



Optimal transport solutions for pileup mitigation at hadron colliders

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TOTAL PU mitigation

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PU mitigation at hadron colliders

PUPPI

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PUPPIML

SSPUPPI

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General idea

Loss function: SWD

Model

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QCD multijet

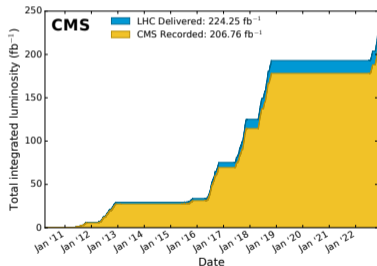
$t\bar{t}$ production

Particle weights

Robustness

Conclusions

PU mitigation at hadron colliders



- At the LHC, usually interested in rare, **head-on pp collisions**
- Maximize probability of head-on collisions by **squeezing the proton bunches** as much as possible
- **Keep instantaneous luminosity high**
- High integrated luminosity \implies better physics outcome
- **Drawback:** non-negligible probability of having **more than one pp collision** per bunch crossing

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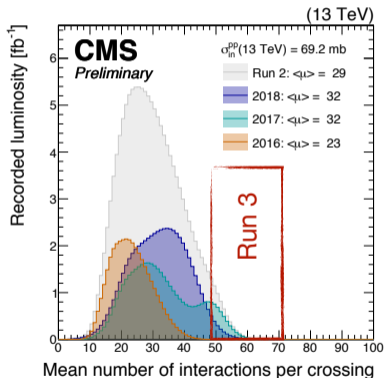
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PU mitigation at hadron colliders



- **Pileup**: additional pp collisions superimposing to main collision
- **PU** has **increased** in Run3 ($\langle n_{\text{PU}} \rangle = 50$) and will increase in HL-LHC ($\langle n_{\text{PU}} \rangle = 140$)
- Will severely **degrade quality of observables** (jet multiplicity, jet substructure, ...) if not properly treated
- **Easy task for charged particles**: use tracking information to disentangle particles
- **Very challenging for neutral particles**

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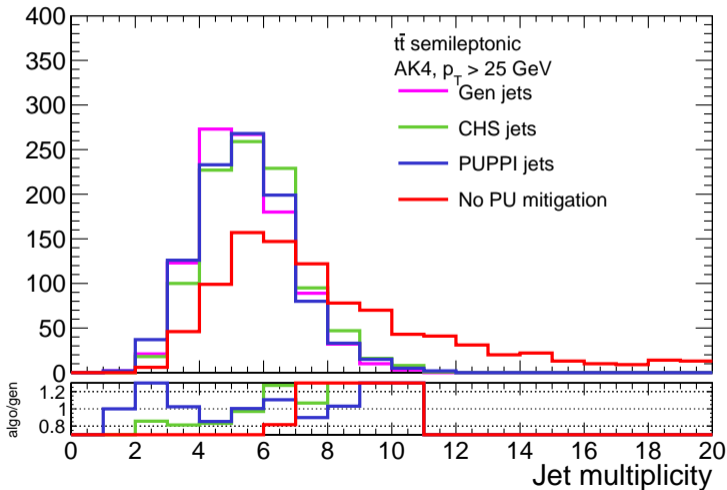
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How bad is pileup?



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State-of-the-art at CMS: PUPPI [1407.6013]



- Starting from Run3, **default PU mitigation technique** in CMS is **PUPPI**
- Rule-based** algorithm
- Calculates a weight $w \in [0, 1]$ for each particle in the event
 - Encodes the probability for a particle to be LV or not
 - Weight used to **reweight the particle 4-momentum before jet clustering**
- For charged: use tracking information and assign 0 or 1
- For neutrals: build α variable

$$\alpha_i = \log \sum_{j \neq i, \Delta R_{ij} < R_0} \left(\frac{p_{Tj}}{\Delta R_{ij}} \right)^2 \begin{cases} |\eta_i| < 2.5 & j \text{ are all charged particles from LV} \\ |\eta_i| > 2.5 & j \text{ are all kinds of particles} \end{cases}$$

- QCD is harder and more collimated than PU \implies higher α than PU

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- To translate into a weight, compare each particle's α with the mean and RMS of PU particles

