TDR Editing

Tuesday CEPC TDR Meeting July 29, 2025

Outline

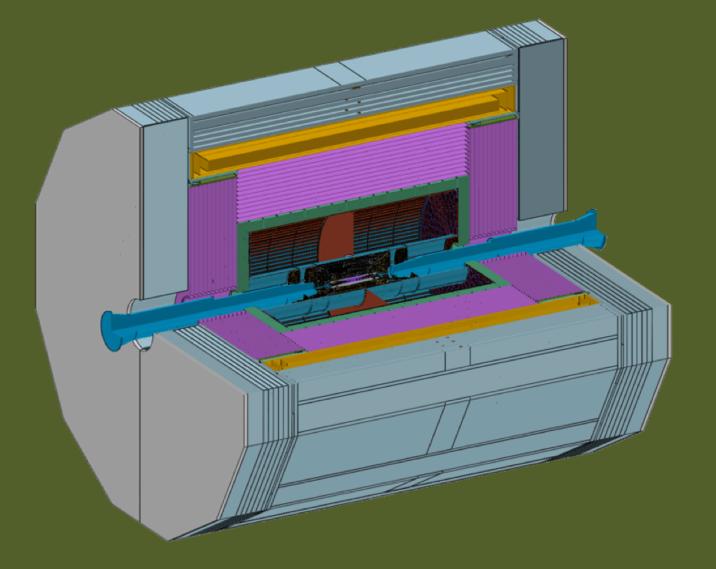
- News from IDRC
- Mechanics issues

- Figures that still need update
- Muon detector by Xiaolong

Draft v0.5.0

CEPC Reference Detector Technical Design Report

Version: v0.5.0 build: 2025-07-15 07:37:45+08:00



Keeping track of modifications

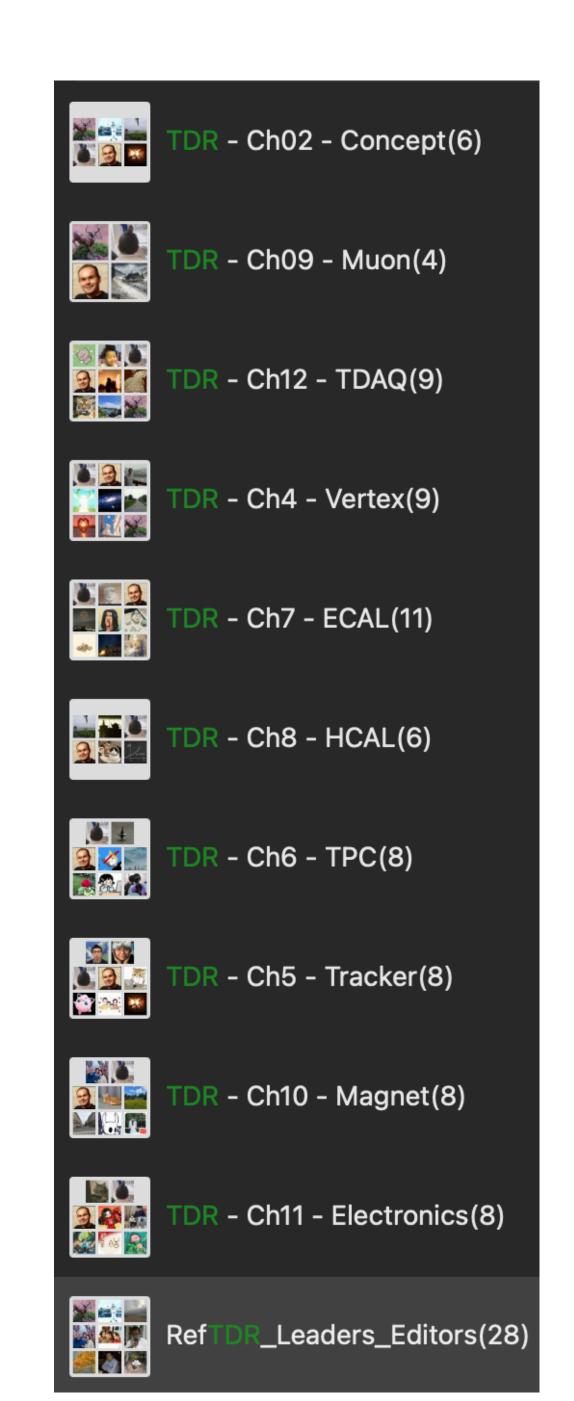
Spreadsheet monitoring the status in IHEP docs:

