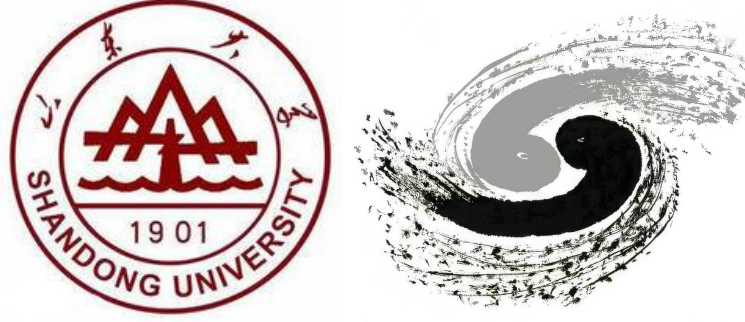


CEPC Drift Chamber Simulation and Reconstruction

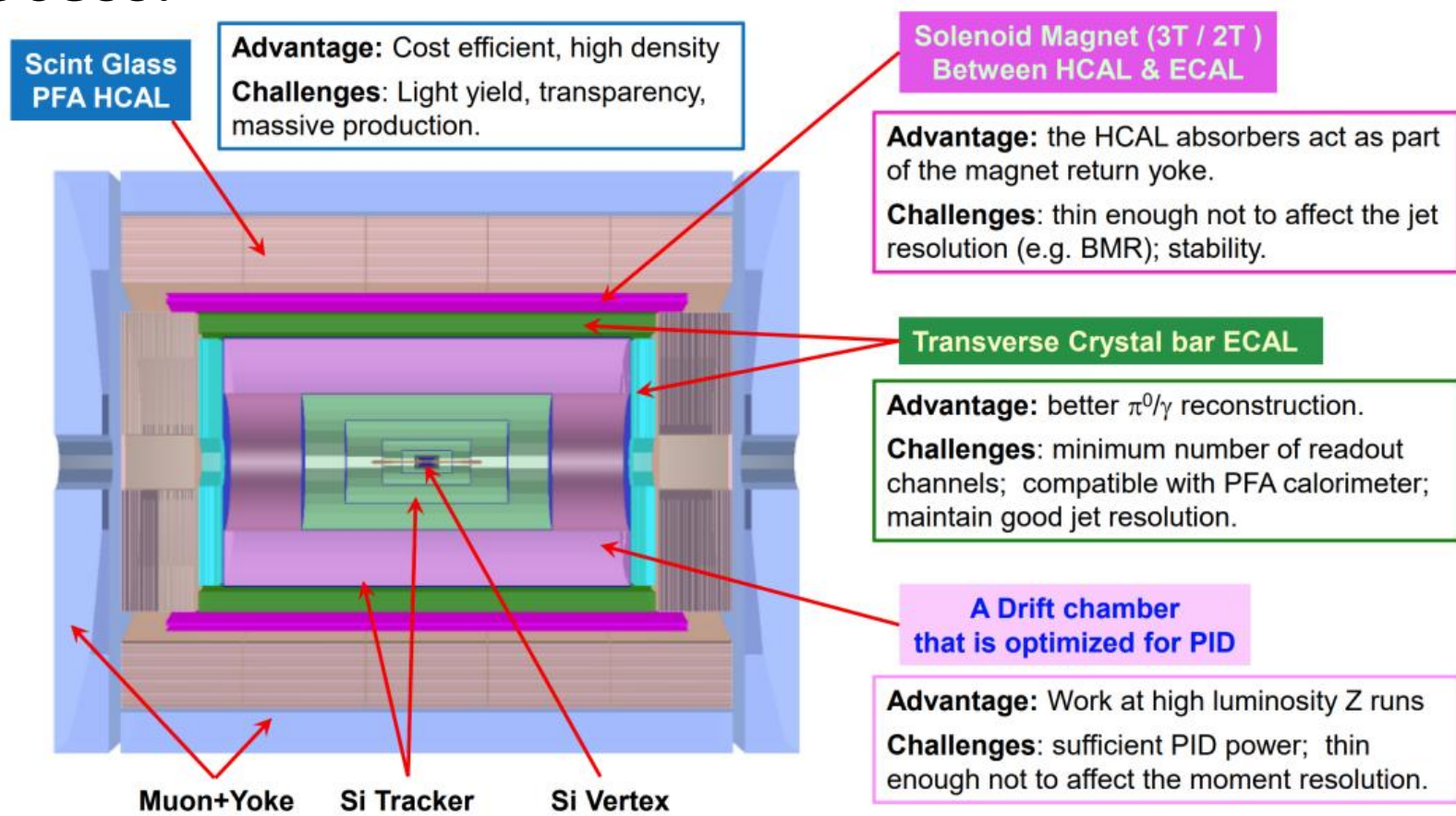
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Introduction