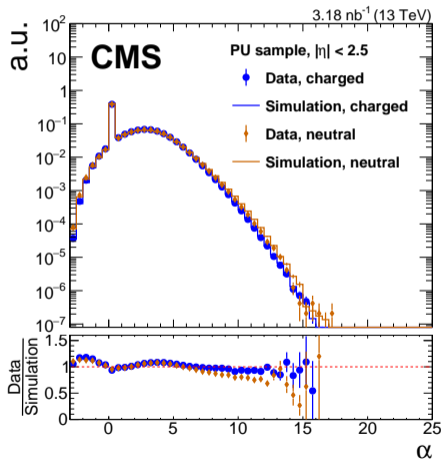
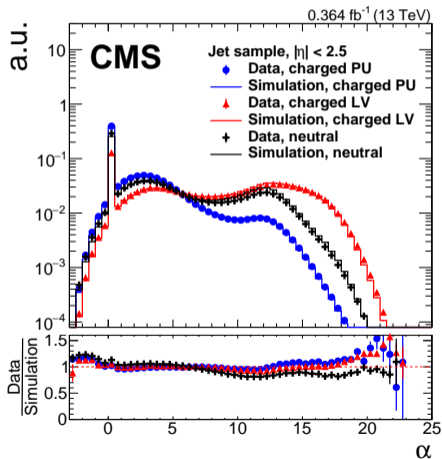
$$\text{signed}\chi_i^2 = \frac{(\alpha_i - \bar{\alpha}_{\text{PU}})|\alpha_i - \bar{\alpha}_{\text{PU}}|}{(\alpha_{\text{PU}}^{\text{RMS}})^2}$$

- Use **charged particles** for $\bar{\alpha}_{\text{PU}}$ and $(\alpha_{\text{PU}}^{\text{RMS}})^2$ computation
- Finally, assume $\text{signed}\chi^2$ follows a χ^2 distribution and assign weight based on CDF

$$w_i = F_{\chi^2, \text{NDF}=1}(\text{signed}\chi^2)$$

- **LV particle** \implies large $\text{signed}\chi^2 \implies$ large CDF \implies **large weight**
- **PU particle** \implies small $\text{signed}\chi^2 \implies$ small CDF \implies **small weight**

State-of-the-art at CMS: PUPPI [1407.6013]



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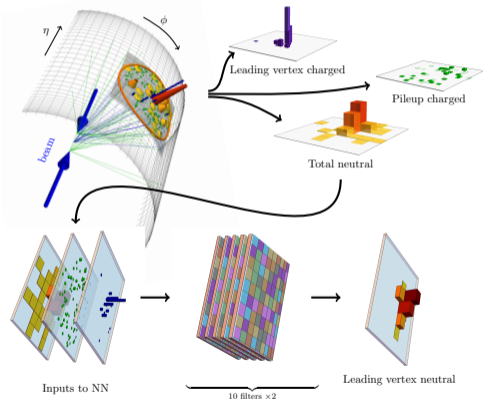
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PileUp Mitigation with Machine Learning: PUMML

[1707.08600]



- **Treat jets as squared images, use CNNs**
- **Input is a three-channel image**
 - Charged radiation from LV
 - Charged radiation from PU
 - Total neutral radiation
- **Output is regressed neutral radiation from LV**
- **Image-based approach overlooks complex detector geometry**

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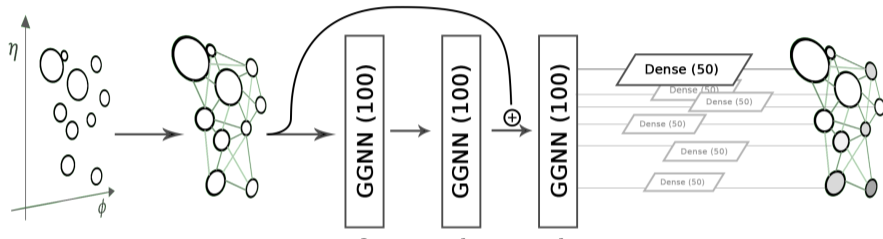
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PUPPI with Machine Learning: PUPPIML [1810.07988]



- PUPPI is based on **local information**: use **GNN** to collect it in **more expressive** ways
- Developed at Delphes particle-level (before interaction with the detector)
- **Fully supervised**: use **truth-labels** coming from Delphes simulation
- These are **not available in full Geant4**-based simulations!

