

Marlin Tracking Software in CEPCSW

**Chengdong FU for CEPC Software Group
IHEP, CAS**

**Joint Workshop of the CEPC Physics, Software and New
Detector Concept**

May 23-25, 2022

Outline

■ Introduction

■ Tracking software

- Tracking tool
- Tracking option

■ Performance study

- Particle gun
- $H \rightarrow \mu\mu$
- Vertex detector
- Non-uniform field
- Background

■ Summary

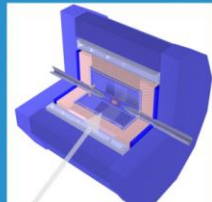
Introduction

Physics process	Measurands	Requirement on tracker
$ZH, Z \rightarrow e^+e^-(\mu^+\mu^-), H \rightarrow \mu^+\mu^-$	$m_H, \sigma(ZH), BR(H \rightarrow \mu^+\mu^-)$	$\Delta(1/p_T) = 2 \times 10^{-5} \oplus \frac{0.001}{p(\text{GeV})\sin^{3/2}\theta}$

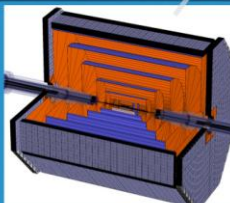
- CEPC being designed as Higgs&Z factory, has basic physics requirements, such as tracking resolution.
- Three detector concepts were designed at CDR stage, and the 4th conceptual detector design has been proposed since 2021.
- Track reconstruction for estimation on detector performance at post age of CDR, exactly as at CDR stage

Particle Flow Approach

Baseline detector
ILD-like
(3 Tesla)

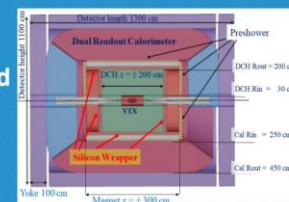


Full silicon tracker concept

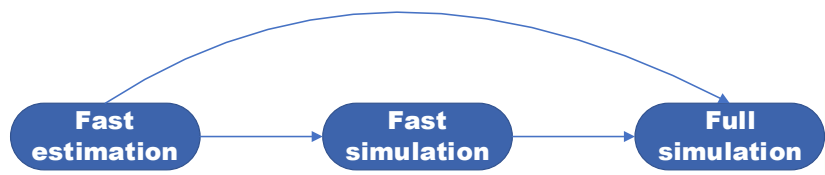


CEPC plans for 2 IPs

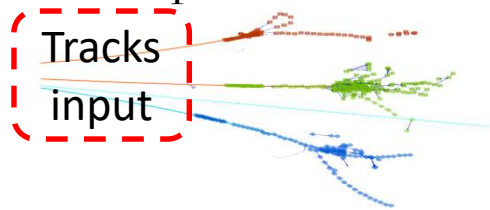
Low magnetic field concept (2 Tesla)



IDEA Concept
also proposed for FCC-ee



- Tracker design: track performance estimation
- As PFA input



Advantage: the HCal absorbers act as part of the magnet return yoke.

Challenges: thin enough not to affect the jet resolution (e.g. BMR); stability.

Advantage: better π^0/γ reconstruction.

Challenges: minimum number of readout channels; compatible with PFA calorimeter; maintain good jet resolution.

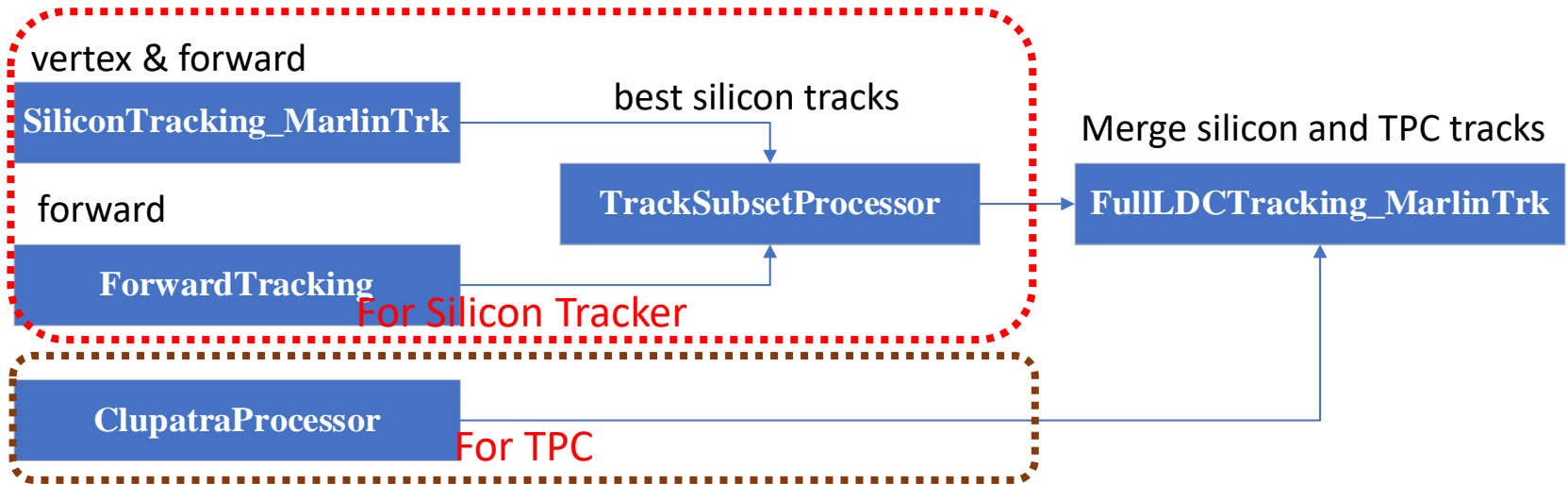
Advantage: Work at high luminosity Z runs

Challenges: sufficient PID power; thin enough not to affect the moment resolution.

