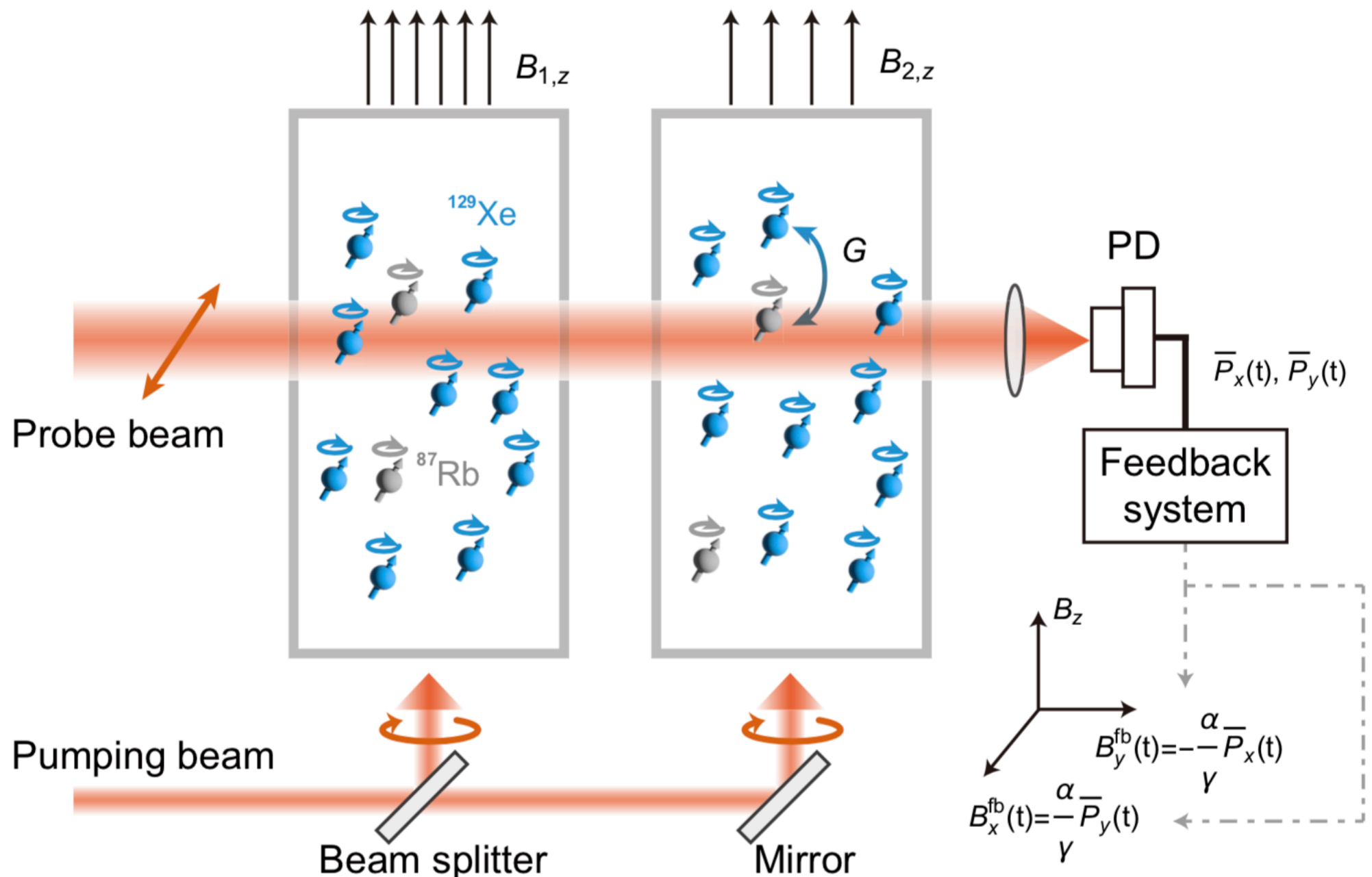
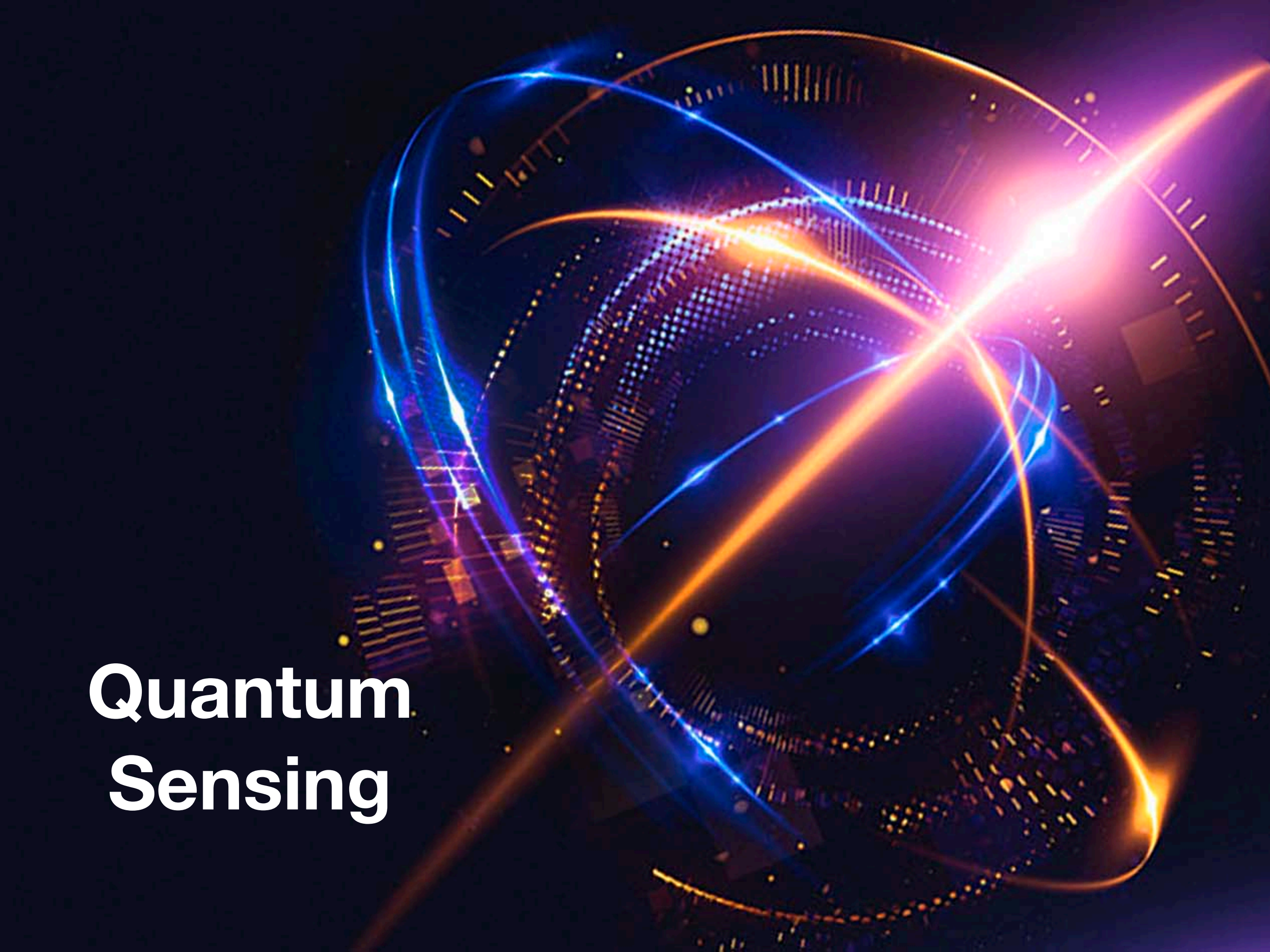


Atomic Magnetometers: Nonlinear Dynamics & Applications

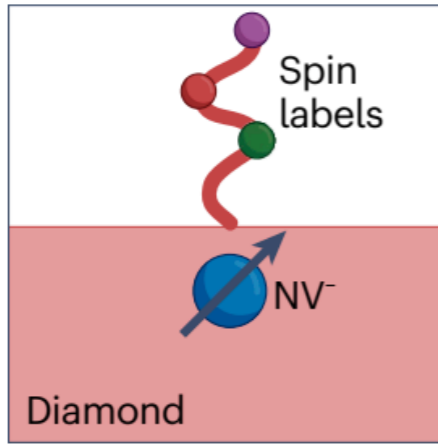
Zhenhua Yu



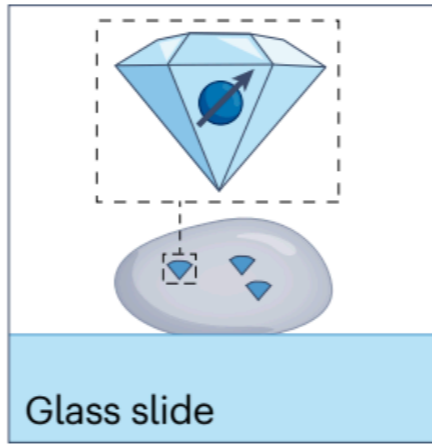
An abstract visualization of quantum sensing. It features a dark background with glowing, swirling lines in blue and orange. The lines form complex, overlapping patterns that suggest a quantum state or a sensor's operation. There are also faint, grid-like structures and small dots scattered throughout the scene, adding to the technical and futuristic feel.

Quantum Sensing

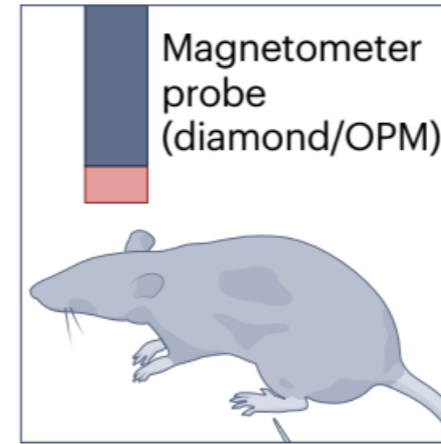
Molecular structure determination



Thermal measurements with nanodiamonds



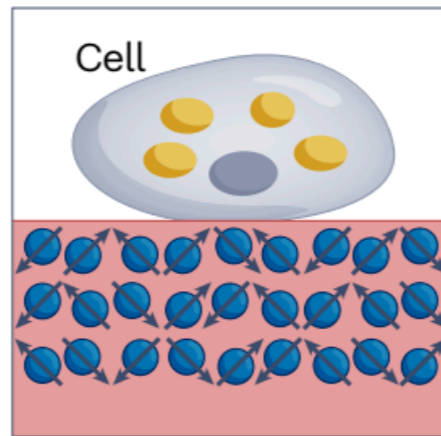
In vivo magnetic activity in animals



Sensitivity

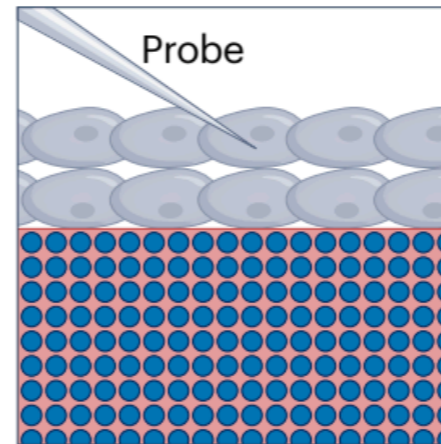
Spatial Resolution

Subcellular organelle metabolic studies



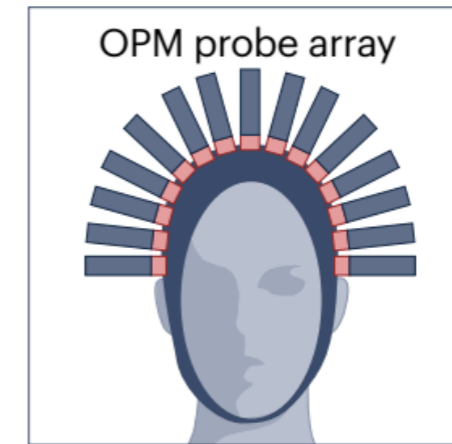
NV ensemble

Electrical activity studies in cellular cultures



Dense NV ensemble

Clinical diagnostics in humans

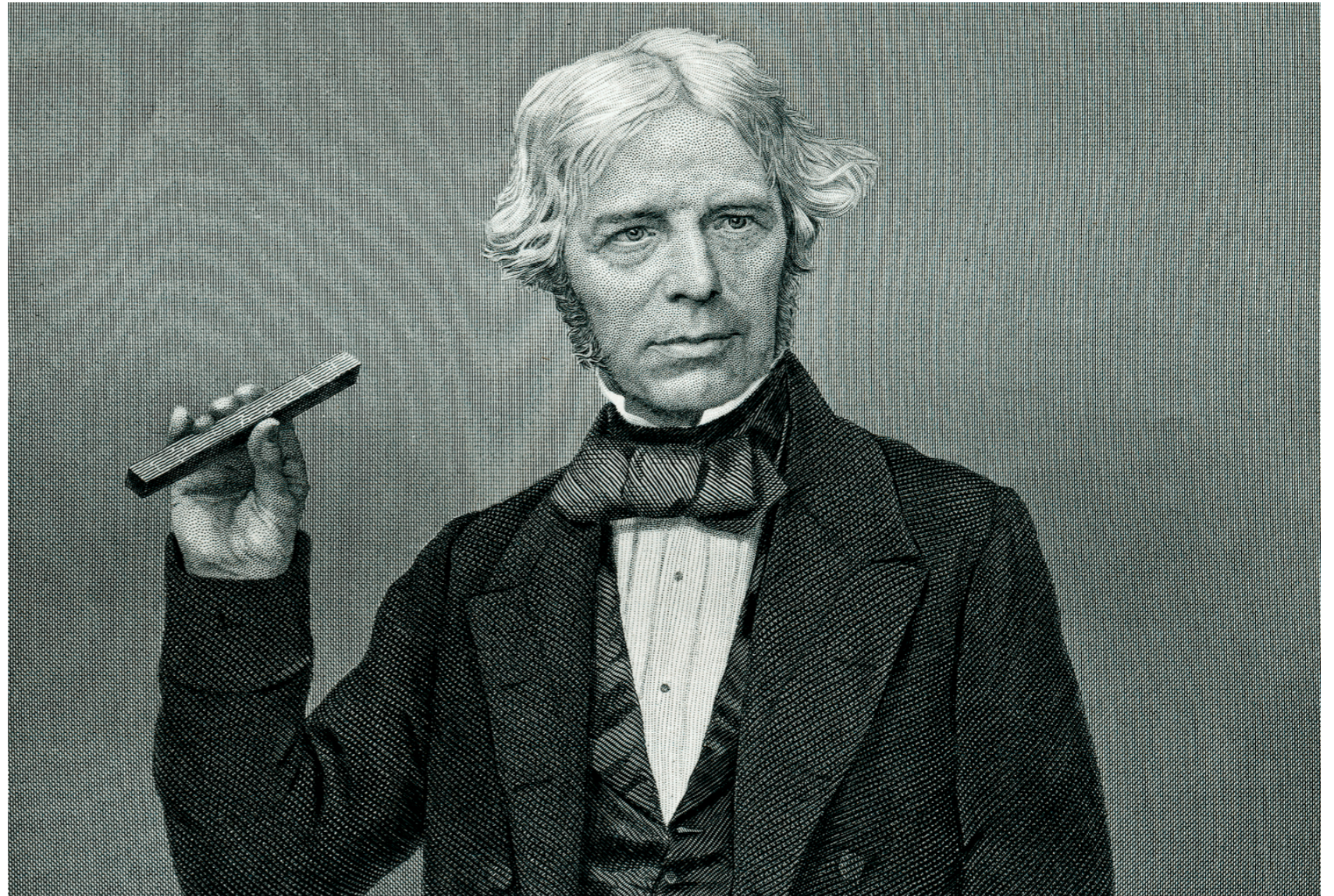
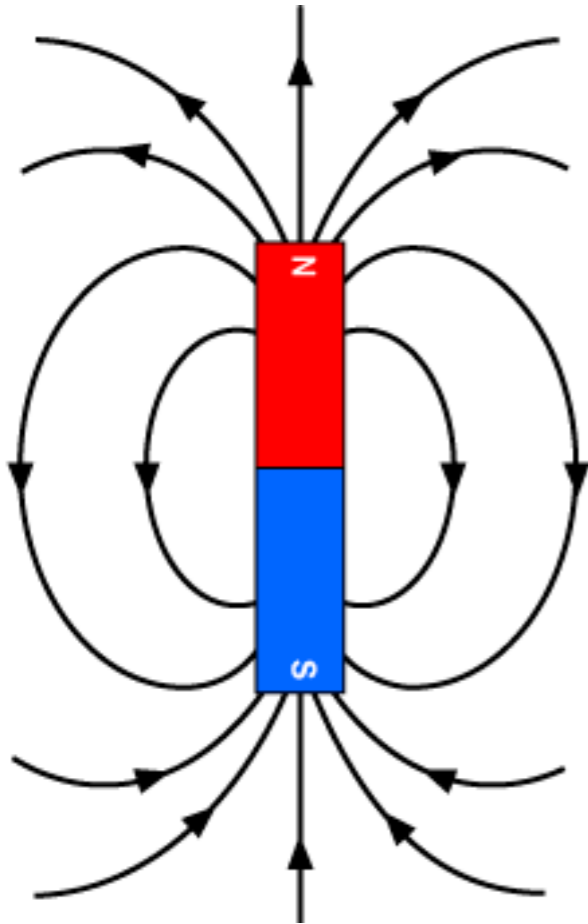


