

# G2HDM模型的线算子谱

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# Outline

- 线算子与广义对称性
- 标准模型的线算子谱
- G2HDM 模型的线算子谱
- 对称性自发破缺
- Theta 角
- 推广到相关标准模型拓展

# 广义对称性

- 在**微分形式语言**中，Noether 流可以认为是1-form的分量

$$J = J_\mu dx^\mu$$

- 它的Hodge dual

$$*J = \frac{1}{(D-1)!} J_\mu \epsilon_{\mu_1 \dots \mu_{D-1}}^\mu dx^{\mu_1} \wedge \dots \wedge dx^{\mu_{D-1}}$$

是一个(D-1)-form, 且是一个闭合形式

- 守恒定律为

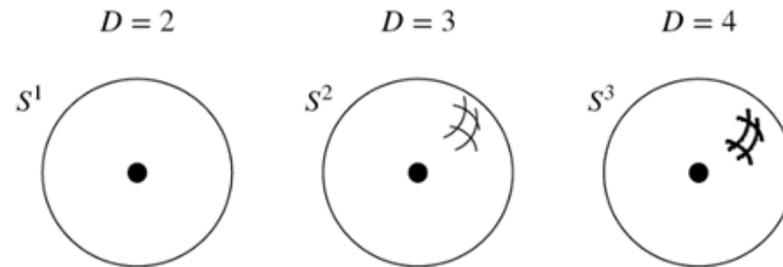
$$d * J = \partial_\mu J^\mu dx^0 \wedge \dots \wedge dx^{D-1} = 0$$

- Noether 荷则在(D-1)维的子流形上积分

$$Q(\Sigma) = \int_\Sigma *J = \int_\Sigma \frac{1}{(D-1)!} J_\mu \epsilon_{\mu_1 \dots \mu_{D-1}}^\mu dx^{\mu_1} \wedge \dots \wedge dx^{\mu_{D-1}}$$

# 对称性的拓扑表述

- 在D维区域 $\Omega_\Sigma$ 进行积分，边界是(D-1)维子流形 $\Sigma$ ， $\partial\Omega_\Sigma = \Sigma$ ，得到
- $\int_{\Omega_\Sigma} \langle d * J\phi(y) \rangle = \int_\Sigma \langle * J\phi(y) \rangle = \langle Q(\Sigma)\phi(y) \rangle$
- Ward等式 $\partial_{\mu x} \langle J_a^\mu(x)\phi(y) \rangle = -i\delta(D)(x-y)\langle \delta_a\phi(y) \rangle$ 变为
- $\langle Q(\Sigma)\phi(y) \rangle = -i \int_{\Omega_\Sigma} d^D x \delta^{(D)}(x-y)\langle \delta_a\phi(y) \rangle$
- $\int_{\Omega_\Sigma} d^D x \delta^{(D)}(x-y)$ 可看成 $\Omega_\Sigma$ 和 $y$ 的相交数，等于 $\Sigma$ 和 $y$ 的环绕数（link number）
- $\text{Link}(\Sigma, y) = \int_{\Omega_\Sigma} d^D x \delta^{(D)}(x-y)$
- $\langle Q(\Sigma)\phi(y) \rangle = -i\text{Link}(\Sigma, y)\langle \delta\phi(y) \rangle$
- $S^{D-1}$ 维球和一个点的环绕



# 对称性的拓扑表述

- 考虑 $\Omega_\Sigma$ 到 $\Omega_\Sigma' = \Omega_\Sigma \cup \Omega_0$ 的变形, 使得 $y$ 不属于 $\Omega_0$

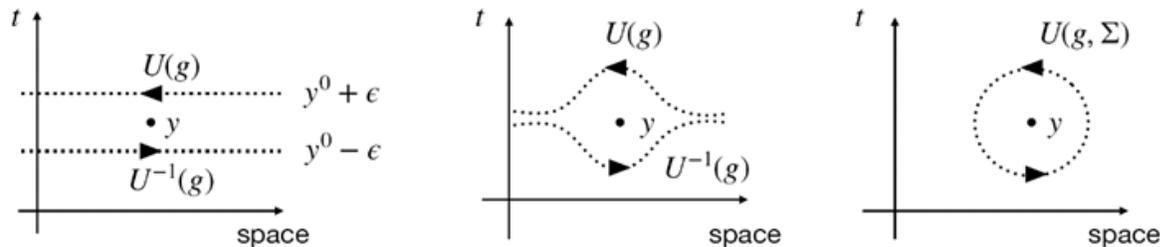
$$Q(\Sigma + \partial\Omega_0) = \int_{\Omega_\Sigma \cup \Omega_0} \langle d * J\phi(y) \rangle = \int_{\Omega_\Sigma} \langle d * J\phi(y) \rangle + \int_{\Omega_0} \langle d * J\phi(y) \rangle$$

$$= \int_{\Omega_\Sigma} \langle d * J\phi(y) \rangle = Q(\Sigma)$$

- 守恒荷 $Q(\Sigma)$ 是拓扑不变量
- 守恒定律 $d * J = 0$ 表述成了算符 $Q(\Sigma)$ 是拓扑不变量

# 对称性的拓扑表述

- $U(g)$  对局域算符的作用,  $\langle U(g)\phi(y)U^{-1}(g) \rangle = R(g)\langle \phi(y) \rangle$
- 如果 $y$ 和 $\Sigma$ 是环绕的, 有
- $\langle U(g, \Sigma)\phi(y) \rangle = R(g)\langle \phi(y) \rangle$ , 其中 $U(g, \Sigma)$ 是与对称群 $g$ 相关联的么正拓扑算符,  $R$ 代表场变换相应的表示,  
 $U(g, \Sigma) = e^{i\alpha_a Q_a}, R(g) = e^{\alpha_a t_a}$ , 其中 $t_a$ 对应于 $\phi$ 所属的表示的生成元
- 这称为0形式对称性, 意味着在对称性下的带荷对象是在一个点, 即在一个0维区域支撑的局域算符 $\phi(y)$



# 广义对称性

- 从普通对称性到高形式对称性

- 经典理论中

$$\delta S = \int d^D x J_a^\mu \partial_\mu \epsilon_a(x)$$

- 经典场的对称性

$$\partial_\mu J_a^\mu = 0, \quad Q_a = \int d^{D-1} x J_a^0 \Rightarrow \frac{d}{dt} Q_a = 0$$

