

Diffusion models for lattice field theory

Gert Aarts

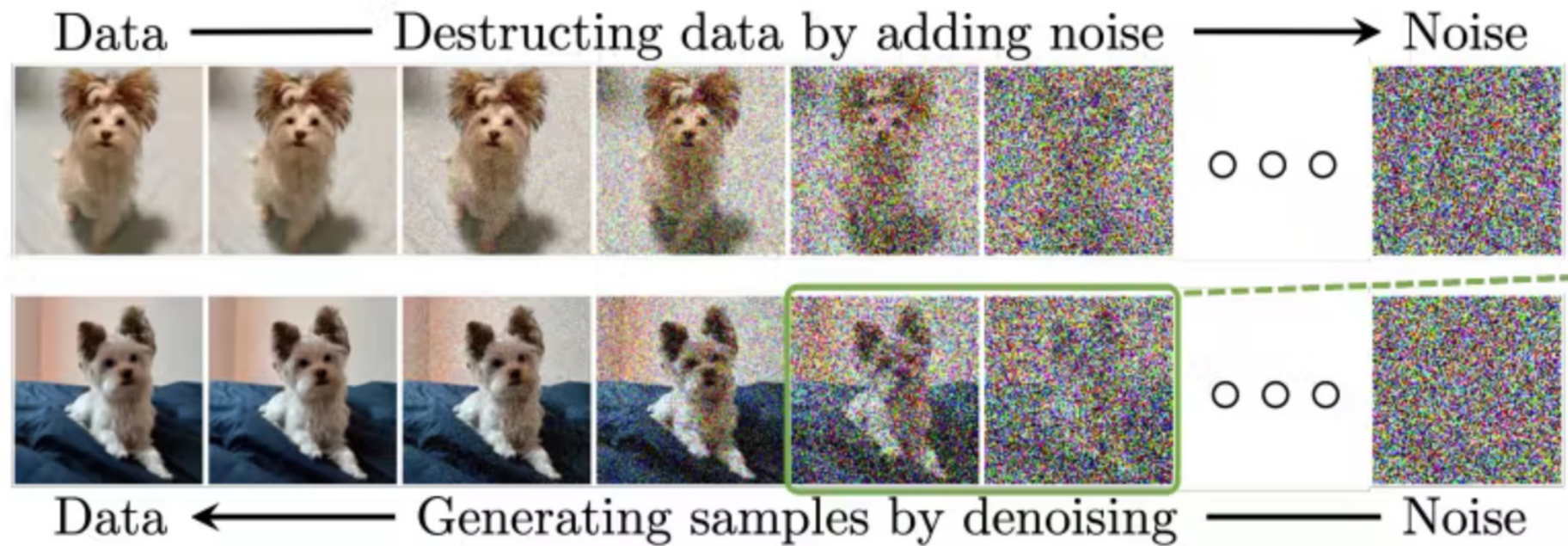
with Lingxiao Wang, Kai Zhou, [Qianteng Zhu](#), Wei Wang and [Diaa Habibi](#)

L Wang, GA, K Zhou, JHEP 05 (2024) 060 [[2309.17082](#) [hep-lat]]

GA, D Habibi, L Wang, K Zhou, Mach.Learn.Sci.Tech. **6** (2025) 2, 025004 [[arXiv:2410.21212](#) [hep-lat]]

Q Zhu, W Wang, GA, K Zhou, L Wang, [2502.05504](#) [hep-lat]

Generative AI using diffusion models



denoising

Generative Modeling by Estimating Gradients of the Data Distribution

Yang Song, Stefano Ermon

[1907.05600](#) [cs.LG]



interpolation

Score-Based Generative Modeling through Stochastic Differential Equations

Yang Song, Jascha Sohl-Dickstein, Diederik P. Kingma, Abhishek Kumar, Stefano Ermon, Ben Poole, [2011.13456](#) [cs.LG]

Motivation: lattice field theory

- generating configurations is one of the bottlenecks in lattice field theory
- images are two-dimensional configurations from some unknown probability distribution
- machine learning algorithms are usually fast and flexible
- we know the distribution $\sim e^{-S}$: can we incorporate ML algorithms in LFT?

Flow-based generative models for Markov chain Monte Carlo in lattice field theory

MS Albergo, G Kanwar, PE Shanahan, Phys. Rev. D 100 (2019) 3, 034515 [[1904.12072 \[hep-lat\]](#)]

Applications of machine learning to lattice quantum field theory

D Boyda, et al, Snowmass 2021, [2202.05838 \[hep-lat\]](#)

Advances in machine-learning-based sampling motivated by lattice quantum chromodynamics

K Cranmer, G Kanwar, S Racanière, DJ Rezende, PE Shanahan, Nature Rev. Phys. 5, 526 (2023)

Physics-driven learning for inverse problems in QCD

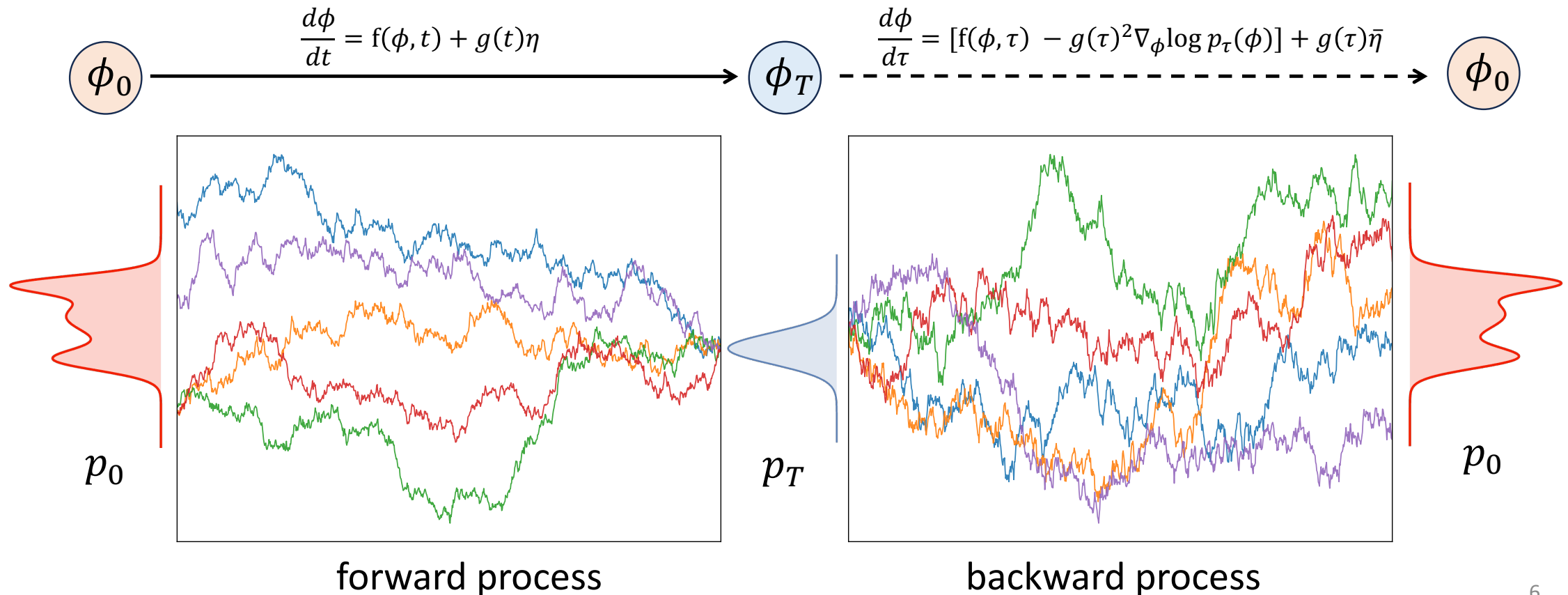
G Aarts, K Fukushima, T Hatsuda, A Ipp, S Shi, L Wang, K Zhou, Nature Rev. Phys. 7 (2025) 154 [[2501.05580 \[hep-lat\]](#)]

Outline

- diffusion models as stochastic processes
- relation to stochastic quantisation
- theoretical analysis of evolution of cumulants
- recent variations and improvements:
 - Metropolis adjusted Langevin algorithm (MALA) / annealing / physics conditioning
 - applied to $U(1)$ gauge theory in two dimensions

Diffusion models: prior and target distributions

- in pictures: p_0 is target (non-trivial), p_T is the prior (easy)



Diffusion models and stochastic quantisation

- images/configurations are generated during backward process
- stochastic process with time-dependent drift and noise strength

$$\frac{\partial \phi(x, \tau)}{\partial \tau} = g^2(\tau) \nabla_{\phi} \log P(\phi; \tau) + g(\tau) \eta(x, \tau)$$

- write $P(\phi; \tau) = \frac{e^{-S(\phi, \tau)}}{Z}$ such that $\nabla_{\phi} \log P(\phi, \tau) = -\nabla_{\phi} S(\phi, \tau)$

- then
$$\frac{\partial \phi(x, \tau)}{\partial \tau} = -g^2(\tau) \nabla_{\phi} S(\phi, \tau) + g(\tau) \eta(x, \tau)$$