History: Tracking for CDR in Marlin

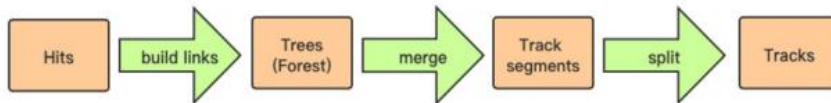
From ILCSOft

- Use different tracking for different trackers, and then merge



Developed inspired by the idea of Arbor

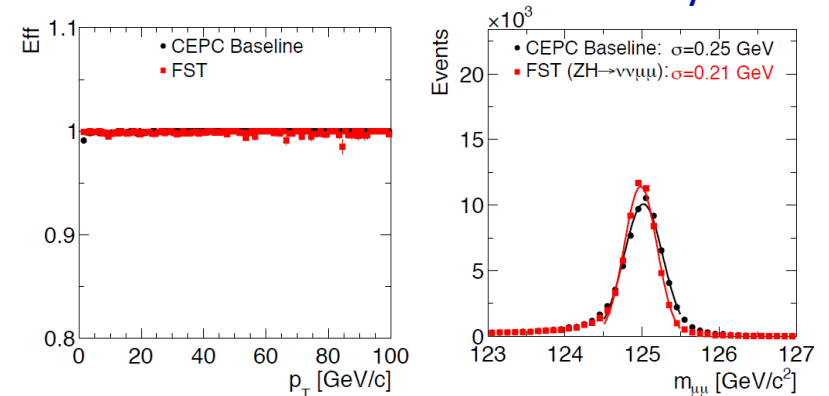
- ArborTracking algorithm



Implement ConformalTracking

- Test for the full silicon tracker (FST) concept

CDR full simulation study



Tracking in CEPCSW

■ CEPCSW

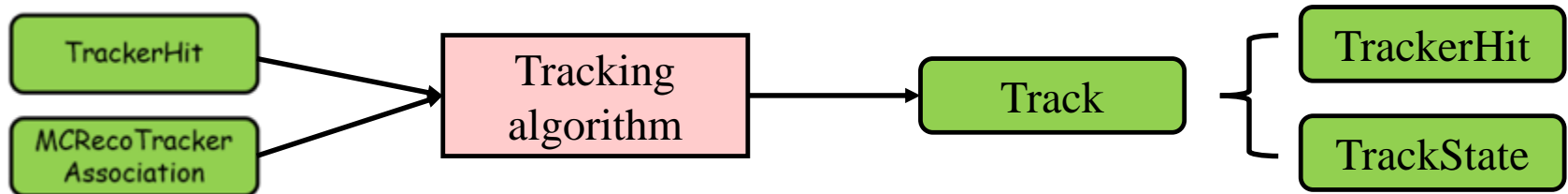
- Core software, Applications, External libraries
- EDM4hep and DD4hep are directly relative with tracking software development.

■ Realize EDM4hep input and output

■ A complete tracking chain same as CDR (Marlin)

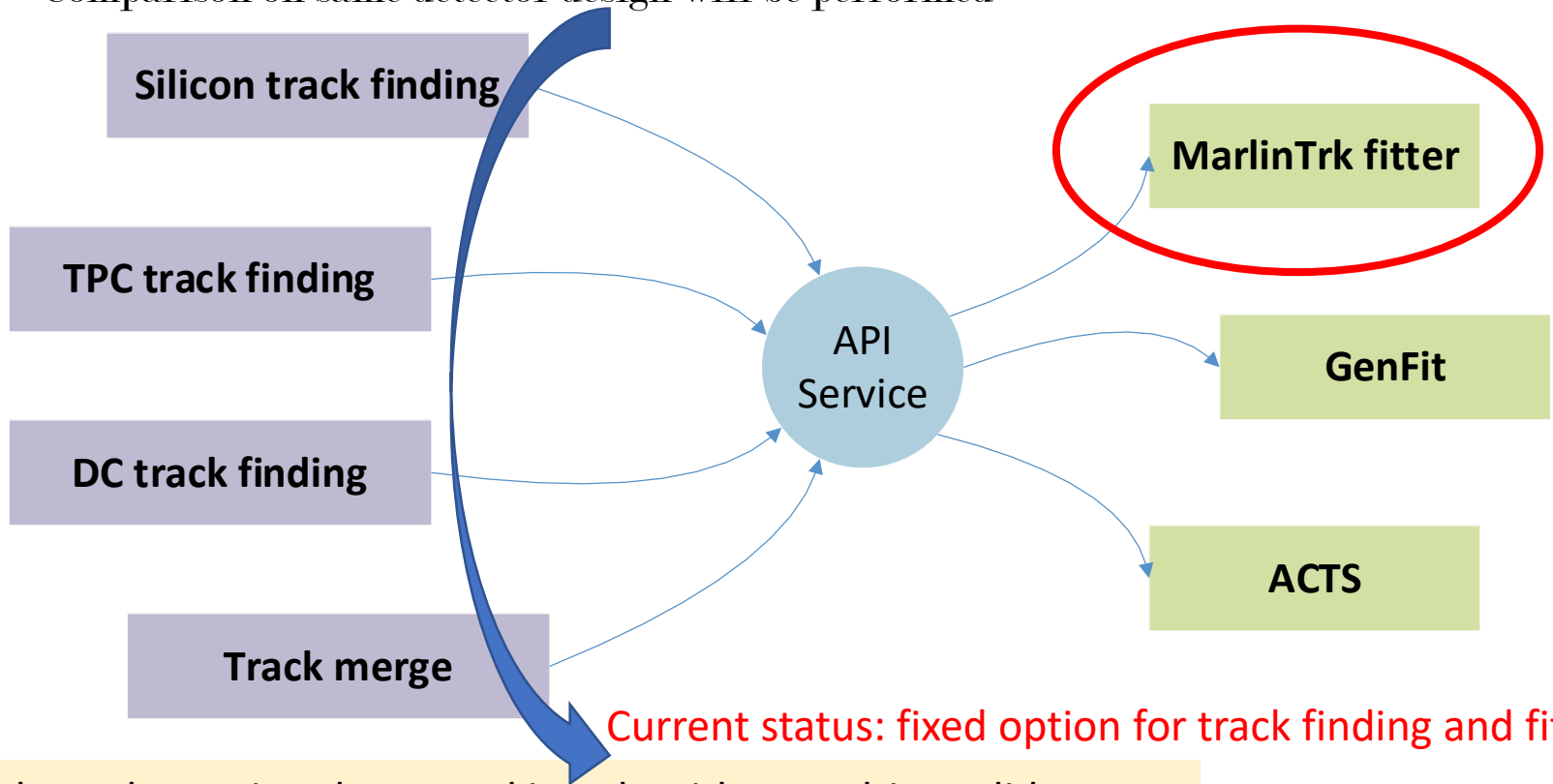
■ GaudiAlgorithm

- initialize() to prepare parameters and services/tools
- execute() to deal with input data (after digitization, edm4hep::TrackerHit)
 - ✓ Create auxiliary objects
 - ✓ Track finding → track candidates
 - ✓ Track fitting → edm4hep::Track (through call fitter interface)
- finalize() to delete auxiliary objects



Propose of Tracking Chain

- Service to call the API of fitter according to option
- Possible to combine differently from track finding to fitting
 - For middle tracking, low CPU time
 - For final tracking, high performance
- Comparison on same detector design will be performed



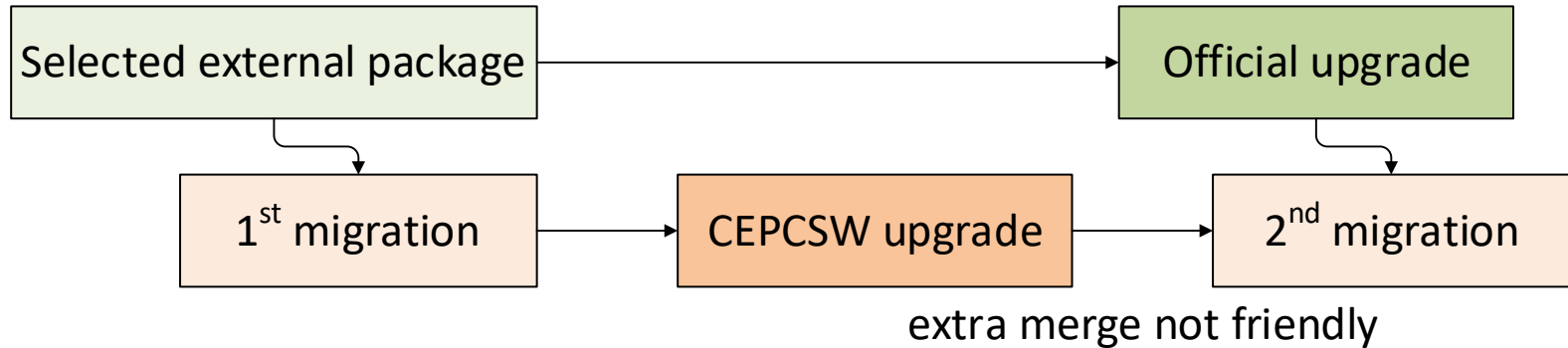
Through running these tracking algorithm, multi-candidates track with different measurement options will be obtained