- 经典场论对称变换正则形式

$$\delta \phi_a = \{ \phi, Q_a \}$$

- 量子场论中对称变换的么正算符可以通过Noether 荷构造

$$U = e^{i\epsilon_a Q_a}$$

- 量子场论对称变换正则形式

$$\delta_a \phi = i[Q_a, \phi]$$

# 高形式对称性

- **从0-form到1-form**
- 0-form的全局对称性：在对称性下的带荷对象是在一个点，参数 $\xi$ 是闭合的0-form,  $d\xi = 0$ ; 局域化 $\delta S = \int_{\mathcal{M}^{(D)}} *J \wedge d\xi$ , 其中 $\xi$ 变为局域参数, 即 $d\xi$ 不再是闭合的; 守恒律 $d * J = 0$
- 1-form的全局对称性：参数 $\xi_1 = \xi_\mu dx^\mu$ 是闭合的1-form; 变换的全局性质转化为参数的平坦条件 $\partial_\mu \xi_\nu - \partial_\nu \xi_\mu = 0$ ; 作用量变分 $\delta S = \int_{\mathcal{M}^{(D)}} *J \wedge d\xi_1$ ;  $*J$ 是 $(D-2)$ -form,  $J$ 是2-form; 守恒律 $d * J = 0$ , 分量为 $\partial_\mu J^{\mu\nu} = 0, J^{\mu\nu} = -J^{\nu\mu}$ ;
- 在闭合 $D - 2$ 子流形上可定义守恒荷,  $Q(\Sigma_{D-2}) \equiv \int_{\Sigma_{D-2}} *J$
- 这个对称性算符下的带荷对象, 即与 $\Sigma_{D-2}$ 具有非平凡环绕的对象

# 高形式对称性的带荷算符

- 为理解1形式对称性下带荷对象，对于0形式对称性变换参数 $\xi$ 为常数的无穷小整体局部算符变换为

$$\phi(x) \rightarrow \phi'(x) = \phi(x) + \xi \delta \phi(x)$$

- 用庞加莱对偶将 $(d - p)$ -形式与 $p$ 维流形关联起来 ( $D - 1 = d$ )

- $\xi_{i_{p+1} \dots i_d}(x) \equiv \frac{1}{p!} \int_{\Sigma_p} \epsilon_{i_1 \dots i_p i_{p+1} \dots i_d} \delta^{(d)}(\vec{x} - \vec{y}) dy^{i_1} \wedge \dots \wedge dy^{i_p}$

- 整体对称性的参数为从 $p$ 维子流形构造的 $(d - p)$ 形式 $\xi_{d-p}(\Sigma_p)$ ，自动满足

$$d\xi_{d-p} = 0$$

# 高形式对称性的带荷算符

- $p = d$ 得到 $\xi(x) = \frac{1}{d!} \int_{\Sigma_d} \epsilon_{i_1 \dots i_d} \delta^{(d)}(\vec{x} - \vec{y}) dy^{i_1} \wedge \dots \wedge dy^{i_d} = 1$ 即普通全局对称性的参数是封闭的0形式，在流形的0维区域（点）上支撑，带荷对象为局域算符
- $p = d - 1$ 的庞加莱对偶是一个1形式 $\xi_1(\Sigma_{d-1})$ ，分量为

$$\xi_{i_d}(x) = \frac{1}{(d-1)!} \int_{\Sigma_{d-1}} \epsilon_{i_1 \dots i_{d-1} i_d} \delta^{(d)}(\vec{x} - \vec{y}) dy^{i_1} \wedge \dots \wedge dy^{i_{d-1}}.$$

# 高形式对称性的带荷算符

- 1形式对称性下的带荷对象是沿线支撑的算符，即线算符。所以给定一个沿线  $\mathcal{C}$  支撑的算符，变换的参数是  $\int_{\mathcal{C}} \xi_i(\Sigma_{d-1}) = \int_{\mathcal{C}} \xi_i dx^i$
- 线算符的无穷小变换： $W[C] \rightarrow W[C]' = W[C] + \int_{\mathcal{C}} \xi_i(\Sigma_{d-1}) \delta W[C]$
- 一般对缺陷线的对称变换： $W[C] \rightarrow W[C]' = W[C] + \int_{\mathcal{C}} \xi_1(\Sigma_{D-2}) \delta W[C]$
- 在1-form对称下，带荷物体是线算子。

# 狄拉克量子条件

- 磁单极

$$\mathbf{B} = \frac{g\mathbf{r}}{4\pi r^3} \Rightarrow \int d\mathbf{S} \cdot \mathbf{B} = g$$

- Dirac quantum condition

$$eg = 2\pi\hbar\mathbb{Z}, \quad e_1g_2 - e_2g_1 = 2\pi\hbar\mathbb{Z}$$

- Theta term

$$S_\theta = \frac{\theta e^2}{4\pi^2\hbar} \int d^4x \frac{1}{4} * F^{\mu\nu} F_{\mu\nu} = -\frac{\theta e^2}{4\pi^2\hbar c} \int d^4x \mathbf{E} \cdot \mathbf{B}$$

- 全导数形式的Theta term

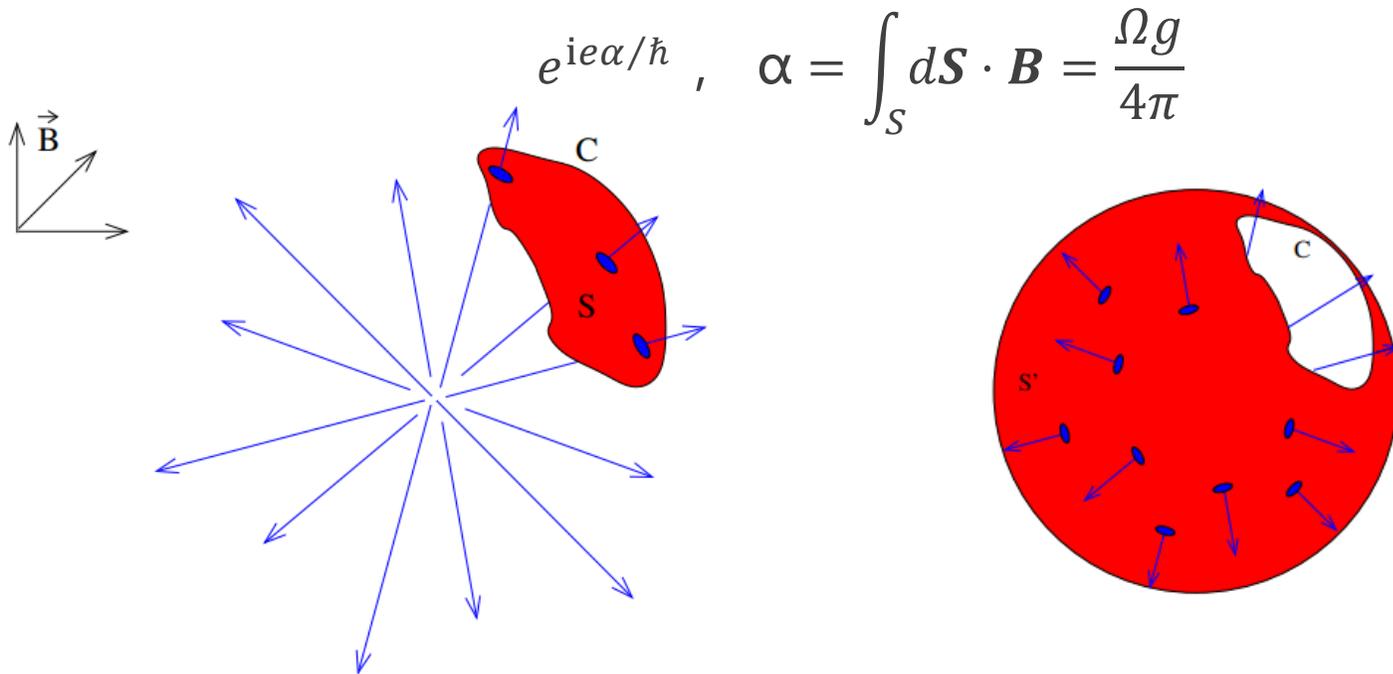
$$S_\theta = \frac{\theta e^2}{8\pi^2\hbar} \int d^4x \partial_\mu (\epsilon^{\mu\nu\rho\sigma} A_\nu \partial_\rho A_\sigma)$$

