



## Alignment of the CMS Silicon Tracker

### Tapio Lampén<sup>1</sup> on behalf of the CMS collaboration

<sup>1</sup>Helsinki Institute of Physics, Helsinki, Finland Tapio.Lampen @ cern.ch

> 16.5.2013 ACAT2013 Beijing, China





# Outline



- Overview of CMS Tracker
- Track-based alignment
- Improvements in CMS Tracker alignment in 2012
- Summary





## **CMS** Detector







## CMS Tracker





1440 pixel modules 15148 strip modules (24244 sensors)

each has 3 translational and 3 rotational degrees of freedom + 3 curvature parameters

→ alignment challenge of 200.000 parameters



#### Various strip module shapes



# Why alignment?





### Track-based alignment

•Basic principle in all track-based alignment methods: minimization of

$$\chi^{2}(\mathbf{p},\mathbf{q}) = \sum_{j}^{tracks} \sum_{i}^{measurements} \left(\frac{m_{ij} - f_{ij}(\mathbf{p},\mathbf{q}_{j})}{\sigma_{ij}}\right)^{2}$$

with respect to alignment parameters **p** (together with **q**) •Modules cannot be treated independently, as alignment parameters correlate via tracks; approach used in CMS in 2012 is the *global fit* approach (Millepede II):

- $f_{ii}$  linearisation leads to a linear equation **Cp**=**b**,
- all alignment parameters solved simultaneously
- method can treat time-dependent effects and is now extended to position sensitive calibration parameters







# Alignment in CMS



•Full-scale alignment: individual sensors (sensor-level):

- 9 degrees of freedom (DoF) for pixel modules,
- 8 DoF's for strip sensors
- time-dependence of large pixel structures

•Alignment of larger rigid structures (frames of modules, layers, subdetectors);

### faster and less tracks required!

- •Alignments applied in 2012:
  - Prompt reconstruction: twice
  - Re-reconstruction: three times

Computing aspects in Millepede II (Full-scale alignment 2011):

Matrix equation to solve: **Cp=b** 

where **C** is n\*n matrix, n~200.000 (in practice 30% of elements non-zero, depends on input data)

Using Fortran program optimized for speed and space:

- iterative MINRES method
- OpenMP used for parallelized computing
- sparsity taken into account

CPU use 45h, Wall clock 10h with 8 threads on Intel Xeon L5520, 2.27 GHz, memory consumption 30 GB



### Alignment - sensor deformations

In reality, sensors are not planar Non-perpendicular tracks are biased, depending on tan  $\Psi!$ 

Investigation of surface shape using:

 $\Lambda u = \Lambda w * \tan \Psi$ 

Important for BPIX layer 1, large track angles, systematic residuals ~100µm at edge of the 66mm wide module

Alignment determines bow parameters, taken into account in hit reconstruction.

Also angles and offsets between two daisy-chained modules in outer Tracker are corrected in alignment





# Weak modes and mass constraints

 Minimization of residuals insensitive to some global distortions These weak modes can however bias track parameters



Solution: cosmic muon tracks

T. Lampén

 $\Delta y = \epsilon * r$ suspected in 2011, observed variation of Z mass as function of  $\Phi$  of positively

Example 3:

"sagitta": dy ~ r curvature bias

charged muon

#### phi-dependent curvature bias

Example 2: "twist": dΦ ~ z curvature bias of charged particles



weak mode even with cosmic muon tracks

**Solution**: 0T cosmic muon tracks or mass constraint ( $Z \rightarrow \mu \mu$ )

2 muons from Z decay not fitted independently (2x5 parameters), but as a fit of 9 parameters and Z mass as virtual measurement (RMS as uncertainty)



### Prompt Calibration Loop



- Prompt Calibration Loop (PCL)
  - calculates 6 alignment parameters for large structures of pixel
  - provides feedback within 48h with latest data to reconstruct the same run



T. Lampén

# 💽 PCL and Pixel movement in November 🎇

- During last month of pp-running in 2012 PCL was running for monitoring (not active)
- Major sudden movement of pixel half-shells along z detected in Nov 22nd (cooling failure)
- PCL activated on Nov 30th to recover this movement









### Muon Curvature Bias

- Several systematic distortions can bias track curvature K~±1/p,
- Z<sub>0</sub>->μ<sup>+</sup>μ<sup>-</sup> events reveal this bias: invariant mass fitted<sup>1</sup> as function of muon direction, separating μ<sup>+</sup> and μ<sup>-</sup>

1) invariant mass distribution fitted with wide fit range 75-105GeV/c<sup>2</sup>, Z<sub>0</sub> width set to PDG value of 2.495 GeV/c<sup>2</sup>, Fit function: a Breit-Wigner function convoluted with Crystal ball function (models finite track resolution and radiative tail) + exponential background











Reconstructed  $Z_0 \rightarrow \mu^+ \mu^-$  mass peak as function of  $\Phi$ 



Amplitude of sinusoidal shape clearly decreased with **weighted** input data, from 0.7 GeV/c<sup>2</sup> to 0.3 GeV/c<sup>2</sup> in barrel

N.B.: this study does not illustrate CMS muon reconstruction and calibration performance; momentum calibration is applied in addition in physics analyses



# Necessity of Z<sub>0</sub> Events



Reconstructed  $Z_0 \rightarrow \mu^+ \mu^-$  mass peak as function of pseudorapidity 2011 data



N.B.: this study does not illustrate CMS muon reconstruction and calibration performance; momentum calibration is applied in addition in physics analyses



## Lorentz Angle calibration and alignment



- Charge drift in magnetic field affects the measured hit position as  $\Delta x = tan(\theta_{LA}) * d/2$
- Most precise way to correct this is integration of  $\theta_{_{LA}}$  calibration to Millepede II alignment procedure
- Data with magnetic field ON and OFF used simultaneously: 60 M tracks (isolated muons, Z<sub>0</sub>→µ<sup>+</sup>µ<sup>-</sup>, cosmic ray muons and field OFF collision data)



#### Comparison of centermost modules from different layers 0.46 tan(0<sup>shift</sup>) 6.6 Layer 1 CMS Preliminary 2012 LAYERS Similar behaviour for Layer 2 **BPIX Ring 4** three layers: Layer 3 more intense radiation in layers 2 and 1 causes earlier decrease. 0.42 A few µm effect, but will be relevant in 2015 with 0.4 increased LHC luminosity Layer 3 Layer 2 0.38 ⊷ Layer 1 0.36 12 14 16 18 20 22 8 10 n 2012 Integrated Luminosity [fb<sup>-1</sup>]





innermost rings

page 17

### Increase followed by a decrease; more rapid for layer 2 smaller difference between rings Slow decrease pronounced for



For each layer: LA for modules of one ring as function of integrated luminosity

## Offset between R1-4 and R5-8 related to different

bias voltages.

# Lorentz Angle calibration and alignment





# Summary



•Alignment with Millepede II of 200.000 alignment parameters used routinely for 2 years

•Quick response to data taking with **run-by-run alignment** of large structures

- •Improvements in 2012:
  - Sensor bows widely used
  - Prompt Calibration Loop operational (end of 2012)
  - Curvature bias modes in better control with  $Z_0 \rightarrow \mu^+ \mu^-$  events
  - Alignment framework extended to treat calibration parameters
  - Lorentz Angle calibration integrated to alignment



### Challenges ahead





From R. Steerenberg, CERN-LHC, LHC Beam Operation Workshop Evian Dec-2012

T. Lampén



## Acknowledgements



- CMS Tracker Alignment group
- Helmholtz Alliance "Physics at the Terascale" https://www.wiki.terascale.de/index.php/Millepede\_II
- Magnus Ehrnrooth Foundation
- Waldemar von Frenckell Foundation

## Thank you for your attention!











### CMS Detector – transverse view





#### T. Lampén

Lorentz Angle validation, BPIX layers 1&2

Obtained LA calibration validated by comparing the combined Millepede approach (alignment + LA) to alignment with standalone calibration.

Distribution of median of unbiased residuals (DMR) between measured and predicted hit position for each module. Independent set of tracks from isolated muons used in validation.



Small, but visible improvement using integrated alignment and calibration.





### Lorentz Angle validation



LA calibration validated by comparing to alignment with standalone calibration.

Distribution of median of unbiased residuals (DMR) between measured and predicted hit position for each module. Independent set of tracks from isolated muons used in validation (from end of 2012).

Clear improvement using integrated alignment and calibration.

Double peak illustrates inconsistency between LA and alignment, corrected in the combined approach.

A few  $\mu$ m effect, but this approach will be more relevant in 2015 with increased LHC luminosity.





### Alignment - sensor deformations



Also, long strip modules in outer Tracker (TOB, outer TEC), consist of two daisy-chained sensors

Typical "kink" angle ~1.6 mrad, resulting to larger effect than sensor bow

3 additional parameters from bows and kink



Taking in to account both kinks (TOB, TEC) and bows (TIB, TOB, TEC, BPIX) makes the dw distribution flat







#### CMS Integrated Luminosity, pp



Out of the 23.3 fb<sup>-1</sup> of data delivered, CMS recorded 21.79 fb<sup>-1</sup>



# Timeline of Alignment in 2012





Full scale alignment based on 2012A+B and CRAFT data

### 2012C+D data used to align high-level structures



"greatest" alignment based on full era

- Object based on past used for future data
- Object based on past used for past data
- Short term interaction

### Displacements of pixel half barrels

- Time-dependent relative shift of 2 pixel half barrels noticed in 2011
- Monitored along z with unbiased primary vertex track-residuals
- 9 intervals found in 2011













Reconstructed  $Z_0^->\mu^+\mu^-$  mass peak as function of both pseudorapidity  $\eta$  and azimuthal angle  $\varphi$  of positive muon (previous plot with  $\eta$  dimension)

Z-axis same in both pictures, centered at peak value of all 2011 events (91.08  $\text{GeV/c}^2$ )



Overall pattern significantly reduced for 2012!

N.B.: this study does not illustrate CMS muon reconstruction and calibration performance; momentum calibration is applied in addition in physics analyses