Migration/Implementation



■ Migrated full tracking chain from **Marlin**

- Switch class to **GaudiAlgorithm**
- Switch data model to **EDM4hep** (first realized)



- **ConformalTracking** migrated into CEPCSW, work well for single particle, more ongoing

■ Another implement way is in considering, to test coversion cost

- Create a GaudiAlgorithm to covert data model and call
 - ✓ EDM4hep→LCIO→call event loop function→LCIO→EDM4hep

■ **Key4hep** (best) in plan

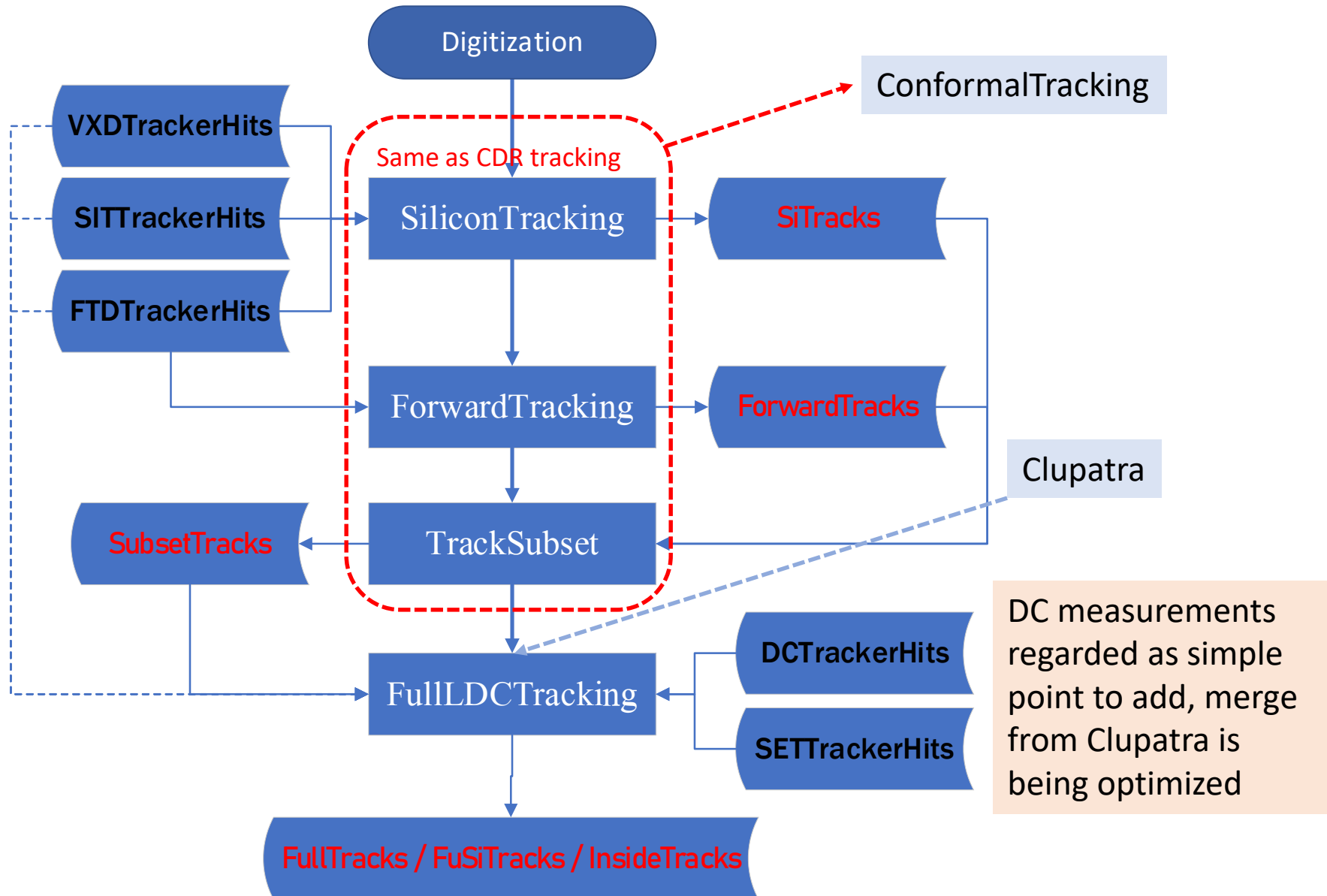
- CallingAlg to call prepared **API**
- event model support with same code is important