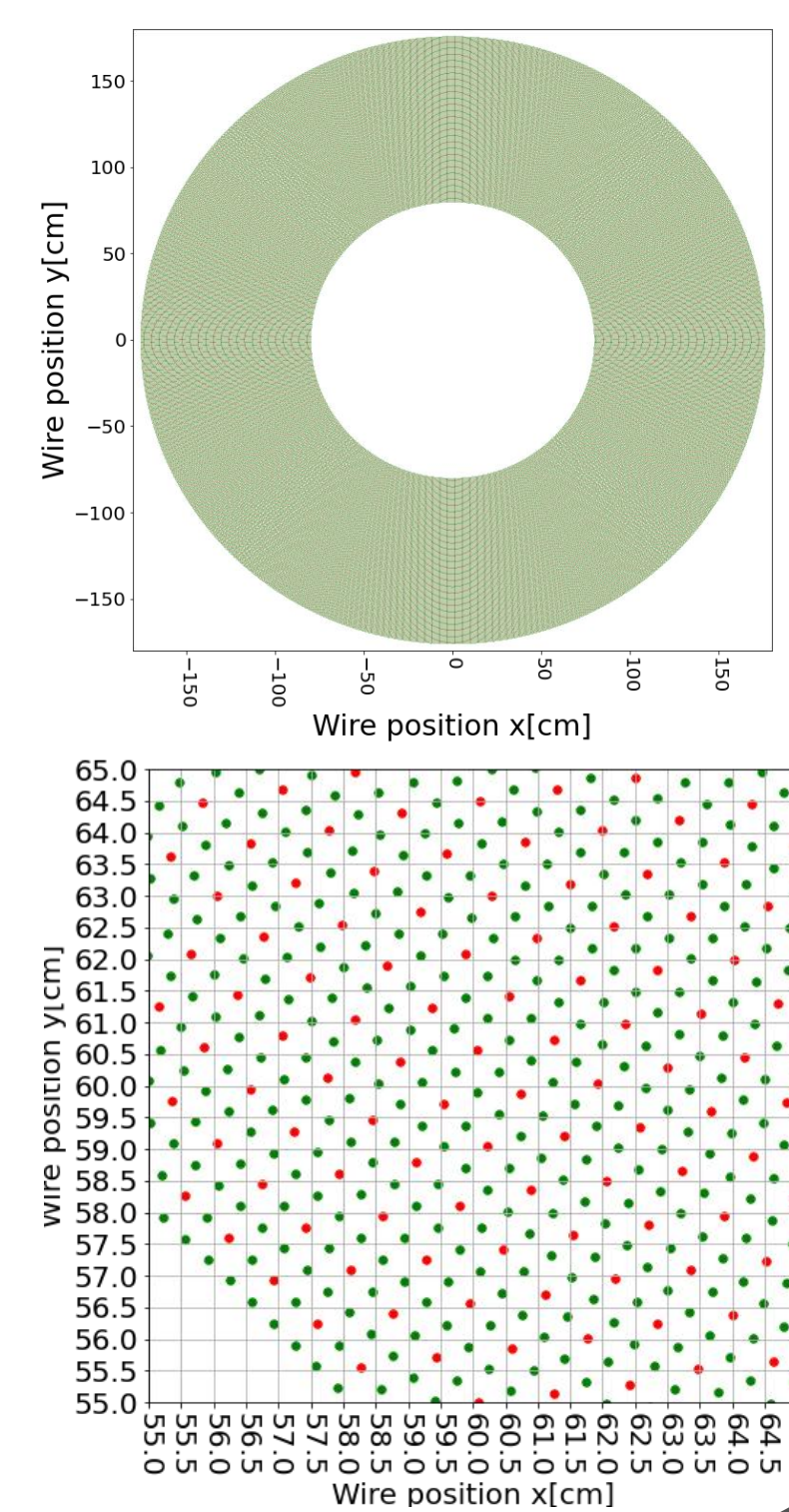
- Drift Chamber (DC) is an important sub-detector of CEPC, and its main function is to accurately measure the momentum and energy loss of charged particles (for particle identification).
- The track reconstruction of charged particles is an important link in the CEPC offline data processing process.
- At present, the track fitting algorithm has been completed, and the tracking algorithm is being developed.
- CKF (Combined Kalman Filter) is used to track finding.



