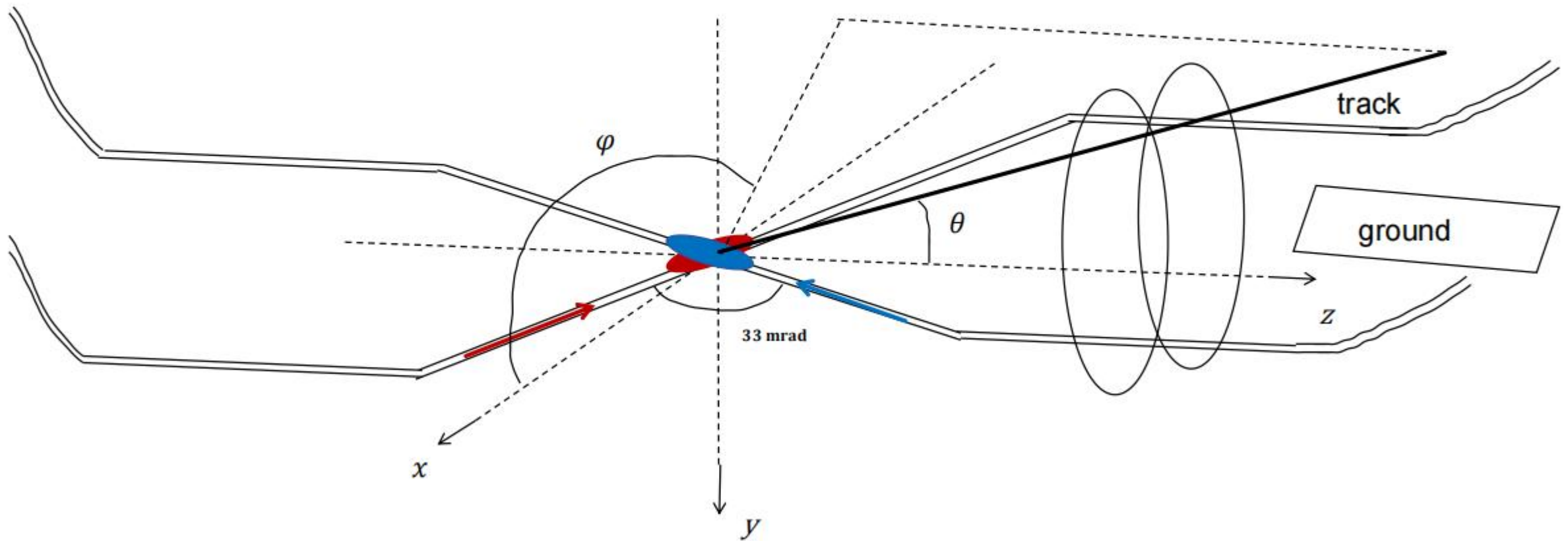


## 2024.3.12 Toy model of FLM (Ignore $B$ )

### 1. Overview in Lab frame



## 2. Hits on FLM

(1) CMS frame moves along  $-x$  with Lab frame  $\Leftrightarrow$  Lab frame moves along  $x$  with CMS frame

CMS frame  $(x, y, z, t)$   
Lab frame  $(x', y', z', t')$

$$\begin{cases} t' = \gamma \left( t - \frac{v}{c^2} x \right), \\ x' = \gamma (x - vt), \\ y' = y, \\ z' = z, \end{cases}$$

Lab frame:  $(E', p'_x, 0, p'_z)$   
CMS frame:  $(E, 0, 0, p_z)$   
Lorentz boost:

$$\begin{pmatrix} E' \\ p'_x \\ 0 \\ p'_z \end{pmatrix} = \begin{pmatrix} \gamma & -\gamma v & & \\ -\gamma v & \gamma & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} E \\ 0 \\ 0 \\ p_z \end{pmatrix}$$

Using  $E^2 - p^2 = E'^2 - p'^2 \approx 0$  and Lorentz boost, we have  $\tan \theta = \gamma v$ , therefore  $v = \tan^2 \theta / (1 + \tan^2 \theta)$   
( $\theta = 16.5$  mrad)

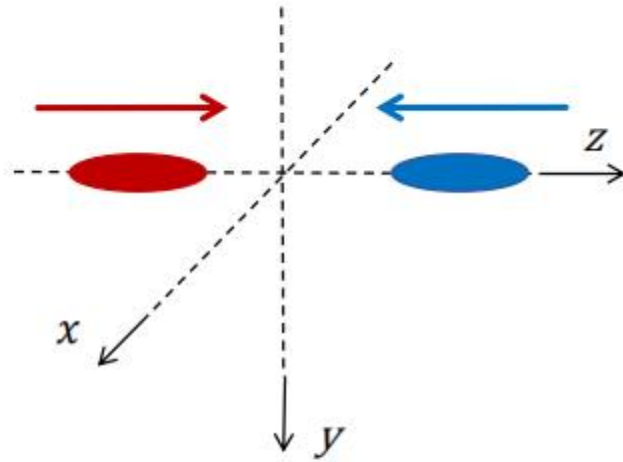
```
for(int i = 0; i < N; i++)
{
    static TRandom3 rndm;
    xi[i] = 0. + rndm.Gaus(0, 6./1000. * gamma);
    yi[i] = 0.;
    zi[i] = 0. + rndm.Gaus(0, 0.36);
    t[i] = (1000. - zi[i])/TMath::Cos(theta);

    xo[i] = xi[i] + TMath::Sin(theta)*TMath::Cos(phi)*t[i];
    yo[i] = yi[i] + TMath::Sin(theta)*TMath::Sin(phi)*t[i];
    zo[i] = 1000.;

    xb[i] = gamma * xo[i] - gamma * v * (zo[i] / (v * TMath::Cos(theta)));
    yb[i] = yo[i];
    zb[i] = zo[i];
    //cout << "xo["<<i<<"]" << xo[i] << endl;
    //cout << "yo["<<i<<"]" << yo[i] << endl;
    //cout << "zo["<<i<<"]" << zo[i] << endl;
    //cout << "t["<<i<<"]" << t[i] << endl;
}
```

