

# Track Reconstruction in Allas



















### **ATLAS Inner Detector**







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• Inner detector track reconstruction up to  $|\eta| = 2.5 \ (\theta \approx 8^\circ)$ 

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- Originally: 3 barrel + 3 endcap layers with planar Si-pixel sensors  $(382 \times 30 \,\mu m^2)$
- Since 2014: additional Insertable B-Layer (IBL) with planar and 3D Si-pixel sensors - significantly improved vertex reconstruction

### **Pixel Detector**

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### NIM.A 568 (2006)





- 4 barrel and 9 endcap layers of silicon strip sensors ( $80 \,\mu$ m pitch)
- Each module consists of 2 sensors that are mounted back-to-back with a stereo angle of 40mrad







- 350k drift tubes filled with Xe- or Ar-based gas mixture
- Radiator material around each tube triggers transition radiation for highly

relativistic particles - x-ray photons absorbed by active gas can be distinguished from ionisation signal (2 readout thresholds) - used for particle identification







Radiation Lengths  $[X_n]$ 

r [mm]



/∆r [mm<sup>-1</sup>





### **Track Reconstruction in ATLAS**

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Material budget can be validated through rate of secondary vertices from hadronic interactions and photon conversions in data













- noise and hit efficiency

![](_page_8_Picture_9.jpeg)

![](_page_9_Figure_0.jpeg)

- Specific energy loss can be used for particle identification
  - Cluster charge in pixel detectors or time-over-threshold in TRT
- Mostly used for exotic particle searches (multi-charged, magnetic monopoles, ...)
- In addition: particle identification from transition radiation signal in the TRT

![](_page_9_Picture_10.jpeg)

![](_page_9_Picture_12.jpeg)

![](_page_10_Picture_0.jpeg)

## **Track Finding in ATLAS**

### ATLAS Primary Tracking

![](_page_10_Figure_3.jpeg)

![](_page_10_Figure_4.jpeg)

• Run multiple track finding passes on the available hits using different strategies and constraints: primary tracking, back-tracking, large-radius tracking (+ dedicated setups for low- $p_T$ , heavy ions, cosmics, etc. that are not run on all events by default)

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![](_page_10_Picture_11.jpeg)

![](_page_10_Figure_12.jpeg)

![](_page_10_Picture_13.jpeg)

![](_page_11_Picture_0.jpeg)

## **Inside-out Tracking**

![](_page_11_Figure_2.jpeg)

- Find all valid combinations of SCT and pixel hit triplets (no mixed seeds):  $p_T > 500 \,\text{MeV}, d_0 < 5 \,\text{mm}, z_0 < 200 \,\text{mm}$
- Seeds are processed depending on their score: high- $p_T$ , low- $d_0$  and a compatible hit in a 4th confirmation layer are preferred
- Combinatorial Kalman Filter is used to extend seeds inwards and outwards
- Confirmed Si-only tracks are extended into the TRT
- Global  $\chi^2$ -fit is used to extract the final track parameters

![](_page_11_Picture_10.jpeg)

![](_page_11_Figure_11.jpeg)

![](_page_11_Picture_12.jpeg)

![](_page_12_Picture_0.jpeg)

![](_page_12_Figure_1.jpeg)

![](_page_12_Figure_2.jpeg)

SCT seeds are formed first. They allow to define the beam spot region, which can then be used to discard large  $z_0$  seeds

## Seeding Performance

![](_page_12_Figure_7.jpeg)

![](_page_12_Picture_8.jpeg)

![](_page_12_Picture_9.jpeg)

![](_page_13_Picture_0.jpeg)

## **Ambiguity Resolution**

![](_page_13_Figure_2.jpeg)

- clusters, etc., before passing the tracks to the final track parameter fit
- mixed-density network is used to assign position uncertainties to the split clusters
- cluster charge

### Track Reconstruction in ATLAS

• An elaborate scoring is used to classify track candidates based on the number hits, number of holes, shared

• For regions of interest within high- $p_T$  jets shared hits are attempted to be split by a neural network. A second

• The rate of merged clusters in jets can be measured in data using the dE/dx distribution extracted from the

![](_page_13_Picture_11.jpeg)

![](_page_13_Picture_12.jpeg)

![](_page_13_Picture_13.jpeg)

![](_page_13_Figure_14.jpeg)

![](_page_13_Picture_15.jpeg)

![](_page_13_Picture_16.jpeg)

![](_page_14_Picture_0.jpeg)

![](_page_14_Figure_1.jpeg)

![](_page_14_Figure_2.jpeg)

![](_page_14_Figure_8.jpeg)

## **Pixel Cluster Splitting**

![](_page_14_Picture_10.jpeg)

![](_page_14_Figure_11.jpeg)

