

1. Fermi 相互作用, β 衰变.

$$n \rightarrow p^+ e^- \bar{\nu}_e$$

$$\mathcal{L}_F = \frac{1}{\sqrt{2}} G_F \cdot \bar{\psi}_n T_1 \psi_p \bar{\psi}_\nu T_2 \psi_e \quad [G_F] = M^{-2}$$

么正性.

$$|out\rangle = S |in\rangle$$

$$|in\rangle \text{ 归一化. } \langle in | in \rangle = 1.$$

$$|out\rangle \text{ 亦可归一化. } \langle out | out \rangle = 1.$$

S 是 $\mathcal{H}_{in} \rightarrow \mathcal{H}_{out}$ 的么正变换. 否则, 我们遗漏了一些 \mathcal{H}_{out} 中的态.

$$S^\dagger S = \mathbb{1} \quad \therefore S = \mathbb{1} + i\mathcal{T} \quad \mathcal{T} \text{ 为跃迁振幅.}$$

$$\therefore S^\dagger S = (1 - i\mathcal{T}^\dagger)(1 + i\mathcal{T}) = \mathbb{1} + i(\mathcal{T} - \mathcal{T}^\dagger) + \mathcal{T}^\dagger \mathcal{T}$$

$$\Rightarrow i(\mathcal{T}^\dagger - \mathcal{T}) = \mathcal{T}^\dagger \mathcal{T}$$

$\mathcal{T} = A + iB$ A, B 均为自伴算子. 则

$$i(\mathcal{T}^\dagger - \mathcal{T}) = i(A^\dagger - iB^\dagger - A - iB) = i(A - iB - A - iB) = 2B$$

$$\mathcal{T}^\dagger \mathcal{T} = (A - iB)(A + iB) = A^2 + B^2 + i[A, B]$$

对于 $|p_1 p_2\rangle \rightarrow |p_1 p_2\rangle$ 散射

$$\begin{array}{ccc} e^+ & e^- & \\ \rightarrow & \leftarrow & \end{array} \quad \rightarrow \quad \begin{array}{ccc} e^- & & e^+ \\ \leftarrow & & \rightarrow \end{array}$$

$$i\langle p_1 p_2 | \mathcal{T}^\dagger | p_1 p_2 \rangle - i\langle p_1 p_2 | \mathcal{T} | p_1 p_2 \rangle$$

$$= \langle p_1 p_2 | \mathcal{T}^\dagger \mathcal{T} | p_1 p_2 \rangle = \int d\pi_f \langle p_1 p_2 | \mathcal{T}^\dagger | f \rangle \langle f | \mathcal{T} | p_1 p_2 \rangle$$

$$= \int d\pi_f |\langle f | \mathcal{T} | p_1 p_2 \rangle|^2$$

$$\langle f | J | p_1, p_2 \rangle = (2\pi)^4 \delta^4(p_1 + p_2 - p_f) \mathcal{M}(p_1, p_2 \rightarrow f)$$

$$\therefore i\mathcal{M}^*(p_1, p_2 \rightarrow p_1, p_2) - i\mathcal{M}(p_1, p_2 \rightarrow p_1, p_2) \geq \int d\pi_f (2\pi)^4 \delta^4(p_1 + p_2 - p_f) |\mathcal{M}(p_1, p_2 \rightarrow f)|^2$$

而对于两体末态 f_2

$$\sigma(p_1, p_2 \rightarrow f_2) = \frac{1}{4E_{cm} |\vec{p}_i|} \int d\pi_{f_2} (2\pi)^4 \delta^4(p_1 + p_2 - p_{f_2}) |\mathcal{M}(p_1, p_2 \rightarrow f_2)|^2$$

$$\therefore \text{Im } \mathcal{M}(p_1, p_2 \rightarrow p_1, p_2) \geq 2E_{cm} |\vec{p}_i| \sigma(p_1, p_2 \rightarrow k_1, k_2)$$

对所有可能的末态求和 \Rightarrow
$$\boxed{\text{Im } \mathcal{M}(p_1, p_2 \rightarrow p_1, p_2) = 2E_{cm} |\vec{p}_i| \sum_f \sigma(p_1, p_2 \rightarrow f)}$$

光学定理.

特别地, 选 $f = p_1, p_2$ 则

$$\text{Im } \mathcal{M}(p_1, p_2 \rightarrow p_1, p_2) \geq 2E_{cm} |\vec{p}_i| \sigma(p_1, p_2 \rightarrow p_1, p_2)$$

可以证明, 上述结果对所有的 l 分波都分别成立.

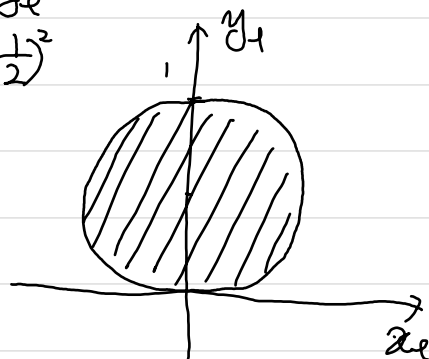
$$\therefore \text{Im } a_l \geq \frac{2|\vec{p}_i|}{E_{cm}} |a_l|^2$$

其中 $\mathcal{M} = 16\pi \sum_{l=0}^{\infty} a_l (2l+1) P_l(\cos\theta)$, a_l 为分波振幅

高能极限 $E_{cm} = \sqrt{s} \gg m_1, m_2 \quad \therefore |\vec{p}_i| \approx E_{cm}/2$

$$\text{Im } a_l \geq |a_l|^2 \quad a_l = x_l + iy_l$$

$$\Rightarrow y_l \geq x_l^2 + y_l^2 \Rightarrow x_l^2 + (y_l - \frac{1}{2})^2 \leq (\frac{1}{2})^2$$



非弹性散射 $M_X = 16\pi \sum_{l=0}^{+\infty} b_l (2l+1) P_l(\cos\theta)$

$$\therefore \text{Im } M(p_1 p_2 \rightarrow p_1 p_2) \geq 2 E_{\text{cm}} |\vec{p}_i| \sigma(p_1 p_2 \rightarrow X)$$

$$\therefore \text{Im } a_l \geq |b_l|^2$$

\therefore High Energy Limit

$$\sigma_T = \frac{1}{32\pi s} \int |M_{Xl}(\cos\theta)|^2 d\cos\theta$$

$$= \frac{8\pi}{s} \int |b_l|^2 (2l+1)^2 P_l(\cos\theta)^2 d\cos\theta$$

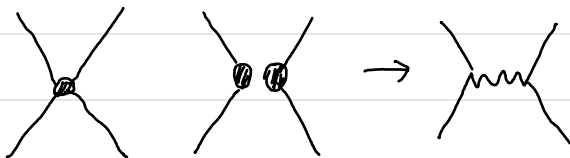
$$= \frac{16\pi(2l+1)}{s} |b_l|^2 \leq \frac{16\pi(2l+1)}{s} \text{Im } a_l \leq \frac{16\pi(2l+1)}{s}$$

考虑 $n + \nu_e \rightarrow p + e^-$ (或 $p + e^- \rightarrow n + \nu_e, \dots$)

$$\sigma_T = \frac{G_F^2 s}{\pi} \delta_{e0}$$

对 0-分波, $\frac{G_F^2 s}{\pi} \geq \frac{16\pi}{s} \Rightarrow$ 高能散射“破坏么正性”

$\exists \lambda \quad W^\pm$



$$\mathcal{H} = \frac{G_F}{\sqrt{2}} J_H^{-\mu} J_L^{+\mu} + \text{h.c.}$$

$$J_H^{-\mu} = \bar{\psi}_p \gamma^\mu (1 - \gamma_5) \psi_n$$

$$J_L^{+\mu} = \bar{\psi}_e \gamma^\mu (1 - \gamma_5) \psi_\nu$$

$$\rightarrow \mathcal{L} = -\frac{g}{2\sqrt{2}} J_H^{-\mu} W_\mu^+ - \frac{g}{2\sqrt{2}} J_L^{+\mu} W_\mu^- + \text{h.c.}$$

$$\mathcal{L} = -\frac{1}{2} W^{\mu\nu} W_{\mu\nu} + m_W^2 W^{+\mu} W_\mu^-$$

$$W_{\mu\nu}^{\pm} = \partial_{\mu} W_{\nu}^{\pm} - \partial_{\nu} W_{\mu}^{\pm}$$

$$\mathcal{M} = \frac{g^2 J_H^{-\mu} J_L^{+\nu}}{8(p^2 - m_w^2 + i\epsilon)} \left(g_{\mu\nu} - \frac{p_{\mu} p_{\nu}}{m_w^2} \right)$$

$$\xrightarrow{p^2 \ll m_w^2} -\frac{g^2}{8m_w^2} J_H^{-\mu} J_L^{+\mu} \quad \therefore \frac{g^2}{8m_w^2} = \frac{G_F}{\sqrt{2}}$$

$$4\sqrt{2} m_w^2 G_F^2 = g^2$$

$$\mathcal{L}^{\nu e} = -\frac{G_F}{\sqrt{2}} \bar{\nu} \gamma^{\mu} (1 - \gamma_5) \nu \bar{e} \gamma_{\mu} (g_{LV}^{e\nu} - g_{LA}^{e\nu} \gamma_5) e$$

$$\mathcal{L}^{\nu h} = -\frac{G_F}{\sqrt{2}} \bar{\nu} \gamma^{\mu} (1 - \gamma_5) \nu \sum_f \left[g_{LV}^{f\nu} \bar{f} \gamma_{\mu} (1 - \gamma_5) f + g_{LR}^{f\nu} \bar{f} \gamma_{\mu} (1 + \gamma_5) f \right]$$

$$\mathcal{L}^{ee} = \frac{G_F}{\sqrt{2}} g_{AV}^{ee} \bar{e} \gamma^{\mu} \gamma_5 e \bar{e} \gamma_{\mu} e$$

$$\mathcal{L}^{eh} = \frac{G_F}{\sqrt{2}} \sum_f \left[g_{AV}^{ef} \bar{e} \gamma^{\mu} \gamma_5 e \bar{f} \gamma_{\mu} f + g_{VA}^{ef} \bar{e} \gamma^{\mu} e \bar{f} \gamma_{\mu} \gamma_5 f \right]$$

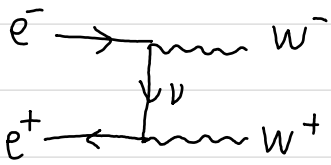
引入带电重矢量玻色 W^{\pm} 后的 Lagrangian

$$\begin{aligned} \mathcal{L} = & \sum_f \bar{\psi}_f (i\not{\partial} - m_f) \psi_f - \frac{1}{2} W^{+\mu\nu} W_{\mu\nu}^{-} + m_w^2 W^{+\mu} W_{\mu}^{-} - \frac{1}{4} F_{\mu\nu} F^{\mu\nu} \\ & - \sum_f e Q_f \bar{\psi}_f \gamma^{\mu} \psi_f A_{\mu} - \frac{g}{2\sqrt{2}} \left[\bar{\psi}_u \gamma^{\mu} (1 - \gamma_5) \psi_d W_{\mu}^{+} + h.c. \right] \\ & - \frac{g}{2\sqrt{2}} \left[\bar{\psi}_\nu \gamma^{\mu} (1 - \gamma_5) \psi_e W_{\mu}^{+} + h.c. \right] \end{aligned}$$

$$\text{其中 } W_{\mu\nu}^{\pm} = D_{\mu} W_{\nu}^{\pm} - D_{\nu} W_{\mu}^{\pm} = \partial_{\mu} W_{\nu}^{\pm} - \partial_{\nu} W_{\mu}^{\pm} \mp ie (A_{\mu} W_{\nu}^{\pm} - A_{\nu} W_{\mu}^{\pm})$$

$$W_{\mu} \text{ 传播子: } -\frac{i}{p^2 - m^2 + i\epsilon} \left(g_{\mu\nu} - \frac{k_{\mu} k_{\nu}}{m^2} \right)$$

$$e^+e^- \rightarrow W^+W^-$$



$$\frac{d\sigma}{d\cos\theta} \sim G_F^2 s (1 - \cos^2\theta) \propto s \quad \text{破坏么正性.}$$

$$E_\mu(\uparrow) = \frac{1}{\sqrt{2}}(0, 1, i, 0) \quad E_\mu(\downarrow) = \frac{1}{\sqrt{2}}(0, 1, -i, 0)$$

$$E_\mu(L) = (0, 0, 0, 1)$$

$$\xrightarrow{W \text{ boost}} \quad E_\mu(L) \rightarrow (\sqrt{\gamma^2 - 1}, 0, 0, \gamma) \quad \gamma = E/m$$

高能行为 $E_\mu(L) \simeq p_\mu/m$

\therefore 纵极化 $VV \rightarrow X$ 的高能行为

$$\mathcal{M} = E_\mu \cdot J^\mu \propto p_\mu J^\mu \quad \therefore J^\mu \lesssim O\left(\frac{1}{s^{3/2}}\right)$$

上述例子显示 $J^\mu \lesssim O(s^{-3/2})$ 不易获得

但确有一类理论 s.t. $p_\mu J^\mu = 0, \quad \partial_\mu J^\mu = 0.$

\rightarrow 规范理论.

小群的 E_2 平移变换

$$E_\mu \rightarrow (0, 1, \pm i, 0) \begin{pmatrix} \gamma & 0 & \sqrt{2\gamma-2} & \gamma-1 \\ 0 & 1 & 0 & 0 \\ \sqrt{\gamma-2} & 0 & 1 & \sqrt{2\gamma-2} \\ 1-\gamma & 0 & -\sqrt{2\gamma-2} & 2-\gamma \end{pmatrix}$$

$$= E_\mu \pm i p_\mu$$

\Rightarrow 0 质量 矢量场 耦合的流, J^μ 必须满足
 $\partial_\mu J^\mu = 0 \quad \leftarrow$ 规范不变.

2. 规范冗余, 规范场

$$[T^a, T^b] = (-1)^{S_1} i f_{abc} T^c$$

$$U(g) \psi_i U(g^{-1}) = \exp((-1)^{S_2} i \theta_a T^a)_{ij} \psi_j$$

$$\mathcal{L} = \bar{\psi}_j (i \delta_{jk} \not{\partial} - m_{jk}) \psi_k.$$

对于不可约表示, $m_{jk} = m \delta_{jk}$.

★ 同一表示的粒子质量相同!!!

红 u , 绿 u , 蓝 u , 质量相同

局域对称变换 (纯被动观点, 不是新的对称性)

$$\mathcal{L}' = \mathcal{L} + \bar{\psi} e^{-(-1)^{S_2} i \theta_a T^a} \cdot i \not{\partial} (e^{(-1)^{S_2} i \theta_b T^b} \psi)$$

$$\rightarrow \mathcal{L} - (-1)^{S_2} \bar{\psi} \gamma^\mu T^a \psi \partial_\mu \theta_a + \mathcal{O}(\theta^2)$$

\therefore 引入辅助场 $\tilde{A}_{\mu,a}$

$$\mathcal{L} = \bar{\psi} (i\not{\partial} + (-1)^{S_3} \gamma^\mu \tilde{A}_{\mu,a} T^a - m) \psi$$

$$\tilde{A}_{\mu,a} \rightarrow \tilde{A}_{\mu,a} + (-1)^{S_2 - S_3} \partial_\mu \theta_a + C_{a,\mu}^b \theta_b$$

$$\Rightarrow \bar{\psi} (i\not{\partial} + (-1)^{S_3} \gamma^\mu \tilde{A}_{\mu,a} T^a) \psi \text{ 变化量为}$$

$$(-1)^{S_3} \bar{\psi} \gamma^\mu T^a [-(-1)^{S_1 + S_2} f_{abc} \tilde{A}_{\mu,b} \theta_c + C_{a,\mu}^b \theta_b] \psi$$

为使 \mathcal{L} 形式不变, 此式 = 0

$$\Rightarrow (-1)^{S_1 + S_2} f_{abc} \tilde{A}_{\mu,b} \theta_c = C_{a,\mu}^b \theta_b$$

$$\therefore \tilde{A}_{\mu,a} \rightarrow \tilde{A}_{\mu,a} + (-1)^{S_2 - S_3} \partial_\mu \theta_a + (-1)^{S_1 + S_2} f_{abc} \tilde{A}_{\mu,b} \theta_c$$

对于有限大变换 $\tilde{A}_\mu \equiv \tilde{A}_{\mu,a} T^a$

$$\tilde{A}_\mu \rightarrow U \tilde{A}_\mu U^{-1} - i(-1)^{S_3} (\partial_\mu U) U^{-1}$$

$$\text{if } \mathcal{L} = \bar{\psi} (i\not{\partial} + \gamma^\mu \tilde{A}_\mu) \psi$$

$$\tilde{A}_{\mu,a} \text{ 的运动方程 } \partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\nu)} = \frac{\partial \mathcal{L}}{\partial A_\nu} \Rightarrow \frac{\partial \mathcal{L}}{\partial A_\nu} = 0$$

$$\therefore \begin{cases} \bar{\psi} \gamma^\mu T^a \psi \equiv 0 & \dots \textcircled{1} \text{ 规范固定} \\ (i\not{\partial} - m + \gamma^\mu \tilde{A}_{\mu,a} T^a) \psi = 0 & \dots \textcircled{2} \end{cases}$$

$$\tilde{F}_{\mu\nu} \equiv \partial_\mu \tilde{A}_\nu - \partial_\nu \tilde{A}_\mu - i(-1)^{S_3} [\tilde{A}_\mu, \tilde{A}_\nu]$$

$$\tilde{F}_{\mu\nu} \rightarrow U \tilde{F}_{\mu\nu} U^{-1}$$

$\text{tr}(\underline{\tilde{F}}^{\mu\nu} \underline{\tilde{F}}_{\mu\nu})$ 为 G 不变动能.

$$\tilde{A}_{\mu,a} = g A_{\mu,a}$$

$$\left\{ \begin{array}{l} [T^a, T^b] = (-1)^{S_1} i f_{abc} T^c \\ \varphi \rightarrow e^{(-1)^{S_2} i \theta_a T^a} \varphi \\ \partial_\mu \rightarrow D_\mu = \partial_\mu - i (-1)^{S_3} g A_{\mu,a} T^a \\ \underline{A}_\mu = A_{\mu,a} T^a \rightarrow U \underline{A}_\mu U^{-1} - (-1)^{S_3} \frac{i}{g} (\partial_\mu U) U^{-1} \\ A_{\mu,a} \rightarrow A_{\mu,a} + (-1)^{S_2-S_3} \frac{1}{g} \partial_\mu \theta_a + (-1)^{S_1+S_2} f_{abc} A_{\mu,b} \theta_c + \mathcal{O}(\theta^2) \\ \underline{F}_{\mu\nu} \equiv F_{\mu\nu,a} T^a = \partial_\mu \underline{A}_\nu - \partial_\nu \underline{A}_\mu - i g (-1)^{S_3} [\underline{A}_\mu, \underline{A}_\nu] \\ F_{\mu\nu,a} = \partial_\mu A_{\nu,a} - \partial_\nu A_{\mu,a} + (-1)^{S_1+S_3} g f_{abc} A_{\mu,b} A_{\nu,c} \\ \underline{F}_{\mu\nu} \rightarrow U \underline{F}_{\mu\nu} U^{-1} \end{array} \right.$$

$$\mathcal{L} = -\frac{1}{4} F_{\mu\nu,a} F^{\mu\nu}_a + \bar{\Psi} (i \not{D} - m) \Psi + (D_\mu \varphi)^\dagger (D^\mu \varphi) - V(\varphi)$$

$$A_{\mu,a} \rightarrow A_{\mu,a} + (-1)^{S_2-S_3} \frac{1}{g} \partial_\mu \theta_a + (-1)^{S_1+S_2} f_{abc} A_{\mu,b} \theta_c$$

选 $\theta_a \propto \delta_{a\alpha}$ $\therefore f_{abc} = -f_{cba}$ $\therefore A_{\mu,a} \rightarrow A_{\mu,a} + (-1)^{S_2-S_3} \frac{1}{g} \partial_\mu \theta_a$
不变.

$\therefore A_\mu J^\mu$ 的 J^μ 满足 $\partial_\mu J^\mu = 0$

量子水平必须仍然保持! \hookrightarrow Ward 恒等式 $Z_g = Z_A^{-1/2}$
| 反常相消

2. 自发对称性破缺, Higgs 机制和 SM Lagrangian

(1). 中性流, SU(2) 对称性 (规范)

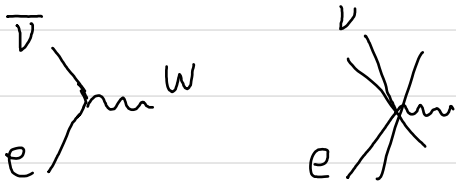
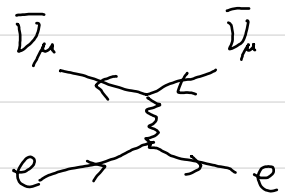
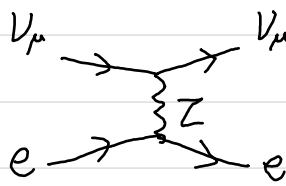
$$Q^2 \ll (100 \text{ GeV})^2.$$

$$\mathcal{L}^{ve} = -\frac{G_F}{\sqrt{2}} \bar{\nu} \gamma_\mu (1 - \gamma_5) \nu \cdot \bar{e} \gamma^\mu (g_{LV}^{ve} - g_{LA}^{ve} \gamma_5) e$$

中微子散射. $\nu_\mu e \rightarrow \nu_\mu e$ $\bar{\nu}_\mu e \rightarrow \bar{\nu}_\mu e$

$$\sigma = \frac{G_F^2 m_e E_\nu}{2\pi} \left[(g_V^{ve} \pm g_A^{ve})^2 + \frac{1}{3} (g_V^{ve} \mp g_A^{ve})^2 \right]$$

$$R \equiv \sigma_{\nu_\mu e} / \sigma_{\bar{\nu}_\mu e}$$



不可能为带电流.

$J^{0\mu}$ — 中性流

$$\bar{\nu} \gamma^\mu (1 - \gamma_5) \nu$$

$$e \gamma^\mu (g_{LV}^{ve} - g_{LA}^{ve} \gamma_5) e$$

....

~~~~~  $W^+$

~~~~~  $W^-$

~~~~~  $Z$  (中性玻色子)

3个生成元.

SU(2)

$\sigma^1 \quad \sigma^2 \quad \sigma^3$

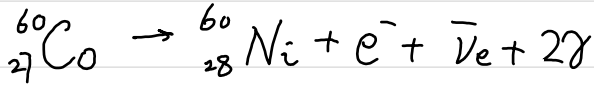
(2) 左手相互作用, 宇称破坏.

" $\theta$ - $\tau$ " 疑难.  $3\pi, 2\pi$  衰变模式

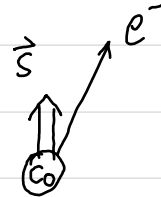
$$P_\pi = -1$$

$$\theta^+ \rightarrow \pi^+ \pi^0$$

$$\tau^+ \rightarrow \pi^+ \pi^+ \pi^-$$



$\beta$  衰变 (带电流) 是纯左手相互作用.



$$\begin{pmatrix} e_L^- \\ \nu_e \end{pmatrix}$$

$$\begin{pmatrix} \mu_L^- \\ \nu_\mu \end{pmatrix}$$

$$\begin{pmatrix} \tau_L^- \\ \nu_\tau \end{pmatrix}$$

$$e_R^-$$

$$\mu_R^-$$

$$\tau_R^-$$

$$\begin{pmatrix} u_L \\ d_L \end{pmatrix}$$

$$\begin{pmatrix} c_L \\ s_L \end{pmatrix}$$

$$\begin{pmatrix} t_L \\ b_L \end{pmatrix}$$

$$u_R$$

$$c_R$$

$$t_R$$

$$d_R$$

$$s_R$$

$$b_R$$

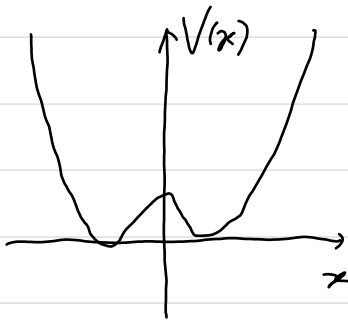
$$\mathcal{L} \neq \bar{\psi}_f (i\not{D} - m_f) \psi - \frac{1}{4} W_{\mu\nu}^a W^{a,\mu\nu}$$

(1)  $\bar{\psi}_f m_f \psi$  不是  $SU(2)$  不变的, 明显破坏

(2)  $W^\pm, Z^0$  的质量非零 ( $\sim 100 \text{ GeV}$ )

# 自发对称性破缺与 Higgs 机制

## (1) 自发对称性破缺



→ 量子力学基态唯一

tunneling eff, instanton

## (2) Nambu - Goldstone 定理

either  $\langle \phi \rangle = 0$ , or massless pseudo-scalar

~~1110~~

例: U(1) 对称性

$$\mathcal{L} = \partial_\mu \phi^* \partial^\mu \phi - V(\phi)$$

$$V(\phi) = \frac{\lambda}{4} (\phi^* \phi)^2 + m^2 \phi^* \phi$$

if  $m^2 < 0$        $\mu^2 \equiv -m^2 > 0$

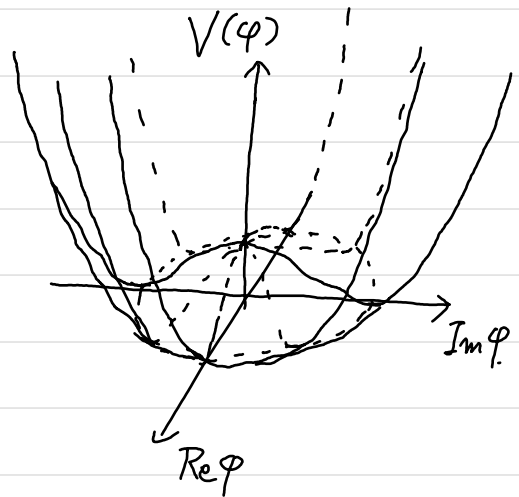
$$\mathcal{L} = \partial_\mu \phi^* \partial^\mu \phi + \mu^2 \phi^* \phi - \frac{\lambda}{4} (\phi^* \phi)^2$$

$$\langle \phi^* \phi \rangle = 2\mu^2 / \lambda \equiv v^2$$

$$\mu^2 = \lambda v^2 / 2$$

$$\langle \phi \rangle = v e^{i\alpha}$$

$$\therefore \phi(x) = (\rho(x) + v) e^{i[\alpha + \theta(x)]}$$



$$\begin{aligned} \mathcal{L} &= \left[ \partial_\mu \rho e^{-i(\alpha+\theta)} - i(\rho+v) \partial_\mu \theta e^{-i(\alpha+\theta)} \right] \left[ \partial_\mu \rho e^{i(\alpha+\theta)} + i(\rho+v) \partial_\mu \theta e^{i(\alpha+\theta)} \right] \\ &\quad + \mu^2 (v^2 + 2v\rho + \rho^2) - \frac{\lambda}{4} (v^4 + 4v^3\rho + 6v^2\rho^2 + 4v\rho^3 + \rho^4) \\ &= \partial_\mu \rho \partial^\mu \rho + (\rho+v)^2 \partial_\mu \theta \partial^\mu \theta + \frac{\lambda}{2} v^4 + \lambda v^3 \rho + \frac{\lambda v^2}{2} \rho^2 \\ &\quad - \frac{\lambda}{4} v^4 - \lambda v^3 \rho - \frac{3}{2} \lambda v^2 \rho^2 - \lambda v \rho^3 - \frac{\lambda}{4} \rho^4 \end{aligned}$$

$$\therefore \mathcal{L} = \partial_\mu \rho \partial^\mu \rho + (v + \rho)^2 \partial_\mu \theta \partial^\mu \theta + \frac{\lambda}{4} v^4 - \lambda^2 v^2 \rho^2 - \lambda v \rho^3 - \frac{\lambda}{4} \rho^4$$

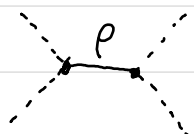
$$\rho \rightarrow \frac{1}{\sqrt{2}} \rho \quad a = \frac{1}{\sqrt{2}} v \theta$$

$$\mathcal{L} = \frac{1}{2} \partial_\mu \rho \partial^\mu \rho - \frac{1}{2} (\lambda v)^2 \rho^2 - \frac{\lambda v}{2\sqrt{2}} \rho^3 - \frac{\lambda}{16} \rho^4 + \frac{1}{2} \partial_\mu a \partial^\mu a + \frac{\rho}{v} \partial_\mu a \partial^\mu a + \frac{\rho^2}{2v^2} \partial_\mu a \partial^\mu a$$

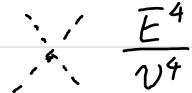
$\rho$  - 质量为  $\lambda v$  的实标量粒子.

$a$  - 零质量 赝标量粒子.

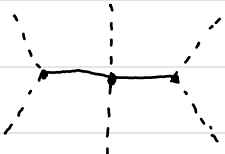
$E \ll \lambda v = M$




$$\frac{1}{v} \cdot \frac{i}{E^2 - M^2} \cdot \frac{1}{v} \sim -\frac{1}{v^2 M^2} \sim \frac{1}{v^4}$$

$$\Rightarrow \frac{1}{v^4} (\partial_\mu a \partial^\mu a)^2$$



$$\frac{E^4}{v^4}$$




$$\frac{1}{v} \frac{i}{E^2 - M^2} \cdot \frac{1}{2v^2} \cdot \frac{i}{E^2 - M^2} \cdot \frac{1}{v} \sim \frac{1}{v^4 M^4} \sim \frac{1}{v^8}$$

$$\Rightarrow \frac{1}{v^8} (\partial_\mu a \partial^\mu a)^3$$


$$\frac{E^6}{v^8}$$



$$\frac{1}{v^{4(N-1)}} (\partial_\mu a \partial^\mu a)^N$$


$$\frac{E^{2N}}{v^{4(N-1)}}$$

$$a a \rightarrow (N-2) a$$

$$\mathcal{M} \sim \frac{E^{2N}}{v^{4(N-1)}}$$

# Gauged symmetry. (Higgs mechanism)

3/1  $\lambda$   $SU(2)$  复标量 2重态

$$H(x) = \begin{pmatrix} \varphi_1 + i\varphi_2 \\ \varphi_3 + i\varphi_4 \end{pmatrix}$$

在 SM 中, 有  $SU(2)_L \times U(1)_Y$  规范群  $\rightarrow W^\pm, Z^0, \gamma$   
今天我们知道,  $H$  在  $SU(2)_L \times U(1)_Y$  变换下满足.

$$H \rightarrow e^{i\alpha_i \frac{\sigma_i}{2}} e^{i\alpha Y} H$$

$$\text{其中 } \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$\text{Dim} \leq 4$  的标量势  $V(H) = \frac{\lambda}{4}(H^\dagger H)^2 - \mu^2 H^\dagger H$

真空位置  $\langle H^\dagger H \rangle = 2\mu^2/\lambda = v^2$

$$\therefore \langle \varphi_1 \rangle^2 + \langle \varphi_2 \rangle^2 + \langle \varphi_3 \rangle^2 + \langle \varphi_4 \rangle^2 = v^2 \quad \text{并且 } \partial_\mu \langle \varphi_i \rangle = 0.$$

$\therefore$  总可以找到整体  $SU(2)_L \times U(1)_Y$  转动, 使得  $\langle H \rangle = \begin{pmatrix} 0 \\ v \end{pmatrix}$   
不妨选择转动后的基底, 因而不失一般性.

$$\langle H \rangle = \begin{pmatrix} 0 \\ v \end{pmatrix} \quad H = \begin{pmatrix} \varphi_1(x) + i\varphi_2(x) \\ v + \varphi_3(x) + i\varphi_4(x) \end{pmatrix}$$

$\therefore SU(2)_L \times U(1)_Y$  是局域对称性, 对每一时空点都可以选不同的  $\alpha_i$  和  $\alpha$ ,  $\alpha_i(x)$ ,  $\alpha(x)$  场

固定  $\langle v \rangle$  后, 只有  $e^{i\theta \frac{\sigma_3}{2}} \cdot e^{i\theta' \frac{I}{2}}$  转动是不改变  $\begin{pmatrix} 0 \\ v \end{pmatrix}$

的. 这意味着  $\sigma_3 + I$  对称性没有被破坏, 同时意味着  $\varphi_1 \dots \varphi_4$  中有 3 个可以通过  $\alpha_i, \alpha$  实现

例:  $\mathcal{L} = (D_\mu \varphi)^* (D^\mu \varphi) + M^2 \varphi^* \varphi - \frac{\lambda}{4} (\varphi^* \varphi)^2 - \frac{1}{4} F_{\mu\nu} F^{\mu\nu}$

$$D_\mu \varphi = \partial_\mu \varphi - ig A_\mu \varphi$$

$$\varphi \rightarrow (v + \rho) e^{i\alpha(x)}$$

但是此时,  $U(1)$  为规范对称性, 所以对任意的  $\varphi(x) = (v + \rho(x)) e^{i\alpha(x)}$ , 总可以做规范变换.

$$e^{-i\alpha(x)}$$

Goldstone 玻色子自由度  $\alpha(x)$  "消失"了!

$$D_\mu [(v + \rho) e^{i\alpha}] = e^{i\alpha} \left[ \partial_\mu \rho - ig \left( A_\mu + \frac{\partial_\mu \alpha}{g} \right) (v + \rho) \right]$$

同时, 规范自由度也消失了. —— 幺正规范

对于  $\varphi = (v + \rho) e^{i\alpha}$ , 总作变换  $\varphi \rightarrow v + \rho$ .  $A_\mu \rightarrow A_\mu + \frac{\partial_\mu \alpha}{g}$

此后不再能做规范变换.

$$C_\mu \equiv A_\mu + \partial_\mu \alpha / g.$$

$$\partial_\mu C_\nu - \partial_\nu C_\mu = \partial_\mu A_\nu - \partial_\nu A_\mu = F_{\mu\nu}$$

$$(D_\mu \varphi)^* (D^\mu \varphi) = [\partial_\mu \rho + ig C_\mu (v + \rho)] [\partial^\mu \rho - ig C^\mu (v + \rho)]$$

$$= \partial_\mu \rho \partial^\mu \rho + g^2 C_\mu C^\mu (v^2 + 2v\rho + \rho^2)$$

$$= \partial_\mu \rho \partial^\mu \rho + 2vg^2 \rho C_\mu C^\mu + g^2 \rho^2 C_\mu C^\mu + g^2 v^2 C_\mu C^\mu$$

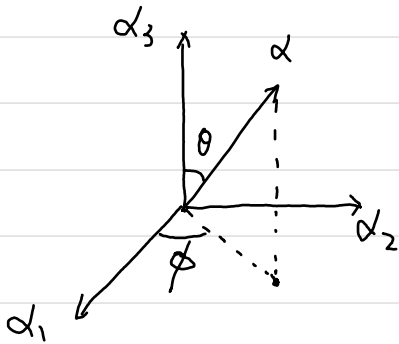
对于  $SU(2)_L \times U(1)_Y$  的 Higgs 场

$$H = \begin{pmatrix} \varphi_1 + i\varphi_2 \\ \varphi_3 + i\varphi_4 \end{pmatrix} \quad \langle H^\dagger H \rangle = v^2$$

$$\Rightarrow \langle \varphi_1 \rangle^2 + \langle \varphi_2 \rangle^2 + \langle \varphi_3 \rangle^2 + \langle \varphi_4 \rangle^2 = v^2$$

选择规范 (幺正规范), 使得时空每一点的  $\langle H \rangle \equiv \begin{pmatrix} 0 \\ v \end{pmatrix}$

$$e^{\frac{i}{2} \alpha_i \sigma_i} = \begin{pmatrix} \cos \frac{\alpha}{2} + i \sin \frac{\alpha}{2} \cos \theta & i e^{-i\phi} \sin \frac{\alpha}{2} \sin \theta \\ i e^{i\phi} \sin \frac{\alpha}{2} \sin \theta & \cos \frac{\alpha}{2} - i \sin \frac{\alpha}{2} \cos \theta \end{pmatrix}$$



$$\alpha = \sqrt{\alpha_1^2 + \alpha_2^2 + \alpha_3^2}$$

$$\sin \theta = \sqrt{\alpha_1^2 + \alpha_2^2} / \alpha$$

$$\cos \theta = \alpha_3 / \alpha$$

$$e^{i\phi} = (\alpha_1 + i\alpha_2) / \sqrt{\alpha_1^2 + \alpha_2^2}$$

$$e^{\frac{i}{2} \alpha_i \sigma_i} H$$

$$= \begin{bmatrix} \varphi_1 \cos \frac{\alpha}{2} - \varphi_2 \sin \frac{\alpha}{2} \cos \theta + \varphi_3 \sin \frac{\alpha}{2} \sin \theta \sin \phi - \varphi_4 \sin \frac{\alpha}{2} \sin \theta \cos \phi \\ + i \left( \varphi_1 \sin \frac{\alpha}{2} \cos \theta + \varphi_2 \cos \frac{\alpha}{2} + \varphi_3 \sin \frac{\alpha}{2} \sin \theta \cos \phi + \varphi_4 \sin \frac{\alpha}{2} \sin \theta \sin \phi \right) \\ - \varphi_1 \sin \frac{\alpha}{2} \sin \theta \sin \phi - \varphi_2 \sin \frac{\alpha}{2} \sin \theta \cos \phi + \varphi_3 \cos \frac{\alpha}{2} + \varphi_4 \sin \frac{\alpha}{2} \cos \theta \\ + i \left( \varphi_1 \sin \frac{\alpha}{2} \sin \theta \cos \phi - \varphi_2 \sin \frac{\alpha}{2} \sin \theta \sin \phi - \varphi_3 \sin \frac{\alpha}{2} \cos \theta + \varphi_4 \cos \frac{\alpha}{2} \right) \end{bmatrix}$$

$$\frac{1}{2} \varphi = \sqrt{\varphi_1^2 + \varphi_2^2 + \varphi_3^2 + \varphi_4^2}$$

$$\varphi_1 = -\varphi \sin \frac{\alpha}{2} \sin \theta \sin \phi$$

$$\varphi_2 = -\varphi \sin \frac{\alpha}{2} \sin \theta \cos \phi$$

$$\varphi_3 = \varphi \cos \frac{\alpha}{2}$$

$$\varphi_4 = \varphi \sin \frac{\alpha}{2} \cos \theta$$

$$\cos \frac{\alpha}{2} = \varphi_3 / \varphi$$

$$\sin \frac{\alpha}{2} \cos \theta = \varphi_4 / \varphi$$

$$e^{i\phi} \sin \frac{\alpha}{2} \sin \theta = -\varphi_2 - i\varphi_1$$

因此, 对于  $H(x) = \begin{pmatrix} \varphi_1(x) + i\varphi_2(x) \\ \varphi_3(x) + i\varphi_4(x) \end{pmatrix}$

总可以做  $SU(2)$  转动

$$U(x) = \begin{pmatrix} \varphi_3 + i\varphi_4 & -\varphi_1 - i\varphi_2 \\ \varphi_1 - i\varphi_2 & \varphi_3 - i\varphi_4 \end{pmatrix} \frac{1}{\sqrt{\varphi_1^2 + \varphi_2^2 + \varphi_3^2 + \varphi_4^2}}$$

使得  $H(x) = \begin{pmatrix} 0 \\ \sqrt{\varphi_1^2 + \varphi_2^2 + \varphi_3^2 + \varphi_4^2} \end{pmatrix}$

选此种(么正)规范

$$H(x) = \begin{pmatrix} 0 \\ v + \frac{1}{\sqrt{2}} h(x) \end{pmatrix}$$

$$\begin{aligned} \therefore D_\mu H &= \partial_\mu H - ig' \frac{y}{2} B_\mu H + ig \frac{\sigma_i}{2} W_\mu^i H \\ &= \begin{pmatrix} \partial_\mu - ig' \frac{y}{2} B_\mu + \frac{i}{2} g W_\mu^3 & \frac{ig}{2} (W_\mu^1 - iW_\mu^2) \\ \frac{ig}{2} (W_\mu^1 + iW_\mu^2) & \partial_\mu - ig' \frac{y}{2} B_\mu - \frac{i}{2} g W_\mu^3 \end{pmatrix} \begin{pmatrix} 0 \\ v + \frac{1}{\sqrt{2}} h \end{pmatrix} \\ &= \begin{pmatrix} \frac{ig}{2} (W_\mu^1 - iW_\mu^2) (v + \frac{1}{\sqrt{2}} h) \\ \frac{1}{\sqrt{2}} \partial_\mu h - \frac{i}{2} (yg' B_\mu + g W_\mu^3) (v + \frac{1}{\sqrt{2}} h) \end{pmatrix} \end{aligned}$$

定义  $W_\mu^\pm = (W_\mu^1 \mp iW_\mu^2) / \sqrt{2}$

$$D_\mu H = \begin{pmatrix} \frac{ig}{\sqrt{2}} W_\mu^+ (v + \frac{1}{\sqrt{2}} h) \\ \frac{1}{\sqrt{2}} \partial_\mu h - \frac{i}{2} (yg' B_\mu + g W_\mu^3) (v + \frac{1}{\sqrt{2}} h) \end{pmatrix}$$

$$\therefore (D_\mu H)^\dagger (D^\mu H) = \frac{g^2}{2} (v + \frac{1}{\sqrt{2}} h)^2 W_\mu^+ W^{-\mu}$$

$$+ \frac{1}{2} \partial_\mu h \partial^\mu h + \frac{1}{4} (v + \frac{1}{\sqrt{2}} h)^2 (yg' B^\mu + g W_\mu^3) (yg' B^\mu + g W^{3\mu})$$



$$\text{定义. } Z_\mu = (y g' B_\mu + g W_\mu^3) / \sqrt{y^2 g'^2 + g^2}$$

$$\begin{aligned} \Rightarrow (D_\mu H)^\dagger (D^\mu H) &= \frac{1}{2} \partial_\mu h \partial^\mu h + \frac{g'^2 v^2}{2} W_\mu^+ W^{-\mu} + \frac{1}{4} (y^2 g'^2 + g^2) v^2 Z_\mu Z^\mu \\ &+ \frac{g'^2 v}{\sqrt{2}} h W_\mu^+ W^{-\mu} + \frac{1}{2\sqrt{2}} (y^2 g'^2 + g^2) v h Z_\mu Z^\mu + \frac{g^2}{4} h^2 W_\mu^+ W^{-\mu} \\ &+ \frac{1}{8} (y^2 g'^2 + g^2) h^2 Z_\mu Z^\mu \end{aligned}$$

$$\mathcal{L}_{KG} = -\frac{1}{4} W_{\mu\nu}^1 W^{1\mu\nu} - \frac{1}{4} W_{\mu\nu}^2 W^{2\mu\nu} - \frac{1}{4} W_{\mu\nu}^3 W^{3\mu\nu} - \frac{1}{4} B_{\mu\nu} B^{\mu\nu}$$

$$\begin{aligned} -\frac{1}{4} W_{\mu\nu}^1 W^{1\mu\nu} &= -\frac{1}{8} (W_{\mu\nu}^+ + W_{\mu\nu}^-) (W^{+\mu\nu} + W^{-\mu\nu}) \\ &= -\frac{1}{8} W_{\mu\nu}^+ W^{+\mu\nu} - \frac{1}{4} W_{\mu\nu}^- W^{+\mu\nu} - \frac{1}{8} W_{\mu\nu}^- W^{-\mu\nu} \end{aligned}$$

$$\begin{aligned} -\frac{1}{4} W_{\mu\nu}^2 W^{2\mu\nu} &= +\frac{1}{8} (W_{\mu\nu}^- - W_{\mu\nu}^+) (W^{-\mu\nu} - W^{+\mu\nu}) \\ &= \frac{1}{8} W_{\mu\nu}^- W^{-\mu\nu} - \frac{1}{4} W_{\mu\nu}^- W^{+\mu\nu} + \frac{1}{8} W_{\mu\nu}^+ W^{+\mu\nu} \end{aligned}$$

$$\text{定义. } A_\mu = (g B_\mu - y g' W_\mu^3) / \sqrt{y^2 g'^2 + g^2}$$

$$\text{则 } B_\mu = (g A_\mu + y g' Z_\mu) / \sqrt{y^2 g'^2 + g^2}$$

$$W_\mu^3 = (-y g' A_\mu + g Z_\mu) / \sqrt{y^2 g'^2 + g^2}$$

$$\text{则 } -\frac{1}{4} W_{\mu\nu}^3 W^{3\mu\nu} - \frac{1}{4} B_{\mu\nu} B^{\mu\nu} = -\frac{1}{4} Z_{\mu\nu} Z^{\mu\nu} - \frac{1}{4} F_{\mu\nu} F^{\mu\nu}$$

$$F_{\mu\nu} \equiv \partial_\mu A_\nu - \partial_\nu A_\mu$$

$$Z_{\mu\nu} \equiv \partial_\mu Z_\nu - \partial_\nu Z_\mu$$

$$W_{\mu\nu}^i = \partial_\mu W_\nu^i - \partial_\nu W_\mu^i + g \varepsilon_{ijk} W_\mu^j W_\nu^k$$

$$\begin{aligned} \therefore W_{\mu\nu}^i W^{i,\mu\nu} &= (\partial_\mu W_\nu^i - \partial_\nu W_\mu^i) (\partial^\mu W^{i,\nu} - \partial^\nu W^{i,\mu}) \\ &+ 2g \sum_{ijk} (\partial_\mu W_\nu^i - \partial_\nu W_\mu^i) W^{j,\mu} W^{k,\nu} \\ &+ g^2 \varepsilon_{ijk} \varepsilon_{iab} W_\mu^j W_\nu^k W^{a,\mu} W^{b,\nu} \end{aligned}$$

$$W_\mu = \begin{pmatrix} \frac{1}{2} W_\mu^3 & \frac{1}{\sqrt{2}} W_\mu^+ \\ \frac{1}{\sqrt{2}} W_\mu^- & -\frac{1}{2} W_\mu^3 \end{pmatrix} = W_\mu^3 \cdot \frac{\sigma^3}{2} + \frac{1}{\sqrt{2}} W_\mu^+ \sigma^+ + \frac{1}{\sqrt{2}} W_\mu^- \sigma^-$$

$$\sigma^+ = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad \sigma^- = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$\therefore \left[ \frac{\sigma^+}{\sqrt{2}}, \frac{\sigma^-}{\sqrt{2}} \right] = \frac{\sigma^3}{2}$$

$$t_+ \equiv \frac{\sigma^+}{\sqrt{2}}, \quad t_- \equiv \frac{\sigma^-}{\sqrt{2}}, \quad t_3 \equiv \frac{\sigma^3}{2}$$

$$\left[ \frac{\sigma^3}{2}, \frac{\sigma^+}{\sqrt{2}} \right] = \frac{\sqrt{2}}{2} \sigma_+^+$$

$$\Rightarrow [t_+, t_-] = t_3$$

$$\left[ \frac{\sigma^-}{\sqrt{2}}, \frac{\sigma^3}{2} \right] = \frac{\sqrt{2}}{2} \sigma_-^-$$

$$[t_-, t_3] = t_-$$

$$\text{注意 } \text{tr}(\ )$$

$$[t_3, t_+] = t_+$$

$$\rightarrow t_+ t_- + t_- t_+$$

$$\therefore f_{+-}^3 = -f_{-+}^3 = 1 \quad f_{+3}^- = -f_{3+}^- = 1$$

$$\therefore f_{ab}^c \downarrow f_{abc}$$

$$f_{-3}^+ = -f_{3-}^+ = 1 \Rightarrow f_{-3+}^- = -f_{3-+}^- = 1$$

$$f_{3+-}^- = -f_{3-+}^- = 1$$

$$f_{3+}^- = -f_{+3}^- = 1 \quad f_{3+-}^- = -f_{+3-}^- = 1 \Rightarrow$$

$$f_{+3-}^- = -f_{+3-}^- = 1$$

$$f_{-3+}^- = -f_{-3+}^- = 1$$

$$\therefore 2g f_{abc} (\partial_\mu W_\nu^a - \partial_\nu W_\mu^a) W^{b,\mu} W^{c,\nu}$$

$$= 2g \left\{ (\partial_\mu W_\nu^+ - \partial_\nu W_\mu^+) (W^{-,\mu} W^{3,\nu} - W^{3,\mu} W^{-,\nu}) \right.$$

$$+ (\partial_\mu W_\nu^- - \partial_\nu W_\mu^-) (W^{3,\mu} W^{+,\nu} - W^{+,\mu} W^{3,\nu})$$

$$\left. + (\partial_\mu W_\nu^3 - \partial_\nu W_\mu^3) (W^{+,\mu} W^{-,\nu} - W^{-,\mu} W^{+,\nu}) \right\}$$

$$= 2g W^{3,\mu} \left\{ W^{-,\nu} W_{\kappa,\nu\mu}^+ - W^{-,\nu} W_{\kappa,\mu\nu}^+ + W^{+,\nu} W_{\kappa,\mu\nu}^- - W^{+,\nu} W_{\kappa,\nu\mu}^- \right\}$$

$$+ 2g W_{\kappa,\mu\nu}^3 (W^{+,\mu} W^{-,\nu} - W^{-,\mu} W^{+,\nu})$$

$$= 4g W^{3,\mu} \left\{ W^{+,\nu} W_{\kappa,\mu\nu}^- - W^{-,\nu} W_{\kappa,\mu\nu}^+ \right\} + 4g W_{\kappa,\mu\nu}^3 W^{+,\mu} W^{-,\nu}$$

$$\begin{aligned}
 (D_\mu H)^\dagger (D^\mu H) &= \frac{1}{2} \partial_\mu h \partial^\mu h + \frac{g^2 v^2}{2} W_\mu^+ W^{-\mu} + \frac{1}{4} (y^2 g'^2 + g^2) v^2 Z_\mu Z^\mu \\
 &+ \frac{g^2 v}{\sqrt{2}} h W_\mu^+ W^{-\mu} + \frac{1}{2\sqrt{2}} (y^2 g'^2 + g^2) v h Z_\mu Z^\mu + \frac{g^2}{4} h^2 W_\mu^+ W^{-\mu} \\
 &+ \frac{1}{8} (y^2 g'^2 + g^2) h^2 Z_\mu Z^\mu
 \end{aligned}$$

$\therefore W^\pm$  的质量  $m_W^2 = g^2 v^2$   
 $Z^0$  的质量  $m_Z^2 = (y^2 g'^2 + g^2) v^2$   
 $A$ , 零质量  $\rightarrow$  光子自由度.

但是  $SU(2)_L \times U(1)_Y \rightarrow U(1)_{em}$ . 中的  $U(1)_{em} \neq U(1)_Y$   
 $A_\mu = (g B_\mu - y g' W_\mu^3) / \sqrt{y^2 g'^2 + g^2} \neq B_\mu$ .

费米子.

|                                                          |                                                               |                                                                 |       |         |          |
|----------------------------------------------------------|---------------------------------------------------------------|-----------------------------------------------------------------|-------|---------|----------|
| $Q_{1L} = \begin{pmatrix} u_L \\ d_L \end{pmatrix}$      | $Q_{2L} = \begin{pmatrix} c_L \\ s_L \end{pmatrix}$           | $Q_{3L} = \begin{pmatrix} t_L \\ b_L \end{pmatrix}$             | $u_R$ | $c_R$   | $t_R$    |
|                                                          |                                                               |                                                                 | $d_R$ | $s_R$   | $b_R$    |
| $L_{1L} = \begin{pmatrix} \nu_{eL} \\ e_L \end{pmatrix}$ | $L_{2L} = \begin{pmatrix} \nu_{\mu L} \\ \mu_L \end{pmatrix}$ | $L_{3L} = \begin{pmatrix} \nu_{\tau L} \\ \tau_L \end{pmatrix}$ | ?     | ?       | ?        |
|                                                          |                                                               |                                                                 | $e_R$ | $\mu_R$ | $\tau_R$ |

$$\begin{aligned}
 \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}: D_\mu \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} &= \begin{pmatrix} \partial_\mu - i\frac{g'}{2}y_f B_\mu + i\frac{g}{2}W_\mu^3 & \frac{ig}{\sqrt{2}}W_\mu^+ \\ \frac{ig}{\sqrt{2}}W_\mu^- & \partial_\mu - i\frac{g'}{2}y_f B_\mu - i\frac{g}{2}W_\mu^3 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \\
 &= \begin{pmatrix} \partial_\mu - i(g'\frac{y_f}{2}B_\mu - gI_3^{(1)}W_\mu^3) & \frac{ig}{\sqrt{2}}W_\mu^+ \\ \frac{ig}{\sqrt{2}}W_\mu^- & \partial_\mu - i(g'\frac{y_f}{2}B_\mu - gI_3^{(2)}W_\mu^3) \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}
 \end{aligned}$$

$$\begin{aligned}
 B_\mu &= (gA_\mu + g'y_H Z_\mu) / \sqrt{g^2 + y_H^2 g'^2} \\
 W_\mu^3 &= (gZ_\mu - g'y_H A_\mu) / \sqrt{g^2 + y_H^2 g'^2}
 \end{aligned}$$

$$\begin{aligned}
 g'\frac{y_f}{2}B_\mu - gI_3 W_\mu^3 &= \frac{1}{\sqrt{g^2 + y_H^2 g'^2}} \left[ \left( \frac{g'y_f}{2}g + gg'I_3 y_H \right) A_\mu \right. \\
 &\quad \left. + \left( g'^2 \frac{y_f y_H}{2} - g^2 I_3 \right) Z_\mu \right] \\
 &= \frac{gg'}{\sqrt{g^2 + y_H^2 g'^2}} \left( \frac{y_f}{2} + I_3 y_H \right) A_\mu + \frac{1}{\sqrt{g^2 + y_H^2 g'^2}} \left( \frac{g'^2 y_f y_H}{2} - g^2 I_3 \right) Z_\mu.
 \end{aligned}$$

Higgs 场是二重态,  $\therefore I_3 = -\frac{1}{2}$  的分量电荷为 0.

对于费米子二重态  $I_3 = \pm \frac{1}{2}$

对于右手费米子单态  $I_3 = 0$ .

选取  $g' \rightarrow y_H g' \rightarrow$  (等效于重新定义  $y_H = +1$ )

$$y_f \rightarrow y_f y_H \uparrow$$

$$\text{上式变为: } \frac{gg'}{\sqrt{g^2 + g'^2}} \left( I_3 + \frac{y_f}{2} \right) A_\mu + \frac{1}{\sqrt{g^2 + g'^2}} \left( g'^2 \frac{y_f}{2} - g^2 I_3 \right) Z_\mu.$$

$$\text{定义: } e = \frac{gg'}{\sqrt{g^2 + g'^2}} \quad Q_f = I_3 + \frac{y_f}{2}$$

$$g' / \sqrt{g^2 + g'^2} = \sin \theta_w$$

$$\frac{g}{\sqrt{g^2 + g'^2}} = \cos \theta_w \quad \frac{g'}{\sqrt{g^2 + g'^2}} = \sin \theta_w \quad \Rightarrow m_w = m_2 \cos \theta_w$$

$$e = \frac{g g'}{\sqrt{g^2 + g'^2}} \quad \Rightarrow \quad g = \frac{e}{\sin \theta_w} \quad g' = \frac{e}{\cos \theta_w}$$

$$\frac{g g'}{\sqrt{g^2 + g'^2}} (I_3 + \frac{Y_f}{2}) A_\mu + \frac{1}{\sqrt{g^2 + g'^2}} (g'^2 \frac{Y_f}{2} - g^2 I_3) Z_\mu$$

$$= e Q_f A_\mu + \left( \frac{e \sin \theta_w}{2 \cos \theta_w} Y_f - \frac{e \cos \theta_w}{\sin \theta_w} I_3 \right) Z_\mu$$

$$\therefore I_3 + \frac{Y_f}{2} = Q_f \quad Y_f = 2(Q_f - I_3)$$

$$\therefore \rightarrow e Q_f A_\mu + \left( (Q_f - I_3) \cdot \frac{e \sin \theta_w}{\cos \theta_w} - \frac{e \cos \theta_w}{\sin \theta_w} I_3 \right) Z_\mu$$

$$= e Q_f A_\mu + \left( Q_f \cdot \frac{e \sin \theta_w}{\cos \theta_w} - I_3 e \left( \frac{1}{\cos \theta_w \sin \theta_w} \right) \right) Z_\mu$$

$$= e Q_f A_\mu - \frac{g}{\cos \theta_w} (I_3 - Q_f \sin^2 \theta_w) Z_\mu$$

$$\therefore D_\mu \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} \partial_\mu - ie Q_f A_\mu + \frac{i g}{\cos \theta_w} (I_3 - Q_f \sin^2 \theta_w) Z_\mu & \frac{i g}{\sqrt{2}} W_\mu^+ \\ \frac{i g}{\sqrt{2}} W_\mu^- & \partial_\mu - ie Q_f A_\mu + \frac{i g}{\cos \theta_w} (I_3 - Q_f \sin^2 \theta_w) Z_\mu \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}$$

$$\therefore i(\bar{\psi}_1 \bar{\psi}_2) \not{D} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \bar{\psi}_1 (i \not{\partial} + e Q_1 A_\mu \gamma^\mu - \frac{g}{\cos \theta_w} (I_3 - Q_1 \sin^2 \theta_w) Z_\mu \gamma^\mu) \psi_1$$

$$+ \bar{\psi}_2 (i \not{\partial} + e Q_2 A_\mu \gamma^\mu - \frac{g}{\cos \theta_w} (I_3 - Q_2 \sin^2 \theta_w) Z_\mu \gamma^\mu) \psi_2$$

$$- \frac{g}{\sqrt{2}} \bar{\psi}_1 \gamma^\mu \psi_2 W_\mu^+ - \frac{g}{\sqrt{2}} \bar{\psi}_2 \gamma^\mu \psi_1 W_\mu^-$$

$$Q_2 = Q_1 - 1$$

对于右手,  $I_3 = 0$

$$\begin{aligned} D_\mu \psi &= \partial_\mu \psi - ig' \frac{\gamma_5}{2} B_\mu \psi \\ &= \partial_\mu \psi - ieQ_f A_\mu \psi - \frac{igQ_f}{\cos\theta_w} \sin^2\theta_w Z_\mu \psi \end{aligned}$$

$$\begin{aligned} \therefore i\bar{\psi} \not{D} \psi &= \bar{\psi} i\not{\partial} \psi + eQ_f \bar{\psi} \gamma^\mu \psi A_\mu + \frac{gQ_f}{\cos\theta_w} \sin^2\theta_w \bar{\psi} \gamma^\mu \psi Z_\mu \\ Q_f &= Y_f/2 \end{aligned}$$

$$\therefore \mathcal{L}_f = i\bar{\psi}_L \not{D}_L \psi_L + i\bar{\psi}_R \not{D}_R \psi_R$$

$$= i\bar{\psi}_1 \not{\partial} \psi_1 + i\bar{\psi}_2 \not{\partial} \psi_2 + eQ_1 \bar{\psi}_1 \gamma^\mu \psi_1 A_\mu$$

$$+ eQ_2 \bar{\psi}_2 \gamma^\mu \psi_2 A_\mu - \frac{g}{2\sqrt{2}} \bar{\psi}_1 \gamma^\mu (1-\gamma_5) \psi_2 W_\mu^+$$

$$- \frac{g}{2\sqrt{2}} \bar{\psi}_2 \gamma^\mu (1-\gamma_5) \psi_1 W_\mu^-$$

$$- \sum_{i=1,2} \frac{g}{2\cos\theta_w} Z_\mu \bar{\psi}_i \gamma^\mu [ (1-\gamma_5) (I_{3i} - Q_i \sin^2\theta_w) - Q_i \sin^2\theta_w (1+\gamma_5) ] \psi_i$$

↓

$$- \frac{g}{2\cos\theta_w} \sum_{i=1,2} Z_\mu \bar{\psi}_i \gamma^\mu [ (I_{3i} - 2Q_i \sin^2\theta_w) - I_{3i} \gamma_5 ] \psi_i$$

# Yukawa Interaction, CKM matrix

Fermion mass.

$$Y_d \bar{Q}_L \cdot H \cdot d_R = Y_d (\bar{u}_L \ \bar{d}_L) \begin{pmatrix} 0 \\ v \end{pmatrix} \cdot d_R = Y_d v \bar{d}_L d_R$$
$$y = (-\frac{1}{3} + 1 - \frac{2}{3}) = 0$$

$$\therefore -Y_d \bar{Q}_L \cdot H d_R + h.c. = -Y_d v \bar{d} d \quad Y_d v = m_d$$

同理.  $Y_e \bar{L}_L \cdot H e_R = Y_e (\bar{\nu}_L \ \bar{e}_L) \begin{pmatrix} 0 \\ v \end{pmatrix} e_R = Y_e v \bar{e}_L e_R$

$$y = (1 + 1 - 2) = 0$$

$$\therefore -Y_e \bar{L}_L H e_R + h.c. = -Y_e v \bar{e} e \quad Y_e v = m_e$$

$m_u = ?$

SU(2) 群的二维表示,  $\xi_\alpha = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix}$

不变量.

$$(1) \quad \eta^\dagger_\alpha \xi_\alpha = (\eta_1^*, \eta_2^*) \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix}$$

$$\xi \rightarrow U \xi, \quad \eta \rightarrow U \eta \quad \therefore \eta^\dagger \rightarrow \eta^\dagger U^\dagger$$

$$\therefore \eta^\dagger \xi \rightarrow \eta^\dagger U^\dagger \cdot U \xi \quad \therefore U \in \text{SU}(2), \quad U^\dagger U = 1$$

$\therefore \eta^\dagger \xi \rightarrow \eta^\dagger \xi$  是不变量.

$$(2) \quad \text{考虑 } \begin{pmatrix} \eta_1 & \xi_1 \\ \eta_2 & \xi_2 \end{pmatrix} \equiv (\eta_\alpha, \xi_\alpha)$$

$$(\eta_\alpha, \xi_\alpha) \rightarrow (U \eta, U \xi) = U \cdot (\eta, \xi)$$

$$\det(\eta, \xi) \rightarrow \det(U \cdot (\eta, \xi)) = \det U \cdot \det(\eta, \xi) = \det(\eta, \xi)$$

$\therefore \det(\eta, \xi)$  是不变量

$$\det(\eta, \xi) = -\det(\xi, \eta) = \varepsilon^{\alpha\beta} \eta_\alpha \xi_\beta \quad \varepsilon^{12} = 1, \varepsilon^{21} = -1, \varepsilon^{11} = \varepsilon^{22} = 0.$$

$$\therefore \det(\eta, \xi) = \varepsilon^{\alpha\beta} \eta_\alpha \xi_\beta = \eta_1 \xi_2 - \eta_2 \xi_1$$

$\therefore$  除  $\bar{Q}_L H$  外, 还有另一个不变量:  $\det \begin{pmatrix} \bar{Q}_L \\ H^\dagger \end{pmatrix}$

$$-Y_u \det \begin{pmatrix} \bar{u}_L & \bar{d}_L \\ 0 & v \end{pmatrix} \cdot U_R = -Y_u v \bar{u}_L U_R$$

$$Y = -\frac{1}{3} - 1 + \frac{4}{3}$$

$$\therefore -Y_u \varepsilon^{\alpha\beta} \bar{Q}_{L\alpha} H_\beta^* U_R = -Y_u v \bar{u}_L U_R$$

为什么  $\varepsilon^{\alpha\beta} \eta_\alpha \xi_\beta$  能构成不变量?

对于  $SU(2)$  的么正表示  $\xi$ ,  $\forall g \in SU(2) \rightarrow \xi \rightarrow U(g)\xi$

$\xi$  构成 2 维复线性空间  $V_C$ , 且  $V_C$  上有内积 (正定非退化二次型):  $(\eta, \xi)$ , s.t.  $(U(g)\eta, U(g)\xi) = (\eta, \xi)$

第一种不变量  $\eta^\dagger \xi$  即此内积

对这一表示, 考虑  $U(g)^*$ , (复共轭但不转置)

$$\text{显然, } U(g_1)^* \cdot U(g_2)^* = (U(g_1) \cdot U(g_2))^* = U(g_1 g_2)^*$$

$\therefore U(g)^*$  也是  $SU(2)$  群的表示, 称为  $2^*$  表示

$U(g)$  称为  $2$  表示.

Question  $2^*$  和  $2$  "等价" 吗?

如果能找到不随  $g$  变化且总使  $U(g)^* = S U(g) S^{-1}$  的常变换  $S$ , 则称  $2$  与  $2^*$  等价. 此时.

$$U(g)^* \xi = S U(g) S^{-1} \xi$$



即  $U(g)^*$  在基底  $\{S\bar{e}_1, S\bar{e}_2\}$  下的表示矩阵  
与  $U(g)$  在基底  $\{\bar{e}_1, \bar{e}_2\}$  下的表示矩阵相同

$$\therefore \text{表示矩阵 } U = \begin{pmatrix} a+bi & c+di \\ -c+di & a-bi \end{pmatrix}, \quad a^2+b^2+c^2+d^2=1$$

$$\therefore U^* = \begin{pmatrix} a-bi & c-di \\ -c-di & a+bi \end{pmatrix}$$

显然, 
$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} a+bi & c+di \\ -c+di & a-bi \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \\ = \begin{pmatrix} -c+di & a-bi \\ -a-bi & -c-di \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} a-bi & c-di \\ -c-di & a+bi \end{pmatrix} = U^*$$

$$\therefore S = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = i\sigma^2 = \varepsilon^{\alpha\beta} \text{ 满足 } U^* = SUS^{-1}$$

显然,  $U^*$  是作用在  $\xi^*$  上的.  $\therefore U^* \xi^* = SUS^{-1} \xi^*$

$\therefore S^{-1} \xi^*$  与  $\xi$  的变换规律相同.  $\therefore (\eta, S^{-1} \xi^*)$  是内积的合法形式.

此即 
$$(\eta_1^*, \eta_2^*) \cdot \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \xi_1^* \\ \xi_2^* \end{pmatrix} = -\eta_1^* \xi_2^* + \eta_2^* \xi_1^*$$

这样 对于 up quark, 我们也可以由  $\begin{pmatrix} 0 \\ v \end{pmatrix}$  得到质量项.

$$\mathcal{L}_{\text{Yukawa}} = -Y_d \bar{Q}_L H d_R - Y_e \bar{L}_L H e_R - Y_u \epsilon^{\alpha\beta} \bar{Q}_{L\alpha} H_\beta u_R + \text{h.c.}$$

$$\begin{aligned} \therefore &= -(\bar{d}_L \bar{s}_L \bar{b}_L) Y_d v \cdot \begin{pmatrix} d_R \\ s_R \\ b_R \end{pmatrix} - (\bar{e}_L \bar{\mu}_L \bar{\tau}_L) Y_e v \begin{pmatrix} e_R \\ \mu_R \\ \tau_R \end{pmatrix} \\ &\quad - (\bar{u}_L \bar{c}_L \bar{t}_L) Y_u v \begin{pmatrix} u_R \\ c_R \\ t_R \end{pmatrix} + \text{h.c.} \end{aligned}$$

$$\text{定义 } M_d = Y_d v \quad M_u = Y_u v \quad M_e = Y_e v.$$

$$\begin{aligned} \therefore \mathcal{L}_{\text{Yukawa}} &= -\bar{D}_L M_d D_R - \bar{D}_R M_d^\dagger D_L \\ &\quad - \bar{E}_L M_e E_R - \bar{E}_R M_e^\dagger E_L \\ &\quad - \bar{U}_L M_u U_R - \bar{U}_R M_u^\dagger U_L \end{aligned}$$

$$D_x \equiv \begin{pmatrix} d_x \\ s_x \\ b_x \end{pmatrix} \quad E_x \equiv \begin{pmatrix} e_x \\ \mu_x \\ \tau_x \end{pmatrix} \quad U_x \equiv \begin{pmatrix} u_x \\ c_x \\ t_x \end{pmatrix}$$

定理: 任意  $n \times m$  矩阵,  $M$ , 一定可以被一对幺正矩阵  $U, V$  对角化

$$UMV = \text{diag}(m_1, m_2, \dots, m_n) \quad \text{且 } m_i \geq 0$$

(Singular Value Decomposition)  $\rightarrow$  Schmidt decomposition  
in Quantum Information

不妨设  $V_u^\dagger M_u U_u$ ,  $V_d^\dagger M_d U_d$ ,  $V_e^\dagger M_e U_e$  对角化. 其非负对角元分别为  $(m_u, m_c, m_t)$ ,  $(m_d, m_s, m_b)$ ,  $(m_e, m_\mu, m_\tau)$

$\therefore$  费米子的质量本征态为  $\begin{pmatrix} V_F F_L \\ U_F F_R \end{pmatrix} = f$

! 左手部分与右手部分的转动不同.

$$\Rightarrow F_L = V_F^\dagger \frac{1}{2}(1-\gamma_5) f$$

$$F_R = U_F^\dagger \frac{1}{2}(1+\gamma_5) f$$

例: up 夸克三个质量本征态  $u, c, t$ , 与  $u_1, u_2, u_3$  的关系

$$\psi_u = \begin{pmatrix} u_L \\ u_R \end{pmatrix} = \begin{pmatrix} V_{u1} u_{1L} + V_{u2} u_{2L} + V_{u3} u_{3L} \\ U_{u1} u_{1R} + U_{u2} u_{2R} + U_{u3} u_{3R} \end{pmatrix}$$

$$\mathcal{L}_K = \bar{\psi}_u (i\not{\partial} - m_u) \psi_u + \bar{\psi}_c (i\not{\partial} - m_c) \psi_c + \bar{\psi}_t (i\not{\partial} - m_t) \psi_t$$

$$+ \bar{\psi}_d (i\not{\partial} - m_d) \psi_d + \bar{\psi}_s (i\not{\partial} - m_s) \psi_s + \bar{\psi}_b (i\not{\partial} - m_b) \psi_b$$

$$+ \bar{\psi}_e (i\not{\partial} - m_e) \psi_e + \bar{\psi}_\mu (i\not{\partial} - m_\mu) \psi_\mu + \bar{\psi}_\tau (i\not{\partial} - m_\tau) \psi_\tau$$

对于  $A_\mu, Z_\mu$  耦合的流. (spin-1 !!!)

$$\therefore \text{形式均为 } \bar{\psi}_{iL} \Gamma_L \psi_{iL} + \bar{\psi}_{iR} \Gamma_R \psi_{iR}$$

$i = 1, 2, 3$  代  $\psi_i$  为流本征态.

$$\therefore \text{在质量本征态下, } J \Rightarrow \bar{f}_L V \Gamma_L V^\dagger f_L + \bar{f}_R U \Gamma_R U^\dagger f_R$$

$$= \bar{f}_L \Gamma_L f_L + \bar{f}_R \Gamma_R f_R$$

$\rightarrow$  GIM 机制

Glashow-Iliopoulos-Maiani

对于带电流,  $W_\mu^\pm$

$$\mathcal{L} = -\frac{g}{\sqrt{2}} (\bar{u}_{1L} \quad \bar{u}_{2L} \quad \bar{u}_{3L}) \gamma^\mu \begin{pmatrix} d_{1L} \\ d_{2L} \\ d_{3L} \end{pmatrix} W_\mu^+ + h.c.$$

$$= -\frac{g}{\sqrt{2}} (\bar{u} \quad \bar{c} \quad \bar{t}) \cdot V_u \gamma^\mu (1 - \gamma_5) V_d^+ \begin{pmatrix} d \\ s \\ b \end{pmatrix} W_\mu^+ + h.c.$$

$$= -\frac{g}{\sqrt{2}} (\bar{u} \quad \bar{c} \quad \bar{t}) \cdot V_u V_d^+ \gamma^\mu (1 - \gamma_5) \begin{pmatrix} d \\ s \\ b \end{pmatrix} W_\mu^+ + h.c.$$

$$V_{CKM} \equiv V_u V_d^+ = \begin{pmatrix} V_{ud} & V_{us} & V_{ub} \\ V_{cd} & V_{cs} & V_{cb} \\ V_{td} & V_{ts} & V_{tb} \end{pmatrix}$$

Cabibbo - Kobayashi - Maskawa matrix

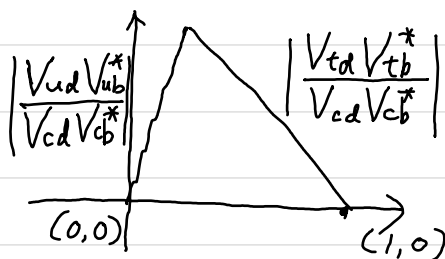
$\therefore V_u, V_d$  为么正矩阵,  $\therefore V_{CKM}$  为  $3 \times 3$  么正矩阵

$$\therefore I = \begin{pmatrix} V_{ud}^* & V_{cd}^* & V_{td}^* \\ V_{us}^* & V_{cs}^* & V_{ts}^* \\ V_{ub}^* & V_{cb}^* & V_{tb}^* \end{pmatrix} \begin{pmatrix} V_{ud} & V_{us} & V_{ub} \\ V_{cd} & V_{cs} & V_{cb} \\ V_{td} & V_{ts} & V_{tb} \end{pmatrix}$$

$$\begin{aligned} \therefore |V_{ud}|^2 + |V_{cd}|^2 + |V_{td}|^2 &= |V_{us}|^2 + |V_{cs}|^2 + |V_{ts}|^2 = |V_{ub}|^2 + |V_{cb}|^2 + |V_{tb}|^2 = 1 \\ V_{ud}^* V_{us} + V_{cd}^* V_{cs} + V_{td}^* V_{ts} &= V_{ud}^* V_{ub} + V_{cd}^* V_{cb} + V_{td}^* V_{tb} \\ &= V_{us}^* V_{ub} + V_{cs}^* V_{cb} + V_{ts}^* V_{tb} = 0 \end{aligned}$$

三个么正三角形

常用  $0 = \frac{V_{ud} V_{ub}^*}{V_{cd} V_{cb}^*} + 1 + \frac{V_{td} V_{tb}^*}{V_{cd} V_{cb}^*}$



$V_{CKM}$  有多少自由度?

$$(\bar{u}, \bar{c}, \bar{t}) \begin{pmatrix} V_{ud} & V_{us} & V_{ub} \\ V_{cd} & V_{cs} & V_{cb} \\ V_{td} & V_{ts} & V_{tb} \end{pmatrix} \begin{pmatrix} d \\ s \\ b \end{pmatrix}$$

$V_{ij}$  有 9 个复相位.

$$\begin{pmatrix} e^{i\delta_{ud}} & e^{i\delta_{us}} & e^{i\delta_{ub}} \\ e^{i\delta_{cd}} & e^{i\delta_{cs}} & e^{i\delta_{cb}} \\ e^{i\delta_{td}} & e^{i\delta_{ts}} & e^{i\delta_{tb}} \end{pmatrix}$$

$$u \rightarrow u e^{i\alpha_u} \dots$$

$$\rightarrow \begin{pmatrix} e^{i(\delta_{ud} - \alpha_u + \alpha_d)} & \dots \\ \dots & \dots \\ \dots & \dots \end{pmatrix}$$

$$\delta_{ud} = \alpha_u - \alpha_d \quad \checkmark$$

$$\delta_{us} = \alpha_u - \alpha_s \quad \checkmark$$

$$\rightarrow \delta_{ub} = \alpha_u - \alpha_b \quad \checkmark$$

$$\delta_{cd} = \alpha_c - \alpha_d = \alpha_c - \alpha_u + \delta_{ud} \quad \checkmark$$

$$\delta_{cs} = \alpha_c - \alpha_s = \alpha_c - \alpha_u + \delta_{us} \quad \times$$

$$\delta_{cb} = \alpha_c - \alpha_b = \alpha_c - \alpha_u + \delta_{ub} \quad \times$$

$$\delta_{td} = \alpha_t - \alpha_d = \alpha_t - \alpha_u + \delta_{ud} \quad \checkmark$$

$$\delta_{ts} = \alpha_t - \alpha_s = \alpha_t - \alpha_u + \delta_{us} \quad \times$$

$$\delta_{tb} = \alpha_t - \alpha_b = \alpha_t - \alpha_u + \delta_{ub} \quad \times$$

剩下 4 个复元素

∴ 无法通过夸克的相位重定义将  $V_{CKM}$  中的相位完全消除

!  $2 \times 2$  情况, 无 CP 相位

可以选取将第一行 (-) 列的相位消去

$$\Rightarrow V_{CKM} = \begin{pmatrix} \cos\theta_1 & -\sin\theta_1 \cos\theta_3 & -\sin\theta_1 \sin\theta_3 \\ \sin\theta_1 \cos\theta_2 & V_{cs} & V_{cb} \\ \sin\theta_1 \sin\theta_2 & V_{ts} & V_{tb} \end{pmatrix}$$

$$V_{1j}^* \cdot V_{2j} = 0 \Rightarrow C_1 S_1 C_2 - V_{cs} S_1 C_3 - V_{cb} S_1 S_3 = 0$$

$$\therefore V_{cb} = \frac{C_1 C_2}{S_3} - \frac{C_3}{S_3} V_{cs}$$

$$V_{1j}^* \cdot V_{3j} = 0 \Rightarrow C_1 S_1 S_2 - V_{ts} S_1 C_3 - V_{tb} S_1 S_3 = 0$$

$$\therefore V_{tb} = \frac{C_1 S_2}{S_3} - \frac{C_3}{S_3} V_{ts}$$

$$\therefore V_{CKM} = \begin{pmatrix} C_1 & -S_1 C_3 & -S_1 S_3 \\ S_1 C_2 & V_{cs} & -\frac{C_3}{S_3} V_{cs} + \frac{C_1 C_2}{S_3} \\ S_1 S_2 & V_{ts} & -\frac{C_3}{S_3} V_{ts} + \frac{C_1 S_2}{S_3} \end{pmatrix}$$

$$V_{j1}^* \cdot V_{j2} = 0 \Rightarrow C_1 C_3 = C_2 V_{cs} + S_2 V_{ts} \Rightarrow V_{ts} = \frac{C_1 C_3}{S_2} - \frac{C_2}{S_2} V_{cs}$$

$$V_{CKM} = \begin{pmatrix} C_1 & -S_1 C_3 & -S_1 S_3 \\ S_1 C_2 & V_{cs} & \frac{C_1 C_2}{S_3} - \frac{C_3}{S_3} V_{cs} \\ S_1 S_2 & \frac{C_1 C_3}{S_2} - \frac{C_2}{S_2} V_{cs} & \frac{C_1 S_2}{S_3} - \frac{C_1 C_3^2}{S_2 S_3} + \frac{C_2 C_3}{S_2 S_3} V_{cs} \end{pmatrix}$$

$$\Rightarrow V_{cs} = C_1 C_2 C_3 - S_2 S_3 e^{i\delta}$$

KM matrix

今天，人们习惯用

$$V_{CKM} = \begin{pmatrix} c_{12} c_{13} & s_{12} c_{13} & s_{13} e^{-i\delta} \\ -s_{12} c_{23} - c_{12} s_{23} s_{13} e^{i\delta} & c_{12} c_{23} - s_{12} s_{23} s_{13} e^{i\delta} & s_{23} c_{13} \\ s_{12} s_{23} - c_{12} c_{23} s_{13} e^{i\delta} & -c_{12} s_{23} - s_{12} c_{23} s_{13} e^{i\delta} & c_{23} c_{13} \end{pmatrix}$$

补充:  $V_{cs}$  的确定.

由  $V_{CKM}^\dagger V_{CKM}$  第2行第2列为1,  $\Rightarrow$

$$1 = s_1^2 c_2^2 + |V_{cs}|^2 + \frac{1}{s_3^2} |c_1 c_2 - c_3 V_{cs}|^2$$

$$V_{cs} = x + iy \Rightarrow$$

$$1 = s_1^2 c_2^2 + x^2 + y^2 + s_3^{-2} (c_1 c_2 - c_3 x)^2 + s_3^{-2} c_3^2 y^2$$

$$\therefore s_3^2 = s_1^2 s_3^2 c_2^2 + s_3^2 x^2 + (c_1 c_2 - c_3 x)^2 + s_3^2 y^2 + c_3^2 y^2$$

$$\therefore y^2 + x^2 - 2c_1 c_2 c_3 x + c_1^2 c_2^2 + s_1^2 c_2^2 s_3^2 - s_3^2 = 0$$

$$(x - c_1 c_2 c_3)^2 + y^2 + c_1^2 c_2^2 s_3^2 + s_1^2 c_2^2 s_3^2 - s_3^2 = 0$$

$$s_3^2 - c_1^2 c_2^2 s_3^2 - s_1^2 c_2^2 s_3^2 = s_3^2 (1 - c_1^2 c_2^2 - s_1^2 c_2^2) = s_3^2 (1 - c_2^2) = s_3^2 s_2^2$$

$$\therefore (x - c_1 c_2 c_3)^2 + y^2 = s_2^2 s_3^2$$

$\therefore V_{cs}$  是圆心在  $c_1 c_2 c_3$ , 半径为  $s_2 s_3$  的复平面上圆上的某一点

$$\therefore V_{cs} = c_1 c_2 c_3 - s_2 s_3 e^{i\delta}$$