

Quasi-optimal weights: a versatile tool of data analysis

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Best ν mass bound from Troitsk- ν -mass (arXiv:1108.5034).

Had been plagued by "Troitsk anomaly" for ~ 10 years.

Anomaly went away after a reanalysis that was made possible by **two enabling technologies:**

Part 1 (this talk) statistics: quasi-optimal weights

Part 2 (next talk) software: Oberon technologies

Reminder

Basic problem of math. statistics:

given

a parameterized distribution

$$\pi_M(\mathbf{P})$$

random sample

$$\{\mathbf{P}_i\}_{i=1\dots N}$$

$$M_0$$

estimate

parameter and error

$$M_*, \sigma_*$$

- least squares (1800s) ← popular but ill-founded
- moments (K.Pearson, 1894) ← inferior (??) => neglected
- maximal likelihood (R.Fisher, 1912) ← best (??)
- chiropractic (event selection, jet algorithms, etc.)

The FFRC Bound

maximal likelihood (R.Fisher, 1912)

$$\sum_i \ln \pi_M(\mathbf{P}_i) \leq \sum_i \ln \pi_{M_{\text{ML}}}(\mathbf{P}_i)$$

$$\sigma_{\text{ML}}^2 = \frac{1}{N} [\text{Fisher's information}]^{-1}$$

absolute minimum

$$\sigma_{\text{ML}}^2 \leq \sigma_*^2$$

NB in practice

$$\frac{\partial}{\partial M} \sum_i \ln \pi_M(\mathbf{P}_i) = 0$$

NB what if $\pi_M(\mathbf{P})$ is unknown
as a formula?**HEP: MC event generators**

The Bound

Fisher 1925

Frechet 1943

Rao 1945

Cramer 1946

*R.A.Fisher,
Proc. Camb. Phil. Soc.
22 (1925) 700-725*

generalized moments

originally (Pearson 1894): $f(\mathbf{P}) = \mathbf{P}^n$
 suboptimal compared with ML

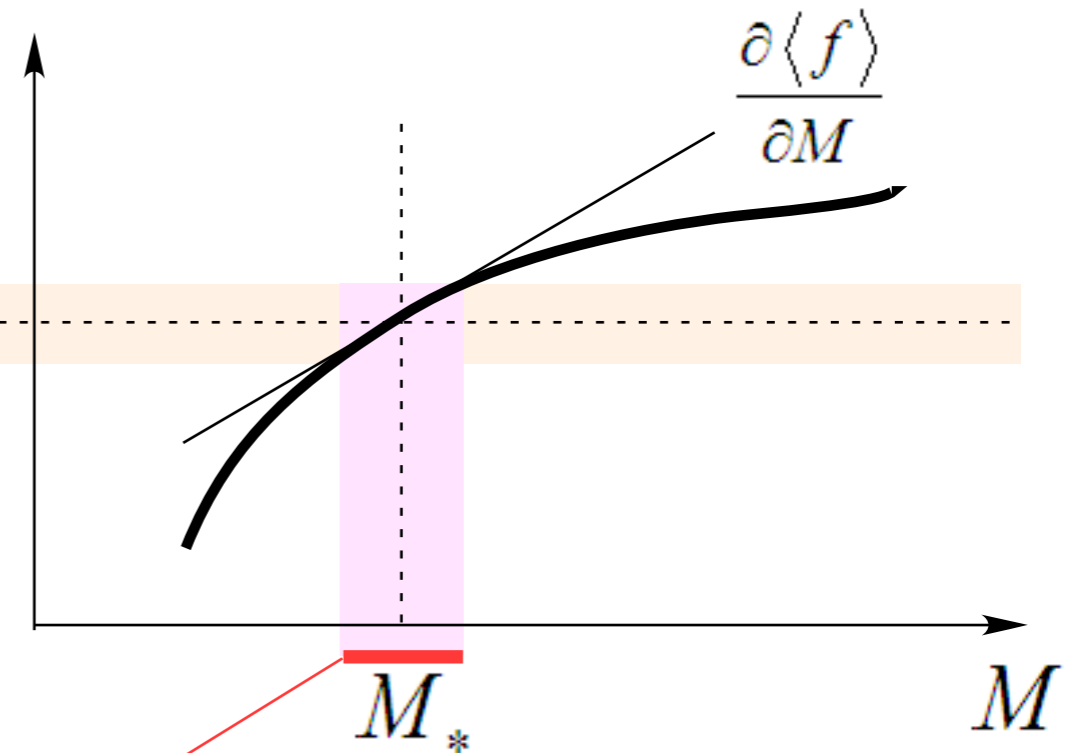
$$\langle f \rangle = \int d\mathbf{P} f(\mathbf{P}) \pi_M(\mathbf{P}) = F(M)$$

