

Tracking in CEPC Silicon Detector

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IHEP, CAS

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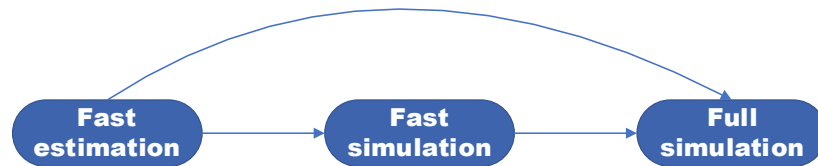
Outline

- Introduction
- Tracking software
- Tracking detectors and tracking finding
- Performance
- Summary

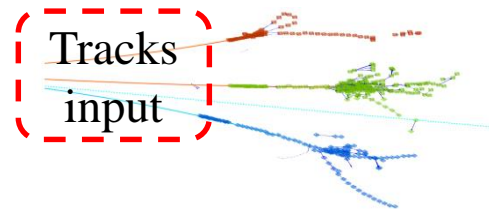
Introduction

Physics process	Measurands	Requirement on tracker
$ZH, Z \rightarrow e^+e^-(\mu^+\mu^-), H \rightarrow \mu^+\mu^-$	$m_H, \sigma(ZH), BR(H \rightarrow \mu^+\mu^-)$	$\Delta(1/p_T) = 2 \times 10^{-5} \oplus \frac{0.001}{p(\text{GeV})\sin^{3/2}\theta}$

- CEPC being designed as Higgs&Z factory, has basic physics requirements, such as tracking resolution.
- Three detector concepts were designed at CDR stage, and the 4th conceptual detector design has been proposed since 2021.
- Track reconstruction for estimation on detector performance at post age of CDR, exactly as at CDR stage



- Tracker design: track performance estimation
- As PFA input



- The silicon detectors are designed as part of all detector concept!

Particle Flow Approach

Baseline detector ILD-like (3 Tesla)

Full silicon tracker concept

CEPC plans for 2 IPs

Low magnetic field concept (2 Tesla)

IDEA Concept
also proposed for FCC-ee

Advantage: the HCal absorbers act as part of the magnet return yoke.

Challenges: thin enough not to affect the jet resolution (e.g. BMR); stability.

Transverse Crystal bar ECAL

Advantage: better π^0/γ reconstruction.

Challenges: minimum number of readout channels; compatible with PFA calorimeter; maintain good jet resolution.

Drift chamber that is optimized for PID

Advantage: Work at high luminosity Z runs

Challenges: sufficient PID power; thin enough not to affect the moment resolution.

CEPCSW & Input

- CEPCSW is a Gaudi-based framework

- Core software, **application**, external libraries

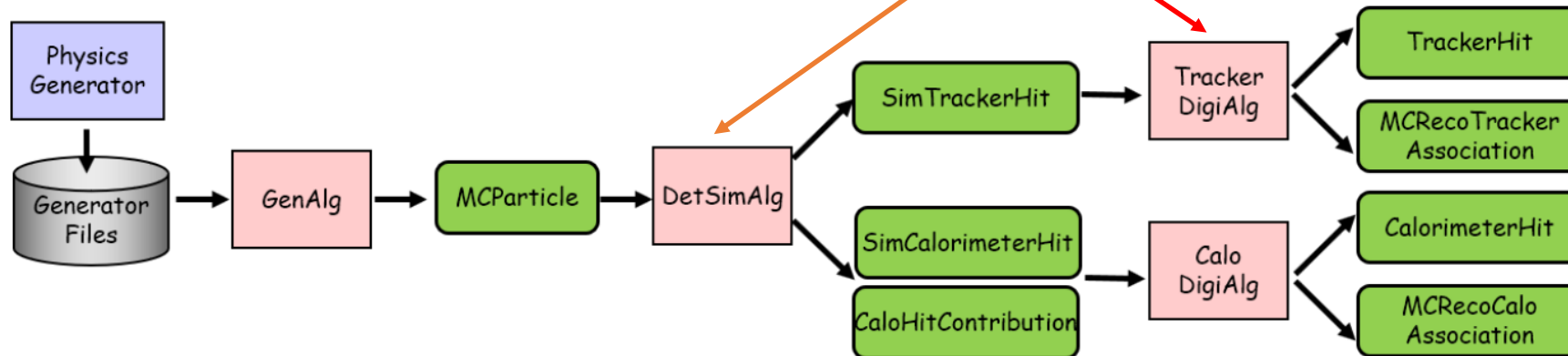
- EDM4hep for event data model

- DD4hep for detector description

- Originally developed for ILC and CLIC but with all of HEP in mind
- Covering the full life cycle of an experiment
 - ✓ Detector concepts, optimization, construction and operation

- DDG4 provides **API** from **xml compact files** and **DD4hep constructor** to **Geant4 geometry**, **DDCore** for interface to **DD4hep geometry** (DetElement, Surface, etc) & **Gear geometry**

- ✓ a single source of information for Geometry, materials, visualization, readout, alignment, calibration, reconstruction etc



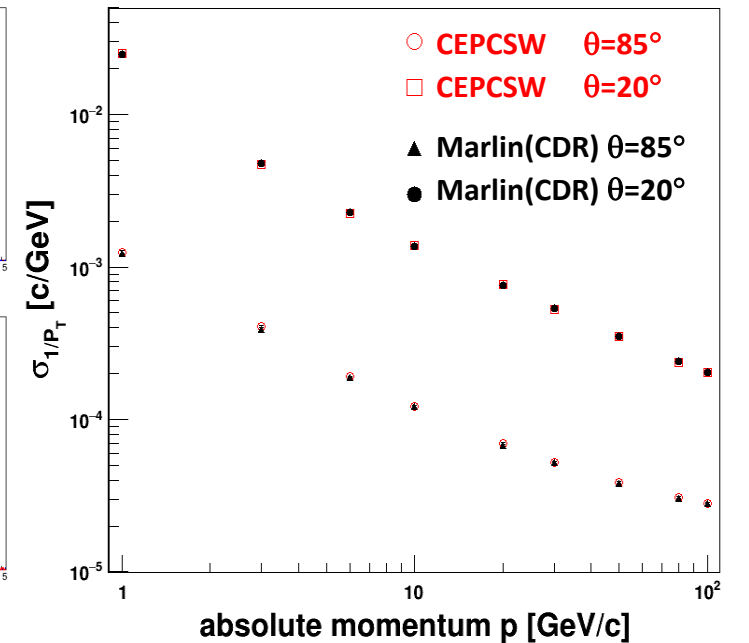
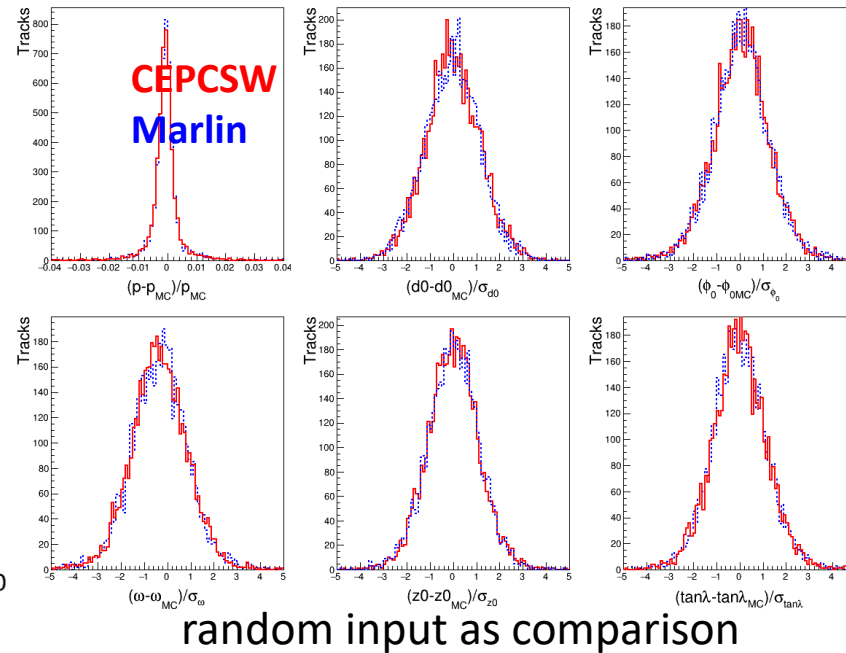
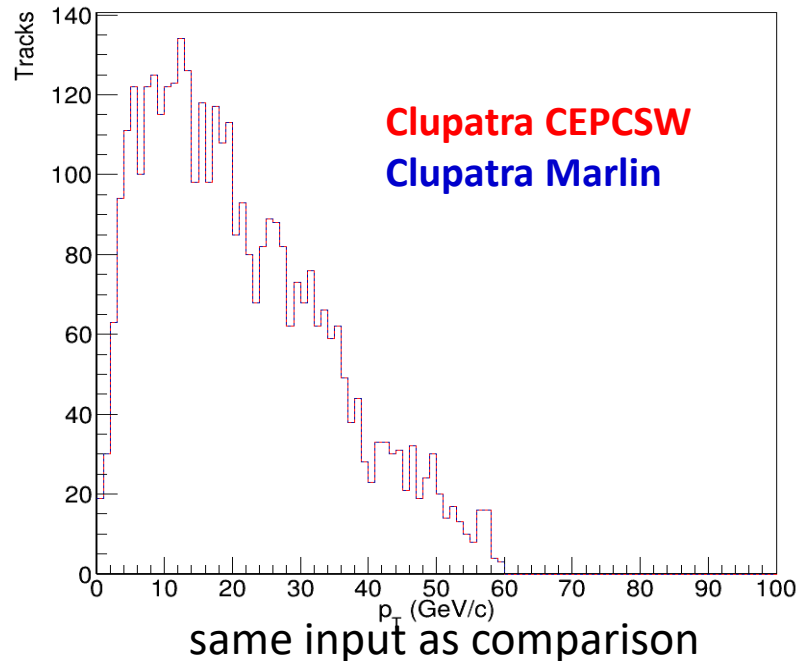
Tracking in CEPCSW