Molecular scale

Cellular scale

Organism scale

Concept of Fields



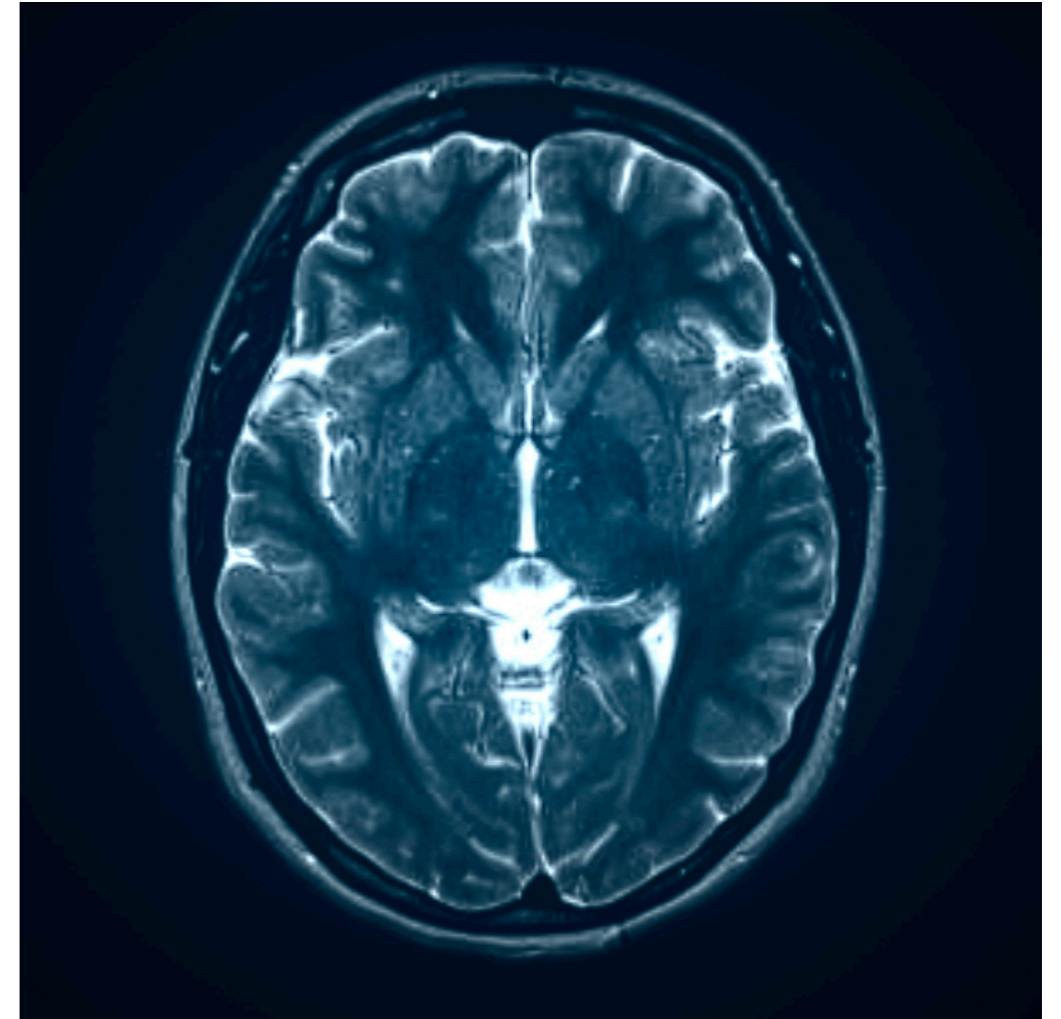
***On New Magnetic Actions* in 1846**

Michael Faraday



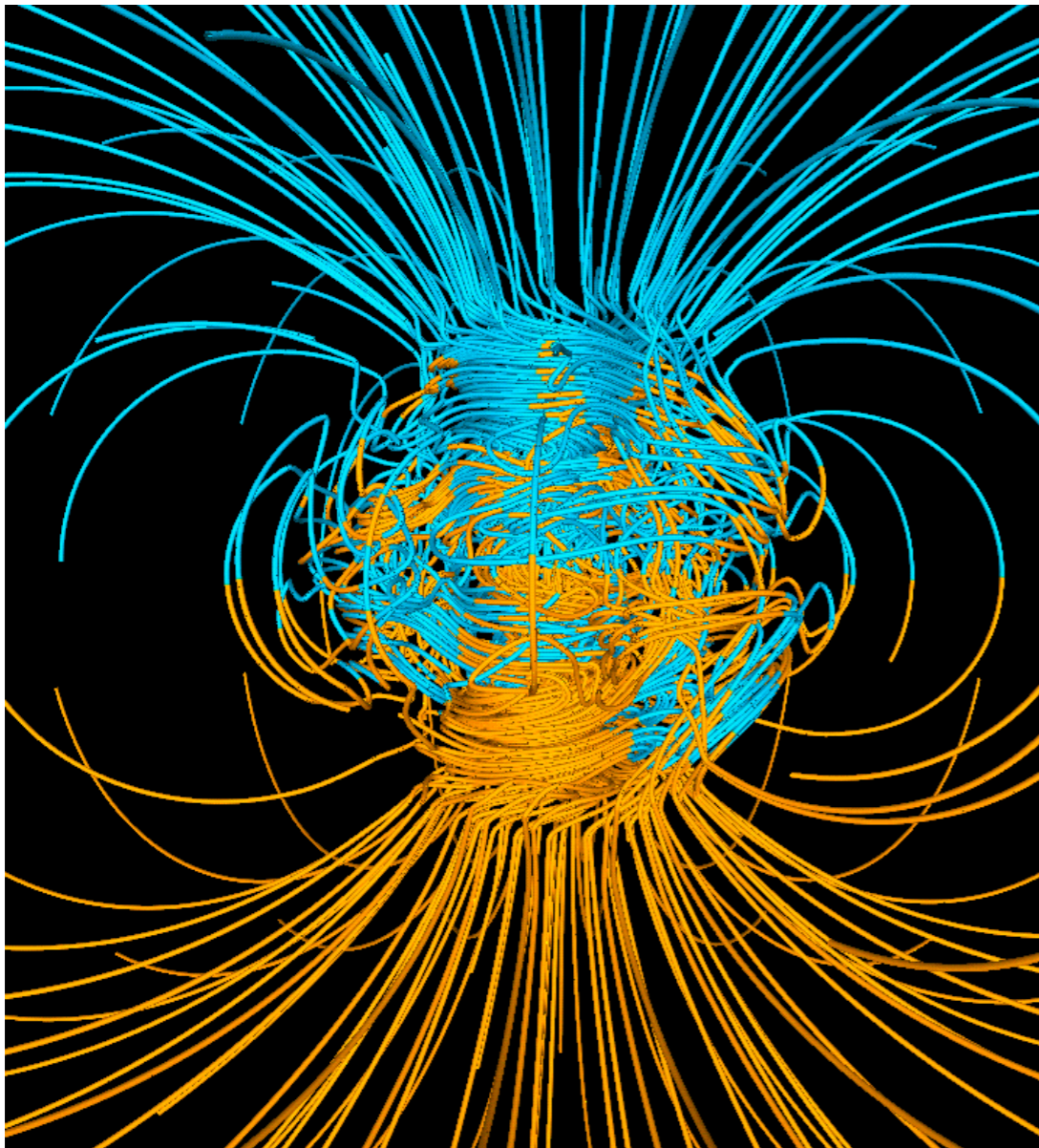
Closest & Remotest

Measurement of Magnetic Fields

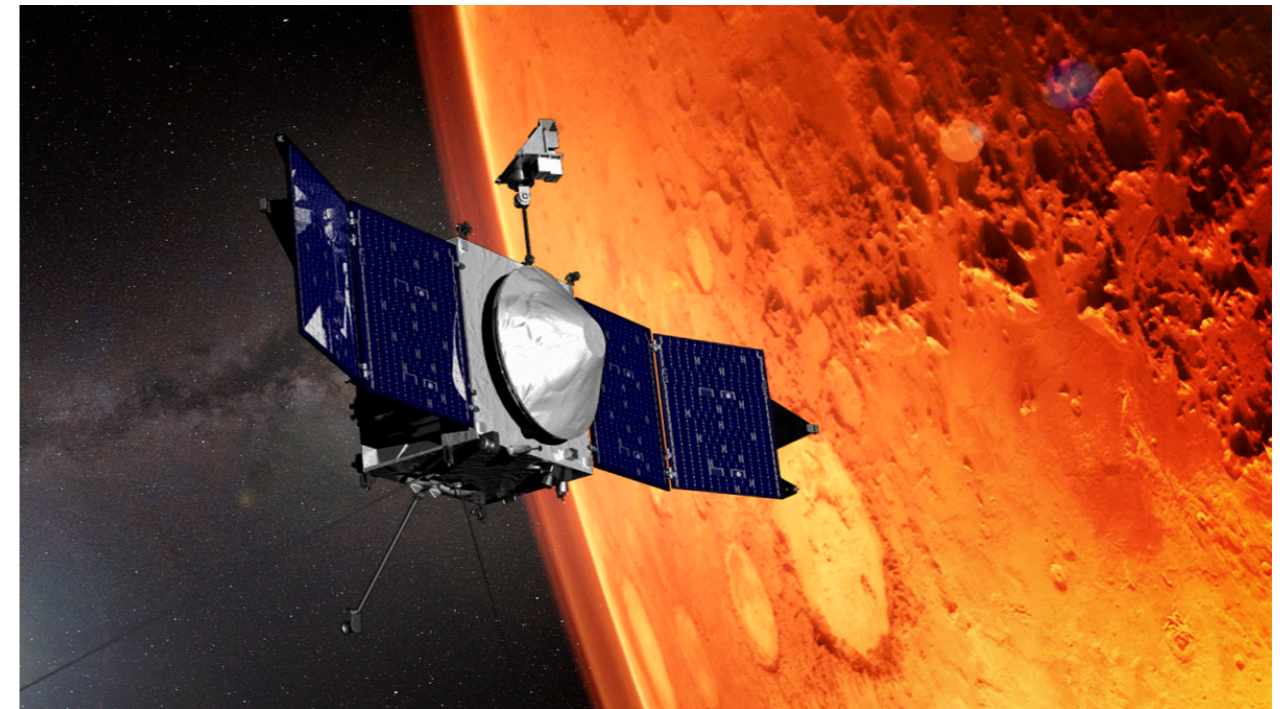


Magnetic Resonance Imaging (MRI)

Measurement of Magnetic Fields



Earth Magnetic Field

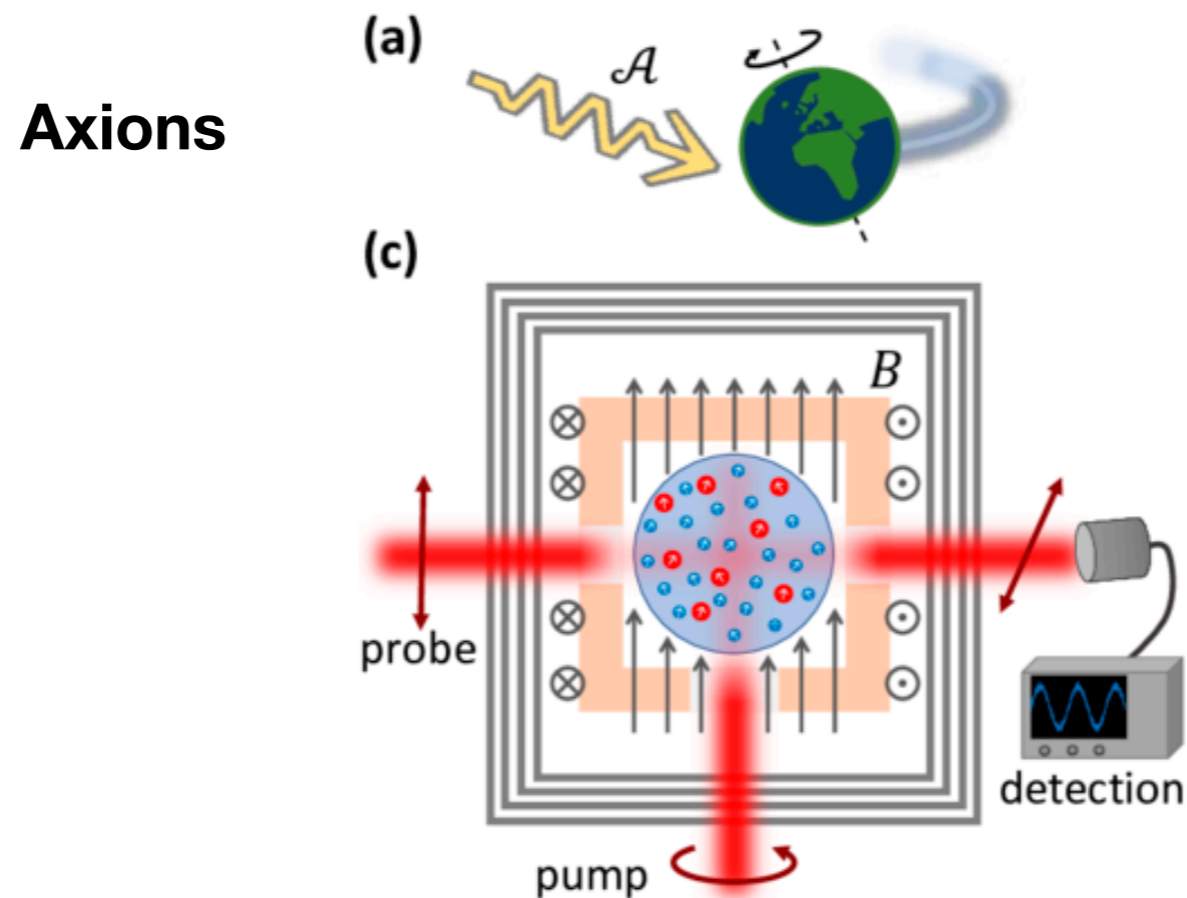


Mars Maven Mission

Mission Facts

Mission Status	Currently Operating
Mars Orbit Insertion	September 21, 2014
Launched	November 18, 2013
Launch Site	Cape Canaveral Air Force Station, Florida

Measurement of Magnetic Fields



$$H_{\text{spin}} = H_{\text{mag}} + H_{\text{BSM}} = -\vec{\mu} \cdot \vec{B}_{\text{ex}} - \vec{\mu} \cdot \vec{\beta}$$

