

# Ongoing development on LGAD

MEI ZHAO

IHEP, BEIJING, NOV 8TH, 2021

## outline



### Development of standard LGAD

Introduction of standard LGAD

Ongoing development of standard LGAD for HL-LHC

Development of IHEP LGAD sensors

### Development of AC-LGAD

AC-LGAD vs standard LGAD

Performance of AC-LGAD

Performance of IHEP AC-LGAD Us

e AC-LGAD for CEPC

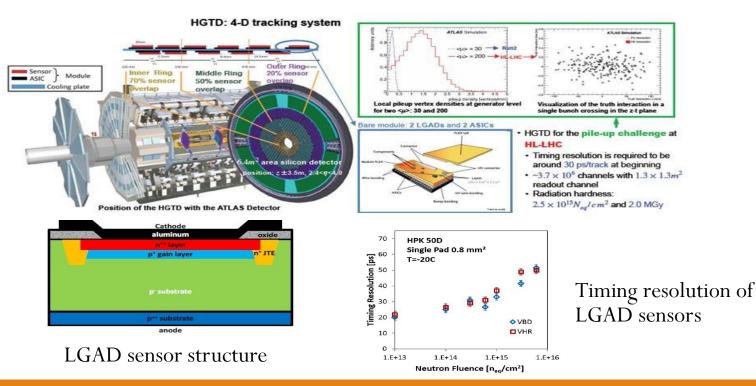
### Summary

# LGAD-timing detector

Low Gain Avalanche Detectors(LGAD) is an avalanche PN diode which work below breakdown voltage(liner mode) and with Gain >10 for effectively charge collection. Results show LGAD sensors have timing resolution better than 50ps.

Because of its good timing performance, LGAD has been chosen as sensors for tracking timing detectors, including ATLAS High Granularity Timing Detector (HGTD) project and CMS Endcap

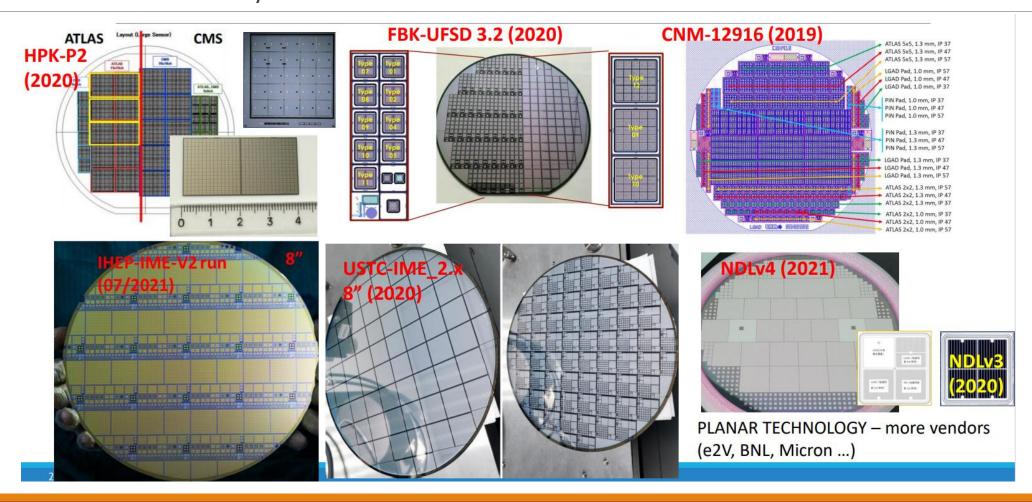
Timing Layer (ETL).





# LGAD-timing detector

Many semiconductor producers and institutes (HPK\FBK\CNM\IHEP\USTC\NDL\BNL) have done researched of LGAD for years