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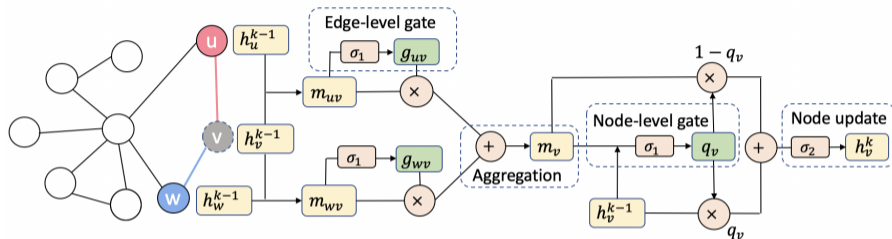
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Semi-supervised PUPPI [2203.15823]



- PUPPI is based on **local information**: use **GNN** to collect it in **more expressive** ways
- Developed at Delphes particle-level (before interaction with the detector)
- **Semi-supervised**: train on charged (labels exist in Geant4 as well), apply on neutrals
- Can train on data, but **requires extrapolations** (charged \rightarrow neutrals, central \rightarrow forward)

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Overview of PU mitigation techniques



- Currently in use (e.g., CMS): **PUPPI** [[1407.6013](#)]
 - **Rule-based** algorithm
 - For each neutral particle, consider the energy of neighboring particles
 - Extract a probability for the particle to be LV or PU
 - Relies on properties of charged particles and **extrapolates to neutrals**
- Nature and complexity of task inspired **machine-learning-based approaches**
 - PUMML: treat jets as images, reconstruct LV neutral radiation [[1707.08600](#)]
 - PUPPIML: use GNN, rely on Delphes truth labels [[1810.07988](#)]
 - Semi-supervised PUPPI: train on charged, apply on neutrals [[2203.15823](#)]
- **Recurring problem**: lack of truth **labels for neutrals** in full simulation
- We developed a **new ML-based approach** to overcome this bottleneck
 - Use **Attention-Based Cloud Network** (ABCNet, [[2001.05311](#)]) **combined with optimal transport**
 - **TOTAL: Training Optimal Transport with Attention Learning**
 - Train model on a Delphes-based simulation of the CMS Phase2 detector

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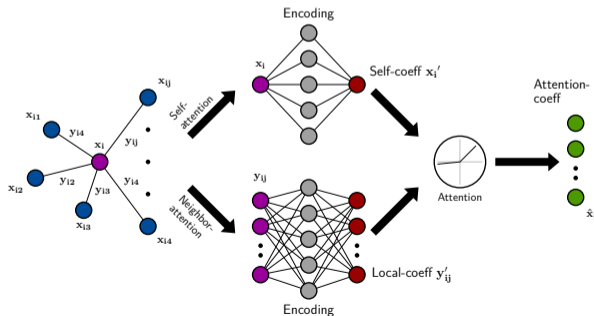
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Attention-Based Cloud network



- ABCNet is an **graph neural network** enhanced **with attention mechanisms**
 - Treat particle collision data as a set of permutation-invariant objects
 - Attention mechanisms filter out the particles that are not relevant for the learning process
- Implemented inside custom **graph attention pooling layers** (GAPLayers)



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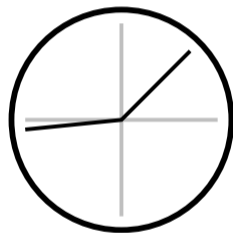
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Attention