# 磁单极

- 类似电荷，可以引入磁荷，或称磁单极。类似静电场，磁荷也可以得到磁荷的场

$$\mathbf{B} = \frac{g\hat{\mathbf{r}}}{4\pi r^3} \Rightarrow \int d\mathbf{S} \cdot \mathbf{B} = g$$

- 如果有电荷为 $e$ 的带电粒子，在磁荷为 $g$ 的磁单极背景场中，保持磁单极固定，让带电粒子沿着磁单极外一闭合路径走一圈。如图，走过的路径是包围面积为 $S$ 的边界，立体角为 $\Omega$ ，那么带电粒子获得相位



# 狄拉克量子条件

- 如右图，路径也是 $S'$ 的边界，立体角 $\Omega' = 4\pi - \Omega$ ，则获得相位变成

$$\alpha' = -\frac{(4\pi - \Omega)g}{4\pi}$$

- 两者获得相位必须相等，即 $e^{ie\alpha/\hbar} = e^{ie\alpha'/\hbar}$ 。这就给出Dirac量子条件

$$eg = 2\pi\hbar n, \quad n \in \mathbf{Z}$$

- 相似地，对于两个既携带电荷又带有磁荷的dyon粒子，带荷分别为 $(e_1, g_1)$ 、 $(e_2, g_2)$ ，Dirac量子化条件推广为

$$e_1 g_2 - e_2 g_1 \in 2\pi\hbar \mathbf{Z}$$



# 标准模型

- 标准模型规范群为  $\tilde{G} = SU(3)_C \times SU(2)_L \times U(1)_Y$

| <i>Matter Fields</i> | $SU(3)_C$ | $SU(2)_L$ | $U(1)_Y$ |
|----------------------|-----------|-----------|----------|
| $Q_L$                | 3         | 2         | 1        |
| $U_R$                | 3         | 1         | 4        |
| $D_R$                | 3         | 1         | -2       |
| $L_L$                | 1         | 2         | -3       |
| $E_R$                | 1         | 1         | -6       |
| $H$                  | 1         | 2         | 3        |

标准模型粒子谱

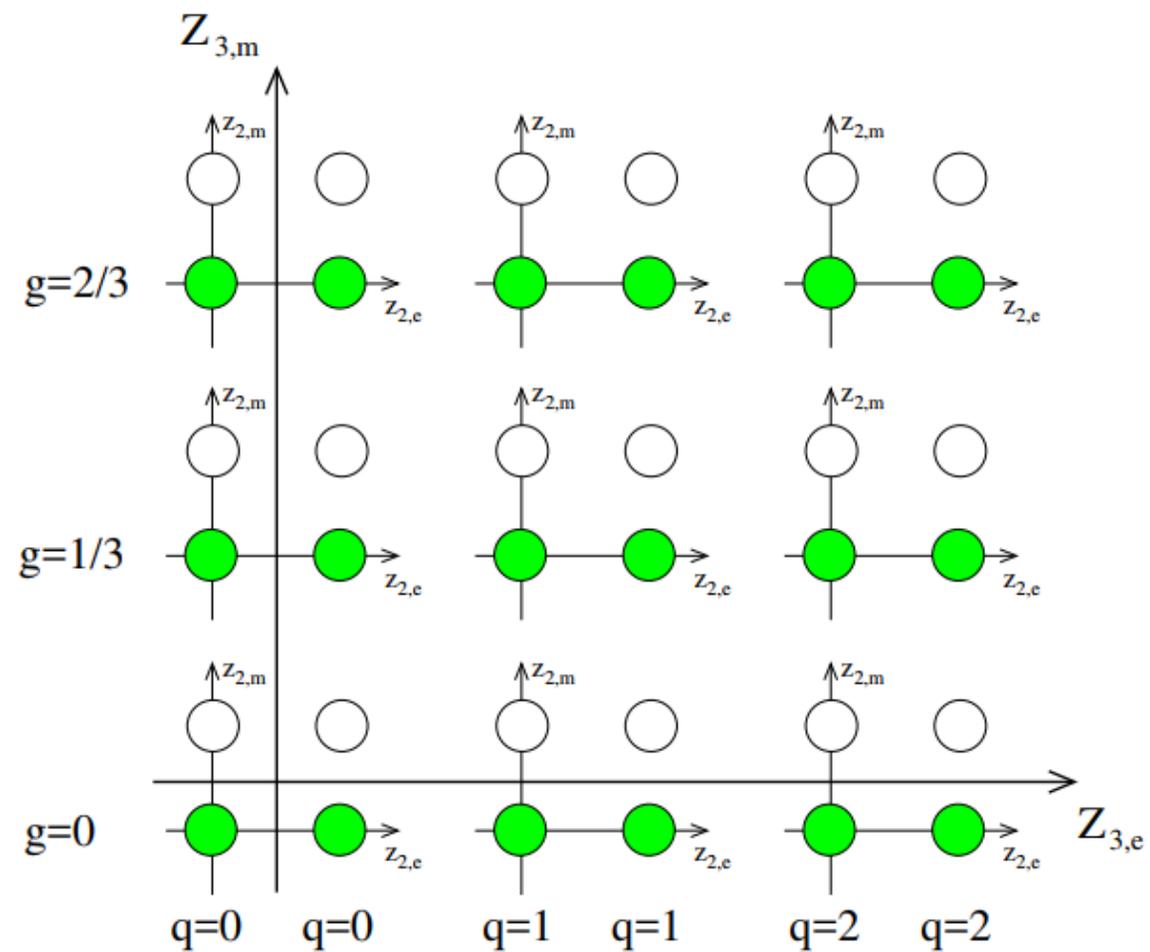
# 标准模型的规范群

- 标准模型规范群可以取为  $G = \tilde{G}/\Gamma$ , 其中  $\Gamma = \mathbf{1}, \mathbf{Z}_2, \mathbf{Z}_3, \mathbf{Z}_6$ , 是  $G$  的中心或中心的子群, 其规范动力学完全相同
- $\Gamma$  的生成元可以写为:  $e^{2i\pi\frac{q}{6}} e^{i\pi z_2^e} e^{\frac{2}{3}i\pi z_3^e}$
- 不同的  $\Gamma$  选择, 规范理论整体性质不同, 其线算子 (Wilson 线, 't Hooft 线) 谱不同
- 线算子 Wilson line:  $W[C] = \text{Tr}_{R_e} P e^{i\oint_C \phi^a}$ , 与表示有关, 可以用权格子空间的点  $z^e$  来标记
- 线算子 't Hooft line:  $T[C] = \text{Tr}_{R_m} P e^{i\oint_C \tilde{\phi}^a}$ , 用根格子空间的点  $z^m$  标记

