



# **TaichuPix3 testbeam at DESY**

Zhijun Liang on behalf of CEPC vertex detector group 2023/01/18



Circular Electron Position Collider



# Overview of MOST2 vertex detector R&D

- Can break down into sub-tasks
  - CMOS Pixel Sensor chip R&D
  - Detector layout optimization, ladder and vertex detector support structure R&D
  - Detector assembly
  - Data acquisition system R&D



CMOS pixel sensor prototyping



# Large-scale sensor TaichuPix-3

#### TaichuPix3 and Challenges for the CMOS sensor

- > Small pixel size -> high resolution (3-5  $\mu$ m)
- High readout speed (<500ns deadtime @40MHz at Z pole) -> for CEPC Z pole high lumi
- Radiation tolerance (per year): 1 MRad

	ALPIDE	ATLAS-MAPS (MONOPIX / MALTA)	MIMOSA
Pixel size	$\checkmark$	Х	$\checkmark$
Readout Speed	Х	$\checkmark$	Х
TID	X (?)	$\checkmark$	$\checkmark$



Chip size :  $26 \times 16 \text{ mm}$ Pixel size :  $25\mu m \times 25\mu m$ 

15.9 mm TCPX3 25.7 mm

TaichuPix-3 chip vs. coin





#### 5 wafers tested

- > 2 wafer based on standard process
  - > Reasonable yield achieved
- > 3 wafer based on modified process
  - Iower yield than the std. process

Wei Wei, Ying Zhang Tianya Wu



Probe card for wafer test

An example of wafer test result



# Testbeam on DESY

# On Site team (DESY)

- Joao (IHEP) Project leader
- Zhijun Liang (IHEP) test beam coordinator
- Tianya Wu (IHEP) Shift leader , ASIC expert
- Ming Qi (NJU) Shift leader
- Lei Zhang (NJU) Shift leader
- Xiaomin Wei (NWPU) ASIC experts
- Jia Zhou (IHEP) DAQ
- Xinhui Huang (IHEP) Assembly
- Shuqi Li (IHEP) Offline
- Hao Zeng (IHEP) Offline
- XueWei Jia (IHEP) Offline



## **Romate support**

WeiWei, Ying Zhang (IHEP) ASIC Jun Hu, Ziyue Yan (IHEP) firmware Hongyu Zhang (IHEP) DAQ Jinyu Fu, Mingyi Dong (IHEP) Assembly Wei Wang, Gang Li, Linhui Wu (IHEP) Offline Yiming Hu, Xiaoxu Zhang (NJU)...



# Introduction of DESY TB21



The electron or positron beams are converted bremsstrahlung beams from carbon fibre targets in the electron-positron synchrotron DESY II with up to 1000 particles per cm<sup>2</sup> and energies from 1 to 6 GeV, an energy spread of ~5% and a divergence of ~1mrad.





## **DESY Testbeam Setup**



- The 6-layer of TaichuPix3 telescope was in the middle of the 5-layer MIMOSA and 4-layer JadePix telescope.
- MIMOSA is fixed there and cannot move. But it can be used to calibrate the position of the TaichuPix3 telescope







Jia Zhou

Tianya Wu

Hongyu Zhang

# Hitmap of 3 GeV beam

Hitmap



col

Board 03 512 384 ₫ 256 128 0 -512 256 768 1024 0 col













# Hitmap of 4 GeV beam

Hitmap



Jia Zhou Tianya Wu Hongyu Zhang



30

- 25

- 20

- 15

- 10

- 5



# Hitmap of 5 GeV beam

Hitmap





CEPC

Jia Zhou Tianya Wu Hongyu Zhang



Jia Zhou

# Hitmap of 6 GeV beam



col

From the hitmap, the position of beam spot is off to the initial one. west-east direction moves from 1.8 to -4.3.











# DESY testbeam Energy Opti

- From hit map, 4GeV is a moderate option.
- $\rightarrow$  Enough data and higher energy
- 4 GeV is used for Threshold scan, the data rate is around 10K B/s for a standard CMOS chip and 67.4K B/s for modified process.
- The valid coincidence tracks are around 41 tracks/ s when chi2<2</li>
- The sensors are working for the full beam time except for the chip replacement. Totally about 100GB valid data were recorded



(a) at TB21  $\,$ 

Refer from:The DESY II test beam facility" https://doi.org/10.1016/j.nima.2018.11.133 NIMA, Volume 922, 1 April 2019, Pages 265-286



## MOST2 offline reconstruction and alignment

Shuqi Li Linghui Wu Gang Li

#### **Track Reconstruction**

- No magnetic field
- Least squares fitting (Straight line fit)
- No considering multi-scattering now