Diffusion models and stochastic quantisation

- then
$$\frac{\partial \phi(x, \tau)}{\partial \tau} = -g^2(\tau) \nabla_{\phi} S(\phi, \tau) + g(\tau) \eta(x, \tau)$$
- very familiar to (lattice) field theorists
- stochastic quantisation (Parisi & Wu 1980)
- path integral quantisation via a stochastic process in fictitious time
$$\frac{\partial \phi(x, \tau)}{\partial \tau} = -\nabla_{\phi} S(\phi) + \sqrt{2} \eta(x, \tau)$$
- stationary solution of associated Fokker-Planck equation $P(\phi) \sim e^{-S(\phi)}$

Diffusion models and stochastic quantisation

$$\frac{\partial \phi(x, \tau)}{\partial \tau} = g^2(\tau) \nabla_{\phi} \log P(\phi; \tau) + g(\tau) \eta(x, \tau)$$

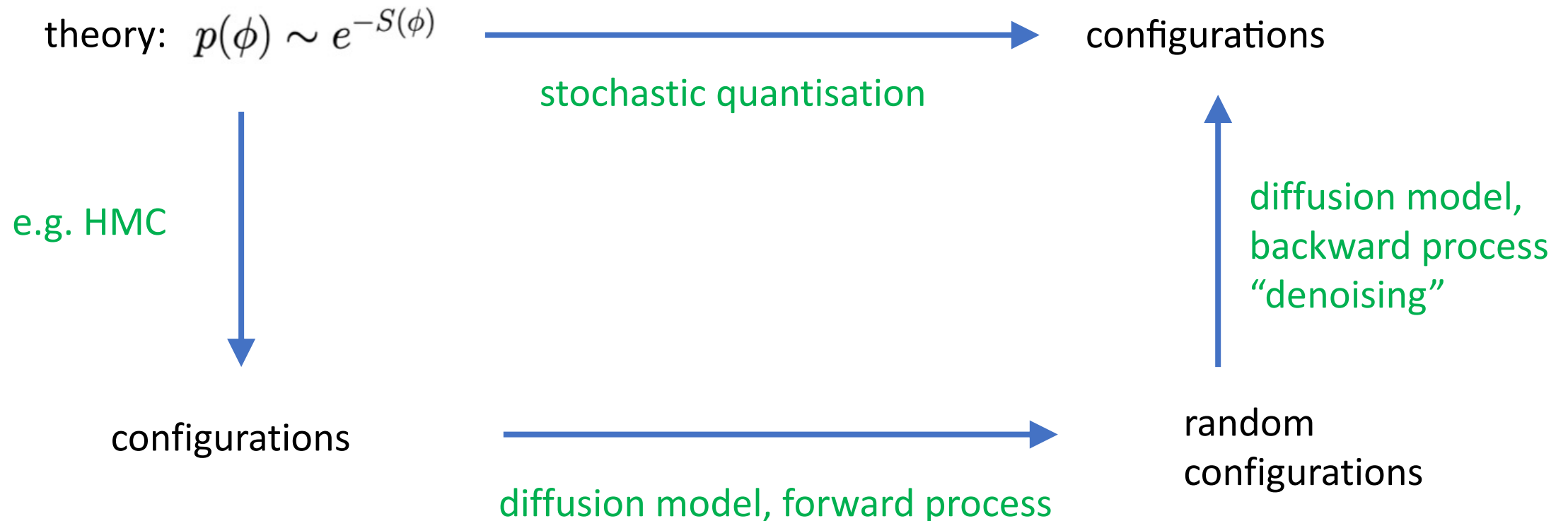
$$\frac{\partial \phi(x, \tau)}{\partial \tau} = -\nabla_{\phi} S(\phi) + \sqrt{2} \eta(x, \tau)$$

similarities and differences:

- ✓ SQ: fixed drift, determined from known action
constant noise variance (but can be generalised using kernels)
thermalisation followed by long-term evolution in equilibrium
- ✓ DM: drift and noise variance time-dependent, learn from data
evolution between $0 \leq \tau \leq T = 1$, many short runs

Diffusion models and stochastic quantisation

- diffusion models as an alternative approach to stochastic quantisation



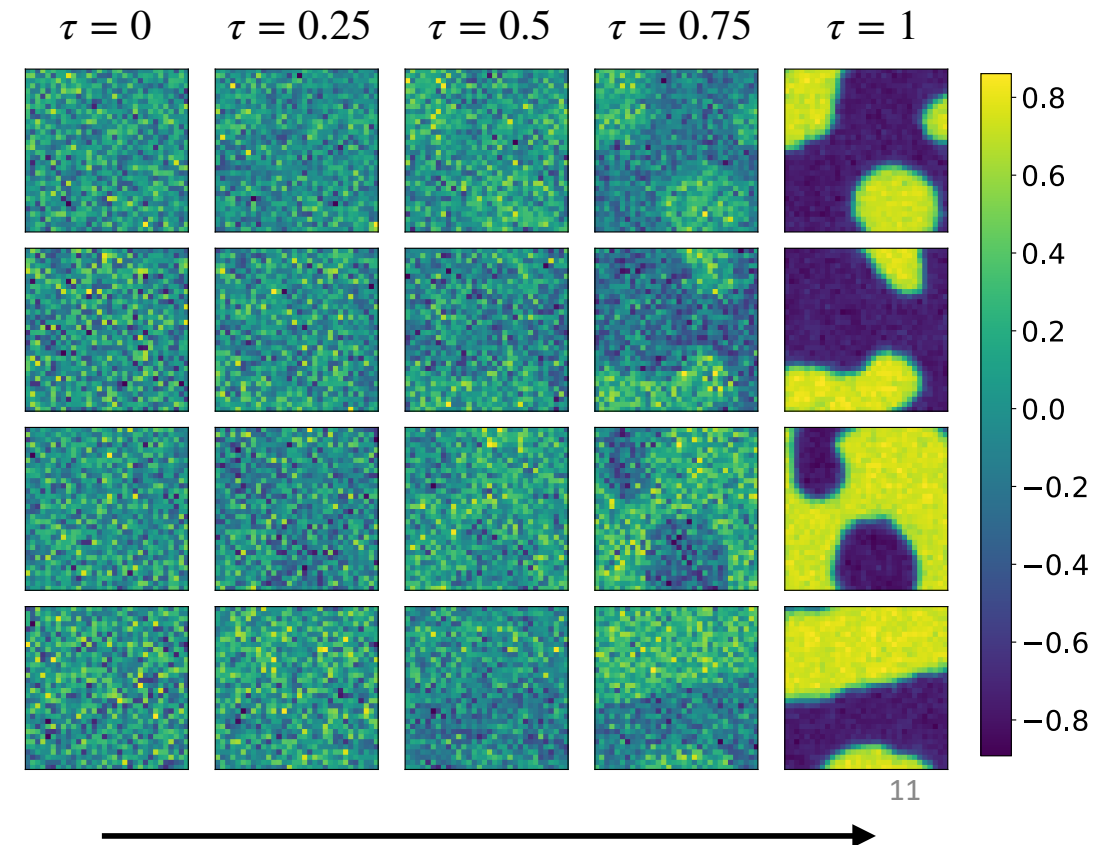
Diffusion model for 2d ϕ^4 lattice scalar theory

- 32^2 lattice, choice of action parameters in symmetric and broken phase
- training data set generated using Hybrid Monte Carlo (HMC)

- first application of diffusion models in lattice field theory

generating configurations:

- broken phase
- “denoising” (backward process)
- large-scale clusters emerge, as expected



Diffusion models: generation of correlations

- forward process $\dot{x}(t) = K(x(t), t) + g(t)\eta(t)$ $0 \leq t \leq T$

noise profile $g(t) = \sigma^{t/T}$

- backward process

$$x'(\tau) = -K(x(\tau), T - \tau) + g^2(T - \tau) \partial_x \log P(x, T - \tau) + g(T - \tau) \eta(\tau)$$

score

$$\tau = T - t$$

two main schemes

- variance-expanding (VE): no drift $K(x, t) = 0$
- variance-preserving (VP) or denoising diffusion probabilistic models (DDPMs):

linear drift $K(x(t), t) = -\frac{1}{2}k(t)x(t)$

$$x_0 \rightarrow x_0 - \mathbb{E}_{P_0}[x_0]$$

Solve forward process

- forward process $\dot{x}(t) = K(x(t), t) + g(t)\eta(t)$ $K(x(t), t) = -\frac{1}{2}k(t)x(t)$
- initial data from target ensemble $x_0 \sim P_0(x_0)$
- solution $x(t) = x_0 f(t, 0) + \int_0^t ds f(t, s)g(s)\eta(s)$ $f(t, s) = e^{-\frac{1}{2} \int_s^t ds' k(s')}$
- second moment/cumulant/variance $\kappa_2(t) = \mu_2(t) = \mu_2(0)f^2(t, 0) + \Xi(t)$

$$\Xi(t) = \int_0^t ds \int_0^t ds' f(t, s)f(t, s')g(s)g(s')\mathbb{E}_\eta[\eta(s)\eta(s')] = \int_0^t ds f^2(t, s)g^2(s)$$

$$f(t, s) = e^{-\frac{1}{2} \int_s^t ds' k(s')}$$

Higher-order moments and cumulants

- moments $\mu_n(t) = \mathbb{E}[x^n(t)]$ and cumulants $\kappa_n(t)$: straightforward algebra

$$\kappa_3(t) = \mu_3(t) = \kappa_3(0)f^3(t, 0)$$

$$\mu_4(t) = \mu_4(0)f^4(t, 0) + 6\mu_2(0)f^2(t, 0)\Xi(t) + 3\Xi^2(t)$$

$$\kappa_4(t) = \mu_4(t) - 3\mu_2^2(t) = [\mu_4(0) - 3\mu_2^2(0)] f^4(t, 0) = \kappa_4(0)f^4(t, 0)$$

$$\kappa_5(t) = [\mu_5(0) - 10\mu_3(0)\mu_2(0)] f^5(t, 0) = \kappa_5(0)f^5(t, 0)$$

