## 第九届手征有效场论研讨会

## **Lattice spectra of** DDK **three-body system with Lorentz covariant kinematic**

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湖南大学 **2024.10.20** 长沙





# **Outline**

- The Quantization Condition (QC) in the finite volume
- The covariant QC of three-particle by NREFT
- DDK three-body system
- Summary and Outlook







## The quantization condition in the finite volume



## The quantization condition in the finite volume



**For the 3-body system, it becomes very complicated,** 

- **1. There are two free momenta**
- **2. How to define the S matrix of three body**
- **3. How to deal with the divergent of three-body re-scattering**

**But the 3-body system is extremely important to describe low energy resonances, such as**  $\eta \rightarrow 3\pi$ ,  $\omega \rightarrow 3\pi$ ,  $\mathsf{N}^*(1440) \rightarrow \mathsf{N}\pi\pi$ .







#### **Why invariant ?**

Typical momenta on the lattice  $(2\pi/L)$  is comparable with  $\pi$  mass, then purely kinematic effect of the relativistic invariant treatment, especially for the **moving frames**. The true amplitude is invariant.

#### **Why a manifestly invariant formulation ?**

Fingding an explicit parameterization of the three-body force that keep the solution of the Faddeev equation invariant! Too difficult and impossiblea proper short-range three-body force. But it is not only very difficult. Making the tree-level kernel of the Faddeev equation relativistic invariant order by order in the EFT expansion also does not work, since cutoff regularization will break counting rules.

On the contrary, a manifestly invariant formulation will keep the three-body force parameterize in terms of Lorentz-invariant structures, where the coupling constants before these terms are indepenedent and the expansion of the short-range part can be organized in accordance with the will-defined counting rules.

#### **How to obtain a manifestly form ?**



Weak Point: additional term will bring new pole when the cut is high.

**How to obtain a manifestly form ?**

 $\mathcal{L} = \mathcal{L}_1 + \mathcal{L}_2 + \mathcal{L}_3$  $\mathcal{L}_1 = \psi^\dagger \left( i \partial_0 - \frac{\nabla^2}{2m} \right) \psi$  $\mathcal{L}_2 = -\frac{C_0}{2} \psi^{\dagger} \psi^{\dagger} \psi \psi - \frac{C_2}{4} (\psi^{\dagger} \nabla^2 \psi^{\dagger} \psi \psi + h.c.) + \cdots$  $\mathcal{L}_3 = -\frac{D_0}{6} \psi^{\dagger} \psi^{\dagger} \psi^{\dagger} \psi \psi \psi - \frac{D_2}{12} (\psi^{\dagger} \psi^{\dagger} \nabla^2 \psi^{\dagger} \psi \psi \psi + h.c.) + \cdots$ 

$$
\mathcal{L}_1 = \psi^{\dagger} 2w_v (i(v\partial) - w_v)\psi
$$
  
\n
$$
\mathcal{L}_2 = -\frac{C_0}{2} \psi^{\dagger} \psi^{\dagger} \psi \psi - \frac{C_2}{4} \left\{ \left( (w_v \mu \psi)^{\dagger} (w_v^{\mu} \psi)^{\dagger} - m^2 \psi^{\dagger} \psi^{\dagger} \right) \psi \psi + h.c. \right\} + \cdots
$$
  
\n
$$
\mathcal{L}_3 = -\frac{D_0}{6} \psi^{\dagger} \psi^{\dagger} \psi^{\dagger} \psi \psi - \frac{D_2}{12} \left\{ \psi^{\dagger} \left( (w_v \mu \psi)^{\dagger} (w_v^{\mu} \psi)^{\dagger} - m^2 \psi^{\dagger} \psi^{\dagger} \right) \psi \psi \psi + h.c. \right\} + \cdots
$$

**Key point**, find a new operator replace  $\partial_0$  and  $\vec{\nabla}$ 

Introduce a four-velocity:  $v^{\mu} = P^{\mu}/\sqrt{P^2}$ A new energy operator:  $\omega_{\rm v} = \sqrt{m^2 + \partial^2 - (\partial \cdot {\rm v})^2}$ A new four momentum operator:  $\omega_{\rm v}^{\mu} = {\rm v}^{\mu} \omega_{\rm v} + {\rm i} \partial_{\perp}^{\mu}$ where  $\partial^{\mu}_{\perp} = \partial^{\mu} - v^{\mu} (\partial \cdot v)$ 