DC Parameters in CEPCSW

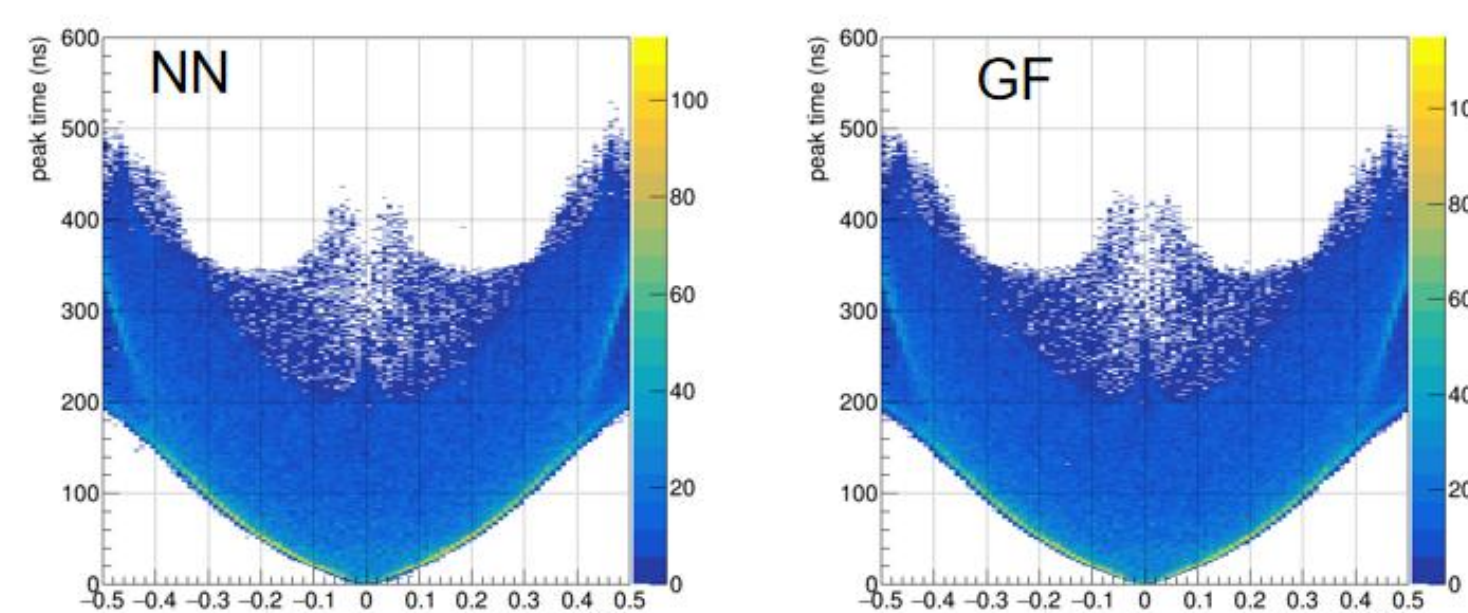
- The base line configuration of DC in CEPCSW

Half length	2980 mm
Inner and outer radius	800 to 1800 mm
# of Layers	100/55
Cell size	~10x10mm/18x18mm
Gas	He:C ₄ H ₁₀ =90:10
Single cell resolution	0.11 mm
Sense to field wire ratio	1:3
Total # of sense wire	81631/24931
Stereo angle	1.64~3.64 deg
Sense wire	Gold plated Tungsten $\phi=0.02mm$
Field wire	Silver plated Aluminum $\phi=0.04mm$
Walls	Carbon fiber 0.2 mm(inner) and 2.8 mm(outer)