→ $\kappa_{n>2}(t) = \kappa_n(0)f^n(t, 0)$

variance-expanding
scheme: no drift

$$f(t, 0) = 1$$

higher cumulants
conserved!

$$\Xi(t) = \int_0^t ds f^2(t, s) g^2(s)$$

Proof to all orders

- generating functionals: average over both noise and target distributions

moments $Z[J] = \mathbb{E}[e^{J(t)x(t)}]$

cumulants $W[J] = \log Z[J]$

- noise average $Z_\eta[J] = \mathbb{E}_\eta[e^{J(t)x(t)}] = \frac{\int D\eta e^{-\frac{1}{2} \int_0^t ds \eta^2(s) + J(t)[x_0 f(t,0) + \int_0^t ds f(t,s)g(s)\eta(s)]}}{\int D\eta e^{-\frac{1}{2} \int_0^t ds \eta^2(s)}}$

- full average $Z[J] = \mathbb{E}[e^{J(t)x(t)}] = e^{\frac{1}{2} J^2(t) \Xi(t)} \int dx_0 P_0(x_0) e^{J(t)x_0 f(t,0)}$

- cumulant generator $W[J] = \log Z[J] = \frac{1}{2} J^2(t) \Xi(t) + \log \int dx_0 P_0(x_0) e^{J(t)x_0 f(t,0)}$

$$f(t, s) = e^{-\frac{1}{2} \int_s^t ds' k(s')}$$

$$\Xi(t) = \int_0^T ds f^2(t, s) g^2(s)$$

Proof to all orders: cumulants

- cumulant generator $W[J] = \log Z[J] = \frac{1}{2} J^2(t) \Xi(t) + \log \int dx_0 P_0(x_0) e^{J(t)x_0 f(t,0)}$
- 2nd cumulant $\kappa_2(t) = \left. \frac{d^2 W[J]}{dJ(t)^2} \right|_{J=0} = \Xi(t) + \mathbb{E}_{P_0}[x_0^2] f^2(t, 0) \quad \checkmark$
- higher-order cumulants $\kappa_{n>2}(t) = \left. \frac{d^n W[J]}{dJ(t)^n} \right|_{J=0} = \frac{d^n}{dJ(t)^n} \log \mathbb{E}_{P_0}[e^{J(t)x_0 f(t,0)}] \Big|_{J=0} = \kappa_n(0) f^n(t, 0) \quad \checkmark$

Two-dimensional scalar fields

extension to scalar fields trivial: each lattice point is treated separately

- forward $\partial_t \phi(x, t) = K[\phi(x, t), t] + g(t)\eta(x, t)$
- backward $\partial_\tau \phi(x, \tau) = -K[\phi(x, \tau), T - \tau] + g^2(T - \tau)\nabla_\phi \log P(\phi, T - \tau) + g(T - \tau)\eta(x, \tau)$
- two-point function $G(x, y; t) \equiv \mathbb{E}[\phi(x, t)\phi(y, t)] = \mathbb{E}_{P_0}[\phi_0(x)\phi_0(y)]f^2(t, 0) + \Xi(t)\delta(x - y)$
- moments $\mu_n(x, t) = \mathbb{E}[\phi^n(x, t)]$ independent of x

$$\Xi(t) = \int_0^t ds f^2(t, s) g^2(s)$$

Generating functionals

full path integral
with sources



- moment generating

$$Z[J] = \mathbb{E}[e^{J(x,t)\phi(x,t)}] = e^{\frac{1}{2} J^2(x,t)\Xi(t)} \int D\phi_0 P_0[\phi_0] e^{J(x,t)\phi_0(x)f(t,0)}$$

- cumulant generating

$$W[J] = \log Z[J] = \frac{1}{2} J^2(x,t)\Xi(t) + \log \int D\phi_0 P_0[\phi_0] e^{J(x,t)\phi_0(x)f(t,0)}$$

variance
preserving

$$f(t, 0) \rightarrow 0$$

variance
expanding

$$f(t, 0) = 1$$

- higher-order cumulants

$$\kappa_{n>2}(t) = \frac{\delta^n W[J]}{\delta J(x,t)^n} \Big|_{J=0} = \frac{\delta^n}{\delta J(x,t)^n} \log \mathbb{E}_{P_0}[e^{J(x,t)\phi_0(x)f(t,0)}] \Big|_{J=0}$$

$$\Xi(t) = \int_0^t ds f^2(t, s) g^2(s)$$

Generating functionals: summary

- euclidean path integral/target distribution is always there in the background

$$W[J] = \log Z[J] = \frac{1}{2} J^2(x, t) \Xi(t) + \log \int D\phi_0 P_0[\phi_0] e^{J(x, t) \phi_0(x) f(t, 0)}$$

- correlations are being destroyed/overwhelmed and retrieved
- if score is determined exactly, full theoretical control

$$\text{FPE: } \partial_t P_t(x) = \frac{1}{2} g^2(t) \partial_x^2 P_t(x)$$

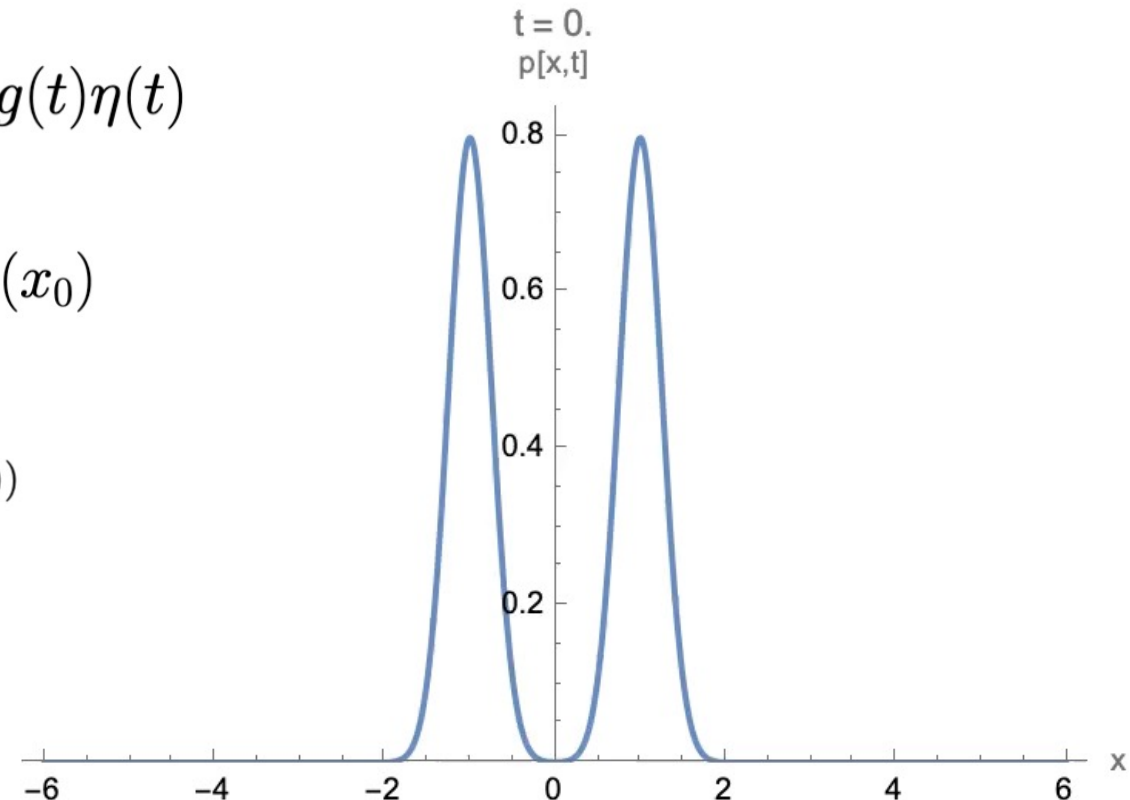
Example: forward evolution

- initial distribution $P_0(x_0)$: Gaussian mixture (two Gaussian peaks)
- add noise in variance-expanding scheme $\dot{x}(t) = g(t)\eta(t)$

