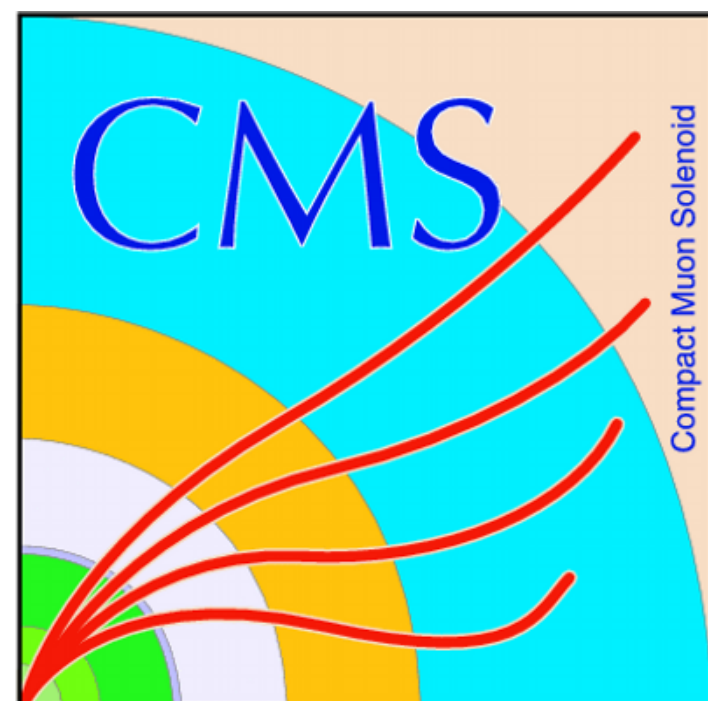
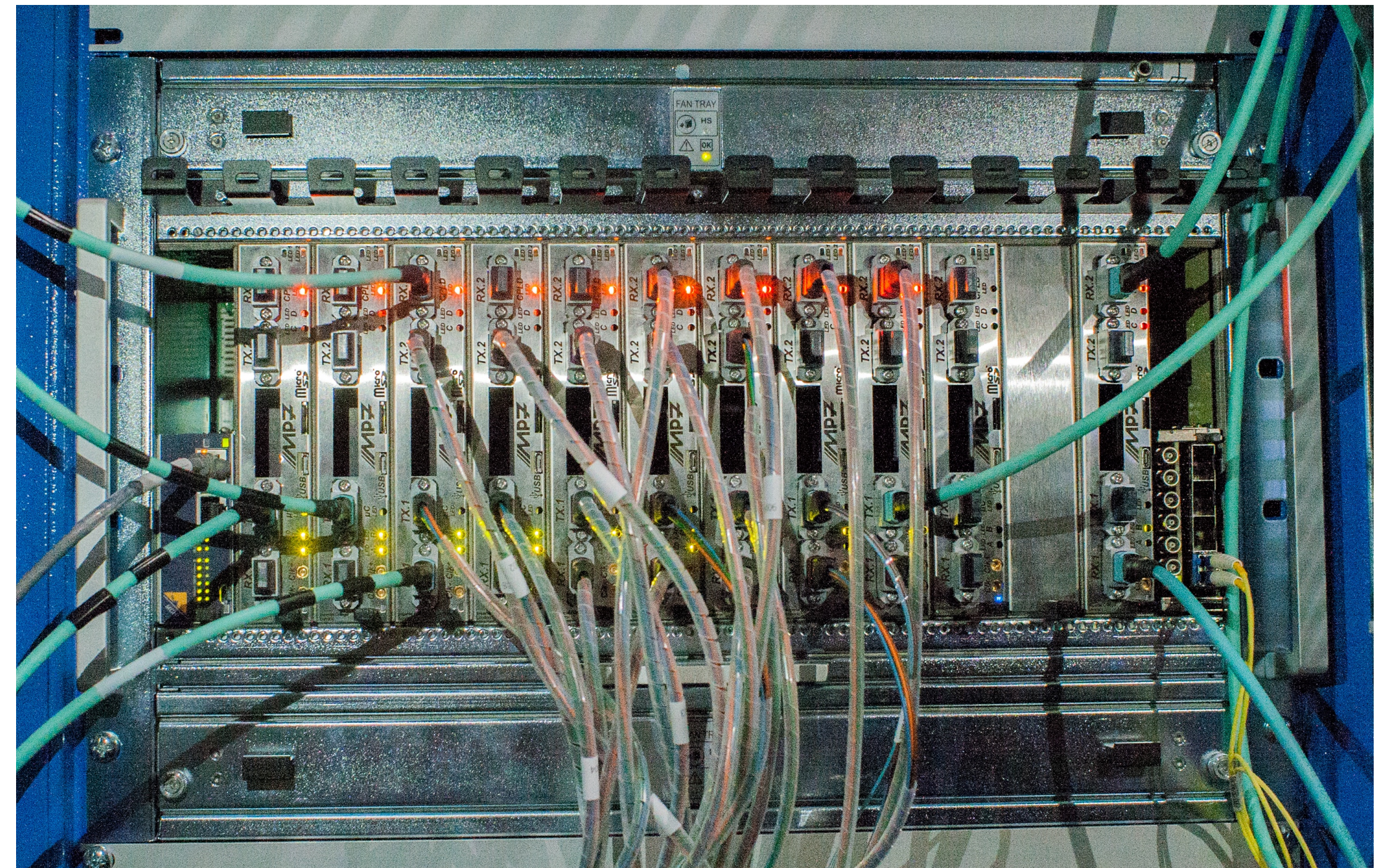


INTERNATIONAL CONFERENCE ON TECHNOLOGY AND INSTRUMENTATION IN PARTICLE PHYSICS

BEIJING, 22-26 MAY 2017

TOM JAMES, IMPERIAL COLLEGE LONDON

TRACK FINDING FOR THE LEVEL-1 TRIGGER OF THE CMS EXPERIMENT

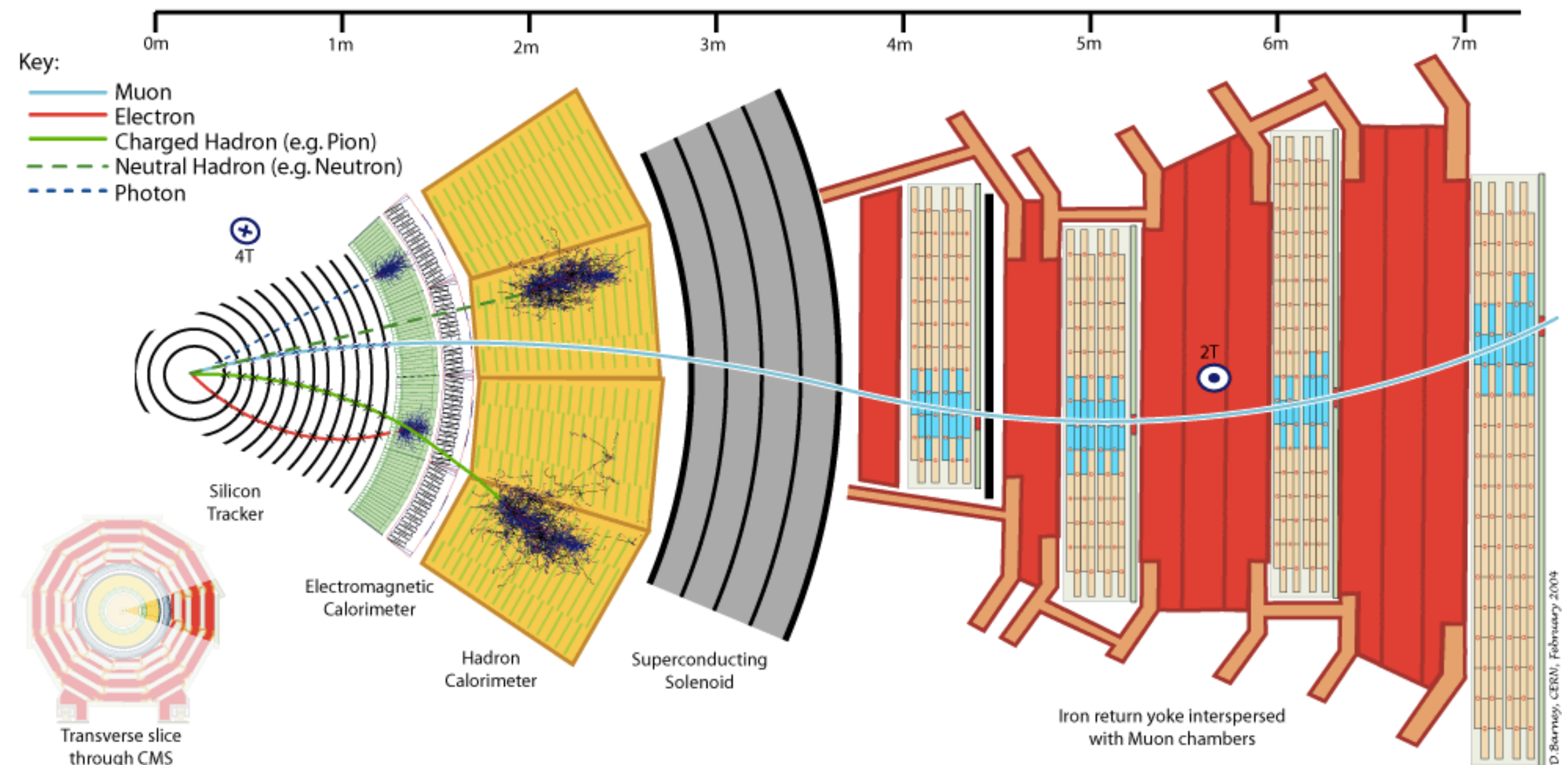


INTRODUCTION TO COMPACT MUON SOLENOID (CMS)

- ▶ **Large, all-purpose detector**, designed to investigate a **wide range of physics** (Higgs, Supersymmetry, Dark Matter). 20-40 **simultaneous collisions (pileup)** at 40 MHz
 1. **Silicon strip tracker** ($\sim 1.2\text{m}$ radius, 200 m^2 area), largest silicon tracker in operation
 2. Within **3.8 T** superconducting solenoid. **Transverse momentum (p_T)** measured with curvature in B-field
 3. **Level-1 (L1) trigger**, latency $O(3\text{-}4\text{ }\mu\text{s})$, rejects uninteresting events, rate reduction $O(\times 400)$
 4. Data size/rate from tracker **too large** to use in L1-trig

p_T = curvature in transverse direction to beam

η = angle in longitudinal direction to beam



HIGH LUMINOSITY LHC

precision measurements, **push** search limits,
rare processes

- ▶ By 2026 - **LHC** will be **upgraded** in **luminosity** -> 2-3x improved **statistics by 2035 vs no upgrade**
- ▶ **Silicon strip tracker will be replaced** (radiation damage) - Phase II CMS
- ▶ **Challenging high occupancy conditions, ~15,000 tracks per bx**, must **perform \geq at present**
- ▶ Need completely **new handle** at L1 trigger, to keep rate < 750 kHz, while maintaining sensitivity to interesting physics
- ▶ **New tracker design** will allow **read out of some data at 40 MHz**

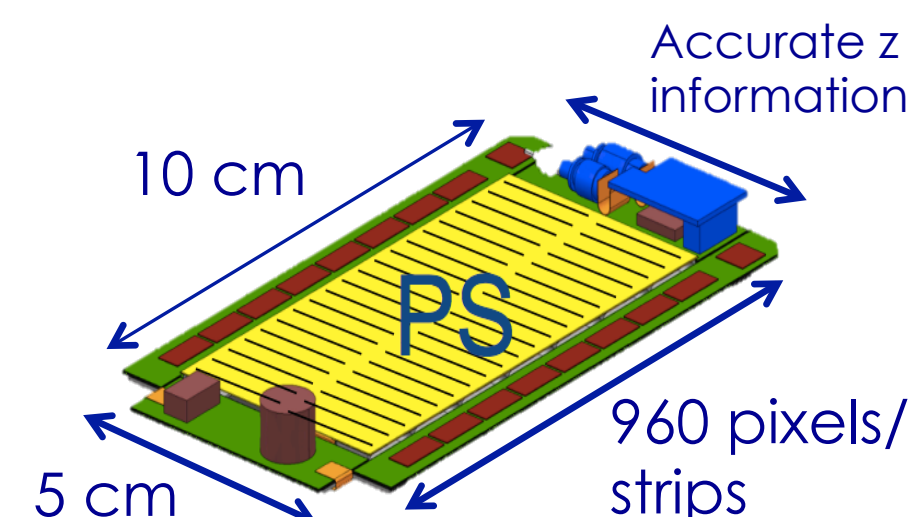


INTRODUCTION

CMS TRACKER UPGRADE

See A. König, *The CMS Tracker Phase II Upgrade for the HL-LHC era*

“PS” Pixel + Strip Modules $20 < r < 60$ cm



Strip Sensor × 2:
2.5 cm × 100 μm

+

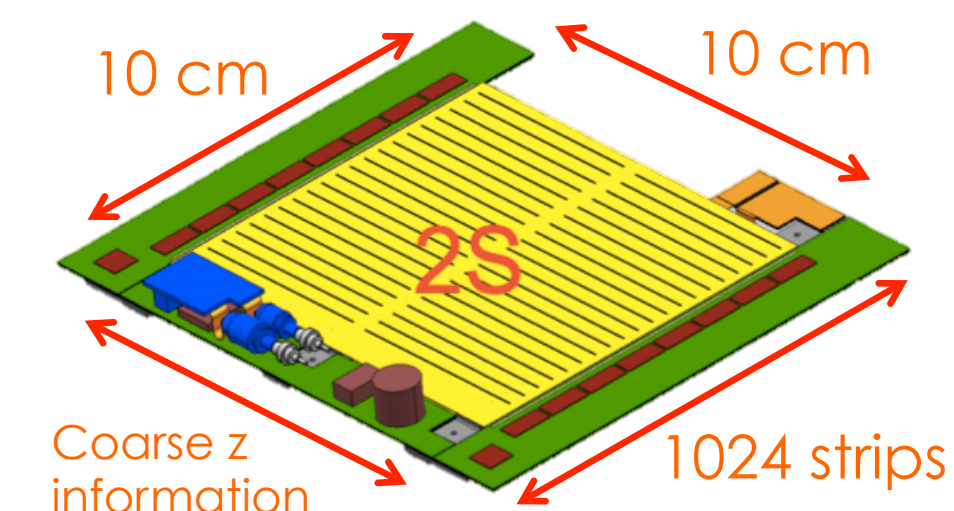
Pixel Sensor × 32:
1.5 mm × 100 μm

“2S” 2 Strip Modules $r > 60$ cm

Strip Sensor × 2:
5 cm × 90 μm

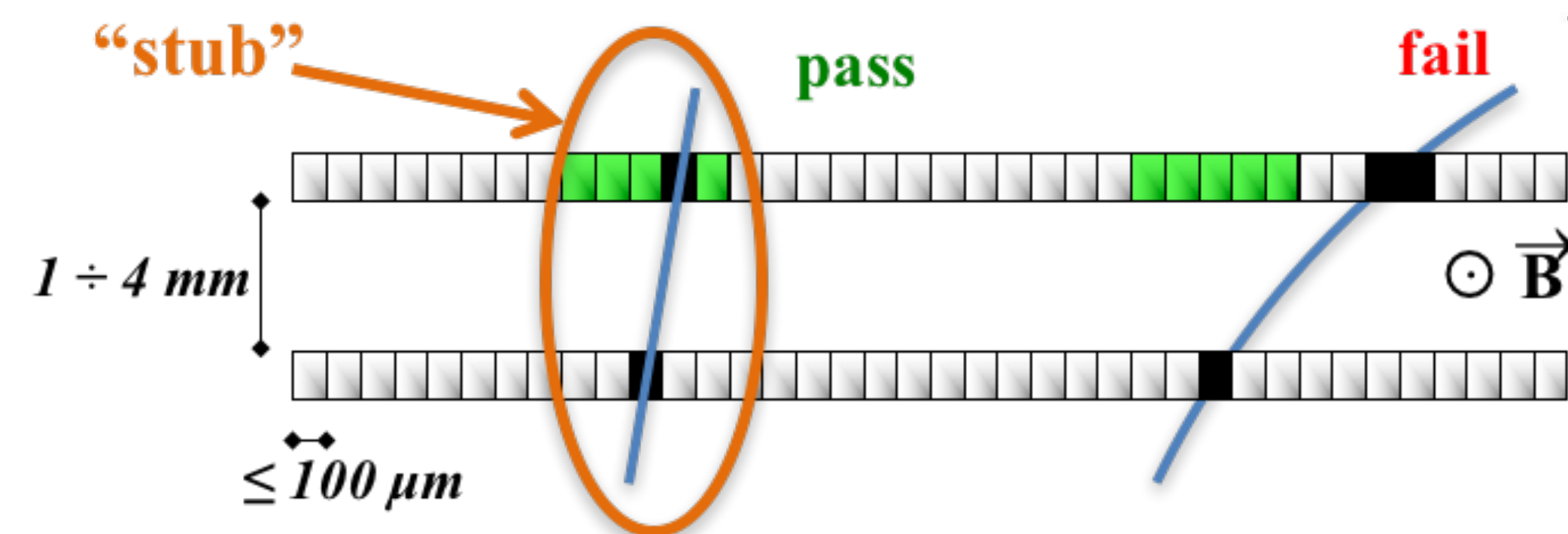
+

Strip Sensor × 2:
5 cm × 90 μm

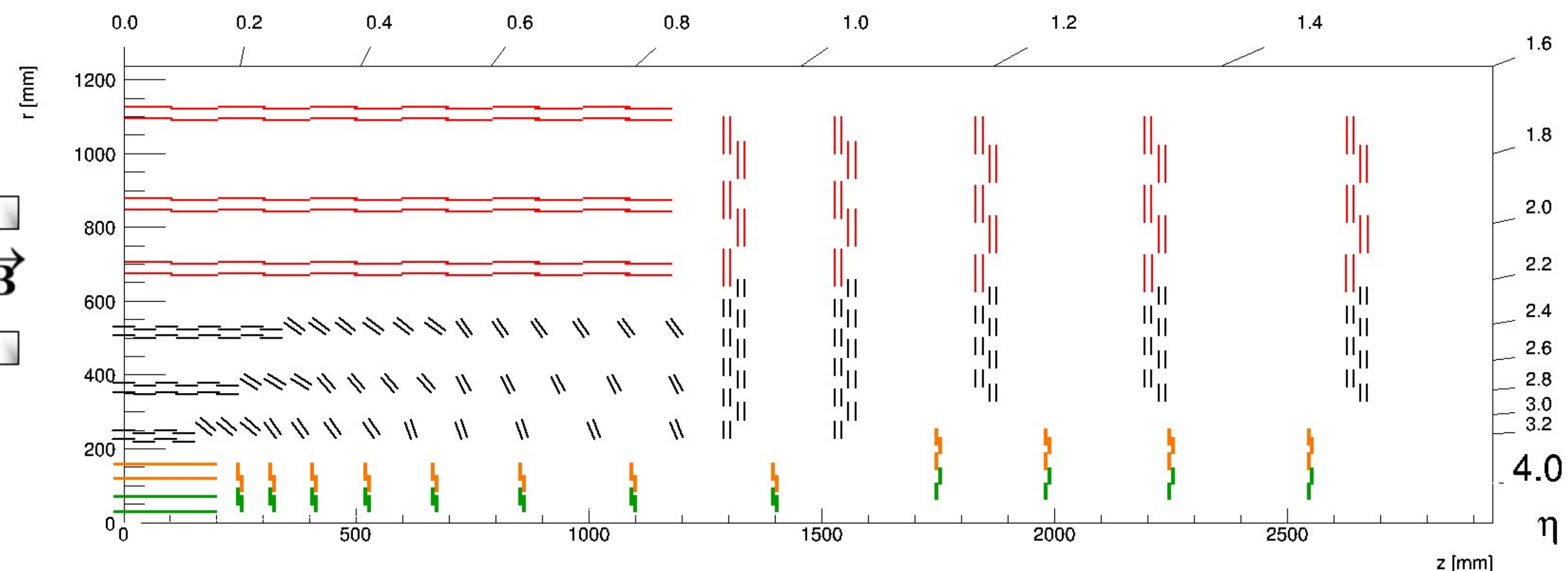


- ▶ High p_T tracks signs of interesting physics (decays of high mass particles)
- ▶ **Novel tracking modules** utilise two **1.6-4.0 mm spaced silicon sensors**, to **discriminate $p_T > 2-3$ GeV**
 - ▶ Forward these **stubs** to **off-detector trigger electronics** - rate reduction $O(10)$

