

Neutrino Reconstruction in TRIDENT Based on Graph Neural Network

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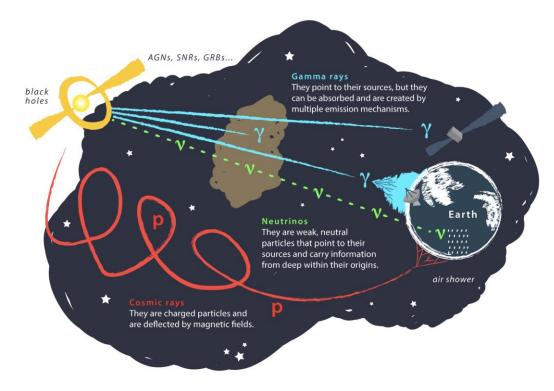
<u>mo cen@sjtu.edu.cn</u> 2023.12.14







Why do we need a neutrino telescope? Probe origins of cosmic ray with neutrino.

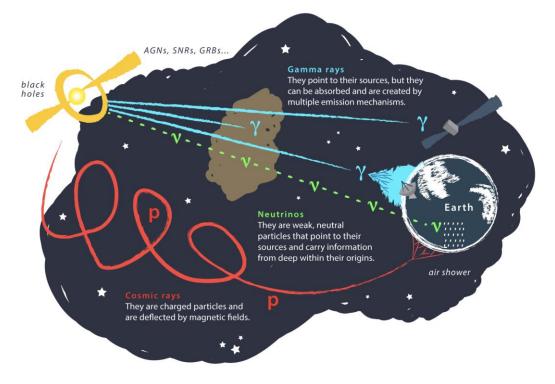


Juan Antonio Aguilar and Jamie Yang. IceCube/WIPAC



Astrophysical neutrino:

Probe origins of cosmic ray with neutrino.



• Small flux $E_{\nu}\Phi_{\nu} < 2 \times 10^{-8} GeV cm^{-2} s^{-2} sr^{-1}$

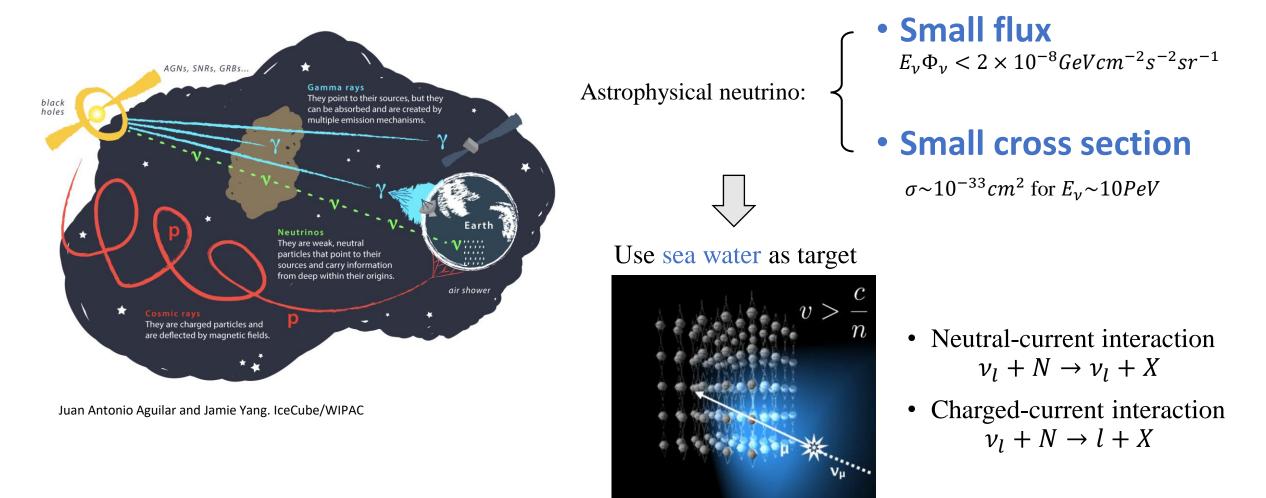
Small cross section

 $\sigma \sim 10^{-33} cm^2$ for $E_{\nu} \sim 10 PeV$

Juan Antonio Aguilar and Jamie Yang. IceCube/WIPAC

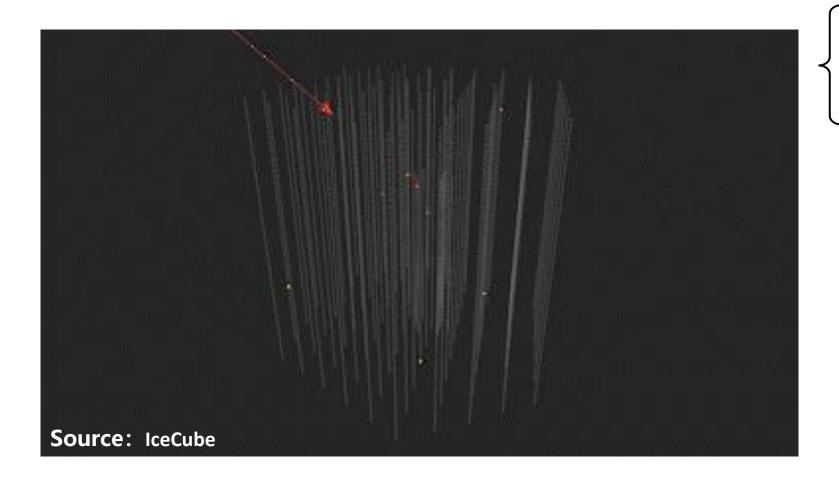


Probe origins of cosmic ray with neutrino.