# 标准模型的线算子

- 一般的线算子既含有电荷又有磁荷，可以用 $(z^e, z^m)$ 来标记
- 标准模型的Wilson line可以用 $(z_2^e, z_3^e, q)$ 标记， 't Hooft line用 $(z_2^m, z_3^m, g)$ 标记
- 它们之间满足Dirac量子化条件： $3z_2^e z_2^m + 2z_3^e z_3^m - 6gq \in 6\mathbf{Z}$
- 对 $G = \tilde{G}/\Gamma$ ，Wilson line在 $\Gamma$ 群元变换下不变（比如：对于 $\Gamma = \mathbf{Z}_3$ ，生成元为 $e^{\frac{2}{3}i\pi q} e^{\frac{2}{3}i\pi z_3^e} = e^{\frac{2}{3}i\pi(q+z_3^e)}$ ，则有 $e^{\frac{2}{3}i\pi(q+z_3^e)} = e^{\frac{4}{3}i\pi(q+z_3^e)} = 1$ 。）可以给出对电荷的约束： $q = z_3^e \text{ mod } 3$
- 通过电荷的约束，求解Dirac量子化条件，可以得到对磁荷的约束： $3g = z_3^m \text{ mod } 3$

# 标准模型的线算子谱



# 标准模型的Theta项

- 规范不变的拉氏量还容许一个表面项，即 $\theta$ 项。对 $U(1) \times SU(N)$

$$S_\theta = \frac{\theta_N}{16\pi^2} \int tr( *f_N f_N ) + \frac{\tilde{\theta}}{16\pi^2} \int *ff$$

- $\Gamma = 1$ 时 $\theta \in [0, 2\pi)$ ， $\theta = 0, \pi$ 理论时间反演不变。
- $\Gamma = \mathbf{Z}_N$ ， $\theta$ 项变为

$$S_\theta = \frac{\theta_N}{16\pi^2} \int tr( *gg ) + \frac{\tilde{\theta} - N\theta_N}{16\pi^2 N^2} \int *(trg)(trg)$$

- $\theta$ 的取值范围会随着 $\Gamma$ 而改变；时间反演不变的 $\theta$ 角会因 $\Gamma$ 不同而不同
- 例如： $\Gamma = \mathbf{Z}_2$ ， $\tilde{\theta} \in [0, 8\pi)$ ， $\tilde{\theta} = 0, 4\pi$ 理论时间反演不变

# G2HDM模型

- 把暗物质纳入规范理论框架，探索新物理需要对标准模型进行拓展
- 规范双希格斯二重态模型 (G2HDM), 规范群:  $\tilde{G} = SU(3)_C \times SU(2)_L \times U(1)_Y \times SU(2)_H \times U(1)_X$

| Matter Fields                  | $SU(3)_C$ | $SU(2)_L$ | $SU(2)_H$ | $U(1)_Y$ | $U(1)_X$ | $h$ -parity |
|--------------------------------|-----------|-----------|-----------|----------|----------|-------------|
| $Q_L = (u_L \ d_L)^T$          | 3         | 2         | 1         | 1/6      | 0        | ++          |
| $U_R = (u_R \ u_R^H)^T$        | 3         | 1         | 2         | 2/3      | 1        | +-          |
| $D_R = (d_R^H \ d_R)^T$        | 3         | 1         | 2         | -1/3     | -1       | -+          |
| $u_L^H$                        | 3         | 1         | 1         | 2/3      | 0        | -           |
| $d_L^H$                        | 3         | 1         | 1         | -1/3     | 0        | -           |
| $L_L = (\nu_L \ e_L)^T$        | 1         | 2         | 1         | -1/2     | 0        | ++          |
| $N_R = (\nu_R \ \nu_R^H)^T$    | 1         | 1         | 2         | 0        | 1        | +-          |
| $E_R = (e_R^H \ e_R)^T$        | 1         | 1         | 2         | -1       | -1       | -+          |
| $\nu_L^H$                      | 1         | 1         | 1         | 0        | 0        | -           |
| $e_L^H$                        | 1         | 1         | 1         | -1       | 0        | -           |
| $H = (H_1 \ H_2)^T$            | 1         | 2         | 2         | 1/2      | 1        | +-          |
| $\Phi_H = (\Phi_1 \ \Phi_2)^T$ | 1         | 1         | 2         | 0        | 1        | -+          |
| $\mathcal{S}$                  | 1         | 1         | 1         | 0        | 0        | +           |

G2HDM的粒子谱

# G2HDM的规范群取法

$$\begin{aligned} G &= \frac{U(1)_Y \times SU(2)_L \times SU(3)_C \times SU(2)_H \times U(1)_X}{\mathbf{Z}_p \times \mathbf{Z}_m} (1) = \frac{U(1)_Y \times SU(2)_H \times SU(3)_C \times SU(2)_L \times U(1)_X}{\mathbf{Z}_p \times \mathbf{Z}_m} (2) \\ &= \frac{U(1)_Y \times SU(2)_L \times SU(3)_C \times SU(2)_H \times U(1)_X}{\mathbf{Z}_p \times \mathbf{Z}_m} (3) = \frac{U(1)_Y \times SU(2)_H \times SU(2)_L \times SU(3)_C \times U(1)_X}{\mathbf{Z}_p \times \mathbf{Z}_m} (4) \\ &= \frac{U(1)_Y \times SU(2)_L \times U(1)_X \times SU(3)_C \times SU(2)_H}{\mathbf{Z}_p \times \mathbf{Z}_m} (5) = \frac{U(1)_Y \times SU(2)_H \times U(1)_X \times SU(3)_C \times SU(2)_L}{\mathbf{Z}_p \times \mathbf{Z}_m} (6) \\ &= \frac{U(1)_Y \times SU(3)_C \times U(1)_X \times SU(2)_L \times SU(2)_H}{\mathbf{Z}_N \times \mathbf{Z}_M \times \mathbf{Z}_P} (7) = \frac{U(1)_Y \times SU(3)_C \times SU(2)_L \times U(1)_X \times SU(2)_H}{\mathbf{Z}_p \times \mathbf{Z}_m} (8) \\ &= \frac{U(1)_Y \times SU(3)_C \times SU(2)_H \times U(1)_X \times SU(2)_L}{\mathbf{Z}_p \times \mathbf{Z}_m} (9) \end{aligned}$$

# G2HDM的Dirac量子条件

- Dirac量子条件:  $-6gq + 3z_2^e z_2^m + 2z_3^e z_3^m + 3x_2^e x_2^m - 6kh = 0 \pmod{6}$
- 以  $G = \frac{U(1)_Y \times SU(2)_L \times SU(3)_C}{\mathbf{Z}_p} \times \frac{SU(2)_H \times U(1)_X}{\mathbf{Z}_m}$  为例
- 可取的中心有  $\Gamma = \mathbf{1}, \mathbf{Z}_{2L}, \mathbf{Z}_{2H}, \mathbf{Z}_3, \mathbf{Z}_{2L} \times \mathbf{Z}_{2H}, \mathbf{Z}_{6L}, \mathbf{Z}_3 \times \mathbf{Z}_{2H}, \mathbf{Z}_{6L} \times \mathbf{Z}_{2H}$  共8种
- 对应生成元有两个  $e^{2i\pi\frac{q}{6}} e^{i\pi z_2^e} e^{\frac{2}{3}i\pi z_3^e}, e^{2i\pi\frac{h}{2}} e^{i\pi x_2^e}$
- 局域动力学在任一中心下不变, 可以给出对电荷的约束
- 通过电荷的约束, 再解Dirac量子化条件, 可以得到对磁荷的约束