- https://docs.ihep.ac.cn/link/ARF4C648FCA57D4CF281A8E821A110229E
- 文件名: Status of TDR.xlsx
- 文件路径: AnyShare://ZHANG Zhaoru(zhangzr)/CEPC Det TDR/Status of TDR.xlsx

Please fill in your input now, and keep it updated as we move along

We will try to do the same!

Provide feedback for improvements



Keeping track of modifications

Blue section of the spreadsheet is for chapter leaders

Chapter	Overall	Chapter	Updated	Tal	oles			Figures		Te	ext Other r
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1 Introduction	100%	100%		100%	100%		100%	1 0	100%	100%	
2 Concept of CEPC Reference Detector	90%	100%		90%	90%	90%		3 0	90%		
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12 Trigger and Data Acquisition	100%	100%	26-Jul	100%	100%	100%	100%	3 0	100%	100%	100%
13 Offline software and computing	100%	100%	28-Jul	100%	100%	100%	100%	1 0	100%	100%	100%
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15 Detector and physics performance	95%	100%	21-Jul	100%	95%	100%	100%		100%	100%	Debug JOI conf

Update status using "blue" color so that we can know it is up to date

News from IDRC

- Barcelona-version comments from IDRC:
 - Previously feedback for: Tracker, Calorimeter, Muon Detector, Mechanics, (TPC from Paul communicated earlier), Electronics, Trigger/DAQ, Magnet
 - Received this week:
 - Software (Cristinel)
 - TPC (Titov)
 - HCAL extra information (Roman)

From

Last Week

Now IDDC	Started	Date
New IDRC	implementingg	plan to finish
Si-Tracker		
TPC	Y	today
ECAL	Y	1 week
HCAL	Y	3-days — 1 week
Muon	Y	2 days
Mechanics	Y	1 week, cabling
Electronics	Y	Done
Trigger/DAQ		3 days
Magnet		Done, today
Software		
TPC (Titov)		

New

- Prior agreement to split mechanics information into two parts:
 - Sub-detector chapters
 - → details on the mechanics of each sub-detector
 - Chapter 14 on Mechanics and Integration
 - → Overall mechanics issues, integration of each sub-detector (interconnects) and installation
- Currently, the mechanics information in the TDR is unbalanced and not detailed enough.
 - Different sub-detectors have different levels of detail
 - FEA simulations results for sub-detectors integration and connections mostly missing
 - Chapter 14 is very detailed on some aspects (e.g. installation and yoke) but lacks technical depth on other critical aspects (e.g. interconnections and sub-detectors deformations and stress)

Not a problem of one single chapter but of the TDR as a whole Need to define today how better to correct this

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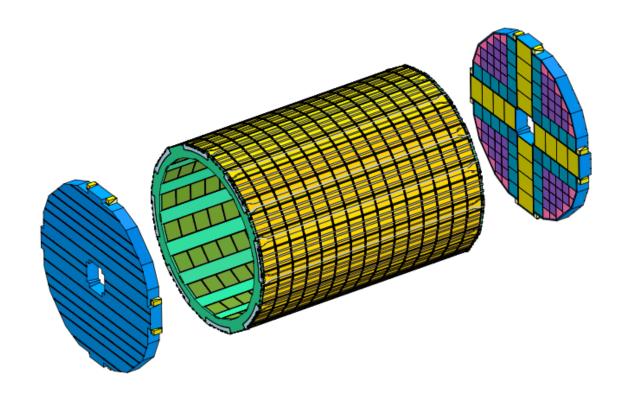