$$\langle f \rangle_{\text{exp}} = \frac{1}{N} \sum_i f(\mathbf{P}_i) = F_*$$

$$\mathbf{Var} \langle f \rangle_{\text{exp}} = \left\langle \left[f - \langle f \rangle_{\text{exp}} \right]^2 \right\rangle_{\text{exp}}$$

$$\mathbf{Var} \langle f \rangle_{\text{exp}} \sim \frac{1}{N} \mathbf{Var} \langle f \rangle$$

$$\mathbf{Var} \langle f \rangle = \left\langle \left[f - \langle f \rangle \right]^2 \right\rangle$$



$$\sigma_*^2 = \mathbf{Var} M_* \sim \left(\frac{\partial \langle f \rangle}{\partial M} \right)^{-2} \mathbf{Var} \langle f \rangle_{\text{exp}}$$

analytical transparency,
 complete control
 but suboptimal

But we do have explicit expression:

$$\sigma_*^2 \sim \frac{1}{N} \left\{ \left(\frac{\partial \langle f \rangle}{\partial M} \right)^{-2} \langle [f - \langle f \rangle]^2 \rangle \right\}$$

Let us minimize it!

$$\frac{\delta}{\delta f(\mathbf{P})} \{ \dots \} = 0 \quad \text{whence} \quad f_{\text{opt}}(\mathbf{P}) = \frac{\partial}{\partial M} \ln \pi_M(\mathbf{P})$$

and the minimum value is Fisher's information!

could have been discovered long ago

FT, arXiv:physics/0108030

M is unknown

iterative procedure: $f_{\text{opt}, M_i}(\mathbf{P}) \rightarrow M_{i+1}$

Equivalence to ML from: $\langle f_{\text{opt}} \rangle = 0$

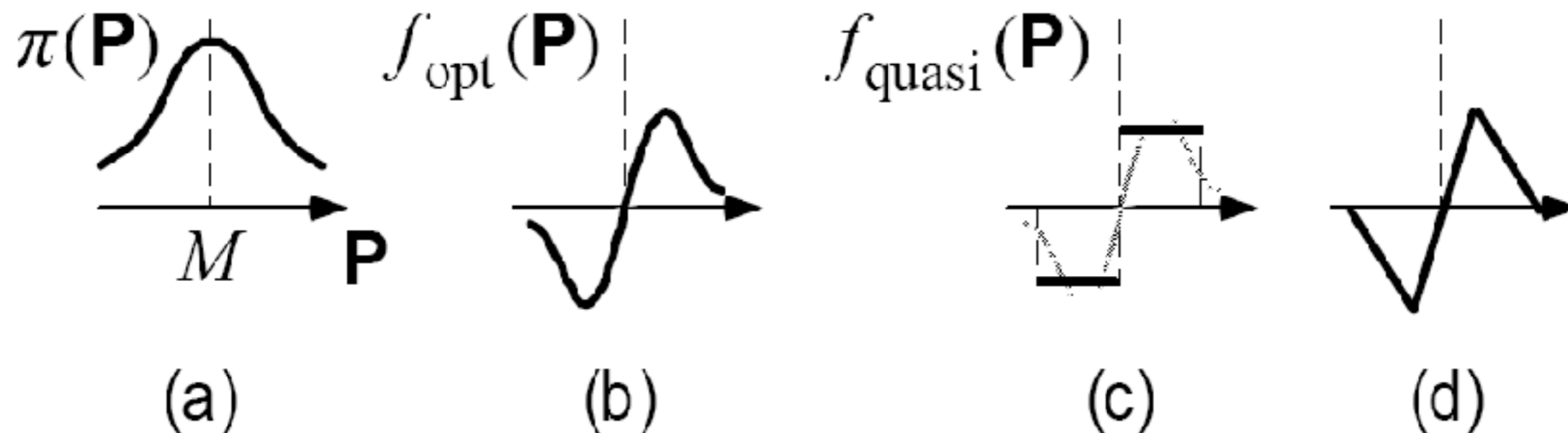
special case for linear dependence on M is known since 1992 --D.Atwood, A.Sony

$$\pi(\mathbf{P}) = \pi_0(\mathbf{P}) + g\pi_1(\mathbf{P}) \quad f_{\text{opt}}(\mathbf{P}) = \frac{\pi_1(\mathbf{P})}{\pi(\mathbf{P})}$$