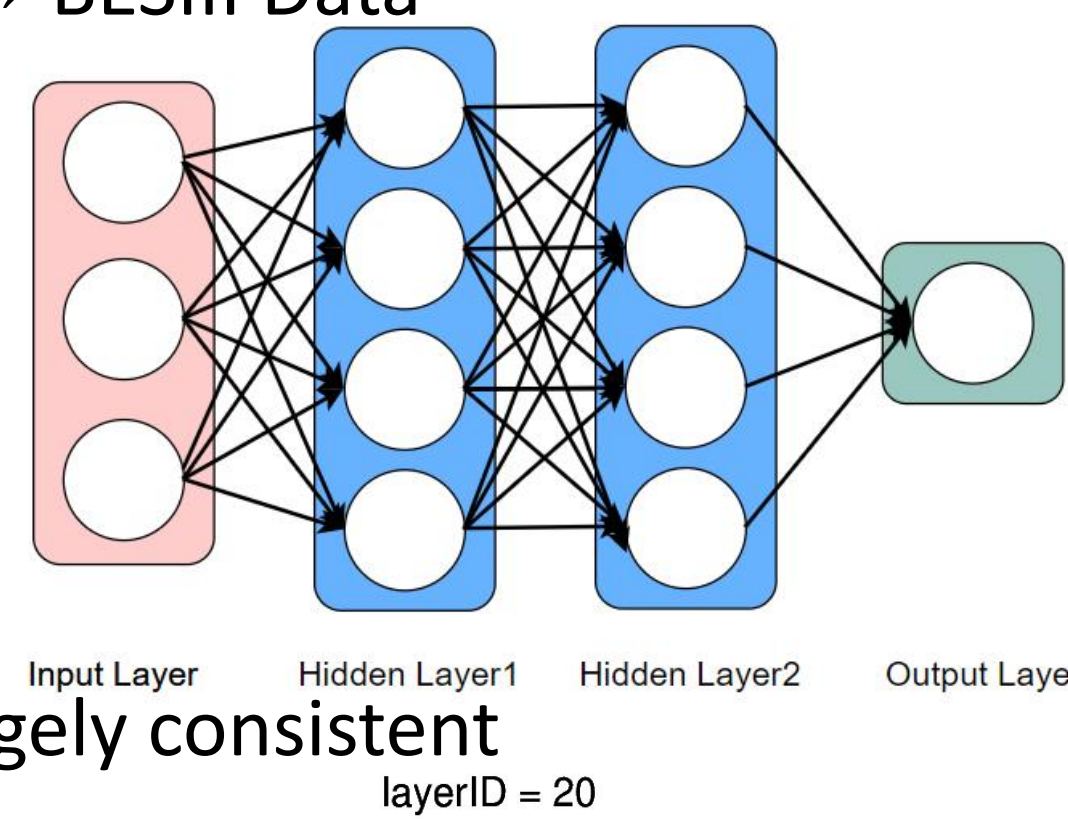


X-T simulations using DNN

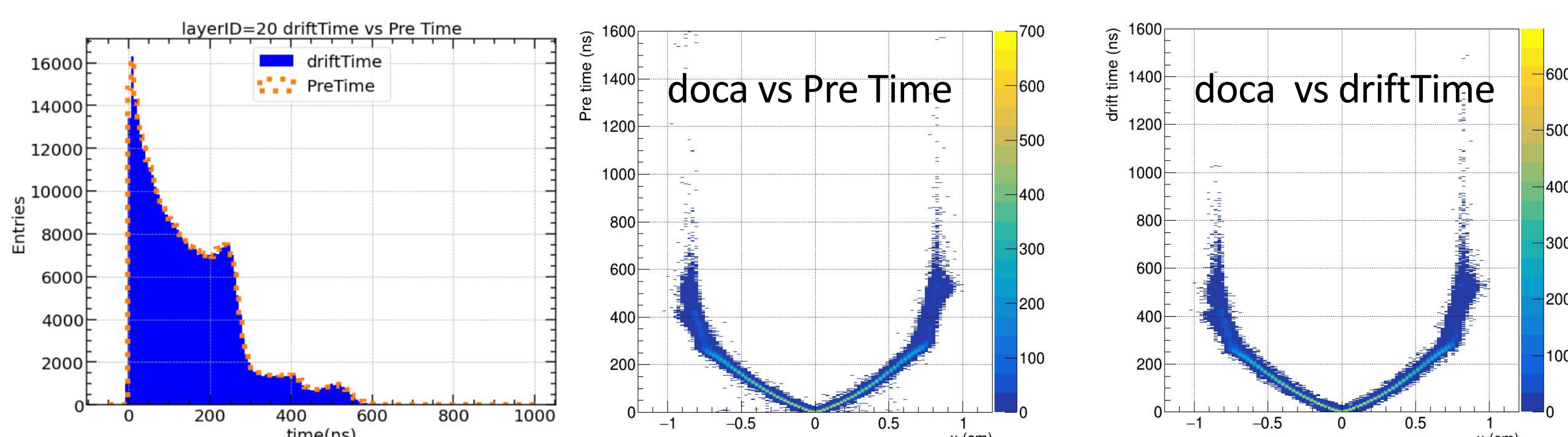
- Garfield++ is used for the simulation in the drift chamber
- Using a machine learning model to learn Garfield simulation \Rightarrow fits well



- Use data to verify the accuracy of the model \rightarrow BESIII Data
- Use DNN networks to learn X-T relationship
 - Input Layer: doca, eangle, N(0,1)
 - Hidden Layer: 814 x 814 x 814
 - Output Layer: Time



- Take layerID=20 as an example:
 - The time distribution is the same
 - The shape of the X-T relationship is also largely consistent



