



Exploration of Matter in Extreme conditions with Machine Learning

Kai Zhou (FIAS) RHIC-BES Seminar

Outline

- Overview : 1, QCD matter in extreme; 2, AI/ML/DL techs
- Heavy Ion Collisions with ML
 - 1.1 Hot matter EOS identification from HIC with DL
 - 1.2 Online event impact parameter determination with Point-Net for CBM
 - 1.3 Bayesian Inference of dense matter EOS from HIC data
- Lattice QCD data analysis with ML

2.1 In-medium heavy quark potential reconstruction with DNN2.2 Unsupervised Spectral function reconstruction with DNN

- Neutron Star EOS inference with ML
- Summary

Overview : QCD matter in extreme

- Phases of matter : solid, liquid, gas, plasma
- Matter in extreme conditions reveals its constituents : <u>nuclear matter</u> → <u>quark matter</u>





"It would be intriguing to explore new phenomena by distributing high energy or high nuclear matter density over a relatively large volume." - T.D. Lee (1974)

To study QCD matter under extreme conditions :

- Nuclear Collisions : heat & compress matter
- Lattice Field Theory : numerically solve partition function
- Neutron Star : dense matter, astronomy constraints





Find and Decode the mapping/representations into Deep Neural Network

Universal approximator (Hastad et al 86 & 91)



Differentiable programming

Backward Propagation

Gradient Descent Algorithm

Overview: Machine learning, Deep Neural Networks, Representation learning





$$f_{NN}(x;\theta) = h_2(w_2h_1(w_1x + b_1) + b_2)$$



Overview: Deep Learning, Differentiable Programming and Automatic differentiation

Deep Learning composes differentiable components to a program, e.g. DNN, then optimizes it with gradients



<u>Chain rule for gradients</u>: $\frac{\partial \mathcal{L}}{\partial \theta} = \frac{\partial \mathcal{L}}{\partial T^n} \frac{\partial T^n}{\partial T^{n-1}} \cdots \frac{\partial T^2}{\partial T^1} \frac{\partial T^1}{\partial \theta}$ Defining <u>adjoint</u> variables : $\overline{T} = \partial \mathcal{L} / \partial T$

 $\frac{\partial T}{\partial \theta}$

$$\overline{T^{i}} = \overline{T^{i+1}} \frac{\partial T^{i+1}}{\partial T^{i}} \qquad \overline{\theta} = \overline{T^{1}}$$



$$\overline{T^{i}} = \sum_{j: \text{ child of } i} \overline{T^{j}} \frac{\partial T^{j}}{\partial T^{i}}$$

Overview: Discriminative and Generative learning

• Discriminative learning : prediction (classification / regression)

Function Fitting

y = f(x)

Conditional Probability $p_{\theta}(y|x) \rightarrow p(y|x)$

• Generative learning : **understand** (generation / clustering)

Joint Probability

$$p_{\theta}(x, y) \rightarrow p(x, y)$$

"What I can not create

I do not understand"



That I cannot reate, I do not understand. IN COMPANY & SOUT . PO Bethe Amenty Probs Know how to solve every problem that has been salved Non Linean Christer

Overview : Our focus of Matter Exploration in extreme with Machine Learning

Questions we will discuss \rightarrow



- Nuclear Collisions :
- Will early dynamic-info survive the evolution? How to decode?
- How to more effectively connect experiment to theory/model?
- Dense matter EoS underlies current low energy HIC observable
- Lattice QCD data:
- Could physical observable evaluation from configs and also partition function be captured by Machine Learning?
 - Inverse problem solving: convert measurement to physics?
- Neutron Star :
 - How to maximumly exploit the astronomy observation?



1.1, Hot matter EoS identification from Heavy Ion Collisions with Deep Learning

With **Longgang Pang**, Nan Su, Yilun Du, Jan Steinheimer, Lijia Jiang, Lingxiao Wang, Hanna Peterson, Horst Stoecker, Xinnian Wang, etc.,

Nature Communications 9 (2018), no.1, 210 JHEP 12 (2019) 122 Eur.Phys.J.C 80 (2020) 6, 516 Phys. Lett. B 811 (2020) JHEP 21 (2021) 184 Phys. Rev. D 103 (2021) 11, 116023

Challenges in heavy ion collisions



- Uncertainties in HIC modeling
- Multiple parameters <u>entangle</u> with multiple observables
- How to disentangle different factors to reveal fundamental physics from the dynamical environment?