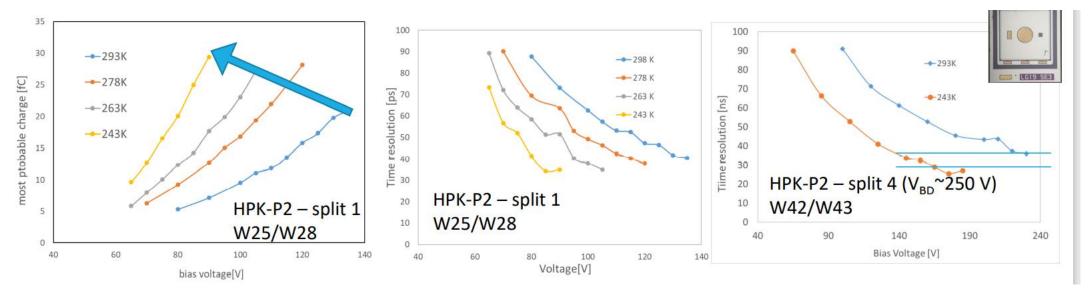


The key property is collection of 4 (ATLAS) /5 (CMS) fC at safe operation voltage over the entire lifetime of the experiments (2.5e15 cm<sup>-2</sup>).

The timing resolution of many sensors all be lower than 50ps and can collect 4fC charge before irradiation.

Breakdown voltages at -30°C are much lower than at room temperature (50-80 V)

Small difference in doping concentration results in very different performance

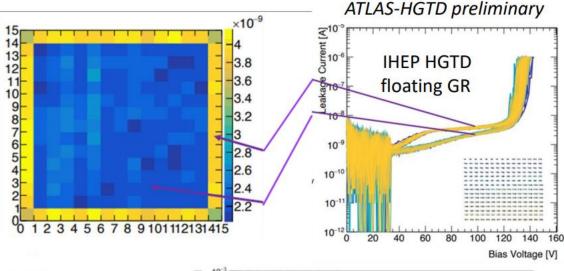


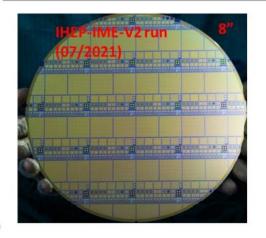


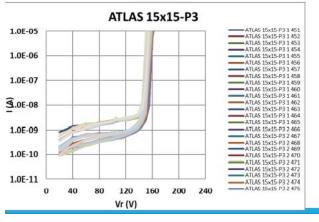
## Full size devices

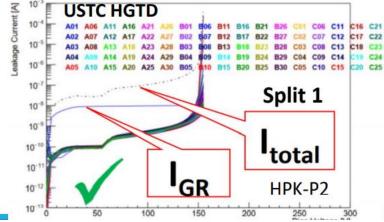
The production of uniform gain layer on large devices has been shown for several vendors.

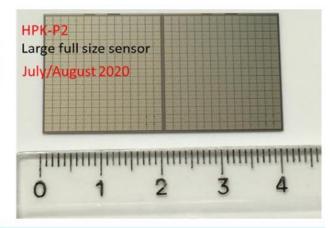
More information on IMEv2 at the coming RD50 workshop.









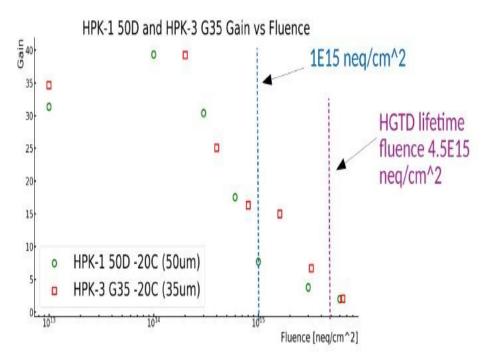


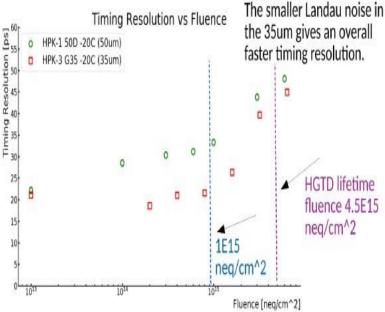
## Performance of LGAD



#### After irradiation Issue:

high voltage needed to get enough charge after 2.5e15 n irradiation was large than 600V; mortality problem during beam testing.





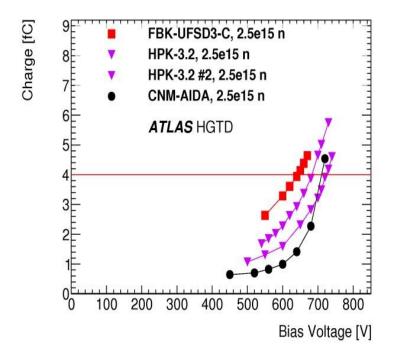
Gain decreases and timing performance change worse as increasing the irradiation fluence



## Performance of LGAD

Higher than 600V voltage for 4fC charges (higher electrical field)

It is observed that destructive breakdowns of sensors at very high bias voltage ~600+/-50V for 50um thick detectors in the test beam





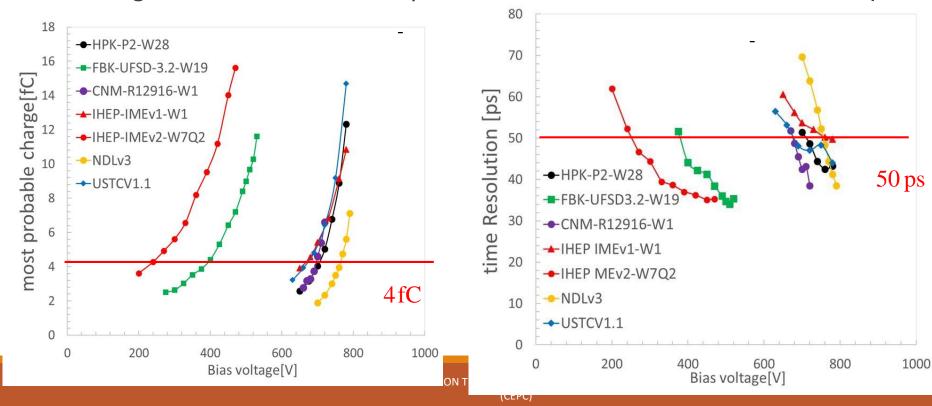


## Performance of LGAD

Recent results of LGAD after neutron irradiation of 2.5e15  $n_{eq}$ /cm<sup>2</sup>

FBK and IHEP-IMEv2 sensors can collected 4fC at voltage <600V and timing resolution also be lower than 50ps

Beam testing of these sensors recently been done at CERN to check the mortality issues

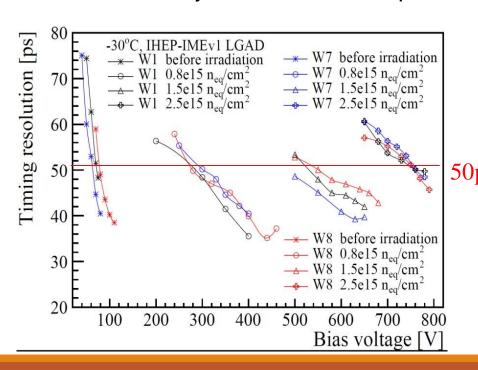


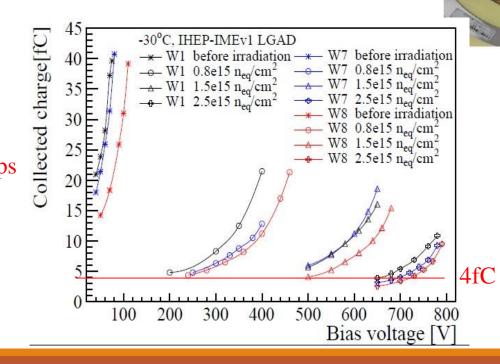


# Development of IHEP LGAD sensors

### IHEP-IMEv1

8 inch wafers with 50um EPI layer were used Submit at May 2020, finish at Sept, 2020







# Development of IHEP LGAD sensors

### • IHEP-IMEv2

8 inch wafers with 50um EPI layer Submit at Jan 2021, finish at April, 2021

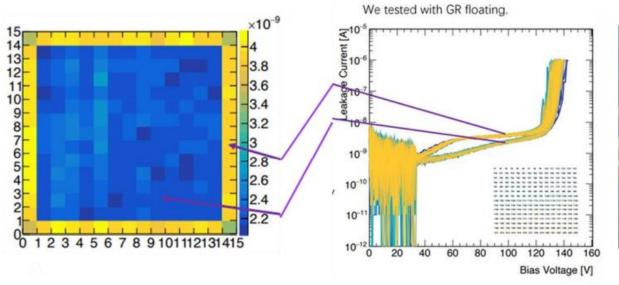
- Add 15x15 sensor array
- Carbon injection to improve irradiation hardness

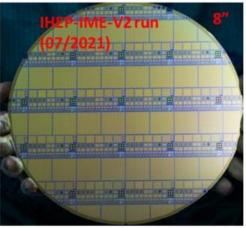
#### Wafer 4: fast annealing

· carbon dose: 0.2 units, 1 unit, 5 units, 10 units

#### Wafer 7 and 8: long time annealing

- carbon dose: 0.2 units, 0.5 units, 1 unit, 2 units (W7
- carbon dose: 3 units, 6 units, 8 units, 10 units (W8)



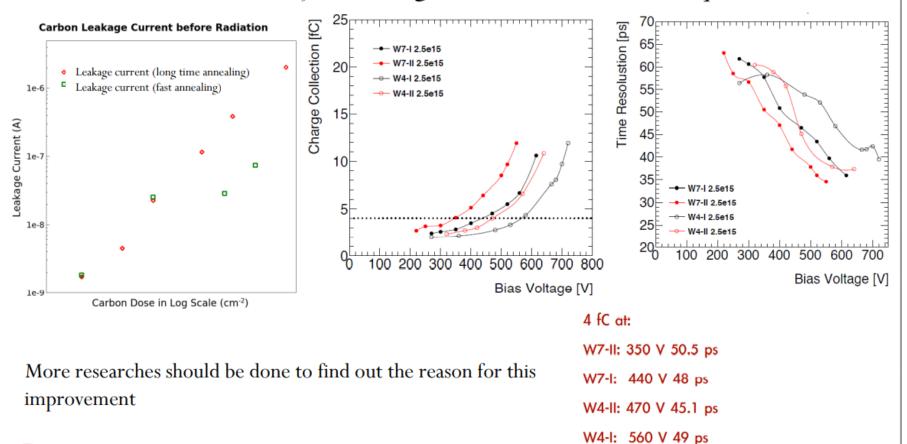


Good uniformity for large size sensors

# Development of IHEP LGAD sensors



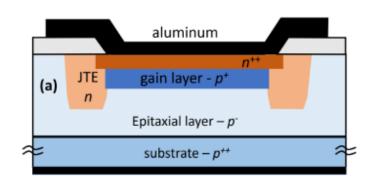
- Leakage current increases as increasing carbon dose
- After irradiation, the sensor can collected 4fC charge at voltage <400V(around 700V for IHEP-IMEv1), the timing resolution is better than 50ps

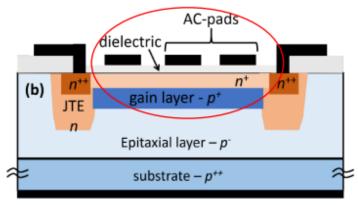


## Standard LGAD vs AC-LGAD



- Set AC coupling capacitor inside the sensor active region,
- ◆ Collected charge from each electrode of coupling capacitor is related with particle injection position.





#### Standard-LGAD

- The DC readout electrode
- Time resolution ~ 35ps
- Position resolution: sensor size
- Dead zone: JTE, Pstop, 50~100um

#### AC-LGAD

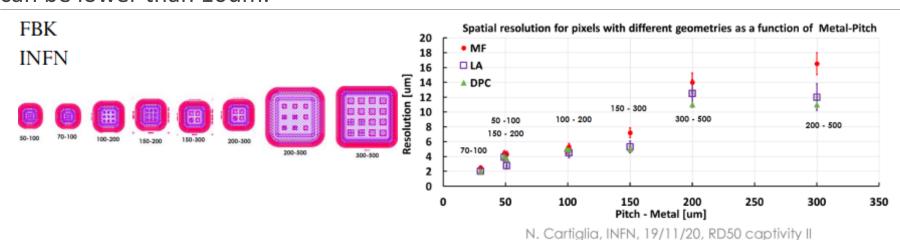
- AC coupled readout electrode
  Signal AC-coupled through dielectric to metal pads
- Time resolution ~ 35ps
- Position resolution: 5-50 um
- Dead zone : 0 mm (no dead zone)

<sup>#</sup>Gabriele D'Amen et al., Electrical and timing performance of AC-LGADs, 37th RD50 Workshop, Zagred, online, 2020.