■ Migrated from Marlin processor (cepcsoft/ILCSOFT) to Gaudi algorithm

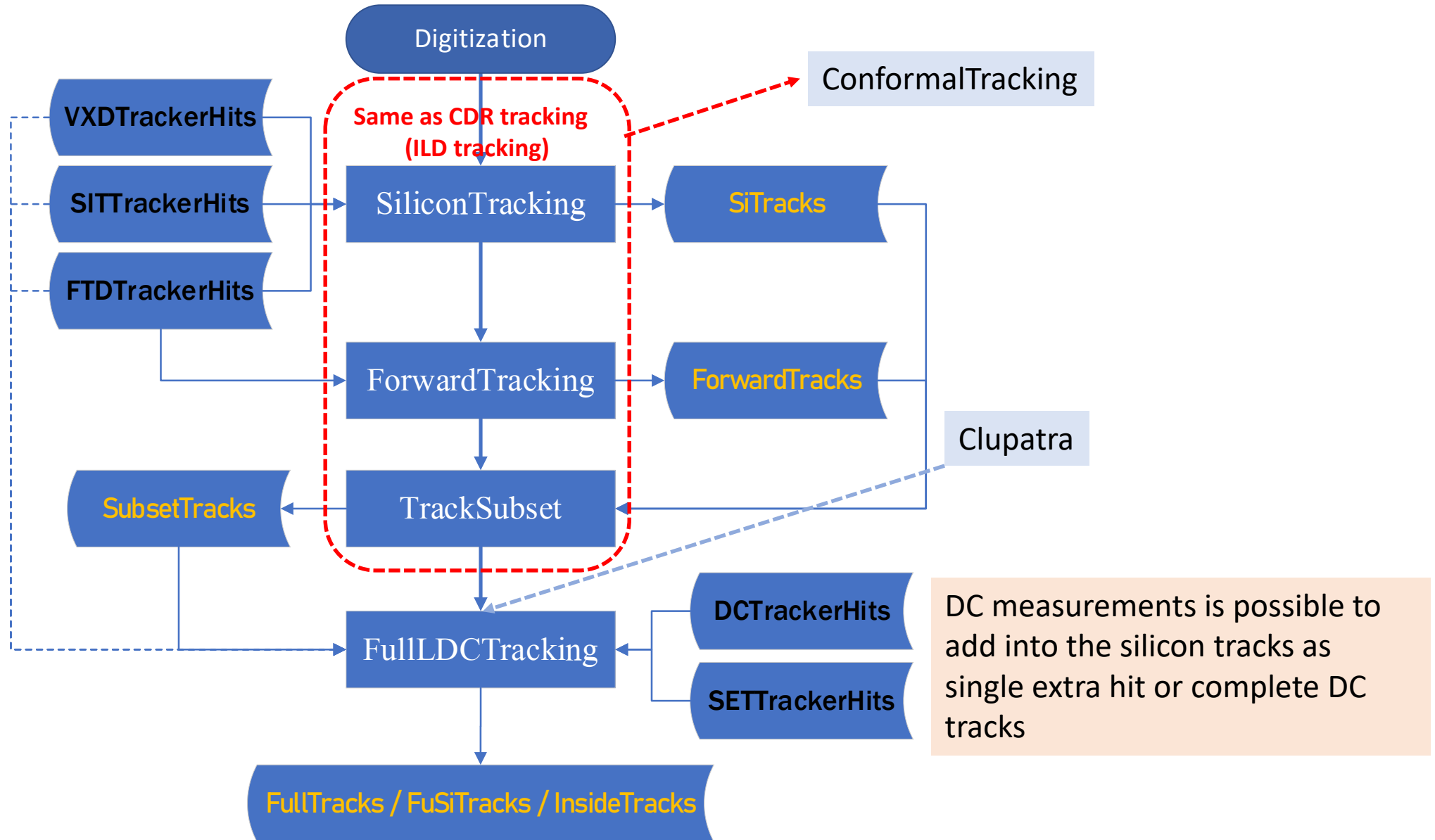
- Geometry: DD4hep extension → Gear
- Interface to call fitter
- Switch data model to EDM4hep

■ Repeat the CDR tracking chain: ILD tracking, ConformalTracking

- Consistent tracking performance between Marlin and CEPCSW
- Possible to continue the CDR study in CEPCSW