# G2HDM的线算子谱

- 以 $\Gamma = \mathbf{Z}_3 \times \mathbf{Z}_{2H}$ 为例, 对应两个生成元分别为

$$e^{\frac{2}{3}i\pi q} e^{\frac{2}{3}i\pi z_3^e} = e^{\frac{2}{3}i\pi(q+z_3^e)}, \quad e^{i\pi x_2^e} e^{i\pi h} = e^{\frac{1}{3}i\pi(3x_2^e+3h)}$$

- 给出对电荷的限制

$$q = z_3^e \bmod 3, \quad h = x_2^e \bmod 2$$

- 给出对磁荷的限制

$$3g = z_3^m \bmod 3, \quad 2k = x_2^m \bmod 2$$

- 以 $\Gamma = \mathbf{Z}_3$ 为例,  $\tilde{\theta} \in [0, 18\pi)$ ,  $\tilde{\theta} = 0, 9\pi$ 理论时间反演不变



# G2HDM的线算子谱

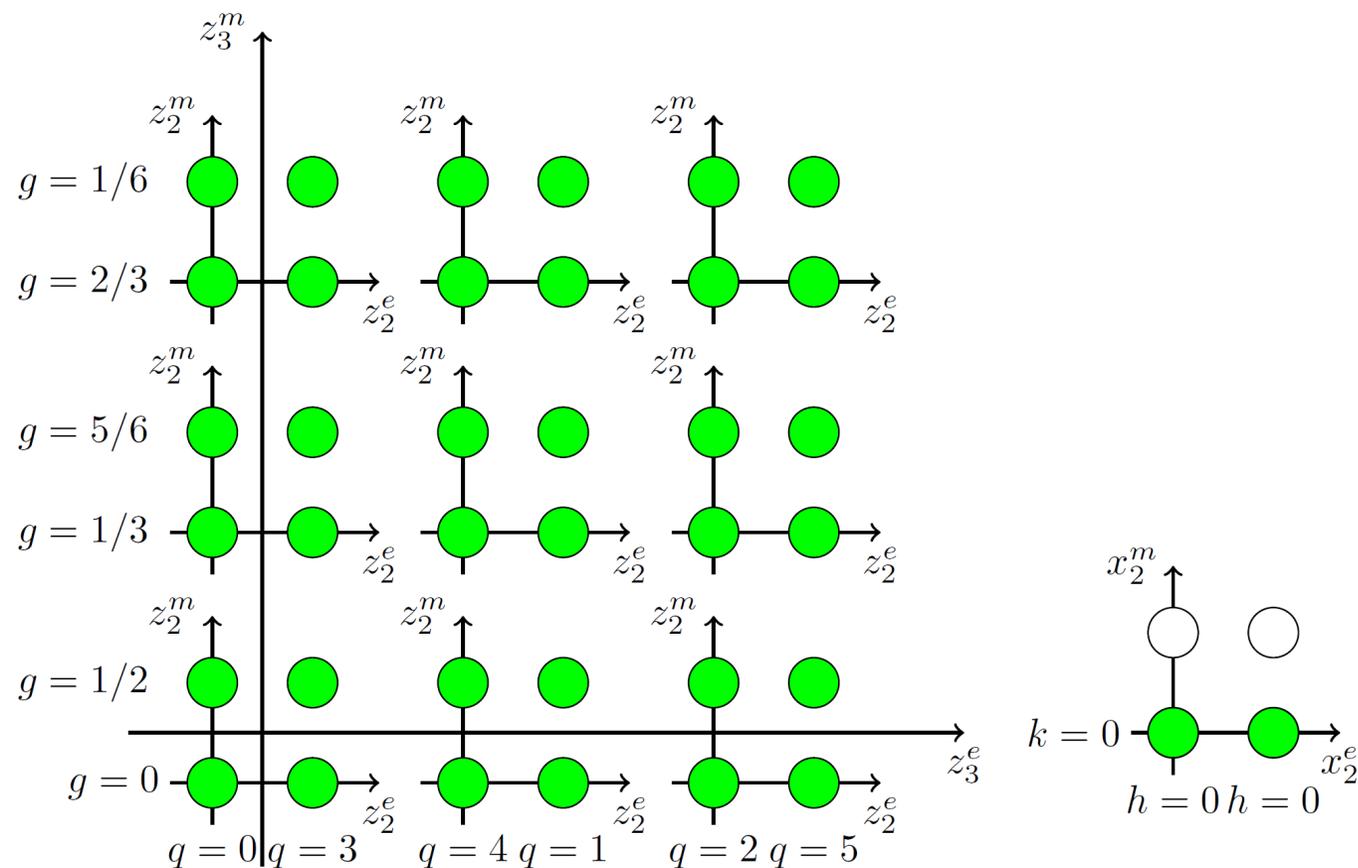
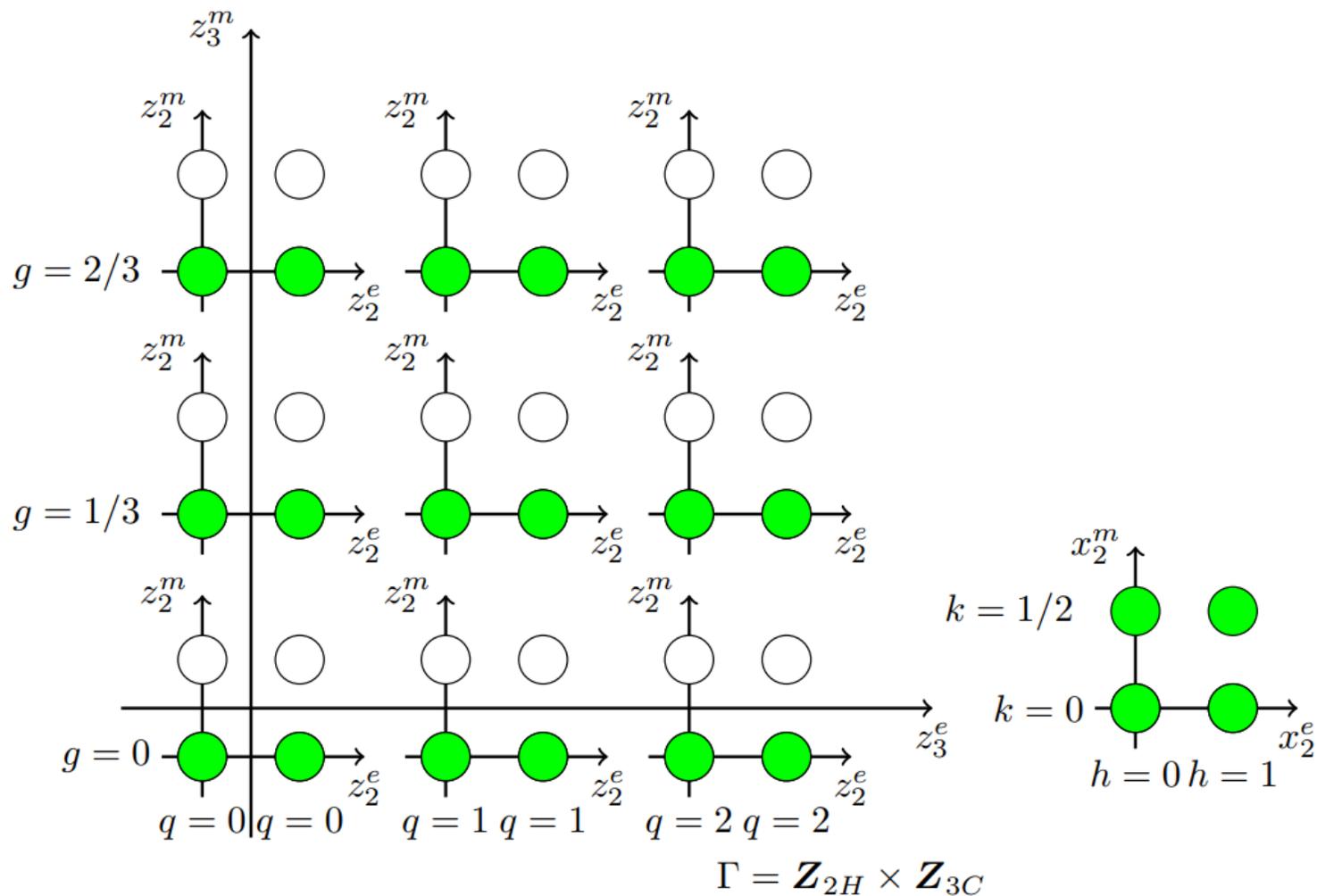