(2) Assuming in CMS frame, IP= (0, 0, 0),  $\varphi = 90^\circ$ ,  $\theta = 30$  mRad and FLM at  $z = 1$  m

CMS frame (Blue points)

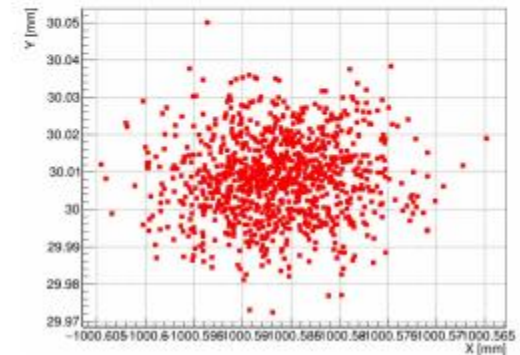
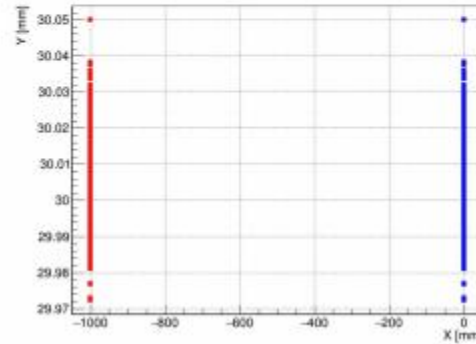
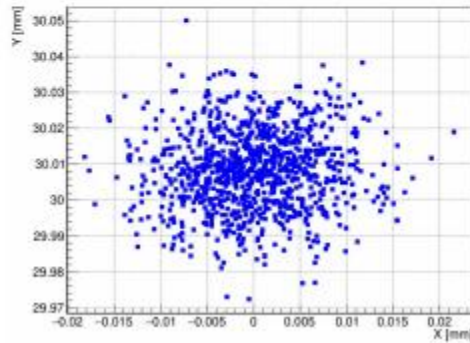
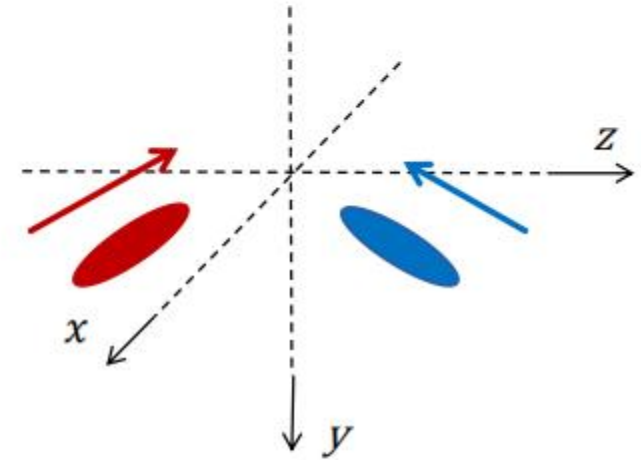


$$\begin{cases} t' = \gamma \left( t - \frac{v}{c^2} x \right), \\ x' = \gamma (x - vt), \\ y' = y, \\ z' = z, \end{cases}$$

$$\tan 16.5 \text{ mRad} = \gamma v$$

$$t = \frac{z}{v \times \cos \theta}$$

Lab frame (Red points)



### 3. Summary of the hit positions

Input  $z$  deviates 1mm, output  $y$  in Lab frame deviates 0.03 mm

```
for(int i = 0; i < N; i++)
{
    static TRandom3 rndm;
    xi[i] = 0. + rndm.Gaus(0, 6./1000. * gamma);
    yi[i] = 0.;
    zi[i] = 0. + rndm.Gaus(0, 0.30);
    t[i] = (hitposi - zi[i])/TMath::Cos(theta);

    xi2[i] = xi[i];
    yi2[i] = yi[i];
    zi2[i] = 1. + zi[i];
    t2[i] = (hitposi - zi2[i])/TMath::Cos(theta);

    xo[i] = xi[i] + TMath::Sin(theta)*TMath::Cos(phi)*t[i];
    yo[i] = yi[i] + TMath::Sin(theta)*TMath::Sin(phi)*t[i];
    zo[i] = hitposi;

    xo2[i] = xi2[i] + TMath::Sin(theta)*TMath::Cos(phi)*t2[i];
    yo2[i] = yi2[i] + TMath::Sin(theta)*TMath::Sin(phi)*t2[i];
    zo2[i] = hitposi;

    xb[i] = gamma * xo[i] - gamma * v * (zo[i] / (v * TMath::Cos(theta)));
    yb[i] = yo[i];
    zb[i] = zo[i];

    xb2[i] = gamma * xo2[i] - gamma * v * (zo2[i] / (v * TMath::Cos(theta)));
    yb2[i] = yo2[i];
    zb2[i] = zo2[i];

    dy[i] = yb2[i] - yb[i];
    dx[i] = xb2[i] - xb[i];
}
```

4. Next steps: BHLumi studies of QED scattering and Geant4 studies of multiple scattering and beam pipe  $\frac{dE}{dx}$