Tracking for Dark SHINE experiment

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Dark SHINE R&D Team

Outline

- 1. Overview & motivation for Dark SHINE experiment
- 2. Detector layout & design of Dark SHINE
- 3. Hardware design & performance for Dark SHINE trackers
- 4. Dark SHINE software & its track reconstruction
- 5. Track reconstruction in Dark SHINE using ACTS
- 6. Summary

Overview & motivation for Dark SHINE experiment

- Thermal Dark Matter (DM) originating as a relic of the hot early universe is one of the most compelling paradigms.
 - Temperature drops due to the over-expansion of the universe -> DM density becomes stable ("freeze-out" mechanism).
- Dark photons is a good candidate of vector massive boson.



Overview & motivation for Dark SHINE experiment

- Dark photon can be produced in eN interaction (electron-on-target)
- Two ways of detection, via its:
 - Visible decay:
 2 interaction vertices -> production rate is suppressed.
 N ~ ε⁴





• Invisible decay:

Better sensitivity due to higher production rate. N ~ ϵ^2 (1- ϵ^2)







Overview & motivation for Dark SHINE experiment

- Invisible decay's signal signature:
 - soft recoil electron,
 - large missing energy & p_T
- Leading background: bremsstrahlung photons





Overview & motivation for Dark SHINE experiment

- Expect a competitive projected sensitivity:
 - 90% C.L. limits are extracted on the ϵ^2 (kinetic mixing parameter) as a function of dark photon mass.
 - Expected to exclude the most sensitive regions from some popular LDM models with >1 yr run.



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Detector layout & design of Dark SHINE

• The Dark SHINE detector hardware technical R&D is carried out in parallel to the full detector system simulation and prospective study/optimization.



DarkSHINE detector sketch

Additional system:

Readout electronics, trigger system, TDAQ, magnetic system (1.5 T), etc.

Detector layout & design of Dark SHINE

• Designed tracking system layout:

			Tagging Tracker							
			Z location [mm]	-607.755	-507.755	-407.755	-307.755	-207.755	-107.755	-7.755
У		X width [mm]	201 mm							
		Y width [mm]	100 mm							
		# of strips	6700 (width 30um)							
			rot angle [rad]	0.05	-0.05	0.05	-0.05	0.05	-0.05	0.05
X h	peam direction		thickness	150 um						
N	Z		Recoil Tracker							
			Z location [mm]	7.905	22.9	05 38.	905	53.905	89.905	180.405
			X width [mm]	201	20	1 2	01	240	360	501
			Y width [mm]	100	100	D 1	00	115	140	200
			# of strips	6700	670	0 67	700	8000	12000	16700
			rot angle [rad]	-0.05	0.0	5 -0	.05	0.05	-0.05	0.05

Hardware design & performance for Dark SHINE trackers



- AC-LGAD silicon strip sensor 1x1 mm² designed with different strip-pad periods.
- The design of AC-LGAD sensor was completed in collaboration with Prof. Zhijun LIANG and Prof. Mei ZHAO from IHEP. (arXiv: 2310.13926)



- High Precision Tracking Detector Experimental Platform @ TDLI.
- Probing system: connect the silicon sensor to test circuits (including the measuring system).
- Drying system and cooling system: a stable temperature and humidity environment for sensor testing.

Hardware design & performance for Dark SHINE trackers

- I-V test: To identify its conductivity and leakage properties.
- C-V test: focus on sensors' junctions, doping concentration and the depletion width.
- W11 & w12 refer to two different sensor wafers with different n+ doping levels (0.01P vs. 10P).



Hardware design & performance for Dark SHINE trackers

- For spatial and time resolution tests:
 - A focused laser beam (1064nm) serves as signal source.
 - Sensor is wire-bounded to a 4-channel readout board.
 - The waveforms are collected by an oscilloscope.



Dark SHINE software & its track reconstruction



- Based on GEANT4 v10.6.0: simulation, analysis, and the event visualization.
- In earlier baseline, tracking algo based on Greedy-Kasa method and KF from Genfit.

Dark SHINE software & its track reconstruction



Momentum reconstruction results from various energy regions were obtained using the earlier DS baseline



The relative uncertainty in reconstructed momentum obtained from **earlier DS baseline**

Using different magnetic fields and mathematical methods (Kalman Filter @ Genfit vs. Riemann Fitter).

- It is hard for Dark SHINE to achieve under earlier framework:
 - non-uniform magnetic field,
 - accurate reconstruction of multi-particle events ...



- The integration of TruthSeeding and KalmanFilter within the ACTS framework yields significant enhancements.
- Evident in both the reconstructed momentum centroid and width (~7.5% -> ~2.0%).



 Comparison of momentum uncertainty between earlier DS tracking Algo & ACTS TruthSeed+KF fitting



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- Momentum reconstruction performance after the application of ActsExamples::SeedingAlgorithm and CKF.
 - tagging single-electron events manifests as follows:
 - The truthP window for reconstructed momentum is 8 ± 0.625GeV
 - efficiency: 99.22% Gauss fit sigma = 0.0478
- Some problems arises...
 - (1) SeedFilter and functionality of KF.
 - 2 The circular region beam (source) spot affects our use of SP-based-Seeding algorithm.





- DarkSHINE: a fixed-target experiment searching for dark photon to light dark matter, demonstrating competitive sensitivity. (Sci. China-Phys. Mech. Astron., 66(1): 211062 (2023)).
- The tracking structure of DS is divided into a 7-layer tagging tracking region and a 6-layer Recoil tracking region. Each layer contains two strip sensors that rotate alternately.
- W11 and W12 sensors, from different doping concentrations, exhibit varied electrical performance:

Туре	W11	W12		
Spatial resolution [µm]	6.5~8.2	8.8~12.3		
Mean value of time resolution [ps]	8.3	11.4		
Break down voltage [V]	390	190		
Gain layer depletion voltage [V]	20	24		
Full-depletion voltage [V]	40	40		

• ACTS has greatly improved the tracking reconstruction performance of Dark SHINE. However, some issues arise when using the ActsExamples::SeedingAlgorithm & CKF.

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"Dark Photon Signals", may be :-D



Thank you!



- 1. Problem from Filter:
 - Because seeding induces a 5% p deviation,
 - After using CKF, decreases to 4.8%.
 - May be focusing on the functionalities of KF and SeedFilter.



Seed P Reconstruction [with truth window]

2. Problem from coordinate system:

- The old coordinate system -> eta=INF() and phi=NULL().
- After rotation -> eta=0 and phi~=0.
- Ø = 60mm circular region beam spot on the sensor plane presents a challenge for calculating the primary vertex using StandardSeeding algorithm.
- Despite attempts at solutions like vertex shifting, (which risks losing physical information,) no viable alternatives have been identified to address this issue.





Sketch for tagging tracking volume

The DS trackers are characterized by the alternating rotation of every two modules, resulting in a more pronounced vertical deviation than the horizontal deviation.

• Results from IHEP



Fig. 8. The directly-measured spatial resolution (black marks) and estimated spatial resolution (red marks) at different N+ doses.



Fig. 11. The jitter component of the time resolution with different N+ doses.

arXiv: 2212.03754