When  $\mathrm{v}^{\mu}=\left( \mathrm{1},\vec{0}\right)$ , in REST FRAME  $\omega_{\rm v}=\sqrt{m^2-\vec{\partial}^{\,2}}$  ;  $\partial_\perp^\mu=\left(0,\vec{\partial}\right)$ ;  $\omega_{\rm v}^\mu=\left(\omega_{\rm v}, {\rm i} \vec{\partial}\right)$ Just rely on  $\vec{\partial}$ 

**We construct several Lorentzinvariant operators just by**  $\vec{\theta}$ and  $v^{\mu}$  !!!





$$
\mathcal{L}_1 = \psi^{\dagger} 2w_v (i(v\partial) - w_v) \psi
$$
  
\n
$$
\mathcal{L}_2 = -\frac{C_0}{2} \psi^{\dagger} \psi^{\dagger} \psi \psi - \frac{C_2}{4} \left\{ \left( (w_v \mu \psi)^{\dagger} (w_v^{\mu} \psi)^{\dagger} - m^2 \psi^{\dagger} \psi^{\dagger} \right) \psi \psi + h.c. \right\} + \cdots
$$
  
\n
$$
\mathcal{L}_3 = -\frac{D_0}{6} \psi^{\dagger} \psi^{\dagger} \psi^{\dagger} \psi \psi - \frac{D_2}{12} \left\{ \psi^{\dagger} \left( (w_v \mu \psi)^{\dagger} (w_v^{\mu} \psi)^{\dagger} - m^2 \psi^{\dagger} \psi^{\dagger} \right) \psi \psi \psi + h.c. \right\} + \cdots
$$
  
\n**Dimer picture**  
\n
$$
(C_0, C_2, D_0, D_2) \sim (\sigma, f_1, h_0, h_2)
$$

$$
\mathcal{L}_1 = \psi^{\dagger} 2w_v (i(v\partial) - w_v)\psi
$$
  
\n
$$
\mathcal{L}_2 = \sigma T^{\dagger} T + \frac{1}{2} \left[ T^{\dagger} (\psi\psi + f_1((w_v\mu\psi)(w_v^{\mu}\psi) - m^2\psi\psi) + \cdots) + h.c. \right] + \cdots
$$
  
\n
$$
\mathcal{L}_3 = h_0 T^{\dagger} T \psi^{\dagger} \psi + h_2 T^{\dagger} T (\psi^{\dagger} w_v^2 \psi + h.c.) + \cdots
$$





$$
\mathcal{L}_2 = -\frac{C_0}{2} \psi^{\dagger} \psi^{\dagger} \psi \psi - \frac{C_2}{4} \Big\{ \big( (w_v \mu \psi)^{\dagger} (w_v^{\mu} \psi)^{\dagger} - m^2 \psi^{\dagger} \psi^{\dagger} \big) \psi \psi + h.c. \Big\} + \cdots \qquad \blacklozenge \qquad = \qquad \blacklozenge \qquad + \qquad \blacklozenge \qquad \blacklozenge \qquad + \qquad \blacktriangleright \bigodot \bigodot \qquad + \qquad \ldots
$$

$$
T_0 = (4C_0) + (4C_0)^2 \frac{1}{2} I + (4C_0)^3 \frac{1}{4} I^2 + \dots = \frac{1}{(4C_0)^{-1} - \frac{1}{2} I}. \qquad I(s) = J(s) + \frac{i\sigma}{16\pi} \qquad \sigma = \left(1 - \frac{4m^2}{s + i\varepsilon}\right)^{1/2}
$$

$$
I = \int \frac{d^D k}{(2\pi)^{D} i} \frac{1}{2w_v(k)(w_v(k) - vk - i\varepsilon)} \frac{1}{2w_v(P - k)(w_v(P - k) - v(P - k) - i\varepsilon)}
$$





 $T_3(p_1, p_2, p_3; q_1, q_2, q_3) = T_3^{\text{disc}} + T_3^{\text{conn}}$ ,

$$
T_3^{\text{disc}} = \sum_{i,j=1}^3 (2\pi)^3 \delta^3(p_{i\perp} - q_{j\perp}) 2w_v(p_i)\tau((K - p_i)^2),
$$
  

$$
T_3^{\text{conn}} = \sum_{i,j=1}^3 \tau((K - p_i)^2) \mathcal{M}(p_i, q_j, K)\tau((K - q_j)^2).
$$