- analytical description $P_t(x) = \int dx_0 P_t(x|x_0) P_0(x_0)$

$$P_t(x|x_0) = \mathcal{N}(x; x_0, \sigma^2(t)) = \frac{1}{\sqrt{2\pi\sigma^2(t)}} e^{-(x-x_0)^2/(2\sigma^2(t))}$$

- peak structure erased



$$0 \leq t \leq T$$

noise profile $g(t) = \sigma^{t/T}$

Example: backward evolution

- target distribution: two Gaussian peaks

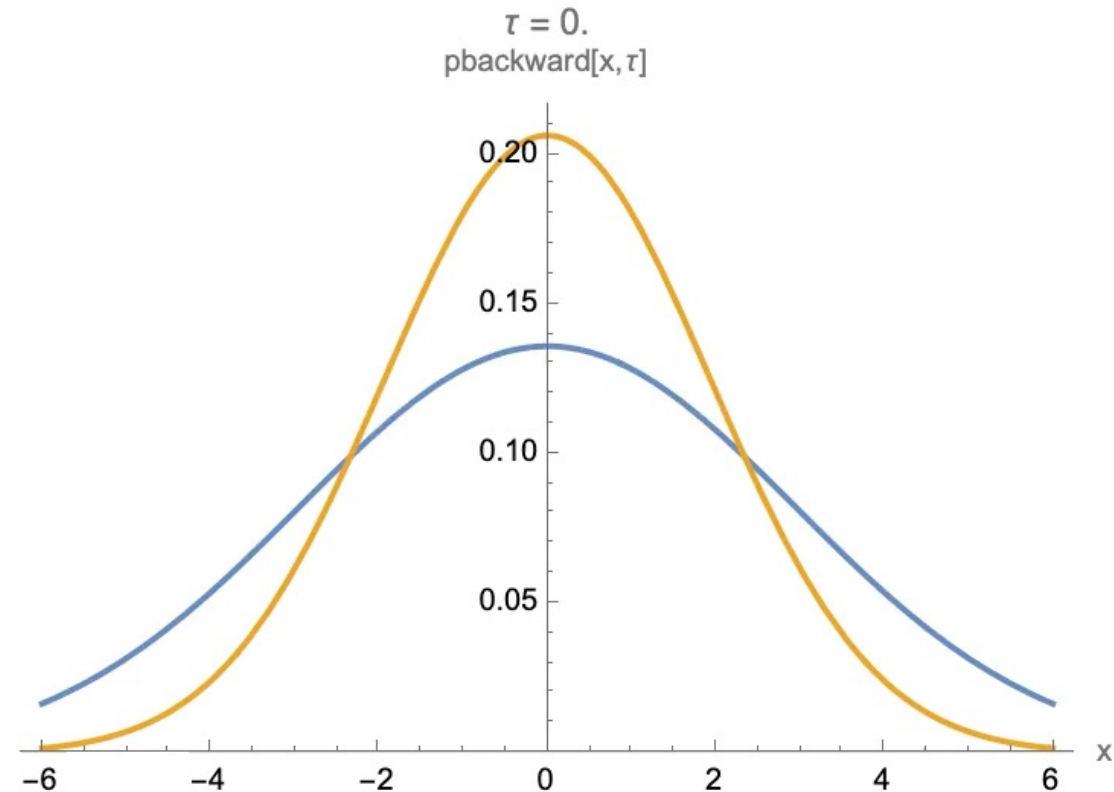
- forward process $\dot{x}(t) = g(t)\eta(t)$

- corresponding backward process

$$x'(\tau) = g^2(T - \tau)\partial_x \log(P(x, T - \tau)) + g(T - \tau)\eta(\tau)$$

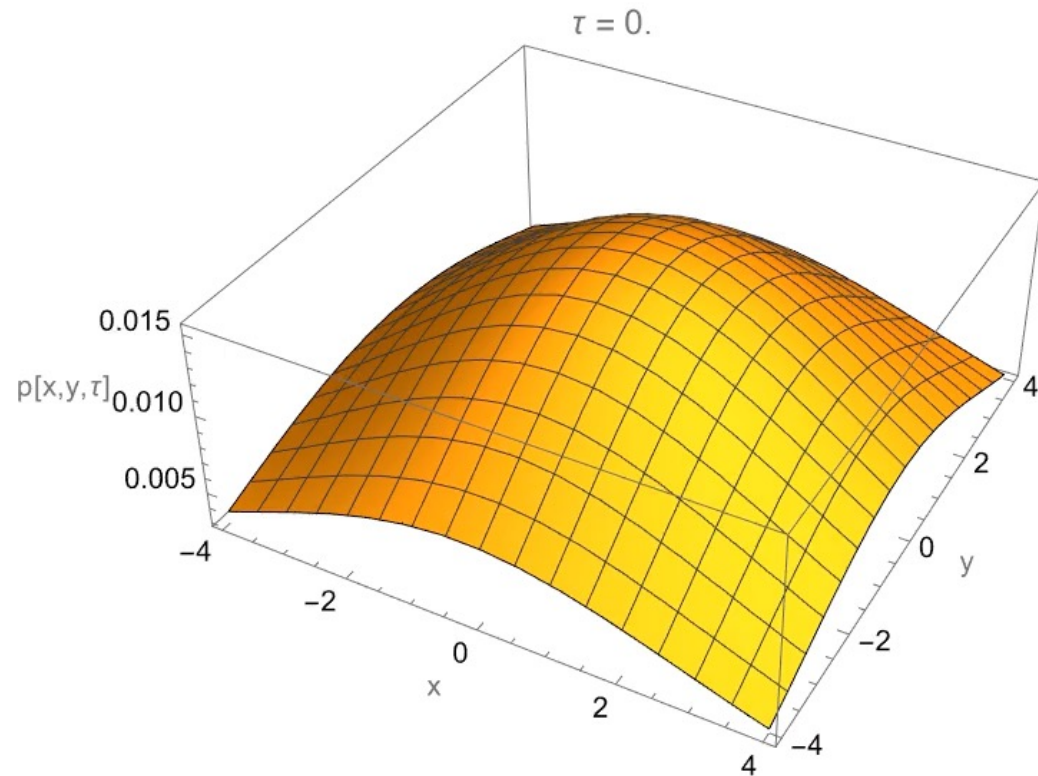
with $\tau = T - t$

solve FPE for backward process
using two initial distributions

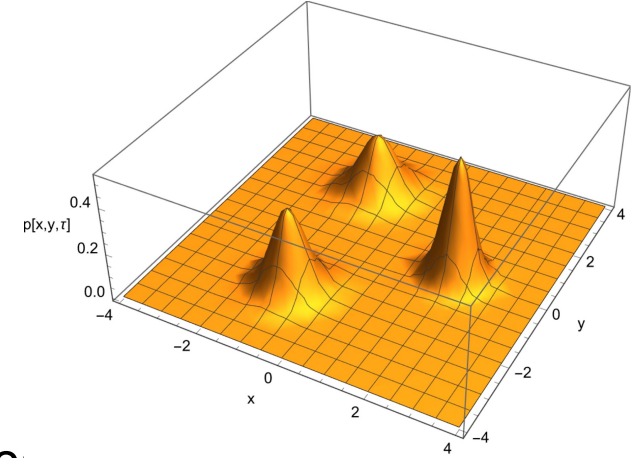
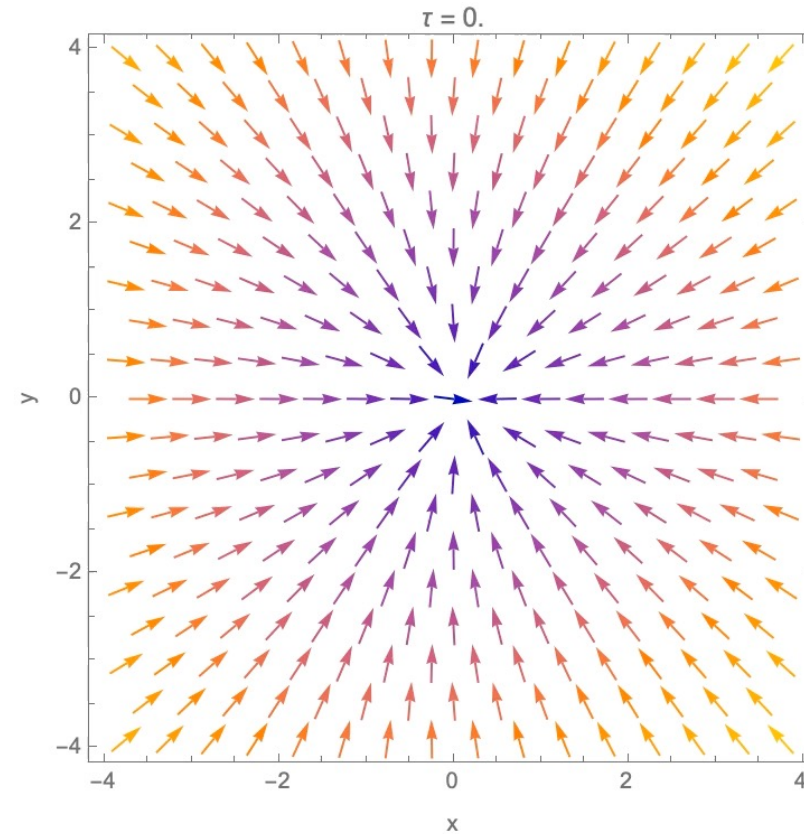