2S PS



Innovative stacked module ideas originated at Imperial College. Prototype modules under beam-testing



Proposed upgraded tracker geometry

TRACK TRIGGER PROPOSAL

- ▶ ~4 μs available for track finding (~12.8 μs total L1)

- ▶ Very high data rates (~20,000 stubs per bx)

- ▶ **Proposal:** A Track Finding Processor (TFP)

- ▶ Data-stream FPGA-based processing board

- ▶ Processes 1/8 of tracker in φ and 1/(time multiplex period)

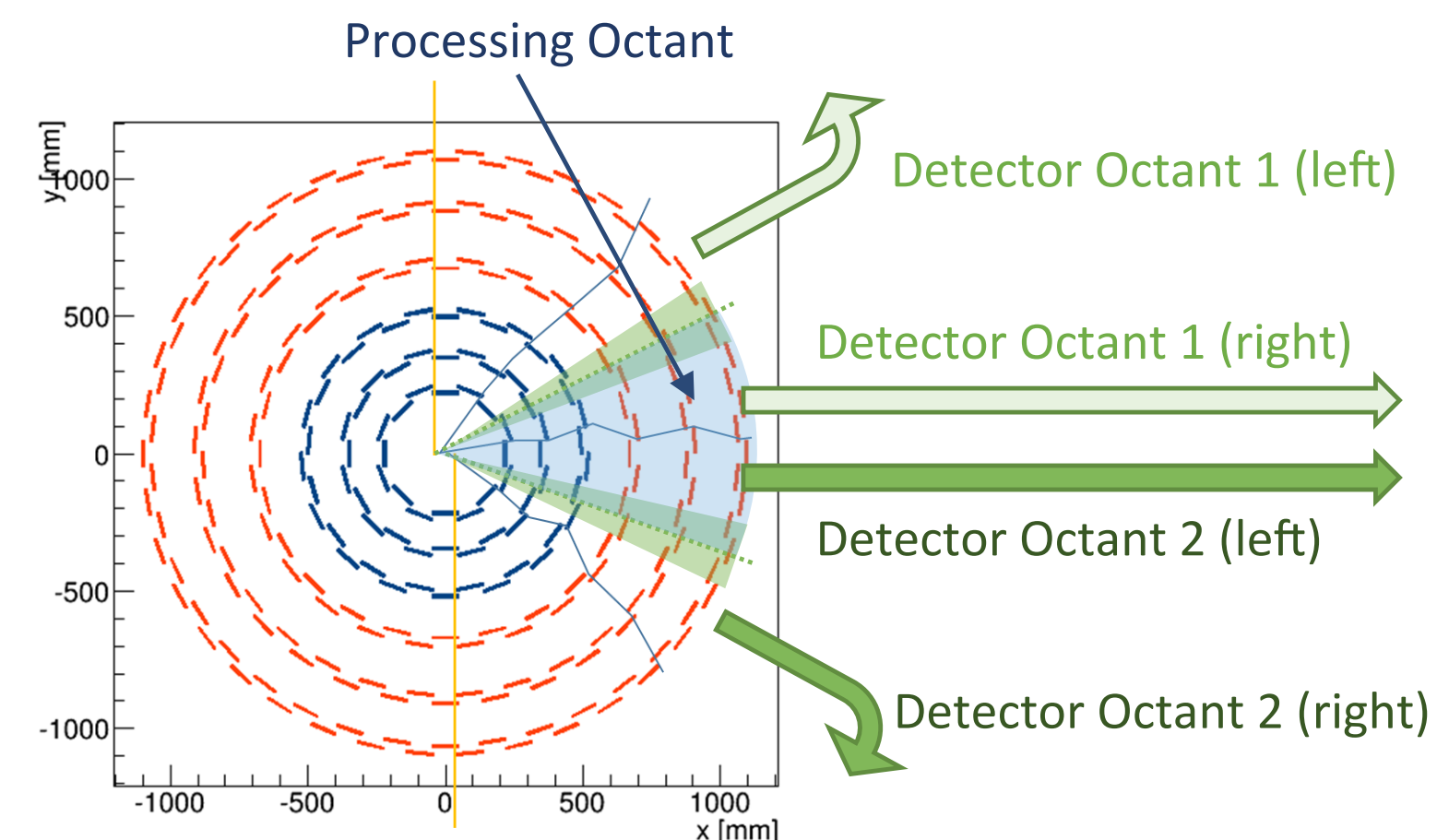
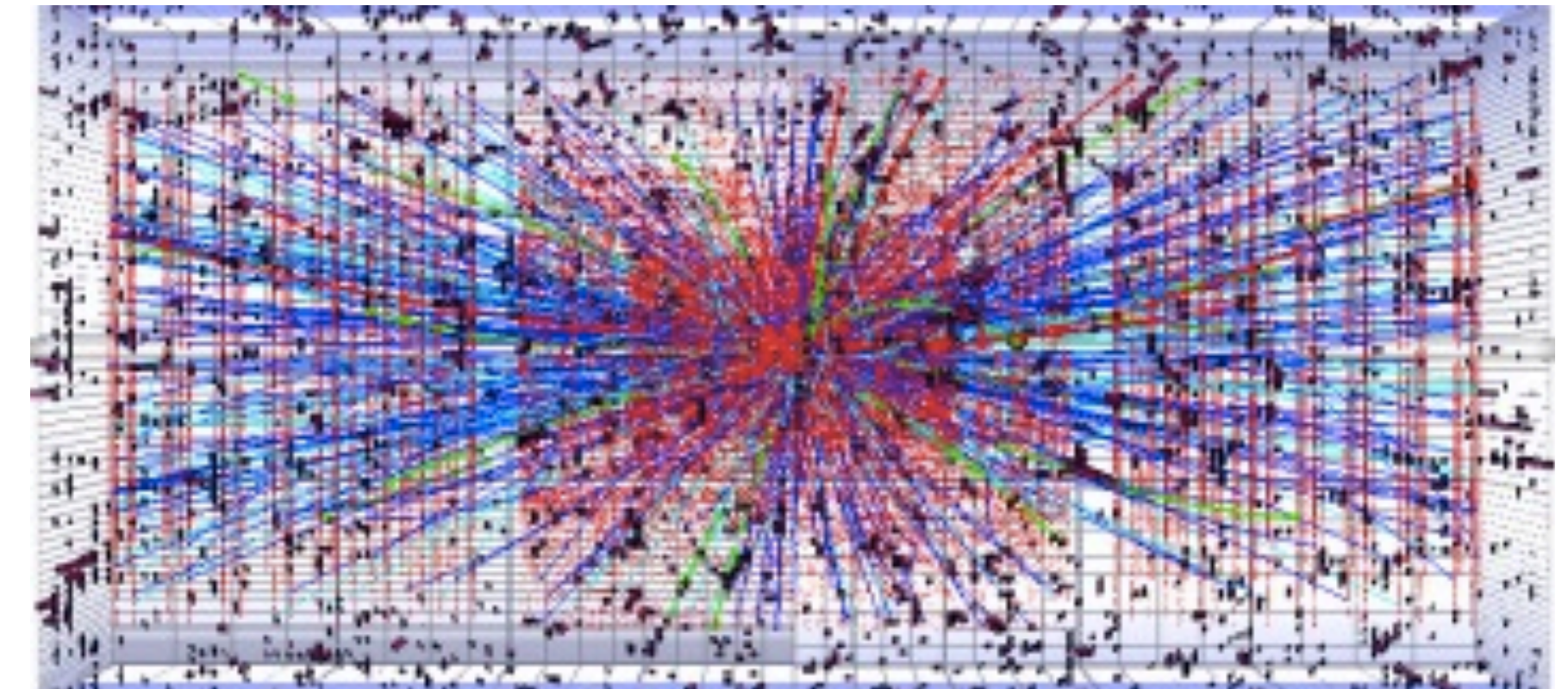
- ▶ **Choice** of physical/time segmentation dictated by data rates out of the detector and into FPGA board

- ▶ **Objective:** Build **hardware demonstrator** to prove **feasibility** and **capability** of such an object

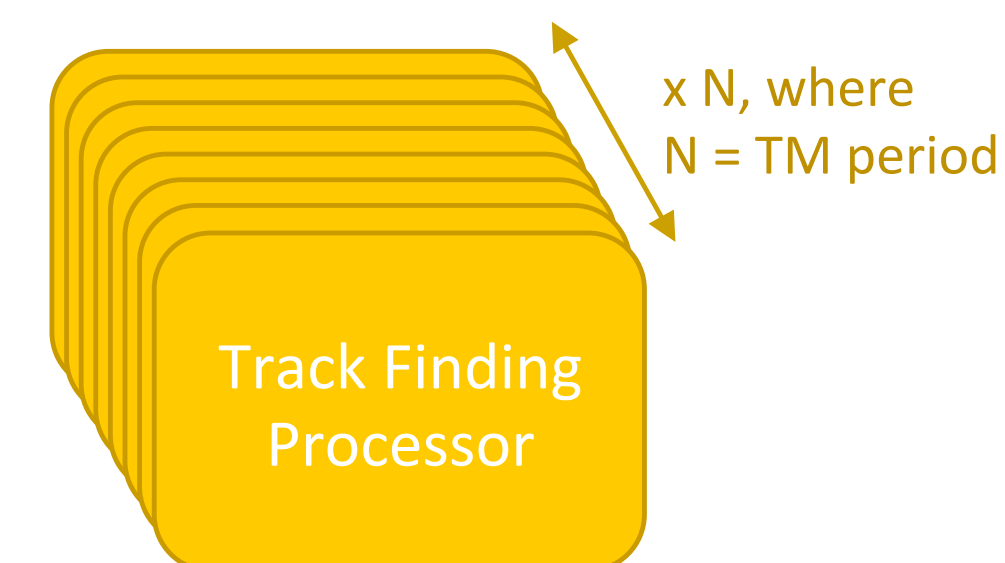
- ▶ Each TFP operates **independently**

- ▶ One TFP becomes the **demonstrator slice**

pileup 140 simulation



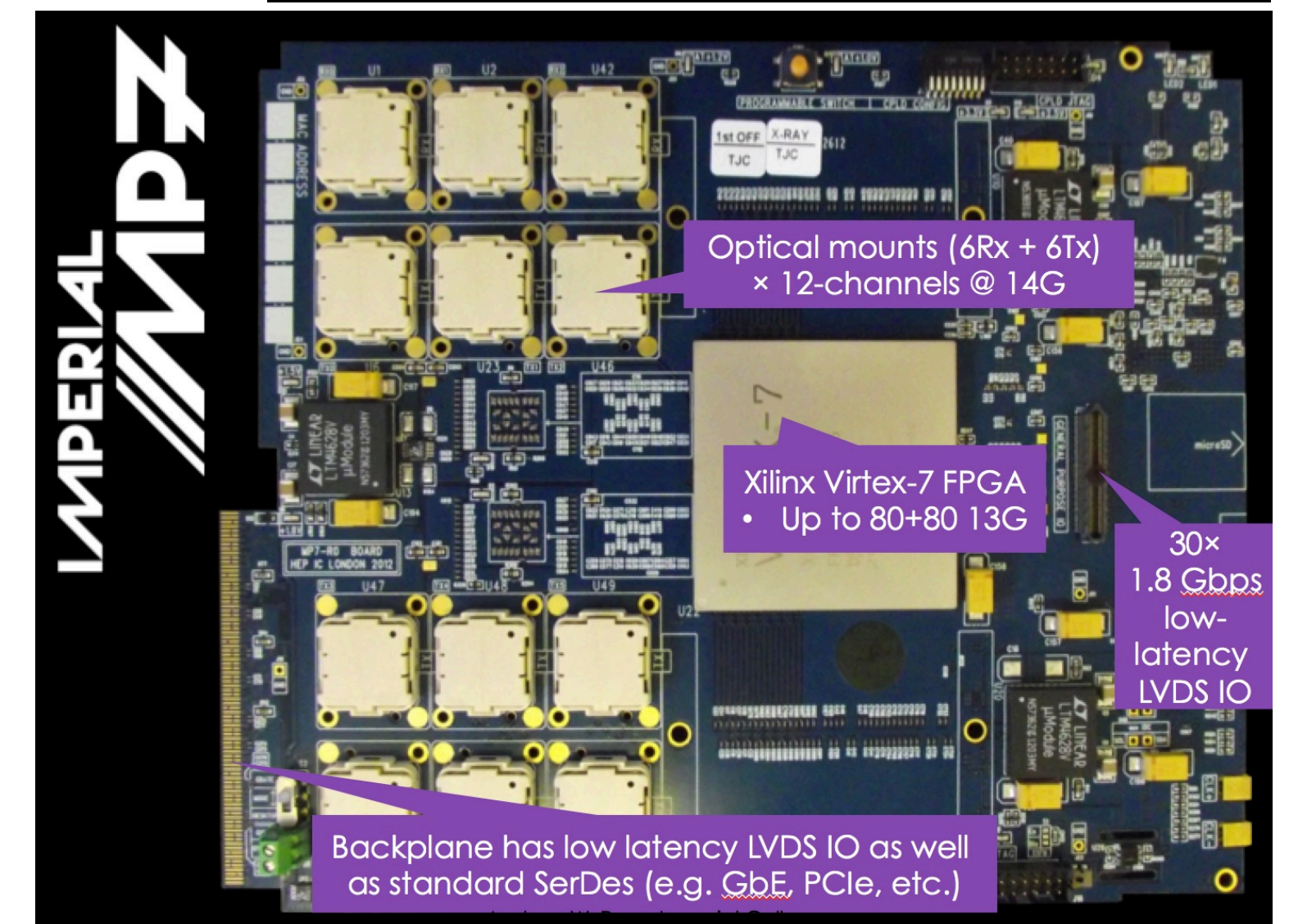
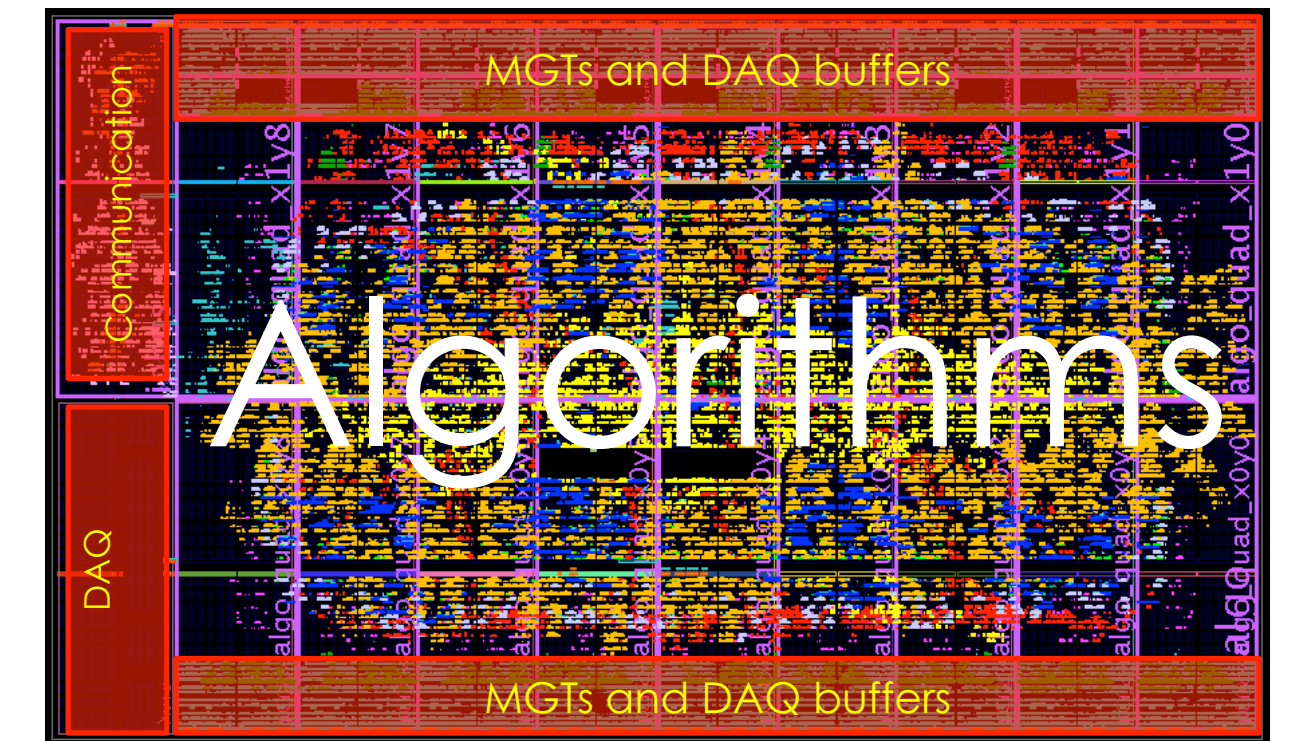
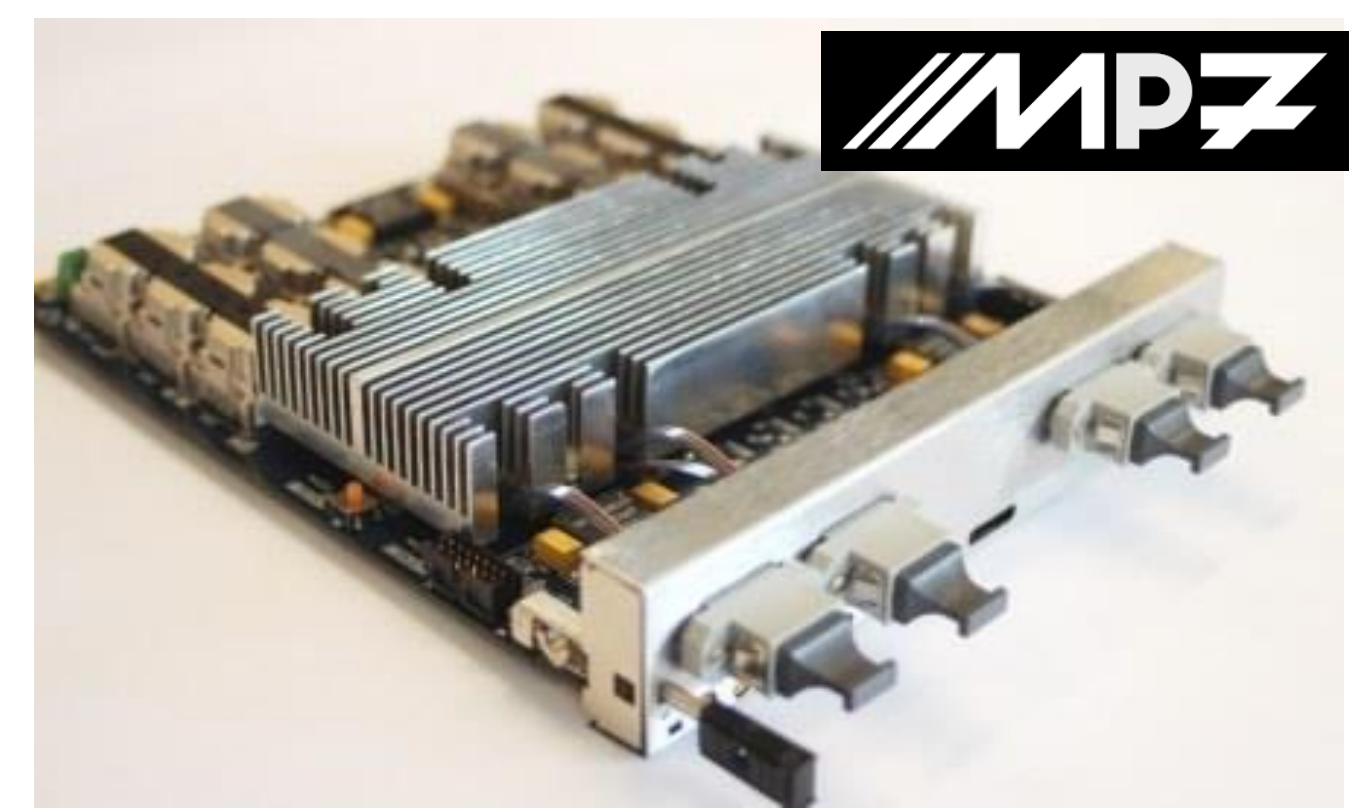
N BOARDS = 8 X TMP



