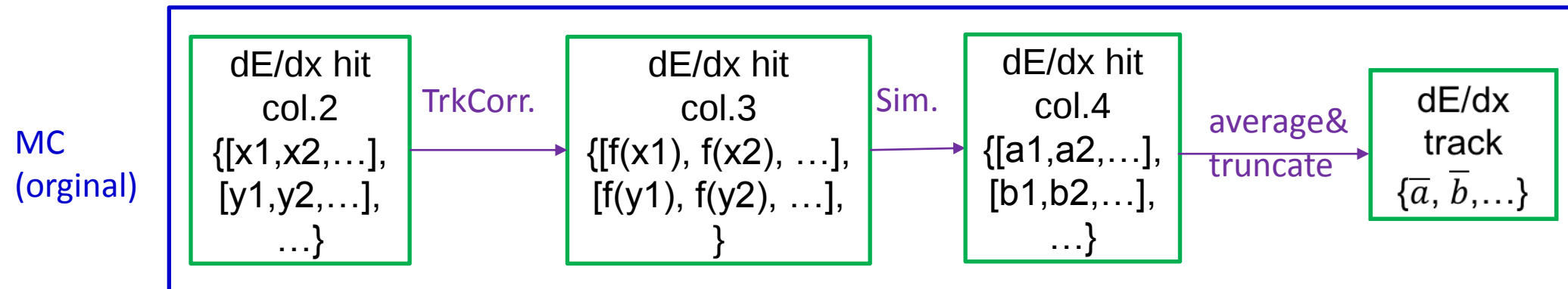
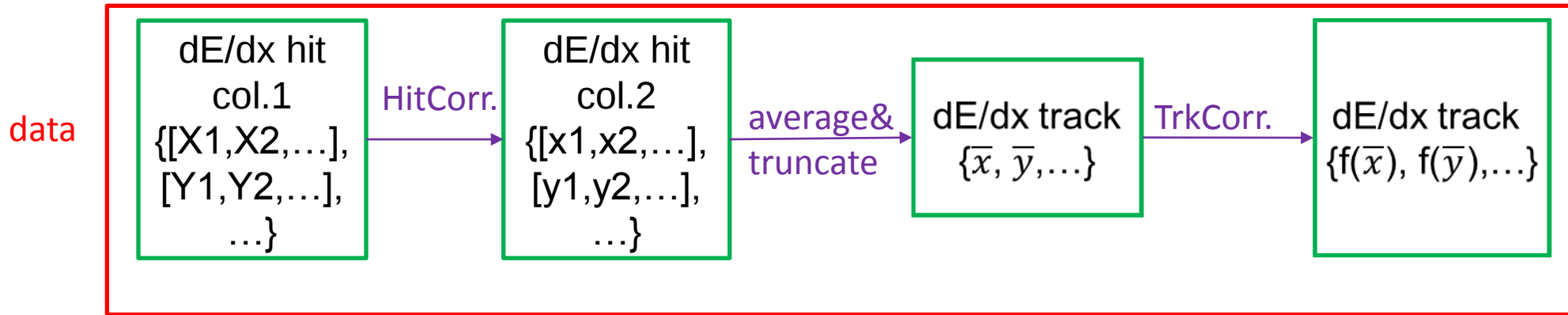