Tracking Chain

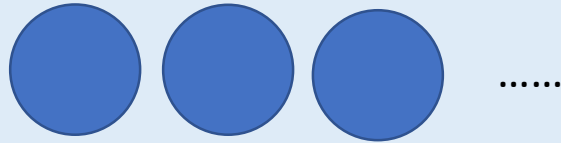


Output

edm4hep::Track

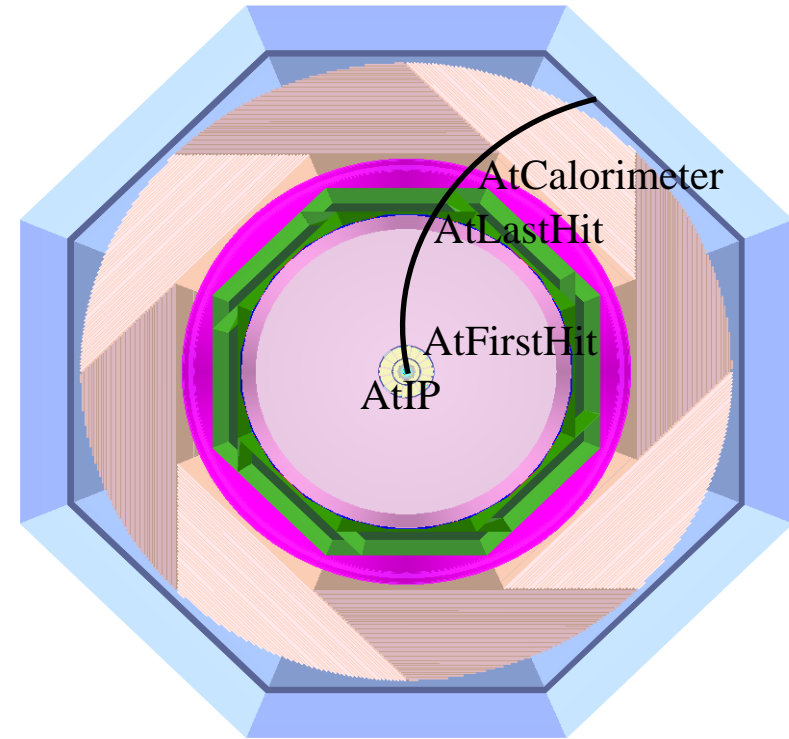
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edm4hep::TrackerHit s



edm4hep::TrackState s

```
std::int32_t location  
float D0  
float phi  
float omega  
float Z0  
float tanLambda  
float time  
edm4hep::Vector3f referencePoint  
std::array<float, 21> covMatrix
```

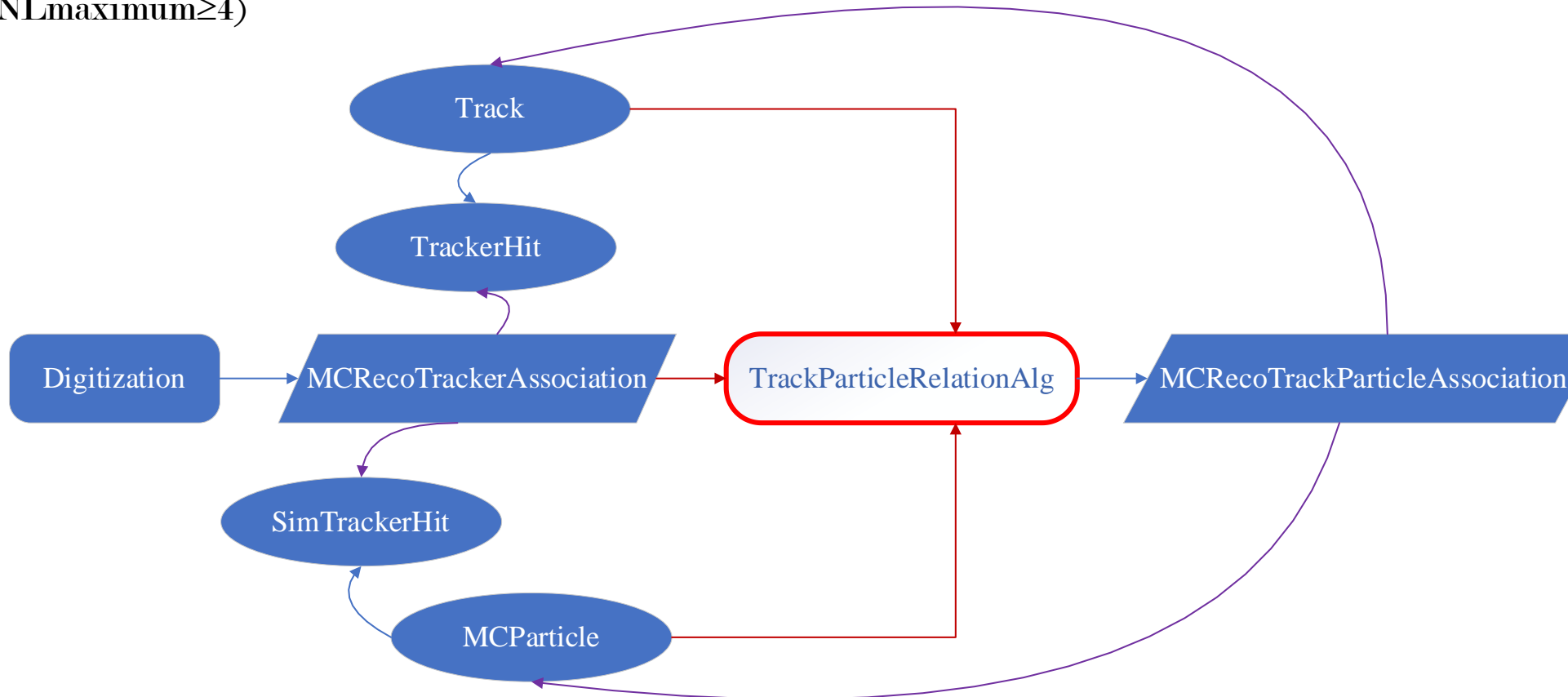


Currently, four TrackStates are in storage:
if(location==edm4hep::TrackState::AtIP)
if(location==edm4hep::TrackState::AtFirstHit)
if(location==edm4hep::TrackState::AtLastHit)
if(location==edm4hep::TrackState::AtCalorimeter)

Association

■ MCRcoTrackParticleAssociation

- Track
- MCParticle
- **weight**: number of tracker hit linked between MCParticle and Track (NL), for a particle, found track (NLmaximum ≥ 4)