THE IMPERIAL MASTER PROCESSOR 7 (MP7)

- ▶ A generic, **high-performance FPGA**, **high-bandwidth**, **data-stream processing double-width AMC card**
- ▶ Currently used widely in CMS trigger
- ▶ **Xilinx Virtex-7 690 FPGA**
- ▶ **72 optical transmitters/receivers** running at **10.3 Gbps** 8b/10b
 - ▶ Usable optical bandwidth **0.55 Tbps** each way
- ▶ **Infrastructure firmware** that provides transceiver buffering, I/O formatting & external communication and configuration kept separate from algorithm space

See A. Thea, The CMS Level-1 Calorimeter Trigger Upgrade for LHC Run II

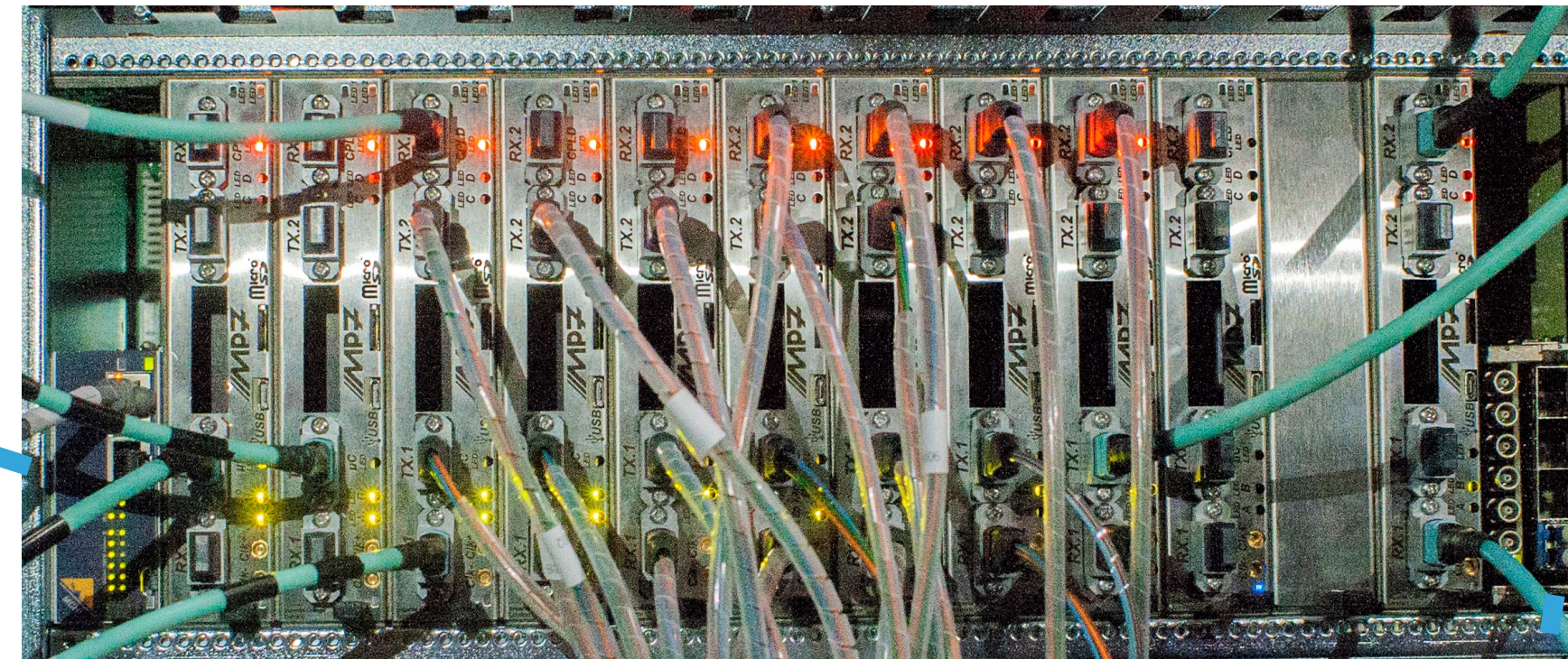


DEMONSTRATOR SYSTEM

11 MP7s in MicroTCA crate



MCH



AMC13

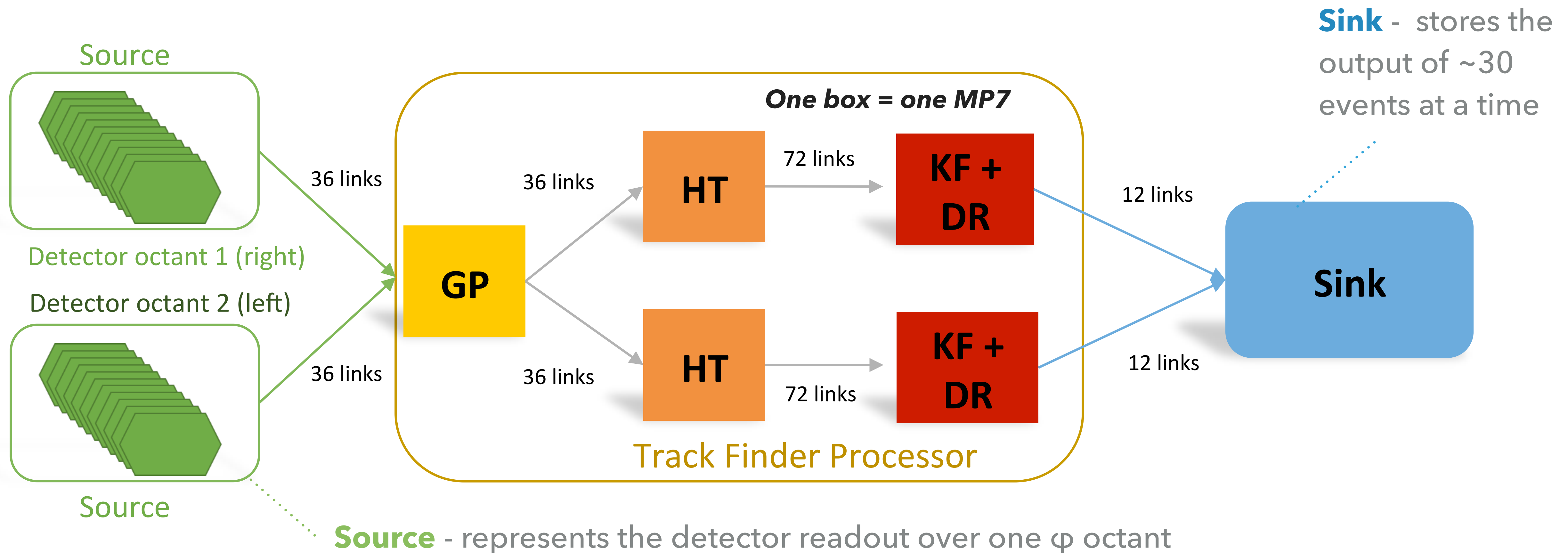
- ▶ CERN rack provides turbine, 3-phase power, air deflector, water cooling/heat exchangers
- ▶ MicroTCA carrier hub (MCH) for GbE communication via backplane
- ▶ AMC13 for synchronisation, timing & control



THE TRACK FINDING PROCESSOR (TFP)

FPGA firmware - generated by a specialised computer language used to describe structure and behaviour of electronic circuits

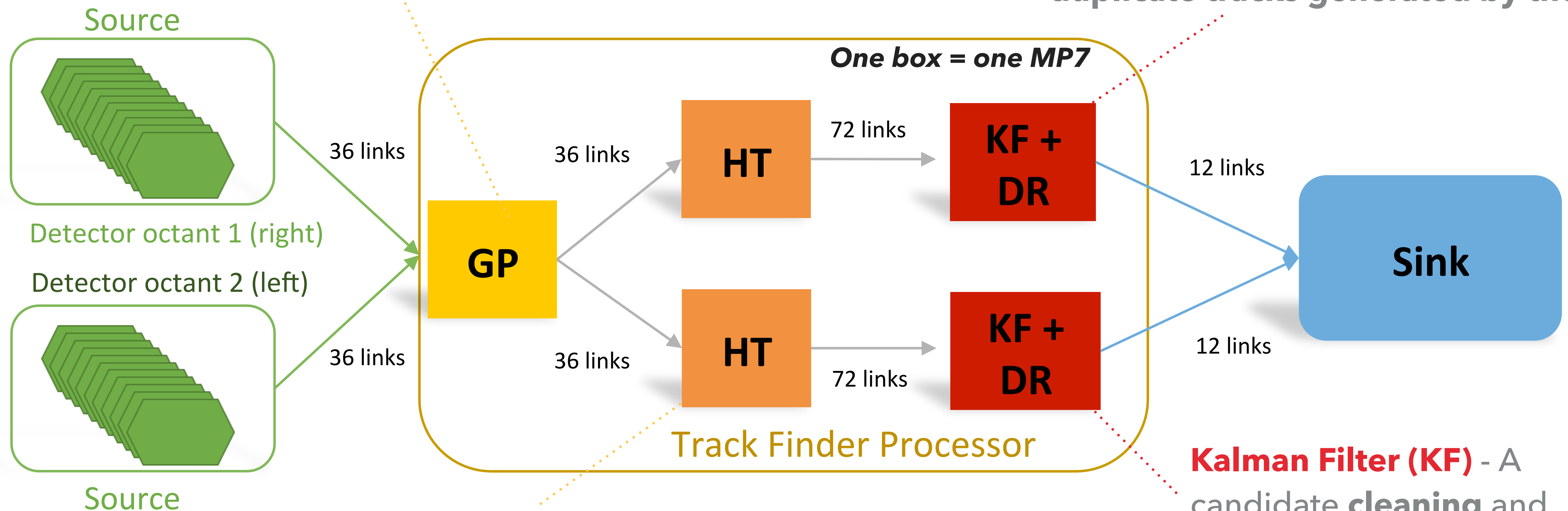
- TFP firmware is divided into logical algorithm elements, where (for demonstration), **each element implemented on a separate MP7** - can extrapolate to future FPGA resources



THE TRACK FINDING PROCESSOR (TFP)

Geometric Processor (GP) - pre-processes stub data, and divides the octant into 36 finer sub-sectors

Duplicate Removal (DR) - Uses precise fit information to **remove** duplicate tracks generated by the HT



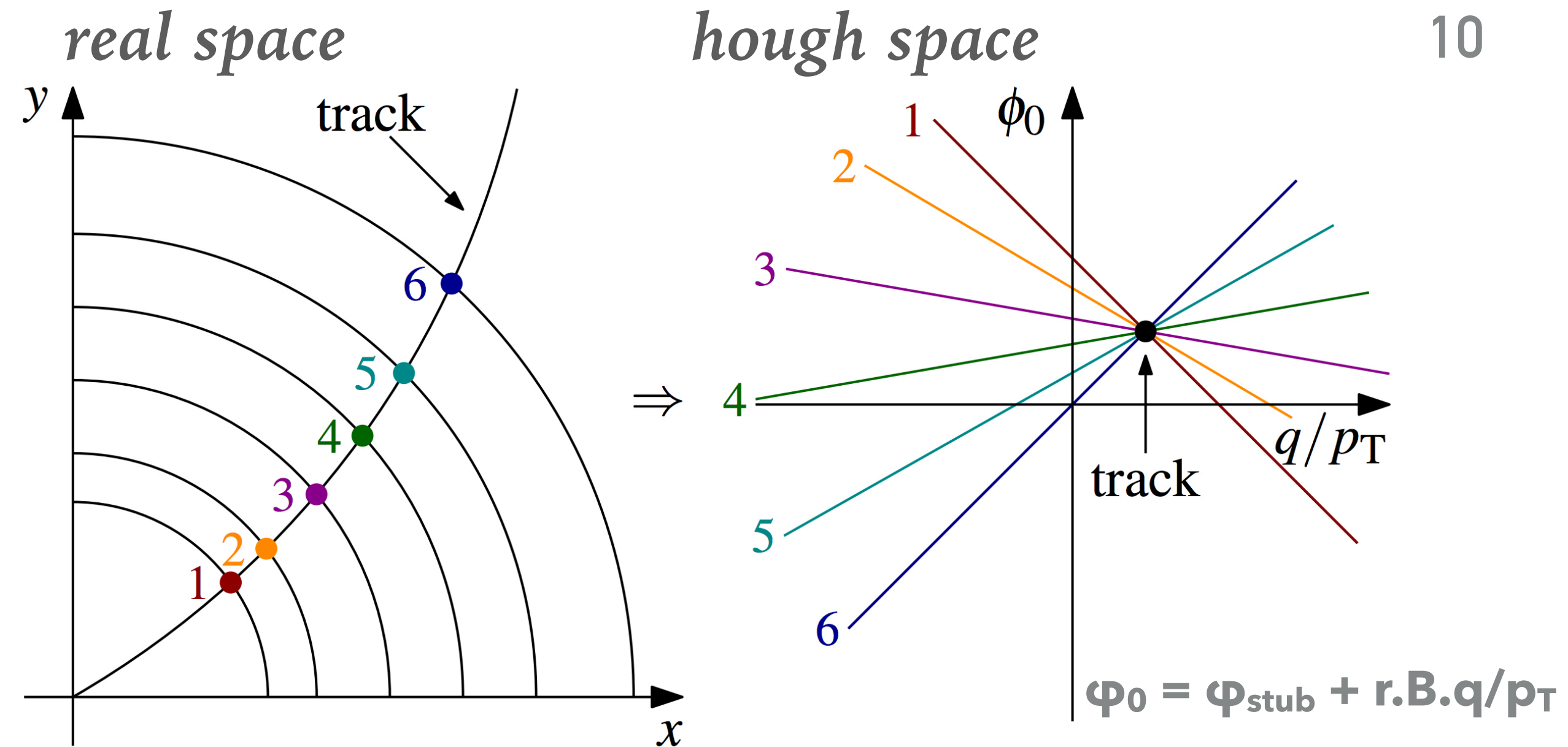
Hough Transform (HT) - A highly **parallelised** first stage **track-finder** that identifies **groups of stubs consistent** with a track in the **r-φ plane**

Kalman Filter (KF) - A candidate **cleaning** and **precision fitting** algorithm

2D HOUGH TRANSFORM (HT)