Frank Gaede, ECFA

ILD also consider

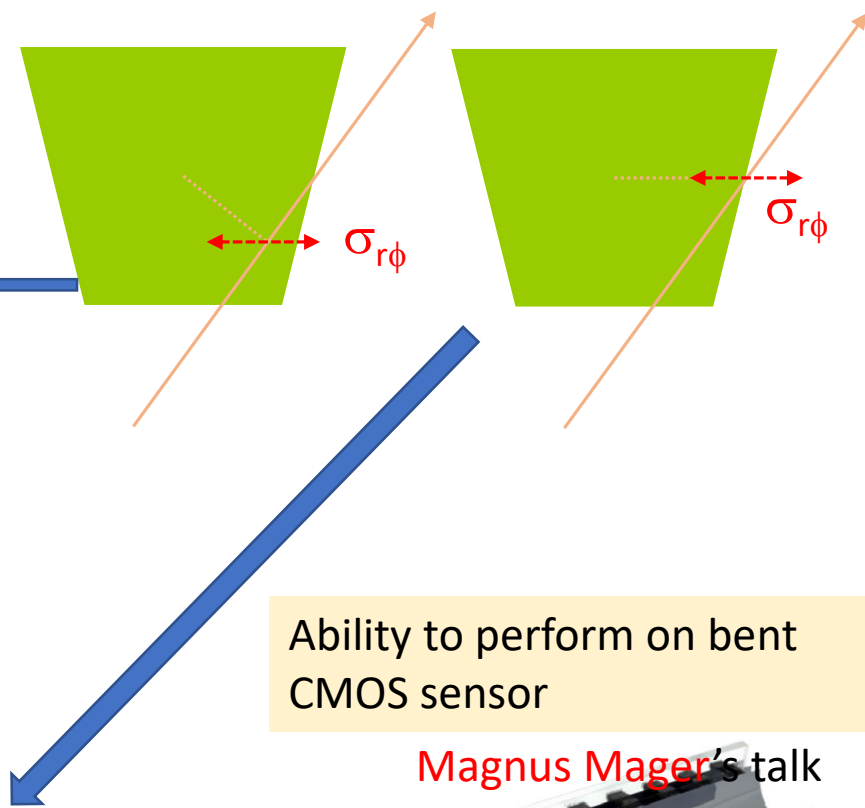
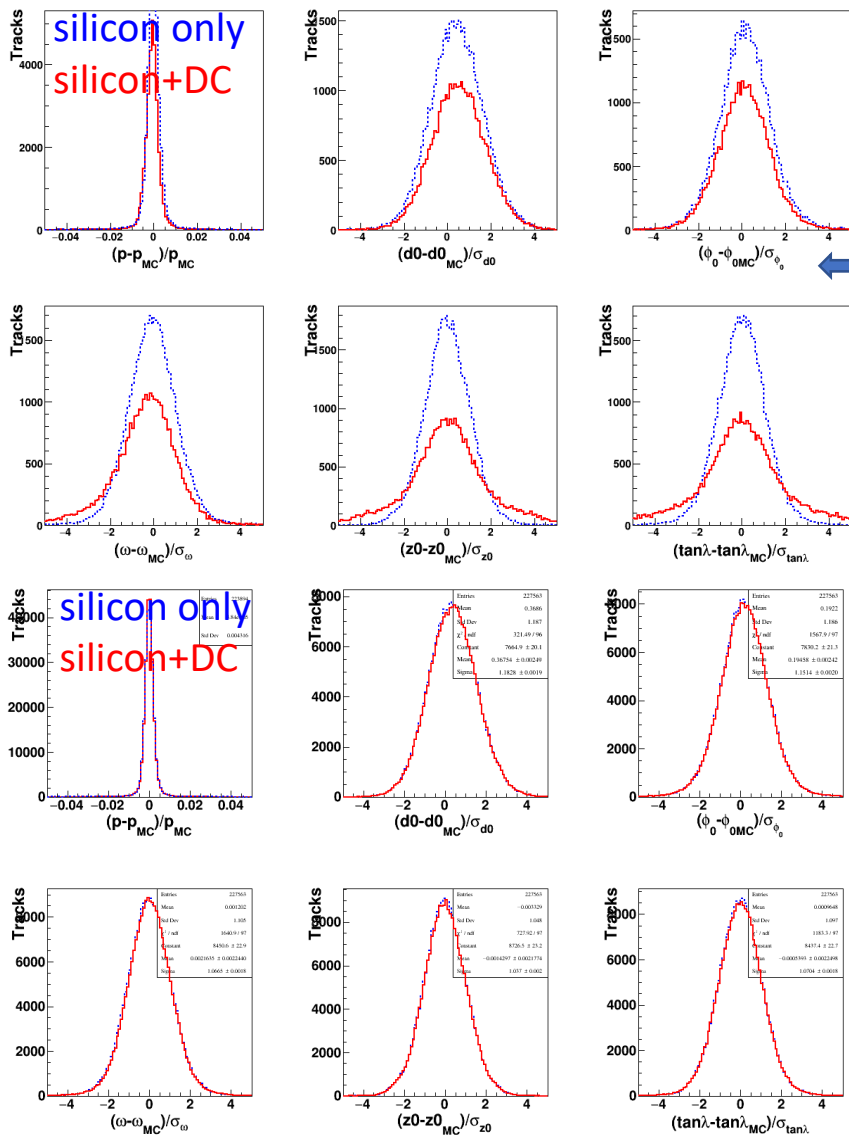
- need to preserve existing pattern recognition tools in transition to Key4hep
 - initially via MarlinWrapper - later via direct ports to Key4hep/EDM4hep

Option for the 4th Conceptual Detector



Simplification of DC Measurement

Work for CylinderMeasLayer

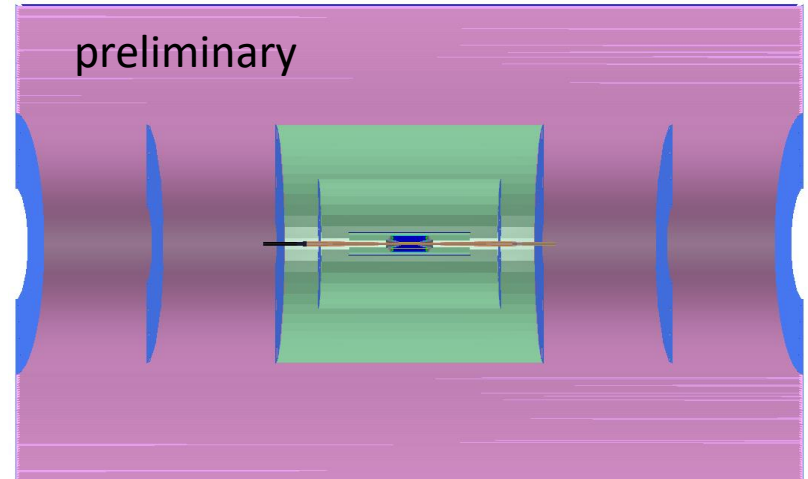
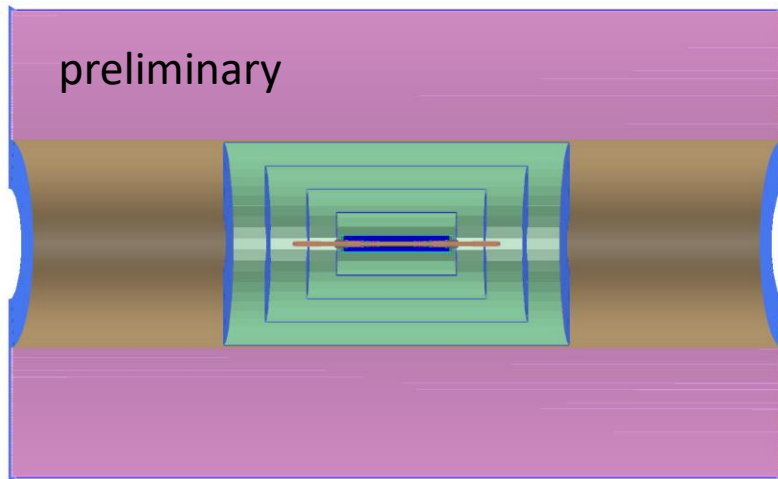