L.G.Pang, K. Zhou, N.Su et al., Nature Commu.9 (2018), no.1, 210

Direct inverse mapping?



- Uncertainties in HIC modeling
- Multiple parameters <u>entangle</u> with multiple observables
- How to disentangle different factors to reveal fundamental physics from the dynamical environment?
- DNN make the road!



L.G.Pang, K. Zhou, N.Su et al., Nature Commu.9 (2018), no.1, 210

Prototype study of deploy AI to decode dynamical physics in Heavy Ion Collisions



- Conventional observable fail !
- Strongly depends on the initial fluctuations and other uncertainties

- ~ 95% EbE classification accuracy!
- Robust against initial condition, eta/s

Conclusion : Information of early dynamics can survive to the end of the hydrodynamics and encoded within the final state raw spectra, immune to evolution's uncertainties, with deep CNN we can decode it back.

Into more realistic cases

Eur.Phys.J.C 80 (2020) no.6,516

U+U 23 GeV/A



JHEP 12,122(2019)

M.O.K, J.S, K. Zhou, et at., Phys. Lett. B 811, 135872 **JHEP** 21 (2021) 184

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1.2, End-to-End Online Event Characteristics for CBM with PointNet

With Manjunath O.K, Jan Steinheimer, Andreas Redelbach, Horst Stoecker

Phys.Lett.B 811 (2020) 135872 Particles 2021, 4(1), 47-52

Motivation : point cloud data structure, and CBM challenge

- Experimental data has inherent point cloud structure
 - Point clouds: collection of points in space
- Point clouds are represented as 2D array.
 - each row= a point in the point cloud
 - each column =a dimension of the point cloud
- PointNet based models learn directly from point clouds.
 - respects the order invariance of point clouds
 - direct processing of experimental data
- Advantages:
 - less processing time ⇒ideal online algorithm
 - optimal for higher dimensional data
- We consider the CBM experiment as a use case
 - Au-Au collisions
 - 10 AGeV
 - CBM Challenges 🚽





Upto 45 AGeV collisions

1000 tracks per collision

TBytes/Second raw data

107 collisions/ Second



- STS-> 8 planes
 - Momentum resolution: 1 %

Take impact parameter for example

- 'b' is not directly measurable in exp
- Final state observables carry the information
 - MC Glauber
 - Percentiles of Nch, Espec are mapped to centrality
 - Only a likely distribution for b in a centrality bin is known







- Works on direct exp. output
- Event-by-event online possible
- Training data generated by
 'UrQMD → CbmRoot'
 10^5 Au+Au 10 AGeV events
 b ~ (0-16)fm



Test Result : resolution, accuracy, more actual case ?





1.3, Bayesian inference of high density EoS from low energy heavy ion collisions

With Manjunath O.K, Jan Steinheimer, Horst Stoecker

To be online soon

The EoS parameterization, the flow and transverse kinetic energy measurements



Emulator with Gaussian Process

- $Obs_i(\boldsymbol{\theta}) \sim GP(\mu(\boldsymbol{\theta}), \kappa(\boldsymbol{\theta}, \boldsymbol{\theta}'))$
- Performance of the trained GP Models : $R^2 \sim 0.9$

0.32

0.40





Closure tests

- Posterior ~ Likelihood * Prior
- Reconstruct well the EoS to 4-6 n_0
- Drop the first 2 points of m_T ? not influence 2-3.5 n_0 but matters for 4-6 n_0





Inference results with experimental data, and predictability





2.1 Basic applications in Lattice calculation for QFT or many-body system

With Gergely Endroedi, Long Pang, Horst Stoecker, Lingxiao Wang, Yin Jiang, Shile Chen, Oleg Savchuk, Lianyi He

Phys.Rev.D 100,011501(R) (2019) arXiv:2005.04857 arXiv:2007.01037

DNN into Quantum Field Theory

• Discriminative DL methods for phase classification and physics regression:



• Generative models for more efficient config sampling and physics decoding:

K. Zhou, et.al, Phys.Rev.D 100,011501(R) (2019)











Exploring Many-Body System Phase Structure Unsupervisedly

• Boltzmann distribution for statistical system (e.g. Field, or simply XY model)

$$p(\phi) = \frac{1}{Z} e^{-S(\phi)} \qquad p(\mathbf{s}) = \frac{e^{-\beta E(\mathbf{s})}}{Z}$$