- We get similar results using flow

Summary

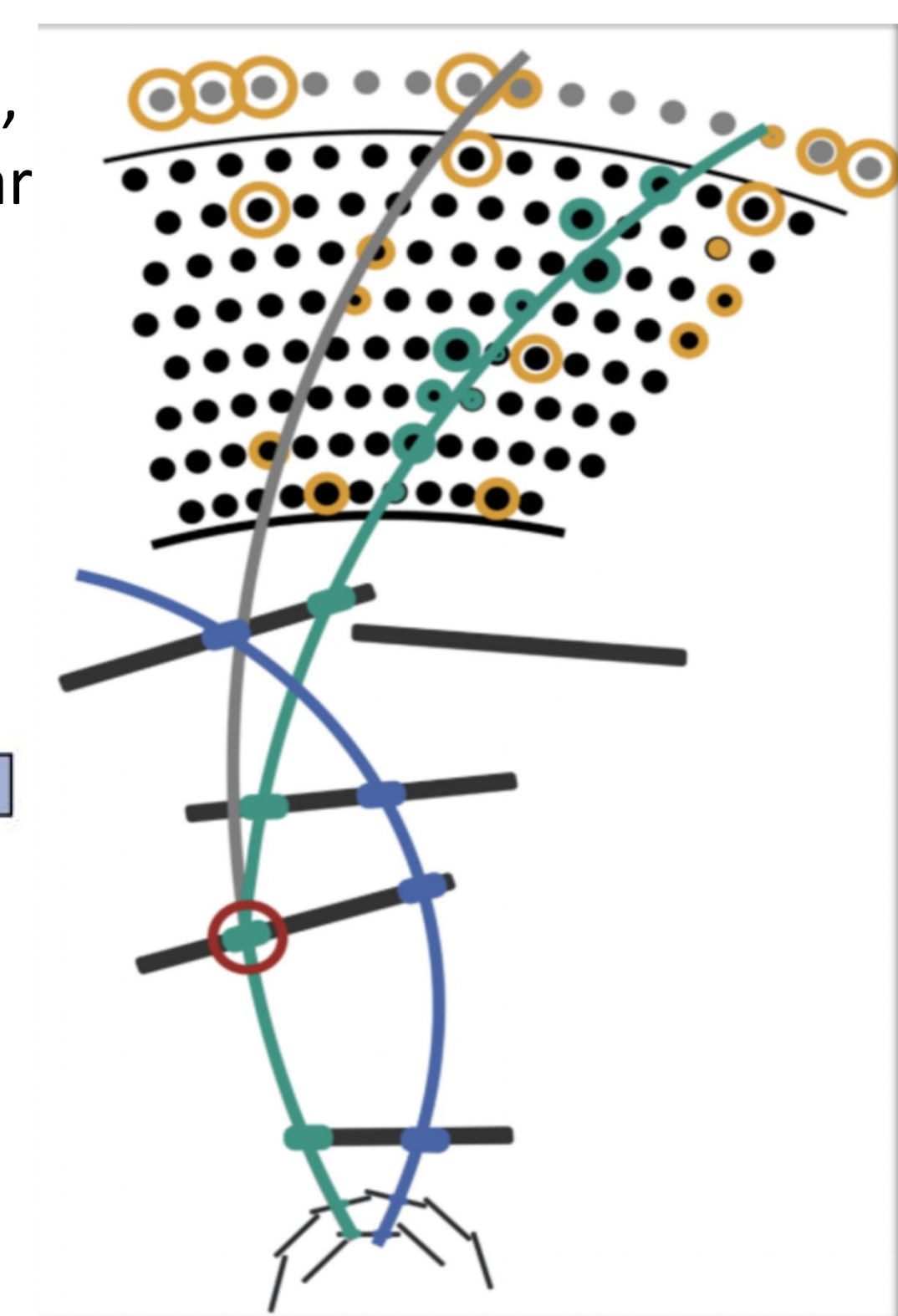
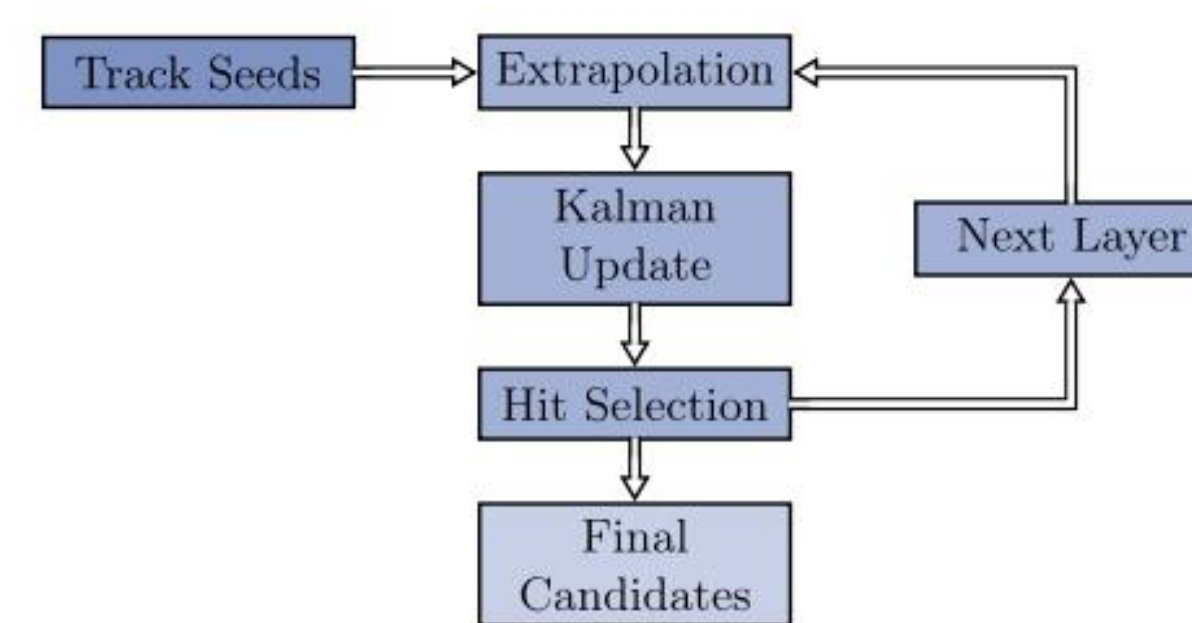
- Preliminary results show that the predicted value is consistent with the training value when using BESIII data for DNN
- Track fitting algorithm inspection is complete and ready for release
- Track finding algorithm completed the investigation and successfully compiled and ran in CEPCSW environment. Our next step is to test the tracking efficiency

DC Track Finding

- CKF (Combinatorial Kalman Filter):
 - a tracking concept that combines track finding and track fitting in a search-tree-based algorithm.
 - It is used by many high energy physics experiments
 - can give precise results leading to high purities as well as high efficiencies
- Track finding using CKF in Drift chamber
 - Used MC Truth
 - Purpose: Select hits belonging to this track through the existing track seed
 - Methods: The reconstructed SiTrack is selected as seed to select DC hits belonging to the same Track
- Current progress:
 - DCTrackFinding algorithm is improved based on the track finding algorithm of Belle II
 - Have preliminary results, and they look good so far

The specific process of CKF

Basic procedure behind the CKF



loop All hits.