Physics beyond the Standard Model

Noble Atom Based Magnetometers



ChemistryLearner.com

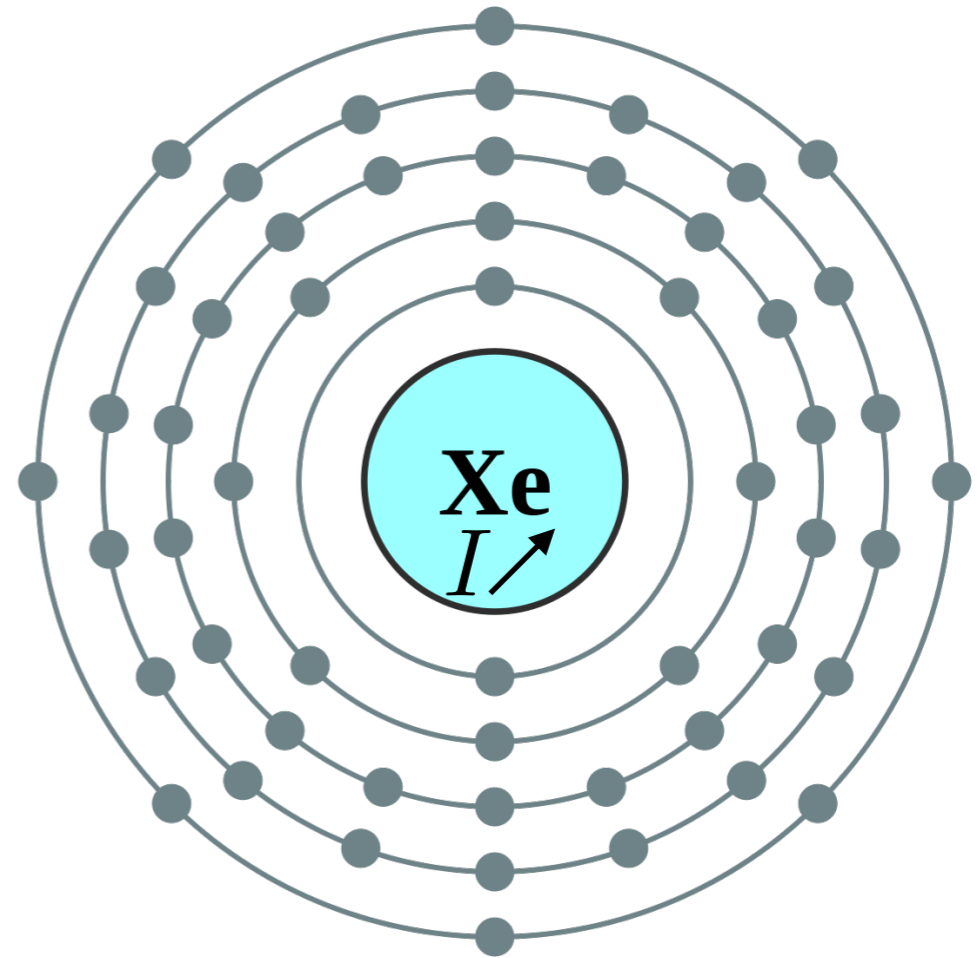
$$S = 0, L = 0$$

$$I_{\text{Xe-129}} = 1/2, I_{\text{Xe-131}} = 3/2$$

Noble Atom Based Magnetometers



ChemistryLearner.com

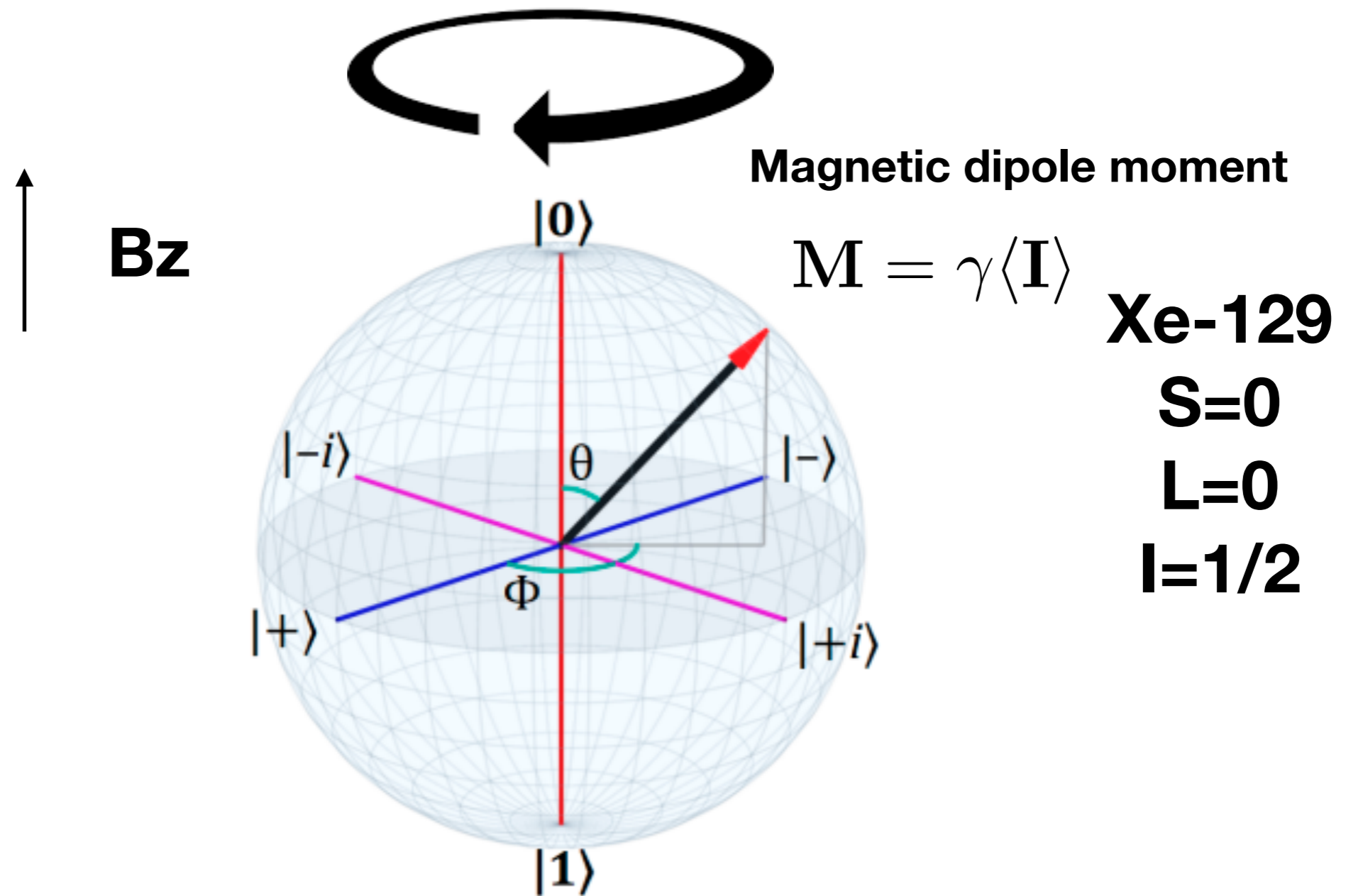


$$S = 0, L = 0$$

$$I_{\text{Xe-129}} = 1/2, I_{\text{Xe-131}} = 3/2$$

Long nuclear spin coherence time

Noble Atom Based Magnetometers



Larmor Precession $\omega_L = \gamma B_z$

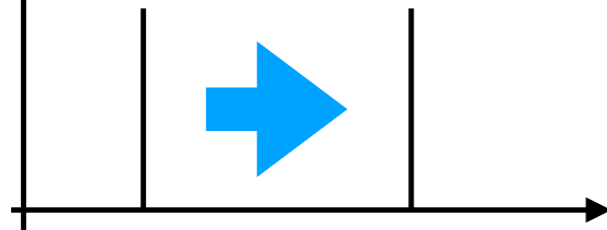
Noble Atom Based Magnetometers

Dark Matter
Particles' Effect

$$\delta B_z$$

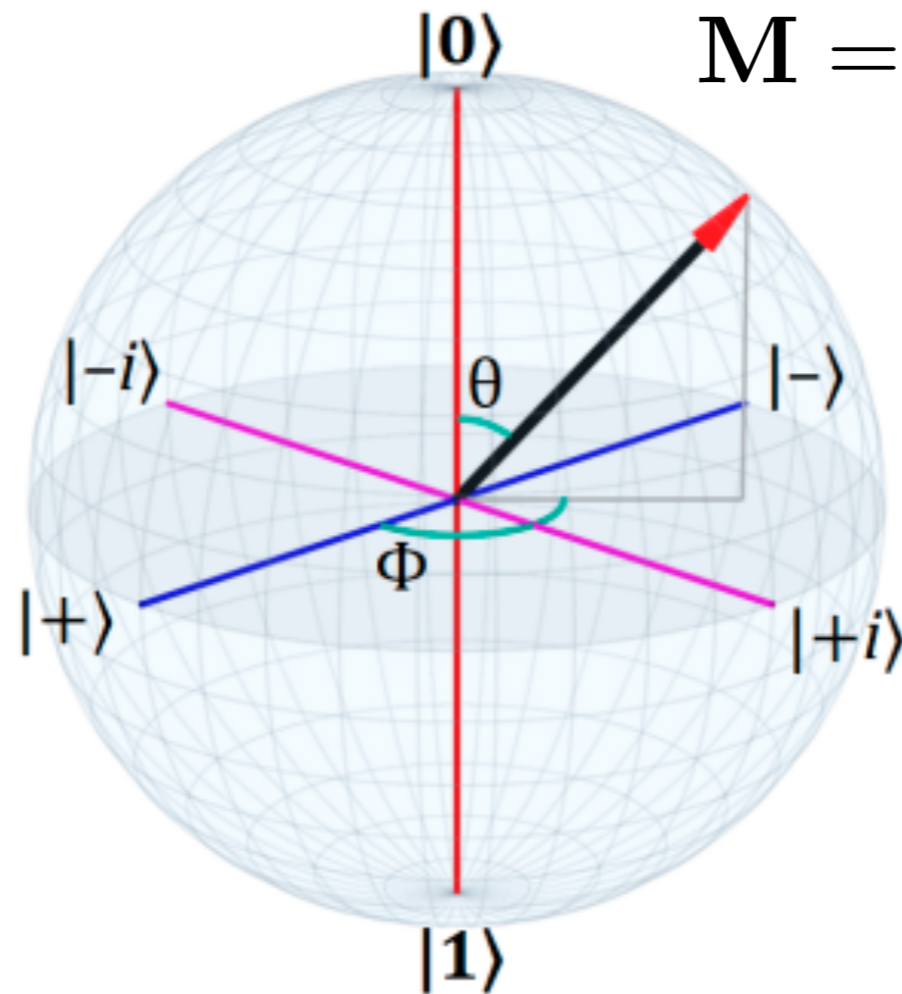
B_z

I Signal intensity



Shift

ω



$$\mathbf{M} = \gamma \langle \mathbf{I} \rangle$$

Xe-129

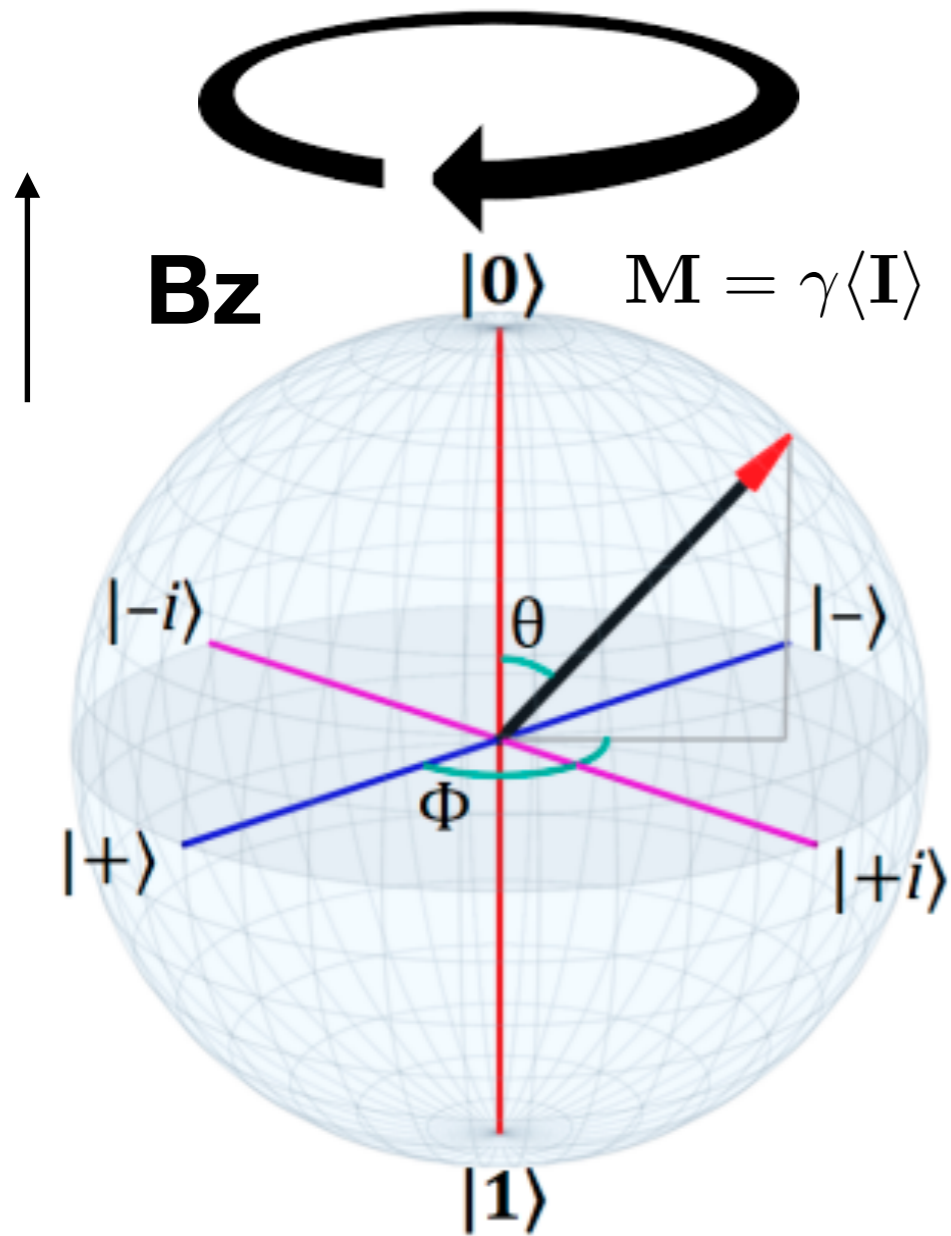
S=0

L=0

I=1/2

Larmor Precession $\omega_L = \gamma B_z$

Obstacle to Precision Measurement: Dissipation

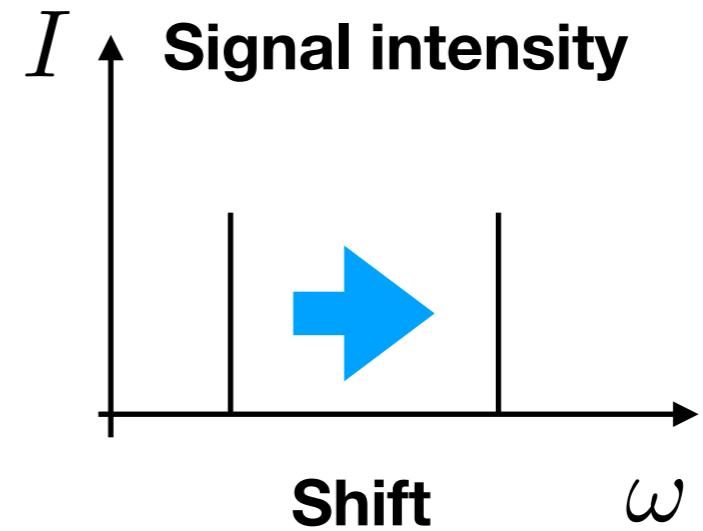


Xe-129

S=0

L=0

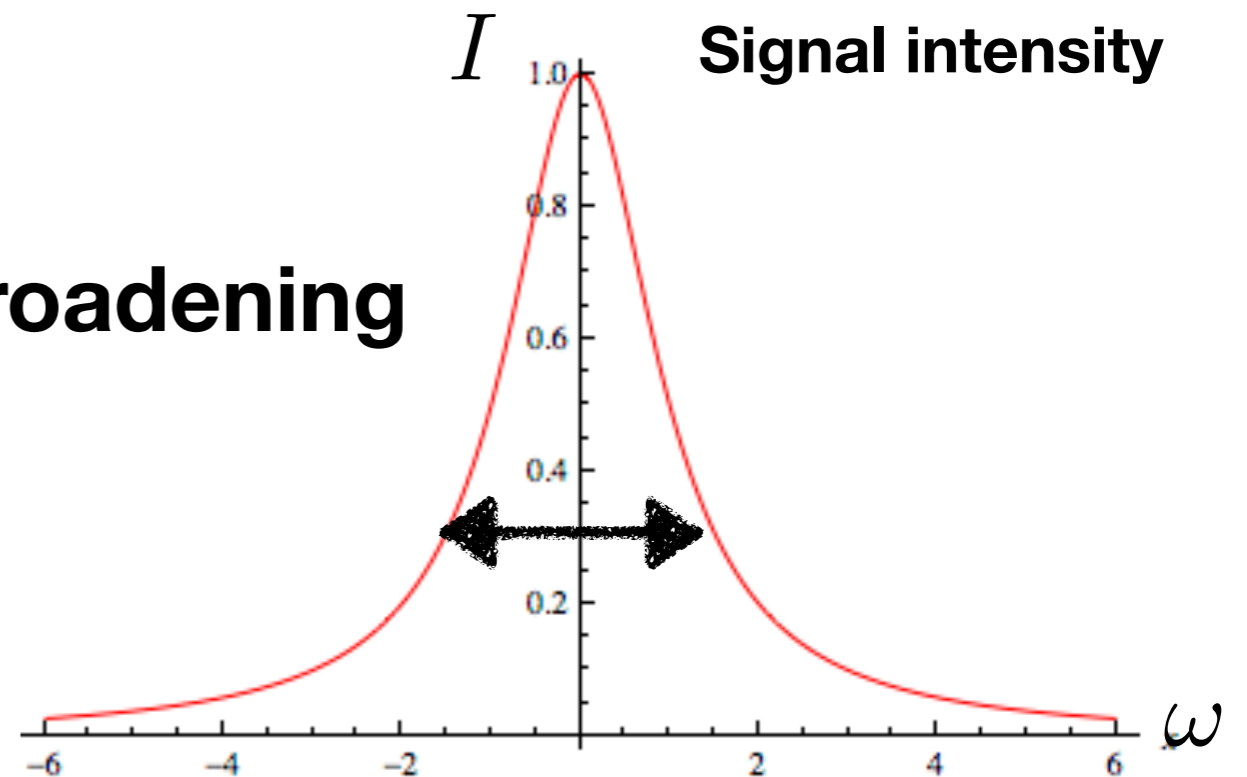
I=1/2



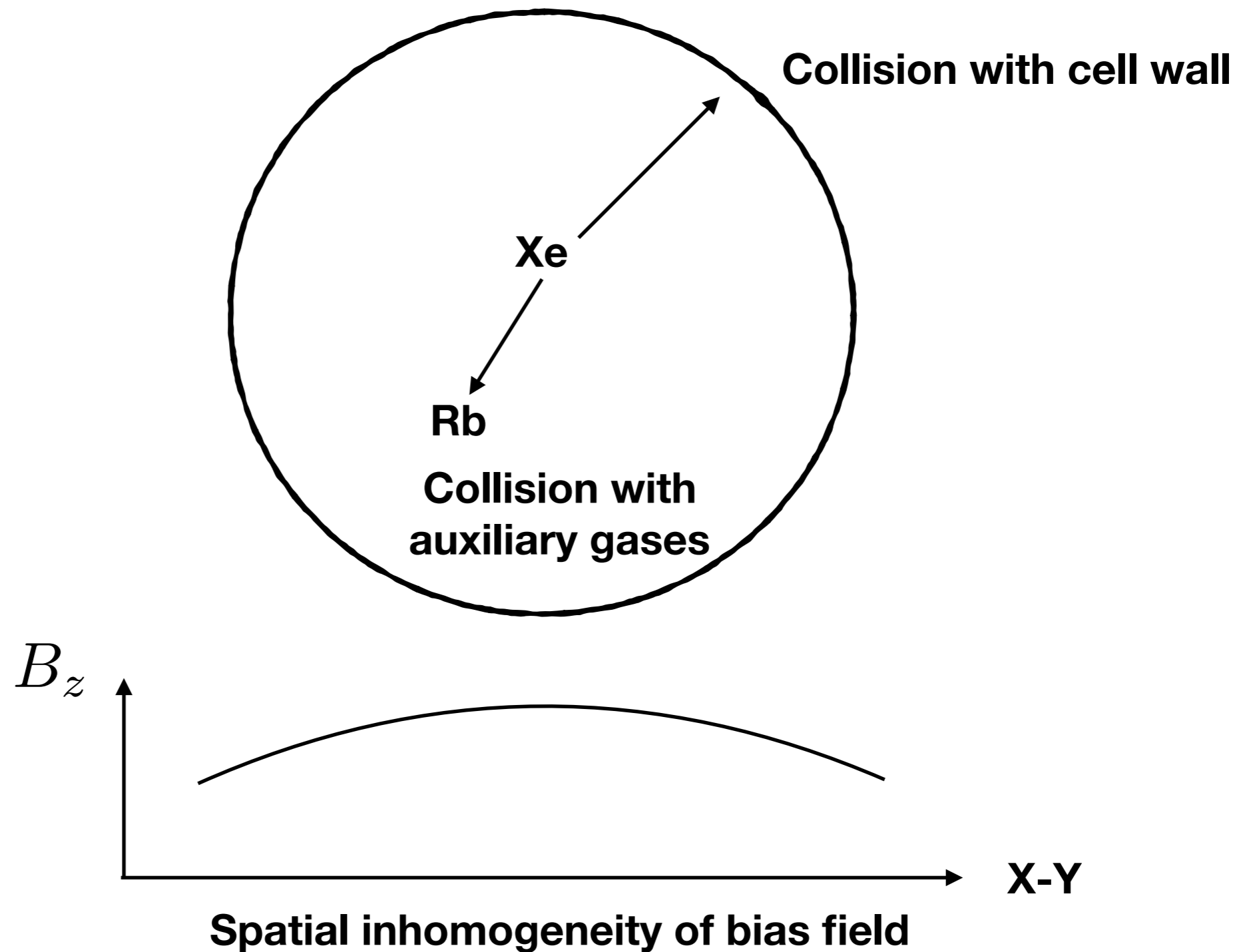
Larmor Precession

$$\omega_L = \gamma B_z$$

Broadening



Where comes dissipation?



Obstacle to Precision Measurement: Dissipation

Xe-129

S=0

L=0

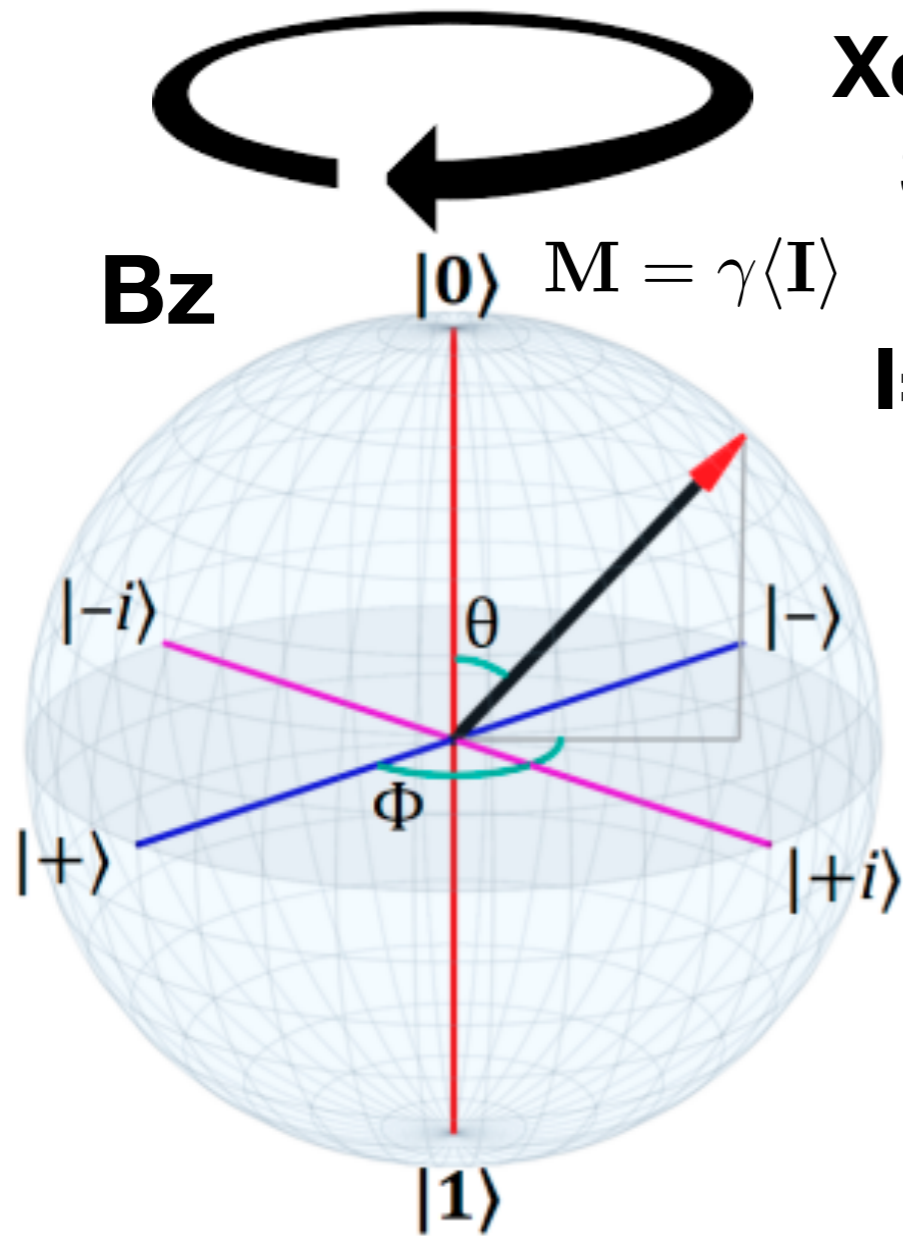
I=1/2

Bloch Equations:

$$\frac{d\mathbf{M}}{dt} = \gamma \mathbf{M} \times \mathbf{B}_0 + \begin{bmatrix} -M_x/T_2 \\ -M_y/T_2 \\ -(M_z - M_0)/T_1 \end{bmatrix}$$

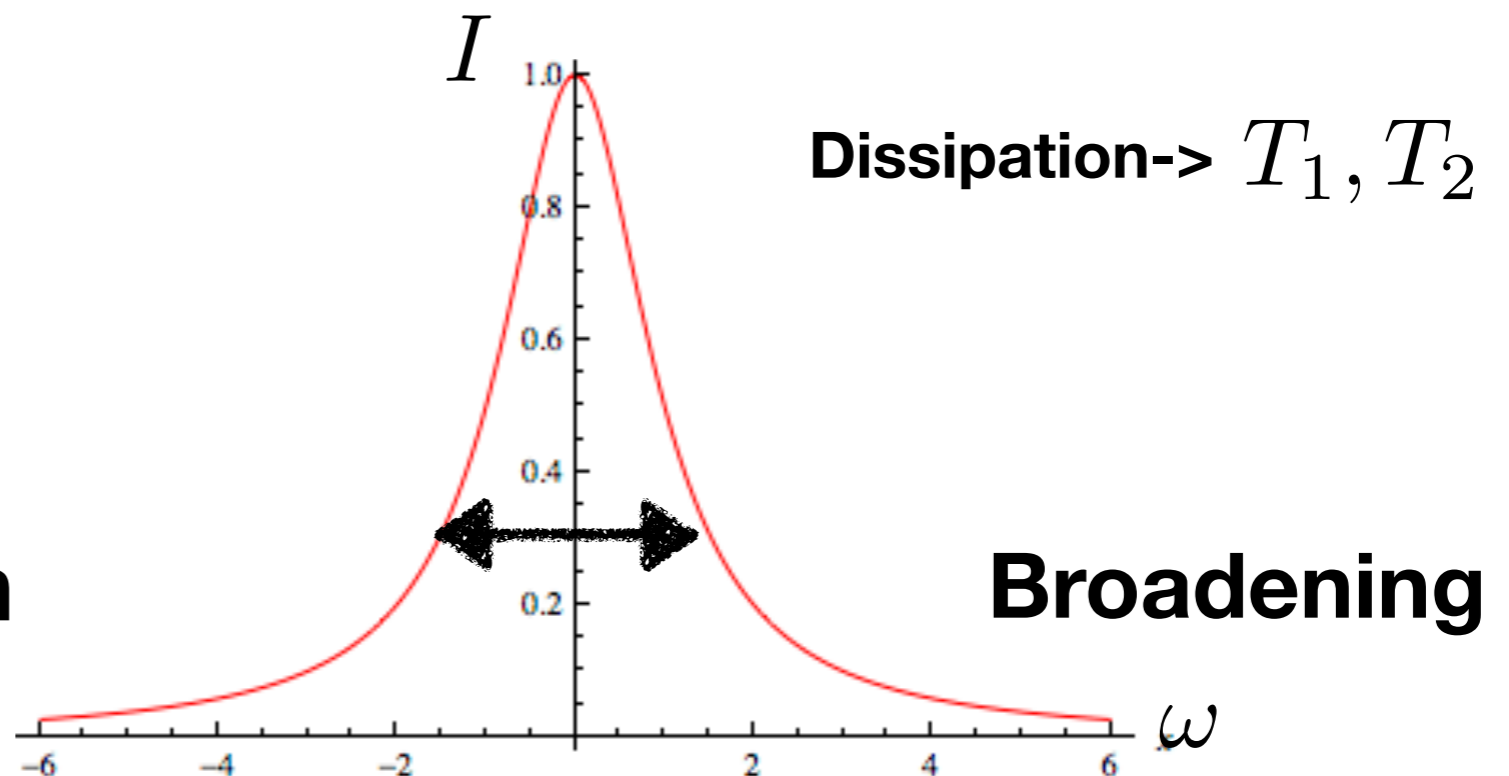
Magnetic dipole moment \mathbf{M}

Pumping

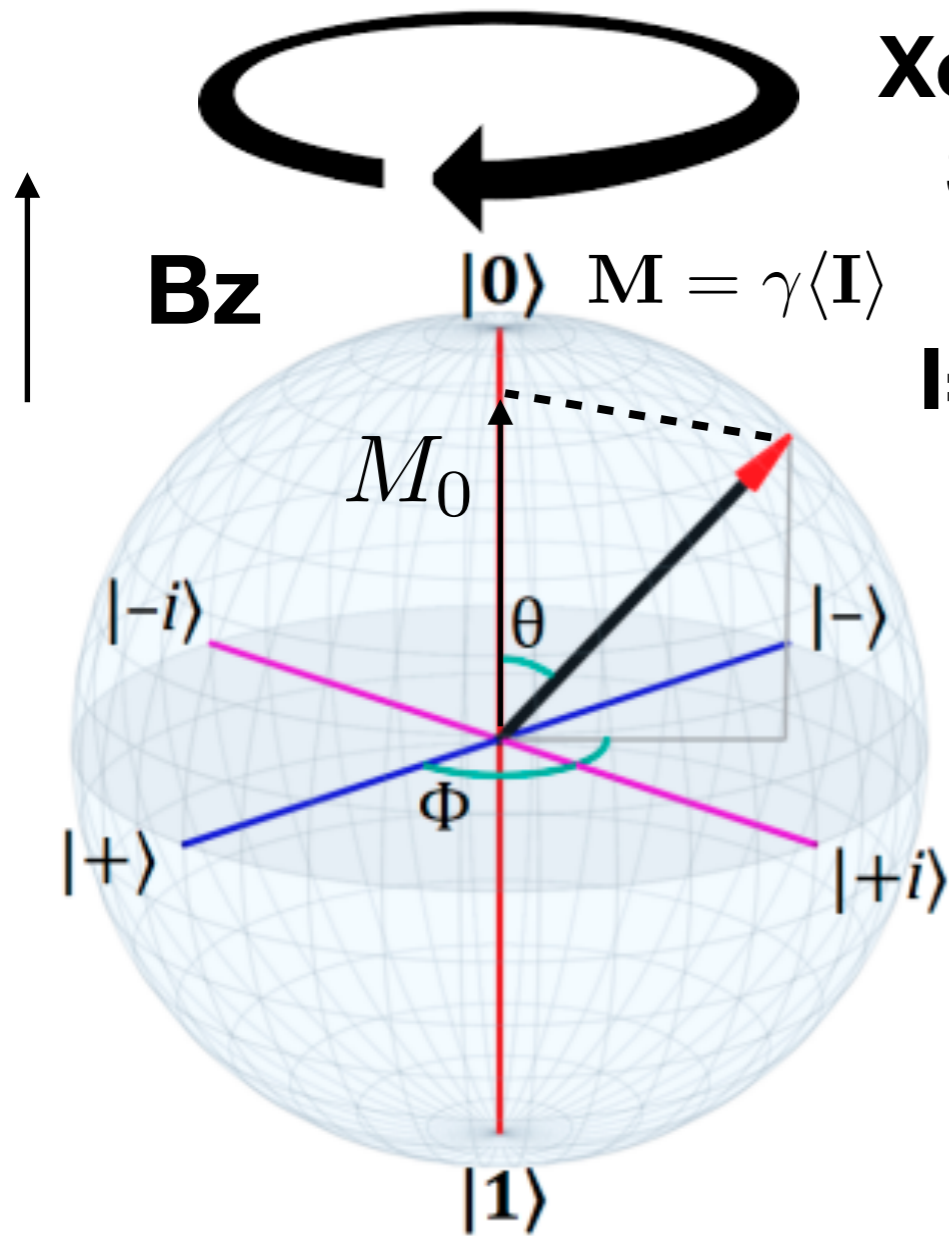


Larmor Precession

$$\omega_L = \gamma B_z$$



Obstacle to Precision Measurement: Dissipation



Xe-129

S=0

L=0

I=1/2

$|0\rangle$ $M = \gamma \langle I \rangle$

Bloch Equations:

$$\frac{d\mathbf{M}}{dt} = \gamma \mathbf{M} \times \mathbf{B}_0 + \begin{bmatrix} -M_x/T_2 \\ -M_y/T_2 \\ -(M_z - M_0)/T_1 \end{bmatrix}$$