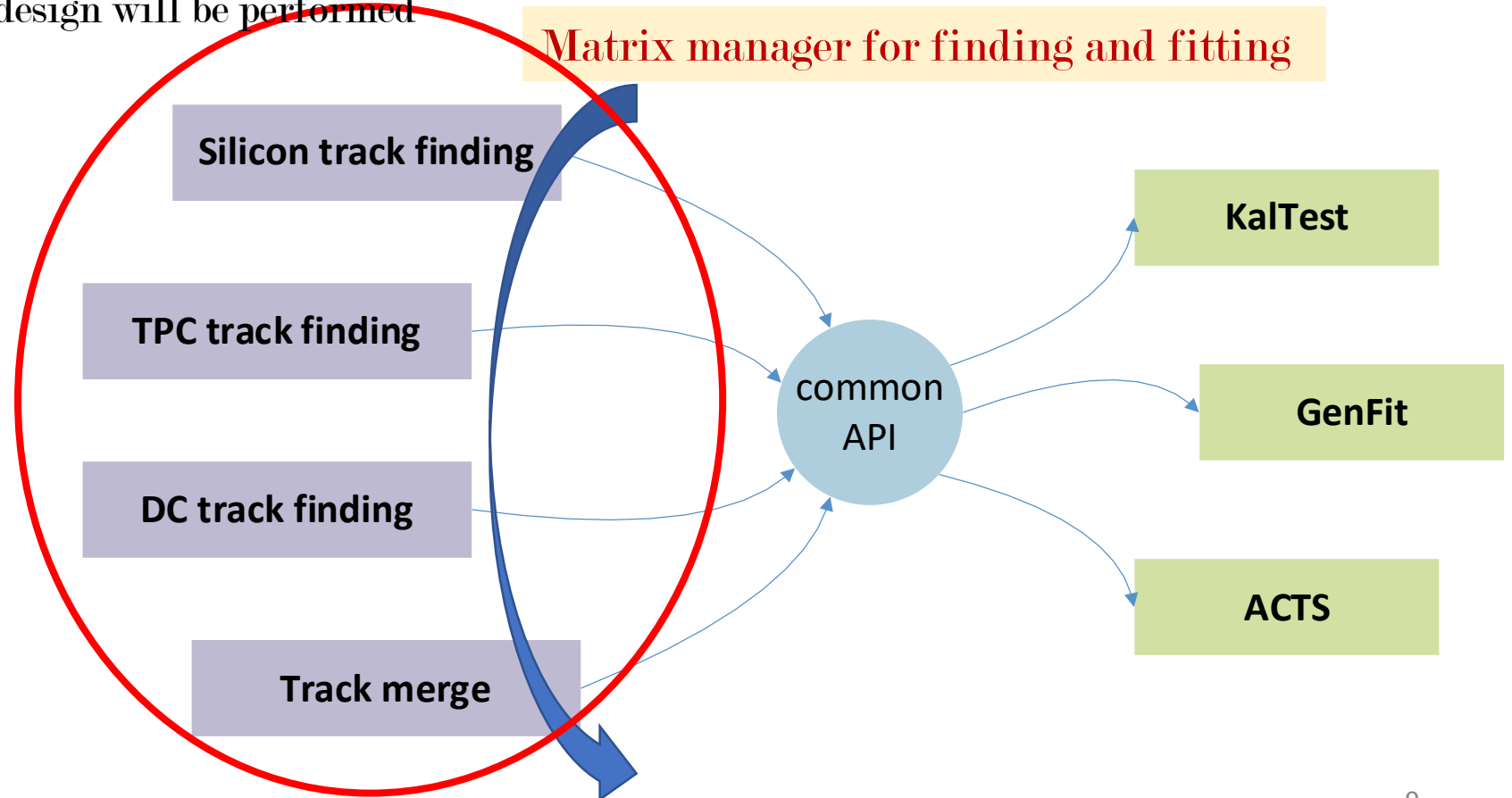
Propose of Tracking Chain

- Call the common API after track finding in all algorithm, and choose fitter according to option
- To choice best combination of track finding and fitting
 - For middle tracking, low CPU time
 - For final tracking, high performance
- Comparison on same detector design will be performed

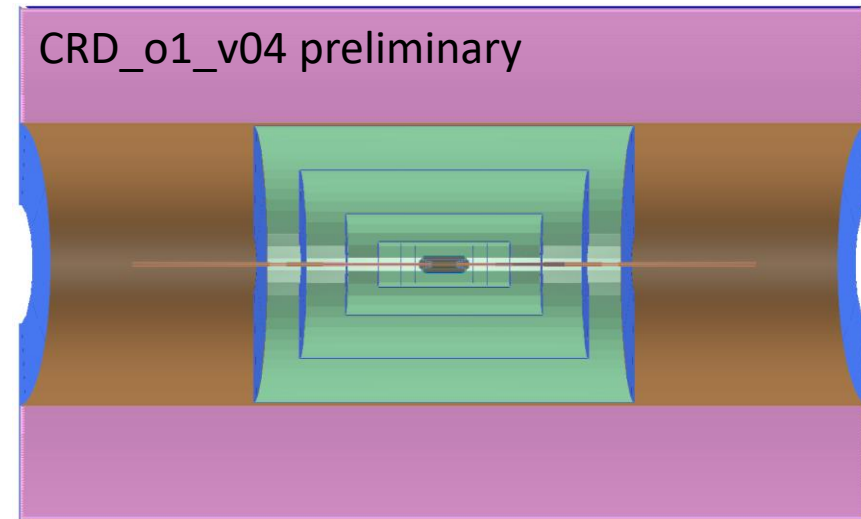
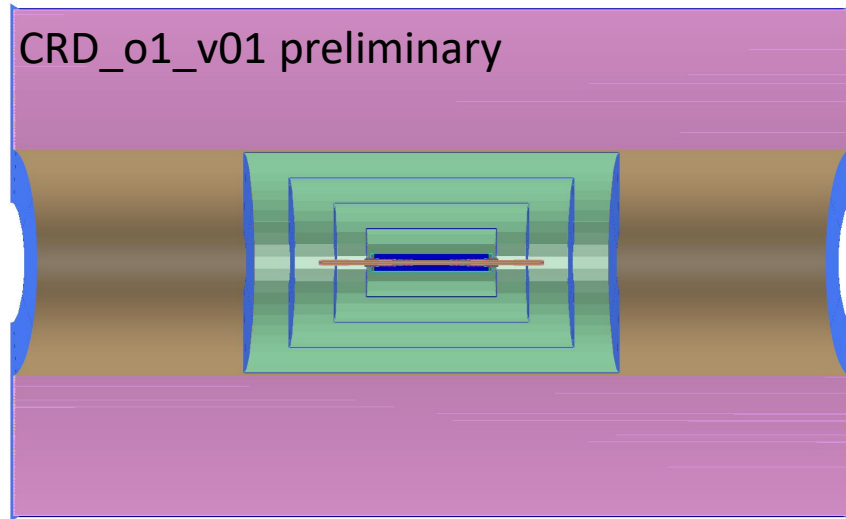
BEST: appropriate performance and CPU time

■ Status

- ConformalTracking has used the common API
 - ✓ KalTest done
 - ✓ DDKalTest, GenFit, ACTS ongoing
- Other tracking algorithms ongoing



Tracking System (developing)



- **Vertex detector (VXD): 6 pixel layers**
 - $\sigma_{r_{\text{phi},z}} = 2.8\mu\text{m}, 6\mu\text{m}, 4\mu\text{m}, 4\mu\text{m}, 4\mu\text{m}, 4\mu\text{m}$
- **Silicon inside/internal DC tracker (SIT): 4 or 3 pixel layers**
 - $\sigma_{r_{\text{phi}}} = 7.2\mu\text{m}, \sigma_z = 86\mu\text{m}$
- **Silicon outside/external DC tracker (SOT/SET): 1 pixel layer**
 - $\sigma_{r_{\text{phi}}} = 7.2\mu\text{m}, \sigma_z = 86\mu\text{m}$
- **Endcap tracker (EIT&EOT/FTD): 2 + 3 pixel layers**
 - $\sigma_{x,y} = 3\mu\text{m}, 3\mu\text{m}, 7.2\mu\text{m}, 7.2\mu\text{m}, 7.2\mu\text{m}$
- **Drift chamber (DC): 18mm or 10 mm cell size**
 - $\sigma_{r_{\text{phi}}} = 100\mu\text{m}, \sigma_z = 2.828\text{mm}$