- Add together self- (x'_i) and local- (y'_{ij}) coefficients and apply non-linearity

$$c_{ij} = \text{LeakyRelu}(x'_i + y'_{ij})$$

- Align coefficients c_{ij} by applying SoftMax

$$c'_{ij} = \frac{\exp(c_{ij})}{\sum_k \exp(c_{ik})}$$

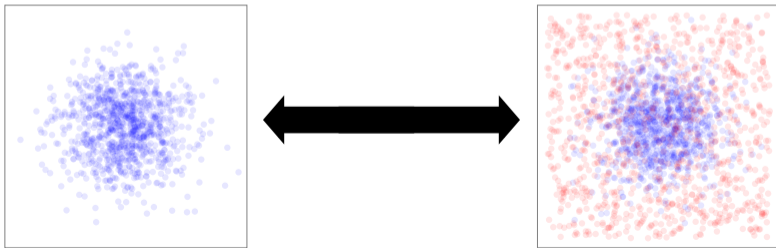
- Get attention coefficients by multiplying y'_{ij} by c'_{ij}

$$\hat{x}_i = \text{Relu} \left(\sum_j c'_{ij} y'_{ij} \right)$$

A novel approach to PU mitigation



- Definition of truth labels is highly non trivial in simulations at hadron colliders
- **Our approach:** simulate **identical** proton-proton **collisions in two scenarios**
 - ① Only the hard interaction is simulated: **no-PU sample**
 - ② Pileup is superimposed to the hard interaction: **PU sample**
- **Do not assign per-particle labels:** rather just assign a “global” label to samples
- Train network to **learn differences between the two samples**



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How to learn: OT concepts for a loss function



- We build a custom **loss inspired by optimal transport** ideas (OT)

- OT example: the **Earth Mover's Distance** is the minimum work to move **earth** to fill some **holes**

$$EMD(\vec{x}, \vec{y}) = \min_f W(f, \vec{x}, \vec{y})$$

- With OT you can **match distributions** (e.g., earth-holes)
- We want to match the distributions for the no-PU particles and **PU particles weighted by an ABCNet weight** ($\vec{\omega}$)

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Limitation of the EMD loss function



- Using the **EMD loss comes with some limitations**
 - We consider 9000 particles per event
 - **High computational cost:** feasible flows f are 9000x9000 matrices
 - Can only match **3D distributions**
 - We worked on a modified loss to
 - **Match higher-dimensionality distributions**
 - Solve OT efficiently
 - **Sliced Wasserstein Distance (SWD)**

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Efficient OT: sliced Wasserstein distance (SWD)



- The optimal transport problem has a **closed form for 1D problems**:

$$W_c(p_X, p_Y) = \int_0^1 c\left(P_X^{-1}(\tau), P_Y^{-1}(\tau)\right) d\tau$$

where p_X, p_Y are 1D PDFs, $P_X^{-1}(\tau), P_Y^{-1}(\tau)$ are the respective CDFs and $c(\cdot, \cdot)$ is the transportation cost function

- No guarantee that the integral is solvable (it depends on the form of $c(\cdot, \cdot)$)
- The **integral can always be approximated** by the finite sum

$$\frac{1}{M} \sum_{m=1}^M c\left(P_X^{-1}(\tau_m), P_Y^{-1}(\tau_m)\right), \quad \tau_m = \frac{2m-1}{2M}$$

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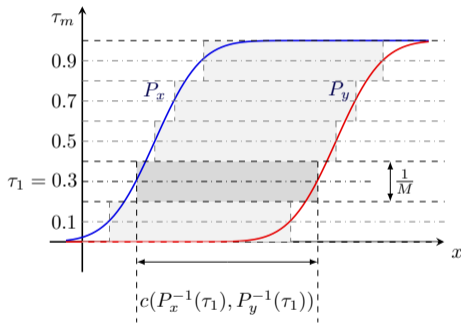
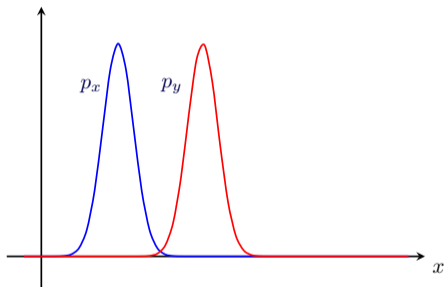
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Example: $M = 5$



• $m \in \{1, 2, 3, 4, 5\} \implies \tau_m = \frac{2m-1}{2M} \in \{0.1, 0.3, 0.5, 0.7, 0.9\}$

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Efficient OT: sliced Wasserstein distance (SWD)



- In the **special case of discrete distributions** (discrete in nature, or resulting from a sampling), PDFs are sums of Dirac's deltas

$$p_x = \frac{1}{M} \sum_{m=1}^M \delta(x - x_m); \quad p_y = \frac{1}{M} \sum_{m=1}^M \delta(y - y_m);$$