Figure 5:  $\Gamma = \mathbf{Z}_{6L}$

# G2HDM的线算子谱



# G2HDM模型的对称性破缺

- 盖尔曼-西岛关系:  $Q = \frac{q}{6} + \frac{1}{2}z_2^e, Q_X = \frac{h}{2} + \frac{1}{2}x_2^e$
- Higgs $(2,2,1)_{3,1}$ 和 $(1,2,1)_{0,1}$ 确定未破缺的 't Hooft line:  $6g = z_2^m \text{mod} 2, 2k = x_2^m \text{mod} 2$
- 未破缺的 't Hooft line的磁荷:  $G = 6g, G_X = 2k$

# G2HDM模型的对称性自发破缺

*Gellmann Nishijima formula*

$$Q = \frac{q}{6} + \frac{1}{2} \lambda_2^e \quad Q_X = \frac{h}{2} + \frac{1}{2} \rho_2^e$$

$$\text{Dirac quantization condition } -6qg + 3z_2^e z_2^m + 2z_3^e z_3^m + 3x_2^e x_2^m - 6hk = 0 \pmod{6}$$

$$(SU(2)_L, SU(2)_H, SU(3))_{Y,X} \Rightarrow (z_2^e, x_2^e, z_3^e)_{q,h}$$

$$\text{higgs} = (2, 2, 1)_{3,1} \Rightarrow (1, 1, 0)_{3,1} = (z_2^e, x_2^e, z_3^e)_{q,h}$$

$$-6qg + 3z_2^e z_2^m + 3x_2^e x_2^m - 6hk = -6 \times 3g + 3z_2^m + 3x_2^m - 6k = 0 \pmod{6} \Rightarrow -6g + z_2^m + x_2^m - 2k = 0 \pmod{2} \Rightarrow 6g + 2k = (z_2^m + x_2^m) \pmod{2}$$

$$\text{higgs} = (1, 2, 1)_{0,1} \Rightarrow (0, 1, 0)_{0,1} = (z_2^e, x_2^e, z_3^e)_{q,h}$$

$$-6qg + 3z_2^e z_2^m + 3x_2^e x_2^m - 6hk = 3x_2^m - 6k = 0 \pmod{6} \Rightarrow 2k = x_2^m \pmod{2}$$

$$G = 6g = z_2^m \pmod{2} = \lambda_2^m$$

$$G_X = 2k = x_2^m \pmod{2} = \rho_2^m$$

$$-6qg + 3z_2^e z_2^m + 3x_2^e x_2^m - 6hk = 0 \pmod{6} \Rightarrow g \left( -q + \frac{1}{2g} z_2^e z_2^m \right) + k \left( -h + \frac{1}{2k} x_2^e x_2^m \right) = 6g \left( -\frac{q}{6} + \frac{1}{6} \frac{1}{2g} z_2^e z_2^m \right) + 2k \left( -\frac{h}{2} + \frac{1}{2} \frac{1}{2k} x_2^e x_2^m \right)$$

$$= 6g \left( -\frac{q}{6} + \frac{1}{2} z_2^e \right) + 2k \left( -\frac{h}{2} + \frac{1}{2} x_2^e \right) = QG + Q_X G_X$$

# G2HDM模型的对称性自发破缺

$$G = \frac{U(1)_Y \times SU(2)_L \times SU(3)_C}{\mathbf{Z}_N} \times \frac{SU(2)_H \times U(1)_X}{\mathbf{Z}_M}$$

$$Q = \frac{q}{6} + \frac{1}{2} \lambda_2^e \quad Q_X = \frac{h}{2} + \frac{1}{2} \rho_2^e$$

$$G = 6g \quad G_X = 2k$$

$$(SU(2)_L, SU(2)_H, SU(3))_{Y,X} \leftarrow (z_2^e, x_2^e, z_3^e)_{q,h}$$

$$\mathbf{1}: \begin{cases} q \in \mathbf{Z} \Rightarrow Q = \frac{1}{6} + 0 = \frac{1}{6} \Rightarrow (1,1,1)_{1,0} \Rightarrow (Q_X = 0); g \in \mathbf{Z} \Rightarrow G = 6; \lambda_2^m = 6 \\ h \in \mathbf{Z} \Rightarrow Q_X = \frac{1}{2} + 0 = \frac{1}{2} \Rightarrow (1,1,1)_{0,1} \Rightarrow (Q = 0); k \in \mathbf{Z} \Rightarrow G_X = 2; \rho_2^m = 2 \end{cases}$$

$$\mathbf{Z}_{2L}: \begin{cases} q = z_2^e \bmod 2; z_2^e = 0,1 \Rightarrow Q = \frac{2}{6} + 0 = \frac{1}{3} \Rightarrow (1,1,1)_{2,0} \Rightarrow (Q_X = 0); g - 2z_2^m = 0 \bmod 2; z_2^m = 0,1 \bmod 2 \Rightarrow G = 3; \lambda_2^m = 3 \\ Q_X = \frac{1}{2} \Rightarrow (1,1,1)_{0,1} \Rightarrow (Q = 0); G_X = 2; \rho_2^m = 2 \end{cases}$$

$$\mathbf{Z}_{2H}: \begin{cases} Q = \frac{1}{6} \Rightarrow (1,1,1)_{1,0} \Rightarrow (Q_X = 0); G = 6; \lambda_2^m = 6 \\ h = x_2^e \bmod 2; x_2^e = 0,1 \Rightarrow Q_X = \frac{2}{2} + 0 = 1 \Rightarrow (1,1,1)_{0,2} \Rightarrow (Q = 0); k - 2x_2^m = 0 \bmod 2; x_2^m = 0,1 \bmod 2 \Rightarrow G_X = 1; \rho_2^m = 1 \end{cases}$$