Review

1. Intro. of new dE/dx rec.

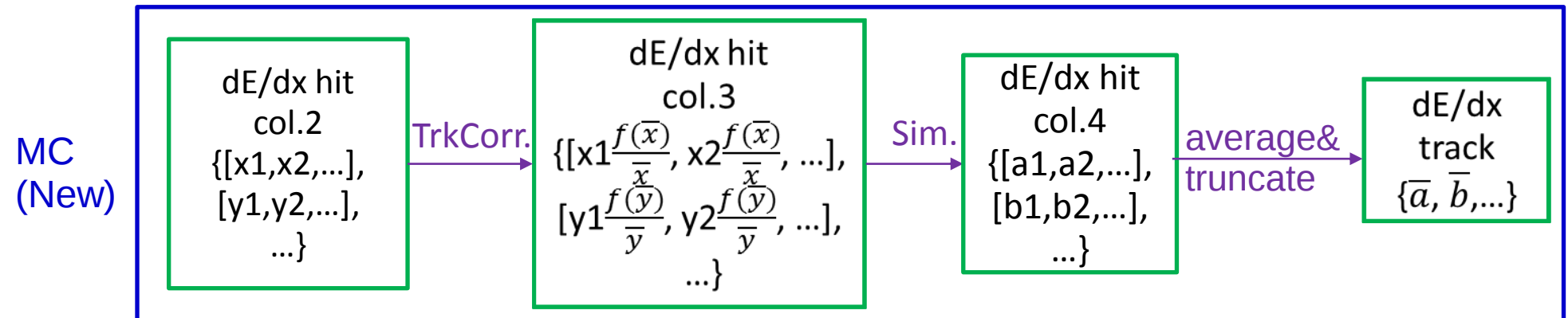
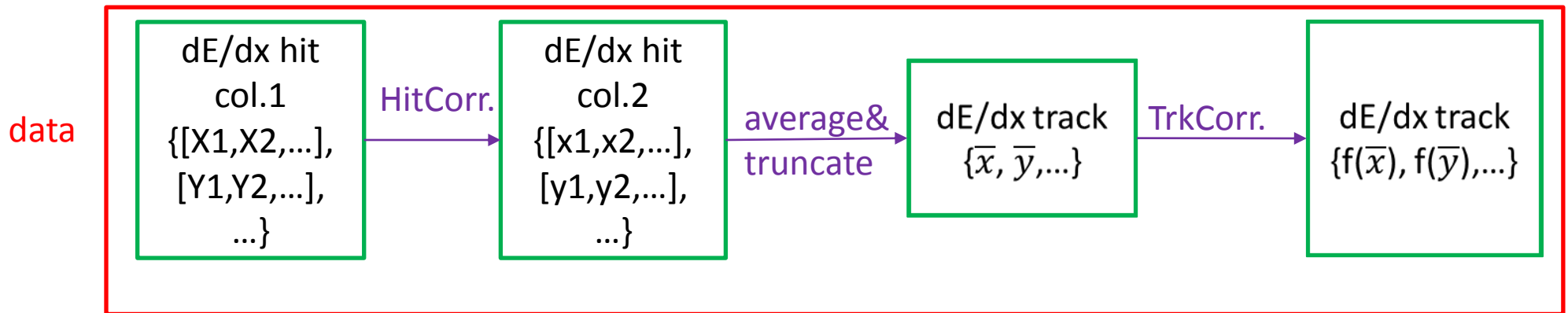
$f(x)$: TrkCorr.

As $f(x)$ is nonlinear, the order of TrkCorr. really matters.



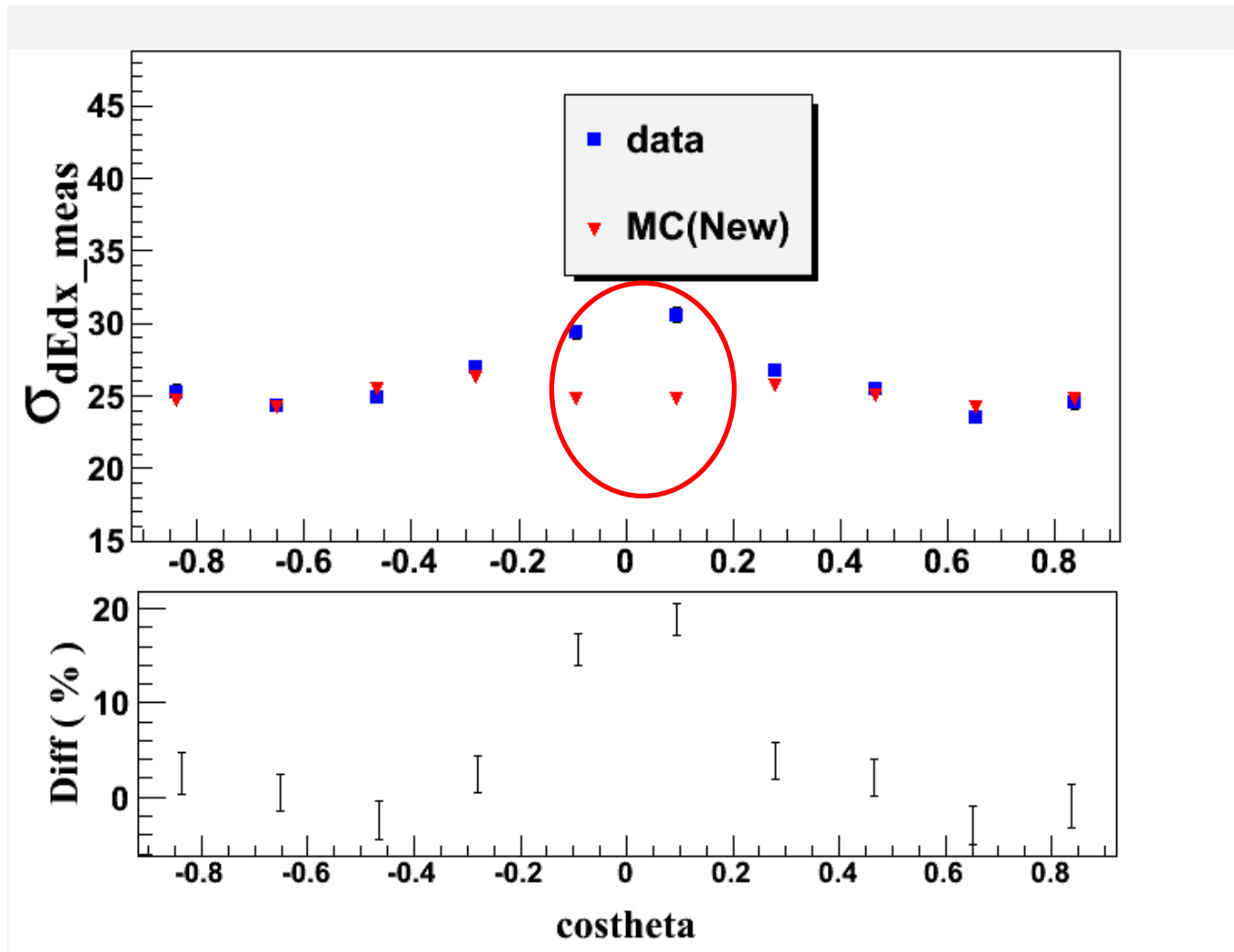
Review

1. Intro. of new dE/dx rec.



Review

1. Intro. of new dE/dx rec. Incredible diff. of σ when $\cos\theta \sim 0$



$$\text{Diff} = \frac{\text{data} - \text{MC}}{\text{data}}$$

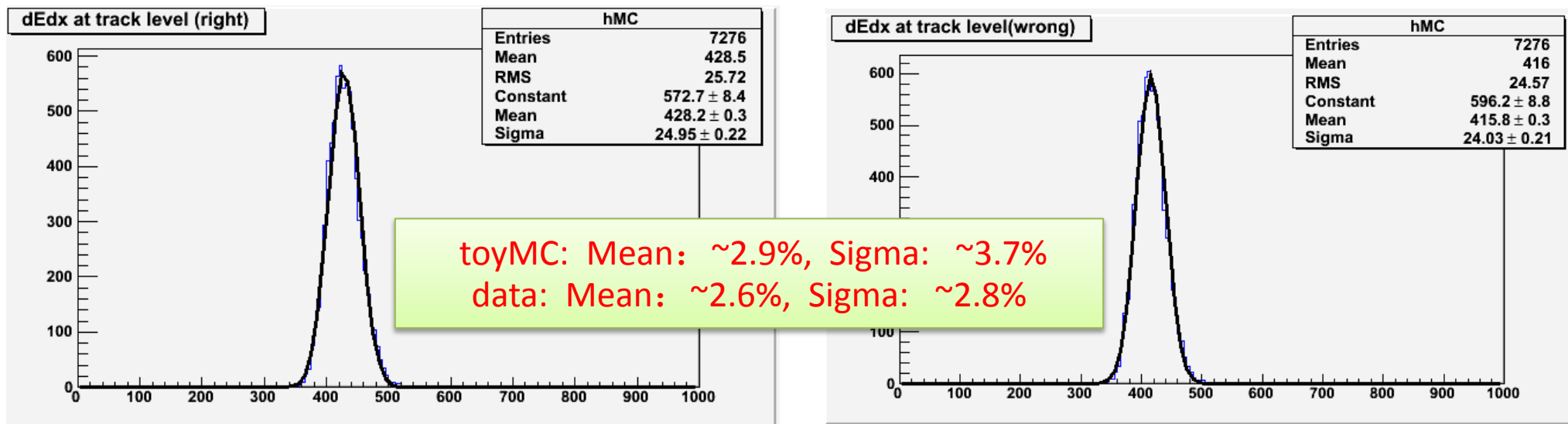
Even if we change binning of $\cos\theta$, the diff. can't be reduced.