2D example: three Gaussian peaks

backward process, starting
from wide normal distribution



score $\nabla \log P_t(x, y)$
during backward process

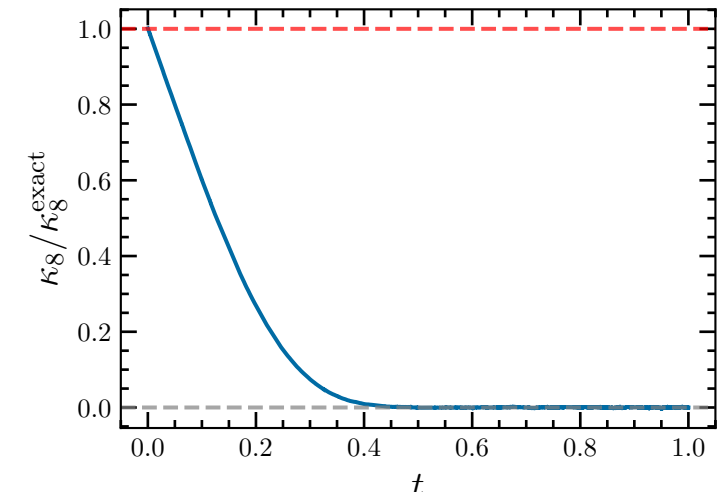
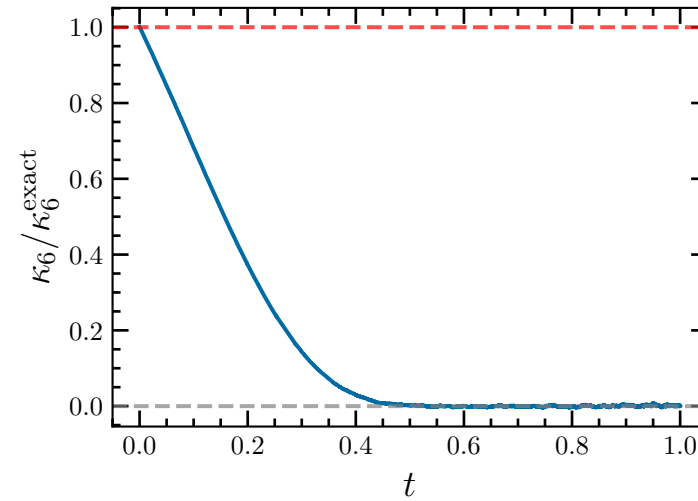
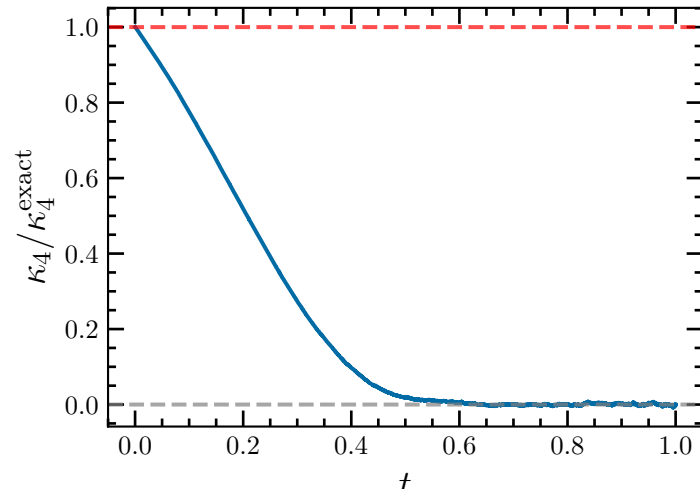


$$\kappa_{n>2}(t) = \kappa_n(0)f^n(t, 0)$$

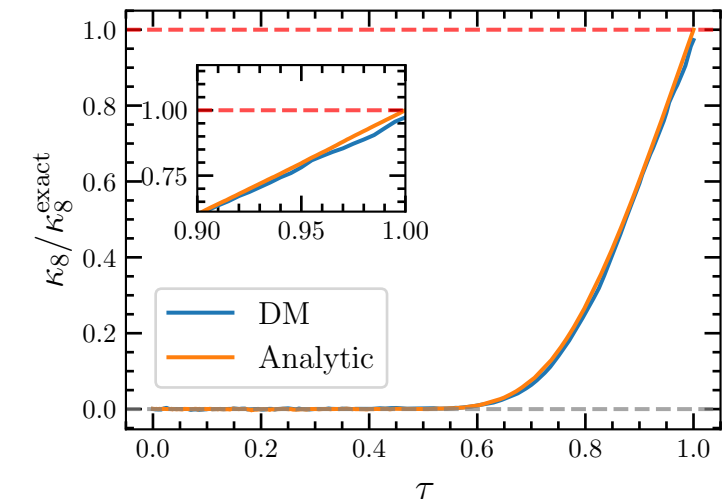
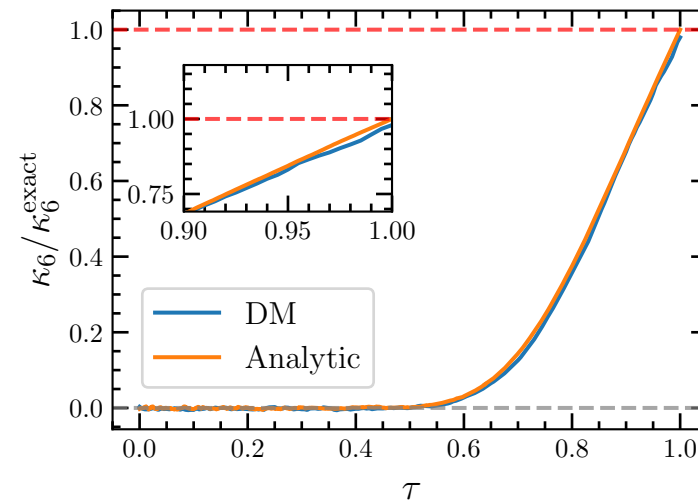
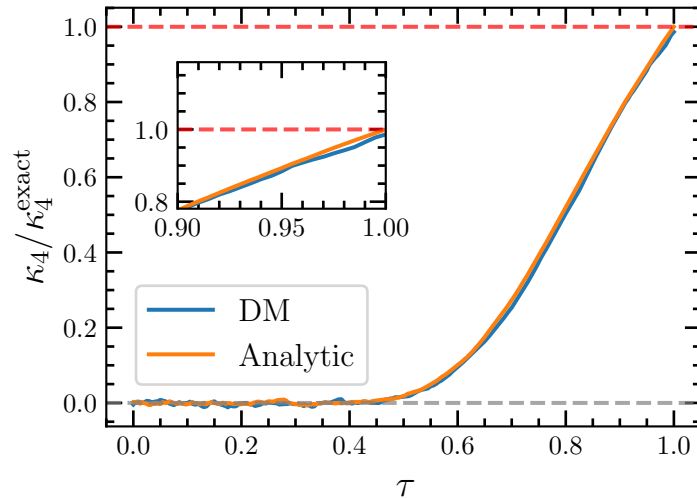
$$f(t, 0) \rightarrow 0$$

4th, 6th, 8th cumulant with drift (DDPM)