Figure 7.10: The ECAL mechanical design with one barrel and two endcaps. The barrel ECAL has 480 modules, which are integrated into a carbon-fiber frame (in lighter green), and is affixed to the barrel HCAL via 8 interconnection points. Cooling plates and cooling pipes are colored in light yellow. Two ECAL endcap discs along with endcap OTK layers are mounted onto the HCAL from each side. Endcap ECAL modules, indicated in various colors for different dimensions and designs, are integrated into one of the discs of a carbon-fiber frame, indicated in blue.

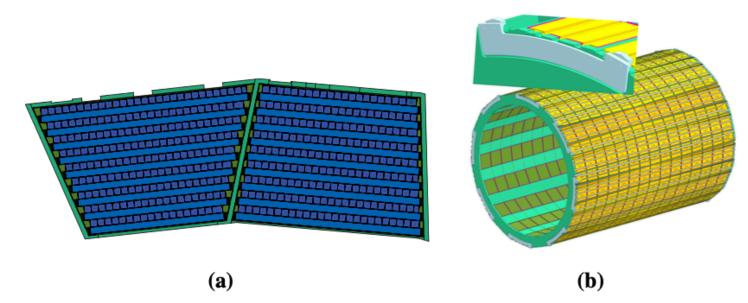


Figure 7.11: The side view of two types of barrel ECAL modules (a); the stainless steel structure for inter-connecting the ECAL barrel to the barrel HCAL, which are embedded in the main carbon-fiber frame (b).

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Barrel structure FEA results FEA has been performed to assess the structural stability of the carbon-fiber frame and evaluate mechanical stress to crystal bars. The structural response was simulated under conditions with a total self-weight of 130 t. The stress distributions in three different directions (i.e. the stress in parallel to the carbon-fiber direction, the stress perpendicular to the carbon-fiber direction and the in-plane shear stress) show that they stay well within the specifications of the cost-effective CFRP option named "T700". Additional 16 fixation points fixing points have been included to the barrel frame cylinder to reinforce structural stability and reduce deformation. The maximum deformation is 2.7 mm, as shown in Figure 7.13, and can meet the design requirement.

Since the design of barrel modules is similar to that of endcaps, FEA results under load are presented in Section 7.2.5.2.

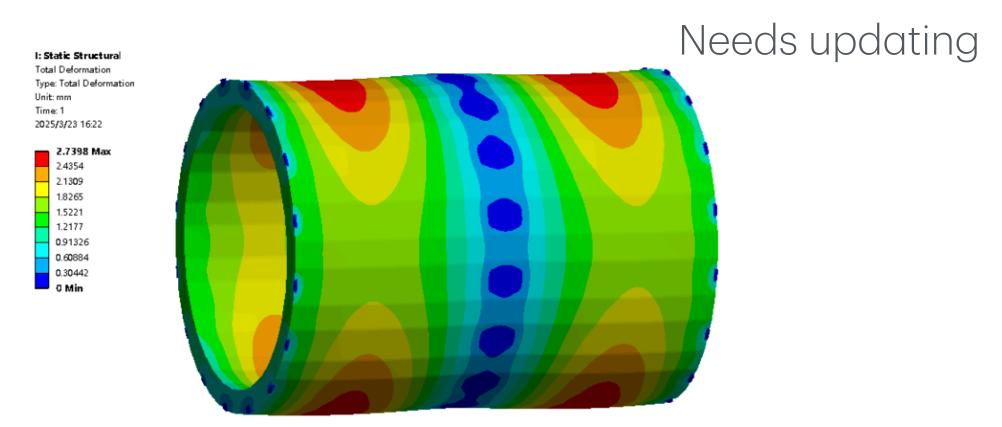


Figure 7.13: Deformation distribution of the ECAL barrel frame with the updated mechanical design by adding extra fixation points in the central cylinder, further reinforcing interconnections with the barrel HCAL.