Probe origins of cosmic ray with neutrino.



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• Small cross section $\sigma \sim 10^{-33} cm^2$ for $E_{\nu} \sim 10 PeV$

Use sea water as target

- Neutral-current interaction $\nu_l + N \rightarrow \nu_l + X$
- Charged-current interaction $\nu_l + N \rightarrow l + X$

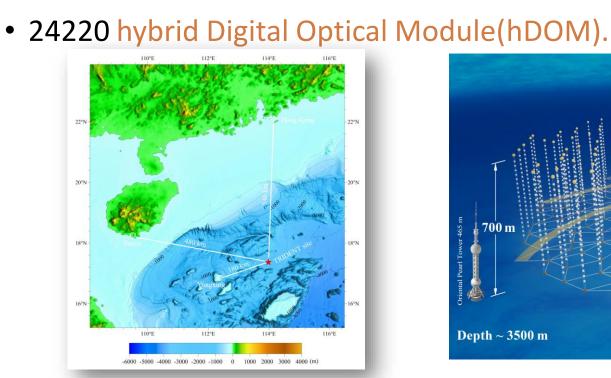


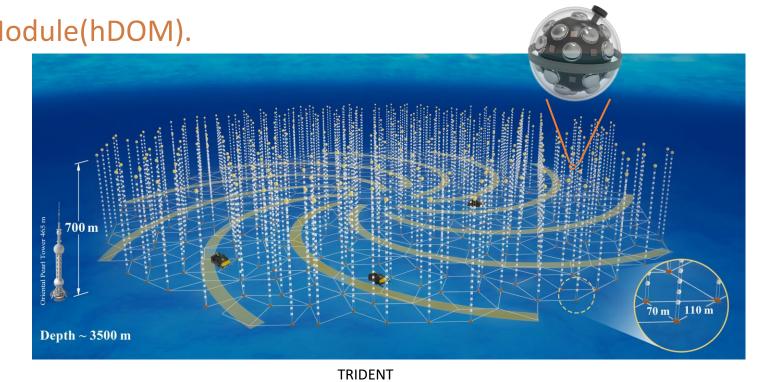
TRIDENT

• **TRIDENT**: **TR**oplcal **DE**ep-sea **N**eutrino **T**elescope.

A multi-cubic-kilometre neutrino telescope in the western Pacific Ocean. Nat Astron (2023).

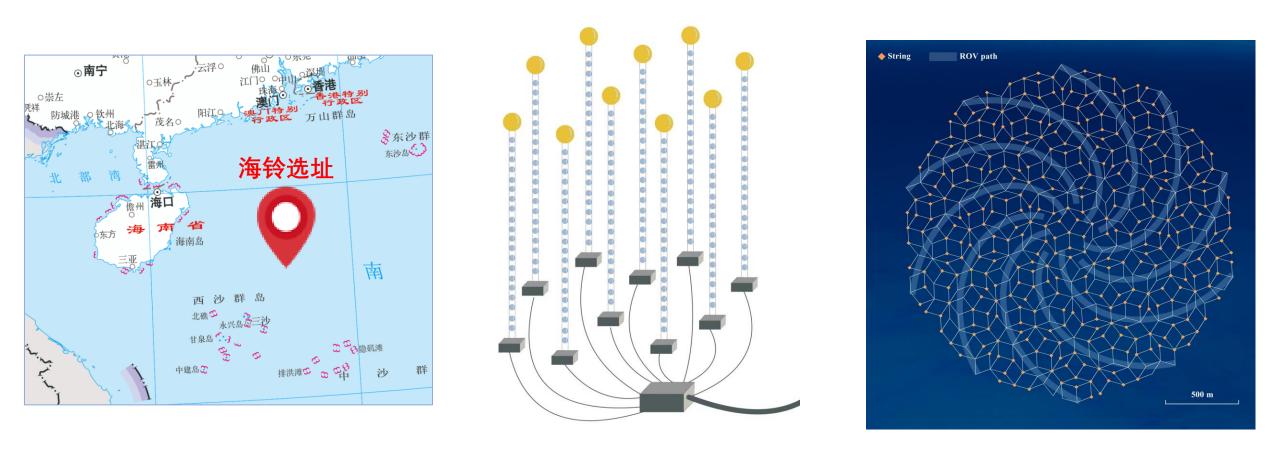
- To be located in the South China Sea.
- Penrose tiling structure with 2000m radius, 700m height (8.7 km³). 3500m deep under sea level.