 $\mathcal{M}(p,q;P)=Z(p,q;P)+\int\frac{d^{4}k}{(2\pi)^{4}}\Theta_{v}(k)Z(p,k;P)\tau((P-k)^{2})\mathcal{M}(k,q;P).$  $\Theta_v(k) = 2\pi \delta(k^2 - m^2) \theta(\Lambda^2 + k^2 - (v \cdot k)^2)$ 



$$
\mathcal{Z}(p,q) = \frac{1}{2w_v(K-p-q)(w_v(p)+w_v(q)+w_v(K-p-q)-vK-i\varepsilon)} + \frac{H_0(\Lambda)}{\Lambda^2}
$$

$$
Z(\vec{p}, \vec{q}, E) = \frac{1}{\vec{p}^2 + \vec{q}^2 + \vec{p} \cdot \vec{q} - mE} + h_0
$$



- In Box, the "p" become discrete  $(2\pi/L)\vec{n}$ ,  $\vec{n} = (n_1, n_2, n_3)$
- **Propagator of dimer,**  $\tau_{L}(s) = \frac{1}{(p_s^{2L}T_{tree}^L)^{-1} \frac{1}{2}I(s)}$

$$
I = \int \frac{d^D k}{(2\pi)^D i} \frac{1}{2w_v(k)(w_v(k) - vk - i\varepsilon)} \frac{1}{2w_v(P-k)(w_v(P-k) - v(P-k) - i\varepsilon)}
$$

$$
\sum_{k=0}^{\text{Box}} \sum_{k=0} I^{FV} = \frac{1}{L^3} \sum_{k=0}^{\infty} \int \frac{dk^0}{2\pi i} \frac{1}{2w_v(k)(w_v(k) - v \cdot k - i\epsilon)} \frac{1}{2w_v(P - k)(w_v(P - k) - v \cdot (P - k) - i\epsilon)}
$$

$$
\tau^{FV} = \frac{1}{\left(p_s^{2L}T_{tree}^L\right)^{-1} - \frac{1}{2}I^{FV}} = \frac{1}{\left(p_s^{2L}T_{tree}^L\right)^{-1} - \frac{1}{2}Re[I^{\infty}] - \frac{1}{2}(I^{FV} - Re[I^{\infty}])} = \frac{16\sqrt{s}\pi}{p_s\cot\delta_L - \frac{1}{32\sqrt{s}\pi}(I^{FV} - Re[I^{\infty}])}
$$

$$
=\frac{16\sqrt{s}\,\pi}{p_s cot\delta_L-\frac{2}{\sqrt{\pi}L\gamma}Z^d_{00}(1;q_0^2)}
$$

Spurious Pole JHEP 07 (2022) 019

$$
s = P^2
$$
,  $\gamma = \left(1 - \frac{\mathbf{P}^2}{P_0^2}\right)^{-1/2}$ ,  $\mathbf{d} = \frac{\mathbf{P}L}{2\pi}$ ,  $q_0^2 = \frac{L^2}{4\pi^2} \left(\frac{s}{4} - m^2\right)$ , and

$$
Z_{00}^{d}(1;q_0^2) = \frac{1}{\sqrt{4\pi}} \sum_{\mathbf{r} \in P_d} \frac{1}{\mathbf{r}^2 - q_0^2}, \ P_d = \{ \mathbf{r} = \mathbb{R}^3 | r_{\parallel} = \gamma^{-1} \left( n_{\parallel} - \frac{1}{2} |\mathbf{d}| \right), \ \mathbf{r}_{\perp} = \mathbf{n}_{\perp}, \ \mathbf{n} \in \mathbb{Z}^3 \}
$$



• Scattering equation,  $M(p,q;P) = Z(p,q;P) + \int \frac{d^4k}{(2\pi)^4} \Theta_v(k) Z(p,k;P) \tau((P-k)^2) M(k,q;P).$  $\Theta_v(k) = 2\pi \delta(k^2 - m^2)\theta(\Lambda^2 + k^2 - (v \cdot k)^2)$ 

$$
\mathbf{Box} \qquad \mathcal{M}^{L}(p,q;P) = Z(p,q;P) + \frac{1}{L^{3}} \sum_{\mathbf{k}} \tilde{\Theta}_{v}(k) Z(p,k;P) \tau^{L}((P-k)^{2}) \mathcal{M}^{L}(k,q;P) \qquad \tilde{\Theta}_{v}(k) = \frac{\theta(\Lambda^{2} + m^{2} - (v \cdot k)^{2})}{2\omega(k)}
$$