Digitization

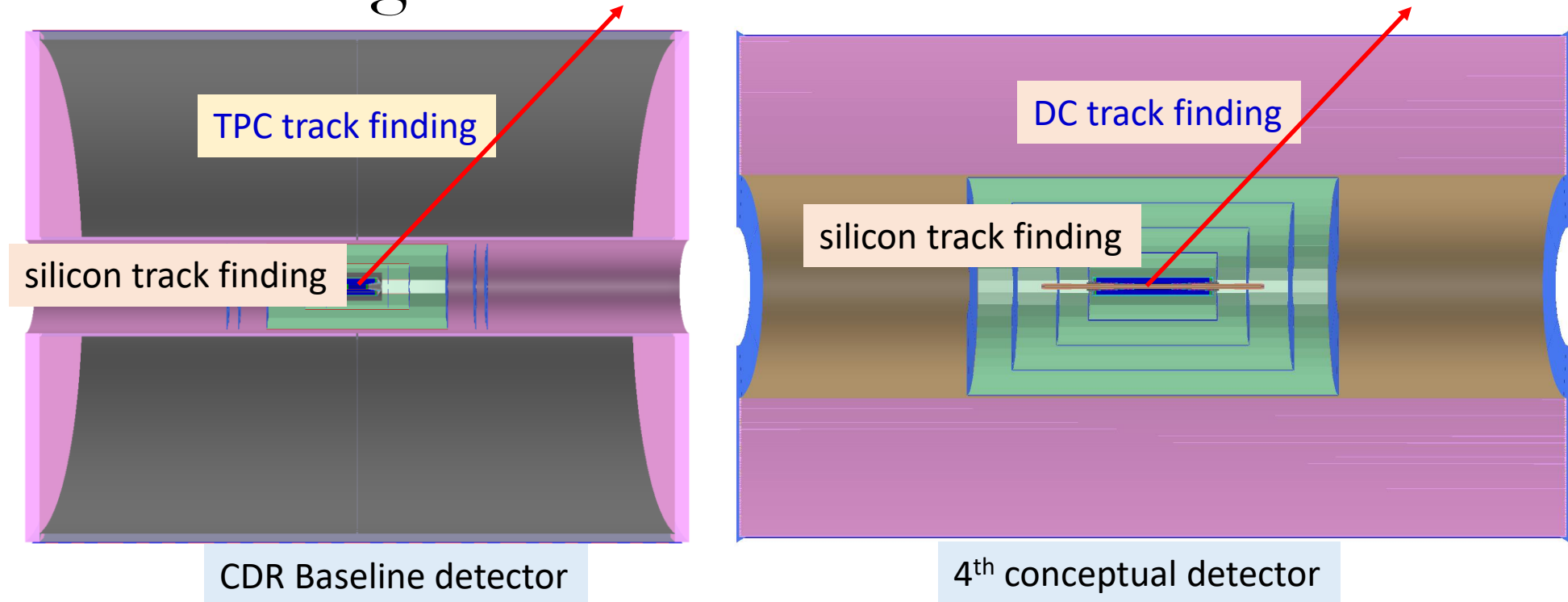
■ PlanarDigiAlg

- Gaussian smearing at measurement dimension (u,v)
- pixel: 2D (u,v)
- strip: 1D $(u,0)$ or $(0,v)$, two doubly layer hits \rightarrow one space point by SpacePointBuilder
- TrackerHit: dU and dV saved in `std::array<float, 6>& CovMatrix`, interface to convert
- Surface in reconstruction: `PlanarMeasLayer`
- future: TrackerHitPlane, but should solve different types of hits in fitting

■ CylinderDigiAlg

- prepared for bent CMOS sensor
- Gaussian smearing at $(R\phi,z)$
- TrackerHit: `std::array<float, 6>& CovMatrix`
- Surface in reconstruction: `CylinderMeasLayer`

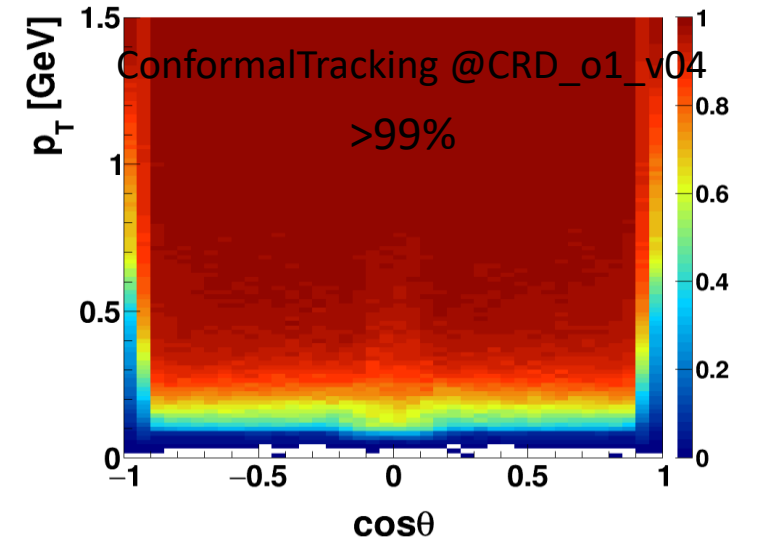
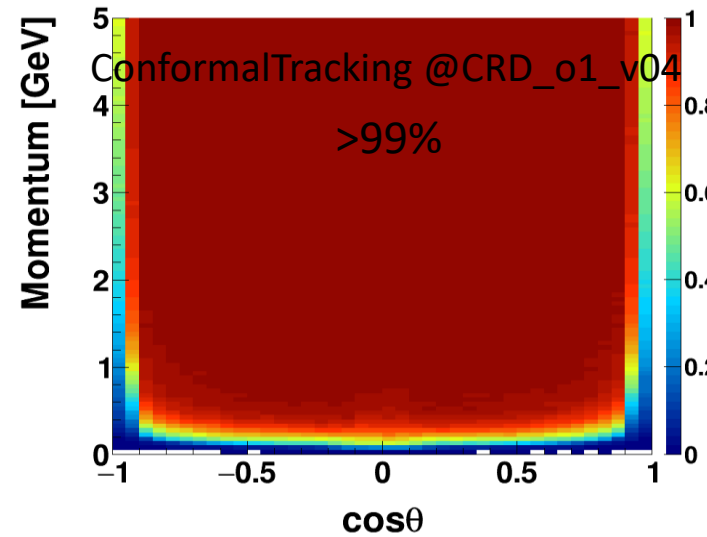
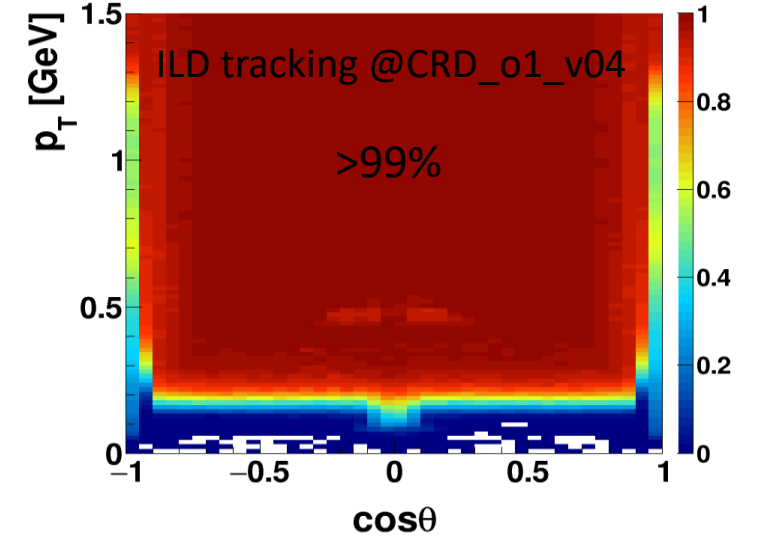
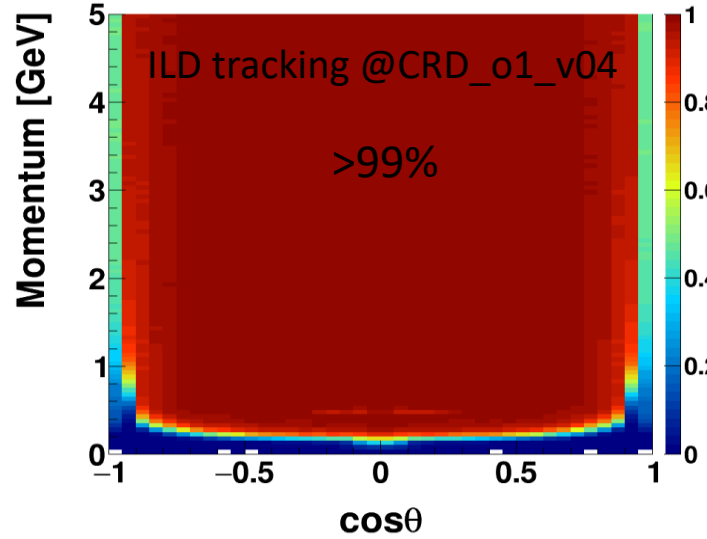
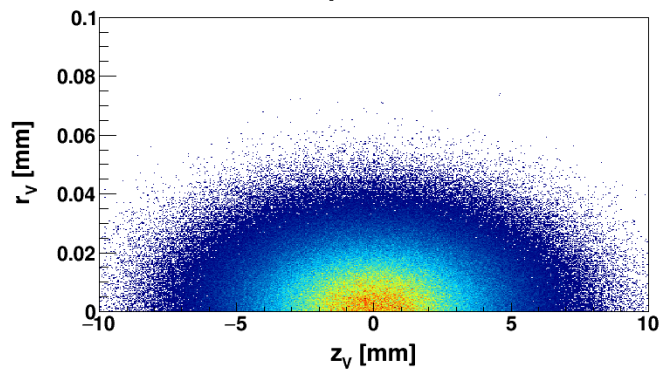
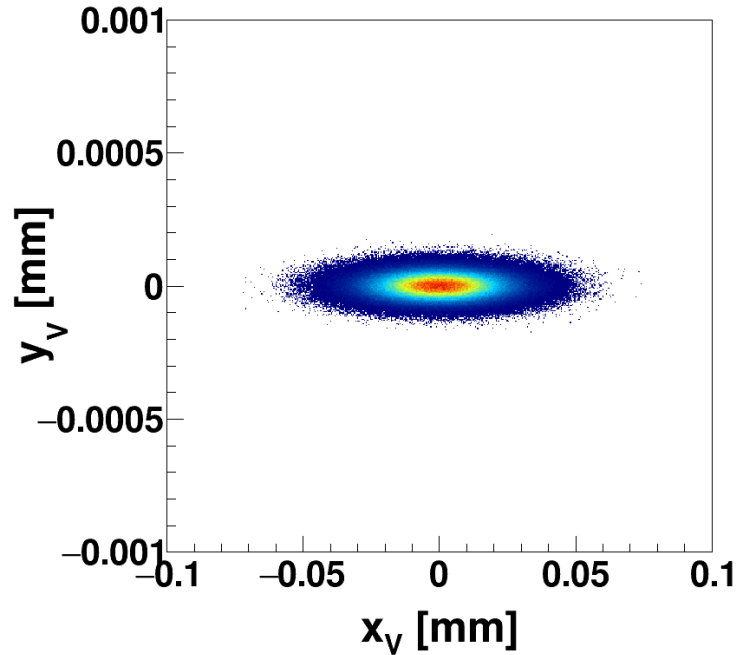
Track Finding