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356		14.1.2 Design requirements	
357	14.2	Sub-detector connections	Detector connections
358		14.2.1 Yoke design	
359		14.2.2 Superconducting solenoid magnet	
360		14.2.3 Barrel HCAL	
361		14.2.4 Barrel ECAL	Chapter organized in order of the installation, which is unnature
362		14.2.5 TPC (barrel OTK)	
363		14.2.6 ITK	Separated barrel and endcap description
364		14.2.7 Beam pipe (VTX and LumiCal)	
365		14.2.8 Endcap ECAL (endcap OTK)	
366		14.2.9 Endcap HCAL	
367		14.2.10 Reliability and safety assessment	
368	14.3	Detector installation	Detector Installation
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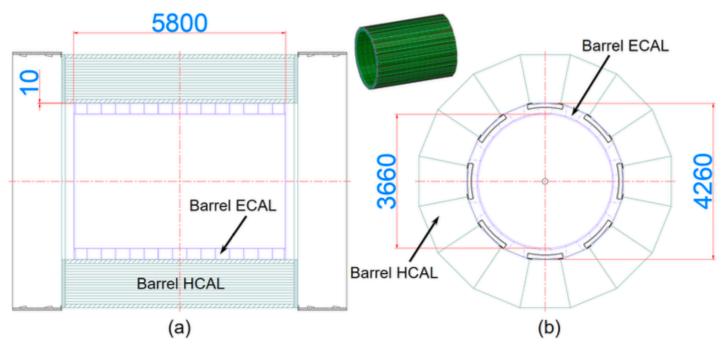


Figure 14.13: Boundary dimensions and location of the barrel ECAL. It is installed inside the barrel HCAL, with a minimum clearance of 10 mm. Units are in millimeters.

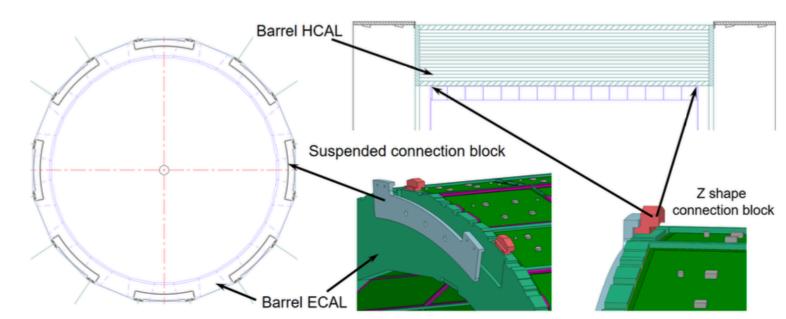


Figure 14.14: Connection structure of the barrel ECAL. Eight-point circular suspension structure are adopted to connect the barrel ECAL and the barrel HCAL.

Similar information to the ECAL chapter, but no FEA or analysis of the strength of the connection, stress and deformations

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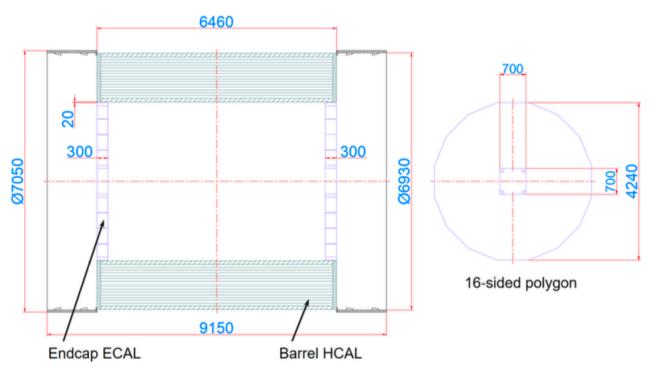


Figure 14.22: Boundary dimensions and location of the endcap ECAL. It is located at both ends of the barrel ECAL, with the minimum clearance of 20 mm for the routing of cable and pipe. Units are in millimeters.