图中国科学院大学

 $\det \left( \delta_{pq} - \frac{1}{L^3} \tilde{\Theta}_v(q) Z(p,q;P) \tau^L((P-q)^2) \right) = 0.$  $\cdot$  QC:

#### **Project to the irreducible representation (irrep)**

- Symmetry breaking
- 
- Box Volume ->
- $Z^{\Gamma}(r,r^{'})=\sum \Big(\mathscr{T}^{\Gamma}(g)\Big)Z(gp_{r}^{(0)},q_{r^{'}}^{(0)})$  $\text{Infinite Volume -& SO(3)} \qquad \qquad \text{or} \qquad \qquad \text{or} \qquad \text{or}$

r indicate the momentum shell,  $\mathcal J$  is the matrix of irrep  $\Gamma$ ,  $g$  is element of group,  $|G|$  and  $\vartheta$  are the order of group and the shell.

• QC for fixed irrep:  $\det \left( \delta_{rr'} - \frac{1}{L^3} \frac{\vartheta_{r'}}{|G|} \tilde{\Theta}_{v}(r') Z^{\Gamma}(r,r';P) \tau ((P-k_{r'})^2) \right) = 0.$ 

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• 3-body bound state of  $DDK$   $J^P=0^-$ ,  $I=$ 1 2 ,  $S = 1$ ,  $C = 2$ Binding energy 70 MeV DK attractive interaction

**Tian-Wei Wu, Ming-Zhu Liu, Li-Sheng Geng, Emiko Hiyama, Manuel Pavon Valderrama PRD100(2019)3, 034029**



FIG. 4: The invariant-mass spectra of  $D^+ D_s^*$  in the (a)  $\Upsilon(1S)$  and (b)  $\Upsilon(2S)$  data samples. The cyan shaded histograms are from the normalized  $M_{D^+}$  and  $M_{D^{*+}}$  sideband events. The blue solid curves show the fitted results with the  $R^{++}$  mass fixed at  $4.14 \text{ GeV}/c^2$  and width fixed at 2 MeV, and the blue dashed curves are the fitted backgrounds.

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FIG. 7. *DDK* states in finite volume. The orange curves are calculated at  $O(p^0)$ , the blue curves at  $O(p^2)$ , and the purple curves at  $O(p^4)$ .

**Non-covariant form Finite volume spectra of DDK system**

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**Phys.Rev.D**

Phys.Rev.D

Jin-

Yi Pang,

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**(2020)**

**11,**

**114515**

$$
\mathcal{L} = \mathcal{L}_1 + \mathcal{L}_2 + \mathcal{L}_3.
$$
\n
$$
\mathcal{L}_1 = D^{\dagger} 2 w_v (v \cdot i \partial - w_v) D + K^{\dagger} 2 w_v (v \cdot i \partial - w_v) K
$$
\n
$$
+ \sigma_{DK} T_{DK}^{\dagger} T_{DK} + \sigma_{DD} T_{DD}^{\dagger} T_{DD}.
$$
\n
$$
\mathcal{L}_2 = T_{DK}^{\dagger} (D \mathscr{F}_{DK} K) + \frac{1}{2} T_{DD}^{\dagger} (D \mathscr{F}_{DD} D) + \text{h.c.}
$$
\n
$$
D \mathscr{F}_{DD} = DD + \frac{1}{8} f_{DD} (D \bar{w}_{\perp}^{\mu} \bar{w}_{\perp \mu} D - (\bar{w}_{\perp}^{\mu} D)(\bar{w}_{\perp \mu} D)).
$$
\n
$$
D \mathscr{F}_{DK} = DK + \frac{1}{8} f_{DK} (u_D^2 D \bar{w}_{\perp}^{\mu} \bar{w}_{\perp \mu} K + u_K^2 K \bar{w}_{\perp}^{\mu} \bar{w}_{\perp \mu} D
$$
\n
$$
- 2 u_{DM} (\bar{w}_{\perp}^{\mu} D)(\bar{w}_{\perp \mu} K)).
$$

 $\mathcal{L}_3 = T_{DK}^{\dagger} D^{\dagger} \mathcal{H} T_{DK} D,$  $\mathscr{H} = h_0 + h_2 \Delta + h_2'(\overleftarrow{\Delta}_T + \Delta_T) + \cdots \quad \Delta \rightarrow (s - s_{th}), \Delta_T \rightarrow \sigma^2 - s_{th}^{(DK)}$ 