- Different pattern recognition for gas tracker and silicon tracker
 - CDR baseline detector
 - ✓ better resolution from TPC track → TPC track as base
 - 4th conceptual detector
 - ✓ worse resolution from DC track → silicon track as base
 - ✓ same silicon tracking can be performed on the full silicon tracker
- Same pattern recognition in once time is in consider

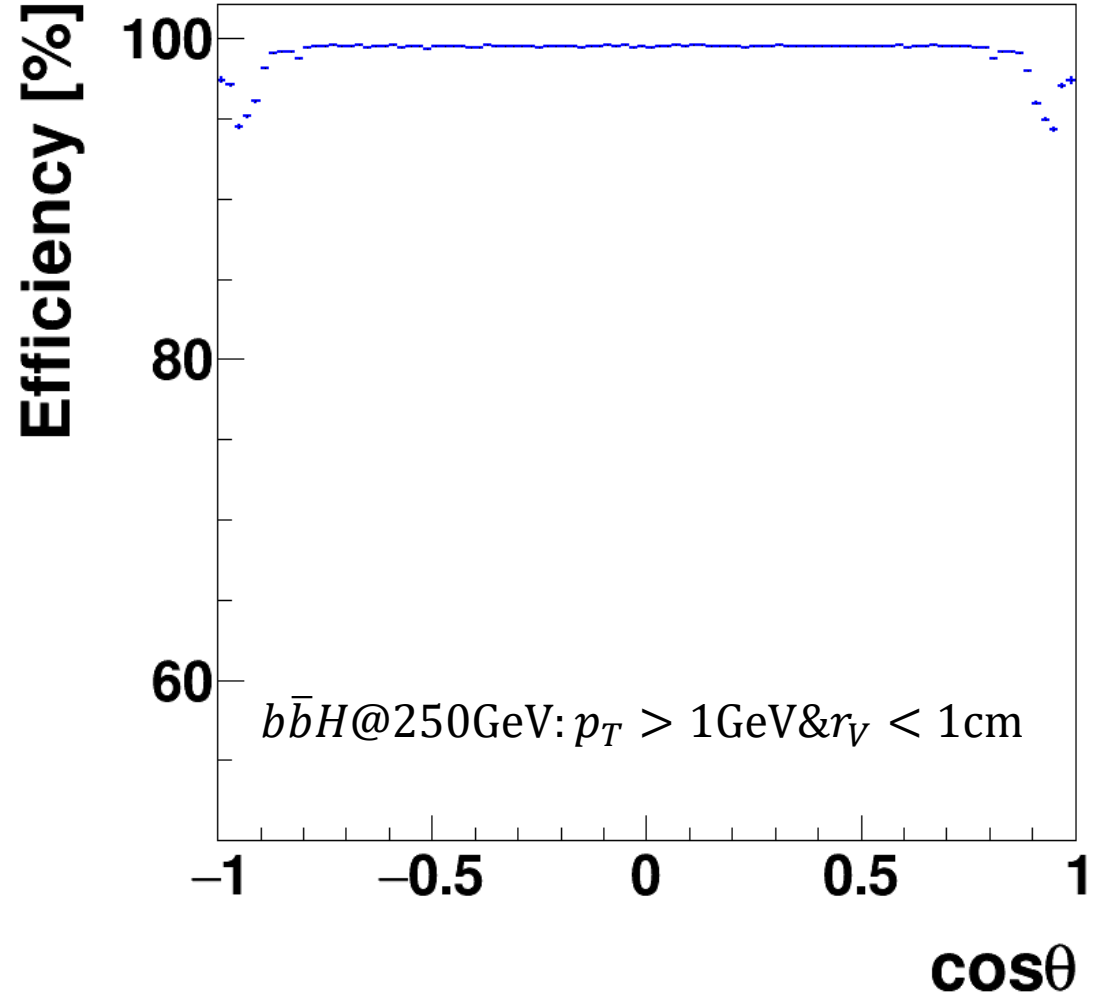
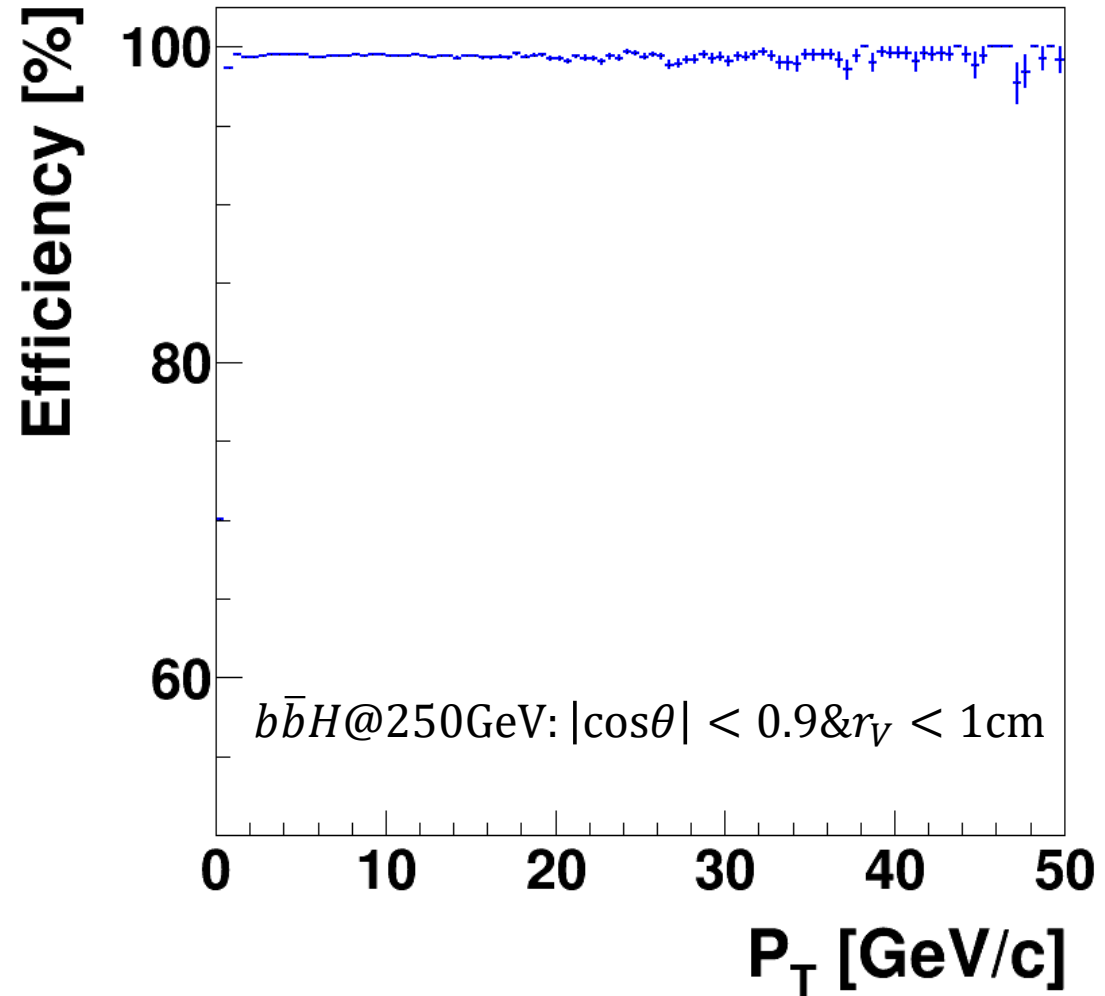
Tracking in ParticleGun

