



### **ToF Measurement with Calorimeter Cluster**

Yuzhi Che Manqi Ruan

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### What could cluster TOF resolution be reached in the CEPC baseline?

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### **Motivation**

- Precise Cluster TOF information produces,
  - higher separation power
  - better PFO clustering.

#### TOF measurement improves the reconstruction of basic level objects

An effective k<sup>±</sup>/π<sup>±</sup>/p<sup>±</sup> identification can be achieved with the combined information of dE/dx and TOF (assumed with a 50 ps time resolution).

 Better PFO clustering (cluster fragments identification) can be achieved with the cluster TOF information.



### **Introduction of showers, clusters & hits**

The fundamental information: calorimeter hits

- energy & time distribution at truth level
- Clustering process

Arbor

- Hit collection efficiency
- Detector response: the hit time resolution

Introduction of Cluster Timing

### The fundamental information: calorimeter hits

Single photon/pion samples with energy from 0 to 30 GeV, in the CEPC baseline setup. Choose the 1-1 reconstruction events (where only 1 cluster is reconstructed).



Number of hits in ECAL/HCAL versus MC particle energy. The error bar represents the standard deviation of the hit num. distribution in the corresponding sample.



### Calorimeter provides many hits for a particle shower



Compared to the EM shower, the ECAL hits in the hadronic shower have lower energy and more compact and faster time.

Introduction of Cluster Timing

#### **Clustering algorithm: Arbor**

The PFA Clustering module collects a part of the shower hits into clusters, only which can be used in TOF reconstruction.

On the CEPC, the Arbor algorithm are used to perform the clustering process.

- Clustering ( Calo hit -> Clusters )
  - Links between hits and hits
  - Bushes (Sub-clusters), clusters
- Cluster identification (charged/neutral particle)
  - Cluster & trajectory matching
  - PID

Because of the correlation of the hits time, energy and position, Arbor tends to collect more calorimeter hits with **higher energy** and **faster time**.





#### Cluster TOF measurement is depends on the clustering algorithm



#### Introduction of Cluster Timing



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N. Akchurin, V. Ciriolo, E. Currás, J. Damgov, M. Fernández, C. Gallrapp, L. Gray, A. Junkes, M. Mannelli, K. H. Martin Kwok, P. Meridiani, M. Moll, S. Nourbakhsh, S. Pigazzini, C. Scharf, P. Silva, G. Steinbrueck, T. T. de Fatis, and I. Vila, On the Timing Performance of Thin Planar Silicon Sensors, Nuclear Instruments and Methods in Physics Research Section A: Accelerators, Spectrometers, Detectors and Associated Equipment 859, 31 (2017).

### A basic TOF reconstruction algorithm

Mimic the intrinsic hit resolution in CEPC software

A basic algorithm

- Select the enough fast hits by delay time
- Take an average as the cluster TOF

Performance parameters: bias & resolution

#### Mimic the detector time response at hit level

- Record the truth level ECAL hits time.
- Smear the hits time with a Gaussian distribution,

$$T_{hit}^{reco} = Gaus(\mu, \sigma),$$
  
$$\mu = T_{hit}^{truth},$$

$$\sigma = \sqrt{\left(\frac{A}{\sqrt{2}S}\right)^2 + C^2}$$

where,

S = the energy deposition in the Si diodes, converted to the unit of MIP,

A = the noise terms, assumed to be  $0.38 ns \times MIP$ ,

C = the constant terms, assumed to be 0.01 ns.



#### **Reconstruct the cluster time**

#### Body content of the basic algorithm:

• Define a *Delay time* for every hit,

$$T_{delay}^{reco} = T_{hit}^{reco} - \frac{L_{IP \to hit}}{c},$$

- Sort all of the cluster hits according to the *T<sub>delay</sub>*
- Define a hits number fraction, **R**
- Take the fastest *R* of the hits, calculate the average time,

$$T_{cluster}^{reco} = \frac{1}{N \cdot R} \sum_{N \cdot R} T_{delay}^{reco} \cdot W$$

where,

- $T_{cluster}^{reco}$  = the reconstructed cluster time,
- N = Number of all hits in the cluster,
- R = hits number ratio defined previously,
- W = weight value, fixed to 1 currently.



