MicroTCA for photon science experiments

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- Introduction PETRA.IV
- Possible applications of MTCA.4
 - Data acquisition for energy dispersive detectors
 - Motion control



Beamline P24

- Chemical crystallography beamline, PETRA extension
- 2 Experimental stations at 84m and 90m
- Optical elements at $55 \pm 5m$



P24 under construction (in early 2017)



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PETRA IV

Upgrade of PETRA III to a diffraction limited storage ring:



PETRA IV

a) single electron



single-electron emission cone (X-ray energy dependent)





c) PETRA IV electron bunch



divergence and size of electron bunches comparable to single-electron emission cone

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PETRA IV

Design lattice:

Hybrid 7 Bend Achromat (H7BA)

adopted from ESRF-EBS



On-Axis Injection using fast kickers

Optimised insertion devices in long straight sections

Main Parameters:

Design Parameters	high brightness	timing
Energy [GeV]	6	
Circumference [m]	2304	
Emittance (hor./vert.) [pm rad]	< 20 / 4	< 50 / 10
Total current [mA]	200	80
Number of Bunches	1600 = 80 x 20	80
Bunch population [10 ¹⁰]	0.6	4.8
Bunch separation [ns]	4 + gaps (20)	96

C. G. Schroer, et al., JSR 25, 1277 (2018).



PETRA IV - The Ultimate 3D X-ray Microscope

Imaging of disordered samples with molecular resolution:



Images: O. Seeck, C. Schroer

Petra IV will need:

- Real time data processing, data reduction
- Fast feedback systems, e.g. for beam stabilization
- Fast, efficient data acquisition
- ► On-the-fly scanning ⇒ modern motion control with fast synchronization

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Upgrade of control and data acquisition electronics



PETRA III VME and NIM



Beam position monitor,



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Struck SIS8300 with Gamma Firmware



122eV FWHM at 5.4keV, shaping time 560ns

Developed in collaboration with DESY-MSK, Jan Timm



Improvements of Gamma firmware

PhD thesis of Sarmad Adeel:



- Faster filtering algorithms, shaping times <300ns, FWHM <155eV</p>
- Support of SIS8300-KU with new MSK firmware framework (in progress...)

Motion control: Four circle diffractometer at P24



- Everything is motorized!
- Synchronous motion
- ► Scan speed 10°/s
- Synchronization of Detectors with µs precision



Motion control: Current PETRA III solution



VME based motion controller (OMS MAXv):



- Phytron ZMX motor drivers in home made crates
- 2 OMS cards per ZMX crate (16 motors) needed
- Synchronization and on-the-fly scans limited





The PETRA IV solution based on MTCA.4

- 16 axes per card
- Synchronization of many cards
- Triggering via MLVDS
- Compatible with ZMX
- Support of modern drivers via EtherCAT, Sercos...
- Compatible with existing software
- Prototype will be ready soon!



Conclusion

Old VME electronics can be replaced by MTCA:

- Different types of ADCs are available
- Photon counting
- Motor controller is in development
- ▶ Much more: Camera interface, GPIO, DACs, Piezo controller, beam stabilization...

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