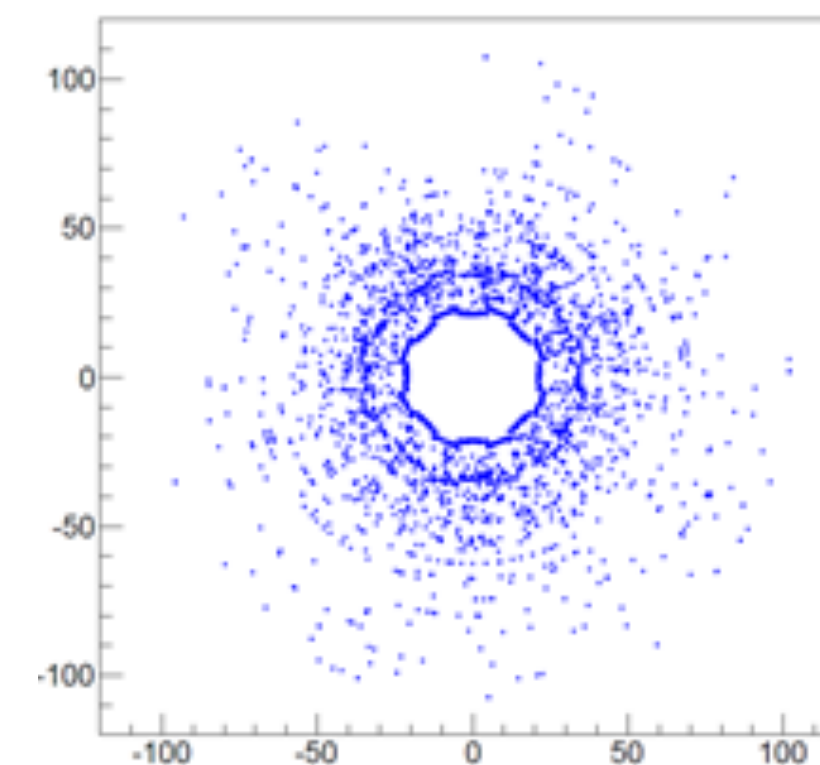
- ▶ Widely used **feature extraction technique** to find **imperfect instances of objects** within a space e.g tracks in our tracker hit map
- ▶ Search for **primary tracks in the r - ϕ plane**, using the **parameterisation $(q/p_T, \phi_0)$**
- ▶ **Stub positions correspond to straight lines in Hough Space**
- ▶ **Where 4 or more lines intersect \rightarrow track candidate**

q/p_T is the free parameter, but p_T estimate from stacked modules used to constrain allowed q/p_T space

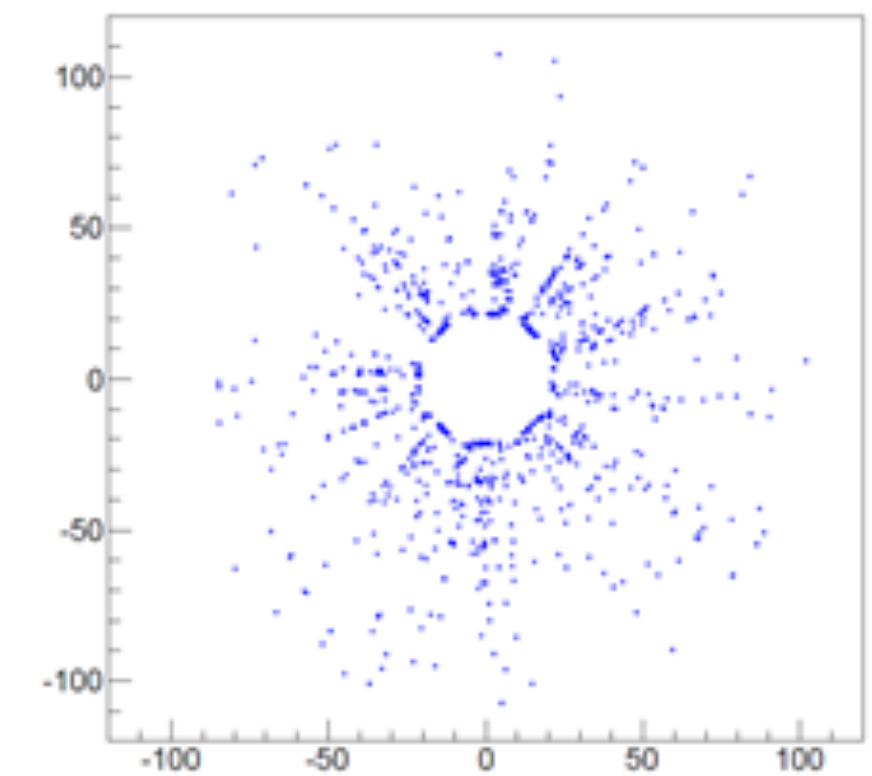


$\sim 20,000$
stubs in tracker

~ 270 track
candidates



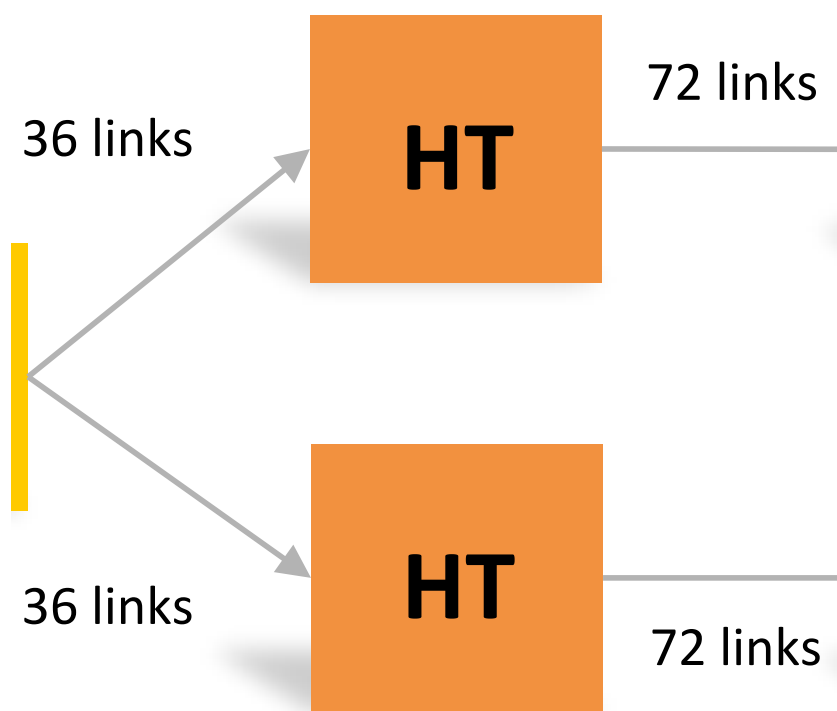
Hough Transform



DEMONSTRATOR FIRMWARE

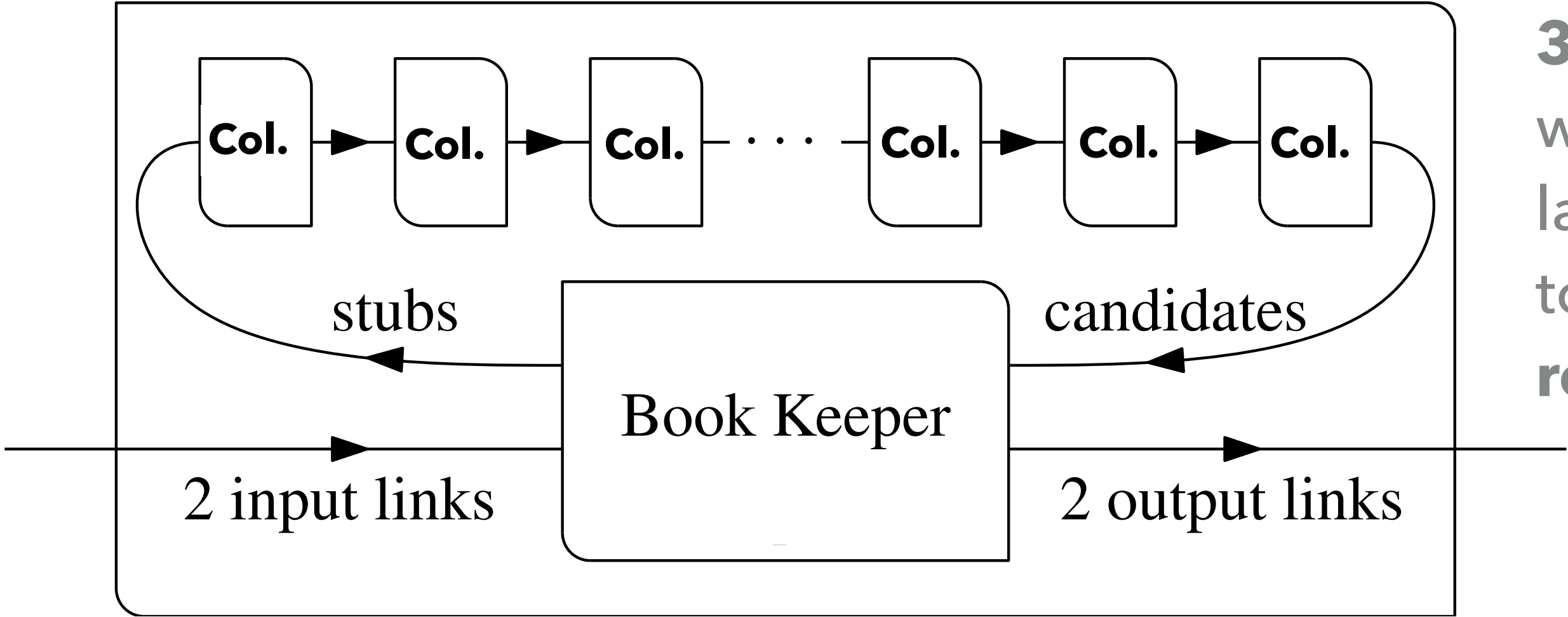
HOUGH TRANSFORM (HT)

- ▶ Each sub-sector implemented as a fully independent, pipelined 32 x 64 array

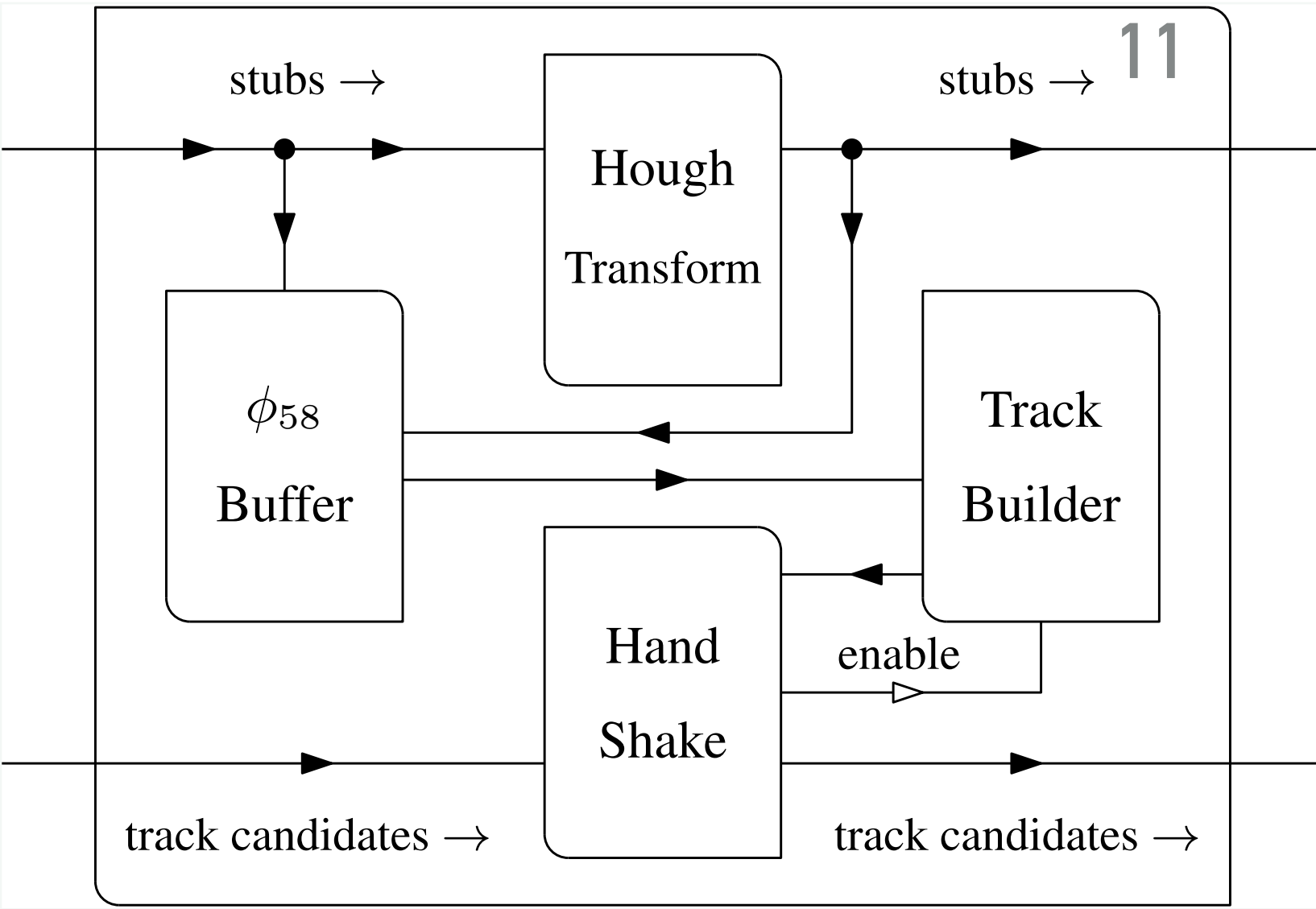
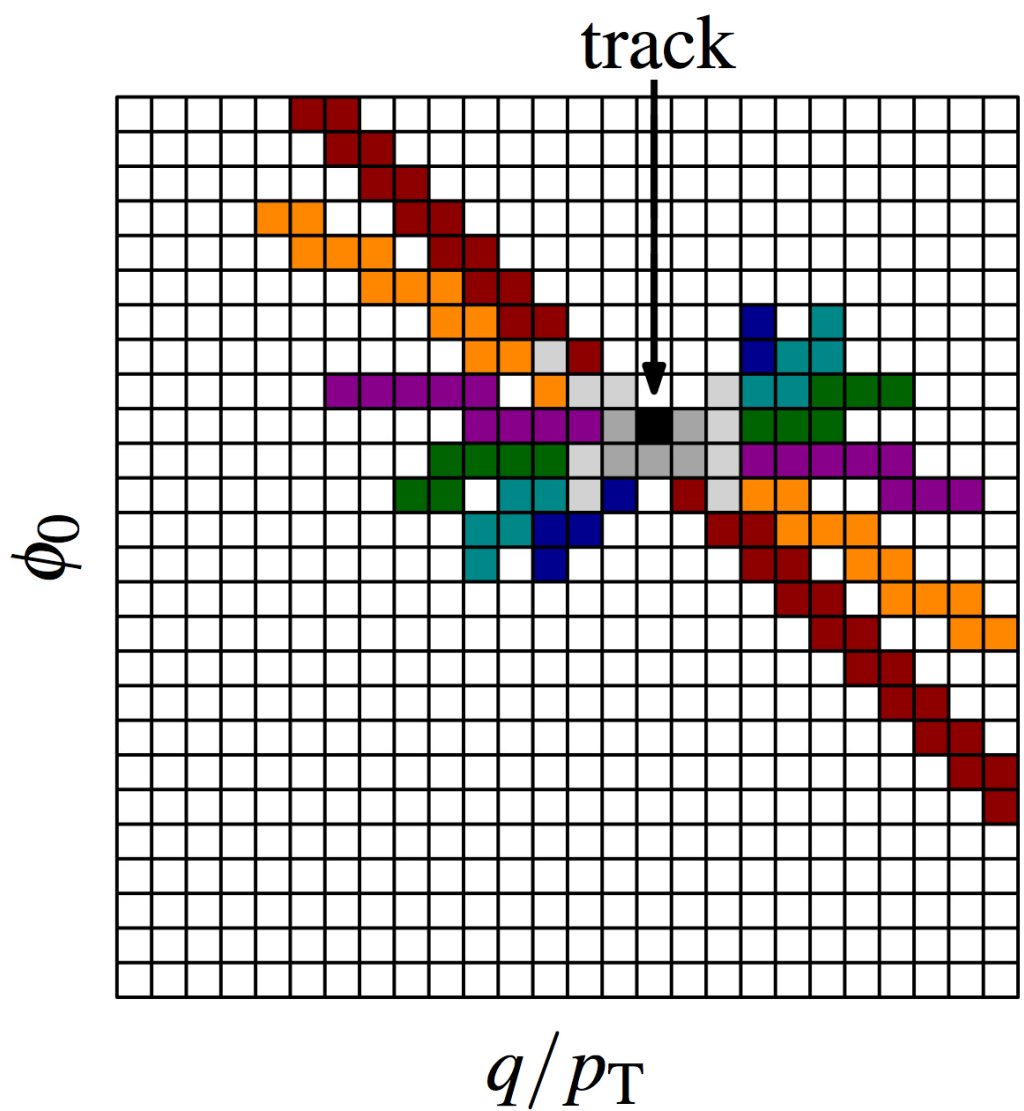


1) Book keeper receives stubs and propagates to each q/p_T column in turn.

p_T estimate from stacked modules used to constrain allowed q/p_T space



One HT sub-sector, 18 per MP7



One HT Column, 32 per sub-sector

3) Candidates marked with stubs from > 4 layers propagate back to the **Book Keeper for read-out**