Example 1

Cauchy distribution, has **no** mean, yet weights work:

$$\pi(\mathbf{P}) \propto \frac{1}{(M - \mathbf{P})^2 + \Gamma^2} \quad f_{M,\text{opt}}(\mathbf{P}) \sim \frac{(M - \mathbf{P})}{(M - \mathbf{P})^2 + \Gamma^2}$$



Any of these shapes would yield a valid estimate for M .

Example 2

Poisson vs Normal

$$\pi_{\mu}(P) \sim \exp\left[-(P - \mu)^2 / 2\sigma^2\right], \quad \varphi_{\text{opt},\mu}(P) \sim (P - \mu), \quad \varphi_{\text{opt},\sigma}(P) \sim (P - \mu)^2$$

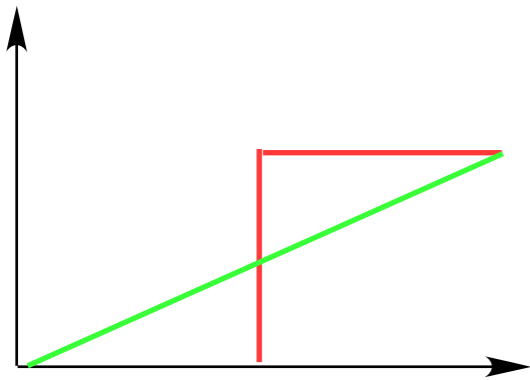
$$\pi_{\mu}(n) = e^{-\mu} \frac{\mu^n}{n!}, \quad \varphi_{\text{opt},\mu}(n) = \left(\frac{n}{\mu} - 1\right)$$

$$\pi_{\mu}(n) \sim \exp\left[-(n - \mu)^2 / 2\mu\right], \quad \varphi_{\text{opt},\mu}(n) \sim \left(\frac{n}{\mu} - 1\right) + \frac{1}{2} \left(\frac{n}{\mu} - 1\right)^2$$

for $\mu \sim 0.15-1.5$, the effect is 10-15%

Example 3

Continuous weight vs Cuts



Ratio of variances = 3

Ratio of sigmas = 1.71 ($3\sigma \rightarrow 5\sigma$)

Continuous weight in this case yields 1.71 times better variance than a cut.

Jorg Pretz: not bounded from above (!?!)

Jorg Pretz 1998, g-2

derived a special case of optimal weights

Example 4

Observation of top quark in all-hadrons channel by D0

P.C.Bhat, H.Prosper and S.S.Snyder,

Top quark physics at the Tevatron, hep-ex/9809011

... To make further progress, D0 performs a multivariate analysis using thirteen variables, described briefly in Table 10. ...

A particularly powerful (and unusual) variable is the average jet count, defined by

$$N_{\text{jets}}^A = \int_{15 \text{ GeV}}^{55 \text{ GeV}} E_T N(>E_T) dE_T / \int_{15 \text{ GeV}}^{55 \text{ GeV}} E_T dE_T,$$

where $N(>E_T)$ is the number of jets with transverse energy greater than E_T . This variable, inspired by the work of Tkachov [90] is interesting in that it assigns a nonintegral "number of jets" to the event. ...

now, a guidance:

$$f_{\text{opt}}(\mathbf{P}) = \frac{\partial}{\partial M} \ln \pi_M(\mathbf{P})$$

a continuous weight

- since the minimum is quadratic,
an approximation to optimal f should be good enough
- therefore works even when no formula for density
- great algorithmic flexibility
e.g. take any MC integrator...
- light in various situations

data processing in HEP then reduces to finding $f_{q\text{-opt}}$ for specific situations

analytical formula is a great force
e.g. to explore how raggedness affects quality

e.g. jet definition...