**Two dimer**   $\tau_{DK}(s) = \frac{1}{b_0^{(DK)} + b_1^{(DK)}(s - s_{\text{th}}) - \Sigma_{DK}(s)}, \quad \tau_{DD}(s) = \frac{2}{b_0^{(DD)} + b_1^{(DD)}(s - s_{\text{th}}) - \Sigma_{DD}(s)}.$ **fields for**   $\Sigma_{DK}(s) = \frac{1}{16\pi^2} \Big( \frac{2p^*_{DK}}{\sqrt{s}} \log \frac{m_D^2 + m_K^2 - s + 2p^*_{DK}\sqrt{s}}{2m_D m_K} - (m_D^2 - m_K^2) \Big( \frac{1}{s} - \frac{1}{(m_D + m_K)^2} \Big) \log \frac{m_D}{m_K} \Big)$ **DK and DD**  $\Sigma_{DD}(s) = \frac{1}{16\pi^2} \frac{2p_{DD}^*}{\sqrt{s}} \log \frac{2m_D^2 - s + 2p_{DK}^* \sqrt{s}}{2m_D^2}$  $\begin{split} \tau^L_{DK}(P) &= \frac{1}{J_{DK}(s) - \mathrm{Re}\Sigma_{DK}(s) - S^L_{DK}(P)},\\ \tau^L_{DD}(P) &= \frac{2}{J_{DD}(s) - \mathrm{Re}\Sigma_{DD}(s) - S^L_{DN}(P)}. \end{split} \quad \begin{split} J(s) &= \Big[\frac{1}{b_0 + b_1(s - s_\mathrm{th}) - \Sigma(s)} - \frac{R_{\mathrm{f}}}{s - s_{\mathrm{f}}} + c_0 + c_1(s - s_\mathrm{th})\Big]^{-1} + \Sigma(s).\\ \mathsf{Spurious~Pole}\\ &= \frac{1}{4\pi^{3/2}L\gamma\sqrt{s}}Z^d_{00}($ 









$$
\mathcal{M}(p,q;P) = Z(p,q;P) + \int \frac{d^4k}{(2\pi)^4} \Theta_v(k) Z(p,k;P) \tau((P-k)^2) \mathcal{M}(k,q;P) \n\mathcal{M} = \begin{pmatrix} \mathcal{M}_{11} & \mathcal{M}_{12} \\ \mathcal{M}_{21} & \mathcal{M}_{22} \end{pmatrix}, \quad Z = \begin{pmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{pmatrix} \quad \tau = \begin{pmatrix} \tau_{DK} \\ \tau_{DD} \end{pmatrix} \n\mathcal{M}^L(p,q;P) = Z(p,q;P) + \frac{1}{L^3} \sum_{k} \tilde{\Theta}_v(k) Z(p,k;P) \tau^L((P-k)^2) \mathcal{M}^L(k,q;P) \n\frac{1}{2w_v^K(P-p-q)(w_v^K(P-p-q)-v \cdot (P-p-q))} + \frac{H_0(\Lambda)}{\Lambda^2} + \frac{H_2(\Lambda)}{\Lambda^4}(s-s_{th}) \nZ_{12}(p,q;P) = Z_{21}(q,p;P) = \frac{1}{2w_v^D(P-p-q)(w_v^D(P-p-q)-v \cdot (P-p-q))} \qquad Z_{22} = 0 \n\tag{Z}_{22} = 0
$$

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#### To fix  $H_0(\Lambda)$  and  $H_2(\Lambda)$

- $DD_{s0}^*(2317)$  scattering length  $a = a(H_0)$
- *DDK* 3-body bound state  $B_3 = B_3(H_0, H_2)$





The finite volume spectra for different total momentum ( $\sqrt{s}$  is scaled by  $m_D$ )







Compare with non-relativistic



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) vs O(p<sup>2</sup>) in (0,0,0)  $O(p^0)$ 中国科学院火学



# **Summary and Outlook** <sup>18</sup>

**We present a covariant form for three-body system by using NREFT for the QC in finite volume and scattering equation in infinite volume.**

**We present the finite spectra of DDK system.**

**A lot of things can be done !**  For example : to  $DD\pi$  system to study  $T_{cc}$ 









### Thanks very much !



