



# Fast simulation of the 4th detector at CEPC with Delphes

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### Outline

- Introduction
- Implementation and validations of CEPC new detector
  - Tracker
  - Particle identification(PID)
  - Calorimeter
- Summary

### The Delphes

- Delphes is a modular framework that simulates the response of a multipurpose detector
- Includes:
  - charged particle propagation in B field
    - Full Covariance
  - EM/Had calorimeters
  - particle-flow
  - •
- Provides:
  - tracks, photons, neutral hadrons
  - Lepton/photon isolation
  - Jets(eekt), missing energy



### Fast simulation of the 4th detector at CEPC

- Delphes can provide a way for physics studies at a fast speed but it is unsatisfactory in simulation of CEPC detector
- In order to physics with new CEPC detector more work
  - Implement the detector with a tcl card
  - Provide a dedicated PID module
  - Provide more flexibility between lepton/photon isolation and jet cluster

### The detector layout

- VTX(Vertex Detector):
  - Six high spatial resolution pixel detector.
  - Accurate measurement of charged particle track parameters
- Drift Chamber:
  - A cylinder with an inner diameter of 0.6 m and an outer diameter of 1.8 m.
  - Determine the momentum of charged particle
- Silicon Tracker:
  - Consist of SIT(Silicon Inner Tracker), FTD(Forward Tracking Detector), SET(Silicon External Tracker), ETD(Endcap Tracking Detector).

R(m)

Provide high precision information of collision points on the trajectory.

- Calorimeter
- Superconducting magnets
- Muon Detector



#### Inner diameter from 0.8m to 0.6m

### Tracker performance







### PID

- **PID** to identify *e*, *μ*, *π*, *K*, *p*, according to the different mass among different particles
- Hadron PID : identify  $\pi$ , K, p in Drift Chamber
- Electromagnetic PID : identify  $e, \mu$  using Energy Calorimeter and Muon Detector



• Pion and kaon identification is always the hardest, because the mass of proton is much greater than pion's and kaon's.

### Hadron PID

- Calculate the probabilities of particles by assuming their masses
  - *π*, *K*, *p* ···

• The most likely assumption is taken



### The calculation of the probability

Define chi-square:

 $(\chi^i)^2 = (\chi_1^i)^2 + (\chi_2^i)$  (It follows a Chi-square distribution of 2 degrees of freedom)







Compare the probabilities **The most likely assumption is taken** 

### K/pi Separation Power(dN/dx)

Consider effect of cluster counting efficiency as a function of dN/dx in xy plane

 $\varepsilon_{counting} = \frac{dN/dx_{meas}}{dN/dx_{real}}$ 

Cluster counting efficiency curve is tested with 2% noise





#### Ideal vs consider cluster counting efficiency



Only considering  $\pi$  and K later 11

### PID efficiency only using dN/dx and tof respectively

# $\frac{n_{sel}}{n_{tot}^{K}}$

- $\epsilon^{K}$  is Kaon PID efficiency
- $n_{sel}^{K}$  is number that K is identified as K  $(Prob^k > Prob^{\pi})$
- $n_{tot}^{K}$  is number of K

#### dominant in the low momentum range

kaon PID efficiency ( $|\cos\theta| < 0.854$ )



#### dominant in the high momentum range

### **PID** efficiency

#### Combine dN/dx and tof



When  $|\cos\theta| < 0.90$ , The PID performance is better

As momentum increases, efficiency decreases quickly

### **Calorimeter Resolution**

Set the resolution formula as a function of energy:

$$\frac{\sigma_E}{E} = \frac{a}{\sqrt{E}} \oplus \frac{c}{E} \oplus b$$

- a , stochastic term:Fluctuations in the number of signal generating processes
- c, noise term:Noise in readout electronics, 'pile-up' due to other particles from other collision events
- b , constant term:Imperfections in calorimeter construction,Nonuniform detector response,etc.