• Variational approach (e.g. mean field theory) : minimize variational Free Energy

$$F_q = \frac{1}{\beta} \sum_{\mathbf{s}} q_{\theta}(\mathbf{s}) \left[\beta E(\mathbf{s}) + \ln q_{\theta}(\mathbf{s})\right] \qquad D_{\mathrm{KL}}(q_{\theta} \parallel p) = \sum_{\mathbf{s}} q_{\theta}(\mathbf{s}) \ln \left(\frac{q_{\theta}(\mathbf{s})}{p(\mathbf{s})}\right) = \beta(F_q - F_q)$$

Introduce more expressive Ansatz with neural network : <u>autoregressive net</u> or Flow model
 D. Wu, et.al., PRL122,080602(2019)

$$q_{\theta}(\mathbf{s}) = \prod_{i=1}^{N} q_{\theta}(s_i \mid s_1, \dots, s_{i-1}) \qquad \hat{s}_i = \sigma \left(\sum_{j < i} W_{ij} s_j \right) = q(s_i = +1 \mid \mathbf{s}_{< i})$$

• generalize to continuous variable systems? Like, for XY model :

$$H = -J \sum_{\langle i,j \rangle} s_i s_j = -J \sum_{\langle i,j \rangle} \cos(\phi_i - \phi_j)$$

Continuous-mixture Autoregressive Network

$$f_{\theta}(s_i|s_1, ..., s_{i-1}) = \frac{\Gamma(a_i + b_i)}{\Gamma(a_i)\Gamma(b_i)} s_i^{a_i - 1} (1 - s_i)^{b_i - 1}$$

L.Wang, Y. Jiang, L.He, **K.Zhou** arXiv:2005.04857

 F_q

Continuous-mixture Autoregressive Network





2.1 From IQCD to in-medium HQ interactions

With Shuzhe Shi, Jiaxing Zhao, Swagato Mukherjee, Pengfei Zhuang

Phys. Rev. D 105 (2022) 1, 1

Large mass scale : $m_Q >> \Lambda_{QCD}$, T, p

- Produced via <u>Hard Processes</u> from early stage
- 'Calibrated' <u>QCD Force</u> HQ interaction

In Vacuum : NR potential (NRQCD) , Cornell-like V(r)

 $V(r) = -\frac{\alpha}{r} + \sigma r + B$

In Medium : Color Screening , Thermal Width

Laine, et.al, JHEP(2007)

Potential model : Inverse Schrödinger equation



Flow chart for "DNN + Schrödinger Eq."



Phys. Rev. D 105 (2022) 1, 1





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 $r (\text{GeV}^{-1})$

Closure Test – reconstruct HTL potential

Provide mass and width of
1S, 2S, 3S, 1P, and 2P states.
@(0, 151, 173, 199, 251, 334) MeV



Results with lattice data for HQ potential

nS

nP

300

250



Chi2-per-data=16.5/30

The reconstructed T, r dependent potential





2.3 Spectral function reconstruction from Euclidean correlator



NeurIPS2021 ''Machine learning and the Physical Science'', arXiv:2112.06206 Phys. Rev. D 106, L051502 (Letter), arXiv: 2111.14760 Computer Physics Communications (2022) 108547, arXiv: 2201.02564





3, Dense matter EoS reconstruction for Neutron Star from M-R observation

With Shriya Soma, Lingxiao Wang, Shuzhe Shi and Horst Stoecker

JCAP08(2022)071 (arXiv:2201.01756) arXiv:2209.08883

From EoS to Stellar Structure (MR)

- Mass ~ 2 solar masses
- Radii ~ 10 km
- Densities ~ 8 ρ_0



• Gravity $\leftarrow \rightarrow$ Pressure

$$rac{dP}{dr} = -rac{G}{r^2}\left(
ho+rac{P}{c^2}
ight)\left(m+4\pi r^3rac{P}{c^2}
ight)\left(1-rac{2Gm}{c^2r}
ight)^{-1}$$

$$M=m(R)=\int_0^R 4\pi r^2
ho\,dr$$

Dense matter Equation of State

 $P(\rho)$

1-to-1 mapping from EoS to M(R)