The endcap ECAL is connected to the barrel HCAL and positioned by the four pairs of adjustable pad irons uniformly distributed around the circumference. Due to the 25-ton weight of the endcap ECAL, the adjustment operation must rely on hydraulic drive or external tooling assistance to support the weight of the endcap ECAL.

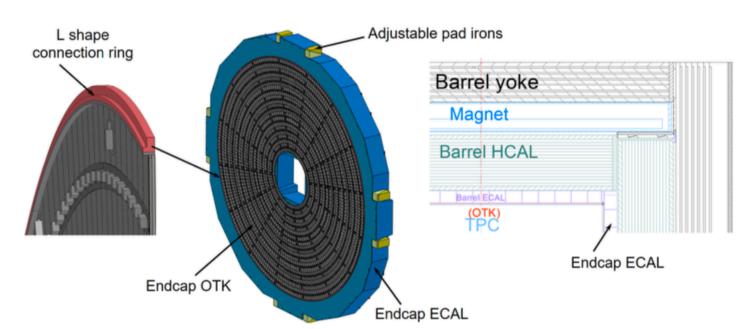


Figure 14.23: Connection structure of the endcap ECAL and the endcap OTK. They are connected and positioned by four pairs of adjustable pad irons uniformly distributed around the circumference.

No information regarding stress, deformation or strength of connection, no FEA

Suggestion: analysis of the interconnections and FEA in the mechanics chapter. Possible?

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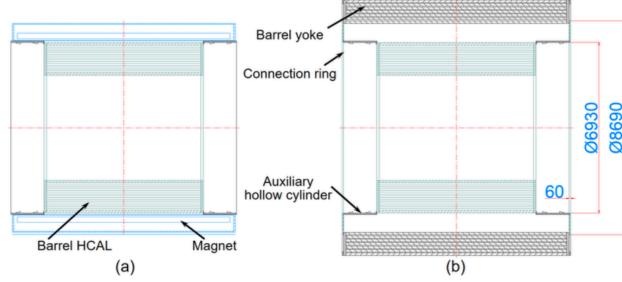


Figure 14.10: Location of the barrel HCAL. It is directly connected to the barrel yoke using the rings. Units are in millimeters.

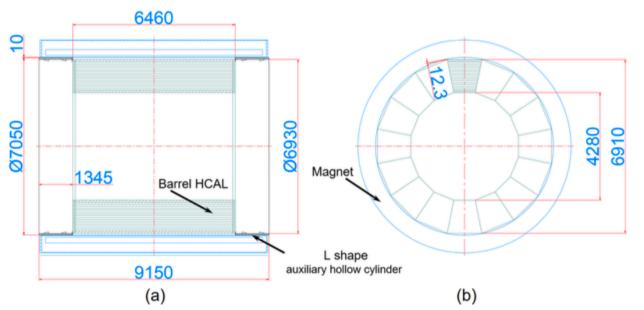


Figure 14.11: Boundary dimensions of the barrel HCAL. The L-shaped auxiliary hollow cylinders serve as both assembly fixture and the key connection interface, with 10 mm clearance between to the magnet. Units are in millimeters.

Many simple drawings with design, but no FEA results on stress, deformation, etc

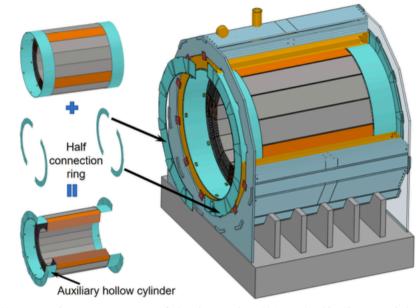


Figure 14.12: Connection structure of the barrel HCAL. Split rings with wire slots connect the HCAL auxiliary cylinder to the barrel yoke flange.