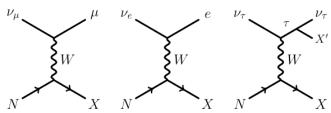
Expected Timeline



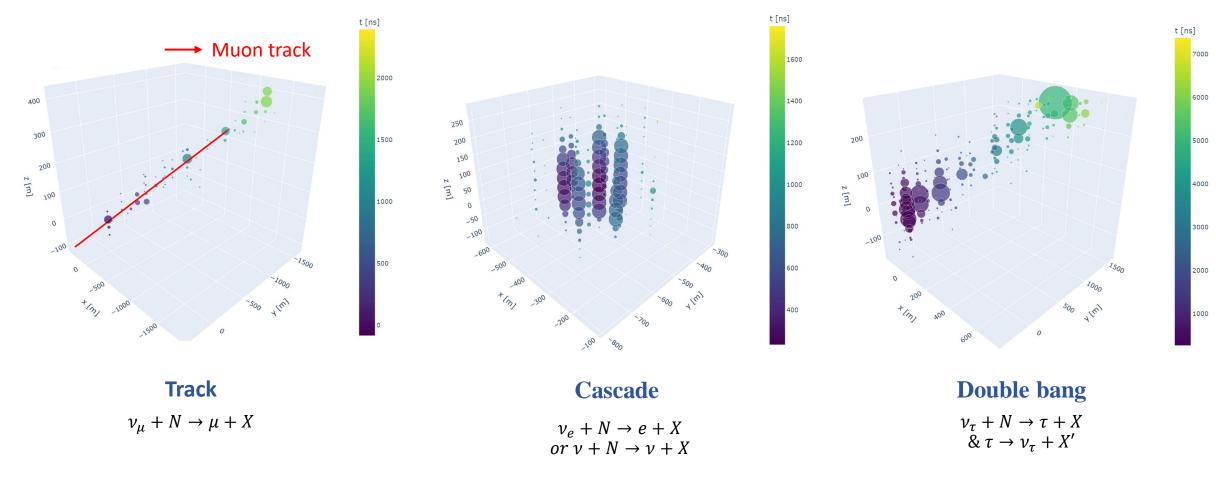
T-REX: 2019-2022 Phase I: 2022-2026 Full detector: 2026-



Neutrino Events



• The size of dots indicates the number of received photons.





Simulation

Neutrino event generator

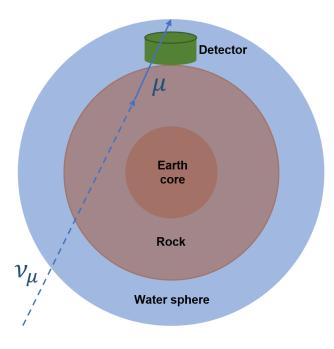
Based on CORSIKA8 (arxiv:2208.14240):

- A preliminary earth model is built.
- Scattering of ν and p is simulated with PYTHIA8.
- Propagation of μ is simulated with PROPOSAL.

Detector simulation

Based on **Geant4**:

- Simulate the propagation of secondary particles.
- Accelerate Cherenkov photons simulation with OptiX.



Preliminary earth model



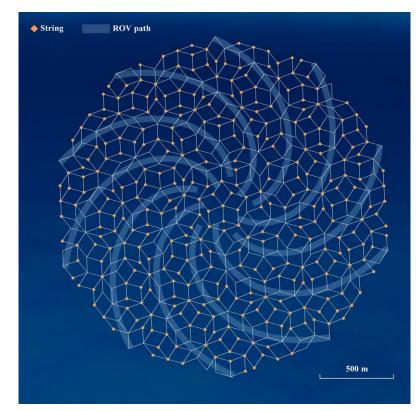
Network Architecture

Neutrino telescope:

- Irregular detector geometry
- Sparse signal

Compared GNN and SSCNN (<u>arxiv:1706.01307</u>) performance:

• GNN outperforms SSCNN in terms of angular resolution in track-like events.



Top view of TRIDENT



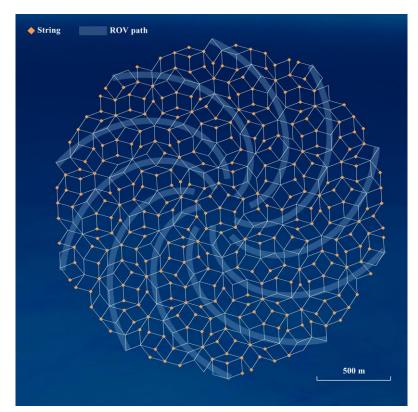
Network Architecture

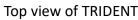
Neutrino telescope:

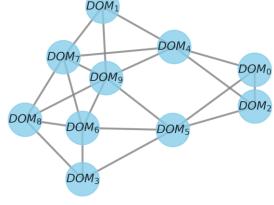
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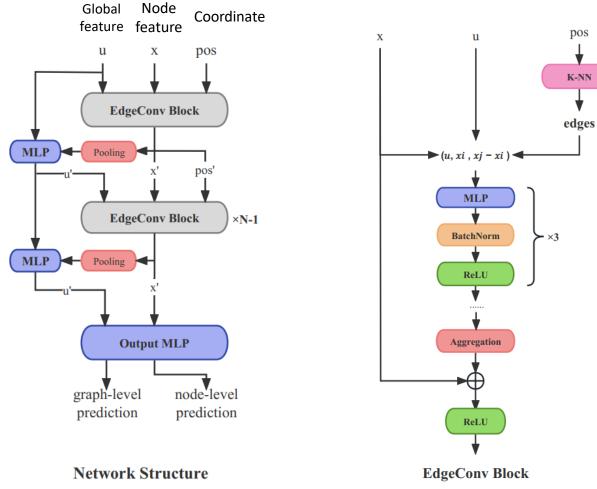
Use point cloud to represent neutrino events:

- Triggered DOMs
- Location of DOMs
- DOM-measured time

- \rightarrow Nodes of point cloud
- \rightarrow Coordinate of nodes, *pos_i*.
- \rightarrow Features of nodes, x_i .



- GNN is built based on EdgeConv block: modified from EdgeConv block used in ParticleNet (arxiv:1902.08570).
- Both graph-level and node-level target can be predicted.





Cascade Reconstruction

Direction & Energy Reconstruction $\nu_e + N \rightarrow e + X$

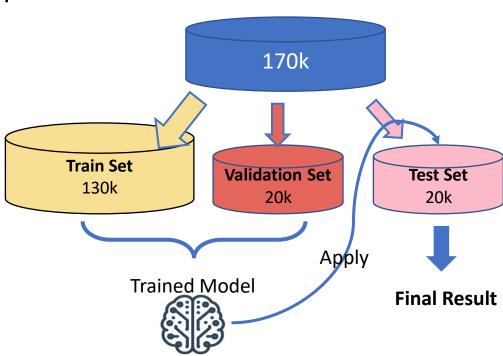


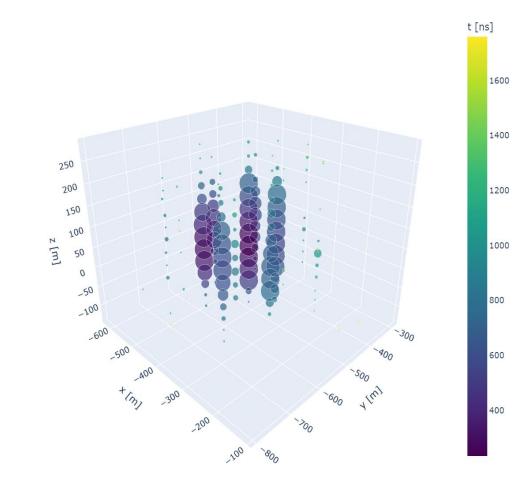
Cascade Reconstruction

v_e direction reconstruction

Configuration for Direction Reconstruction

- v_e energy: 100TeV
- Sample size:



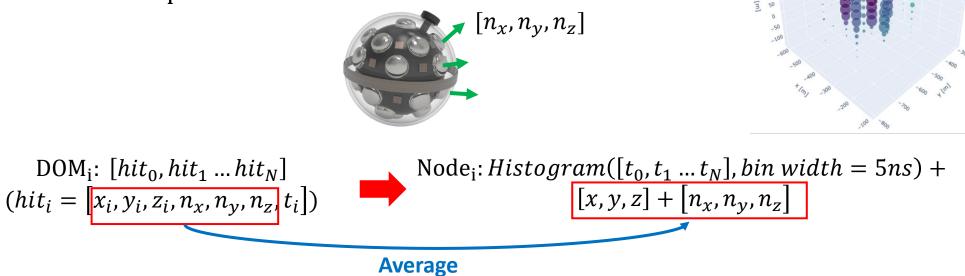




Cascade Reconstruction

v_e direction reconstruction

• Input feature of DOM_i:



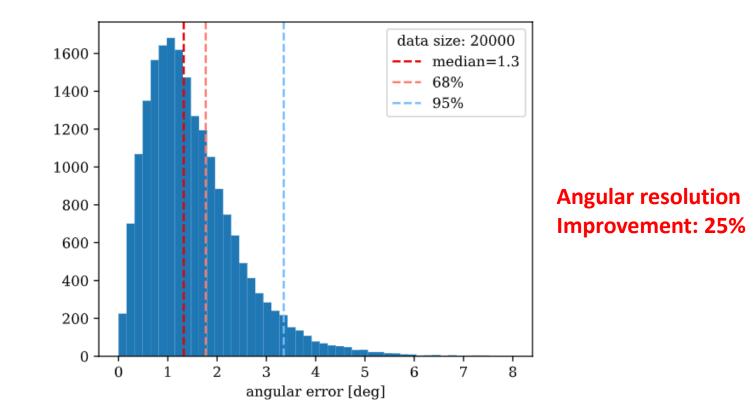
- Histogram is further modified (normalization): $Node_i = [x, y, z, n_x, n_y, n_z, \ln(Histogram + 1)]$
- Network is trained to predict \hat{n}_{ν} with MSE loss:

$$Loss = \left| \frac{\overline{output}}{|output|} - \hat{n}_{truth} \right|^2$$



v_e direction reconstruction

- Angular error: angle between recon_direction and truth_direction
- Resolution reaches 1.3 degrees. As a comparison: likelihood method: ~1.7 degrees (DOI: 10.22323/1.301.0950)