Magnetic dipole moment \mathbf{M}

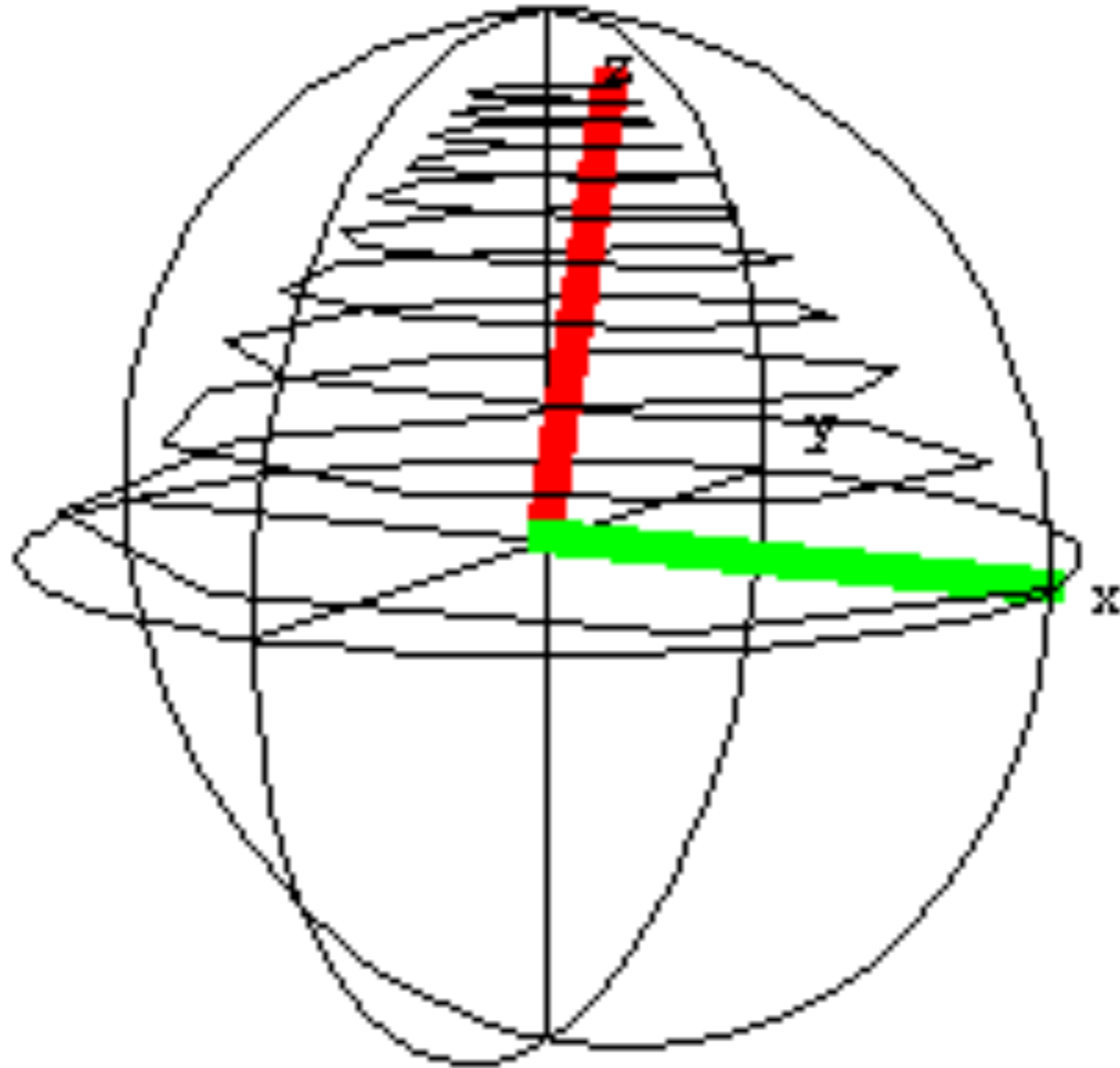
Pumping

Long time steady state:

$$M_x = M_y = 0, \quad M_z = M_0$$

Larmor Precession

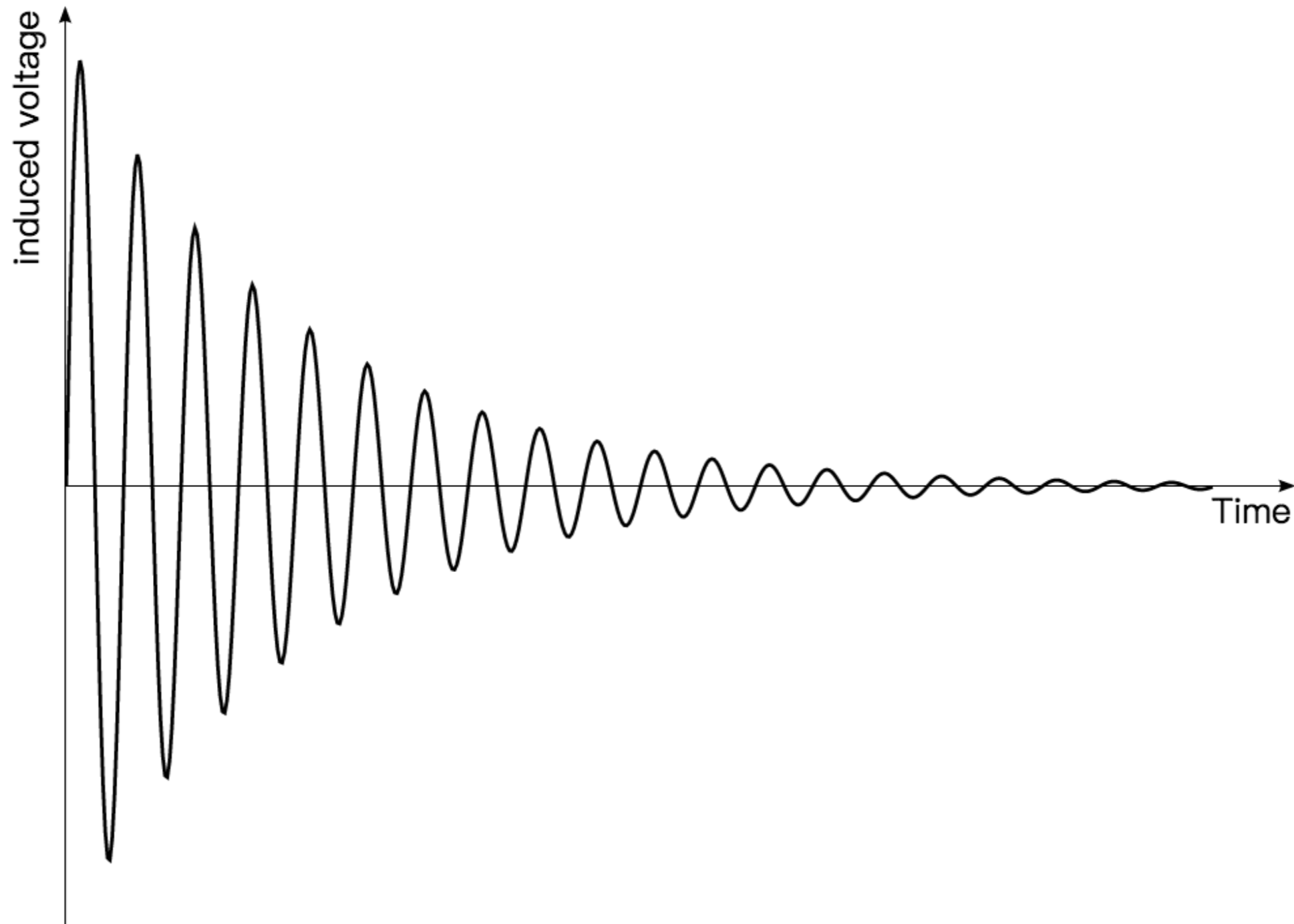
$$\omega_L = \gamma B_z$$



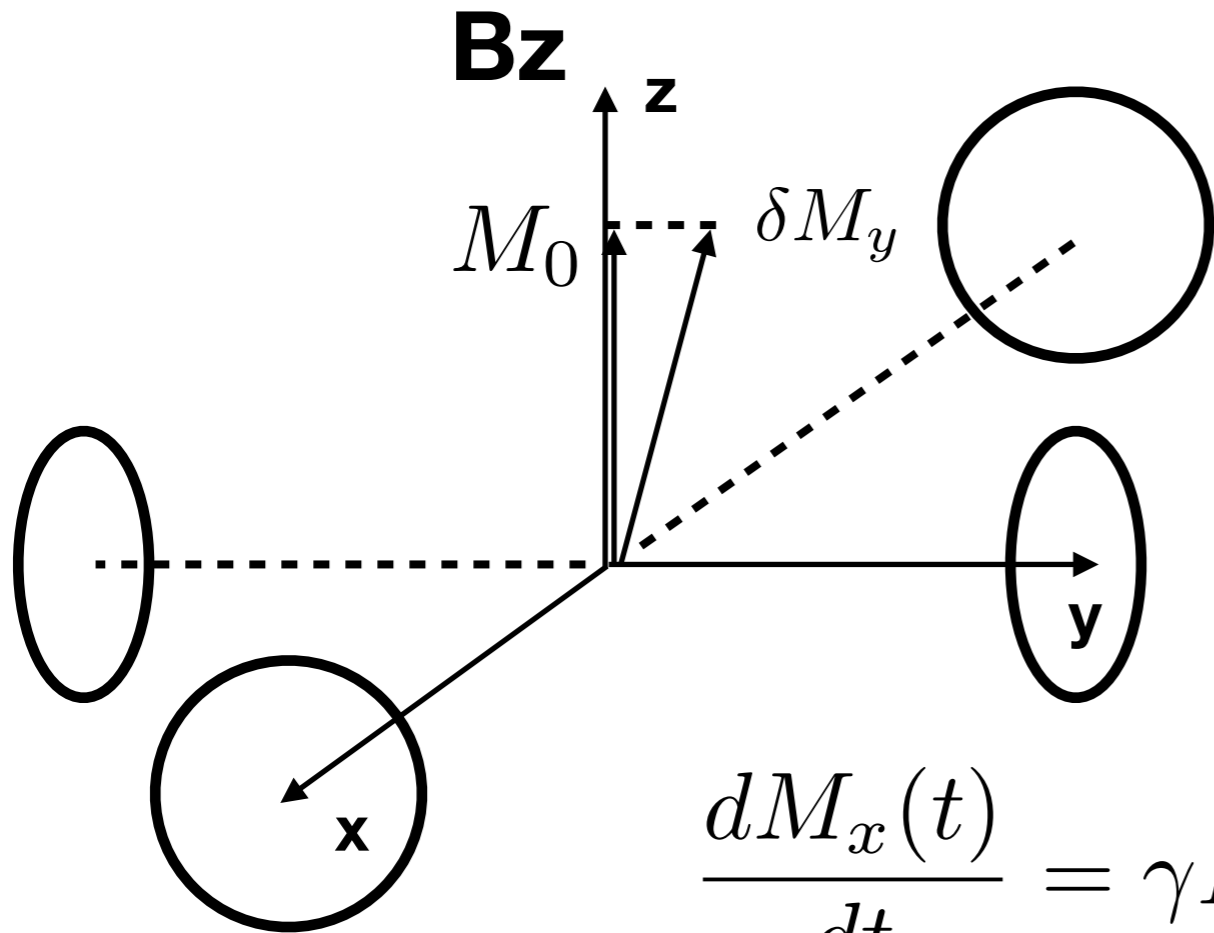
Long time steady state: $M_x = M_y = 0, M_z = M_0$

Free Induction Decay

M_x



Another Scheme : Feedback



$$B_x(t) = \alpha M_y(t) / \gamma$$

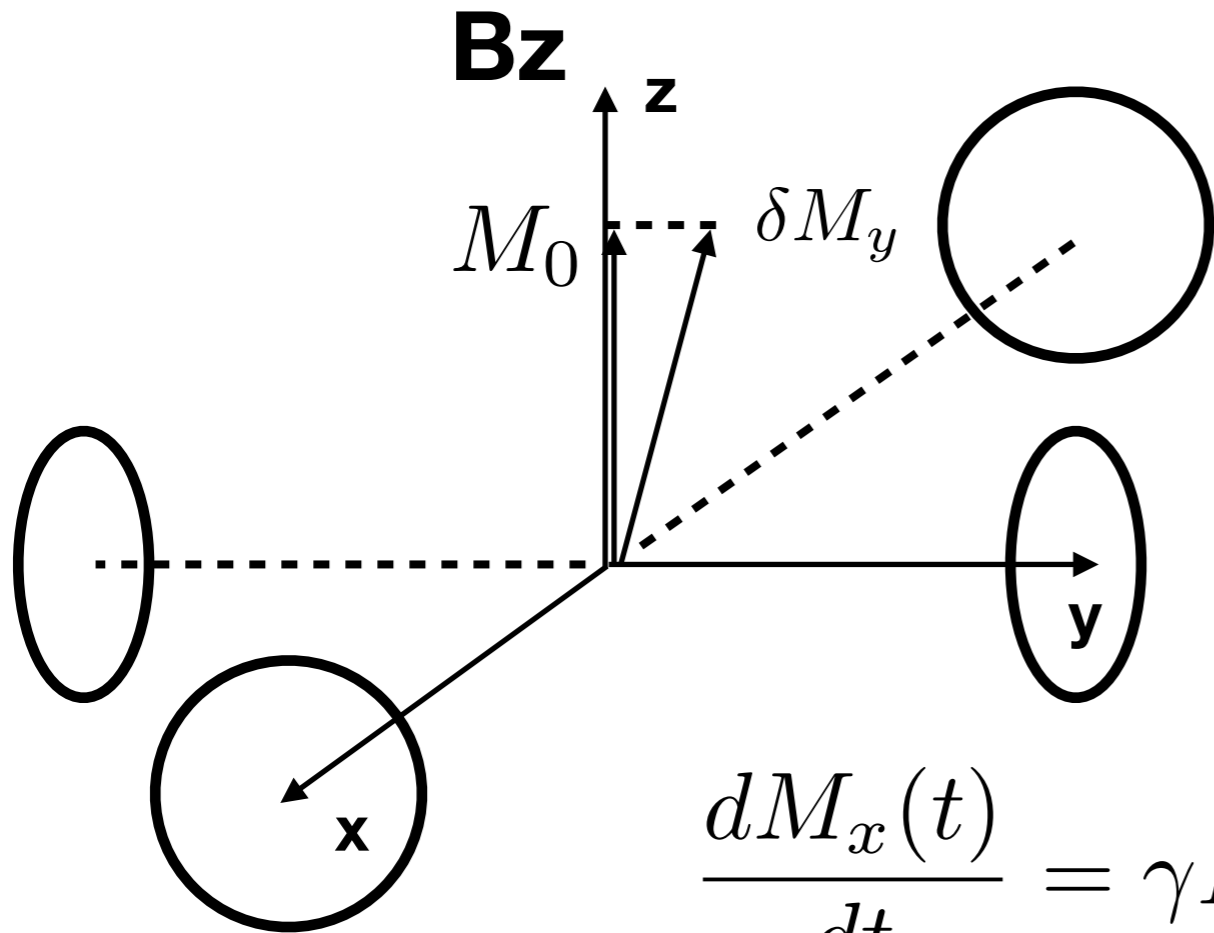
$$B_y(t) = -\alpha M_x(t) / \gamma$$

$$\frac{dM_x(t)}{dt} = \gamma B_z M_y + \alpha M_z M_x - \frac{M_x}{T_2}$$

$$\frac{dM_y(t)}{dt} = -\gamma B_z M_x + \alpha M_z M_y - \frac{M_y}{T_2}$$

$$\frac{dM_z(t)}{dt} = \alpha (M_x + M_y)^2 - \frac{M_0 - M_z}{T_1}$$

Another Scheme : Feedback



$$B_x(t) = \alpha M_y(t) / \gamma$$

$$B_y(t) = -\alpha M_x(t) / \gamma$$

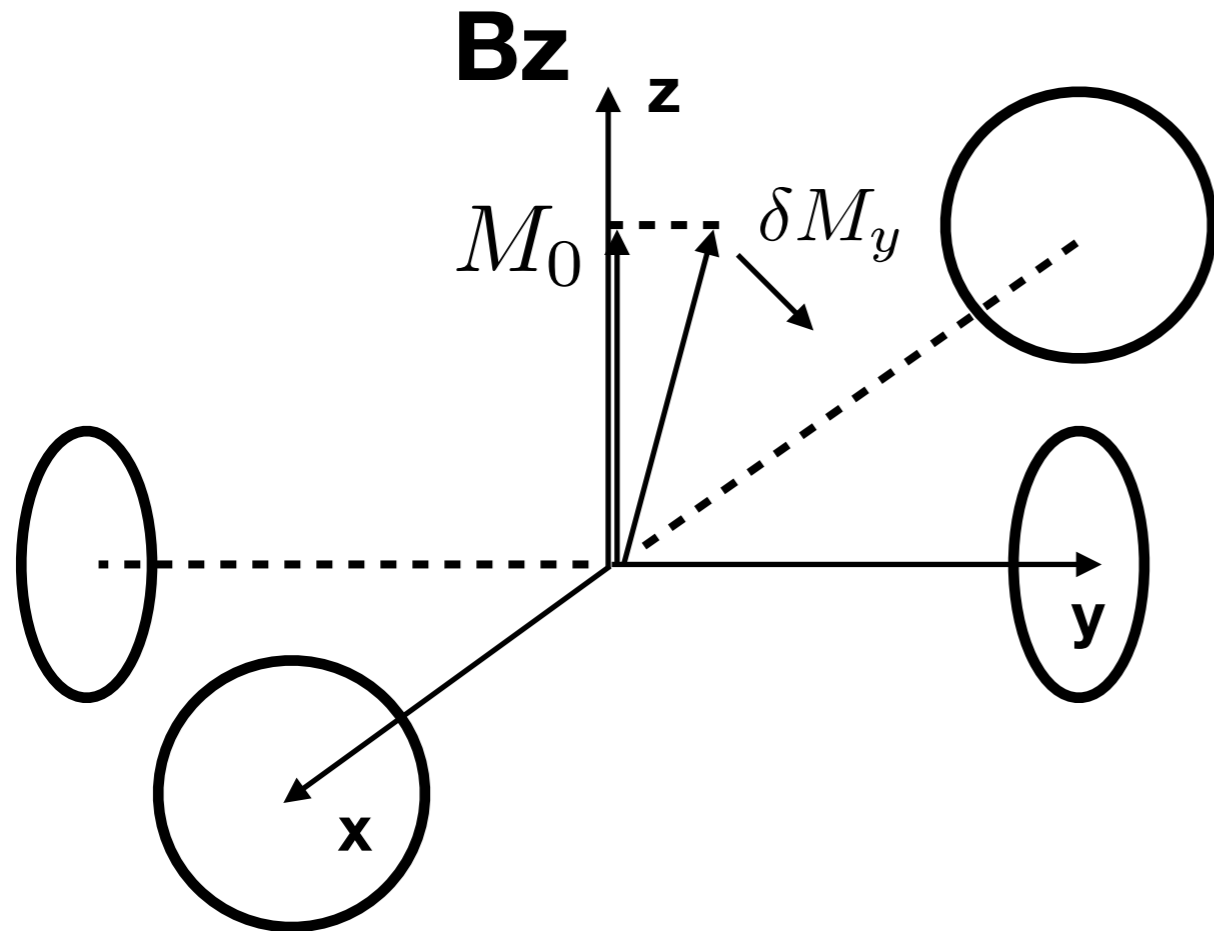
Deviate from the steady state (0,0,M_0)

$$\frac{dM_x(t)}{dt} = \gamma B_z M_y + \alpha M_z M_x - \frac{M_x}{T_2}$$

$$\frac{dM_y(t)}{dt} = -\gamma B_z M_x + \alpha M_z M_y - \frac{M_y}{T_2}$$

$$\frac{dM_z(t)}{dt} = \alpha (M_x + M_y)^2 - \frac{M_0 - M_z}{T_1}$$

Another Scheme : Feedback



$$B_x(t) = \alpha M_y(t) / \gamma$$

$$B_y(t) = -\alpha M_x(t) / \gamma$$

Deviate from the steady state (0,0,M_0)