■ 20 prongs: $p \in (0, 5) \text{ GeV}$, $\theta \in (5^\circ, 175^\circ)$



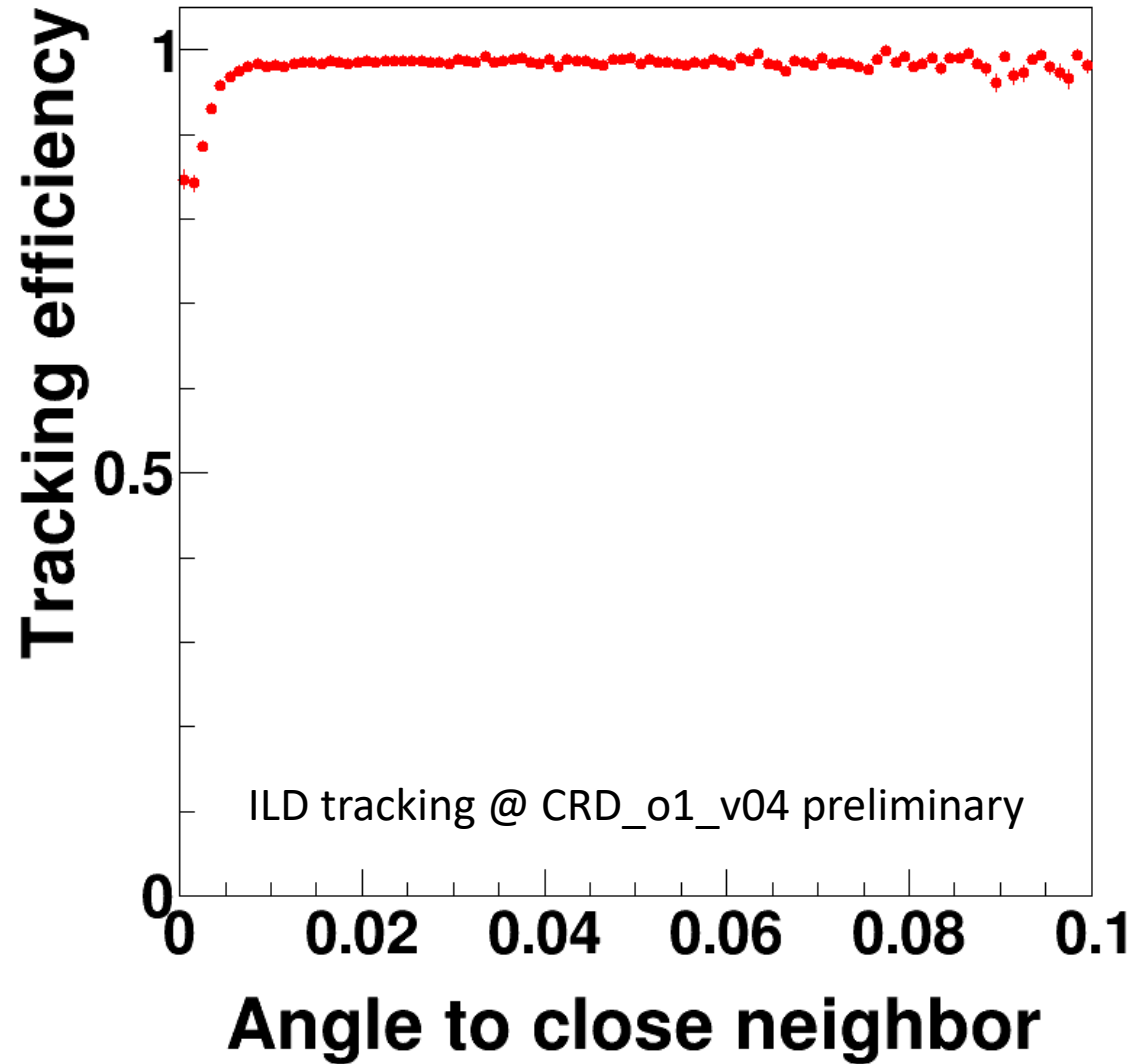
Efficiency in $b\bar{b}H$

■ Observe particle: has ≥ 6 hits in trackers



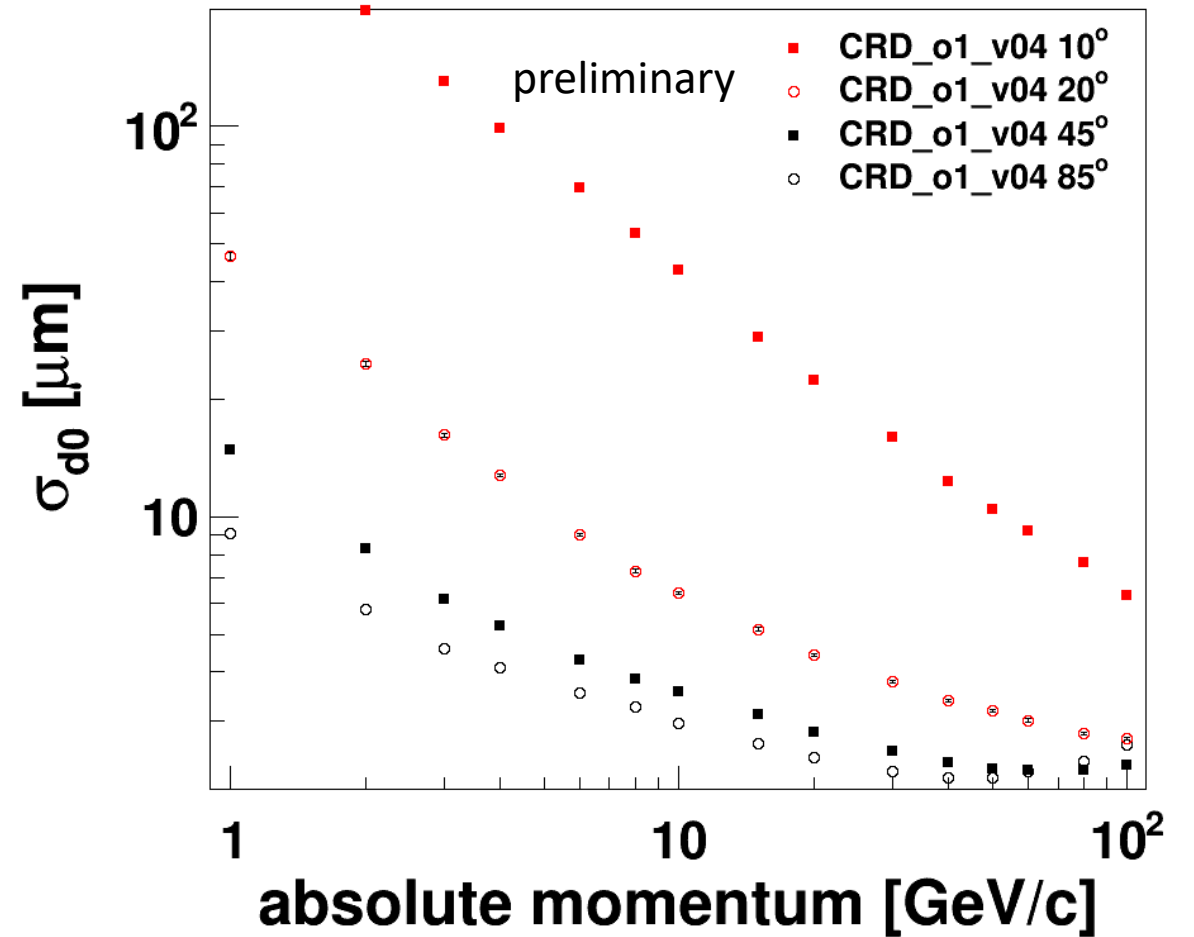
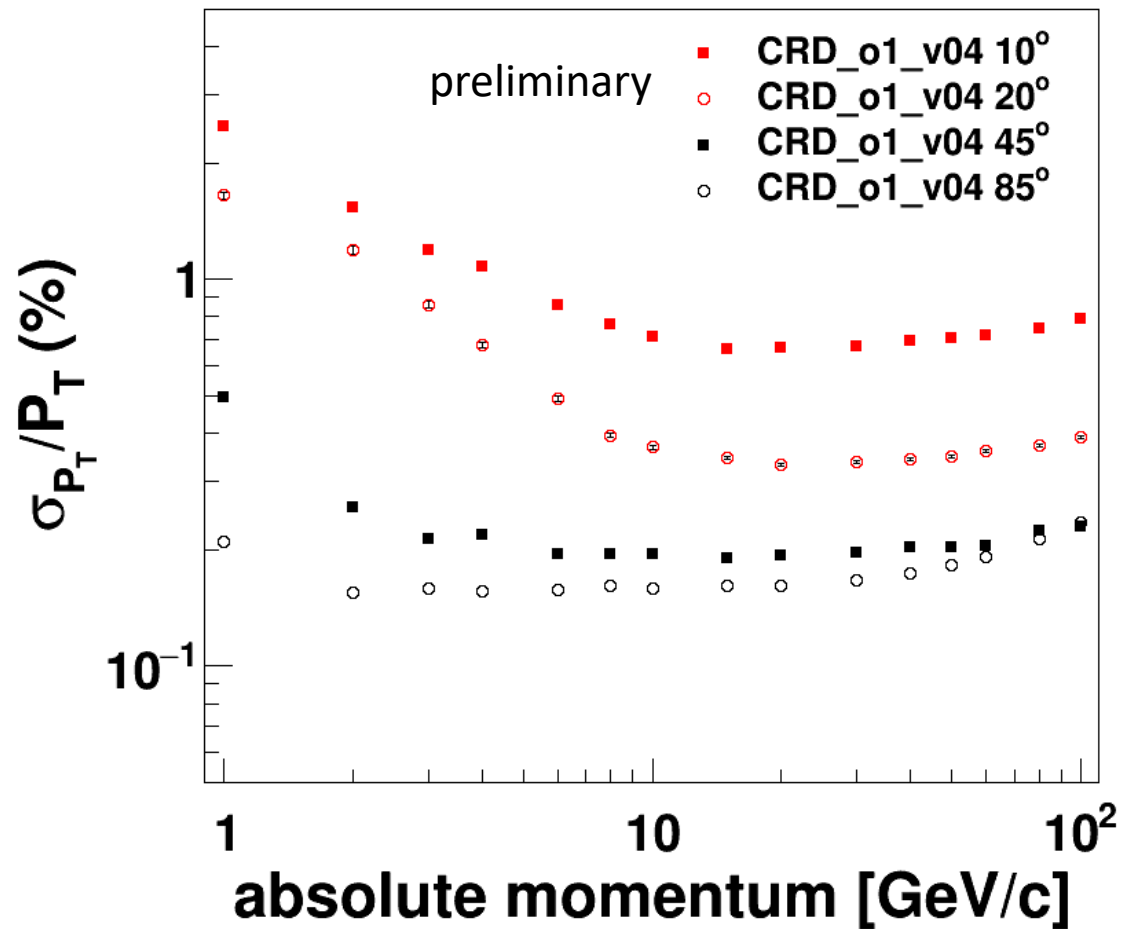
Efficiency in $\tau \rightarrow 3\text{prong}$

- Observed particles (N): has ≥ 6 linked tracker hits
 - Has linked track (Nf)
 - $\varepsilon = Nf/N$
- Search the close neighbor in the final state particles



Resolution

■ $\sigma_{IP}=(15\mu\text{m}, 36\text{nm}, 2.8\text{mm})$



Summary

- Built tracking software for the silicon detectors in CEPCSW, digitization, track finding, track fitting and association maker.
- Tracking chain composed of Gaudi algorithms works on multiple detector designs. There are two parallel silicon tracking (ILD tracking and ConformalTracking) in development.
- Multiple fit tools (DDKalTest, GenFit, ACTS) are ongoing to implement into same tracking algorithm through the common API. The ConformalTracking has been updated.
- More performance test (multiple particle gun, $b\bar{b}H$, $\tau \rightarrow 3prong$) has been performed.
 - Still has many improved space, such as stability of ConformalTracking.

Thanks very much for your attention!