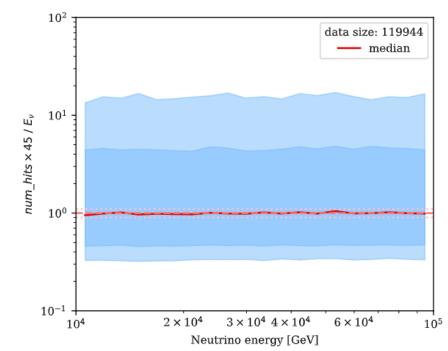
ν_e energy reconstruction

Configuration for Energy Reconstruction

- v_e energy: 10TeV ~ 100TeV
- Sample size: 150k samples are splitted into:

```
train: validation: test = 120k: 15k: 15k
```

Linearity between num_hits & Energy



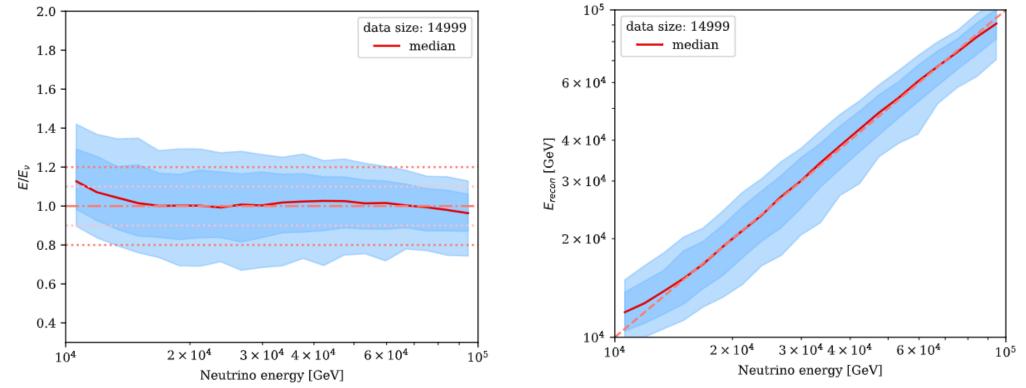


• Train GNN with:

$$\log_{10} E = GNN(graph) + \log_{10}(num_hits \times 45)$$

$$Loss = (\log_{10} E - \log_{10} E_{truth})^2$$

 Energy resolution is around 10% for high energy event – comparable results with the traditional likelihood method.





Track Reconstruction

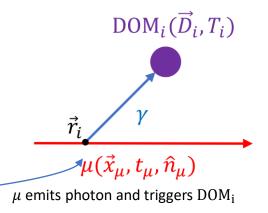
Direction Reconstruction $\nu_{\mu} + N \rightarrow \mu + X$

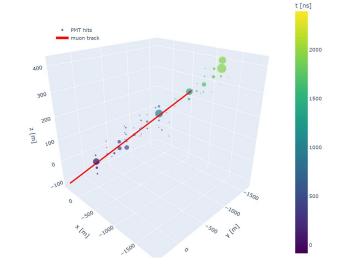


Track Reconstruction

- v_{μ} Direction reconstruction
- *train* : *validation* : *test* = 900*k* : 70*k* : 100*k*
- Input features: location \overrightarrow{D}_i , first photon arrival time T_i and number of photo hits n_i .
- To make full use of the geometric feature of track-like events, the network is trained to predict $\vec{r_i}$ for each DOM_i.
- Linear fit on the predicted \vec{r}_i' to reconstructs \hat{n}_{μ} .
- Loss function: mean square error (MSE) with weight proportional to n_i :

$$Loss = \Sigma_i n_i \times \left| \overrightarrow{output}_i - \vec{r}_i \right|^2 / \Sigma_i n_i$$





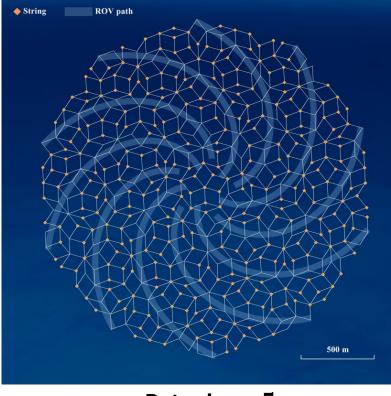
Track-like event display



• Data Augmentation: based on symmetry of TRIDENT.