#### **Performance evaluation**

• Cluster truth TOF,

 $T_{cluster}^{truth} = \min\left\{T_{hit}^{truth} - \frac{L_{IP \to hit}}{c}\right\}$ 

• Time reconstruction bias,

 $\Delta T = Mean \{ T_{cluster}^{reco} - T_{cluster}^{truth} \}$ 

• Time resolution,

 $\boldsymbol{\sigma T} = StdDev\{T_{cluster}^{reco} - T_{cluster}^{truth}\}$ 

- The performance depends on,
  - hits number fraction, *R*,
  - incident particle type and momentum,
  - intrinsic time resolution at hit level.....



Different between the truth cluster TOF and the reconstructed cluster TOF, in the (left) photon clusters sample, and (right) pi+ clusters sample.

The mean value of the above distribution is defined as the **bias**, and the standard deviation is defined as the time **resolution**.

### **Performance @ CEPC basline**

- Default configuration
- Bias & resolution
- Relationship between intrinsic resolution & cluster TOF resolution

### Hits number ratio and energy dependence of cluster timing

Default set up:

- CEPC baseline geometry
- Clustering algorithm, Arbor
- Experimental intrinsic hit time resolution terms
  - $A = 0.38 ns \times MIP$ ,
  - C = 0.01 ns.
- $e^-, \pi^+, k^+, p^+, \gamma$  with 1 ~ 30 GeV momentum.
- Select the events in which only one cluster exists.



### Hits number ratio and energy dependence of cluster timing



#### Time estimator performance vs. incident momentum



(a) Bias vs. incident momentum

(b) Resolution vs. incident momentum

Fix the effective hits number fraction R = 80%

Hadronic shower time resolution: 50 ps ~ 100 ps & EM shower time resolution: 10 ps ~ 30 ps

#### What if the detector is improved?



Scale the intrinsic time resolution curve with a factor:

$$\sigma = factor \cdot \sqrt{\left(\frac{A}{\sqrt{2}S}\right)^2 + C^2}$$

When scale the intrinsic time resolution with factors from 0.1 to 1.5, the cluster TOF resolution changes with significant linearity, especially for EM showers.

### Summary

- Conclusion
  - The dependent factors of cluster TOF reconstruction
  - The performance of the basic algorithm
- Future

### **Cluster TOF measurement by CEPC calorimeter**

- A brief cluster TOF reconstruction algorithm are implemented.
- The performance of a cluster TOF algorithm depends on
  - incident particle type and energy,
  - detector geometry and PFA clustering algorithm,
  - intrinsic hit time resolution, including a noise term A and a constant term C
- At CEPC baseline set up and supported intrinsic hit time resolution (A = 0.38 ns\*MIP, C = 0.01 ns), the performance of the mentioned algorithm are evaluated:
  - for EM showers with 1 to 30 GeV, optimized effective fraction R ~ 0.9, corresponding resolution 10 ~ 30 ps,
  - for hadronic showers with 1 to 30 GeV, optimized effective fraction R ~ 0.9, corresponding resolution ~ 50 ~ 100 ps,
- Good linearity: when the intrinsic time resolution scale by a factor from 0.1 to 1.5, the reconstructed TOF resolution scaled by the same factor.

#### Summary

#### Future

- Optimize the TOF reconstruction algorithm
- Research the scaling behavior of the reconstructed TOF on,
  - the calorimeter cell size
  - the ECAL layer number
- Evaluate the separation power of **charged particles** at different momentum.
  - Deal with the issue of the estimator bias
- Evaluate the **cluster fragments** identification ability of the cluster TOF.
- ... ...





# **Thanks for your attention!**

December, Beijing

## Update 1: The bias & resolution method

- 1. Cut Window:  $V_{median} \pm 5\sigma_{all}$
- 2. Bias = mean
- 3. Resolution = Std Dev



## Update 3: Using HCAL + ECAL information

**Assumption:** The intrinsic time resolution of HCAL gRPC is the same with ECAL Si diodes.  $\sigma_t = \frac{A}{\sqrt{2}E} \oplus C$ , where  $A = 0.38 \text{ ns} \cdot MIP$  and C = 0.01 ns

HCAL information help to reduce the Reco. TOF resolution from ~50 ps to ~20 ps.