If

$$\frac{d\delta M_y}{dt} = (\alpha M_0 - 1/T_2)\delta M_y$$

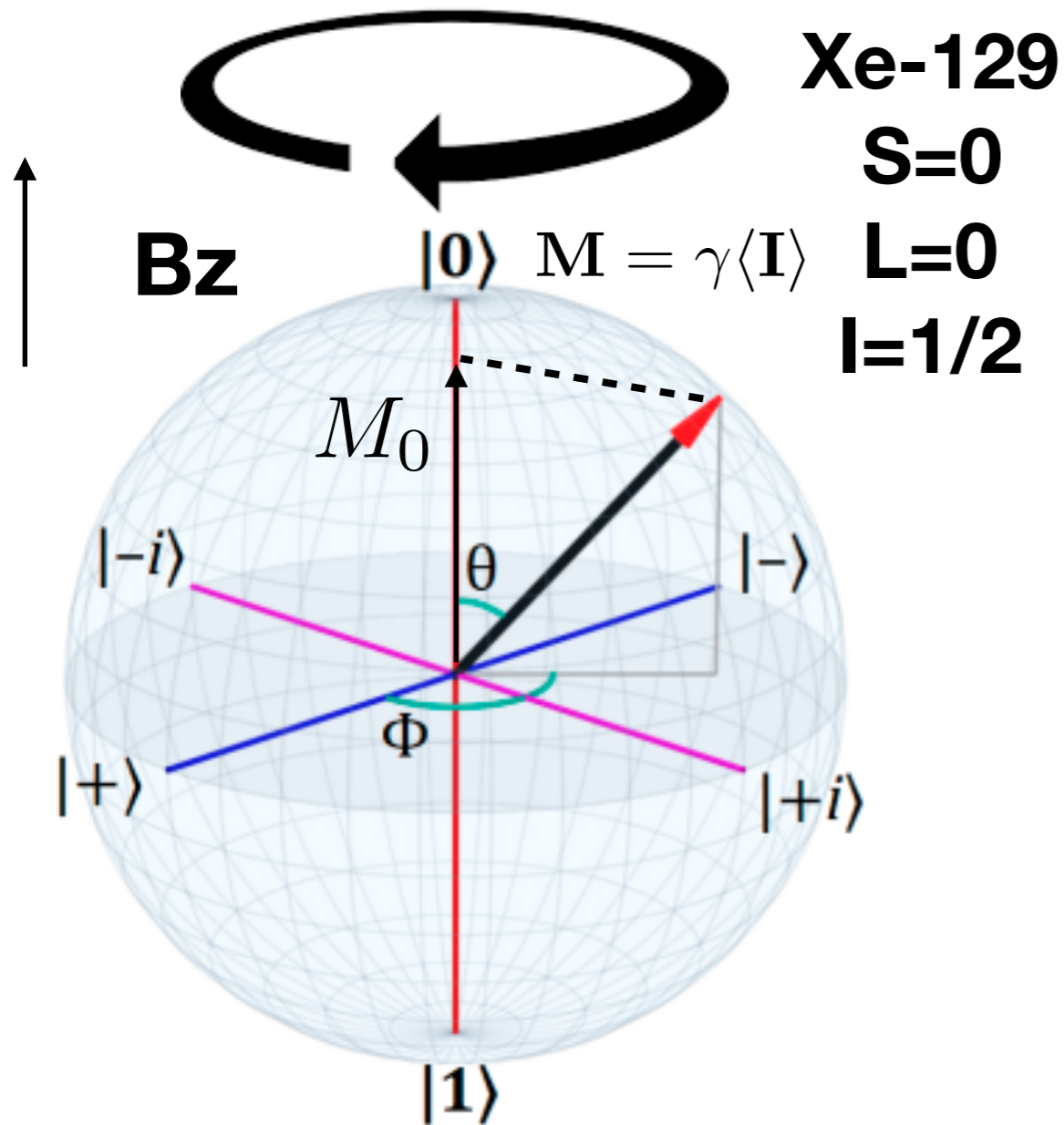
$$\alpha M_0 - 1/T_2 > 0 \quad \textbf{unstable}$$

$$\frac{dM_x(t)}{dt} = \gamma B_z M_y + \alpha M_z M_x - \frac{M_x}{T_2}$$

$$\frac{dM_y(t)}{dt} = -\gamma B_z M_x + \alpha M_z M_y - \frac{M_y}{T_2}$$

$$\frac{dM_z(t)}{dt} = \alpha (M_x + M_y)^2 - \frac{M_0 - M_z}{T_1}$$

Steady Precession - Limit Cycle



Bloch Equations:

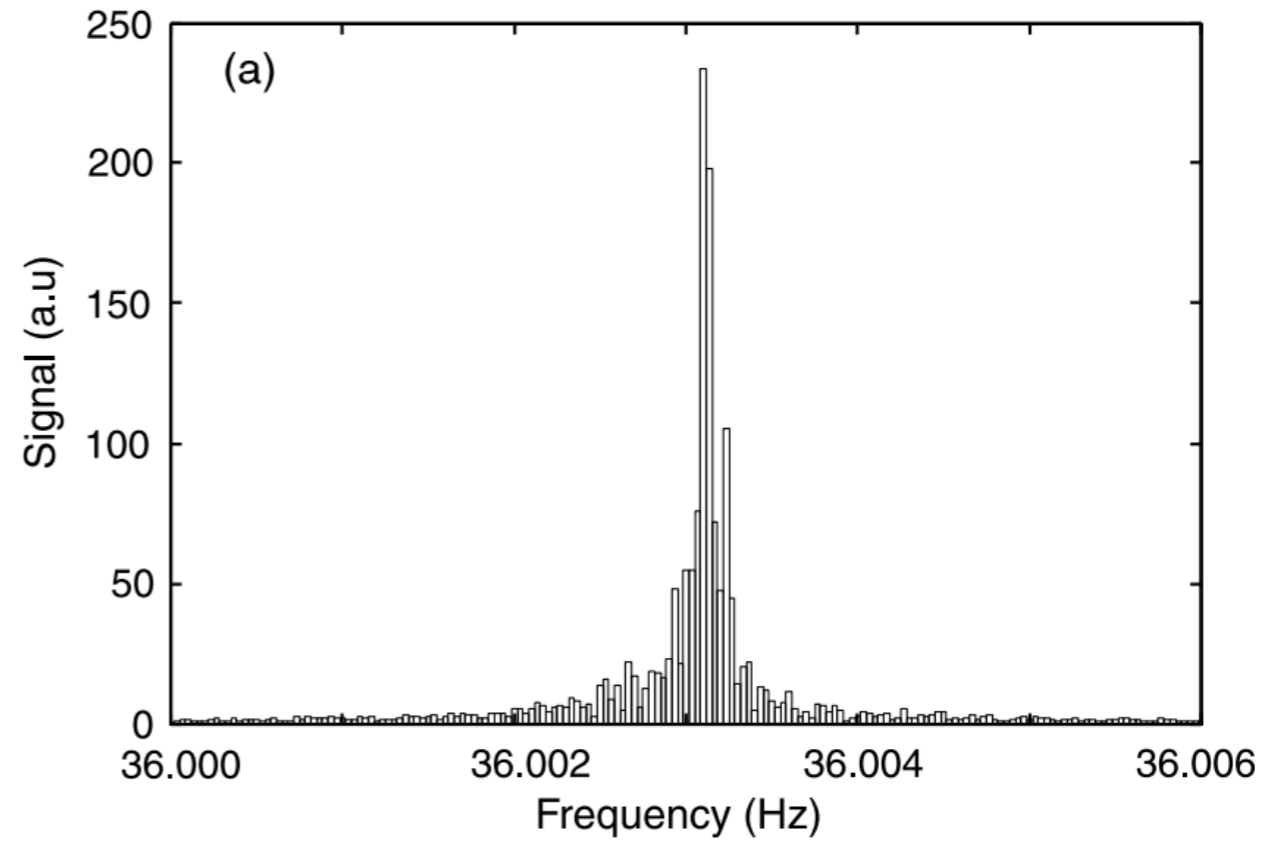
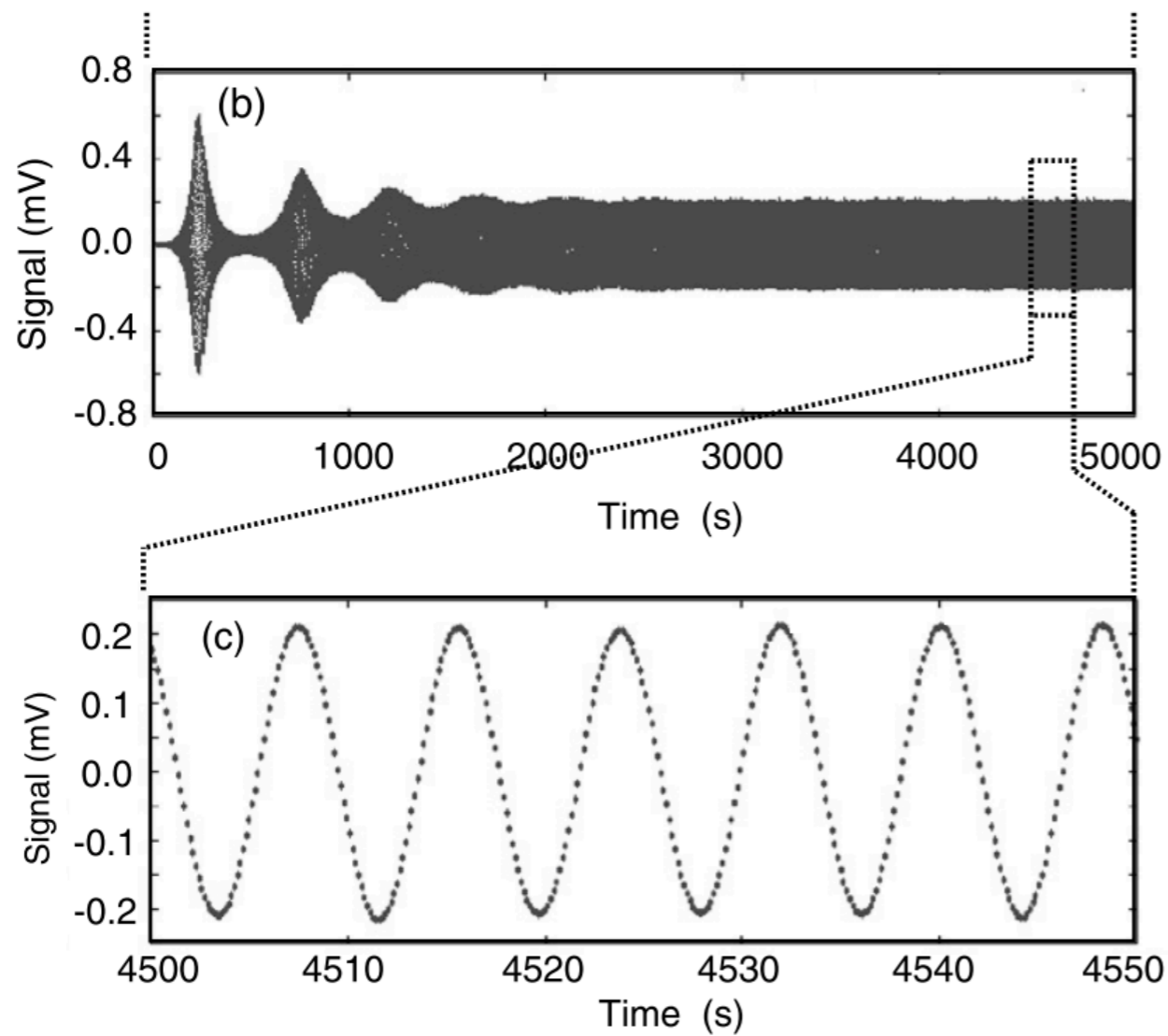
$$\frac{dM_x(t)}{dt} = \gamma B_z M_y + \alpha M_z M_x - \frac{M_x}{T_2}$$

$$\frac{dM_y(t)}{dt} = -\gamma B_z M_x + \alpha M_z M_y - \frac{M_y}{T_2}$$

$$\frac{dM_z(t)}{dt} = \alpha (M_x + M_y)^2 - \frac{M_0 - M_z}{T_1}$$

Larmor Precession

$$\omega_L = \gamma B_z$$



$$B_0 = 3.04 \mu T, T_m = 3 \times 10^4 s$$

$$\Delta\nu_{FT} = 50 \mu Hz$$

Fig. 3. (a) Spin maser oscillation signal observed in a time span of 24 hours. (b) Transient pattern in the initial spin maser oscillation. (c) Steady state oscillation after the transient settled. The signals shown in the ordinates represent the beat between the spin detection signal and a 36.12 Hz fixed frequency reference signal for a lock-in amplifier.

A. Yoshimi, et al, Physics Letters A 376, 1924 (2012)

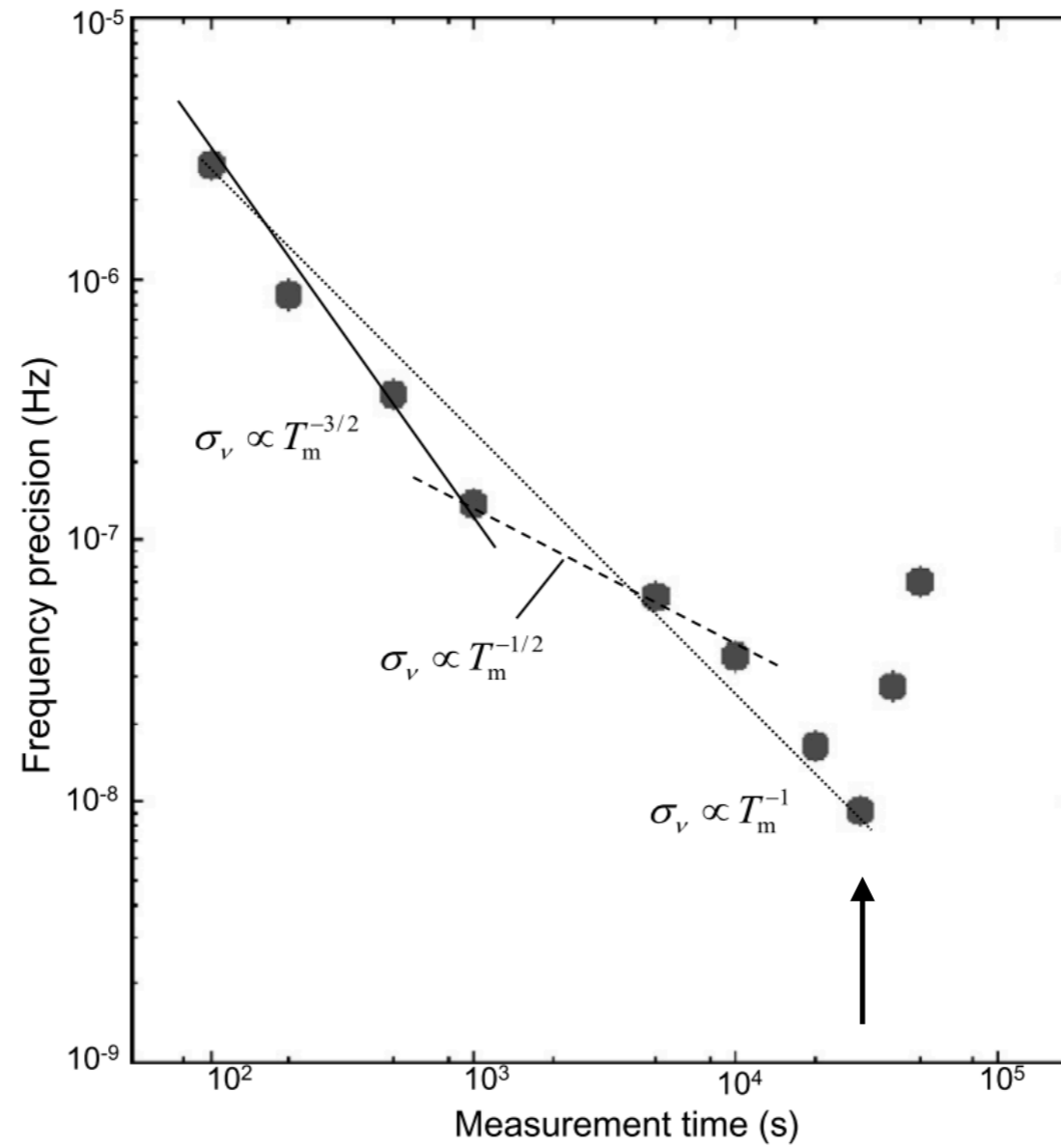


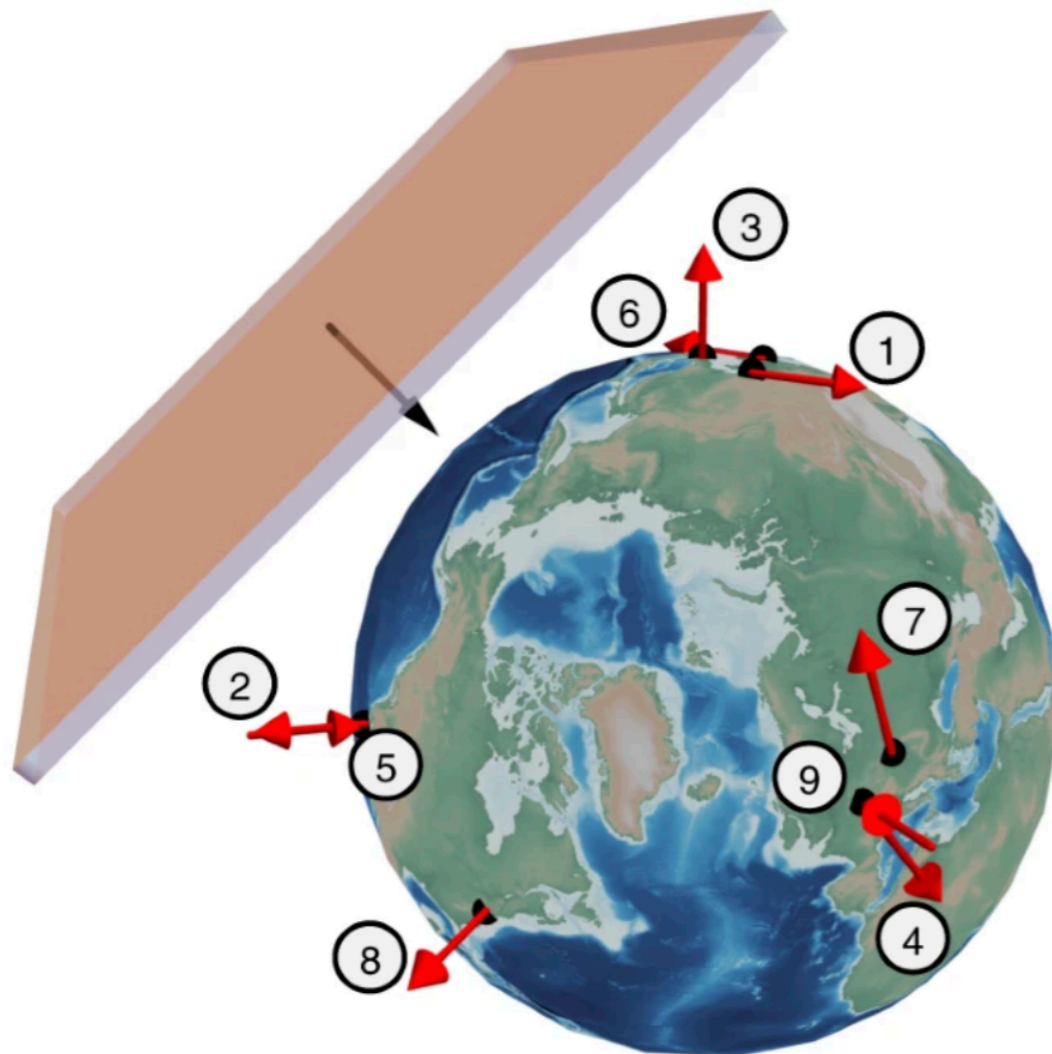
Fig. 7. Frequency precision of the spin oscillation. The abscissa represents the standard deviation of the frequency ν determined by fitting a function $\phi(t) = 2\pi\nu t + \phi_0$ to the observed precession phases ϕ from $t = 0$ to $t = T_m$. Solid, dotted and dashed lines are the presentation of three cases with power laws $\sigma_\nu \propto T_m^{-3/2}$, $\sigma_\nu \propto T_m^{-1}$, and $\sigma_\nu \propto T_m^{-1/2}$ respectively.

A. Yoshimi, et al, Physics Letters A 376, 1924 (2012)

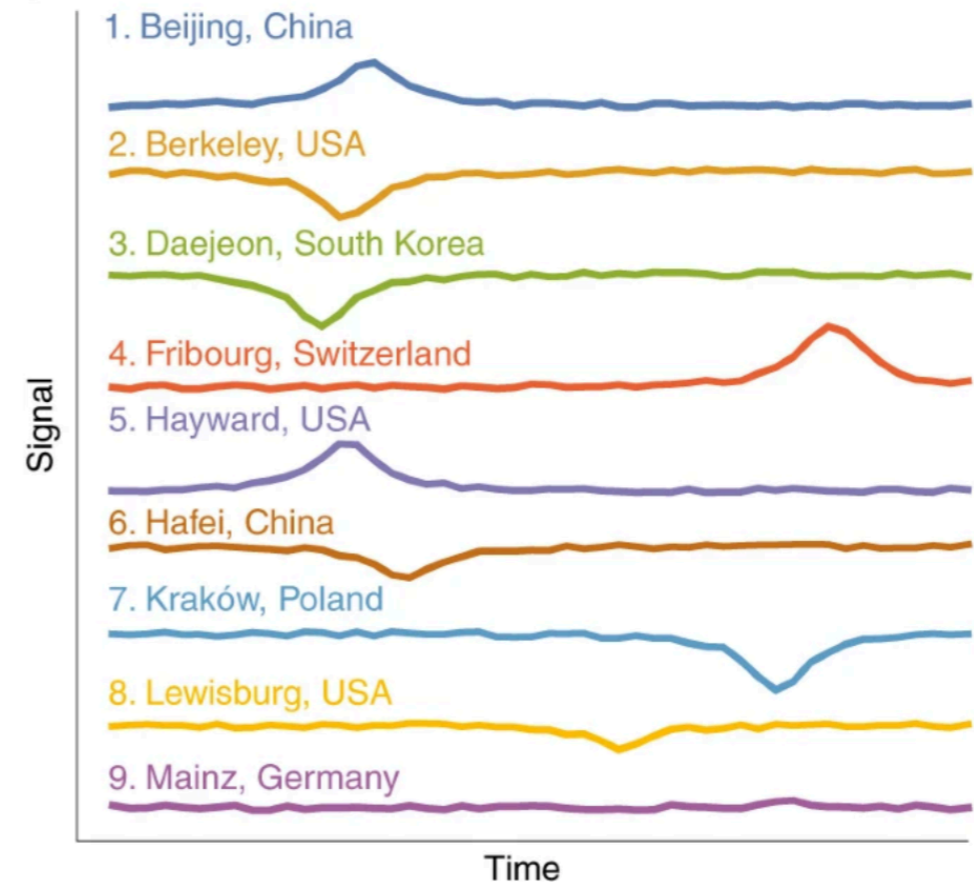
Co-magnetometers

Fig. 1: Visualization of an ALP domain-wall crossing.

a



b



a, Image showing the Earth together with the position and sensitive axes of the GNOME magnetometers during Science Run 2. Position and sensitive axes are shown as red arrows. The crossing direction of the domain wall is represented as a black arrow (Extended Data Table 1). b, Simulation of the signals expected to be observed from a domain-wall crossing at the different magnetometers comprising the network.