DEMONSTRATOR ALGORITHMS

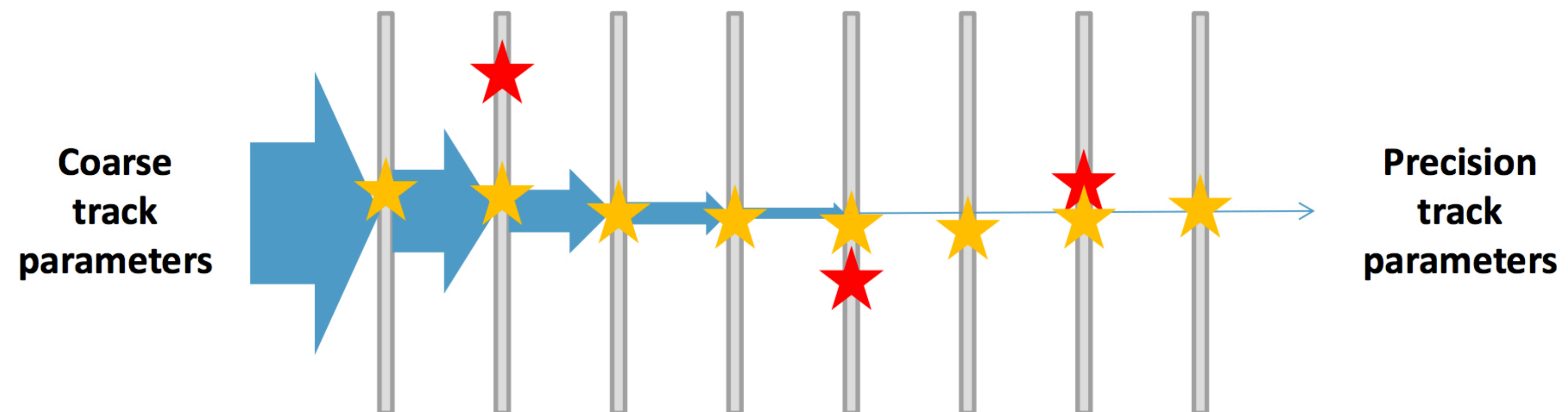
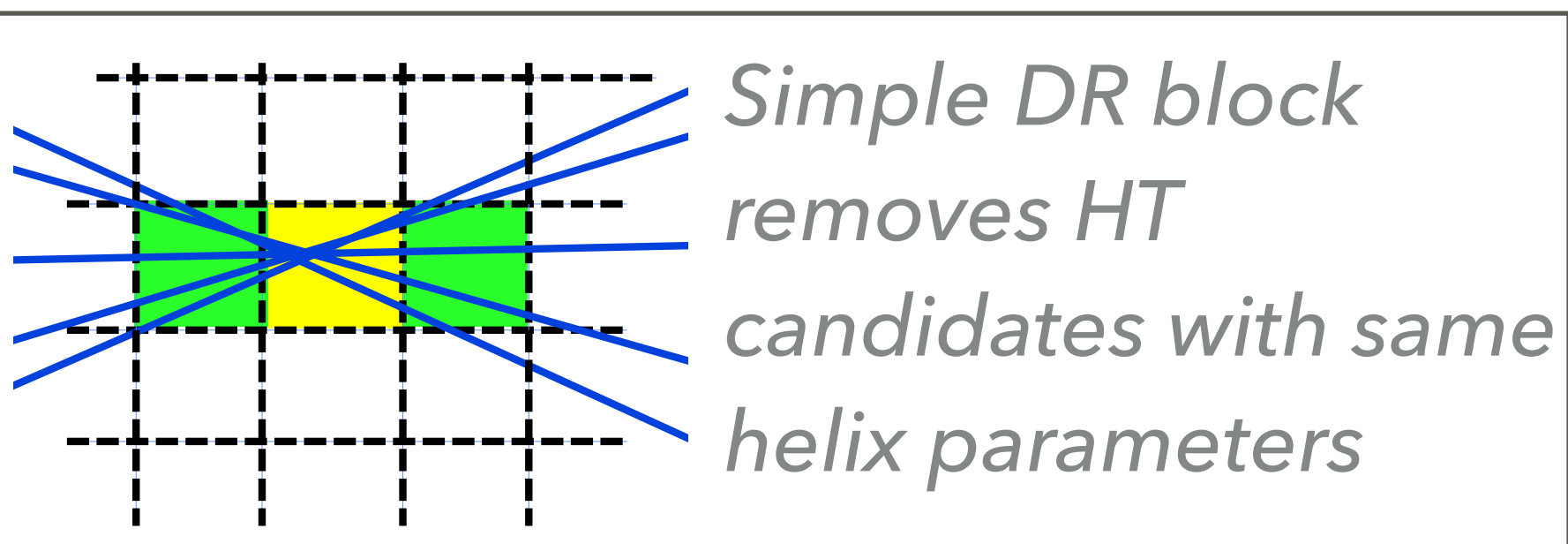
3D KALMAN FILTER (KF)

state = estimated track parameters

12

measurements = stubs on track candidate

- Commonly used **iterative algorithm**; **series of measurements** containing inaccuracies and noise -> estimates of **unknown variables**
 1. Initial estimate of track parameters (HT seed) & their uncertainties
 2. Stub used to update state (weighted average)
 3. χ^2 calculated, used to reject false candidates, incorrect stubs on genuine candidates
 4. Repeat until all stubs are added



DEMONSTRATOR FIRMWARE

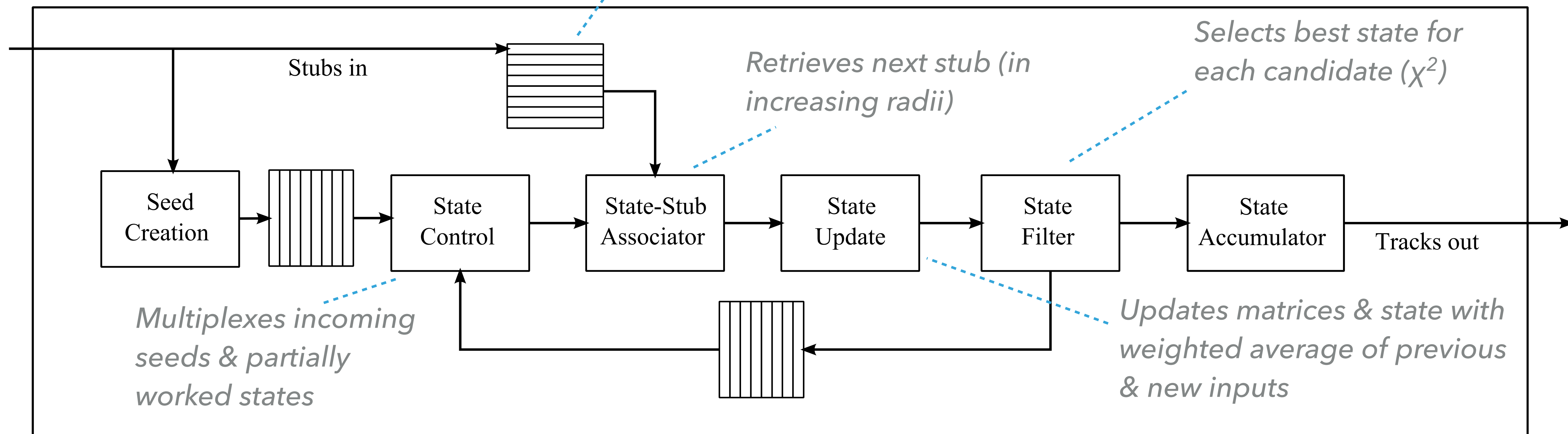
KALMAN FILTER (KF)

state = estimated track parameters

13

Incoming stubs
stored in BRAM for
later retrieval

REPEAT FOR (A CONFIGURABLE)
ACCUMULATION PERIOD (OR UNTIL 4
STUBS ARE ADDED TO ALL TRACKS)



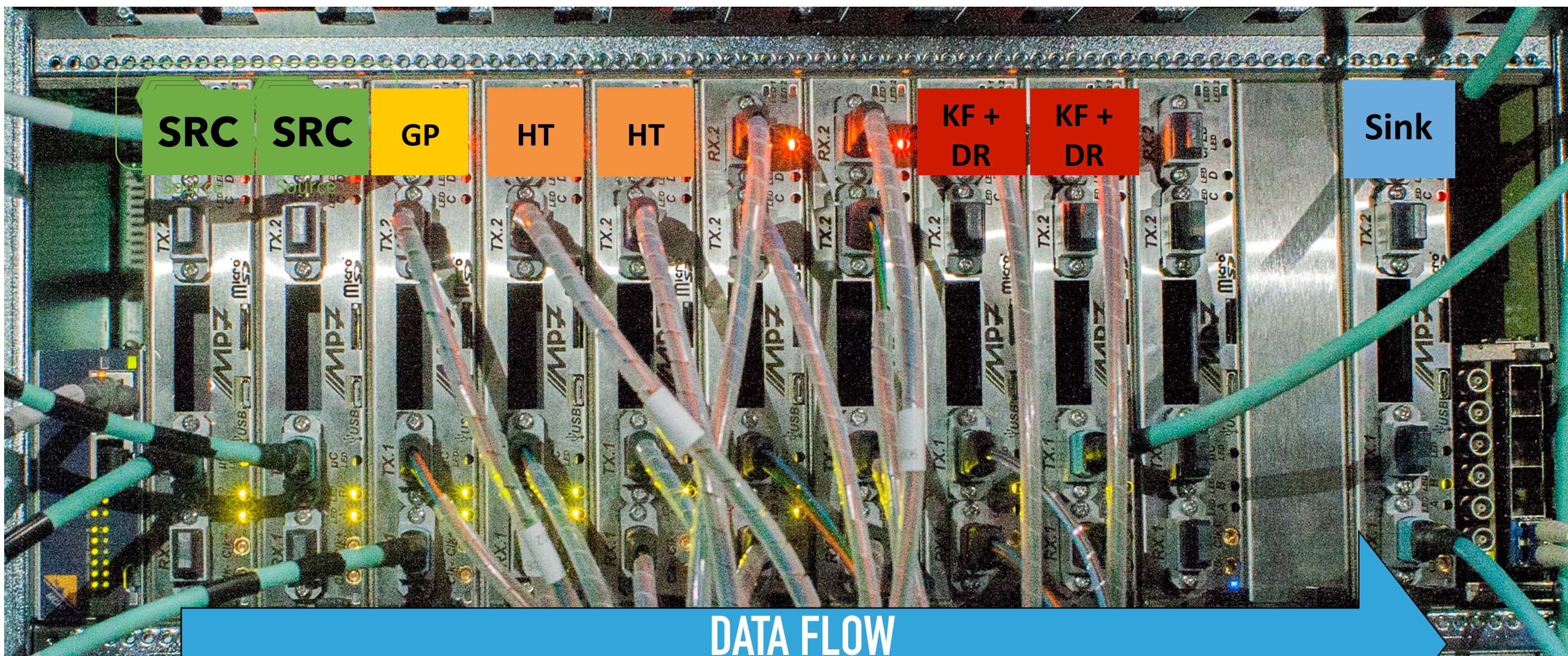
One KF node - 36 per MP7

- **Accumulation period** configured to **1550 ns**
- **Processing latency** dominated by **matrix maths** update, **230 ns / iteration**

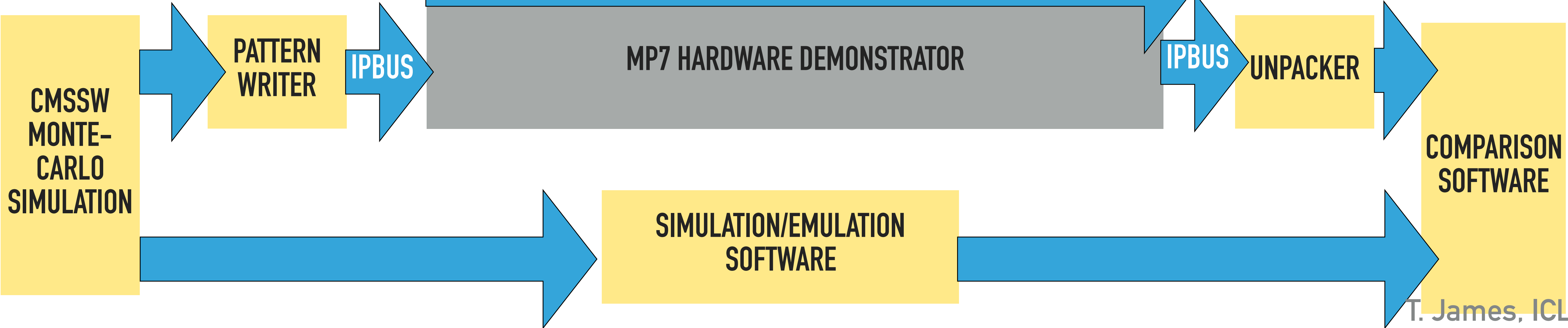
DEMONSTRATOR DATA TAKING

Objective - Run **Monte-Carlo physics samples** emulating conditions at **HL-LHC** through hardware demonstrator

Take data for **all octants** sequentially



Compare **hardware** directly with **software** emulator

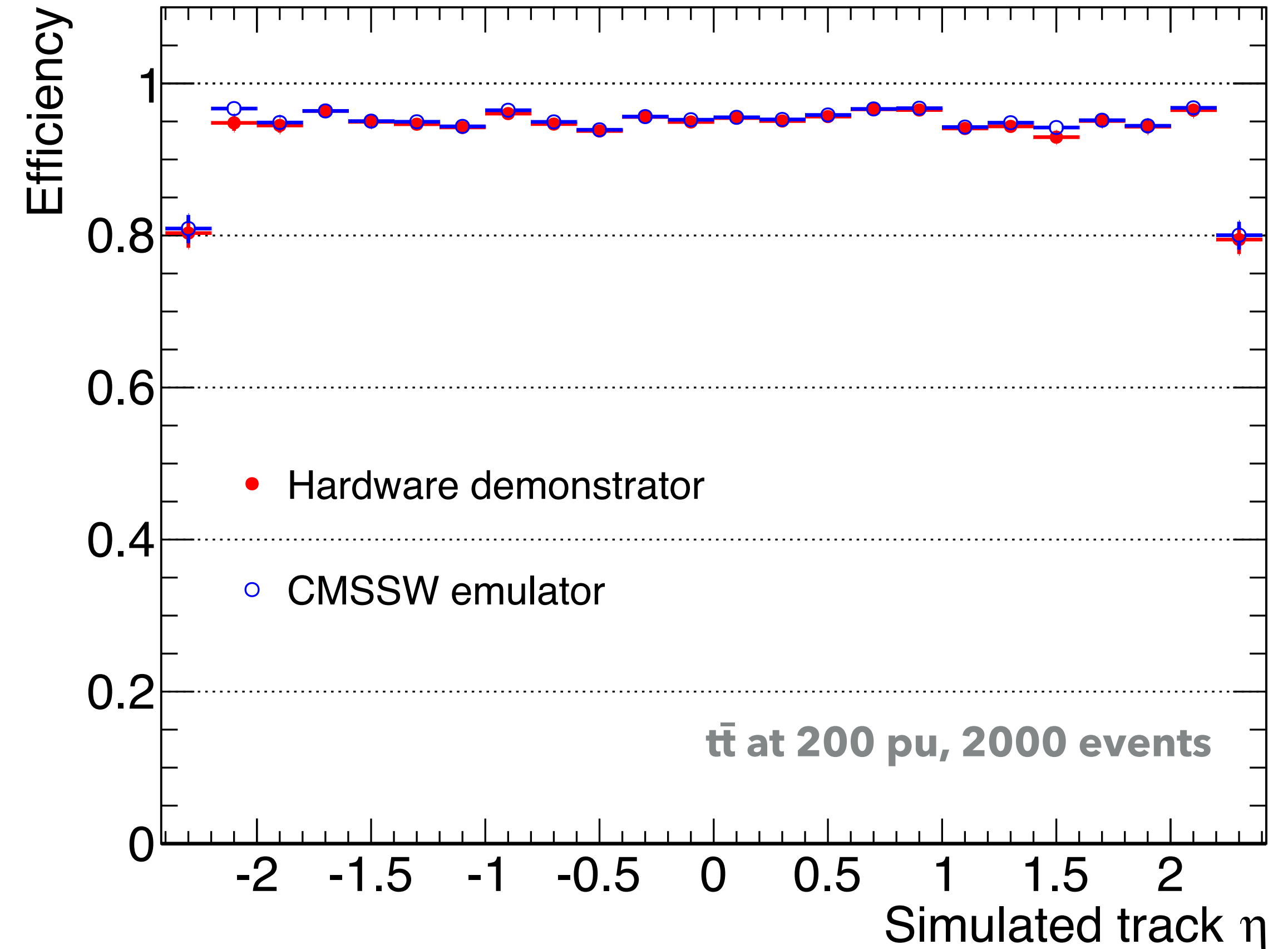
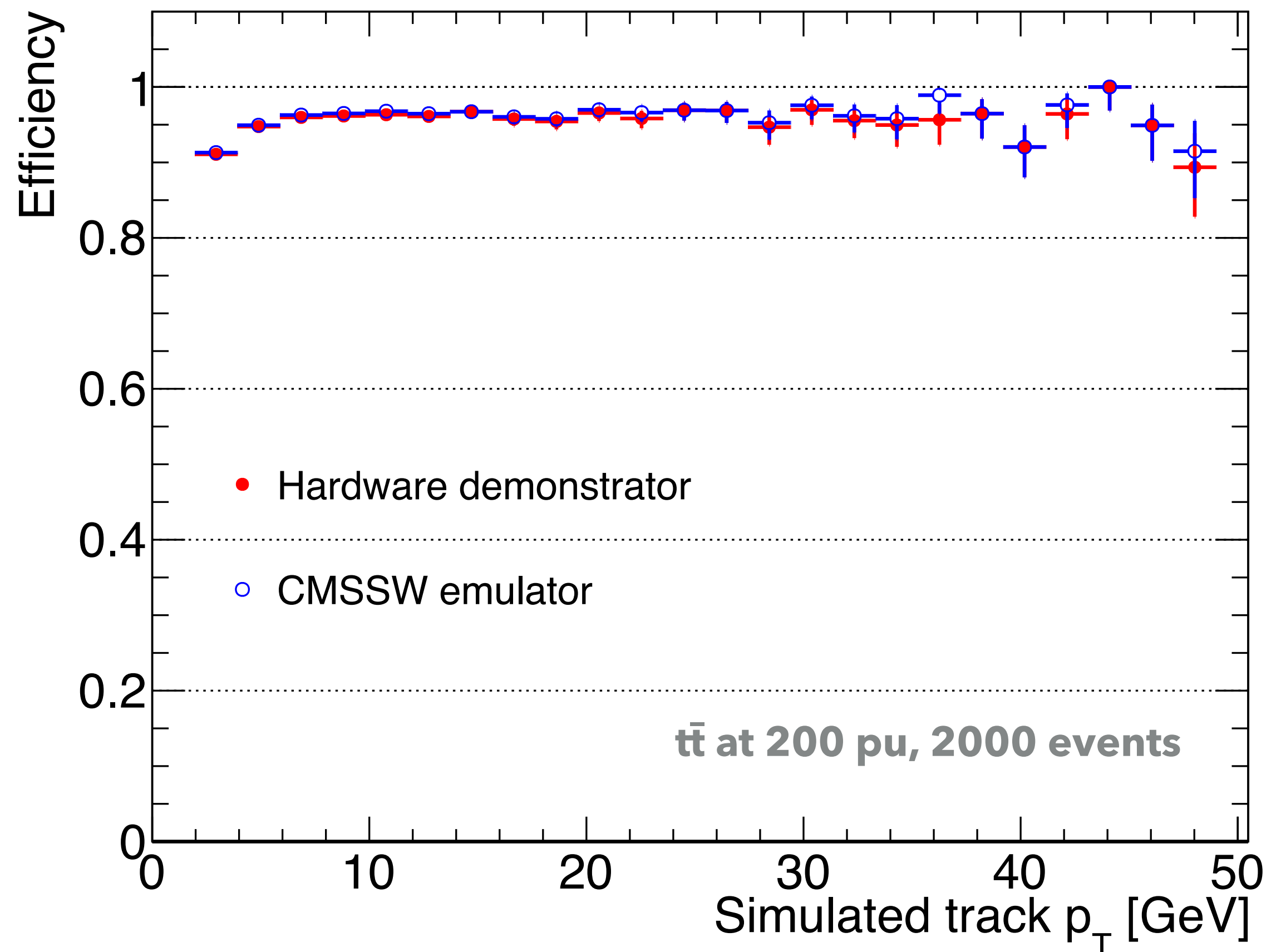
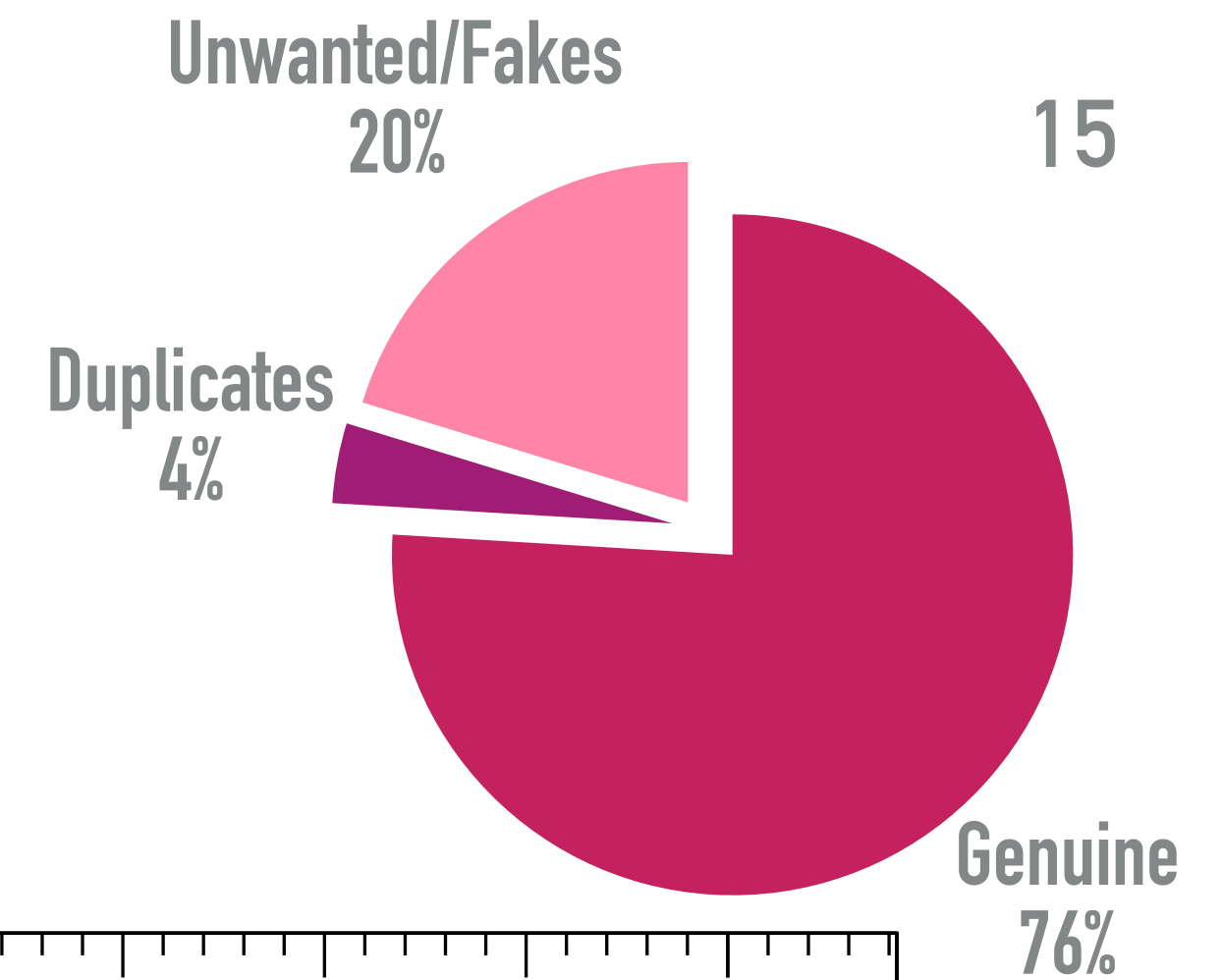