- The integral of a Dirac's delta is the Heaviside's step function $\Theta \implies \implies$ CDFs are Heaviside functions

$$P_x(t) = \int_{-\infty}^t p_x(z) dz = \frac{1}{M} \int_{-\infty}^t \sum_{m=1}^M \delta(z - x_m) dz = \frac{1}{M} \sum_{m=1}^M \Theta(t - x_m)$$

- **If we sort the samples by feature**, the CDFs become a **sum of steps**

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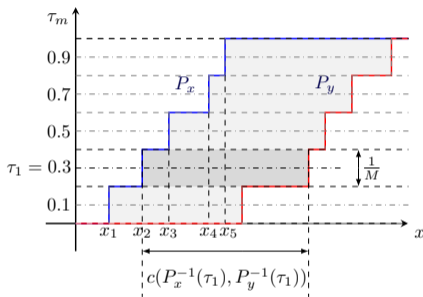
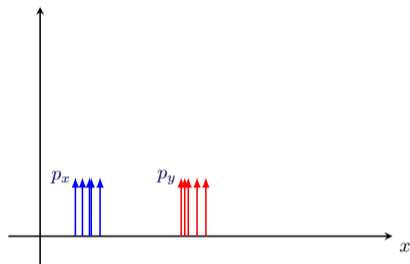
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- $m \in \{1, 2, 3, 4, 5\} \implies \tau_m = \frac{2m-1}{2M} \in \{0.1, 0.3, 0.5, 0.7, 0.9\}$

- Note that

$$P_x^{-1}(\tau_m) = x_m; \quad P_y^{-1}(\tau_m) = y_m$$

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- Note that

$$P_x^{-1}(\tau_m) = x_m; \quad P_y^{-1}(\tau_m) = y_m$$

- Therefore

$$W_c(p_X, p_Y) = \frac{1}{M} \sum_{m=1}^M c(P_X^{-1}(\tau_m), P_Y^{-1}(\tau_m)) = \frac{1}{M} \sum_{m=1}^M c(x_m, y_m)$$

- The **1D OT problem is reduced to a sorting** of the 1D feature
 - Fast and easy to solve**

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CHECKPOINT

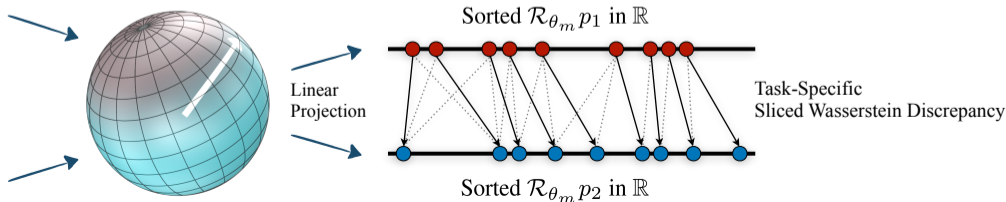
- ① Optimal transport problem has a closed form in 1D
- ② For sampled distributions, the problem is reduced to a sorting of the 1D feature
- ③ Particles have multi-dimensional distributions though. How to apply this?



Efficient OT: sliced Wasserstein distance (SWD)

- Each particle is a sample from a n -D feature space
- **SWD**: take n -D feature space and **project (slice)** it to 1D
- Project on a vector belonging to S^{n-1}
- For robustness, take **multiple random slices**

- Now can **solve the 1D OT problem for each slice**
- **Sort particles by slice**
- The **average on all slices and particles** becomes the **loss function**



Energy conservation in OT: MET constraint



- SWD focuses on the optimal matching between individual particles in no-PU and PU samples
 - No guarantee that energy is conserved between the two
- Add an **event-level MET constraint** term to the loss
 - Enforce energies in no-PU and PU events to be similar
- Final loss function:

$$\mathcal{OT} = \text{SWD}(\vec{x}_p \cdot \vec{\omega}, \vec{x}_{np}) + \text{MSE}(\text{MET}(\vec{x}_p \cdot \vec{\omega}), \text{MET}(\vec{x}_{np}))$$

where \vec{x}_p = PU sample; \vec{x}_{np} = no-PU sample; MSE = mean squared error