**Axion-like particles
for dark matter**

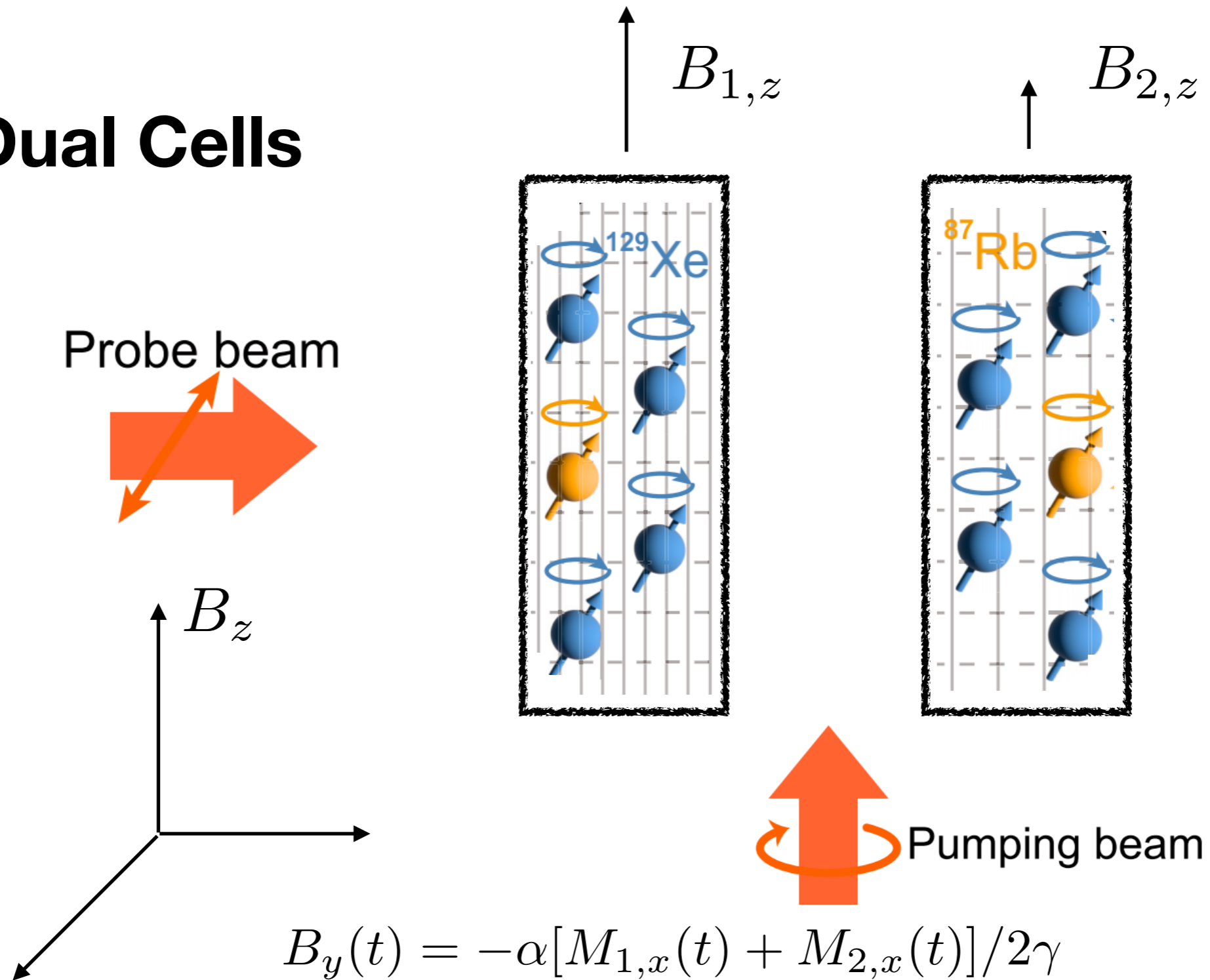
$$H_{\text{lin}} = -(\hbar c)^{3/2} \frac{\xi}{f_{\text{SB}}} \frac{\mathbf{S}}{\|\mathbf{S}\|} \cdot \nabla a(\mathbf{r}, t), \quad H_Z = -\gamma \mathbf{S} \cdot \mathbf{B},$$

The global network of optical magnetometers for exotic (GNOME) physics searches

S. Afach, *et. al*, Nature Physics 17, 1396–1401 (2021)

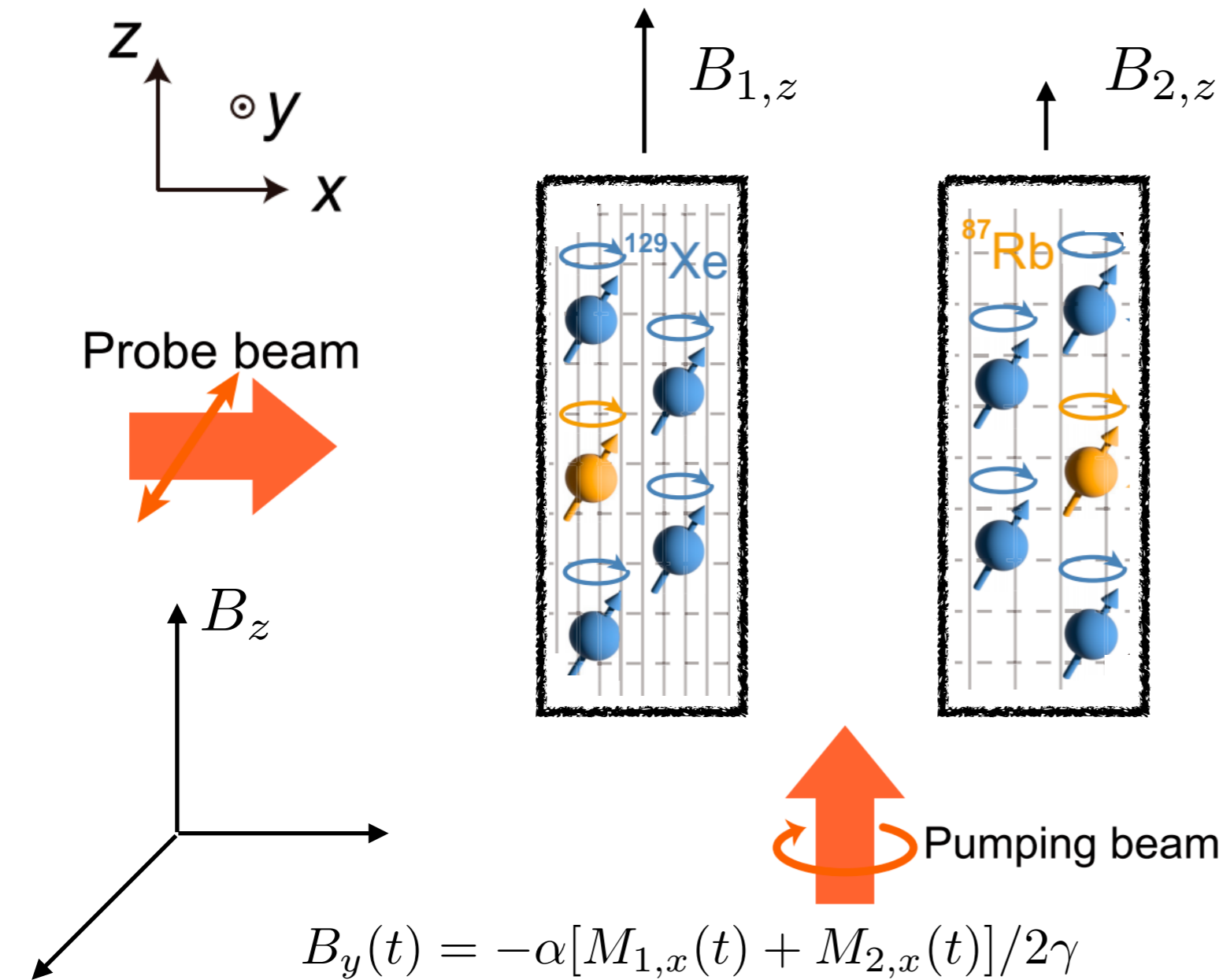
A New Coupled Set-up

Dual Cells



$$B_x(t) = \alpha[M_{1,y}(t) + M_{2,y}(t)]/2\gamma$$

Bloch Equations



$$\omega_{1,L} = \gamma B_{1,z}$$

$$\omega_{2,L} = \gamma B_{2,z}$$

$$\omega_{1,L} = \omega_c + \epsilon/2$$

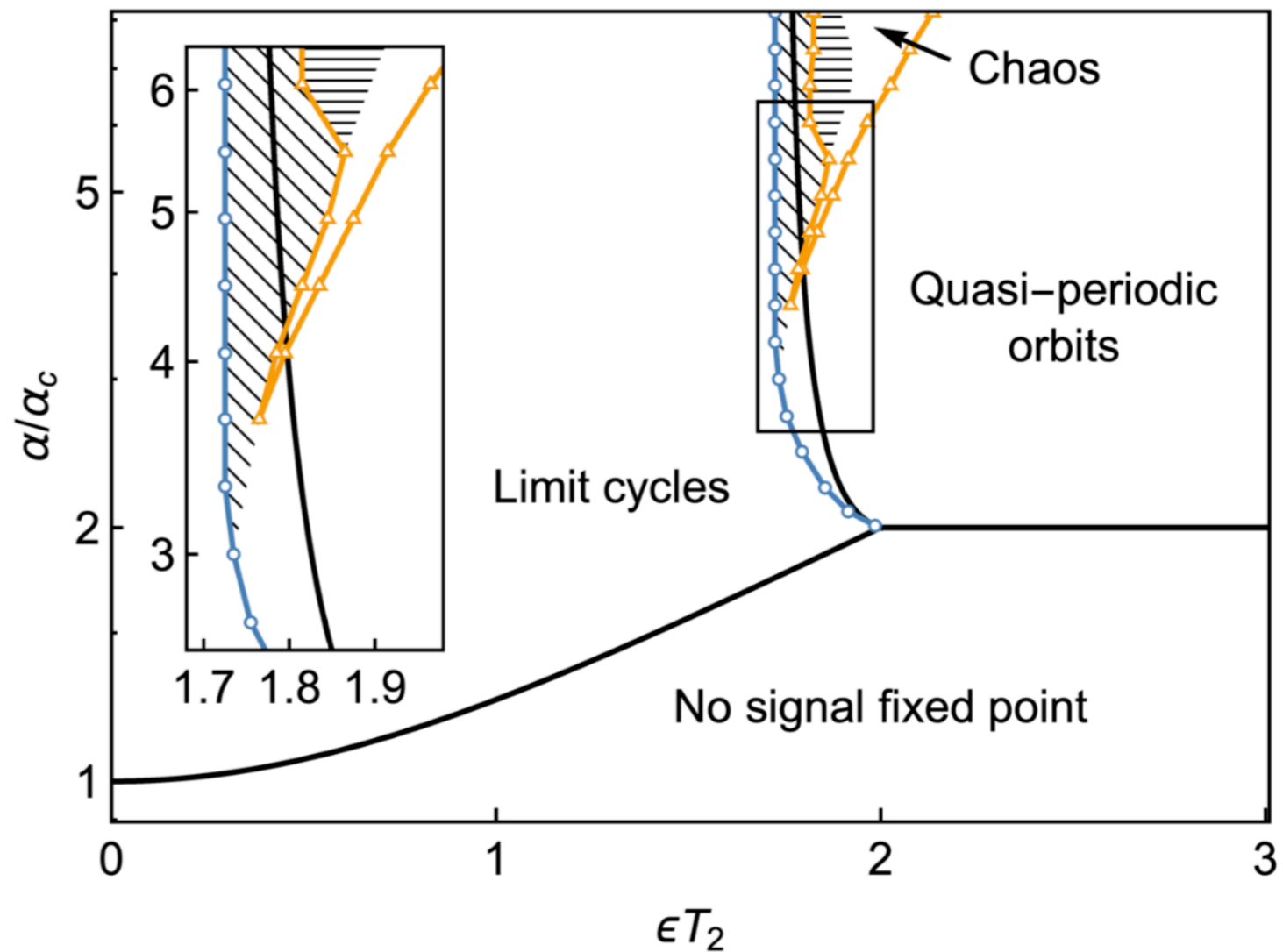
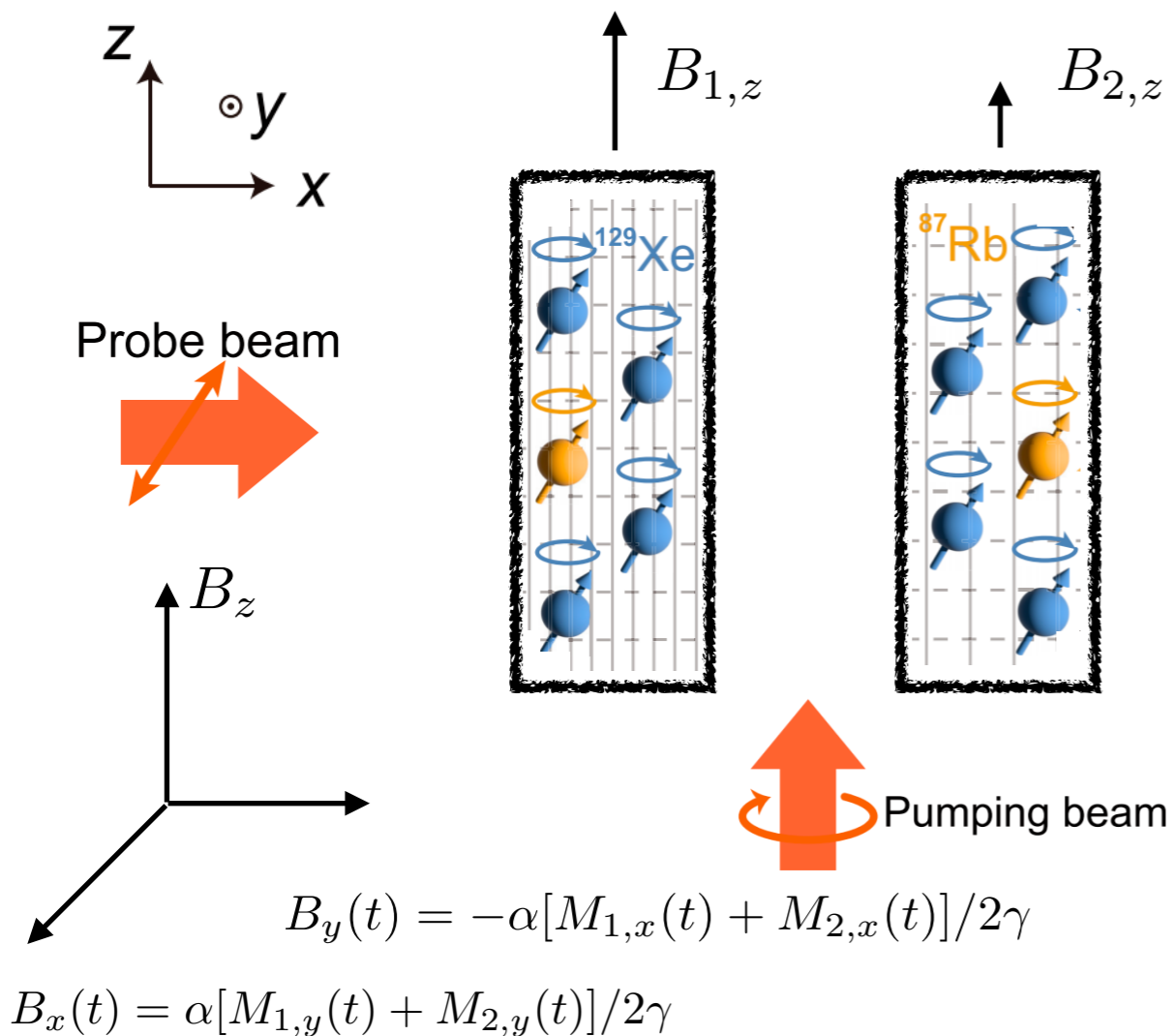
$$\omega_{2,L} = \omega_c - \epsilon/2$$

$$B_y(t) = -\alpha[M_{1,x}(t) + M_{2,x}(t)]/2\gamma$$

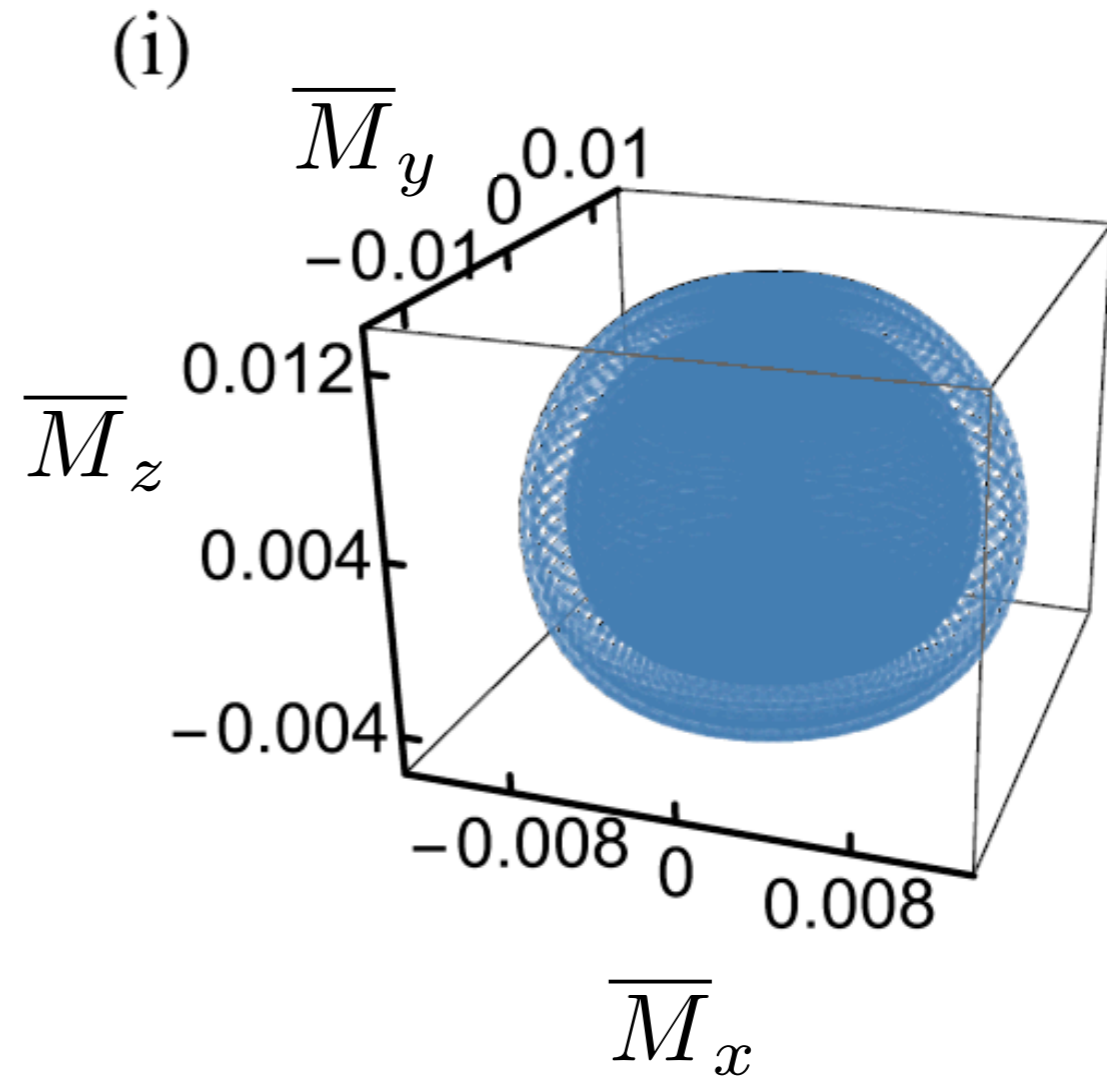
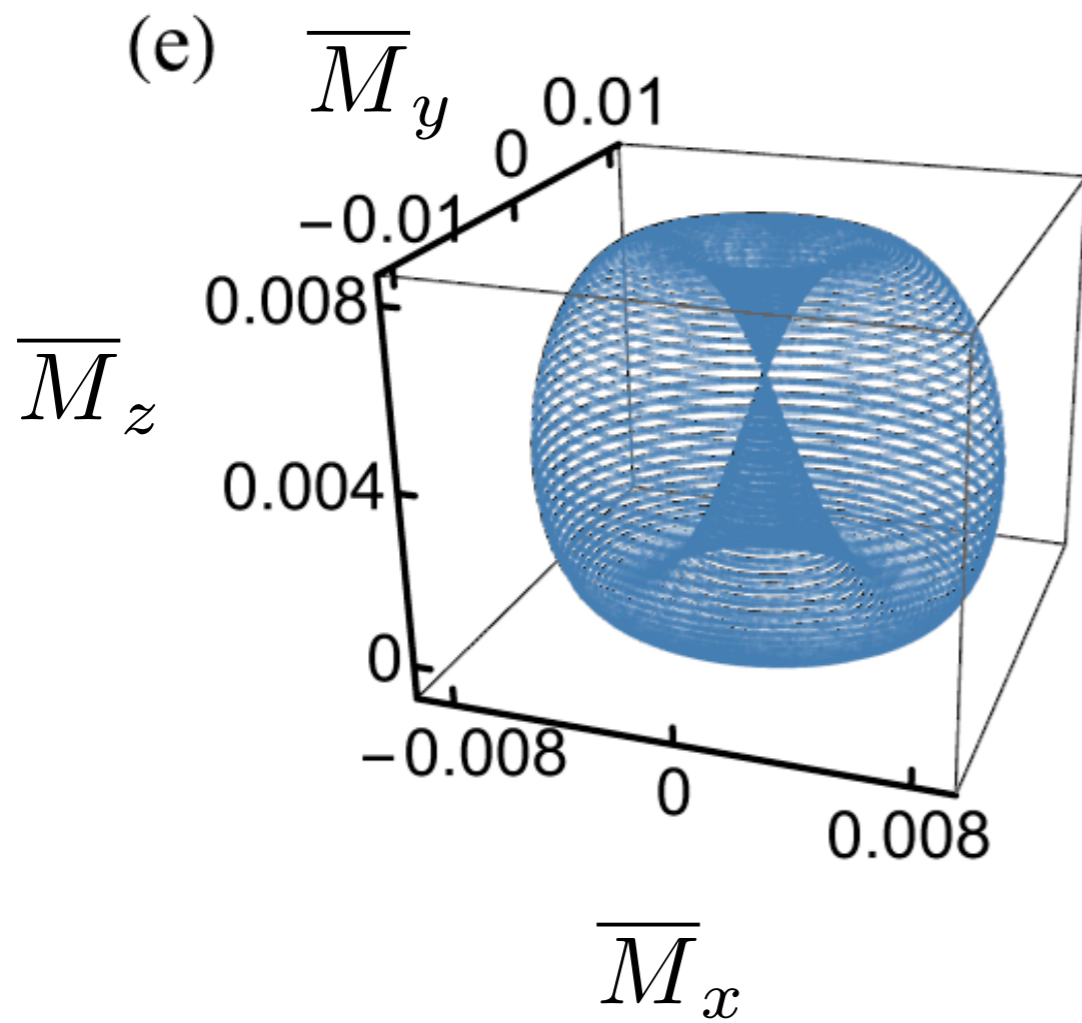
$$B_x(t) = \alpha[M_{1,y}(t) + M_{2,y}(t)]/2\gamma$$

$$\frac{d\mathbf{M}_j}{dt} = \gamma \mathbf{M}_j \times \mathbf{B}_j + \begin{bmatrix} -M_{j,x}/T_2 \\ -M_{j,y}/T_2 \\ -(M_{j,z} - M_0)/T_1 \end{bmatrix}$$