# G2HDM模型的对称性自发破缺

$$\mathbf{Z}_{3C} : \begin{cases} q = z_3^e \bmod 3; z_3^e = 0, 1, 2 \Rightarrow Q = \frac{1}{6} + 0 = \frac{1}{6} \Rightarrow (1, 1, 3)_{1,0} \Rightarrow (Q_X = 0); g - 3z_3^m = 0 \bmod 3; z_3^m = 0, 1, 2 \bmod 3 \Rightarrow G = 2; \lambda_2^m = 2 \\ Q_X = 1 \Rightarrow (1, 1, 1)_{0,1} \Rightarrow (Q = 0); G_X = 2; \rho_2^m = 6 \end{cases}$$

$$\mathbf{Z}_{2L} \times \mathbf{Z}_{2H} : \begin{cases} Q = \frac{1}{3} \Rightarrow (1, 1, 1)_{2,0} \Rightarrow (Q_X = 0); G = 3, \lambda_2^m = 3 \\ Q_X = 1 \Rightarrow (1, 1, 1)_{0,2} \Rightarrow (Q = 0); G_X = 1, \rho_2^m = 1 \end{cases}$$

$$\mathbf{Z}_6 : \begin{cases} q = (3z_2^e - 2z_3^e) \bmod 6; z_2^e = 0, 1; z_3^e = 0, 1, 2 \Rightarrow Q = \frac{2}{6} + 0 = \frac{1}{3} \Rightarrow (1, 1, 3)_{2,0} \Rightarrow (Q_X = 0); 6g = (3z_2^m + 2z_3^m) \bmod 6; z_2^m = 0, 1 \bmod 2; z_3^m = 0, 1, 2 \bmod 3 \Rightarrow G = 1; \lambda_2^m = 1 \\ Q_X = \frac{1}{2} \Rightarrow (1, 1, 1)_{0,1} \Rightarrow (Q = 0); G_X = 2; \rho_2^m = 2 \end{cases}$$

$$\mathbf{Z}_{2H} \times \mathbf{Z}_{3C} : \begin{cases} Q = \frac{1}{6} \Rightarrow (1, 1, 3)_{1,0} \Rightarrow (Q_X = 0); G = 2, \lambda_2^m = 2 \\ Q_X = 1 \Rightarrow (1, 1, 1)_{0,2} \Rightarrow (Q = 0); G_X = 1, \rho_2^m = 1 \end{cases}$$

$$\mathbf{Z}_{2H} \times \mathbf{Z}_6 : \begin{cases} Q = \frac{1}{6} \Rightarrow (1, 1, 3)_{2,0} \Rightarrow (Q_X = 0); G = 1, \lambda_2^m = 1 \\ Q_X = 1 \Rightarrow (1, 1, 1)_{0,2} \Rightarrow (Q = 0); G_X = 1, \rho_2^m = 1 \end{cases}$$

# G2HDM模型的Theta角

- how the line operators vary under the  $\theta$  angle. There are 5 such angles, calling  $\tilde{\theta}, \theta_2, \theta_3, \tilde{\omega}$  and  $\omega_2$ , for  $U(1)_Y, SU(2)_L, SU(3)_C, U(1)_X$  and  $SU(2)_H$ , respectively.
- the quotient gauge group of the G2HDM could be divided into two categories.  

$$\frac{U(1) \times \dots}{Z_N} \times \frac{U(1) \times \dots}{Z_M} \times \dots \text{ or } \frac{U(1) \times U(1) \times \dots}{Z_N} \times \dots$$
- Theta terms of the G2HDM
- $$S_\theta = \frac{\tilde{\theta}}{16\pi^2} \int dx^4 \widetilde{*f\tilde{f}} + \frac{3\theta_2}{16\pi^2} \int dx^4 tr(*f_2 f_2) + \frac{2\theta_3}{16\pi^2} \int dx^4 tr(*f_3 f_3) + \frac{\tilde{\omega}}{16\pi^2} \int dx^4 \widetilde{*g\tilde{g}} + \frac{\omega_2}{16\pi^2} \int dx^4 tr(*g g)$$
- Where  $\tilde{f}, f_2, f_3$  are the strength of  $U(1)_Y, SU(2)_L, SU(3)_C$  field, respectively. And  $\tilde{g}, g$  for  $U(1)_X$  and  $SU(2)_H$ , respectively.

# G<sub>2</sub>HDM模型的Theta角

- Theta terms of  $\frac{U(1) \times SU(N)}{Z_N}$  theory are
- $S_\theta = \frac{\theta_N}{16\pi^2} \int d^4x \text{tr}(*FF) + \frac{\tilde{\theta} - N\theta_N}{16\pi^2 N^2} \int d^4x *(\text{tr}F)(\text{tr}F)$
- Strength  $F$  derived from field  $a + \tilde{a}1_N$ .  $a$  and  $\tilde{a}$  are  $U(1)$  and  $SU(N)$  gauge fields, respectively.  $\theta_N \in [0, 2\pi)$ ,  $\tilde{\theta} \in [0, 2\pi N^2)$ , now.
- Consider  $\frac{U(1) \times SU(N) \times SU(M)}{Z_{N \times M}}$ . Theta terms of  $U(1) \times SU(N) \times SU(M)$  theory are
- $S_\theta = \frac{M\theta_N}{16\pi^2} \int dx^4 \text{tr}(*f_N 1_M f_N 1_M) + \frac{N\theta_M}{16\pi^2} \int dx^4 \text{tr}(*f_M 1_N f_M 1_N) + \frac{\tilde{\theta}}{16\pi^2} \int dx^4 *f\tilde{f}$

# G2HDM模型的Theta角

- To describe this new  $U(N \times M)$  gauge theory, we introduce two gauge fields  $a_N + \tilde{a}1_N$  and  $a_M + \tilde{a}1_M$ . Then, we could obtain the strength of these two fields  $F_N = f_N + \tilde{f}1_N$  and  $F_M = f_M + \tilde{f}1_M$ . Theta terms for  $\frac{U(1) \times SU(N) \times SU(M)}{Z_{N \times M}}$  theory are
- $$S_\theta = \frac{M\theta_N}{16\pi^2} \int dx^4 tr( {}^*F_N 1_M F_N 1_M ) + \frac{N\theta_M}{16\pi^2} \int dx^4 tr( {}^*F_M 1_N F_M 1_N ) + \frac{\tilde{\theta} - NM^2\theta_N - MN^2\theta_M}{16\pi^2(N \times M)^2} \int dx^4 {}^*tr(\tilde{f}1_{N \times M})tr(\tilde{f}1_{N \times M})$$
- $tr(\tilde{f}1_{N \times M})$  the last term equals to  $tr(F_N 1_M)$  or  $tr(F_M 1_N)$ . We can find that  $\theta_N \in [0, 2\pi), \theta_M \in [0, 2\pi)$  while  $\tilde{\theta} \in [0, 2\pi N^2 M^2)$