![](_page_14_Figure_12.jpeg)

![](_page_15_Figure_2.jpeg)

- loss from Bremsstrahlung which leads to larger scattering angles
- Allow additional scattering probabilities, modelled as a sum of Gaussian distributions (Gaussian Sum Filter)

![](_page_15_Picture_5.jpeg)

• By default all trajectories assume pion tracks - electrons can have significantly larger energy

![](_page_15_Picture_8.jpeg)

![](_page_15_Picture_9.jpeg)

![](_page_15_Picture_10.jpeg)

![](_page_16_Picture_0.jpeg)

## **TRT Track Extensions**

- Tracks from the Si-only tracking are attempted to be extended into the TRT
- All TRT straws consistent with the track road are considered and labelled as "precision hit" if the track passes within  $1.75\sigma$  of the TRT drift-circle. Hits that are not precision hits get a penalty in the fit
- Several iterations of the global  $\chi^2$  fit are performed until it converges. Only candidates with more than 30% precision hits are accepted as TRT extensions to ensure improvement of the track parameter measurement

### ATL-PHYS-PUB-2015-018

![](_page_16_Figure_9.jpeg)

![](_page_16_Picture_10.jpeg)

![](_page_16_Picture_11.jpeg)

![](_page_17_Picture_0.jpeg)

- To recover photon conversion tracks and other late decays, a back-tracking pass is run after the inside-out tracking
- Start from EM cluster with  $E_T > 6$  GeV to define a region of interest
- Use Hough-transformation of all TRT hits in this  $\phi$ -region in a to form segments and define the initial track parameters
- Look for Si-hit pairs that confirm the TRT segment, and run the usual inside-out Kalman-Filter + TRT extension to finalise the tracks
- TRT segments that find only 1 or 0 Si-hits are not used as track candidates in general, but still used in photon conversion tagging

## **Back Tracking**

![](_page_17_Figure_10.jpeg)

![](_page_17_Picture_12.jpeg)

## **Inner Detector Alignment**

![](_page_18_Picture_1.jpeg)

![](_page_18_Figure_2.jpeg)

- The detector modules are not fixed in space: They move whenever the magnets are turned on, due to temperature effects, bending, etc.
- These effects need to be considered for ultimate precision
- The alignment constants are updated for all runs, and even within runs (not all degrees of freedom) **Track Reconstruction in ATLAS**

![](_page_18_Figure_7.jpeg)

• Use muons from Z and  $J/\psi$  decays to determine all module positions and orientations by global  $\chi^2$  minimisation

![](_page_18_Figure_12.jpeg)

![](_page_18_Picture_13.jpeg)

![](_page_19_Picture_0.jpeg)

## Inner Detector Alignment

### Eur. Phys. J. C 80 (2020) 1194

Level	Description	Structures	DoF	Additio
1	IBL Pixel detector SCT endcaps (SCT barrel fixed)	1 1 2	All All All except <i>T<sub>z</sub></i>	
	TRT split into barrel and 2 endcaps	3	All except $T_z$	
Si 2	Pixel and IBL barrel split into layers Pixel endcaps split into disks SCT barrel split into layers	4 6 4	All All All	Beam s momer impact
	SCT endcaps split into disks	18	All	mpuor
Si 3	Pixel and IBL barrel modules Pixel endcaps modules SCT barrel modules SCT endcaps modules	1736 288 2112 1976	All $T_x, T_y, R_z$ All $T_x, T_y, R_z$	Beam s momen impact module
TRT 2	TRT barrel split into barrel modules TRT endcaps split into wheels Pixel and SCT detectors fixed	96 80	All except $T_y$ $T_x, T_y, R_z$	Momer impact
TRT 3	TRT straws Pixel and SCT detectors fixed	351k	$T_x, R_z$	

![](_page_19_Figure_6.jpeg)

![](_page_19_Figure_7.jpeg)

![](_page_19_Picture_16.jpeg)

![](_page_20_Picture_0.jpeg)

![](_page_20_Figure_1.jpeg)

![](_page_20_Picture_3.jpeg)

![](_page_20_Picture_4.jpeg)

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![](_page_21_Picture_0.jpeg)

Eur. Phys. J. C 83 (2023) 1081

![](_page_21_Figure_3.jpeg)

- Run dedicated pass on remaining hits with significantly relaxed requirements ( $d_0 < 300$  mm,  $z_0 < 500$  mm). Only consider SCT seeds since pixel hits are mostly missed.