Stability Diagram

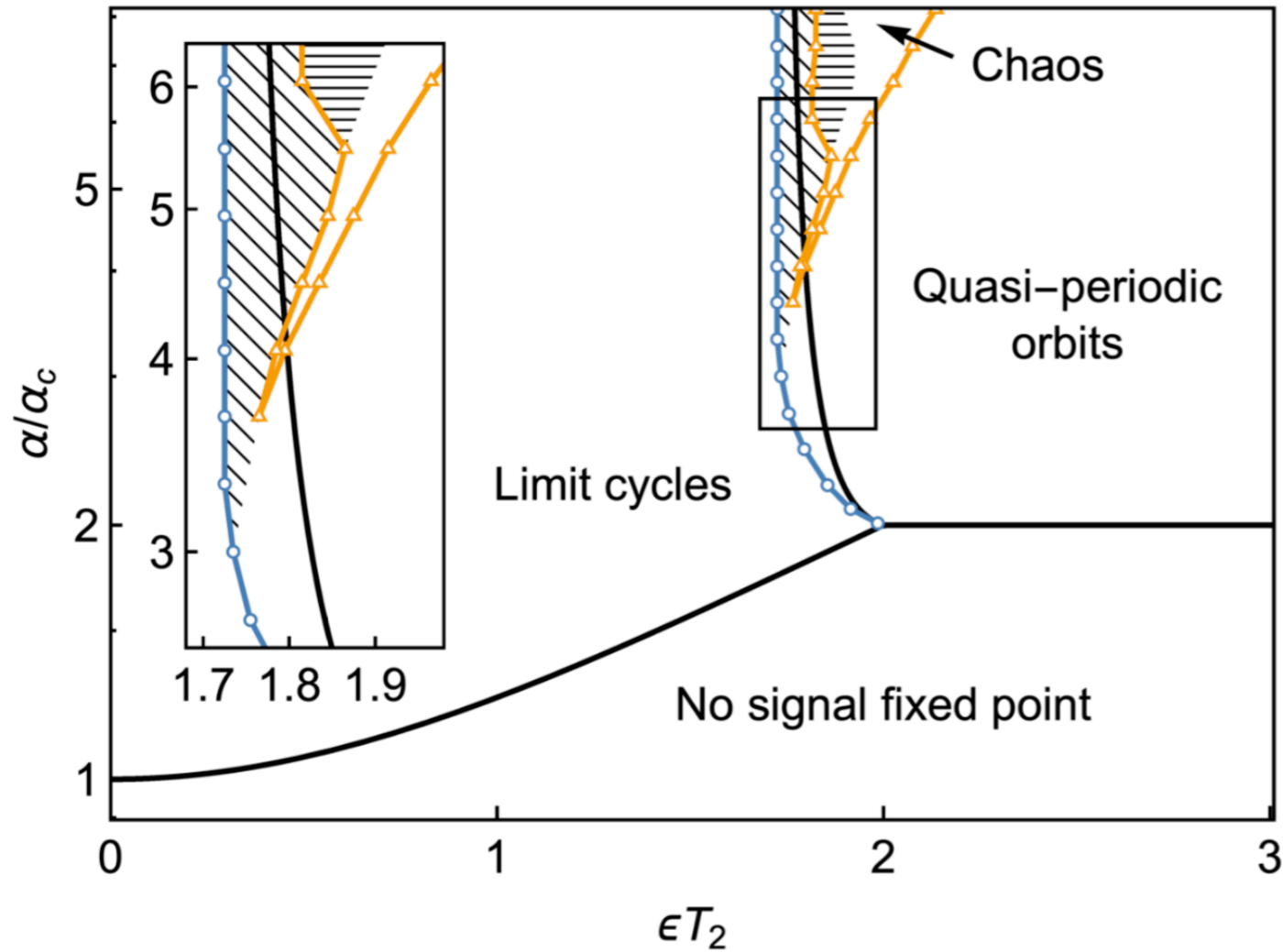


Spot by Sight



Which is which?

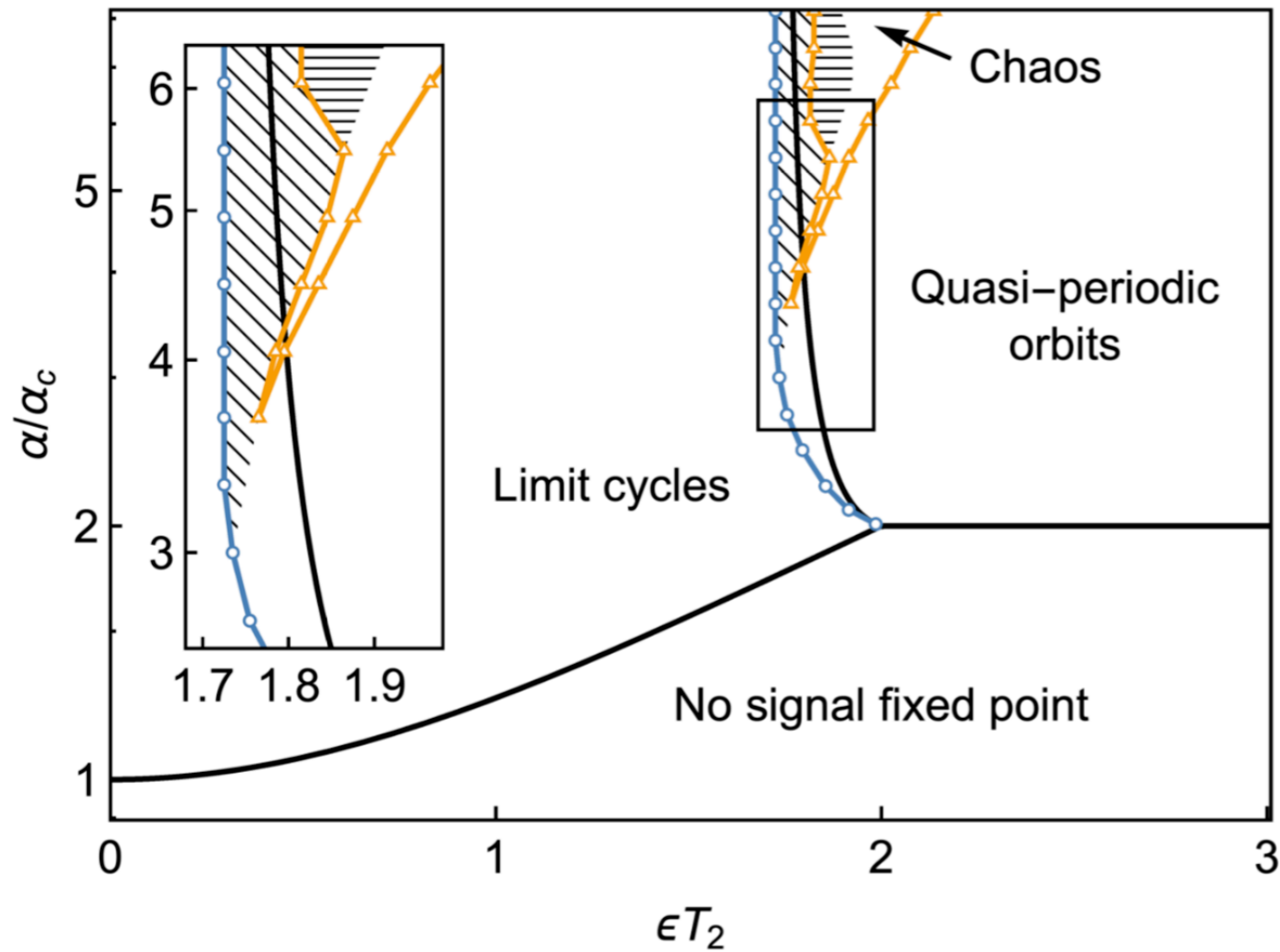
Dimension Reduction



$$M_{1,x}^2 + M_{1,y}^2 = M_{2,x}^2 + M_{2,y}^2$$

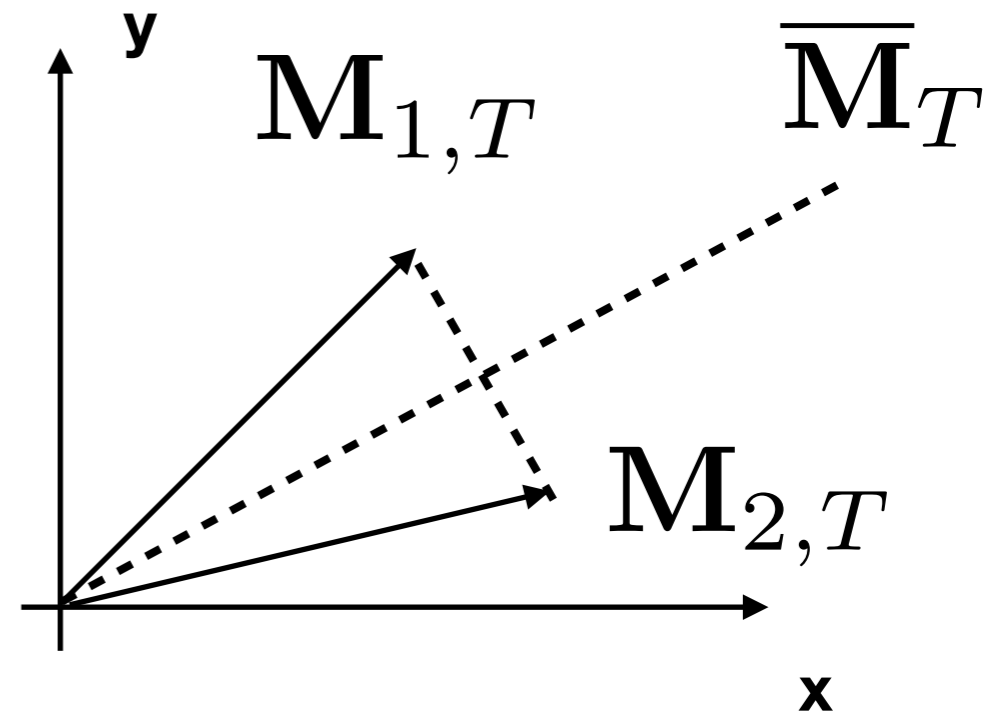
$$M_{1,z} = M_{2,z}$$

Dimension Reduction

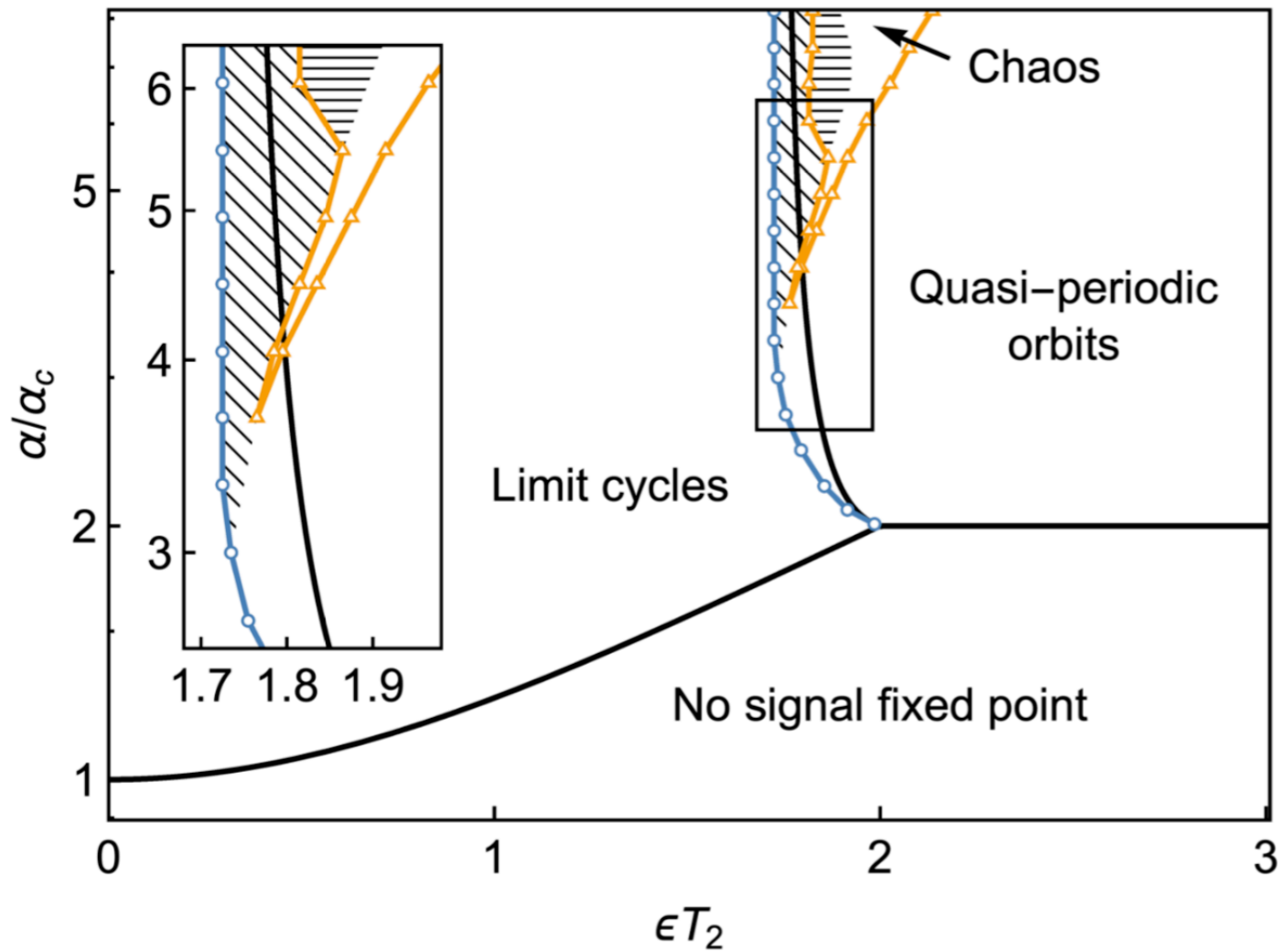


$$M_{1,z} = M_{2,z}$$

$$M_{1,x}^2 + M_{1,y}^2 = M_{2,x}^2 + M_{2,y}^2$$

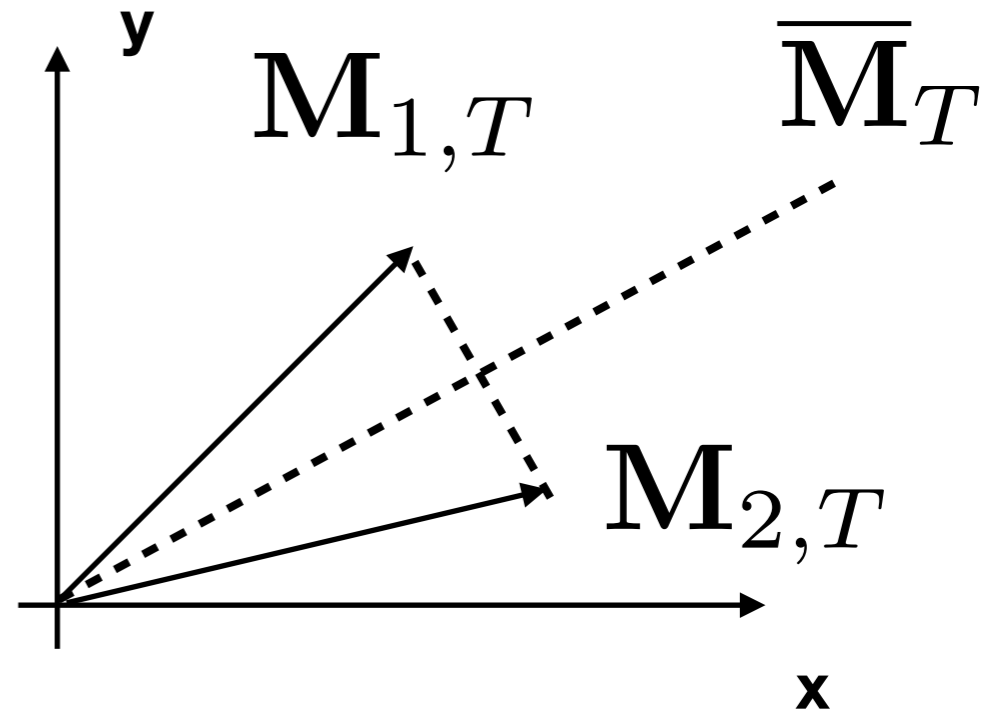


Dimension Reduction



$$M_{1,z} = M_{2,z}$$

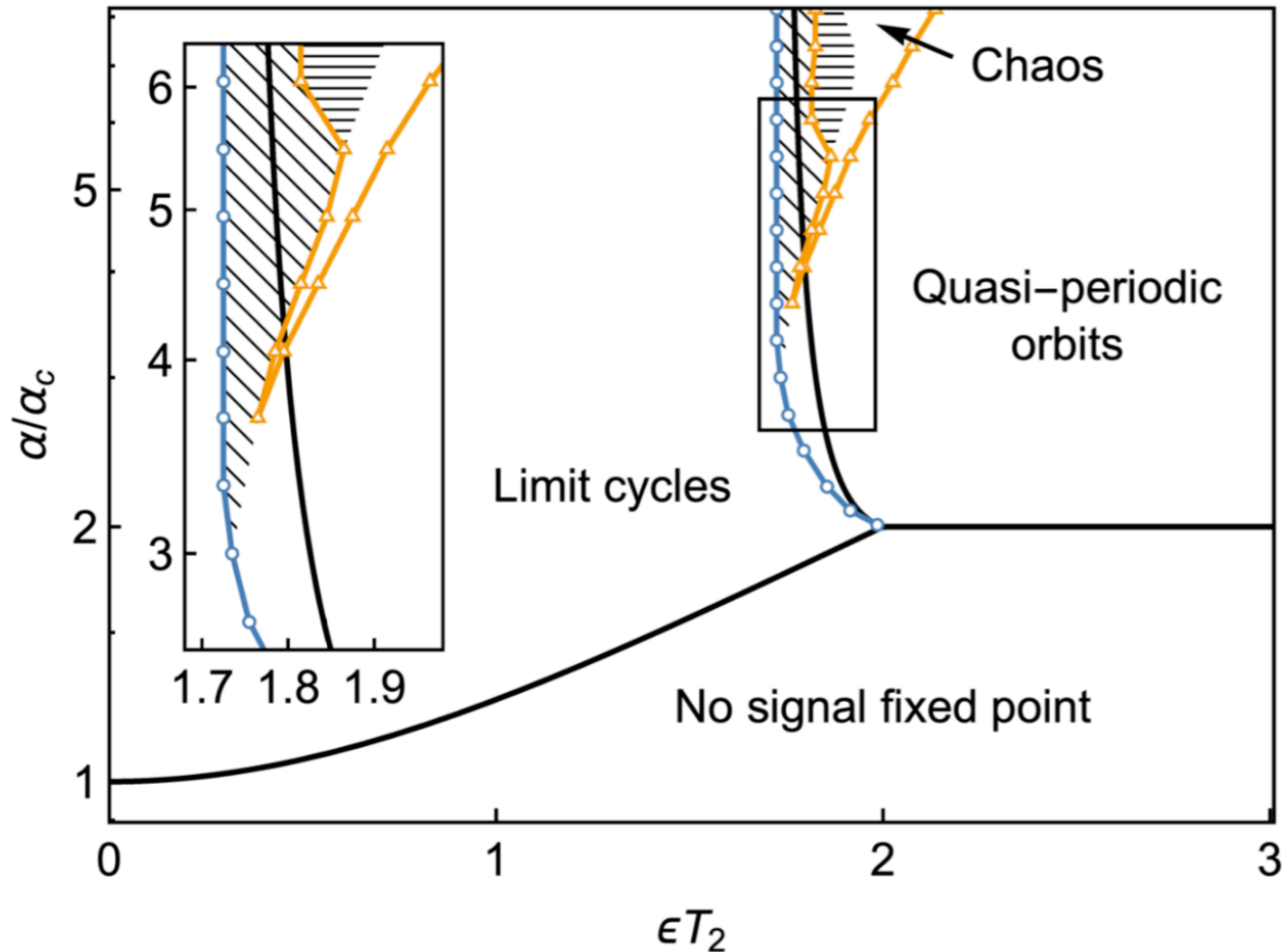
$$M_{1,x}^2 + M_{1,y}^2 = M_{2,x}^2 + M_{2,y}^2$$



$$\overline{M}_T \equiv \overline{M}_x + i\overline{M}_y \equiv Ae^{i\theta}/2$$

$$\Delta M_T \equiv M_{1,T} - M_{2,T} \equiv Be^{i(\theta+\pi/2)}$$

Dimension Reduction



$$\begin{aligned} \frac{dA}{dt} &= \alpha \bar{M}_z A + \epsilon B/2 - A/T_2 \\ \frac{dB}{dt} &= -\epsilon A/2 - B/T_2 \\ \frac{d\bar{M}_z}{dt} &= -\alpha A^2/4 - (\bar{M}_z - M_0)/T_1 \\ \frac{d\theta}{dt} &= -\omega_c \end{aligned}$$