Non-uniform event sample

FT, arXiv:physics/0604127

$U_i \rightarrow \pi_{i,\theta}(P), \{U_i, P_i\}_i$ U_i is a control parameter

If all P_i for different U_i are independent then the situation reduces to the simple case by defining a composite event and the corresponding probability density:

$$\otimes_i (P_i) \quad \prod_i \pi_{i(\theta)}(P)$$

The opt. weight:

$$\varphi_{\text{opt}}(\{P_i\}) = \sum_i \frac{\partial}{\partial \theta} \ln \pi_{i(\theta)}(P_i) = \sum_i \varphi_{\text{opt},i}(P_i)$$

Explicit formula for var:

$$\mathbf{Var} \varphi_{\text{opt}} = \sum_i \left[\varphi_{\text{opt},i}(P_i) - \langle \varphi_{\text{opt},i} \rangle_{\theta_{\text{exp}}}^{\text{th}} \right]^2$$

Straightforward to code.

Notes on usage from Troitsk-nu-mass:

Implementation is straightforward
solution of systems of equations instead of optimum search

MC tests: equivalent to ML

Churns out results where MINUIT collapses ("narrow valleys")

Can easily accomodate information about Poisson etc.
(actually, this was the initial concern)

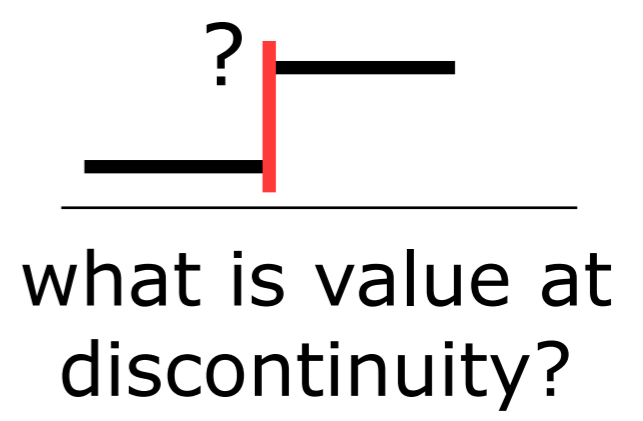
With poor statistics multidimensional systems of equations may not have a solution;
in practice this was not a problem but some research may be called for (same for Student-type correcting factors).

Deep mathematical reasons to consider weights.

~~Sets~~ → Functions and Functionals (+Categories)

conventional view of function: $x \rightarrow g(x)$

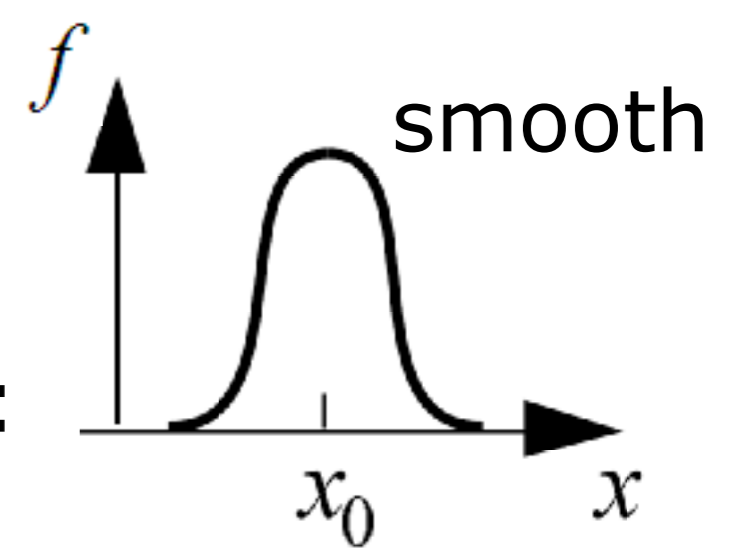
fully meaningful only for continuous $g(x)$



more satisfactory description:

$$f \rightarrow \langle g f \rangle \quad \left[= \int dx g(x) f(x) \right]$$

where f are the so-called "test functions":



OK for continuous functions

OK++ for discontinuous ("generalized") functions

instead of comparing point values,
one now compares weighted/smeared values

(recall Galerkin method from the geophysics talk by J.-P. Vilotte)

The same conceptual framework:

Optimal Jet Definition

$O(N)$ behavior

arXiv:hep-ph/0301185

Efficient multi-dimensional density modelling

from a random sample arXiv:physics/0401012

Quasi-optimal weights

+

Density modelling

+

Optimal Jet Definition

=

A systematic comprehensive framework

for HEP data processing