DEMONSTRATOR RESULTS

TRACK FINDING PERFORMANCE

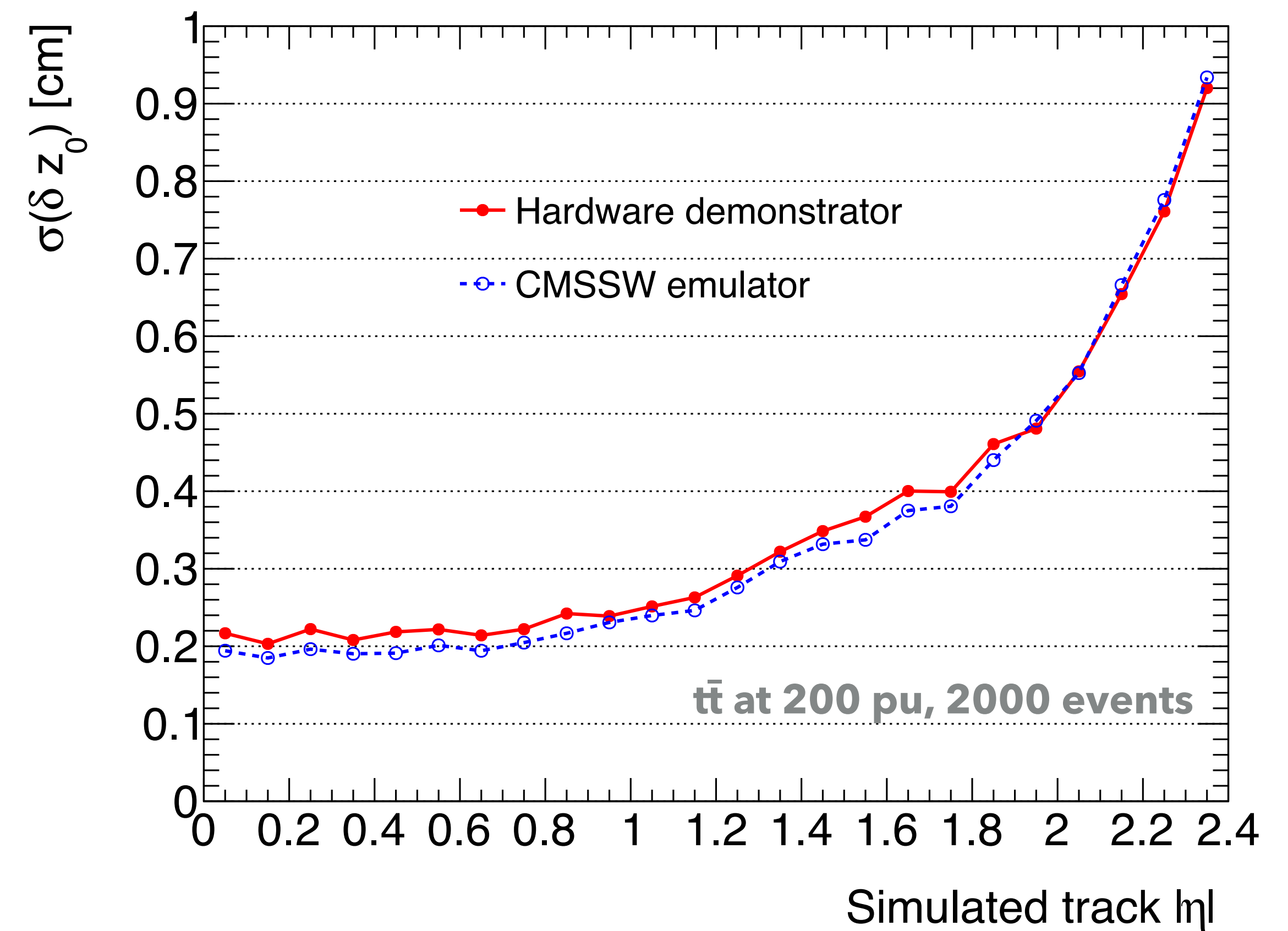
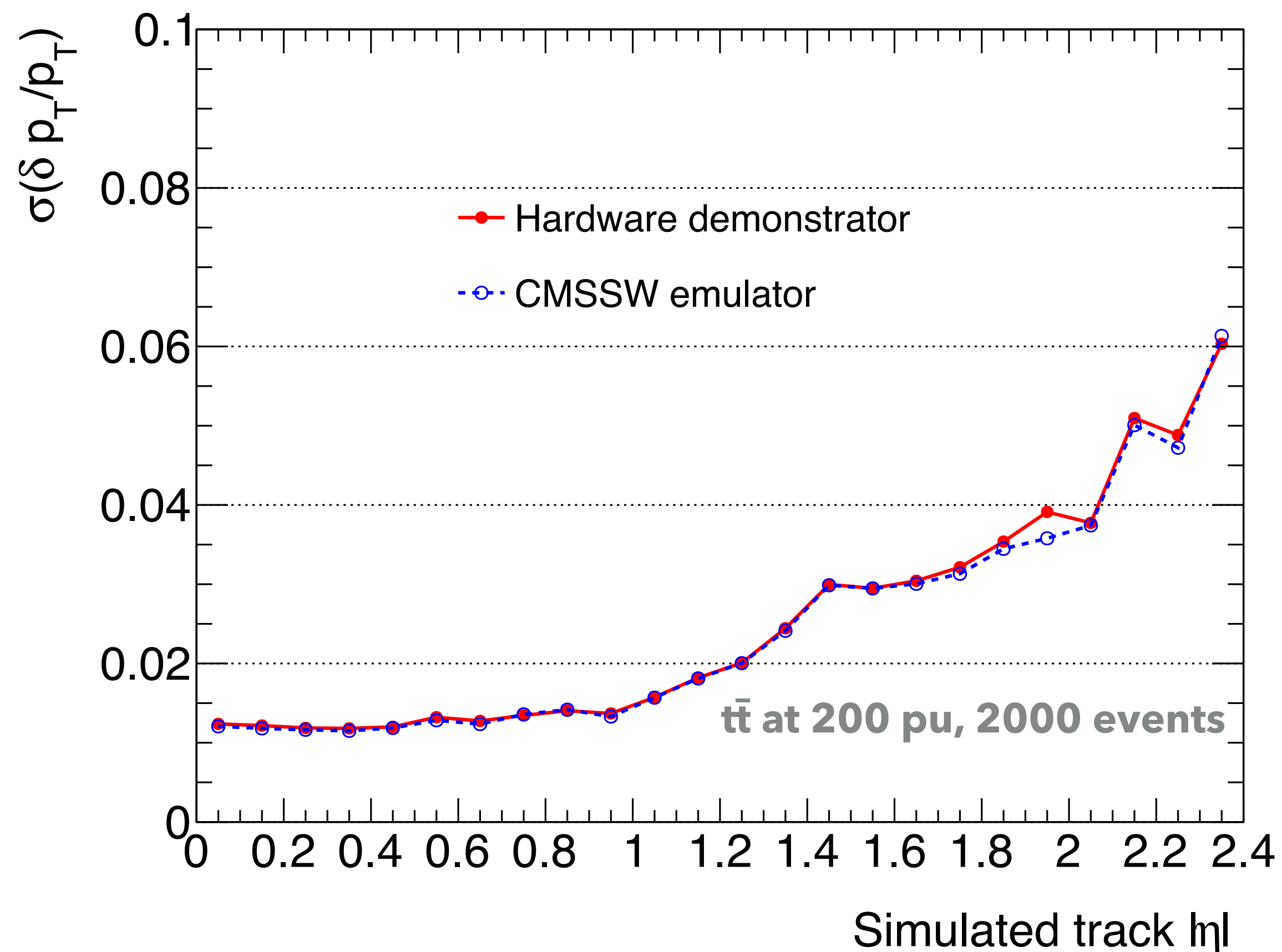
- ▶ **95% average track finding efficiency** for inclusive $t\bar{t}$ tracks (> 3 GeV)
- ▶ **97% for muons**

~70 tracks per event average
($t\bar{t}$ at 200 PU)



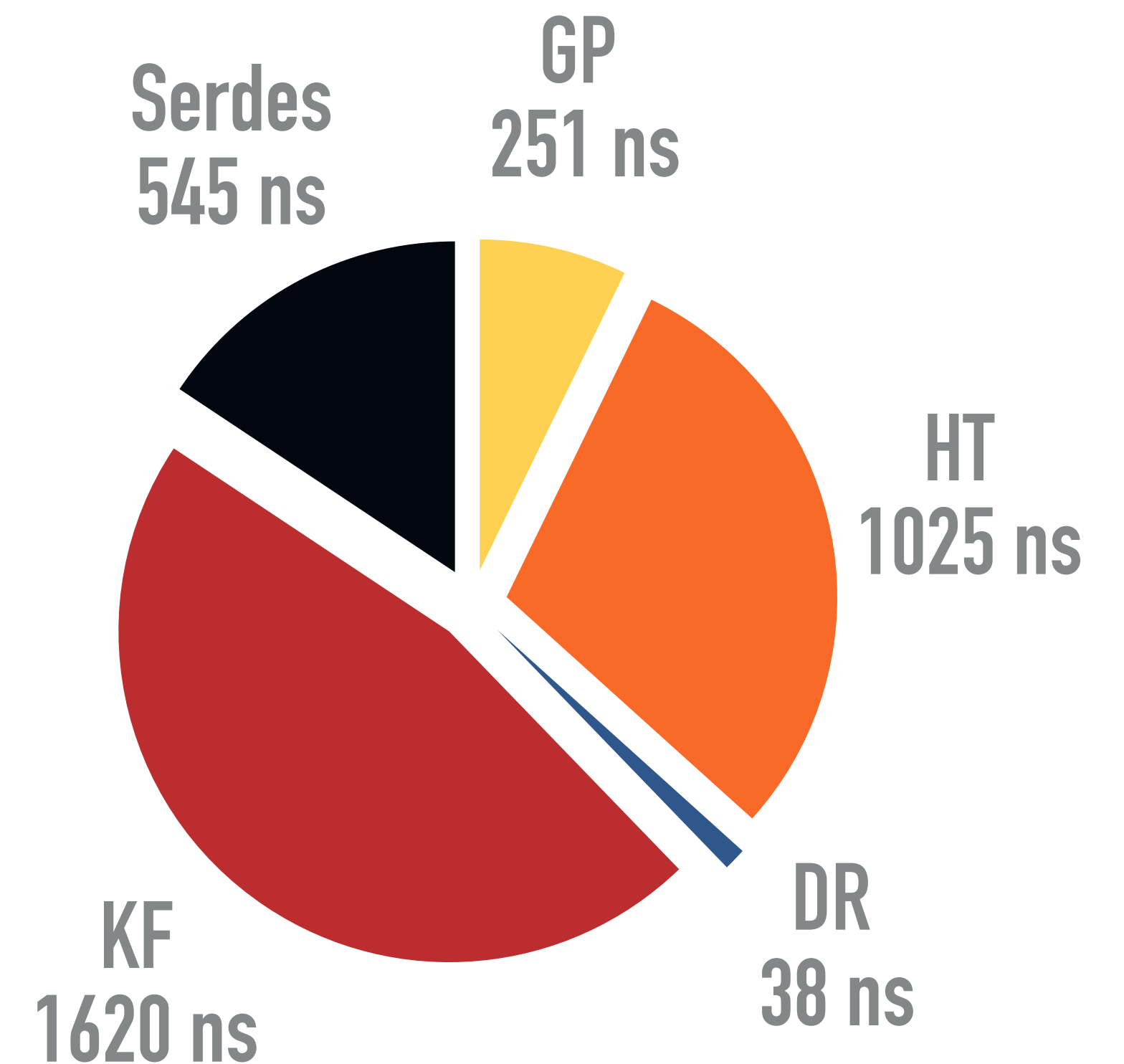
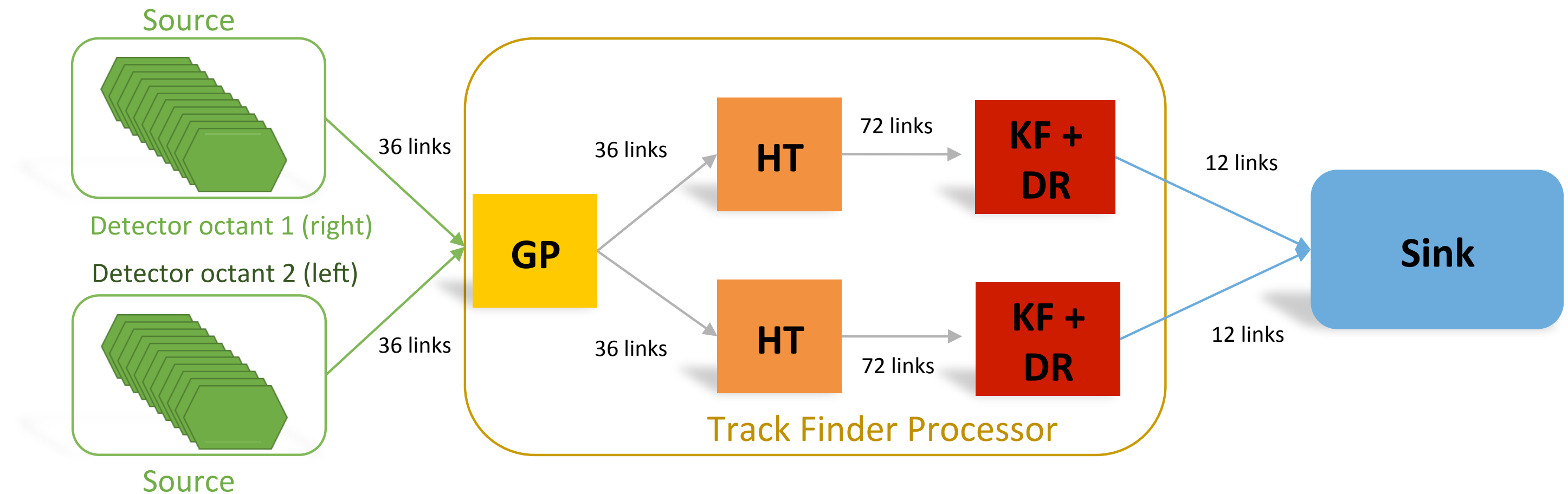
TRACK FINDING PERFORMANCE

- ▶ ~1% p_T resolution, 2 mm z_0 resolution in barrel
- ▶ 1-2 extra bits to encode stub position, z_0 res -> 1 mm in barrel



LATENCY MEASUREMENTS

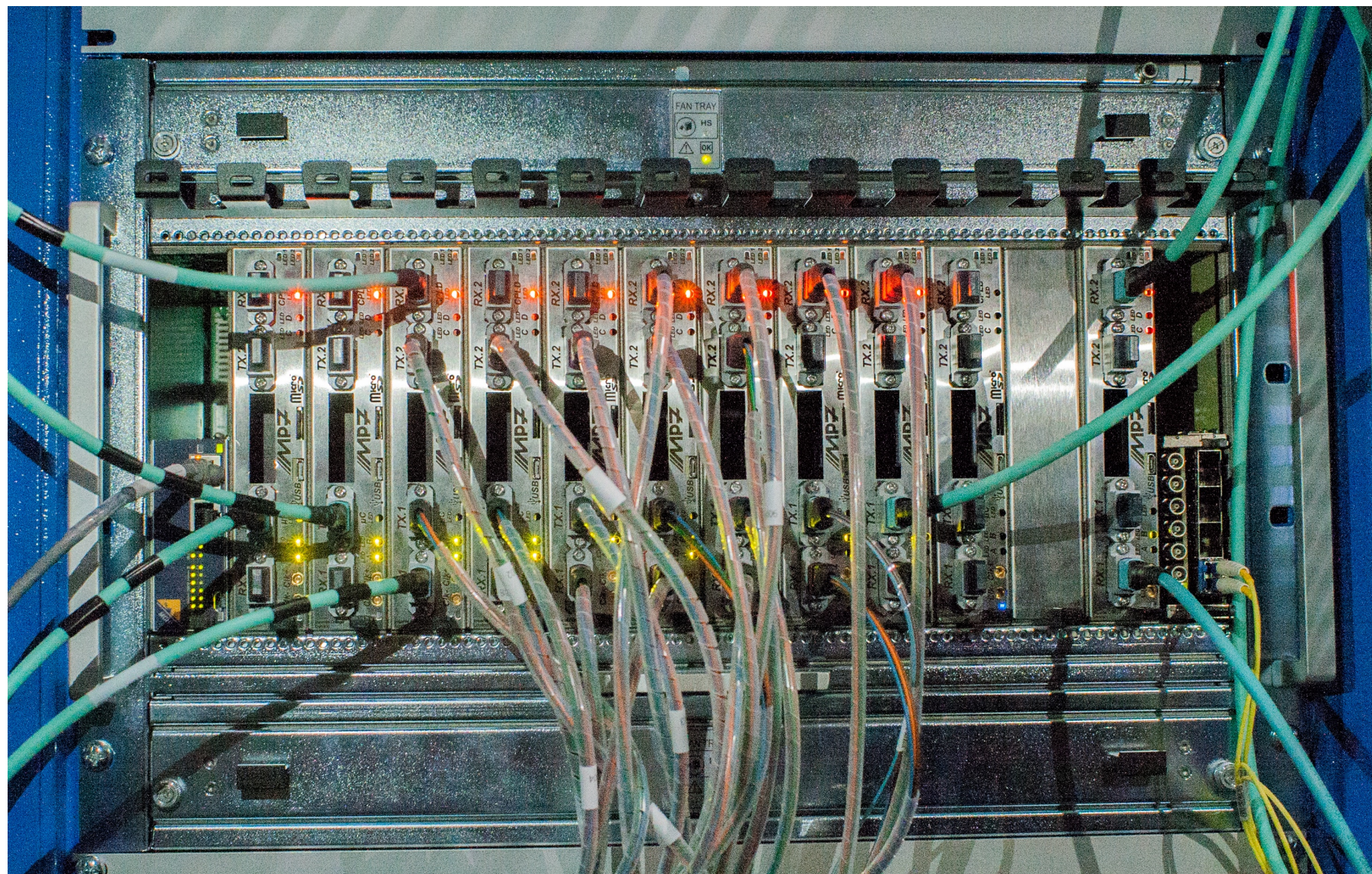
- ▶ **Fixed latency** - event independent
- ▶ Plenty of margin in design
- ▶ Room to increase clock speed, link speed, and to improve utilisation -> **lower latency possible**



CONCLUSIONS SUMMARY

18

- ▶ **Highly flexible** track-finder/pattern recognition algorithm
- ▶ **Highly scalable**, time/physical segmentation could be as large/small as required based on data rates
- ▶ **Proven** with **currently available hardware**, that a level-1 track-trigger based on **FPGA** processing boards is a **feasible** and **safe** solution
- ▶ Plenty of **time to improve and optimise** algorithms for global trigger requirements



Thanks for listening

I look forward to answering your questions

REFERENCES

- ▶ [CMS Collaboration, "Technical Proposal for the Phase-II Upgrade of the CMS Detector", Technical Report CERN-LHCC-2015-010. LHCC-P-008. CMS-TDR-15-02, Geneva, Jun, 2015.](#)
- ▶ CMS Collaboration, "CMS Technical Design Report for the Phase-2 Tracker Upgrade", Technical Report CERN-LHCC-2017-xxx. CMS-TDR-xxx, Geneva, month, 2017.
- ▶ [G. Hall, "A time-multiplexed track-trigger for the {CMS} HL-LHC upgrade", Nuclear Instruments and Methods in Physics Research Section A: Accelerators, Spectrometers, Detectors and Associated Equipment 824 \(2016\) 292 - 295, doi:10.1016/j.nima.2015.09.075. Frontier Detectors for Frontier Physics: Proceedings of the 13th Pisa Meeting on Advanced Detectors.](#)
- ▶ [K. Compton et al., "The MP7 and CTP-6: multi-hundred Gbps processing boards for calorimeter trigger upgrades at CMS", Journal of Instrumentation 7 \(2012\) C12024, doi:10.1088/1748-0221/7/12/C12024.](#)
- ▶ [M. . Pesaresi, "Development of a new Silicon Tracker for CMS at Super-LHC". PhD thesis, Imperial College London, 2010.](#)
- ▶ [M. Pesaresi and G. Hall, "Simulating the performance of a p T tracking trigger for CMS", Journal of Instrumentation 5 \(2010\) C08003, doi: 10.1088/1748-0221/5/08/C08003.](#)
- ▶ [An FPGA-Based Track Finder for the L1 Trigger of the CMS Experiment at the High Luminosity LHC Presented at 20th IEEE-NPSS Real Time Conference, Padua, Italy, 5-10 Jun 2016, doi:10.1109/RTC.2016.7543102.](#)

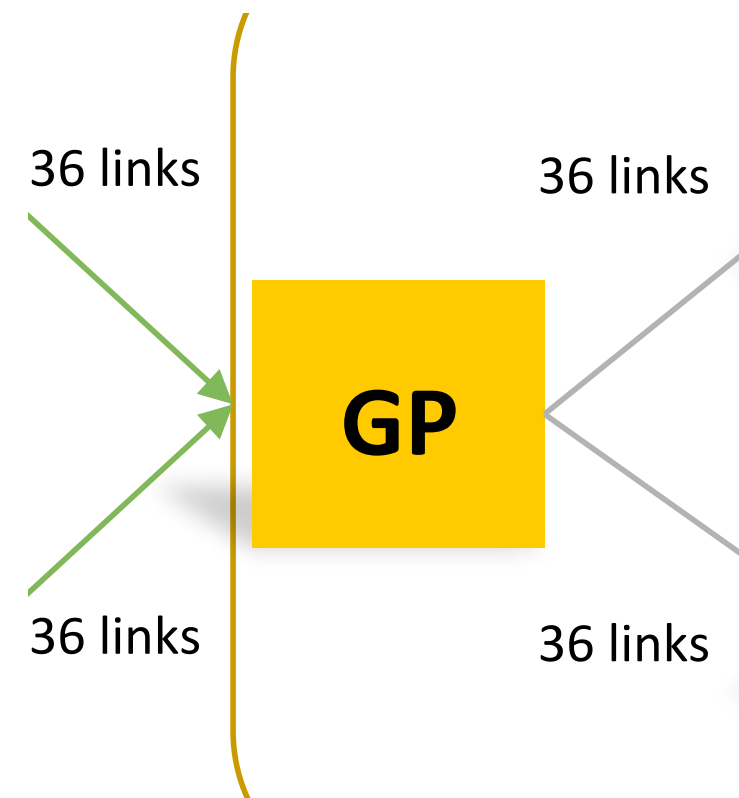
ACKNOWLEDGEMENTS

- ▶ We gratefully thank the following sources for their support of this work
 - ▶ Science & Technology Facilities Council (STFC)
 - ▶ EU FP7-PEOPLE-2012-ITN project nr. 317446, INFIERI, "Intelligent Fast Interconnected and Efficiency Devices for Frontier Exploration in Research and Industry"
 - ▶ Maxeler Technologies
 - ▶ The Worshipful Company of Scientific Instrument Makers (UK)

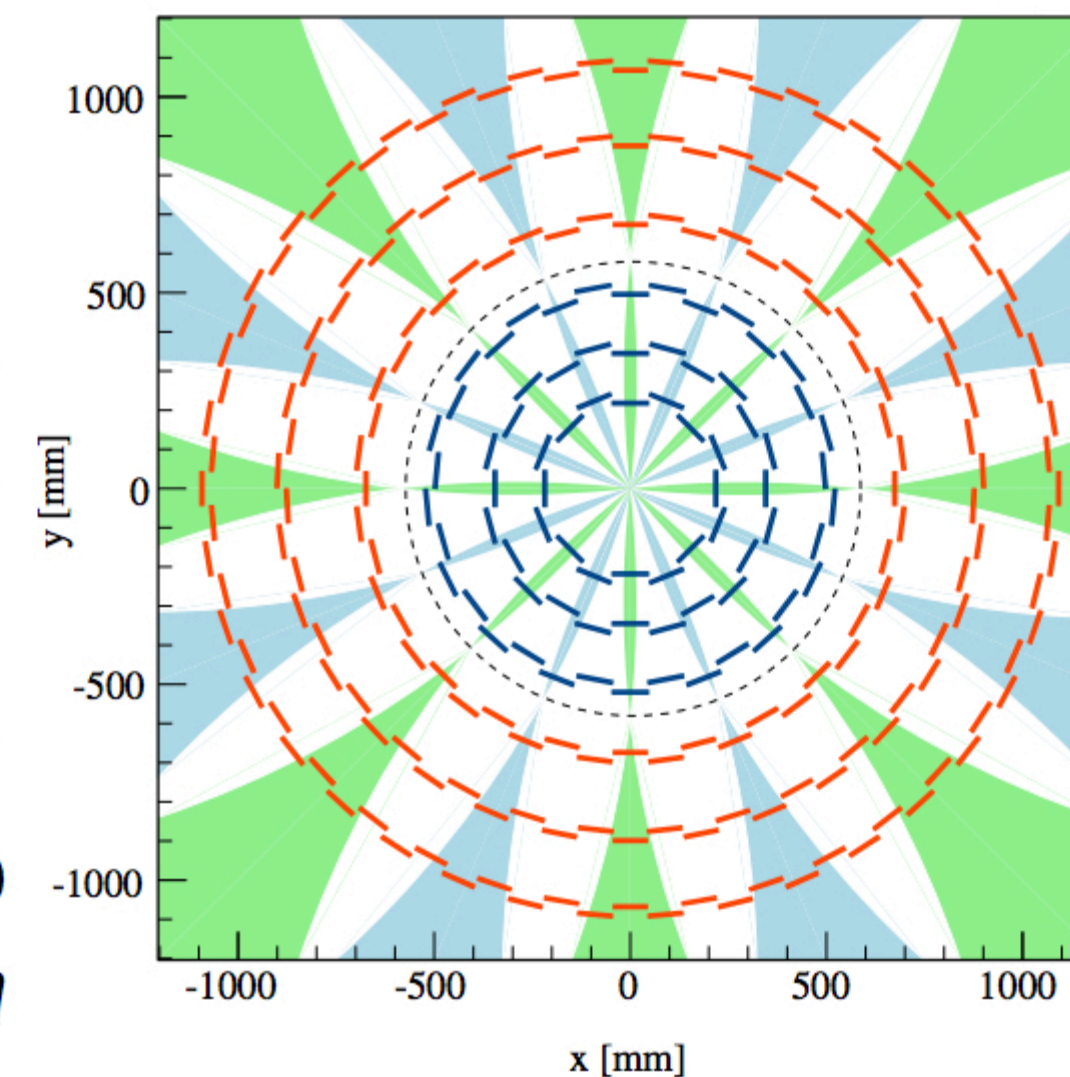
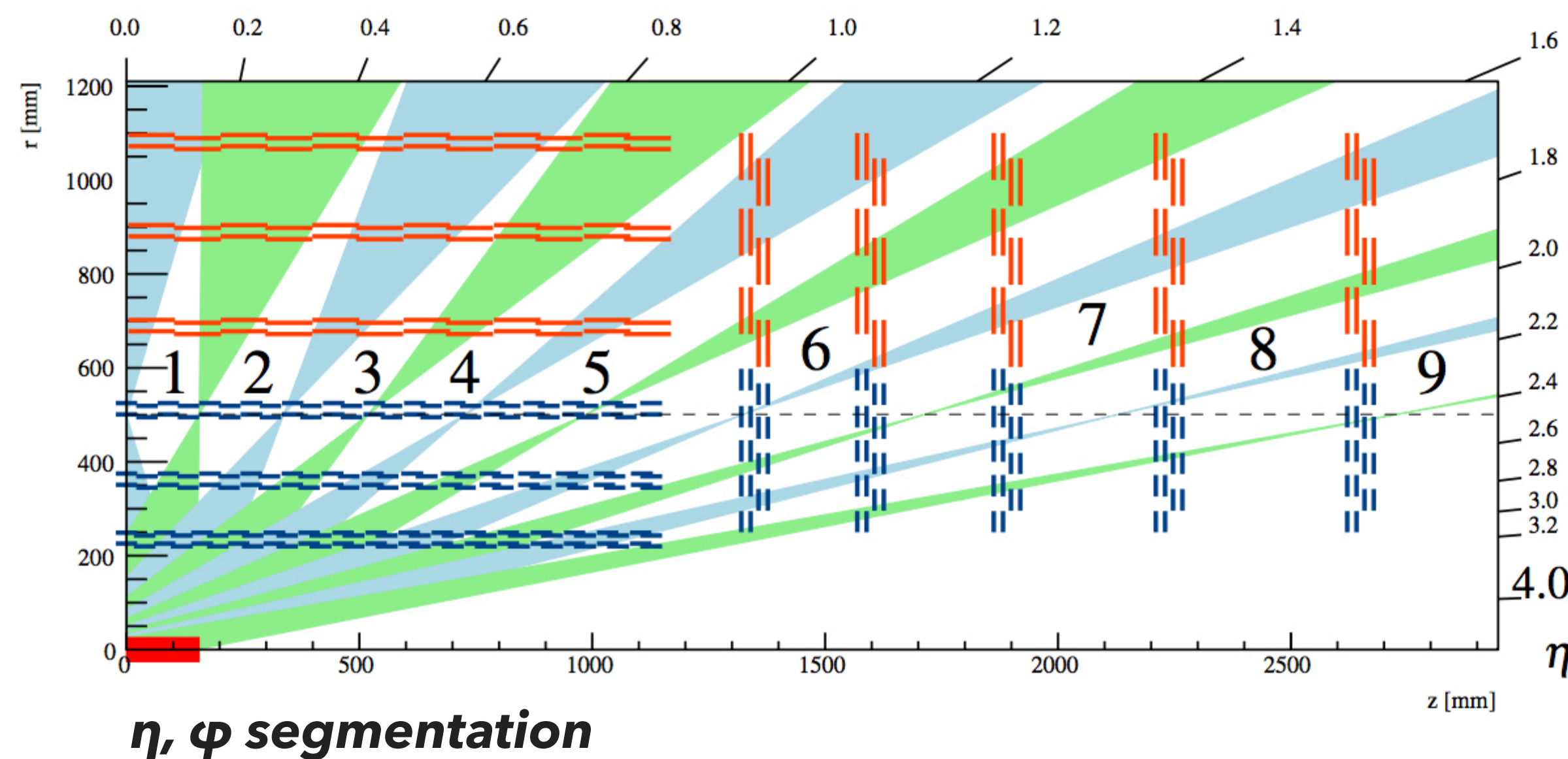


THE WORSHIPFUL
COMPANY OF SCIENTIFIC
INSTRUMENT MAKERS

GEOMETRIC PROCESSOR (GP)



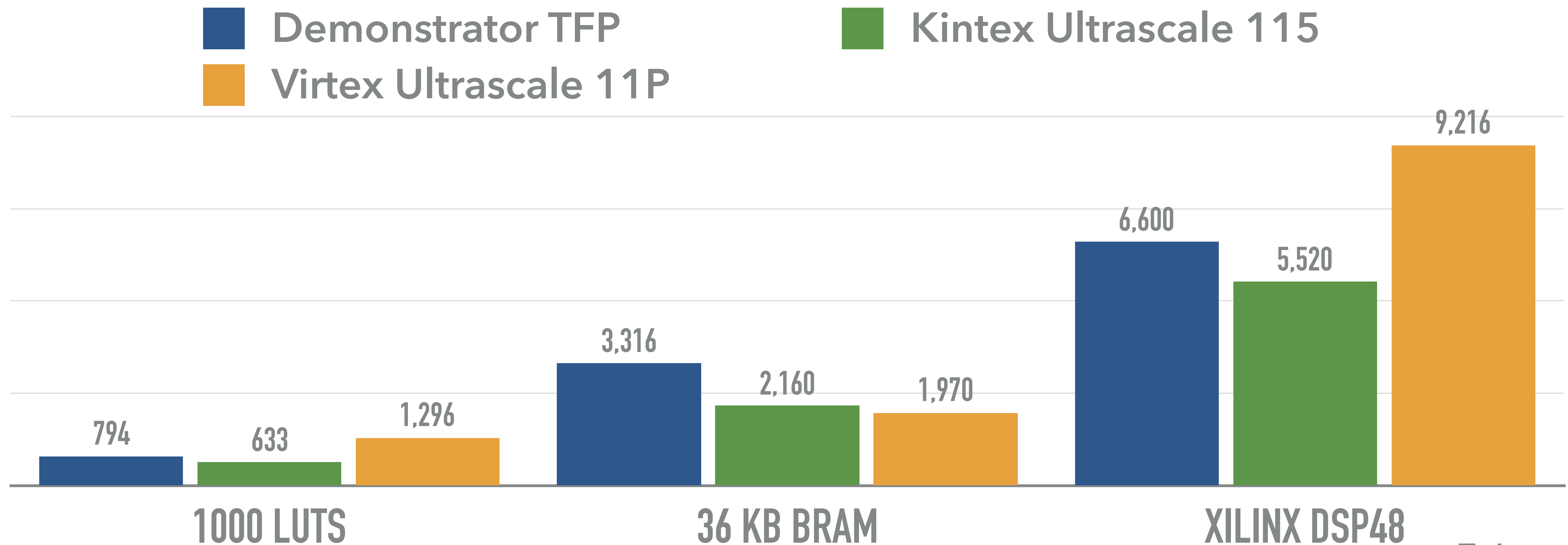
- ▶ **Assigns stubs to $2\varphi \times 18\eta$ sub-sectors, duplicating** across boundaries when necessary
- ▶ Simplifies the track-finding task and allow for increased parallelisation downstream



- ▶ **Routes all stubs** in a given sector to **dedicated output link pairs**
 - ▶ 72 inputs \rightarrow 36 outputs
- ▶ Highly configurable arbitrator blocks

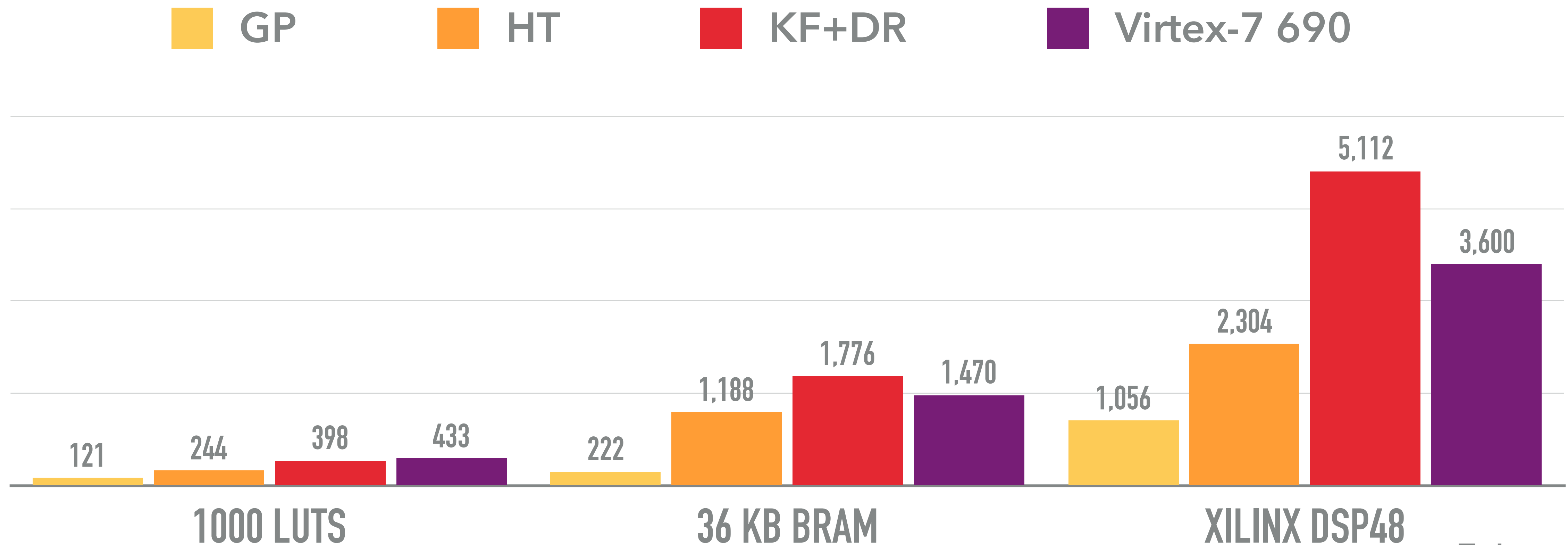
RESOURCE USAGE & FUTURE FPGA CHIPS

- ▶ Overall **resource usage** of the system shows that with some optimisations, a future TFP could feasibly consist of **two** KU115 or **one** VU11P FPGA
- ▶ Future work will be to build a system using the **KU115 FPGA** and **16.3 Gbps optical links** with a target latency of 2 μ s



RESOURCE USAGE & FUTURE FPGA CHIPS

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- ▶ Future work will be to build a system using the **KU115 FPGA** and **16.3 Gbps optical links** with a target latency of 2 μ s



RESOURCE USAGE & FUTURE FPGA CHIPS

- ▶ Overall **resource usage** of the system shows that with some optimisations, a future TFP could feasibly consist of **two** KU115 or **one** VU11P FPGA
- ▶ Future work will be to build a system using the **KU115 FPGA** and **16.3 Gbps optical links** with a target latency of 2 μ s

	LUTs [10 ³]	DSPs	FFs [10 ³]	BRAM (36 Kb)
GP	121	1056	205	222
HT	244	2304	299	1188
KF and DR	398	5112	316	1776
Infrastructure per MP7	90	0	91	291
TFP Total (excl. infrastructure)	763	8472	820	3186
Virtex 7 690	433	3600	866	1470
Kintex Ultrascale 115	633	5520	1266	2160
Virtex Ultrascale+ 11P	1296	9216	2592	2016

BACKUP

SIMULATION RESULTS

Stage	Efficiency [%]	# of tracks	# of fakes	# of duplicates
HT	97.1	331	139	126
KF	95.1	190	27	103
DR	94.4	79	16	3
Full chain	94.4	79	16	3

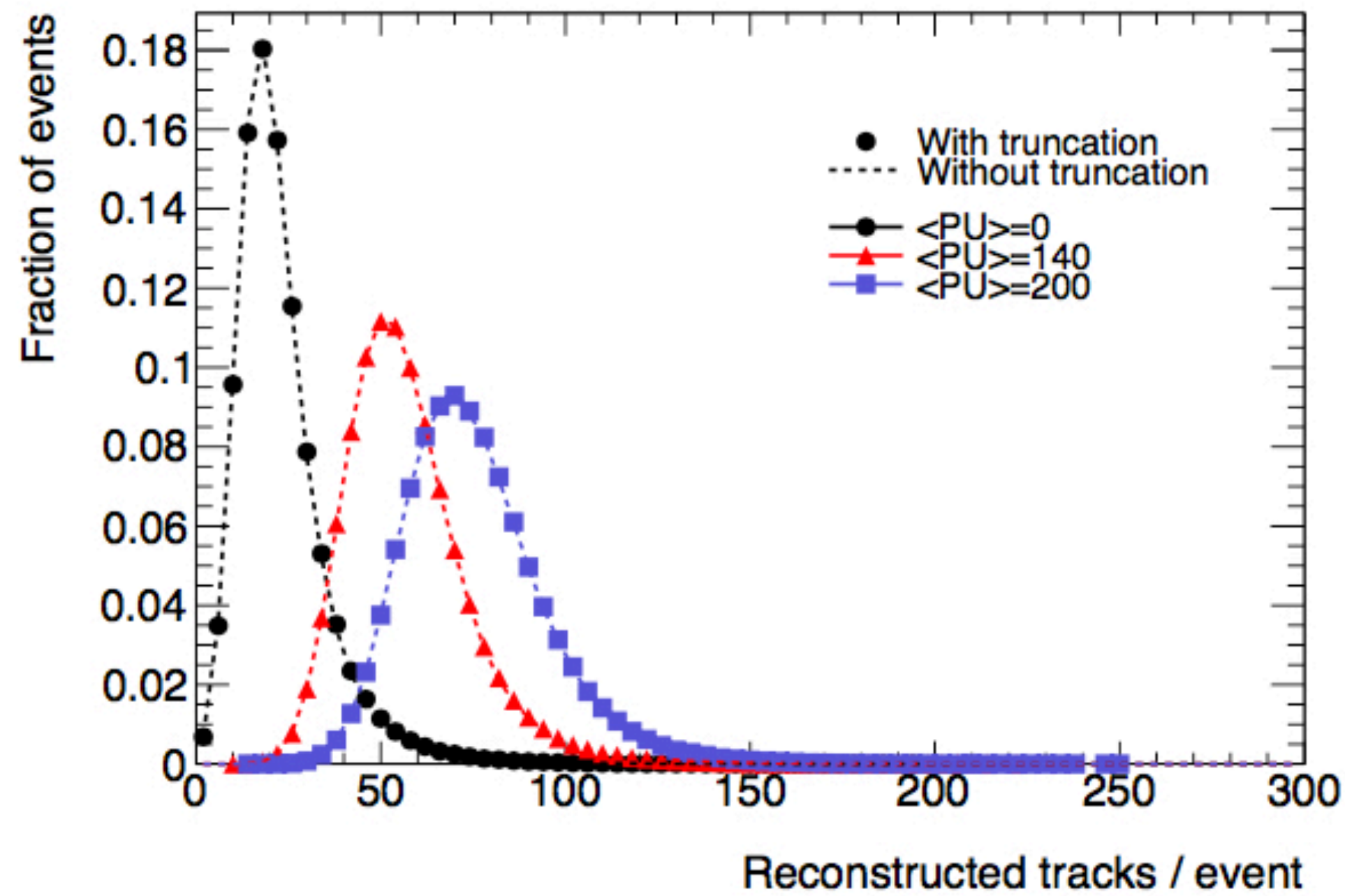


Figure 22: Total number of reconstructed tracks per event reconstructed in the tracker when processing $t\bar{t}$ events superimposed in 0, 140, and 200 PU events. These results are obtained from emulation, and are shown for when effects of truncation, caused by excess data flow through the system, are both included and excluded.

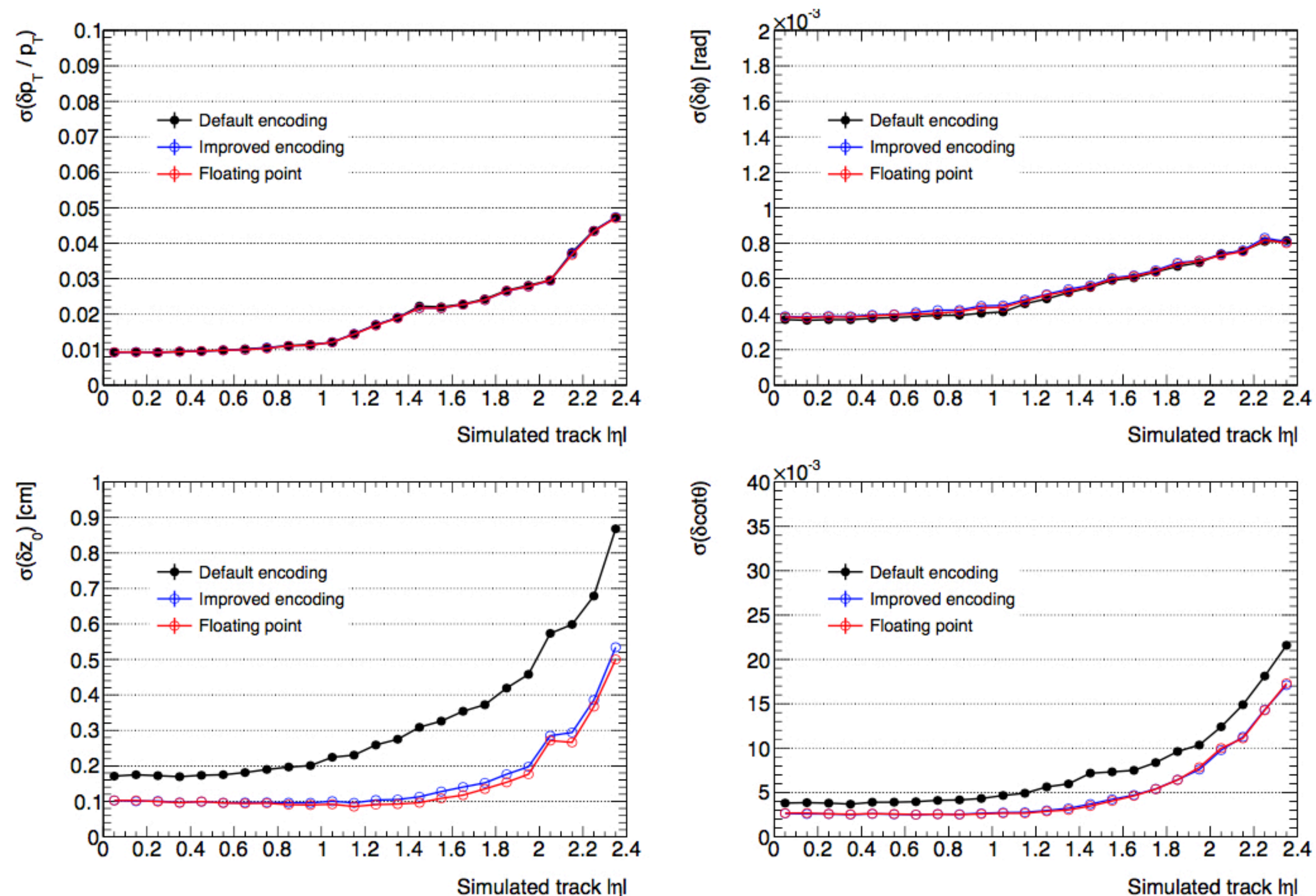
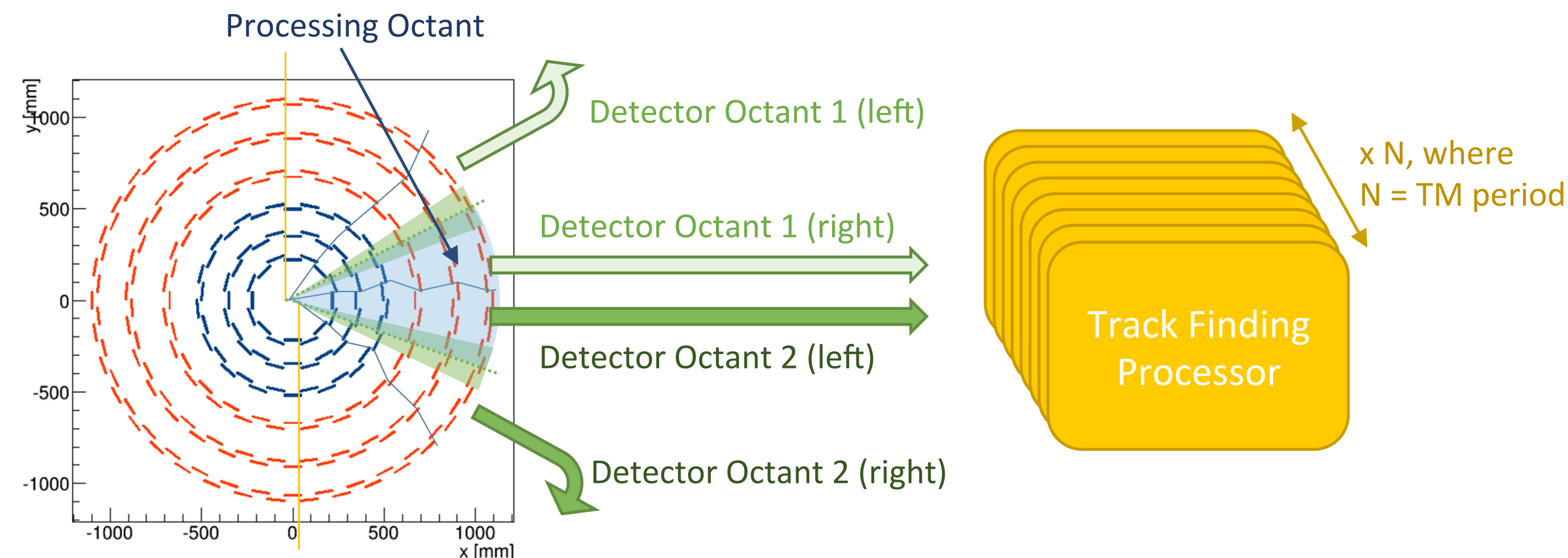


Figure 21: Relative p_T resolution, ϕ resolution [rad], z_0 resolution [cm] and $\cot\theta$ resolution measured for single isolated muons, with $5 < p_T^\mu < 15 \text{ GeV}$ obtained from emulation, using different levels of precision in simulation: Default encoding (10-bit r , 12-bit z , 15-bit ϕ stub coordinates); improved encoding (12-bit r , 14-bit z , 15-bit ϕ stub coordinates); and full floating-point simulation.

TRACK TRIGGER PROPOSAL

- ▶ Total available L1 time will be $12.5\ \mu\text{s}$, but **only $\sim 4\ \mu\text{s}$ is available for track finding**
- ▶ Must construct a track finder that is capable of processing **very high data rates ($\sim 20,000$ stubs per event)** down to the $O(10)$ genuine/interesting tracks expected on average, within this latency target
- ▶ **Proposal: Track Finding Processor (TFP) (FPGA data stream processing boards) receive data links from adjacent detector octants in φ**

- ▶ Fully **time-multiplexed** system
 - ▶ Processing of subsequent events done on parallel independent nodes
- ▶ **No further duplication or sharing between regions is required downstream**



- ▶ Each **TFP processes $1/8$ in φ and $1/\text{tmp}$ (time multiplex period) in time**
- ▶ **Highly scalable** system
- ▶ **One TFP becomes the demonstrator slice unit**