Ability to perform on bent CMOS sensor

Magnus Mager's talk

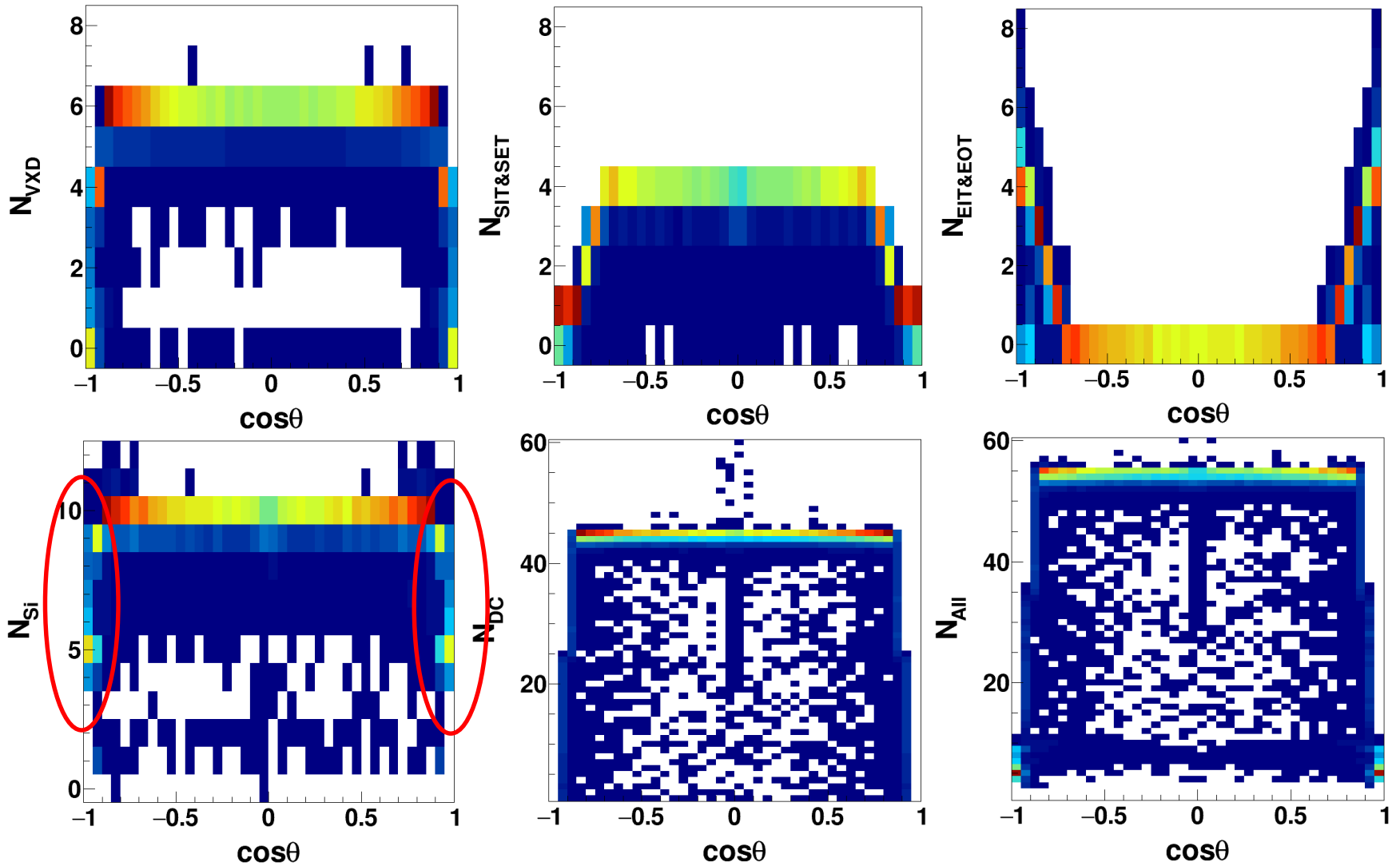


Track System



- **Status:** workable for optional detector concepts
- **Vertex detector (VXD):** 6 pixel layers
 - $\sigma_{r_{\text{phi},z}} = 2.8\mu\text{m}, 6\mu\text{m}, 4\mu\text{m}, 4\mu\text{m}, 4\mu\text{m}, 4\mu\text{m}$
- **Silicon inside/internal DC tracker (SIT):** 4 or 3 pixel layers
 - $\sigma_{r_{\text{phi}}} = 7.2\mu\text{m}, \sigma_z = 86\mu\text{m}$
- **Silicon outside/external DC tracker (SOT/SET):** 1 pixel layer
 - $\sigma_{r_{\text{phi}}} = 7.2\mu\text{m}, \sigma_z = 86\mu\text{m}$
- **Endcap tracker (EIT&EOT/FTD):** 2 + 3 pixel layers
 - $\sigma_{x,y} = 3\mu\text{m}, 3\mu\text{m}, 7.2\mu\text{m}, 7.2\mu\text{m}, 7.2\mu\text{m}$
- **Drift chamber (DC):** 18mm or 10 mm cell size
 - $\sigma_{r_{\text{phi}}} = 100\mu\text{m}, \sigma_z = 2.828\text{mm}$

Hits Number in Fit



■ **Barel:** ~ 10 silicon hits used in fit; **Endcap:** 10 or less, determined by vertex cover range

Efficiency VS Time Cost

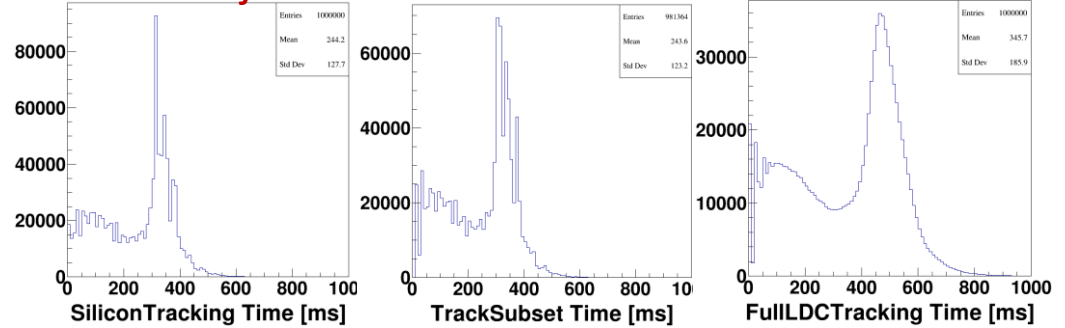
20 particle in each event

- $p \in [2, 50]$ GeV/c
- $\theta \in [40^\circ, 140^\circ]$
- Independent:
($e^+, e^-, \mu^+, \mu^-, \pi^+, \pi^-, K^+, K^-, p^+, p^-$) $\times 2$
- Vertex: (beam parameter @Higgs)
 - ✓ $\sigma_x = 15 \mu\text{m}$
 - ✓ $\sigma_y = 36 \text{nm}$
 - ✓ $\sigma_z = 3.9 \text{mm}$