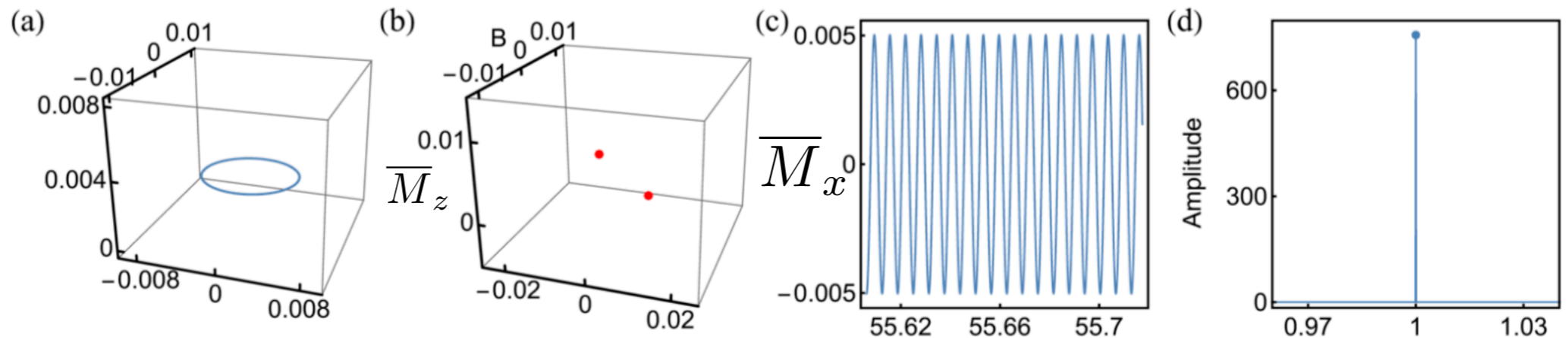
$$\bar{M}_T \equiv \bar{M}_x + i\bar{M}_y \equiv Ae^{i\theta}/2$$

$$\Delta M_T \equiv M_{1,T} - M_{2,T} \equiv Be^{i(\theta + \pi/2)}$$

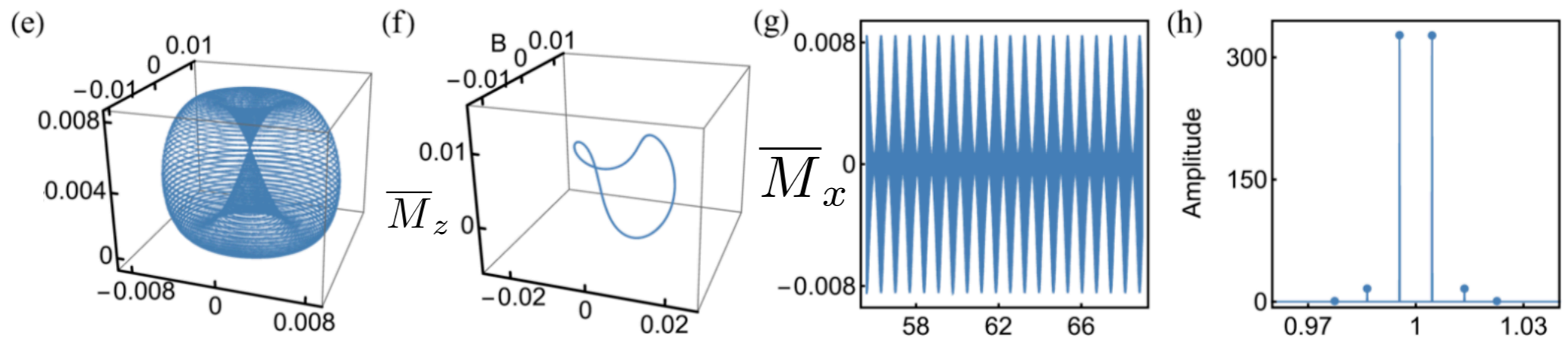
6 -> 3

Phase Portraits

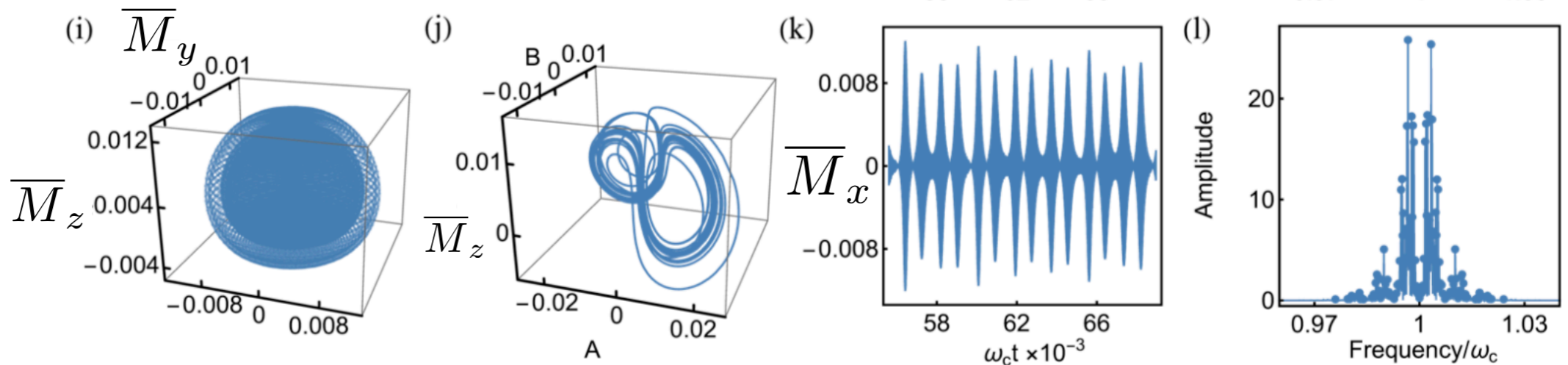
Limit Cycles



Quasi-periodic
Orbits



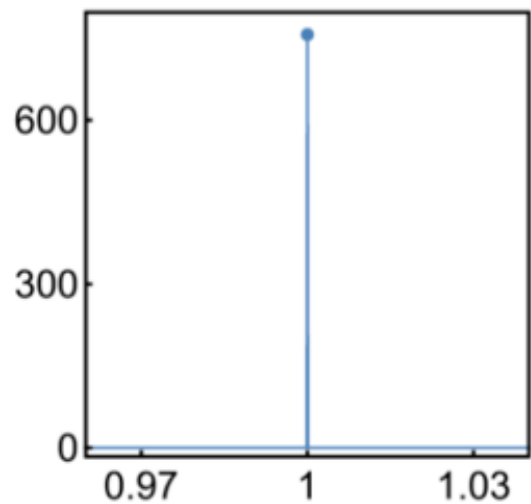
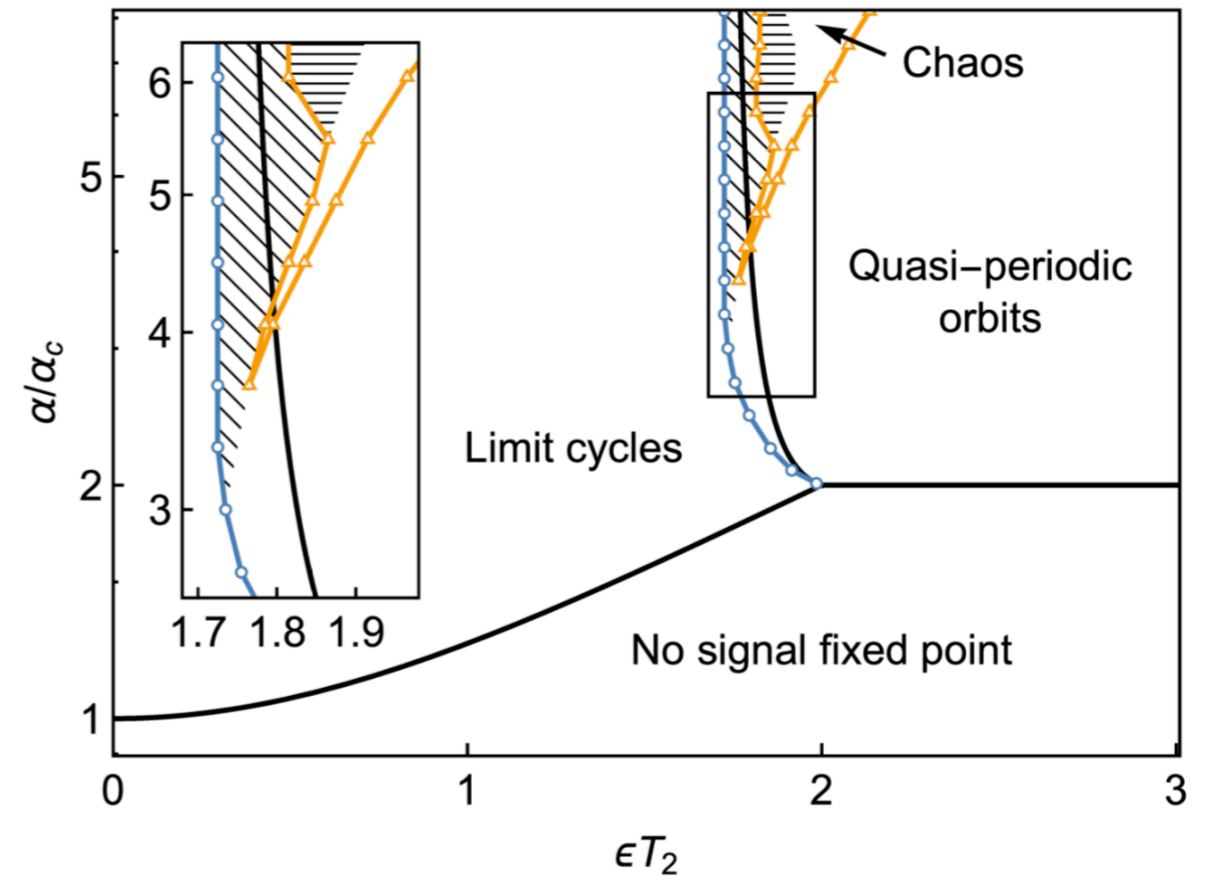
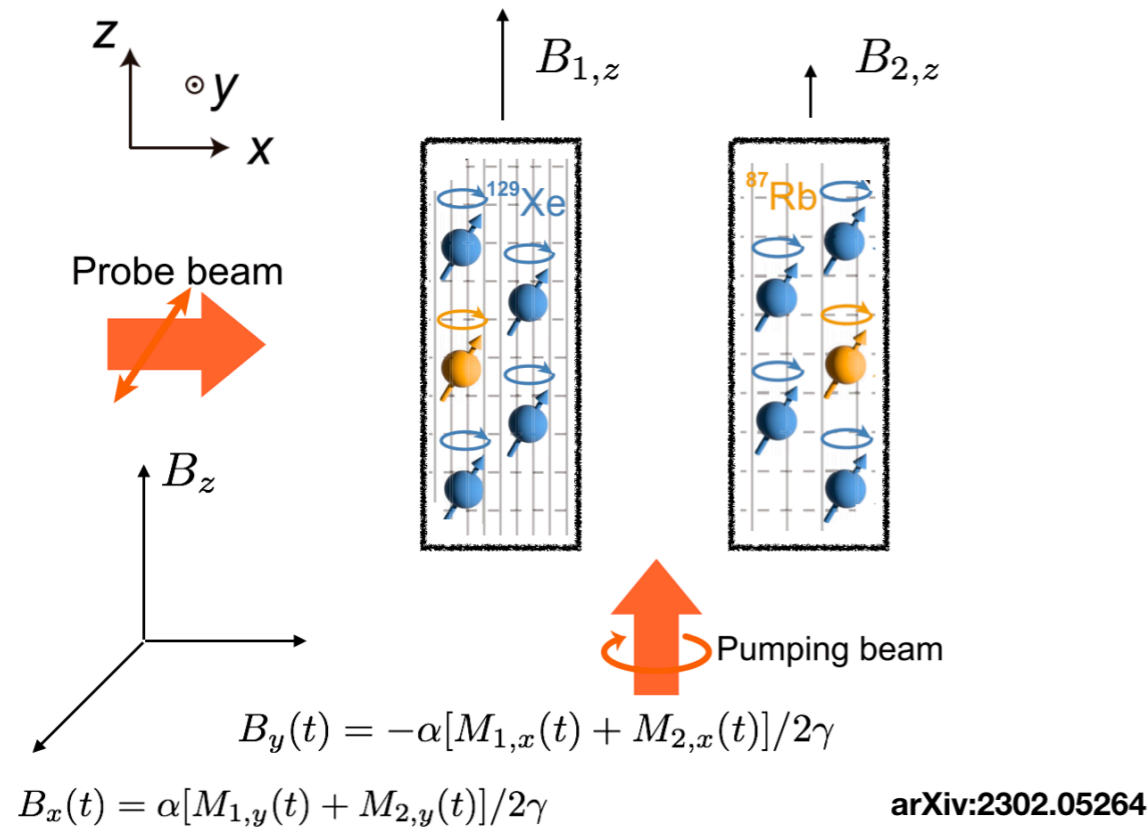
Chaos



\overline{M}_x

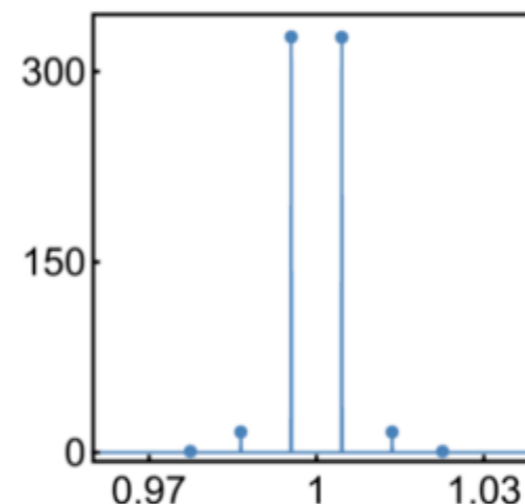
Summary

A New Coupled Set-up



Limit Cycle

$$\omega_s = \frac{\omega_{1,L} + \omega_{2,L}}{2}$$

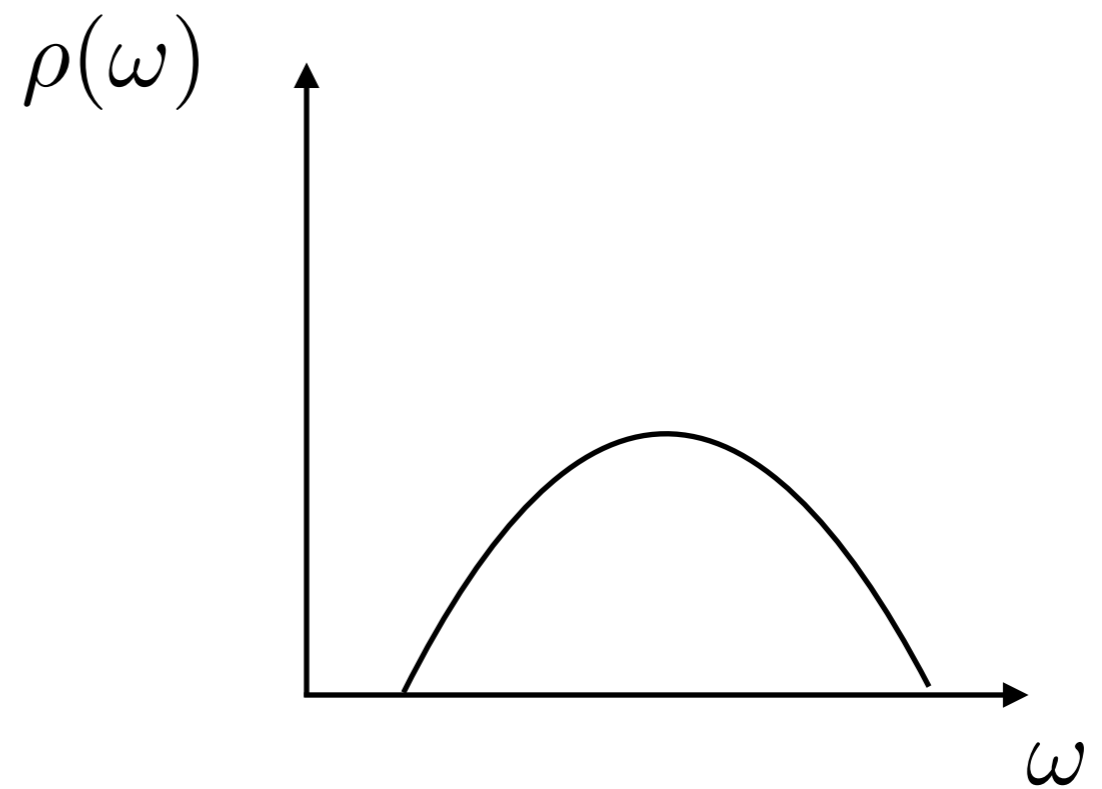
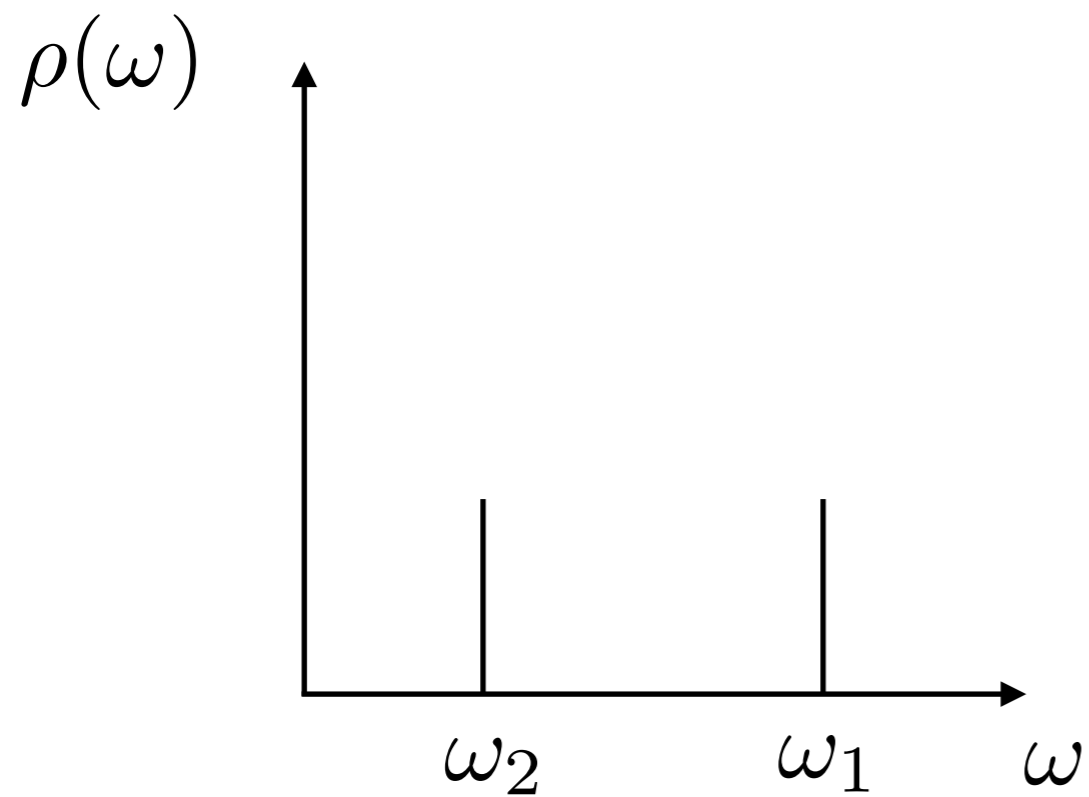


QPO

**Multi-band
Excitation**

Thanks for Your Attention

Continuum Limit



Continuum Limit: Stability Diagram