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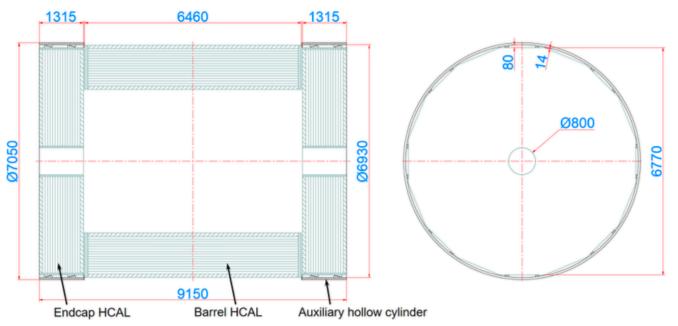


Figure 14.24: Boundary dimensions and location of the endcap HCAL. It is installed in the auxiliary hollow cylinder of the barrel HCAL, the clearance between them is ranged from 14 mm to 80 mm for routing space. Units are in millimeters.

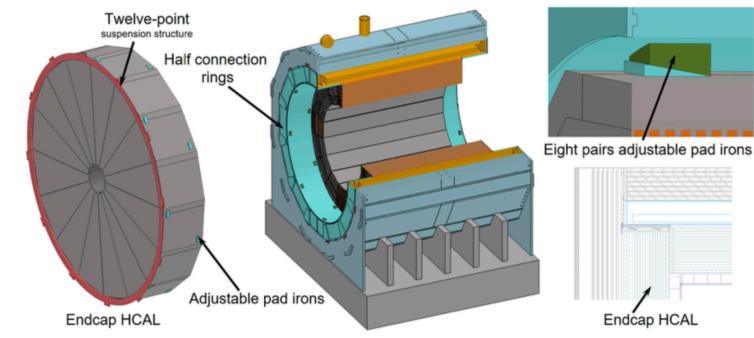


Figure 14.25: Connection structure of the endcap HCAL. The endcap HCAL is rigidly connected to the barrel yoke through eight pairs of adjustable pad irons, two pairs of axial pads, and a twelve-tooth flange, ensuring stable support for the superconducting magnet.

Many simple drawings with design, but no FEA results on stress, deformation, etc

Suggestion: analysis of the interconnections and FEA in the mechanics chapter. Possible?

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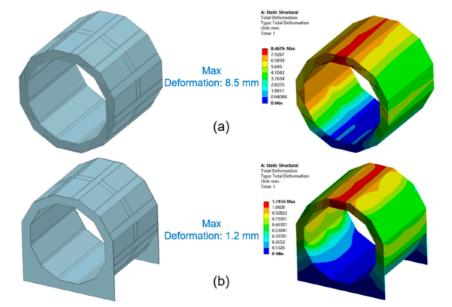


Figure 14.6: Overall deformation comparison of FEA results for the barrel yoke without and with the end flanges. (a) Maximum deformation is 8.5 mm without the end flanges; (b) Maximum deformation is 1.2 mm with the end flanges.

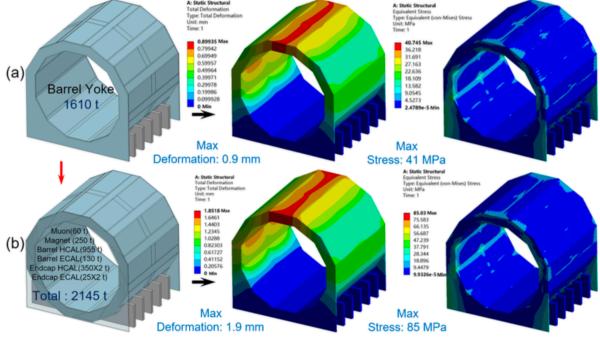


Figure 14.26: FEA results of the barrel yoke deformation and stress under two loading condition. (a) bare yoke condition:load is self-weight of barrel yoke. (b) with sub-detectors condition:load is self-weight of barrel yoke and 2145 tons. (including the superconducting solenoid magnet, the barrel HCAL, the barrel ECAL, the endcap HCAL, the endcap ECAL and the barrel muon detectors. The weight of the lightweight tracker detector is ignored.)