Ignoring the noise term,

- for ECAL, set  $a_E = 0.03$ ,  $b_E = 0.01$
- for HCAL:set  $a_H = 0.4, b_H = 0.02$ consider  $H \rightarrow \gamma \gamma$ ,  $H \rightarrow gg \rightarrow 2$  jets, draw the invariant mass spectrum

### Gamma and jet

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Mean =  $124.99 \pm 0.002$  GeV, Resolution =  $0.96 \pm 0.01$  GeV



Mean =  $125.82 \pm 0.013$  GeV, Resolution =  $4.78 \pm 0.013$  GeV

### Summary

- Simulation of CEPC the 4th detector with Delphes is ready to use
  - The detector layout is implemented and validated
  - PID : probabilities of different hypotheses of tracks provided for analyzers
  - Guarantee there is no overlap between lepton/photon isolation and jet clustering with eekt
- Still many works need to do
  - More validation
  - updates according to detector optimization.
  - More realistic simulation of dN/dx and cluster counting efficiency curve will be improved
  - ...
- Welcome to use and feedback!

### **Thanks!**

# Backup

### Tracker layout

Detector	Layer	Radius(mm)	Halfz(m)	Material budget[x/X0]
VXD(	1	16	0.2	0.0015
	2	18	0.2	0.0015
	3	38	0.2	0.0015
	4	40	0.2	0.0015
	5	58	0.2	0.0015
	6	60	0.2	0.0015
Shell	1	65	0.2	0.0015
SIT	1	120	0.241	0.0065
	2	270	0.455	0.0065
	3	420	0.721	0.0065
	4	570	0.988	0.0065
Inner wall	1	600	2.98	0.00104
DC	80	600-1800	2.98	0.002
Outer wall	1	1800	2.98	0.01346
SET	1	1815	2.98	0.0065

### Tracker layout

Detector	Rin(mm)	Rout(mm)	Z(m)	Material budget[x/X0]
DSK1A	29.5	120	0.241	0.0065
DSK1B	29.5	120	-0.241	0.0065
DSK2A	30.5	270	0.455	0.0065
DSK2B	30.5	270	-0.455	0.0065
DSK3A	32.5	420	0.721	0.0065
DSK3B	32.5	420	-0.721	0.0065
DSK4A	34	570	0.988	0.0065
DSK4B	34	570	-0.988	0.0065
ETD1	600	1822	3.0	0.0065
ETD2	600	1822	-3.0	0.0065

### The calculation of $\chi$

• dN/dx 
$$x_1^i = \frac{(dN/dx)_{meas} - (dN/dx)_{exp}^i}{(\sigma)_{dN/dx}^i}$$
  
• dN/dx and  $(\sigma)_{dN/dx}$  are functions of  $\beta\gamma$   
•  $dN/dx_{exp} = f(\beta\gamma) * \varepsilon_{counting}$  (f is the theoretical function that only depends on  $\beta\gamma$ )  
•  $(\sigma)_{dN/dx} = \varepsilon_{counting} * \sqrt{f(\beta\gamma)}$   
• In the formula:  
•  $(dN/dx)_{exp}$  and  $(\sigma)_{dN/dx}$  are calculated with  $\beta\gamma$ 's for 5 particle hypotheses  
•  $(dN/dx)_{meas}$  follows a Poisson distribution with mean and sigma calculated with the truth  $\beta\gamma$   
• TOF  $x_2^i = \frac{(tof)_{meas} - (tof)_{exp}^i}{(\sigma)_{tof}^i}$   
•  $(tof)_{exp} = \frac{L}{v} = \frac{L}{\beta c}$   $\beta = \frac{p}{\sqrt{p^2 + (m^i)^2}}$   
•  $(tof)_{meas}$ : follows a Gaussian distribution with mean =  $(tof)_{exp}$  and  $(\sigma)_{tof}$   
•  $(\sigma)_{tof} = 30ps$