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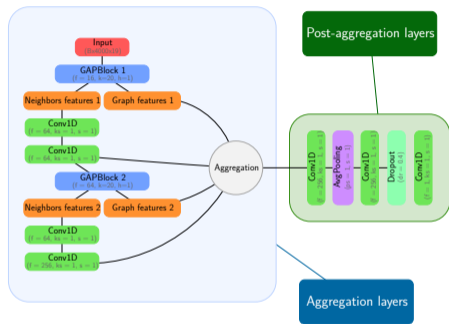
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The model



- **9 input features:**

- (p_T, η, ϕ, E)
- Charge
- PDG ID
- dXY & dZ impact parameters
- PUPPI weight

- **Loss:** $\text{SWD}(\vec{x}_p \cdot \vec{\omega}, \vec{x}_{np}) + \text{MET constraint}$

- **Cost function:** squared distance

- **Sliced features:** (p_T, η, ϕ, E)

- **Output:** per-particle weight $\vec{\omega}$

- Train on **300k events**, equally split between QCD multijet, $t\bar{t}$ dileptonic and VBF Higgs(4ν) processes
- Consider **9000 particles per event** (zero-padding included)
- Gather the **20 k-nearest neighbors** for each particle when building graph

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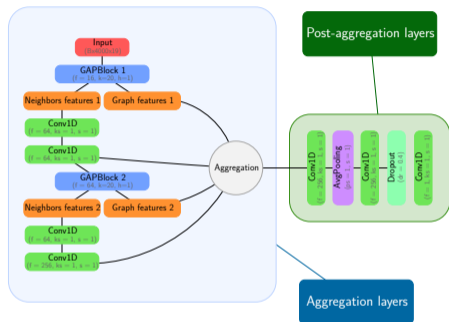
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The model



- **Compare TOTAL with PUPPI and no-PU** scenario
- **Reweight** each particle's 4-momentum by the network weight
- **Cluster** TOTAL jets and TOTAL MET

- We define the resolution as:

$$\delta = \frac{q_{75\%} - q_{25\%}}{2}$$

where $q_{X\%}$ is the X-th quantile of the considered response distribution

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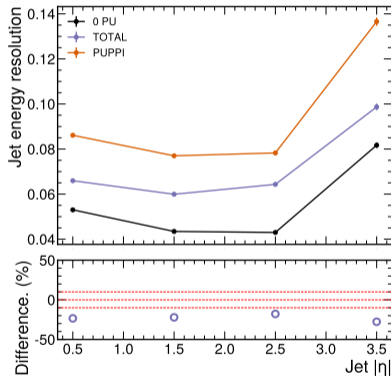
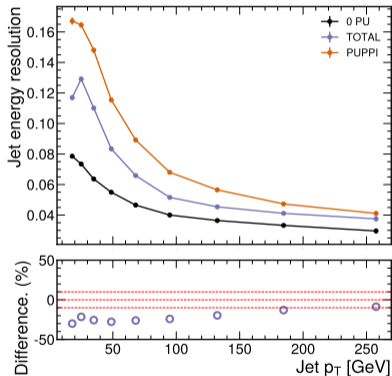
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Results: QCD multijet



- Jet energy resolution as a function of jet p_T (left) and jet η (right)
- Improvement up to 30% in JER, up to 25% in η resolution

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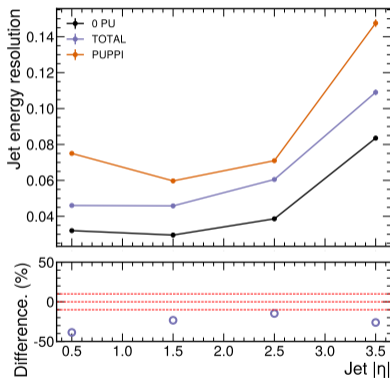
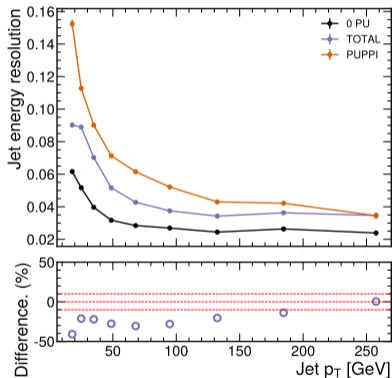
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Results: dileptonic $t\bar{t}$