forward



backward



analytic = analytic score

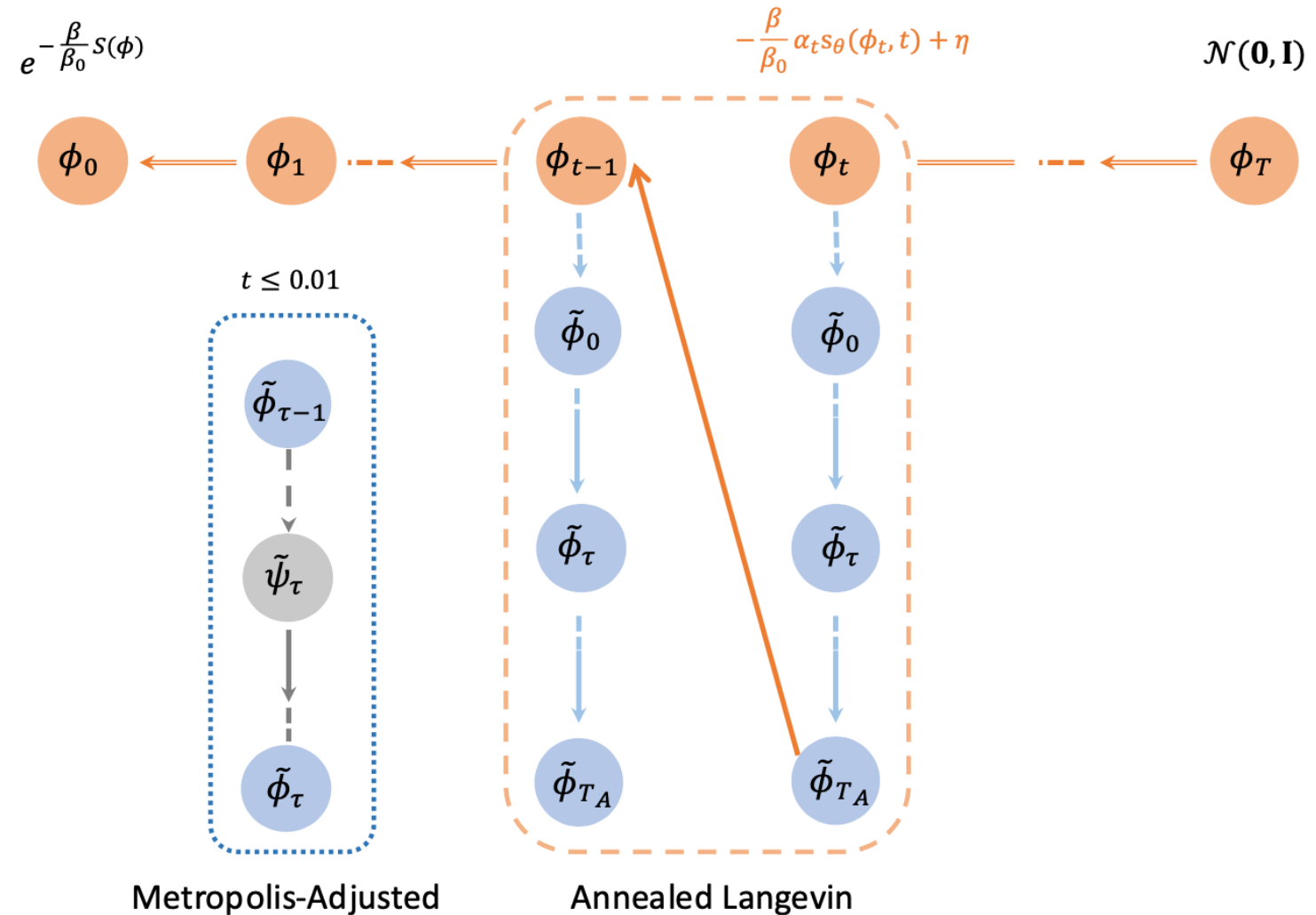
Incorporate (new/old) ideas in diffusion models

- exactness → include an accept/reject step
- thermalisation: score is time dependent, system never thermalises → annealing
- train at one set of parameters, apply trained model at different set → conditioning
- apply to 2D U(1) gauge theory

Incorporate (new/old) ideas in DM dynamics

backward process
(after model has been trained)

- Metropolis-adjusted Langevin algorithm (MALA)
- annealing stage: thermalisation
- reweighting from β_0 to β

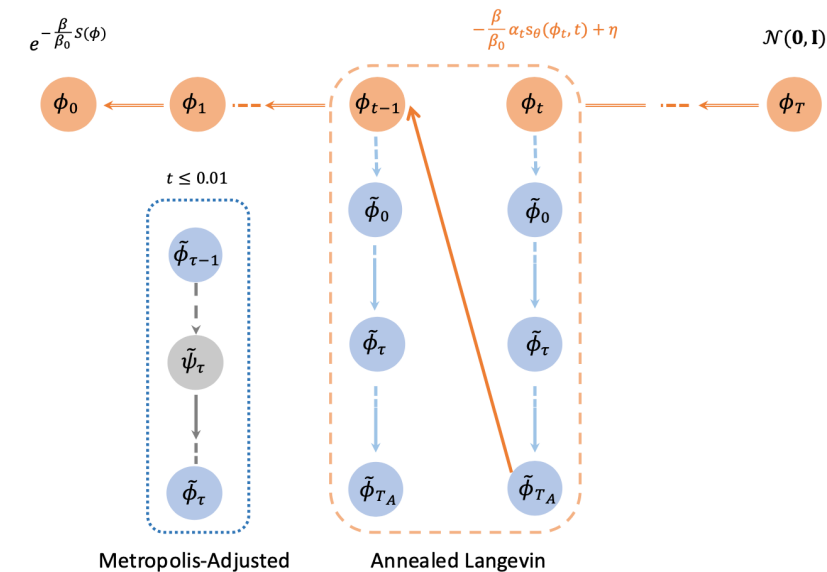


Metropolis-adjusted Langevin algorithm (MALA)

- include an accept/reject step: well-known in Langevin dynamics *

$$\phi_{\tau+1} = \begin{cases} \psi_{\tau+1} & \text{with probability } \min \left\{ 1, \frac{p(\psi_{\tau+1})q(\phi_{\tau}|\psi_{\tau+1})}{p(\phi_{\tau})q(\psi_{\tau+1}|\phi_{\tau})} \right\} \\ \phi_{\tau} & \text{with the remaining probability,} \end{cases}$$

- include ratio of target distributions $p(\phi) \sim e^{-S(\phi)}$
- and ratios of transition amplitudes



$$q(\phi_{\tau}|\psi_{\tau+1}) = \frac{1}{(4\pi\alpha_i)^{n/2}} \exp \left(-\frac{1}{4\alpha_i} \|\phi_{\tau} - (\psi_{\tau+1} + \alpha_i f(\psi_{\tau+1}, \tau + 1))\|_2^2 \right)$$

* G.O. Roberts and J.S. Rosenthal, Optimal scaling of discrete approximations to Langevin diffusions, Journal of the Royal Statistical Society: Series B (Statistical Methodology) 60 (1998) 255

Metropolis-adjusted Langevin algorithm (MALA)

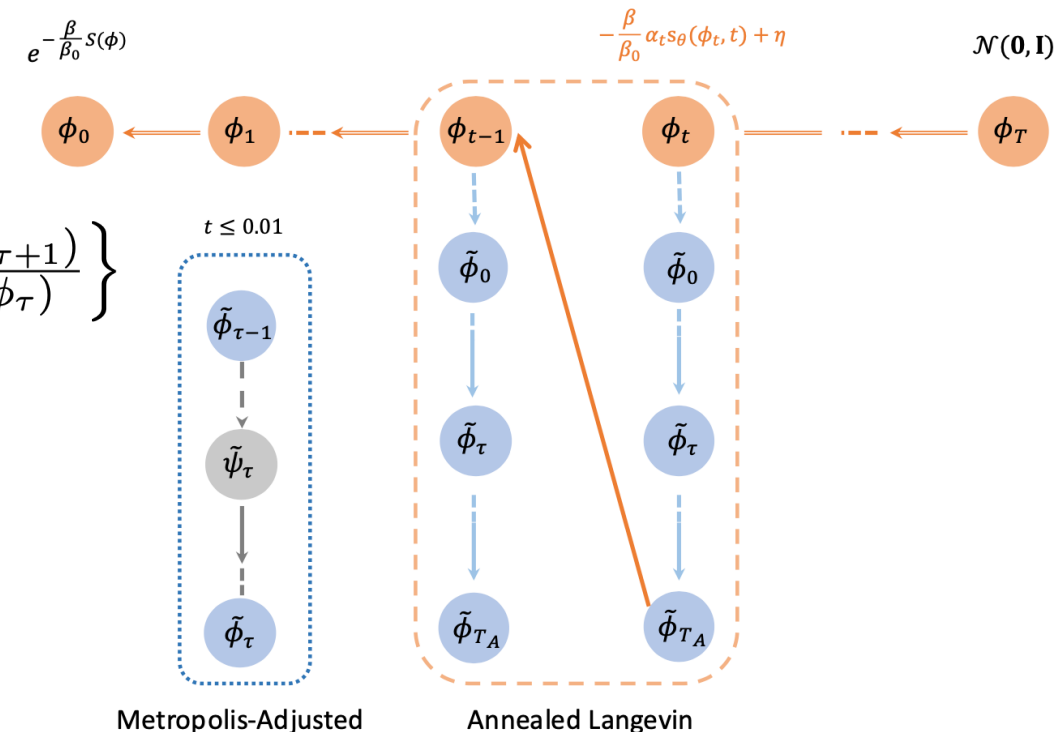
- include an accept/reject step

$$\phi_{\tau+1} = \begin{cases} \psi_{\tau+1} & \text{with probability } \min \left\{ 1, \frac{p(\psi_{\tau+1})q(\phi_{\tau}|\psi_{\tau+1})}{p(\phi_{\tau})q(\psi_{\tau+1}|\phi_{\tau})} \right\} \\ \phi_{\tau} & \text{with the remaining probability,} \end{cases}$$

- only done towards end of backward process
- learned score should be fairly close to “exact” score

