

# Noise-resilient phase estimation with randomized compiling

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# Quantum phase estimation

Given a unitary operator  $U$ , how to get the phases of its eigenvalues? That is, given a circuit implementation of

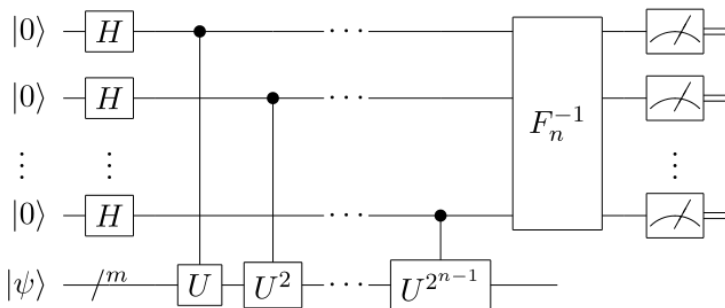
$$U = \sum_a e^{i\lambda_a} |\phi_a\rangle\langle\phi_a|,$$

how to efficiently get phases  $\lambda_a$ ?

The applications of phase estimation:

- Estimate the eigenvalues of a Hamiltonian.
- Factorization or order-finding.
- Linear systems of equations.

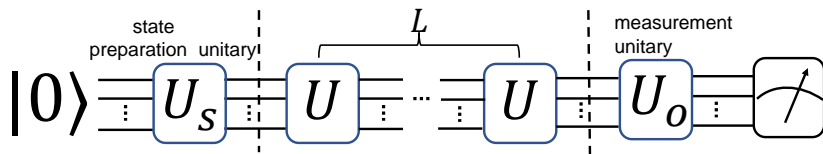
# Phase estimation based on quantum Fourier transform



Drawbacks (in NISQ era):

- Require ancillary qubits and control version of  $U$ .
- Require quantum error correction to combat noise.

# Control-free phase estimation



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The expectation value of the operator  $O$  is

$$\begin{aligned}\langle O \rangle_L &= \langle \psi | (U^\dagger)^L O U^L | \psi \rangle \\ &= \sum_{a,b} c_a c_b^* \langle \phi_b | O | \phi_a \rangle e^{i(\lambda_a - \lambda_b)L}\end{aligned}$$

where  $|\psi\rangle = \sum_a c_a |\phi_a\rangle$ .

**This work introduces an error mitigation method for control-free phase estimation.**

# A benign type of noise

Assume a noisy channel  $\mathcal{E}(\rho) = \sum_k E_k \rho E_k^\dagger$  is appended to the unitary channel  $\mathcal{U}$ , and the resultant noisy gate is  $\tilde{\mathcal{U}} = \mathcal{E}\mathcal{U}$ . The measured signals  $\langle O \rangle_L$  are a damping oscillating function. Control-free phase estimation actually measures the eigenvalues of  $\tilde{\mathcal{U}}$  under noise.

## Theorem

*If every Kraus operator  $E_k$  of a noise  $\mathcal{E}$  is Hermitian, then the noisy version  $\tilde{\mathcal{U}} = \mathcal{E}\mathcal{U}$  of a unitary channel  $\mathcal{U}$  keeps the phases unchanged up to the first-order correction.*

# A short proof

The perturbation matrix is

$$\Delta = \tilde{U} - U = (\mathcal{E} - \mathcal{I})U.$$

Then for a non-degenerate eigenvalue  $e^{i(\lambda_a - \lambda_b)}$  with eigen-operator  $|\phi_a\rangle\langle\phi_b|$ , the first order correction is

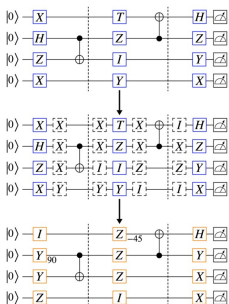
$$\begin{aligned}\epsilon &= \text{tr}\{(|\phi_a\rangle\langle\phi_b|)^\dagger \Delta (|\phi_a\rangle\langle\phi_b|)\} \\ &= e^{i(\lambda_a - \lambda_b)} [\text{tr}\{|\phi_b\rangle\langle\phi_a| \mathcal{E} (|\phi_a\rangle\langle\phi_b|)\} - 1] \\ &= e^{i(\lambda_a - \lambda_b)} \left[ \text{tr}\left\{ |\phi_b\rangle\langle\phi_a| \sum_k E_k |\phi_a\rangle\langle\phi_b| E_k^\dagger \right\} - 1 \right] \\ &= e^{i(\lambda_a - \lambda_b)} \left[ \sum_k \langle\phi_a| E_k |\phi_a\rangle \langle\phi_b| E_k^\dagger |\phi_b\rangle - 1 \right].\end{aligned}$$

Noisy eigenvalue under the first order correction is

$$e^{i(\lambda_a - \lambda_b)} + \epsilon = e^{i(\lambda_a - \lambda_b)} \left[ \sum_k \langle\phi_a| E_k |\phi_a\rangle \langle\phi_b| E_k^\dagger |\phi_b\rangle \right].$$

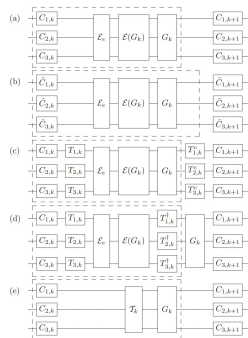
# Randomized compiling

RC can convert the noise in each cycle of a circuit into stochastic Pauli noise with depth of the circuit unchanged.



Phys. Rev. X 11, 041039 (2021)

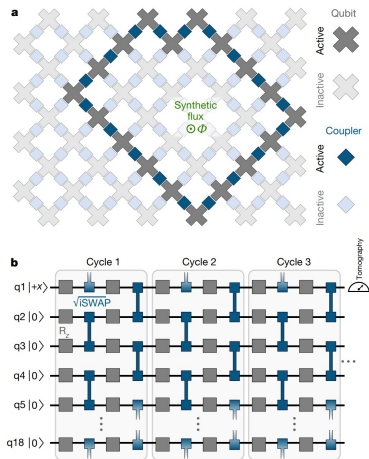
$$\text{Pauli twirling: } \frac{1}{N} \sum_{n=1}^N \mathcal{T}_n^\dagger \mathcal{E}(G_k) \mathcal{E}_e \mathcal{T}_n = \mathcal{E}_p$$



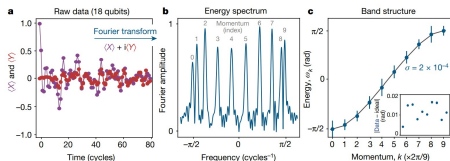
Phys. Rev. A, 94(5), 052325.



# Google experiments



$$\text{Hamiltonian: } \sum_m \sigma_m^+ \sigma_{m+1}^- + \sigma_m^- \sigma_{m+1}^+$$



The reasons of high accuracy:

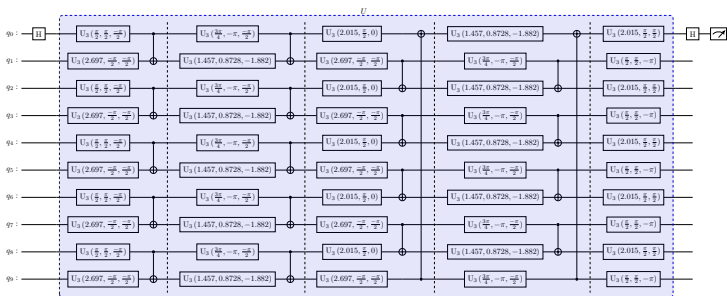
- The problem is insensitive to  $T_1$ ,  $T_2$ .
- Unitary errors are corrected at the level of two qubits.

Nature 594.7864 (2021): 508-512.

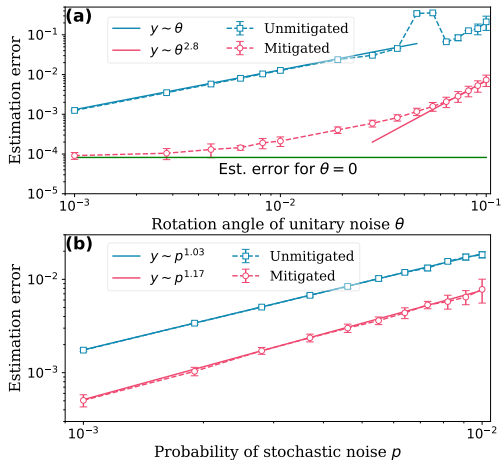
# Simulation of Google experiments

Simulation parameters:

- Max num of repetitions of  $U$  is  $L_{\max} = 50$ .
- To keep the resource cost the same, num of shots for each bare circuit is  $N_s = 10^5$ ; and  $N_s = 10^5/N_r$  for each randomized circuit, where  $N_r = 20$  is the num of randomized circuits for each bare circuit.



# Simulation results



# Order finding

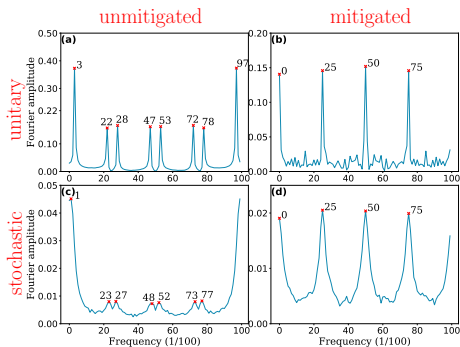
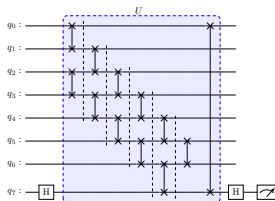
The order finding problem is to find the least positive integer  $r$  such that for two specified coprime numbers  $x$  and  $N$  ( $x < N$ ) we have  $x^r = 1 \pmod{N}$ . The factoring problem can be converted to the order finding problem.

The order finding problem can be solved by finding the phase of the unitary operator  $U$  that is defined as

$$U|y\rangle = |xy \pmod{N}\rangle.$$

The phases of  $U$  are  $0, \frac{1}{r}, \frac{2}{r}, \dots, \frac{r-1}{r}$ .

# Simulation of order finding: $x = 4, N = 255$



# Summary

- Theoretically identify a benign type of noise for phase estimation.
- Use randomized compiling to get the desired type of noise and achieve a practical error mitigation in a generic noise environment without any quantum resource overhead.