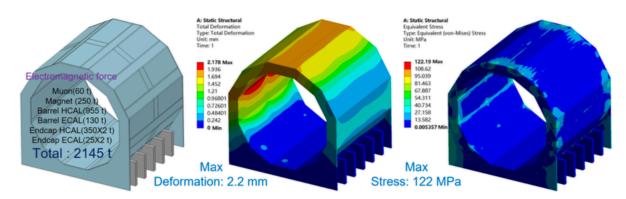


Figure 14.27: Deformation and stress of the barrel yoke under the electromagnetic force load with sub-detectors condition.

Many FEA plots and analysis of the yoke, this gives the impression we only studied the yoke mechanics and nothing else

Suggestion: analysis of the interconnections and FEA in the mechanics chapter. Possible?

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Note: no detailed FEA analysis of the interconnections in these chapters or in chapter 14

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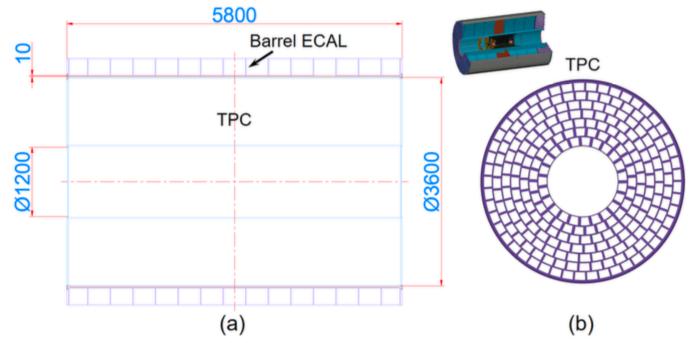


Figure 14.15: Boundary dimensions and location of the TPC. It is mounted inside the barrel ECAL with a minimum clearance of 10 mm. Units are in millimeters.

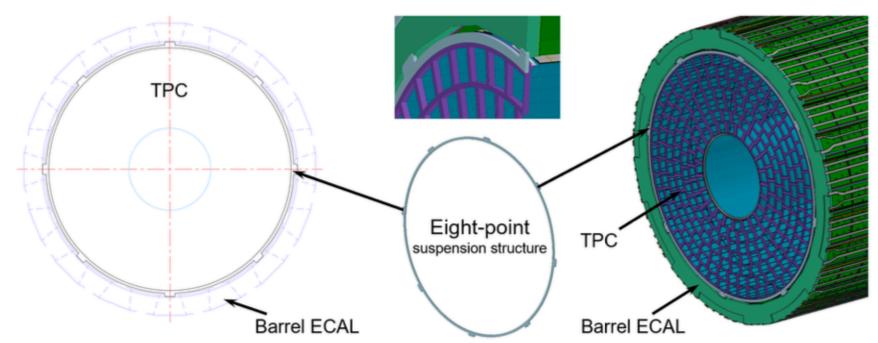


Figure 14.16: Connection structure of the TPC. The TPC is connected to the barrel ECAL by eight-point suspension structure with the slots for cabling and piping.

Note: no detailed FEA analysis of end plate or interconnection in TPC chapter or chapter 14

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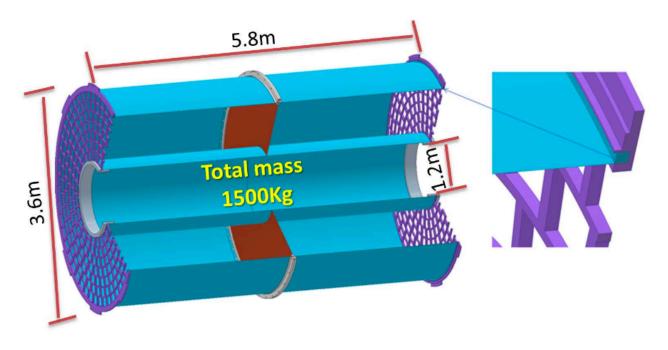


