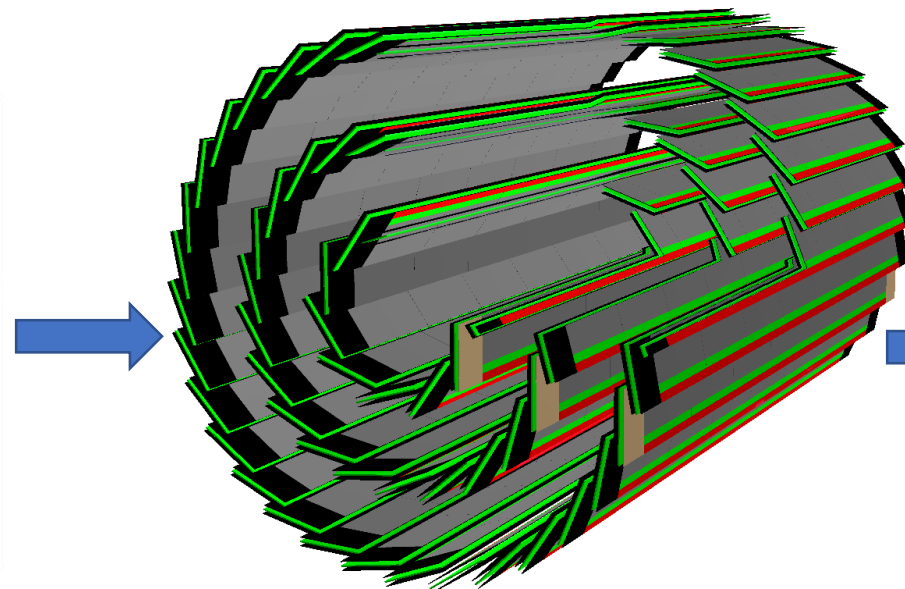
CEPC vertex detector simulation

- The MOST2 vertex geometry and ladder were implemented into the CEPCSW framework.
- Code was reviewed by Chendong and merged into the official CEPCSW github repository.
- The code could be used for MOST2 vertex prototype test beam simulation

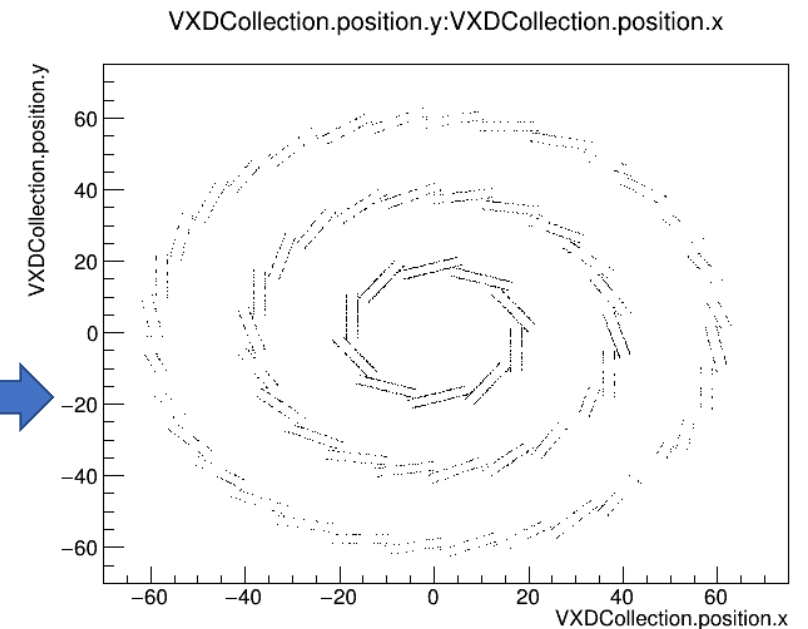
Merged mirgquest merged 10 commits into `cepc:master` from `zenghaozhu:master`



Mechanical design



Geometry (only barrel)



Simulation hits distribution

Summary

- $H \rightarrow 2a \rightarrow 4\tau$ merged analysis:
 - Validation for the new derivation TAUP6 is almost done
 - The RNN variables distribution after muon removal are in very good shape
 - The tau reco and id efficiency was recovered after removing the muon and re-run the standard tau algorithm.
 - TAUP6 is running in the SUSYTool very successful
 - The new derivation was accepted by the tau CP people
 - merging the code into the official repository
- Qualification task: HGTD module automation assembly
 - Several modules have been assembled and tested
 - QT note draft has been written
- CEPC vertex detector simulation
 - The MOST2 vertex geometry and ladder design was merged into CEPCSW github repository
- Next
 - $H \rightarrow 2a \rightarrow 4\tau$ merged analysis:
 - Merging the code and official production (Lianyou Shan)
 - Produce DAOD (data, MC) privately
 - Regions, selections study
 - Qualification task: HGTD module automation assembly
 - Final report
 - Technical Supervisor approval
 - Continue part-time work
 - CEPC vertex detector simulation
 - Help with the test beam geometry simulation

$H \rightarrow 2a \rightarrow 4\tau$ merged analysis

- $H \rightarrow 2a \rightarrow 4\tau$: a mass range 4~15 GeV
 - Boosted a decays into two merged tau
 - Only consider “had-mu” merged case: $\Delta R(\mu, \tau_{had}) < 0.4$.
- Dedicated had-mu di-tau tagger has been developed
 - Measuring efficiency in data is still difficult (no enough Upsilon)
- Moving to the muon removal method
 - Tracks which satisfy “Medium” muon ID working point were removed from the reconstructed τ_{jet} candidates at the xAOD level (R21).
 - Muon tracks and associated clusters will be removed
 - Relevant tau ID variables were re-calculated after muon removed.
- The muon removal method was implemented in a new derivation TAUP6 for the 4τ merged analysis