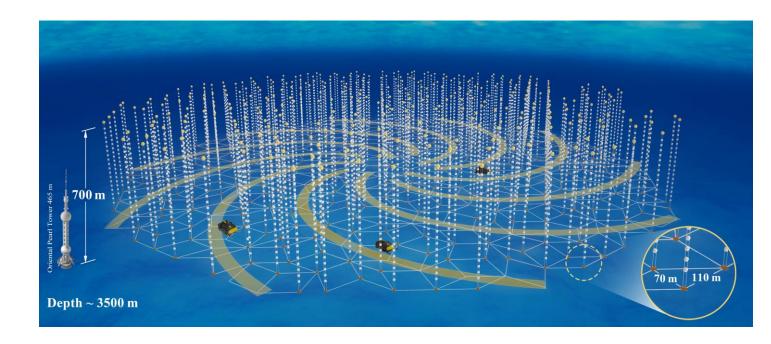
5-fold Rotational Symmetry

Invariant under 36° rotation around z-axis



Reflection Symmetry

Invariant under $x \rightarrow -x$ and $z \rightarrow -z$

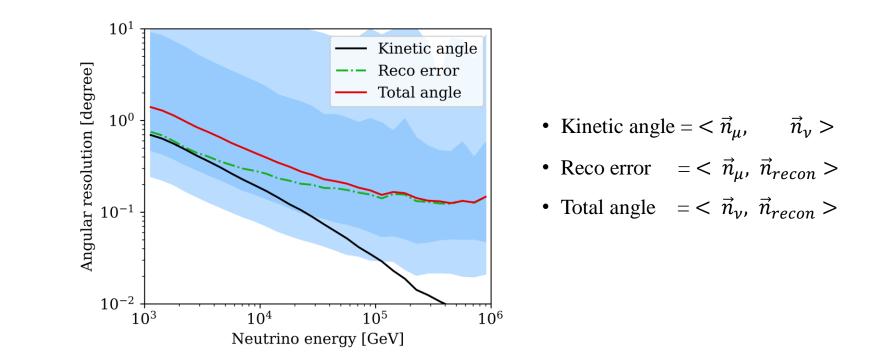


Data size imes 5



ν_{μ} Direction reconstruction

- Model is trained on events with **track length > 500m**.
- Median angular error decreases from 1 degree to 0.1 degree as the energy of v_{μ} increases competitive to the result of likelihood method.





- Simulated neutrino events in TRIDENT are represented as point clouds and are reconstructed by Graph Neural Network.
- GNN demonstrates high accuracy in reconstructing v_e and v_{μ} events in neutrino telescope:

Task	Resolution (GNN)	Resolution (Traditional method)
Cascade direction	1.3 degrees	1.7 degrees
Cascade energy	10% (>50 TeV)	5~20%
Track direction	~0.1 (>50 TeV)	0.1 (>50 TeV)



- Simulated neutrino events in TRIDENT are represented as point clouds and are reconstructed by Graph Neural Network.
- GNN demonstrates high accuracy in reconstructing v_e and v_μ events in neutrino telescope:
 - **25% improvement** for v_e direction reconstruction.
 - 10% energy resolution for $v_e \& 0.1$ angular resolution for v_{μ} : competitive to traditional method.
- Reconstruction speed achieved by GNN (~1 ms/event) significantly outperforms the speed of likelihood method (~1 s/event).

- Improvement of neutrino reconstruction will be further studied.
- Future research will try to enhance the method's robustness against experimental uncertainties and noise.



Thanks for listening!

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Neutrino Telescope





• Learning rate:

Initial learning Rate = 0.003

Ir scheduler: ReduceLROnPlateau(factor=0.5, patience=5)

• optimizer:

Adam(betas=(0.9, 0.999), eps=1e-8, weight_decay=0)



Likelihood Reconstruction of v_e

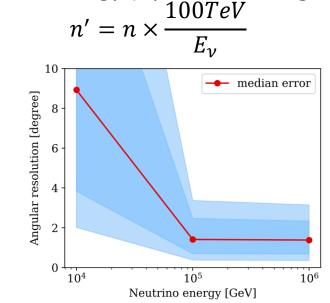
$$\log \mathscr{L} = \sum_{empties} \log[P_i^{nohit}] + \sum_{hitPMTs} \log[1 - P_i^{nohit}]$$

$$P_i^{nohit} = \exp[-H_{i} \cdot (r_i \cdot r_i \cdot r_i \cdot F_{i}) - P_{i} \cdot T]$$

$$\Gamma_i = \exp[-\mu_{sig}(\Gamma_i, z_i, u_i, E_S) - \kappa_{bg} \cdot \Gamma]$$

(equation 5.2) are considered. The expected number of hits from the shower μ_{sig} is evaluated using interpolation of a three-dimensional histogram depending on r_i, z_i and a_i at a shower energy of 1 PeV (figure 8). The expected number of hits at different shower energies is calculated using the fact that the number of emitted photons scales linearly with the shower energy E_S .