### Alignment

- Using Millepede (c++ version) matrix method
- Correct for the misalignment chip position
- Evaluate the influence of different alignment parameters on spatial resolution















$$\longrightarrow \Delta \vec{p}_1 = S^{-1} \left( \vec{b}_1 - C_{21}^T C_{22}^{-1} \vec{b}_2 \right)$$



• Matrix S with smaller size than C, and C<sub>22</sub> is easy to invert

Alignment

Method - millepede matrix method

•

- Six alignment parameters considered
  - Translation along X, Y, Z direction
  - Rotation around X, Y, Z axis





# Chi2 of the track before and after Alignment

 $\chi^2(\alpha) = \sum_{i=1}^n \frac{f(x_i, \alpha) - e_i)^2}{\sigma_i^2}$ 

- Chi2 (no dividing ndf) distribution before and after alignment
- Chi2 of the track reduced significantly after alignment



unbiased Residual plots before and after alignment (4GeV)



#### Cluster size vs. chip threshold (4GeV)



 If lowering the threshold, cluster size will be dominated by cluster with 2 hit

 In general, the higher the threshold, the smaller the



Modified : full depletion, faster charge collection





Resolution vs. chip threshold (4GeV) : Standard process

- > The spatial resolution of standard chip improved with lowering the threshold
  - Can reach around 5µm resolution
  - without Kalman filter (without correction for multiple scattering)
- > The spatial resolution can reach about  $3.5\mu m$  with chi2 cut
  - Suppress the multiple scattering effect with Chi2 cut

#### All tracks



#### Tracks with small Chi2 Suppressing multiple scattering Board5, Threshold(Board5) 10->24->32->48->64->96



# Standard : no full depletion

#### Modified : full depletion, faster charge collection



Shuqi Li Linghui Wu Gang Li Zhijun Liang Xuewei Jia Joao





Resolution vs. chip threshold (4GeV) : modified process

# Modified process chip has effectively low threshold Resolution is similar to the resolution with standard process













Tracks with small Chi2 Suppressing multiple scattering

Board2, Threshold(Board2) 16->24->32->48->64->96





## efficiency vs. chip threshold (4GeV) : standard process

- $\succ$  Hit Efficiency increased slightly as reducing the threshold
- ➢ Overall efficiency is about ~99% in study



CIED

LiYiMing Hu(NJU)

Shuqi Li

Threshold

# Progress for flex board

- Testbench setup:  $2 \sim 3$  chips wire bonded on one flex
  - Can communicate with TaichuPix in OCT mode (self-checking mode)
  - Issue: Readout lots noise in charge injection mode
  - Challenge:
    - Long flex cable (~70cm) $\rightarrow$  some issue with power distribution and delay
    - Missing test point to debug the communication issue
  - News :
    - Made a hard PCB with test point, try to understand the issue,
    - The hard PCB is working correctly and a 4 layer flex board is under testing.



#### 2~3 TaichuPix3 chips wire bonded on one flex

Jun Hu Ying Zhang Wei Wei Ziyue Yan Wei Wang

#### Hard PCB with test points



#### Electronics test bench





# Progress for flex board

- Ladder readout is working now in laser test, after fixing a floating pad in digital injection.
- Noise level is a bit higher in 2-layer flex than in 4-layer flex



Exposure 1s with a 100 Hz laser source @ITHR=96

Ying Zhang Wei Wang





# Ladder loading

Wire-bonding



- Loading procedure of ladder on vertex detector has been tested
- Ladder with one TaichuPix3 chip with wirebonds and 9 dummy silicon chip
- Wire-bonding was protected during loading







Jinyu Fu

Xinhui Huang



## Summary

- DESY testbeam achieved the expected goal
  - TaichuPix3 telescope basically works well
  - The preliminary offline results shows a spatial resolution less than 5  $\mu m,$  more analysis is going on.
  - the vertex detector prototype is supposed to DESY again for testbeam in April 2023.
- MOST2 project final review
  - Project execution time up to end of April
  - Final reports need to be ready to submit before July 21st

关于开展国家重点研发计划"大科学装置前沿研究"重点 专项"高能环形正负电子对撞机关键技术研发和验证"项 目综合绩效评价工作的通知







# Thanks for your attention!



2023/1/18



40000 E

30000 E

20000 E

10000 E

-8.06

-0.04

-0.02

0.02 0.04 0.06 residual(x<sub>meas</sub> - x<sub>predict</sub>) [mm]

20000

10000

-8.06

-0.04

-0.02

0

0 0.02 0.04 0.06 residual(x<sub>meas</sub> - x<sub>predict</sub>) [mm]

40

20

-8.06

-0.04

-0.02

20000

10000

0 0.02 0.04 0.06 residual(y<sub>meas</sub> - y<sub>predict</sub>) [mm]

