

Recap on track reconstruction in HEP

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Workshop of Computing Software and Technologies in HEP Experiments, Qingdao, June 10, 2023

Tracking what for?

- Track finding: associate discrete measurements (a.k.a. hits) to individual tracks
- Track fitting: estimate properties of tracks at target (reference) position
 - Position, momentum (with magnetic field), charge, possibly dE/dx (and velocity)





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Tracking is crucial to success of physics programs



 Tracking is about vertex reconstruction, jet reconstruction and flavor tagging, pileup mitigation, particle identification...



Figure from Eur. Phys. J. C 76, 581

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Tracking drives the precision of detector alignment



Track-based alignment: Simultaneous optimization of local track parameters and global alignment parameters:

$$\chi^{2} = \sum_{i} \chi_{i}^{2} = \sum_{i} [\vec{m_{i}} - \vec{h_{i}}(\vec{x_{i}}(\vec{\alpha}), \vec{\alpha})]^{T} V^{-1} [\vec{m_{i}} - \vec{h_{i}}(\vec{x_{i}}(\vec{\alpha}), \vec{\alpha})]$$



Tracking detectors

- Tracking is possible due to interaction of charged tracks with detector material
 - Energy loss by ionization (and bremsstrahlung for electron)
- Ionization detector:
 - Continuous: e.g. gaseous detectors (drift chamber, Time Projection Chamber)
 - Discrete: e.g. silicon planar detector



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n-Si

SiO₂

A view of a track

- What we want to know:
 - How far is a track from a reference point, or more accurately, a reference line (e.g. the beam line or drift wire), usually described by impact track parameters d0, z0 (or dz)?
 - What is the **intersection** of a track with a planar detector?
 - The momenta and track direction at a particular point
 - The **charge** of the track
 - Possibly the **time** of the track upon reaching a point

Track parameterization

e.g. ATLAS parameterization: (lx, ly, ϕ , θ , q/p)

lx, ly: track position, either d0, z0 or lx, ly on a real planar detector (the same parameterization with different reference surfaces) ϕ , θ : track direction track track q: charge p: momentum x-y plane x-y plane p Corresponding parameterization at BESIII, BELLE II From E. Moyse $(d_0, \phi, \kappa, d_1, tan\lambda)$ or $(d_0, \phi_0, \omega, d_1, tan\lambda)$

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Track propagation

- Track propagation is solved numerically using fourth-order **Runge-Kutta-Nyström** method in (**inhomogeneous**) magnetic field
- Propagation of both the track parameters vector and their covariance taking into account **material effects** (both energy loss and multiple scattering)



Track finding

- Global approach: e.g. Hough transform, Graph Neural Networks
- Local approach: e.g. Cellular automaton, Combinatorial Kalman Filter (CKF)



Figure from Sara Pohl's thesis

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Figures from ACTS readthedocs

Track fitting

- Least-square fitter:
 - Difficulty with material effects, but can resolve drift distance left/right ambiguity
- Kalman-filter (being used more):
 - More elegant handling of material effects, more extension-friendly



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Track selection

- Reconstructed raw tracks are often passed to further filtering (might involves scoring)
 - Tracks can be scored based on track parameters, fitting quality, number of (shared) hits...
 - Track with poor qualities are removed

e.g. Ranking Neural Network for separation of good and bad tracks by at least a margin

$$loss_{part} = \frac{1}{N_{tracks}} \sum_{max(0, x - y + margin)}^{tracks}$$



See slides of Corentin Allaire at CHEP2023

x: track score; y: good track score; margin = 0.05

Tracking performance

Tracking efficiency and rate of fake/duplicate tracks

- Fake track: sometimes, the hits left on detector by several particles can be accidentally grouped to make a track
- Duplicate track: two reconstructed tracks can be largely overlapped



Examples of tracking performance of STCF using ACTS: arXiv:2301.04306

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Tracking performance

Tracking resolution

- Characterizing the accuracy of the reconstructed track parameters
- Relevant with the intrinsic resolution, layout and material budget of detectors



Examples of tracking performance of STCF using ACTS: arXiv:2301.04306

Towards the future HEP tracking

- Experiments need high-performance tracking software to not compromise physics goals
 - Preserved efficiency, precision and speed with increased luminosity (e.g. $\langle \mu \rangle = 200$ at HL-LHC, up to 7k particles per event)
 - Capability of handling particles with complicated experimental signatures
 - Easy to extend for new detector technologies
 - Supports parallelization (even with heterogeneous computing)
 - Ease of maintenance



e.g. ATLAS at HL-LHC

How about a common tracking software?

- Tracking is a necessity at particle and nuclear physics experiments
- Tracking experience can be shared with different experiments
- Common software can save manpower from duplicated development and facilitate the long-term maintenance
 - e.g. great success of GEANT4, ROOT, DD4hep...!

We already started the effort >5 years ago: A Common Tracking Software (ACTS) project!

➔ See <u>A. Salzburger's talk</u> right away



Summary

- Tracking is pivotal to reconstruction, identification and calibration of high-level physics objects
- Resolving individual tracks is a non-trivial task
 - Material effects, bending by magnetic field, possible huge amount of combinatorics...
- Tracking is concerned with efficiency, resolution and CPU needs
- Tracking will become even more challenging in the future
- We need a performant, extendable, maintainable, and even detector agnostic tracking software to achieve our physics goals
 - A common tracking software, i.e. ACTS, keeps growing and maturing (A. Salzburger's talk right away)
 - Stay tuned for talks of J. Zhang (BESIII), H. Zhou (STCF) and M. Liu (CEPC) for experiment-specific tracking strategies

Thank you