• Former GNN result on samples with other energy (by linear scaling num_photons):





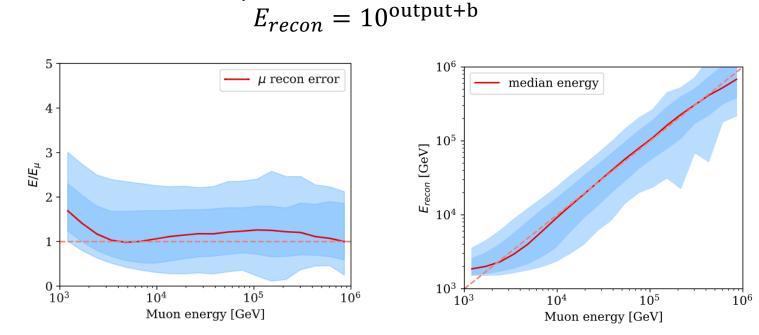
Track-like Events Reconstruction

Energy reconstruction

- Same input features as the direction reconstruction.
- Network is trained with MSE loss to predict $\log_{10} E_{\mu}$. Weight $w = \log_{10} E_{\mu} 2.5$ is applied:

$$Loss = w \left(output - \log_{10} E_{\mu} \right)^2$$

• A shift term, b = 0.15 is added to outputs of the model:

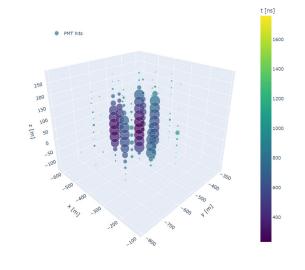


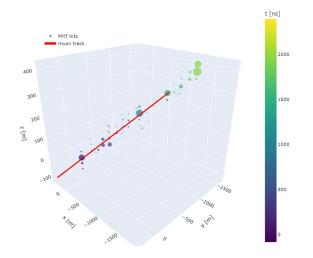


Contents of Tasks

- Reconstruction of ν_e /cascade events
 - **Direction** Reconstruction
 - Energy Reconstruction

- Reconstruction of ν_{μ} /track events
 - Direction Reconstruction



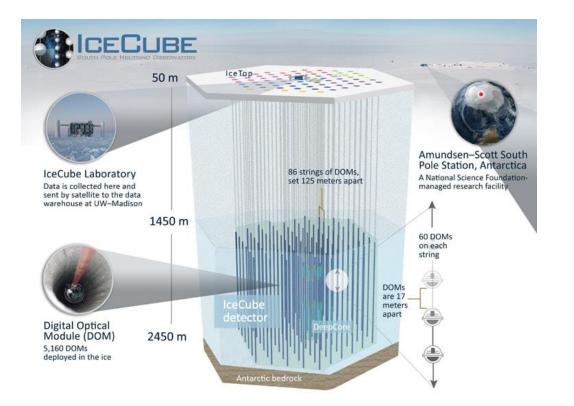


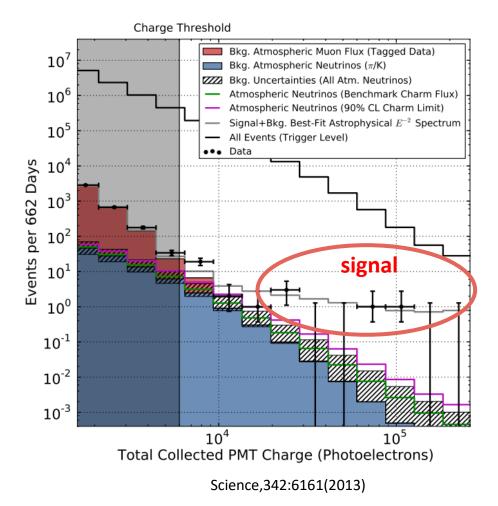




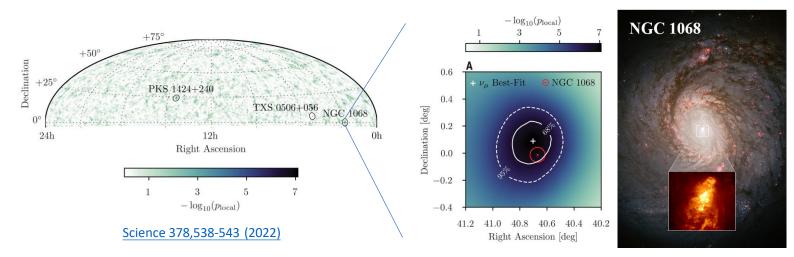
• Currently the largest neutrino telescope.

• Detected astrophysical neutrinos in 2013. <u>Science 342,1242856(2013)</u>

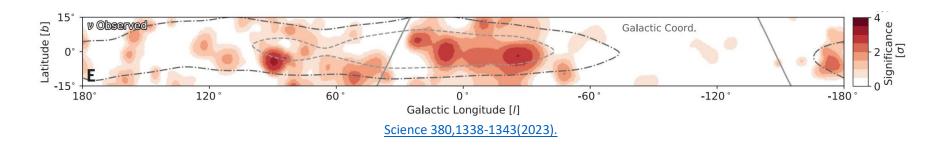




• Evidence for neutrino emission from the nearby active galaxy NGC 1068 (2022).