Select candidate hits

If retained,

track correction is required

Determine whether to retain

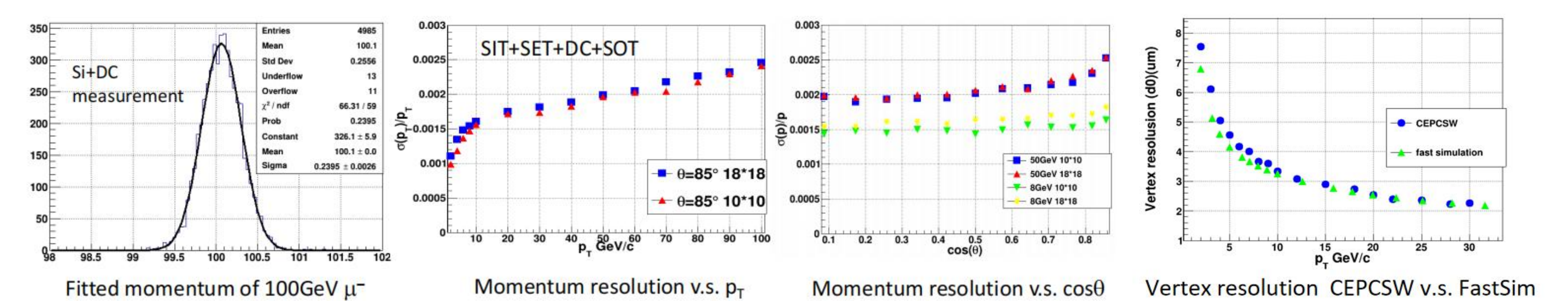
according to the residual

Extrapolate from position

and momentum

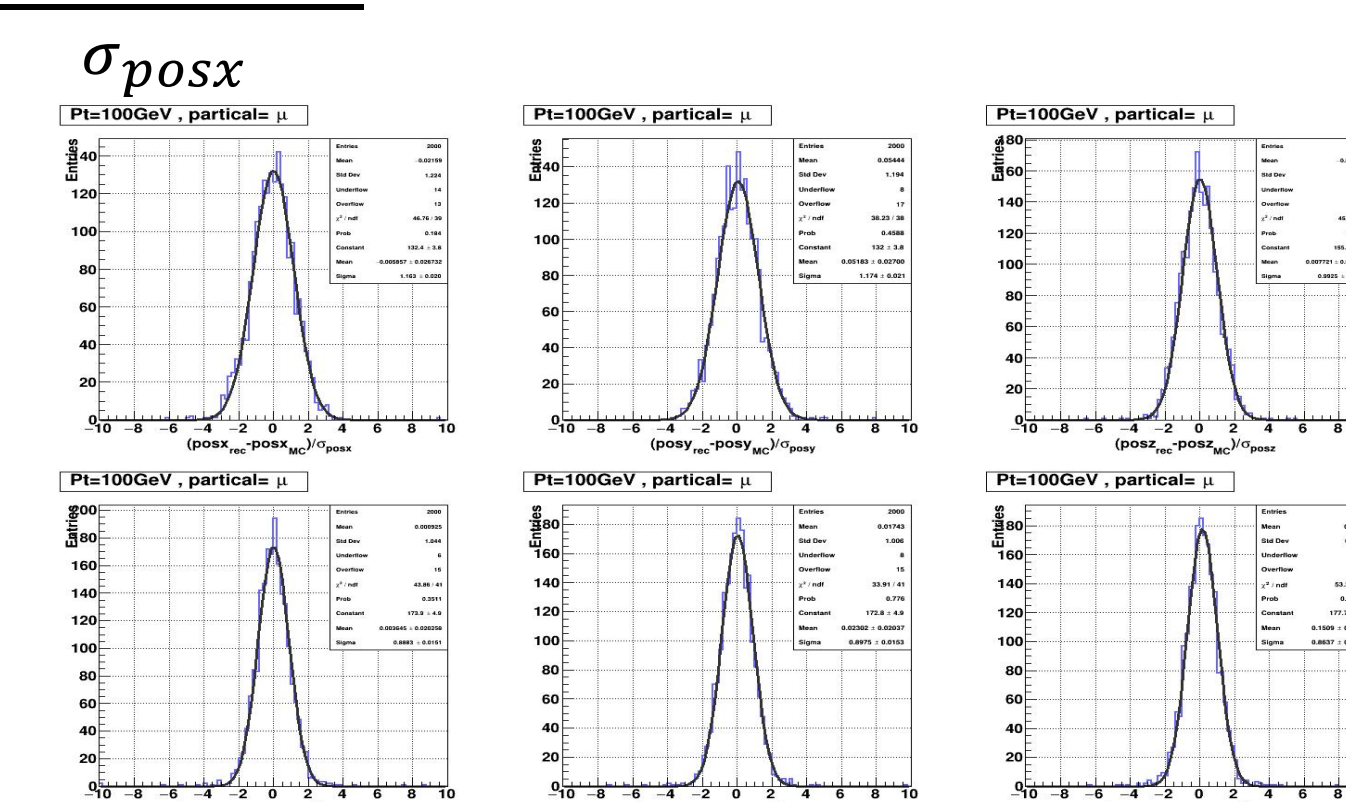
DC Track Fitting

- The track fitting is ready for release in CEPCSW
 - Use a Genfit as external libraries to do kalman track fitting
 - Intergrate Bfield, material and geometry from DD4hep and EDM4hep
- Track fitting with detector measurements is implemented
 - Track fitting combines the silicon detector and drift chamber
 - The preliminary result is consistent with fast simulation



- Check of track fitting algorithm

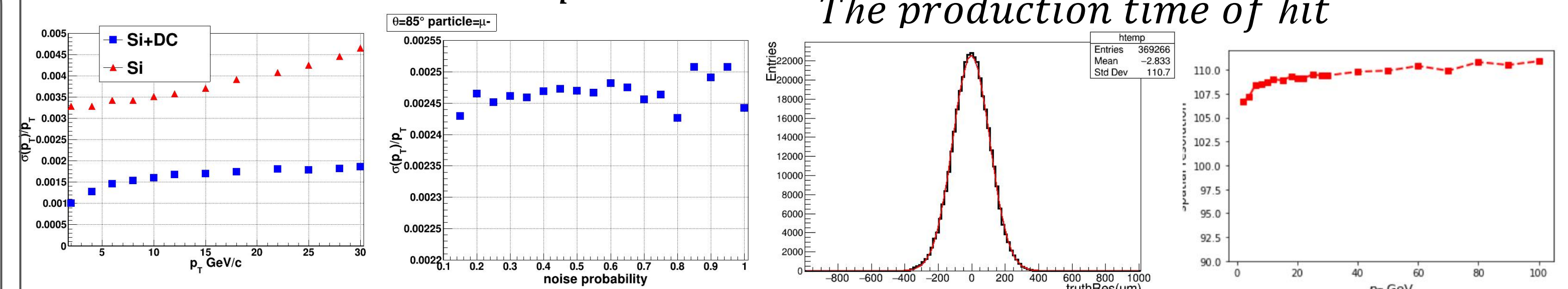
- 6 parameters ($pos_x, pos_y, pos_z, Mom_x, Mom_y, Mom_z$) distribution
- $pos_x - pos_{xMC}$



- Momentum resolution of Si vs Si+DC

- With a drift chamber, the momentum resolution is significantly better
- Add noise
 - If 10% of cells in each layer may generate noise, the probability that noise may overwrite hit is:

$$p = 10\% \times \frac{\text{The time of noise generation}}{\text{The production time of hit}}$$



- Spatially resolved distribution

- Residual = the closest distance of fitting track - the closest distance (doca)
- The spatial resolution set in the drift chamber is 110um, and the spatial resolution of the reconstructed tracks is about 110um, and the difference is within 2um