Figure 6.1: The Layout diagram of the TPC fieldcage, the designed boundary connection with ITK, OTK and ECAL sub-detectors

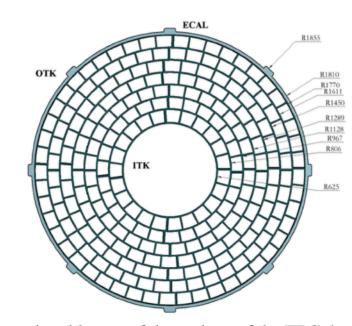


Figure 6.3: Two-dimensional layout of the endcap of the TPC detector, with each endcap equipped with 248 individual detector modules. The aluminum endcap offers a combination of lightweight and high strength properties, making it suitable for maintaining structural integrity while minimizing material budget (unit:mm).

Note: no detailed FEA analysis of the interconnections in these chapters or in chapter 14

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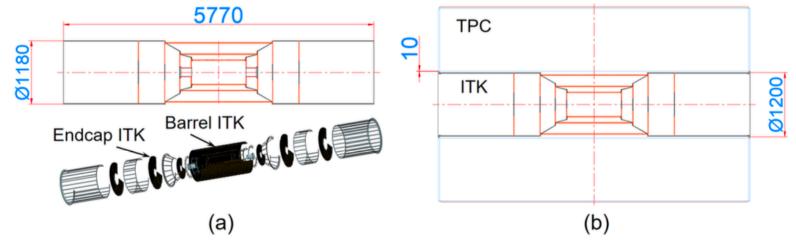


Figure 14.18: Boundary dimensions and location of the ITK. ITK is located inside TPC with a 10 mm clearance, total length of it is 5770 mm and the outer diameter is 1180 mm. Units are in millimeters.

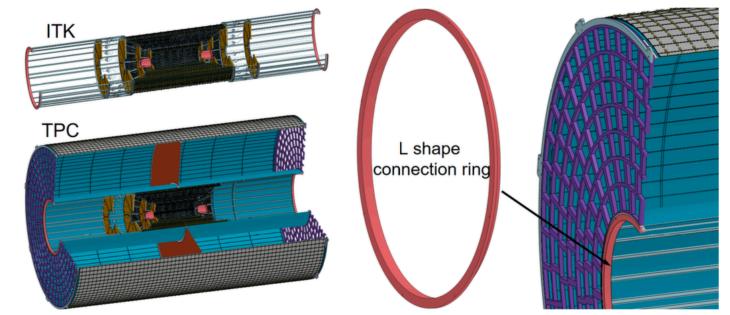


Figure 14.19: Connection structure of the ITK. The L shape rings at both ends connect the ITK to the TPC

Note: no detailed FEA analysis of support structure

Chapter Structure

Chapter X:			
X.	1	Overview	What are we going to build? Design , expected performance ("requirements")
X.	2	Detailed Design	
X.	2.	1 Detailed design	
X.	2.	2 Challenges and critical R&D	
X.	3	Key Technologies to address challenges	
X.	4	R&D and prototypes	
X.	5	Simulation and Performance	
Χ.	6	Alternative Solutions	Can be either backup or more advanced solution (demonstrate backup solutions are in hand and that their possible selection still meet the requirements)
X.	7	Summary and Future Plan	
X.	8	(Cost table and justification)	Eventually to be moved to a common chapter

- Sections should not have more than 4 numbered subsection levels x.y.z.w
- If using AI, editors need to read the AI output and finalize the text themselves. Cannot blindly use AI output. Also, AI usage should be minimized to correct english, NOT write sections from scratch
- Captions should be long and describe plot, not just a title