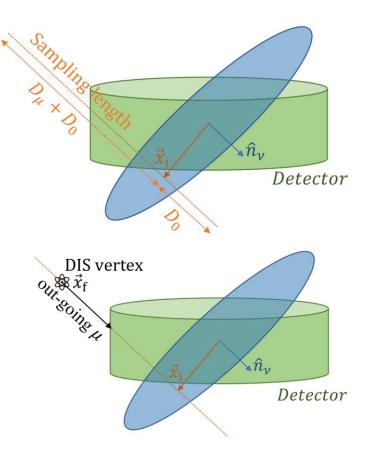


• Observation of high-energy neutrinos from the Galactic plane (2023)





v_{μ} Vertex Sampling





Effective Area of v_{μ}

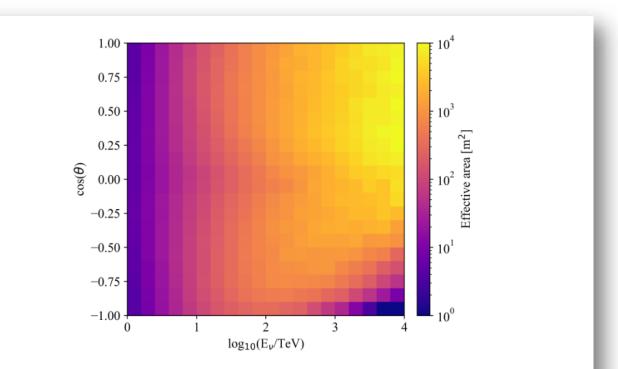


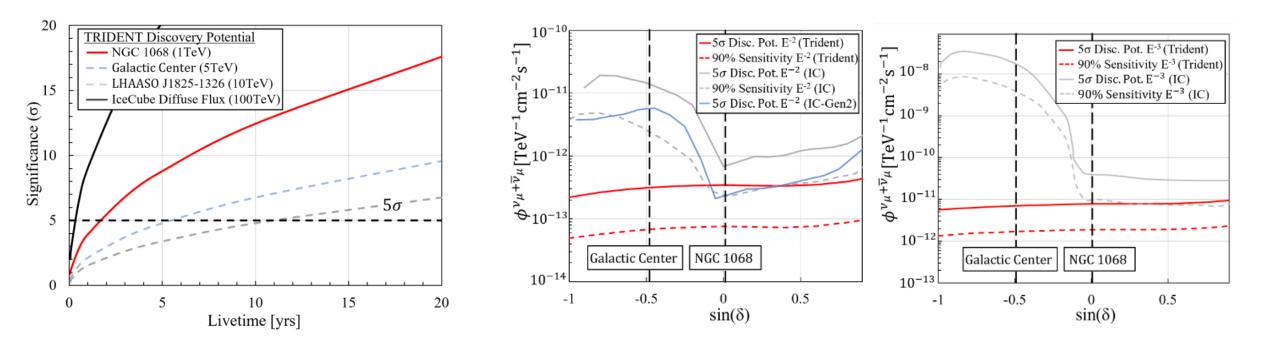
Figure 15: Effective areas at event reconstruction level for ν_{μ} track events as a function of primary neutrino energy and zenith angle in TRIDENT. At an energy of ~ 100 TeV, the effective area for up-going events is expected to reach 7×10^2 m². Only events with anglular error less than 6 degree are selected to evaluate the effective area.

arXiv:2207.04519



Significance & Sensitivity

arXiv:2207.04519





Comparison with Likelihood Method

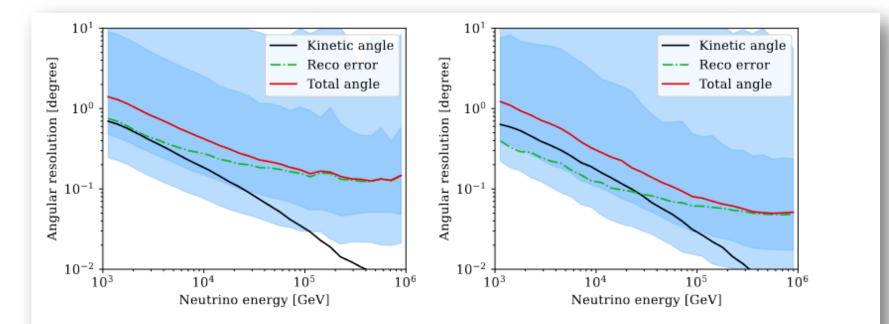


Figure 5: Median angular error of GNN (left) and likelihood method (right) depend on energy of v_{μ} . The median angle between the reconstructed track and the true direction of μ and v_{μ} is visualized by the green and red lines, respectively. Color bands exhibits the 68% and 90% quantiles. Black lines are the median angle between direction of μ and v_{μ} .



Track-like Events Reconstruction

Direction reconstruction

- Model is trained on events with track length > 500m.
- Median angular error decreases from 1 degree to 0.1 degree as the energy of ν_{μ} increases.