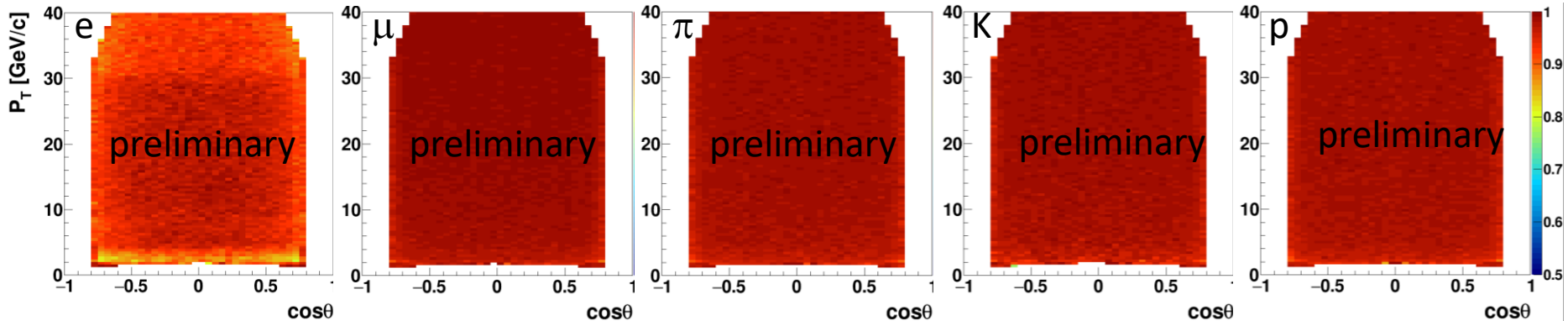
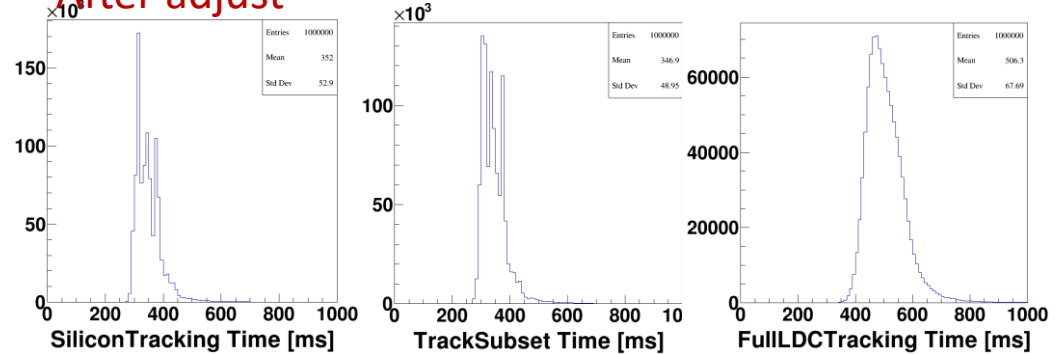
Tracking efficiency

- Match: >50% of hits shares between MC truth and tracks
- Improve through adjust pattern recognition

Before adjust



After adjust



Resolution of Higgs Mass ($H \rightarrow \mu\mu$)

DC600-1800:18mm

DC800-1800:18mm

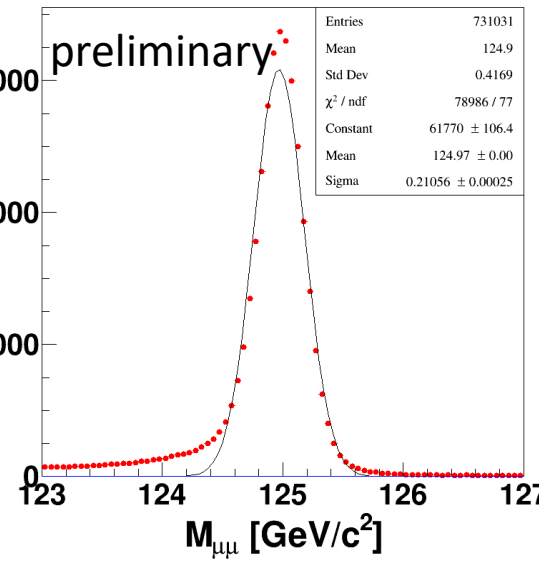
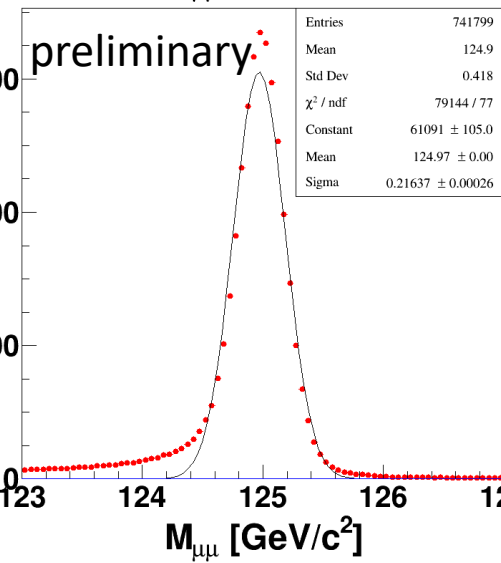
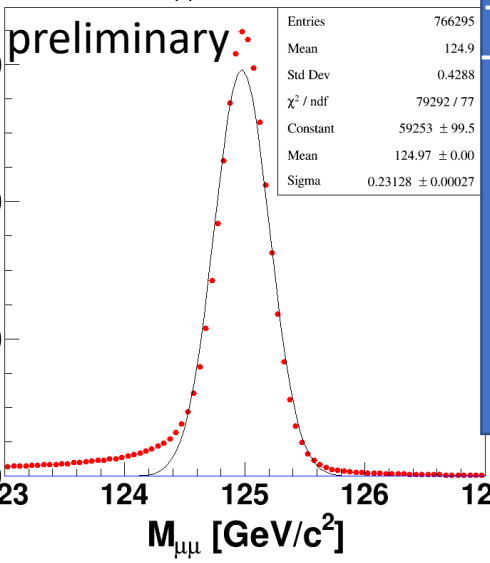
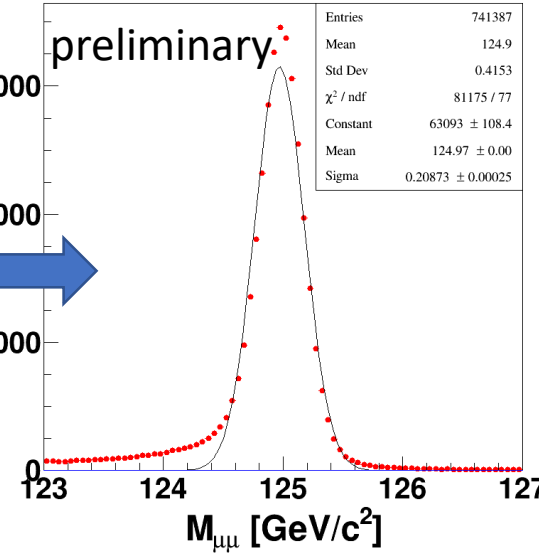
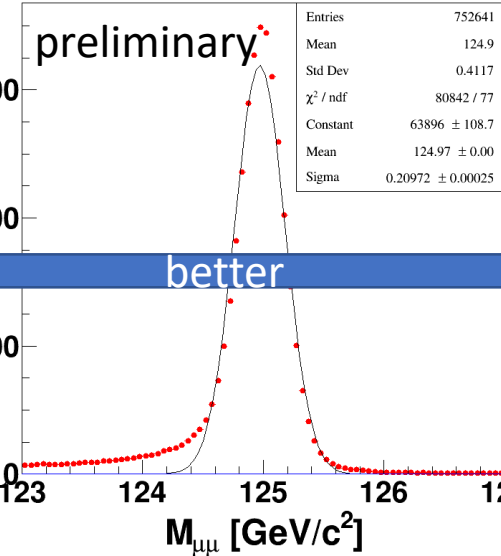
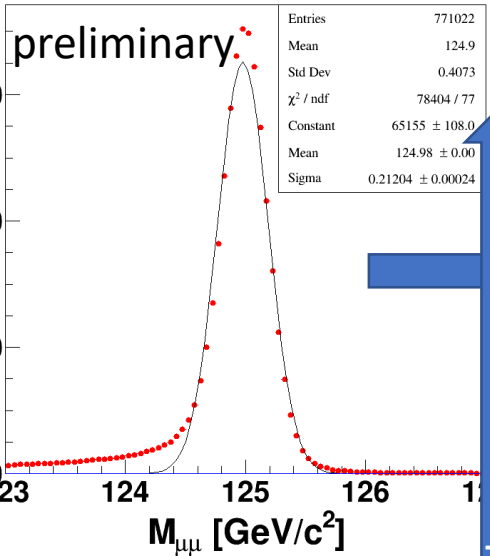
DC1000-1800:18mm