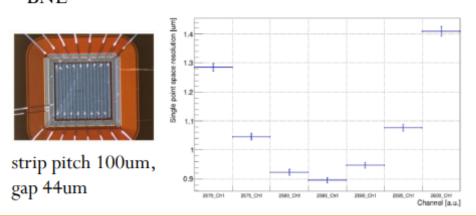


# Development of AC-LGAD

BNL、FBK、IHEP etc. have done research on AC-LGAD(RSD), the spatial resolution of this sensor can be lower than 10um.



BNL



AC-LGAD's time resolution~26ps Spatial resolution of ~1um achievable using two strips near the laser focus point

Results obtained in collaboration with FNAL using 120 GeV proton beam show excellent 4D performances for AC-LGADs ( $\sigma_t = 30$  - 35 ps,  $\sigma < 15~\mu \text{m}$ ) and  $\sim 100\%$  detection efficiency

Gabriele D'Amen1, PSD12 2021

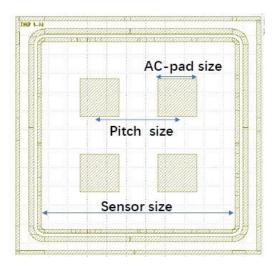


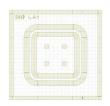
## AC-LGAD sensors developed by IHEP

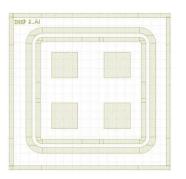
### IHEP AC-LGAD first batch:

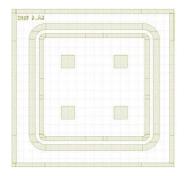
### Sensors with different pad-pitch size

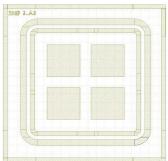
Sensors	Sensor size [µm]	AC-pad size [μm]	Picth size [μm]
1-A7	1000	100	450
2-A2	2000	300	1200
2-A1	2000	600	1200
2-A3	2000	750	1000
4-A1	4000	1000	2000







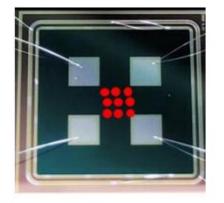


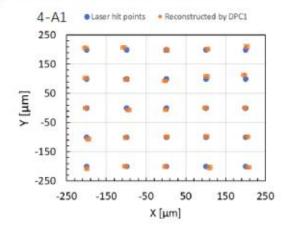




## AC-LGAD sensors developed by IHEP

hit position vs Reconstructed position (DCP method)

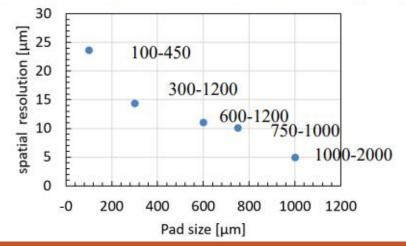




### Spatial resolution:

The standard deviation of the displacement difference between the laser and

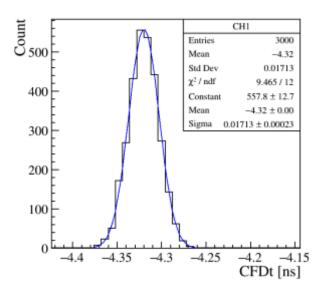
the reconstruction  $(d_L-d_R)$ 





## Timing performance of IHEP AC-LGAD

- The timing resolution is about 15-17 ps (Laser testing)
- Almost no difference for different size of the pads



Sensors	Pad-pitch (µm)	Timing resolution (ps)
1-A7	100-450	15
2-A2	300-1200	16
2-A1	600-1200	17
2-A3	750-1000	17
4-A1	1000-2000	17

From laser test results, the pad size may not affect the time resolution of the AC-LGAD.

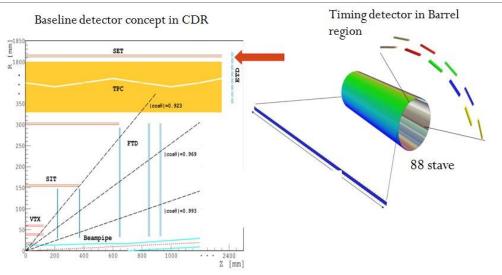
Beam testing should be done to check the real spatial and timing resolution.



## Application of LGAD in CEPC

• AC-LGAD(Time resolution < 50ps, spatial resolution < 10um)

May be used as outer Si tracker for CEPC?