## Update 4: Perfect clustering vs. Arbor clustering

Perfect clustering: All of the ECAL & HCAL hits

Arbor clustering: All of the Cluster hits

**Threshold:**  $E_{CaloHit} > 5 \times 10^{-5} \text{ GeV}, E_{SimCalo} > 1 \times 10^{-4} \text{ MIP}, \& T^{truth} > 0.$ 

 $0 \sim 30 \; GeV \, \pi^+$  sample:





Timing performance of the Arbor clustering closes to the perfect situation.

Perfect clustering	Arbor clustering
──── MCP p: 1.0 ~ 2.0 GeV	MCP p: 1.0 ~ 2.0 GeV
MCP p: 2.0 ~ 3.0 GeV	—→— MCP p: 2.0 ~ 3.0 GeV
─── MCP p: 3.0 ~ 4.0 GeV	—→— MCP p: 3.0 ~ 4.0 GeV
─── MCP p: 4.0 ~ 5.0 GeV	—→— MCP p: 4.0 ~ 5.0 GeV
──── MCP p: 5.0 ~ 10.0 GeV	MCP p: 5.0 ~ 10.0 GeV
──── MCP p: 10.0 ~ 15.0 GeV	—→— MCP p: 10.0 ~ 15.0 GeV
──── MCP p: 15.0 ~ 20.0 GeV	—→— MCP p: 15.0 ~ 20.0 GeV
——— MCP p: 20.0 ~ 30.0 GeV	—→— MCP p: 20.0 ~ 30.0 GeV

Legends

## Update 4: Perfect clustering vs. Arbor clustering

Perfect clustering: Only the ECAL hits

Arbor clustering: All of the Cluster hits

**Threshold:**  $E_{CaloHit} > 5 \times 10^{-5} \text{ GeV}, E_{SimCalo} > 1 \times 10^{-4} \text{ MIP}, \& T^{truth} > 0.$ 

 $0 \sim 30 \; GeV \pi^+$  sample:





Resolution vs. hits fraction R

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——— MCP p: 4.0 ~ 5.0 GeV	— — — MCP p: 4.0 ~ 5.0 GeV
—— MCP p: 5.0 ~ 10.0 GeV	— → — MCP p: 5.0 ~ 10.0 GeV
—— MCP p: 10.0 ~ 15.0 GeV	——— MCP p: 10.0 ∼ 15.0 GeV
—— MCP p: 15.0 ~ 20.0 GeV	——— MCP p: 15.0 ~ 20.0 GeV
—— MCP p: 20.0 ~ 30.0 GeV	— → — MCP p: 20.0 ~ 30.0 GeV



### Update 4: Perfect clustering vs. Arbor clustering

The Intrinsic time resolution scale factor = 1

Use ECAL + HCAL hits.





Resolution vs. hits fraction R

Perfect clustering	Arbor clustering
──── MCP p: 1.0 ~ 2.0 GeV	—→— MCP p: 1.0 ~ 2.0 GeV
MCP p: 2.0 ~ 3.0 GeV	—→— MCP p: 2.0 ~ 3.0 GeV
──── MCP p: 3.0 ~ 4.0 GeV	—→— MCP p: 3.0 ~ 4.0 GeV
──── MCP p: 4.0 ~ 5.0 GeV	—→— MCP p: 4.0 ~ 5.0 GeV
──── MCP p: 5.0 ~ 10.0 GeV	— → — MCP p: 5.0 ~ 10.0 GeV
──── MCP p: 10.0 ~ 15.0 GeV	— <b>→</b> — MCP p: 10.0 ~ 15.0 GeV
──── MCP p: 15.0 ~ 20.0 GeV	— <b>→</b> — MCP p: 15.0 ~ 20.0 GeV
MCP p: 20.0 ~ 30.0 GeV	— <b>→</b> — MCP p: 20.0 ~ 30.0 GeV

Legends

#### $0 \sim 30 \; GeV \gamma$ sample: