Tracker optimization for the Fourth Detector Concept of CEPC

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 $s = y_3 - \frac{y_1 + y_2}{2}$

 $\delta s = \delta y_3 - \frac{1}{2}\delta y_1 - \frac{1}{2}\delta y_2$

1.Abstract

The tracking system of the fourth conceptual detector at CEPC consists of a silicon pixel vertex detector, a silicon tracker of HV-CMOS, and a drift chamber (DC). In addition to tracking, the DC plays an important role in particle identification which is essential for flavour physics programme. The layout design will be a trade-off between optimal tracking and PID performance. Large DC volume will benefit identification of various hadrons, but should not cost deterioration of tracks. The study of tracking performance as function of CEPC DC volume is necessary, using two fast-simulation tool and two full-simulation tools validating each other.

2.Introduction

Tracking system consists with a silicon pixel vertex detector(VXD), a silicon tracker (SIT and SET) i > Momentum error -Sagitta measurement without multiple scattering

of HV-CMOS, and a drift chamber (DC)

- □ Particle ID with a drift chamber is a key feature for the 4th conceptual detector
- □ Most hadrons (K/pi) of CEPC are below 20 GeV/c
- □ The tracker must have sufficient good momentum resolution for tracks < 20 GeV/c (flavor and jet study)



3. Momentum Uncertainty





□ Important features:

the percentage error is proportional to the p itself

□ VXD has already been optimized by others







Tools used for calculation & simulation

□ Two fast tools

- Analytic calculation based on python developed by Gang Li et al
- LDT: a matlab fast simulation package developed by Wiener group
- □ Full simulation implemented in CEPCSW, CKF (Combined Kalman Filter) is used to track finding, reconstructed by
 - GenFit: developed by Yao Zhang et al
 - MarlinTrk: ILCSoft tracking maintained by Chengdong Fu

- the error is inversely proportional to B
- the error is inversely proportional to 1/L2
- the error is proportional to spatial resolution



- Necessary to have more measurements at the middle for better resolution
- The optimal allocation of measurements is 1:2:1
- Momentum error with multiple scattering (MS)
 - □ It is found to be complicated, when considering more factors on the momentum measurement.
 - The left figures indicate that the MS affect the tracks, and the MS was influenced by the amount of materials, layout, momentum, and so on
 - □ There are quite a few factors affect the momentum measurement,
 - the relationships among them are shown in the right



Without DC hits





- The three lines has a small difference without DC hits but with DC materials
- SIT's location has a small effect on momentum measurement
- DC inner radius at 1.0m is better than 0.6 or 0.8m





□ Validation: GenFit and MarlinTrk, w/o DC Hits

- The results are very similar when we don't use the DC hits,
- There are a little differences between these two, especially at low momentum

➢ With DC hits



GenFit with DC Hits: --- 0.6~1.8 m 0.8~1.8 m 1.0~1.8 m 10 p, [GeV/c]





- □ Validation: GenFit and MarlinTrk, with DC Hits
- The difference becomes **more significant** when DC Hits are used, in particular at low momentum
- The results of other simulations are consistent with the analytic calculation

5. Physics Performance

10 p, [GeV/c]

6. Conclusion & Discussion

□ Analytic calculation with DC hits

- The difference becomes **more significant** when DC Hits are used, in particular at low momentum
- DC inner radius at 0.6m is better for tracks < 40 GeV/c





The sigmas of Higgs Mass $(H \rightarrow \mu \mu)$

1.0-0.8-0.6-DC volume 1.8(m) 1.8(m) 1.8(m)W/0.210 0.209 0.212 DCHits(GeV) W/0 0.216 0.211 0.231 DCHits(GeV)

□ For Higgs physics(at high momentum), the DC volume has little effect on momentum measurement

□ Using DC will significantly improve higgs momentum measurement

Comments on tools

□ Good agreement between AnaCalc & LDT

Good agreement between GenFit and MarlinTrk w/o DC

□ Rough agreement between GenFit and MarlinTrks w/ DC

□ All trends of different tools are consistent

Preliminary conclusion

D DC useful for momentum measurement

- Shapes and trends are constantly consistent for all results
- More consistent results of different methods need more tuning

□ Larger DC favored by low momentum (<20 GeV) tracks

□ Larger DC also benefits PID





The 2023 international workshop on the high energy Circular Electron-Positron Collider (CEPC), Nanjing, Oct 23-27, 2023