Micro to Macro





 $-\frac{dP}{dr} = \frac{\left[\epsilon(r) + P(r)\right] \left[M(r) + 4\pi r^3 P(r)\right]}{r[r - 2M(r)]}$

$$\frac{dM(r)}{dr} = 4\pi r^2 \epsilon(r),$$





Infer matter's EoS inside NS from M(R)







S.Soma, L.Wang, S.Shi, H. Stoecker, and K. Zhou, JCAP08(2022)071



Generalized Bayesian Inference :

- The EoS is represented by DNN universal, unbiased, but more params
- The TOV eqs solving is replaced by a well-trained DNN
- Gradient based optimization and sa mpling for M-R data

Validate on closure tests w/o and with noise



Neutron Star Observables



With real observables



Conclusion

We demonstrated that physics of early dynamics (e.g. EoS, CME, centrality info.) in heavy ion collisions can survive into final states, with its signal can be decoded by machine learning and immune to model uncertainties. <u>ML thus constructs an efficient</u> <u>bridge in connecting theory to experiment for physics exploration!</u>

Inverse Problems happened in nuclear physics can be well handled/improved by deep learning based solving, e.g. for real-time potential, spectral function reconstruction, neutron star EoS constraining.

Generative deep learning models can help many-body physics in efficient sampling, mitigating critical slowing-down, represent ensemble of configs in one setup (Net)



- Physics Priors are needed for solving the inverse problem , coult be put into :
- 1, **training data (Implicit) :** train **proper DNN** to learn the inverse mapping can learn directly the general mapping, avoid case-specific retraining
- 2, **inference process (Explicit) :** Chi2 fit+**Bayesian** inference+Gradient Descent <u>Automatic differentiation</u> and <u>Network representation</u>

Result : model dependency ?



Perturbation on Schroedinger Eq.

$$\left(\frac{\hat{p}^2}{2m} + V(r)\right) |\psi_i\rangle = E_i |\psi_i\rangle,$$

$$\left(\frac{\hat{p}^2}{2m} + V(r) + \delta V(r)\right) |\psi_i'\rangle = (E_i + \delta E_i) |\psi_i'\rangle.$$

$$|\psi_i'\rangle = |\psi_i\rangle + \sum_{j\neq i} \frac{\langle \psi_j | \delta V(r) | \psi_i \rangle}{E_i - E_j} |\psi_j\rangle.$$

Hellmann-Feynman theorem

Phys. Rev. (1939)

$$\delta V(r) = v \,\delta(r - r_k), \quad \Box \Longrightarrow$$

$$\frac{\delta m_i}{\delta V_R(r)} = -\frac{\delta \Gamma_i}{\delta V_I(r)} = |\psi_i(r)|^2,$$
$$\frac{\delta m_i}{\delta V_I(r)} = \frac{\delta \Gamma_i}{\delta V_R(r)} = 0.$$

Uncertainty Estimation – Bayesian Inference

Posterior($\boldsymbol{\theta}$ |data) $\propto L(\boldsymbol{\theta}$ |data) · Prior($\boldsymbol{\theta}$).

 $L(\boldsymbol{\theta}|\text{data}) = P(\text{data}|\boldsymbol{\theta}) \propto \exp[-\chi^2(\boldsymbol{\theta})/2].$

Posterior(
$$\boldsymbol{\theta}$$
|data) = $N_0 \exp\left[-\frac{\chi^2(\boldsymbol{\theta})}{2} - \frac{\lambda}{2}\boldsymbol{\theta} \cdot \boldsymbol{\theta}\right]$

 $\operatorname{Prior}(\boldsymbol{\theta}) \propto \exp[-\frac{\lambda}{2}\boldsymbol{\theta} \cdot \boldsymbol{\theta}].$

Sample potentials ~ $P(V_{\theta}(T, r)) = \text{Posterior}(\theta | \text{data})$.

Reference Sampler ~
$$\widetilde{P}(\theta) = (2\pi)^{-N_{\theta}/2} \sqrt{\det[\Sigma^{-1}]} \times \exp\left[-\frac{\Sigma_{ab}^{-1}}{2}(\theta_a - \theta_a^{\text{opt}})(\theta_b - \theta_b^{\text{opt}})\right]$$
 $\left(\Sigma_{ab}^{-1} \equiv \frac{\partial^2 J(\theta)}{\partial \theta_a \partial \theta_b}\right)$

re-weighting with : $\omega(\theta) = p(V_{\theta}(T,r))/\tilde{p}(\theta)$ to grantee posterior sampling