### **Clear the requirement**

area, channels, spatial resolution, timing resolution

### New design for this application

Strip or pixel, pitch-pad size, process parameters for Gain layer

#### New readout board (electric circuit)

less charge and high timing requirement

More Beam testing about timing and spatial performance



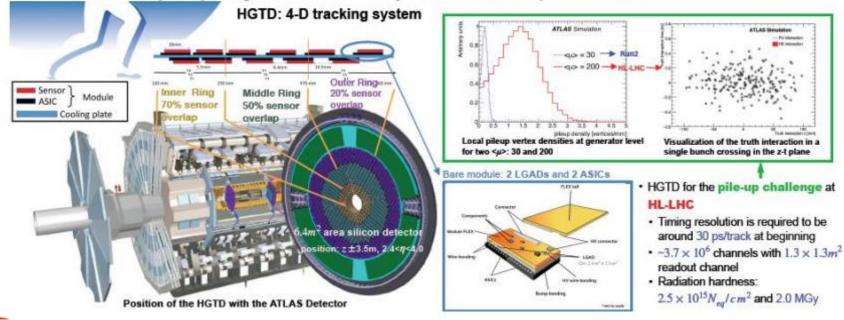
## Summary

◆The recent performance of LGAD sensors, especially the improved post-irradiation performance by changing process for LGAD sensor fabrication including IHEP carbonated LGAD sensors

- ◆ The performance of AC-LGAD sensors designed by different institute show spatial resolution of these sensors can be lower than 10um.
- ◆ Application of AC-LGAD in CEPC also be discussed and we still need do more research for this

## Backup

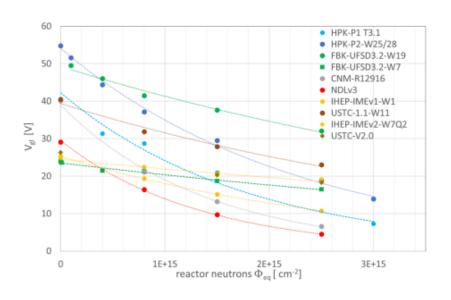
The expected increase of the particle flux at the high luminosity phase of the LHC (HL-LHC) with instantaneous luminosities up to  $L=7.5\times10^{34} cm^{-1} s^{-1}$  will have a severe impact on the ATLAS detector performance. The pile-up is expected to increase on average to 200 interactions per bunch crossing. The reconstruction and trigger performance for electrons, photons as well as jets and transverse missing energy will be severely degraded in the end-cap and forward region, where the liquid Argon based electromagnetic calorimeter has coarser granularity and the inner tracker has poorer momentum resolution compared to the central region. A High Granularity Timing Detector (HGTD) is proposed in front of the liquid Argon end-cap calorimeters for pile-up mitigation and for bunch per bunch luminosity measurements.

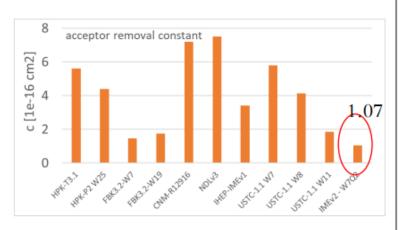




# Backup

 $\bullet~V_{gl}$  change and acceptor removal



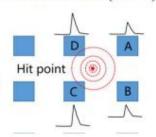


### DPC method

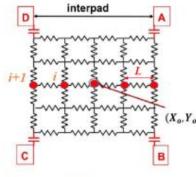
Position reconstruction by Discretized

Positioning Circuit model (DPC)#

\*M. Tornago, et al. Nuclear Inst. and Methods in Physics Research, A 1003 (2021) 165319



Discretized Positioning Circuit model (DPC)



$$X = X_0 + k_x (\frac{q_A + q_B - q_C - q_D}{q_A + q_B + q_C + q_D}) = X_0 + k_x m$$

$$Y = Y_0 + k_y (\frac{q_A + q_D - q_B - q_C}{q_A + q_B + q_C + q_D}) = Y_0 + k_y n$$

$$k_x = L \frac{\sum (m_{i+1} - m_i)}{\sum (m_{i+1} - m_i)^2}$$
  $k_y = L \frac{\sum (n_{i+1} - n_i)}{\sum (n_{i+1} - n_i)^2}$ 

### hit position vs Reconstructed position