# G<sub>2</sub>HDM模型的Theta角

- What if there are two  $U(1)$  gauge group in the denominator of the quotient group? Theta terms for  $U(1)_Y \times U(1)_X \times SU(N)$  gauge theory are

- $$S_\theta = \frac{\theta_N}{16\pi^2} \int dx^4 \text{tr}(\star f_N f_N) + \frac{\tilde{\theta}}{16\pi^2} \int dx^4 \star \tilde{f} \tilde{f} + \frac{\tilde{\omega}}{16\pi^2} \int dx^4 \star \tilde{g} \tilde{g}$$

- We introduce two gauge fields, and  $a_N + \tilde{b}1_N$ . Where  $\tilde{b}$  is  $U(1)_X$  gauge field whose strength is  $\tilde{g}$ , and  $a_N$  is  $SU(N)$  gauge field whose strength is  $f_N$ . Then, we can obtain the strength of these two fields

- $F = f_N + \tilde{f}1_N$  and  $G = f_N + \tilde{g}1_N$

# G<sub>2</sub>HDM模型的Theta角

- So, the theta terms for  $\frac{U(1)_Y \times U(1)_X \times SU(N)}{Z_N}$  can then be written as
- $$S_\theta = \frac{\theta_N}{16\pi^2} \frac{1}{2} \int dx^4 [tr(*FF) + tr(*GG)] +$$

$$\frac{\tilde{\theta} - \frac{N\theta_N}{2}}{16\pi^2 N^2} \int dx^4 *tr(\tilde{f}1_N)tr(\tilde{f}1_N) + \frac{\tilde{\omega} - \frac{N\theta_N}{2}}{16\pi^2 N^2} \int dx^4 *tr(\tilde{g}1_N)tr(\tilde{g}1_N)$$
- Where  $tr(\tilde{f}1_N)$  equals to  $trF$ , and  $tr(\tilde{g}1_N)$  equals to  $trG$ . From this equation, we get  $\theta \in [0, 2\pi)$  while  $\tilde{\theta} \in [0, 2\pi N^2)$  and  $\tilde{\omega} \in [0, 2\pi N^2)$ .

# G2HDM模型的Theta角

- for  $\frac{U(1)_Y \times U(1)_X \times SU(N) \times SU(M)}{Z_{N \times M}}$  gauge theory. Theta terms for  $U(1)_Y \times U(1)_X \times SU(N) \times SU(M)$  are
- $S_\theta = \frac{M\theta_N}{16\pi^2} \int dx^4 tr( *f_N 1_M f_N 1_M ) + \frac{N\theta_M}{16\pi^2} \int dx^4 tr( *f_M 1_N f_M 1_N ) + \frac{\tilde{\theta}}{16\pi^2} \int dx^4 \widetilde{*f} \tilde{f} + \frac{\tilde{\omega}}{16\pi^2} \int dx^4 \widetilde{*g} \tilde{g}$
- There are four canonically normalized gauge fields that introduced, that  $a_N + \tilde{a}1_N, a_N + \tilde{b}1_N, a_M + \tilde{a}1_M$  and  $a_M + \tilde{b}1_M$ . The strength of these fields are
- $F_N = f_N + \tilde{f}1_N, G_N = f_N + \tilde{g}1_N, F_M = f_M + \tilde{f}1_M$  and  $G_M = g_M + \tilde{g}1_M$
- respectively.

# G2HDM模型的Theta角

- the theta terms become  $S_\theta = \frac{M\theta_N}{16\pi^2} \frac{1}{2} \int dx^4 [ {}^*tr(F_N 1_M F_N 1_M) + tr( {}^*G_N 1_M G_N 1_M ) ] + \frac{\theta_M}{16\pi^2} \frac{1}{2} \int [ tr( {}^*F_M 1_N F_M 1_N ) + tr( {}^*G_M 1_N G_M 1_N ) ] +$

$$\frac{\tilde{\theta}}{N^2 M^2} - \frac{1}{2} \frac{\theta_N}{N} - \frac{1}{2} \frac{\theta_M}{M} \int dx^4 {}^*tr(\tilde{f} 1_{N \times M}) tr(\tilde{f} 1_{N \times M})$$

$$+ \frac{\tilde{\omega}}{N^2 M^2} - \frac{1}{2} \frac{\theta_N}{N} - \frac{1}{2} \frac{\theta_M}{M} \int dx^4 {}^*tr(\tilde{g} 1_{N \times M}) tr(\tilde{g} 1_{N \times M})$$
- Where  $tr(\tilde{f} 1_{N \times M})$  equals to  $tr(F_N 1_M)$  and  $tr(F_M 1_N)$ ,  $tr(\tilde{g} 1_{N \times M})$  equals to  $tr(G_N 1_M)$  and  $tr(G_M 1_N)$ . We can tell that  $\theta_N, \theta_M \in [0, 2\pi)$  while  $\tilde{\theta} \in [0, 2\pi N^2 M^2)$  and  $\tilde{\omega} \in [0, 2\pi N^2 M^2)$

# G<sub>2</sub>HDM模型CP不变Theta角

- For different quotients, there are different kind of theta terms.
- $G = \frac{U(1)_Y \times SU(2)_L \times SU(3)_C}{Z_N} \times \frac{SU(2)_H \times U(1)_X}{Z_M}$
- Take  $\Gamma = Z_{2L} \times Z_{2H}$  for example. There are two  $U(2)$   $\theta$  angles, say  $\tilde{\theta}$  and  $\tilde{\omega}$ . In which,  $\theta_3 = 0, \pi$ . Here, when  $\theta_2 = 0$ , it has  $\tilde{\theta} = 0, 4\pi$ ; when  $\theta_2 = \pi$ , it has  $\tilde{\theta} = 2\pi, 6\pi$ . Meanwhile, it has  $\tilde{\omega} = 0, 4\pi$  when  $\omega_2 = 0$  and  $\tilde{\omega} = 2\pi, 6\pi$  when  $\omega_2 = \pi$ . All of these are CP invariant, like the theories of  $\Gamma = Z_{2L}$  and  $\Gamma = Z_{2H}$

# Conclusion and outlook

- The spectrum of line operator in G2HDM model is obtained for all the possible cases
- The variation of Theta angles under different center group is presented for all the possible cases
- The spectrum of line operator under spontaneously symmetry breaking is discussed for all the possible cases
- The similar treatment to the left-right symmetric model of electro-weak interaction with  $\tilde{G} = (SU(3) \times SU(2)_L \times U(1)_{B-L}) \times SU(2)_R$  is in progress
- The inclusion of axion couplings can result the non-invertible symmetry
- THANKS