-8.06

-0.04

-0.02

0 0.02 0.04 0.06 residual(y<sub>meas</sub> - y<sub>predict</sub>) [mm]





residual(x<sub>meas</sub> - x<sub>predict</sub>) [mm]

xdirection, ChipID = 1

residual(x<sub>meas</sub> - x<sub>predict</sub>) [mm]



ydirection, ChipID = 0



CEPC













# Overview of testbeam

Dec.12-Dec. 17:(SETUP 1)

• 1-6: W2R3, W2R11, W2R12, W2R10, W2R29, W2R26 Dec. 17:(SETUP 2)

- 1-6: W2R3, <u>W9R3</u>, W9R4, W9R6, W2R29, W2R12 Dec. 18-Dec.19(SETUP 3)
- 1-6: W2R3, <u>W9R5</u>, <mark>W9R4</mark>, W9R6, W2R29, W2R12

Dec. 20- Dec.22(SETUP 4)

• 1-6: W2R3, W9R5, W2R11, W9R6, W2R29, W2R12

The beam energy was tested from 3GeV 4GeV 5GeV 5.4GeV 6GeV

- $\succ$  W9R3 had a higher noisy pixels and replaced with W9R5
- ➤ W9R4 was easy to lose analog current and replaced with W2R11

Note : W2 : No.2 Wafer by standard CMOS process ; R3 : chip position on wafer is 3 ; W9 : No.9 Wafer by modified CMOS process ;







- Board2 with modified technology has a larger depletion layer than Board5 with standard technology
- In general, the higher the threshold, the worse the resolution



Spatial resolution vs. chip threshold (4GeV) [Comparison of Clustersize = 1 and Clustersize > =

Board2(modified) ClusterSize == 1

ClusterSize >= 1





# Threshold scan

- With SETUP 4. (W2R3, W9R5, W2R11, W9R6, W2R29, W2R12)
- Scan ITHR of board 5 (W2R29) with10 16 24 32 48 64 96; 4GeV ;30min for each run; keep the rest of boards unchanged
- Scan ITHR of board 2 (W9R5) with16 24 32 48 64 96; 4GeV ;30min for each run; keep the rest of boards unchanged

➤ W9R5: the spatial resolution is 4.9 at ITHR16 when chi2 <2

 $\geq$  W2R29: the resolution goes to 5.09 at ITHR10 when chi2 < 2

Chip	VBG[V]	ITHR16 Threshold[V]	ITHR32 Threshold[V]	ITHR64 Threshold[V]	ITHR96 Threshold[V]	ITHR16 mask pixels	ITHR32 mask pixels
W2R29	0.740	0.2654	0.3345	0.4468	0.5452	82	1
W9R5	0.737	0.1596	0.1983	0.2683	0.3113	26	4





# Hitmap of 5.4 GeV beam

Hitmap



10 - 8 - 6 - 4 - 2



- 6 layer chips
- 4cm between each other
- electron beam energy 3-6 GeV
- One of the chips is the detector under test (dut), the others are the telescope
- Steps for track finding and reconstruction
- Finding hits in every chip with same time stamp of FPGA (+/- 1)
- Forming adjacent hits into a cluster
- No considering multiple clusters on one chip for one track currently
- Track fitting
- least squares line fitting

$$x = a1z + b1;$$
  
 $y = a2z + b2;$ 

Chi2 definition:  $\chi^2(\alpha) = \sum_{i=1}^n \frac{f(x_i, \alpha) - e_i)^2}{\sigma_i^2}$ , sigmax = sigmay = 25um/sqrt(12)







The first step in the characterization of the telescope as a tracking device was the measurement of the intrinsic resolution of the reference planes and the ultimate spatial resolution achievable combining all the hits into a track. The single plane resolution ( $\sigma_{DUT}$ ) can be obtained from the measured residual width ( $\sigma_{meas}$ ) and the telescope resolution ( $\sigma_{tel}$ ) using Eq. (1)

$$\sigma_{\rm meas}^2 = \sigma_{\rm DUT}^2 + \sigma_{\rm tel}^2 \tag{1}$$

The telescope resolution can be determined assuming that the reference planes all have the same intrinsic resolution using Eq. (2)

$$\sigma_{\rm tel}^2 = k \sigma_{\rm plane}^2 \tag{2a}$$

and

$$k = \frac{\sum_{i}^{N} z_{i}^{2}}{N \sum_{i}^{N} z_{i}^{2} - (\sum_{i}^{N} z_{i})^{2}}$$
(2b)

The formula for the geometrical scaling factor k defined in (2b) is based on the assumption that the DUT is positioned at z=0 and it reduces to 1/N if the reference planes are is symmetrically distributed around the DUT and the beam and telescope axes are parallel.