- Jet energy resolution as a function of jet p_T (left) and jet η (right)
- Improvement up to 40% in JER, up to 40% in η resolution

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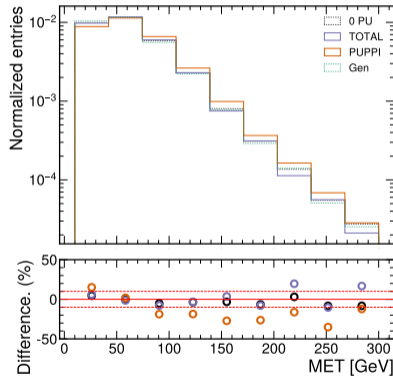
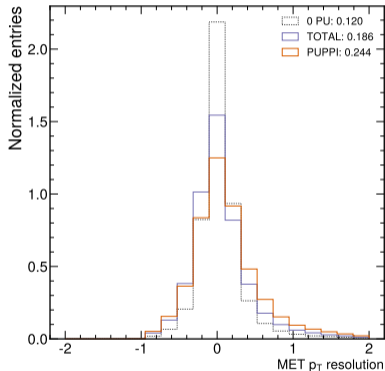
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Results: dileptonic $t\bar{t}$



- MET p_T resolution (left); MET p_T distribution (right)
 - MET resolution is reduced by 24%

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PUPPI

PUMML

PUPPIML

SSPUPPI

TOTAL PU mitigation

General idea

Loss function: SWD

Model

Results

QCD multijet

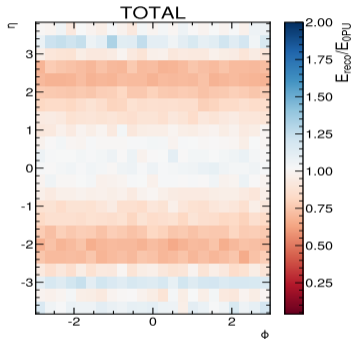
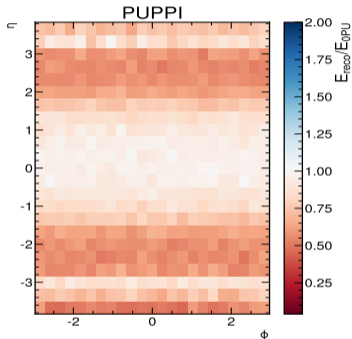
$t\bar{t}$ production

Particle weights

Robustness

Conclusions

Inspecting particles weights



- Ratio $\frac{p_T \times \omega}{p_{T, \text{noPU}}}(\eta, \phi)$ for PUPPI and TOTAL (right) in QCD multijet events
- Smoother behavior for TOTAL in central and forward region
- Still room for improvement in transition region

TOTAL PU mitigation

F. Lemmi

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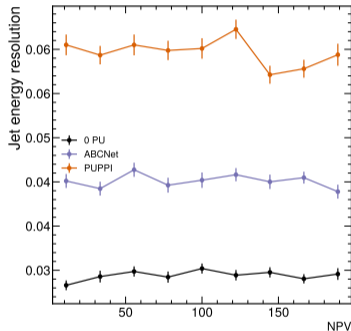
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- Evaluate resolution on **processes and PU scenarios unseen during training**
- Network is trained on $QCD+t\bar{t}+VBF$ with $\langle NPV \rangle = 140$
- Evaluate on $W+jets$ production, flat NPV between 0 and 200

Conclusions



- We presented **novel algorithm to reject PU particles** at high-intensity hadron colliders
 - Trained and tested on Delphes simulation of Phase2 CMS detector
- We are Training Optimal Transport with Attention Learning: **TOTAL**
- We **solved the longstanding problem of neutral labels** in PU mitigation
- **We do not rely on explicit, per-particle labeling**
- **Learning happens through OT in a self-supervised fashion**
- Such an algorithm will be **crucial at the High-Luminosity LHC**, where much harsher data-taking conditions are expected
- Our **approach can be generalized** to a wide range of denoising problems
 - Only needed input is a reliable simulation of signal and noise

TOTAL PU mitigation

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