with DC hits

wo DC hits, but with DC material

better

better



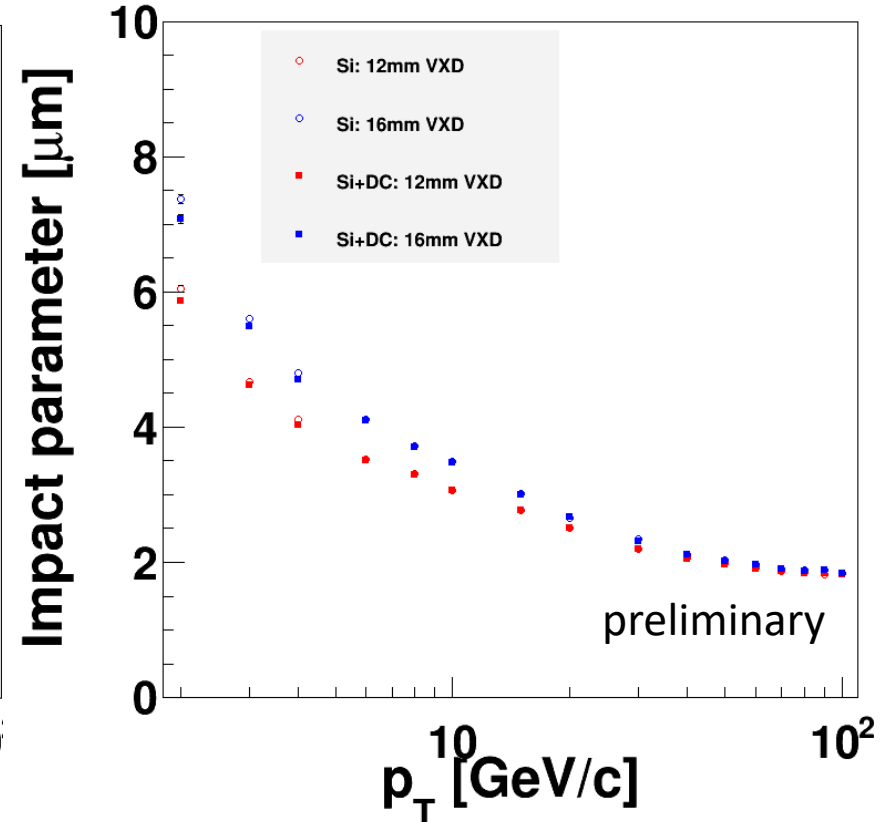
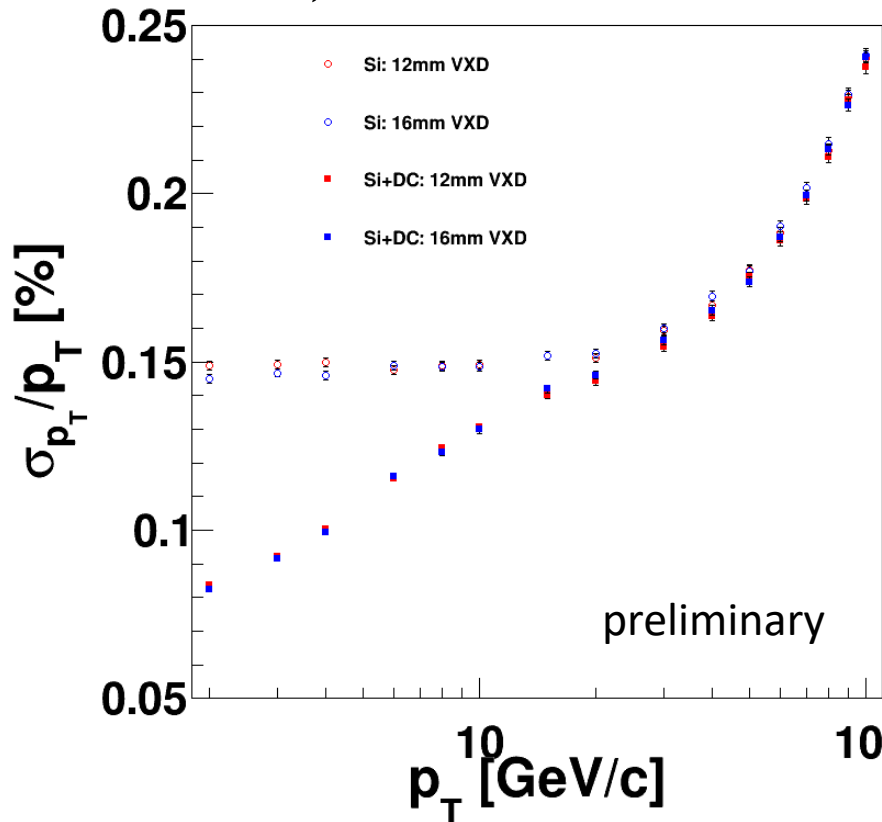
Effect of Inner Radius of Vertex

■ CRD beam pipe

- Inner radius: 14mm → Vertex: 16mm

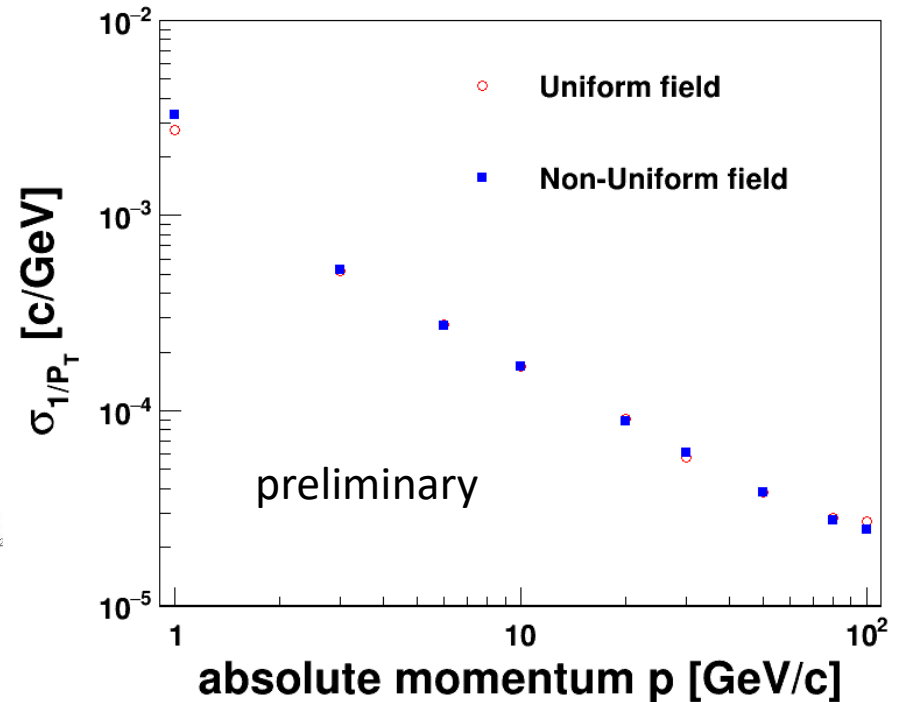
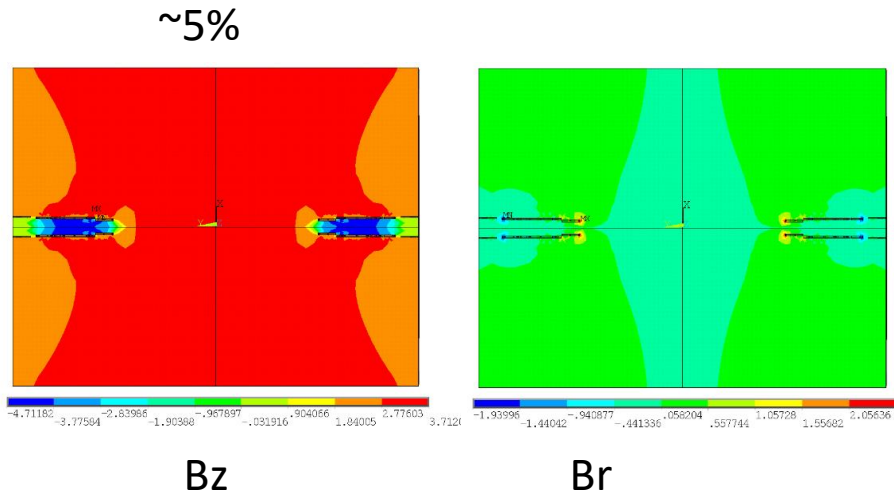
■ Newest beam pipe:

- Inner radius: 10mm → Vertex: 12mm (keep layer5/6, and move layer3/4 2mm)



Non-uniform Field Test on MarlinTrk

- Include non-uniform field by map files through GenericBFieldMapBrBz in simulation
- Keep to use field value at $(0,0,0)$ in reconstruction
 - Resolution changes very small: $(\sigma_{Pt} - \sigma_{Pt,non})/\sigma_{Pt} \sim 4\% @ 100\text{GeV}$
 - momentum departure from MC truth, to correct through average past field



Background

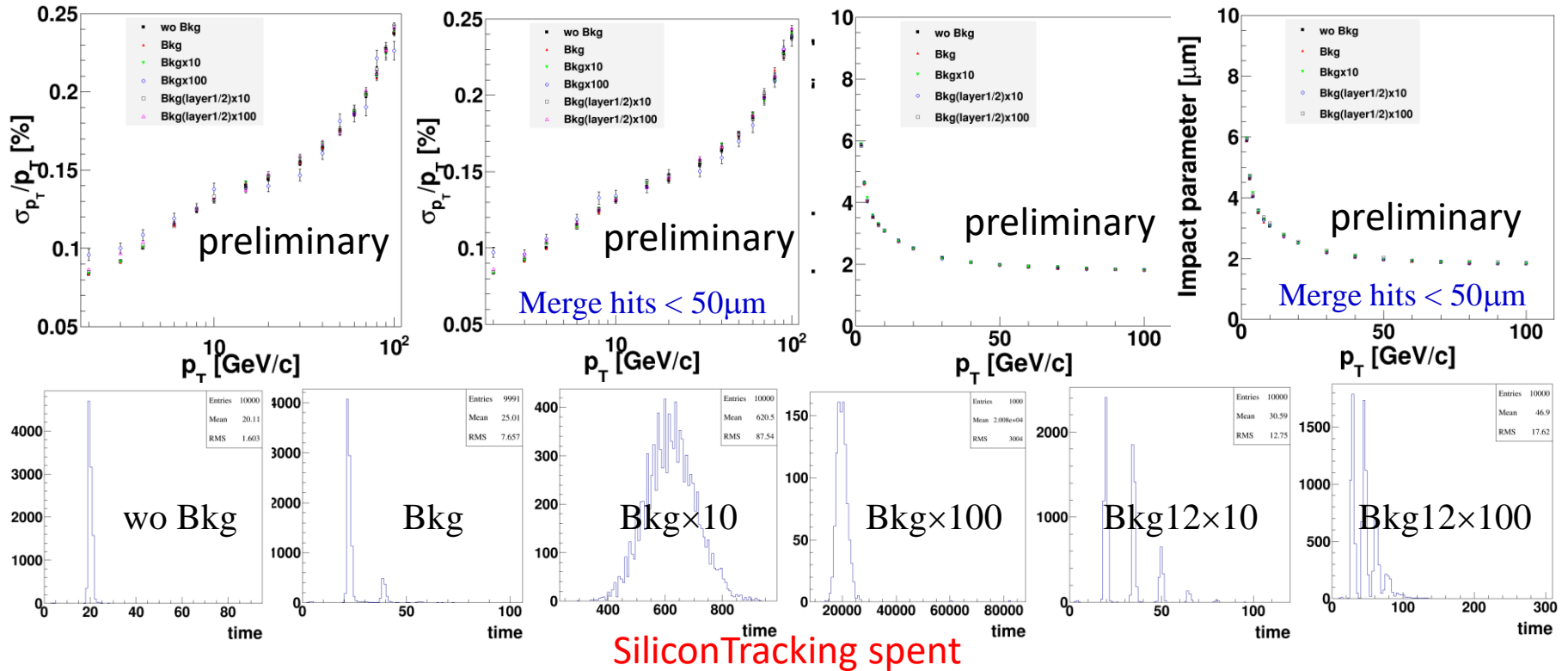
- As known, more close to beam line, more background from beam
- According to **Haoyu's** talk on 2021 Workshop

Name	Position	Hit/cm ² /BX	Hit/cm ² /s
VTX	15 mm	~2.3	~3.33e7
SIT	15 cm	~0.01	~14507
TPC	50 cm	~0.005	~7253
Ecal	200 cm	~1e-4	~145
Hcal	220 cm	~2e-6	~2.9

- Assume $\sim e^{-r/c}$
- For VTX ($r_{1st\ layer}=12mm$), Hit/cm²/BX
 - ✓ 2.6, 2.4, 1.0, 0.96, 0.41, 0.38 as baseline
 - ✓ $\times 10$ for all layers
 - ✓ $\times 100$ for all layers
 - ✓ $\times 10$ for 1st/2nd layers
 - ✓ $\times 100$ for 1st/2nd layers
- Background mixing (simply) with single muon ($\theta=85^\circ$)
 - Random hits at silicon sensors
 - Optional merge for distance less than 50 μ m
 - ✓ Center of merged hits as new position
- More reliable estimation needs beam simulation to generate beam background

Effect of Background

- Background cause fake tracks, extremely, fake tracks will even exceed real tracks much more.
- Increase CPU time
 - More hits, more track finding time
 - More fake tracks, more track fitting time
- If several Hits/cm²/BX, background's effect will be small



Summary

- Tracking algorithm and Kalman filter tool have been migrated from Marlin into CEPCSW, work well for the CDR detector.
- Tracking option from digitization to track finding to track fitting has been defined.
- Performance study shows reasonable tracking efficiency, resolution, CPU time.
- But tracking parameter set still has improving capacity. Generally, tracking efficiency is competition of CPU time.
- Non-uniform field and background are considered in preliminary, showing small effect on resolution. Further study is still needed.

Thanks very much for your attention!