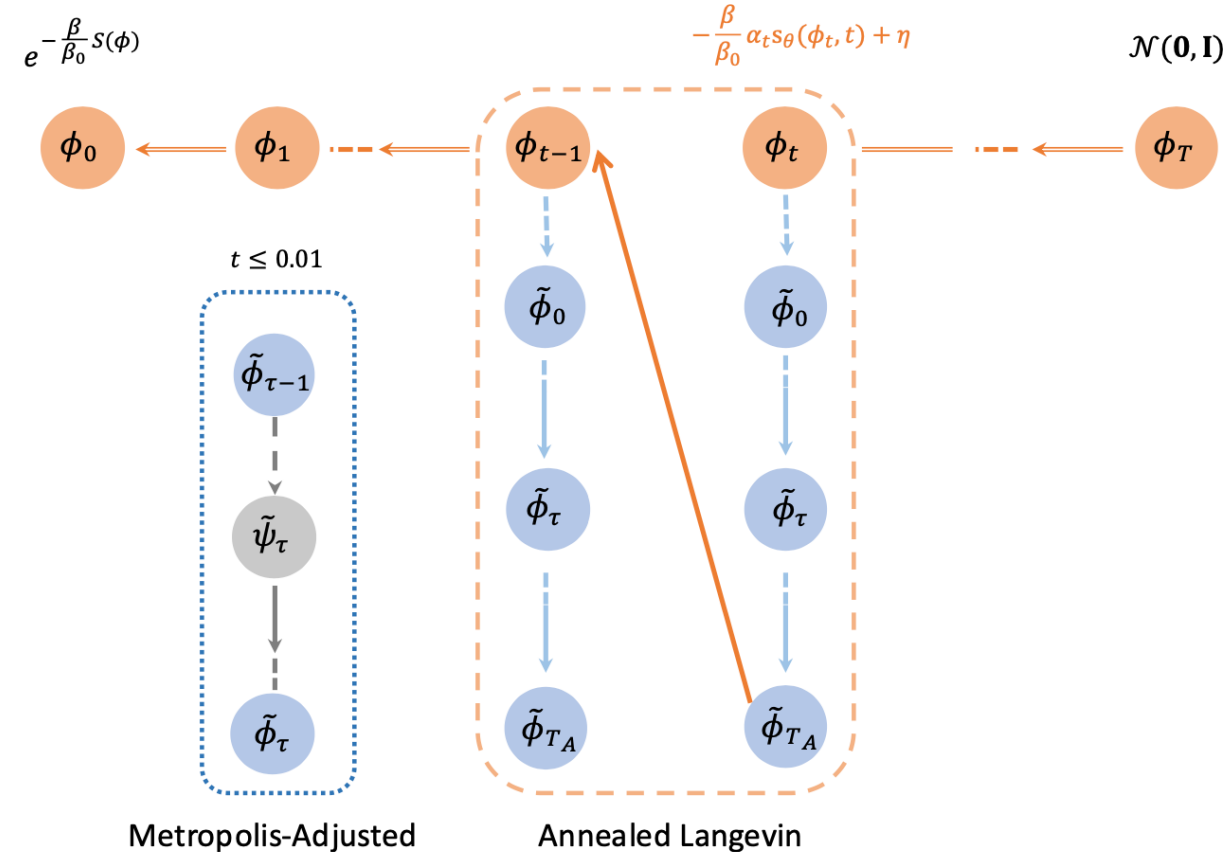
$$\nabla \log p(\phi) \qquad p(\phi) \sim e^{-S(\phi)}$$

- Markov chain starting from each configuration towards end of backward process



Annealing

- score (drift or force in Langevin equation) is time dependent
 - system never thermalises
 - allow for additional steps at fixed score
- annealing
- strictly speaking not needed, but seems useful

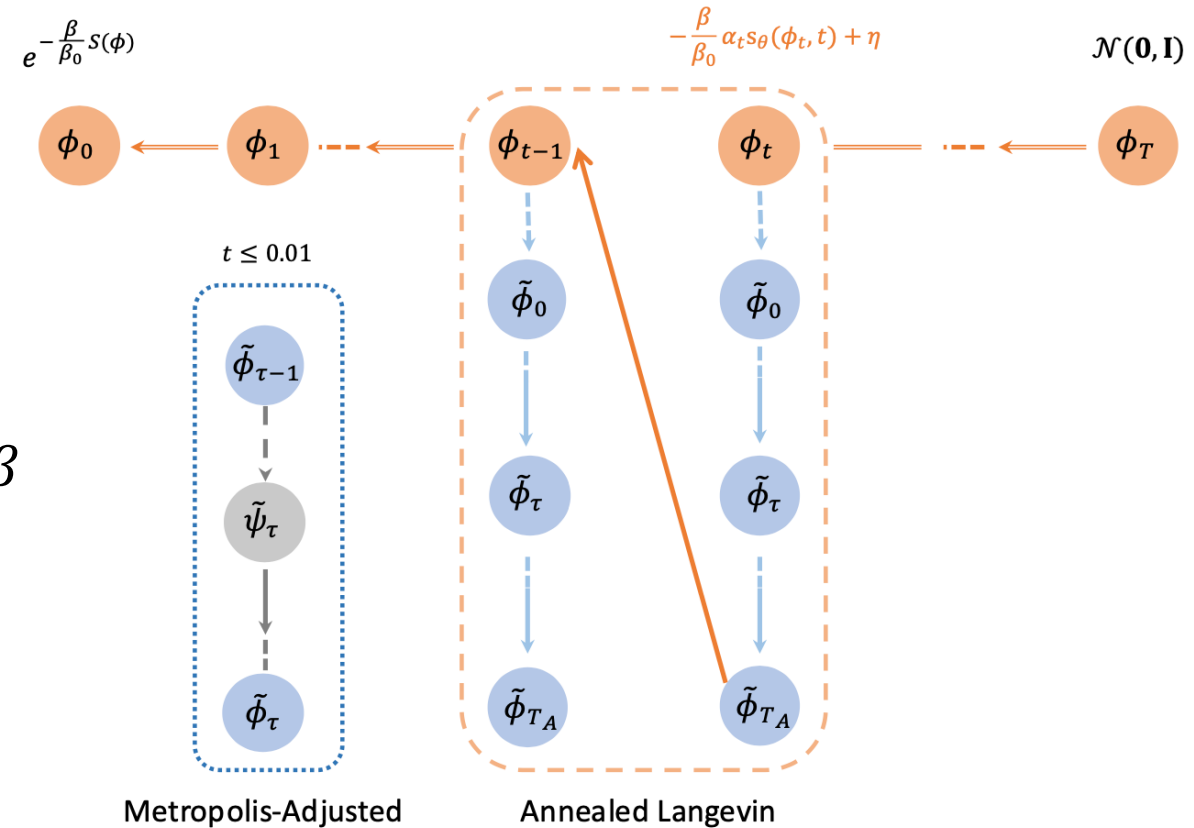


Physics conditioning (gauge theory)

- train using data generated at β_0
- employ at different β values
- applied to U(1) gauge theory: action scales with β

motivated by stochastic quantisation:

- drift is proportional to β

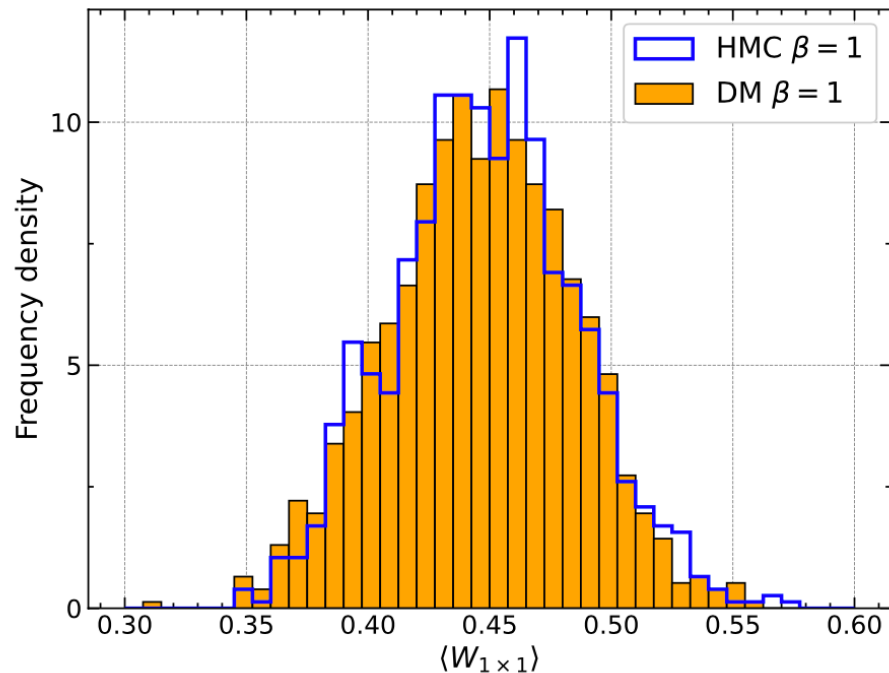


Two-dimensional U(1) gauge theory

- training: 30k configurations at $\beta = 1$ on 16^2 obtained using HMC
- generating: 1024 configs at $\beta = 1, 3, 5, 7, 9, 11$ on $8^2, 16^2, 32^2$

2D U(1) gauge theory: vary the volume

- training: 30k configurations at $\beta = 1$ on 16^2 obtained using HMC
- generating: 1024 configs at $\beta = 1, 3, 5, 7, 9, 11$ on $8^2, 16^2, 32^2$