### **Long-Lived Particles**

![](_page_21_Figure_9.jpeg)

• Tracks originating from long-lived decays ( $K_s$  or BSM particles) often fail the default track parameter cuts

![](_page_21_Picture_12.jpeg)

![](_page_21_Picture_15.jpeg)

![](_page_22_Picture_0.jpeg)

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![](_page_22_Figure_3.jpeg)

- The original version was only run on 10% of the data due to the large CPU time consumption.
- about 5% track finding efficiency allows to run this algorithm by default on all data
- (like secondary vertex fit)

Track Reconstruction in ATLAS

## Large Radius Tracking

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• Significant reduction in run time by allowing at most 1 hole and narrowing the search road: losing

• The large number of fake tracks at high pile-up gets reduced once physics requirements are applied

![](_page_22_Picture_13.jpeg)

![](_page_22_Picture_14.jpeg)

![](_page_22_Picture_15.jpeg)

![](_page_23_Picture_0.jpeg)

![](_page_23_Figure_1.jpeg)

- Before the start of Run 3 the track finding logic was completely revisited to reduce the CPU time
- Tighten impact parameter cuts in the seeding, no more shared pixel hits in seeds, narrower search road when extending seeds, require 8 instead of 7 silicon hits before TRT extension, higher cluster energy required to seed back-tracking, ...

![](_page_23_Figure_6.jpeg)

![](_page_23_Figure_9.jpeg)

![](_page_23_Picture_10.jpeg)

![](_page_23_Picture_12.jpeg)

# **Performance after CPU Optimisation**

![](_page_24_Figure_1.jpeg)

- to the reduced number of fake tracks

![](_page_24_Figure_5.jpeg)

• The tightened selections results in 1-4% loss of track finding efficiency but reduces the number of fake tracks by more than one order of magnitude, especially at high pile-up

• Total speed up of up to factor 2, and and a reduction of event size by up to 40%, due

![](_page_24_Picture_8.jpeg)

![](_page_24_Figure_9.jpeg)

![](_page_24_Picture_10.jpeg)

![](_page_24_Picture_11.jpeg)

![](_page_25_Picture_0.jpeg)

![](_page_25_Picture_2.jpeg)

## **Finding and Fitting Vertices**

![](_page_25_Figure_5.jpeg)

Mean Number of Interactions per Crossing

• Typically over 50-60 pile-up interactions per bunch-crossing in Run 3!

![](_page_25_Picture_8.jpeg)

![](_page_25_Picture_11.jpeg)

![](_page_26_Picture_0.jpeg)

![](_page_26_Picture_1.jpeg)

![](_page_26_Figure_3.jpeg)

- used mode finder)
- defined by cutting on these weights

## **Primary Vertex Finding**

• Find maxima in track density along z, group tracks accordingly before using them for a primary vertex fit. Use the Gaussian smoother algorithm for the seed definition since Run 3 (before we

• Compatible tracks are combined in a weighted Kalman-Filter in the Adaptive Multi-Vertex Fitter

• Each track is assigned a weight for each vertex association. The track-to-vertex association is

![](_page_26_Figure_12.jpeg)

![](_page_26_Figure_13.jpeg)

![](_page_26_Figure_14.jpeg)

![](_page_26_Picture_15.jpeg)

![](_page_26_Picture_16.jpeg)

![](_page_27_Picture_0.jpeg)

## **Tracking at the HL LHC**

![](_page_27_Figure_2.jpeg)

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![](_page_27_Picture_7.jpeg)

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![](_page_28_Figure_0.jpeg)

- pixel detector, extend using a combinatorial Kalman filter
- At the expected pile-up of 200, the ITk maintains a very similar track reconstruction efficiency and a significantly reduced number of fake tracks, allowing track finding up to  $|\eta| = 4$

• Track finding follows the same principles as the current ATLAS tracking: find and confirm seed triplets in the

• The baseline inside-out tracking is implemented and stable - work on special cases and extra tracking passes

![](_page_28_Picture_11.jpeg)

![](_page_29_Figure_0.jpeg)

![](_page_29_Picture_4.jpeg)

![](_page_30_Picture_0.jpeg)

## Outlook

- 4 reconstruction

![](_page_30_Figure_4.jpeg)

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Efficiency **ATLAS** Simulation Preliminary  $\sqrt{s}=14$  TeV, t $\overline{t}$ ,  $<\mu>=200$ ,  $p_{-}>2$  GeV 1.2 ITk layout: 23-00-03 IDTR-2023-06 0.6 0.4 CKF track finding 0.2 **GNN track finding** 10 20 30 p<sub>T</sub> [GeV]

• The track finding is currently being re-implemented from scratch using ACTS - will be the default for Run

• Novel approaches are being investigated: track finding with GNNs; using GPUs (online or offline) or FPGAs (for HL LHC event filter tracking)

![](_page_30_Picture_9.jpeg)

![](_page_30_Figure_11.jpeg)

![](_page_30_Figure_12.jpeg)

![](_page_30_Figure_13.jpeg)

![](_page_30_Picture_14.jpeg)