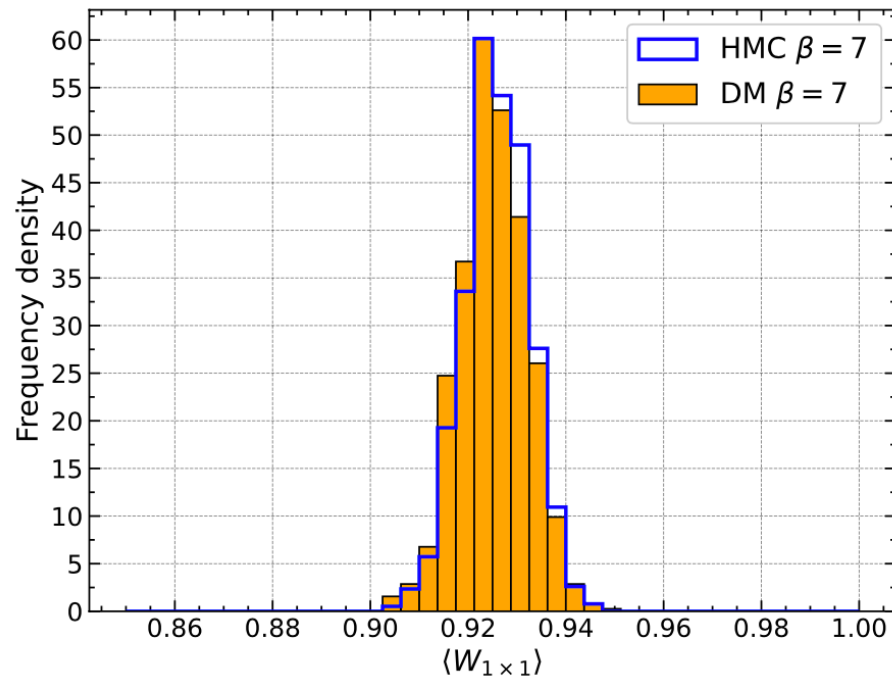
$\beta = 1, L = 16$, HMC vs DM

Lattice Size (L)	1 \times 1 Wilson Loop			
	HMC	DM	Langevin	Exact
8	0.447(72)	0.445(74)	0.443(80)	0.446
16	0.447(37)	0.446(37)	0.444(36)	0.446
32	0.446(18)	0.445(19)	0.445(18)	0.446
64	0.446(9)	0.446(11)	0.445(9)	0.446

increase the volume, after training on $L = 16$

2D U(1) gauge theory: vary the coupling

- training: 30k configurations at $\beta = 1$ on 16^2 obtained using HMC
- generating: 1024 configs at $\beta = 1, 3, 5, 7, 9, 11$ on $8^2, 16^2, 32^2$



coupling (β)	1 \times 1 Wilson Loop			
	HMC	DM	Langevin	Exact
3	0.811(17)	0.811(17)	0.809(17)	0.810
5	0.894(9)	0.894(9)	0.891(10)	0.894
7	0.926(7)	0.926(7)	0.924(6)	0.926
9	0.944(3)	0.942(4)	0.940(6)	0.942
11	0.954(3)	0.953(4)	0.950(5)	0.953

increase the coupling, after training at $\beta = 1$

$\beta = 7, L = 16$, HMC vs DM

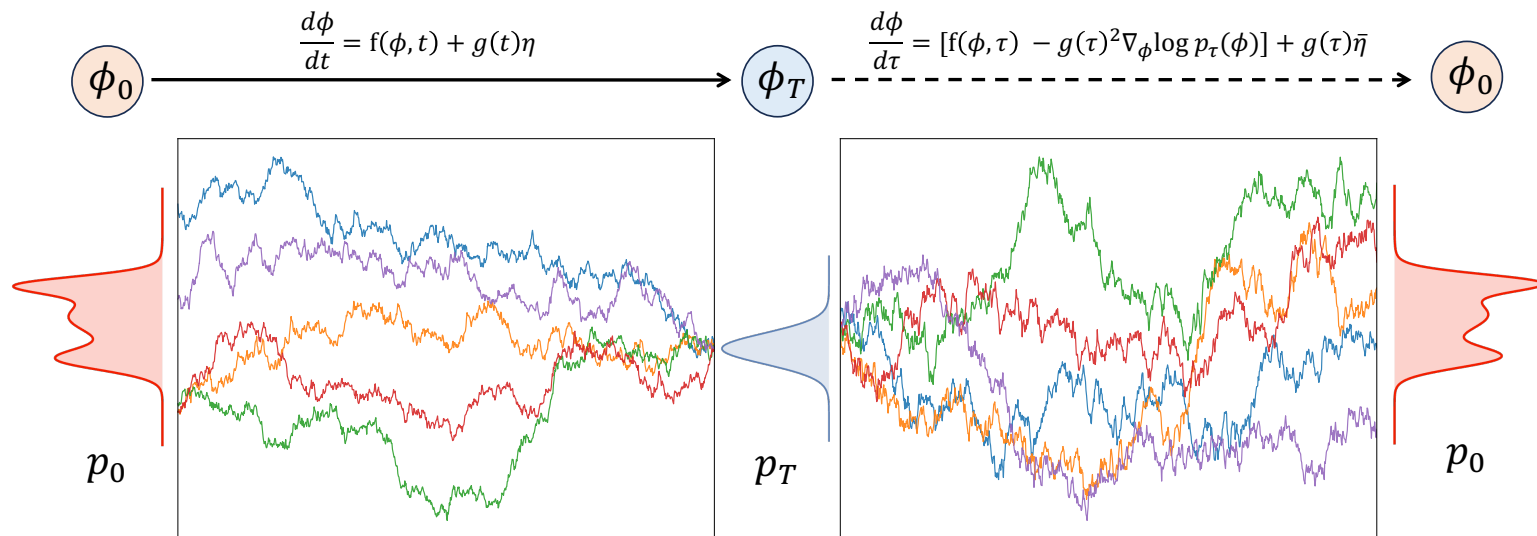
Summary: diffusion models

- offer a new approach for ensemble generation to explore in LFT
- learn from data: requires high-quality ensembles
- closely related to stochastic quantisation
- need better understanding of precision and exactness
- indicated three promising directions to be explored further

BACKUP SLIDES

Score matching: learn the drift for backward process

- one degree of freedom, variance-expanding scheme: $\dot{x}(t) = g(t)\eta(t)$ $\eta \sim \mathcal{N}(0, 1)$
- time-dependent distribution $P(x, t) = P_t(x)$ describes forward and backward process
- so-called **score** $\nabla \log P_t(x)$ is not known, needs to be “learnt” during forward process



Score matching: learn the drift for backward process

- one degree of freedom, variance-expanding scheme: $\dot{x}(t) = g(t)\eta(t)$ $\eta \sim \mathcal{N}(0, 1)$
- time-dependent distribution $P(x, t) = P_t(x)$ describes forward and backward process
- so-called **score** $\nabla \log P_t(x)$ is not known, needs to be “learnt”
- loss function $\mathcal{L}(\theta) = \frac{1}{2} \int_0^T dt \mathbb{E}_{P_t(x)} \left[\sigma^2(t) \|s_\theta(x, t) - \nabla \log P_t(x)\|^2 \right]$ $\sigma^2(t) = \int_0^t ds g^2(s)$
- $s_\theta(x, t)$ approximates score, vector field learnt by some neural network
- introduce conditional distribution $P_t(x) = \int dx_0 P_t(x|x_0)P_0(x_0)$ initial data $P_0(x_0)$

$$P_t(x) = \int dx_0 P_t(x|x_0)P_0(x_0)$$

Score matching: learn the drift

- loss function $\mathcal{L}(\theta) = \frac{1}{2} \int_0^T dt \mathbb{E}_{P_t(x)} \left[\sigma^2(t) \|s_\theta(x, t) - \nabla \log P_t(x)\|^2 \right]$

- diffusion process $\dot{x}(t) = g(t)\eta(t)$ easily solved $x(t) = x_0 + \sigma(t)\eta(t)$ $\sigma^2(t) = \int_0^t ds g^2(s)$

- conditional distribution $P_t(x|x_0) = \mathcal{N}(x; x_0, \sigma^2(t)) = \frac{1}{\sqrt{2\pi\sigma^2(t)}} e^{-(x-x_0)^2/(2\sigma^2(t))}$

- and hence $\nabla \log P_t(x_t|x_0) = -(x_t - x_0)/\sigma^2(t)$

- loss function $\mathcal{L}(\theta) = \frac{1}{2} \int_0^T dt \mathbb{E}_{P_t(x_t)} \left[\left\| \sigma(t)s_\theta(x_t, t) + \frac{x_t - x_0}{\sigma(t)} \right\|^2 \right]$
 $= \frac{1}{2} \int_0^T dt \mathbb{E}_{P_t(x_t)} \left[\|\sigma(t)s_\theta(x_t, t) + \eta(t)\|^2 \right]$

tractable, computable