2. Possible problems

(1) the error in “truncate & average” part

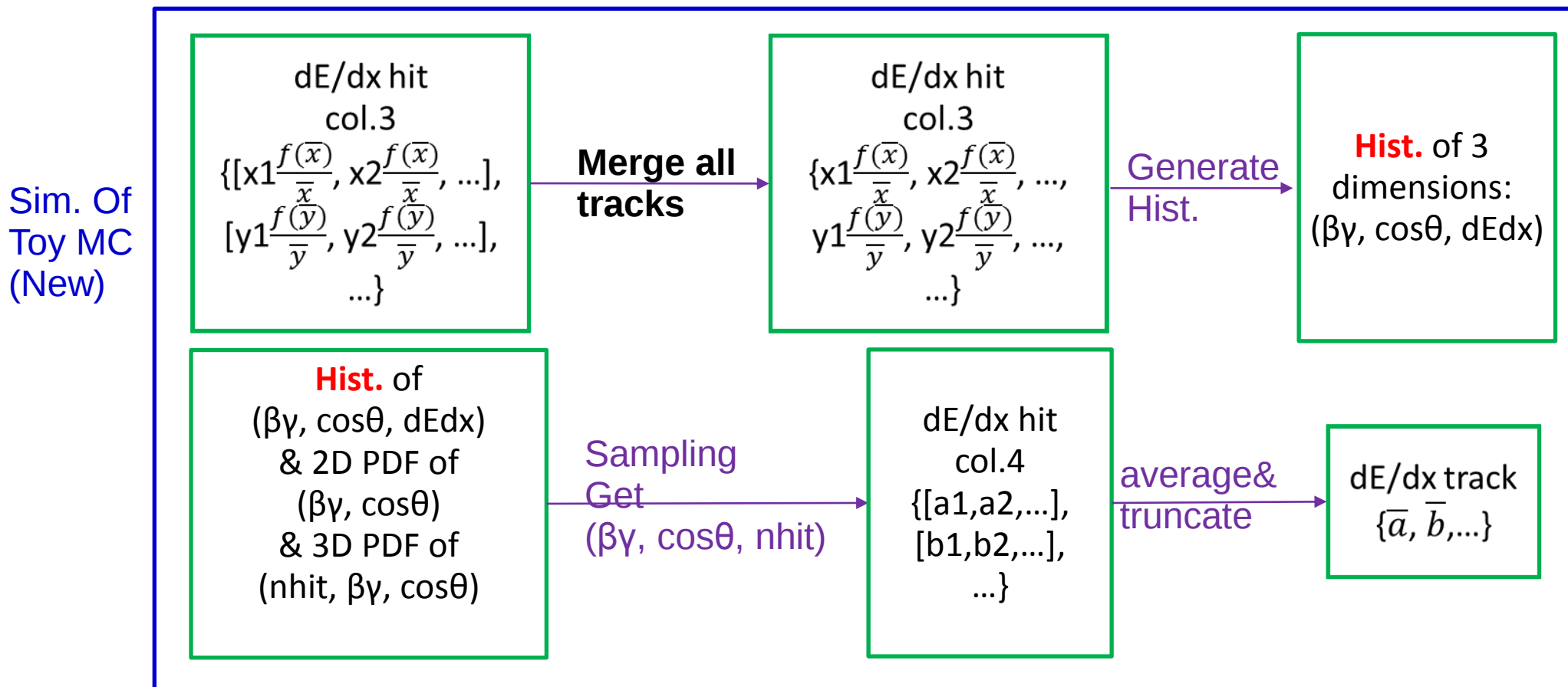
- Track级别的dE/dx通过对hit级别的dE/dx进行截断（低端5%和高端75%）然后平均得到。
- 重建算法中截断平均的错误：击中数 $n_{hit} < 10$ 时，计算平均值时少算截断后击中级别dE/dx最高值。(对data和MC都存在这个问题)

$$\frac{390 + 400 + 410 + 420 + 430 + 440 + 450}{7} = 420$$
$$\frac{390 + 400 + 410 + 420 + 430 + 440 + \cancel{450}}{7} = 355.7$$



2. Possible problems

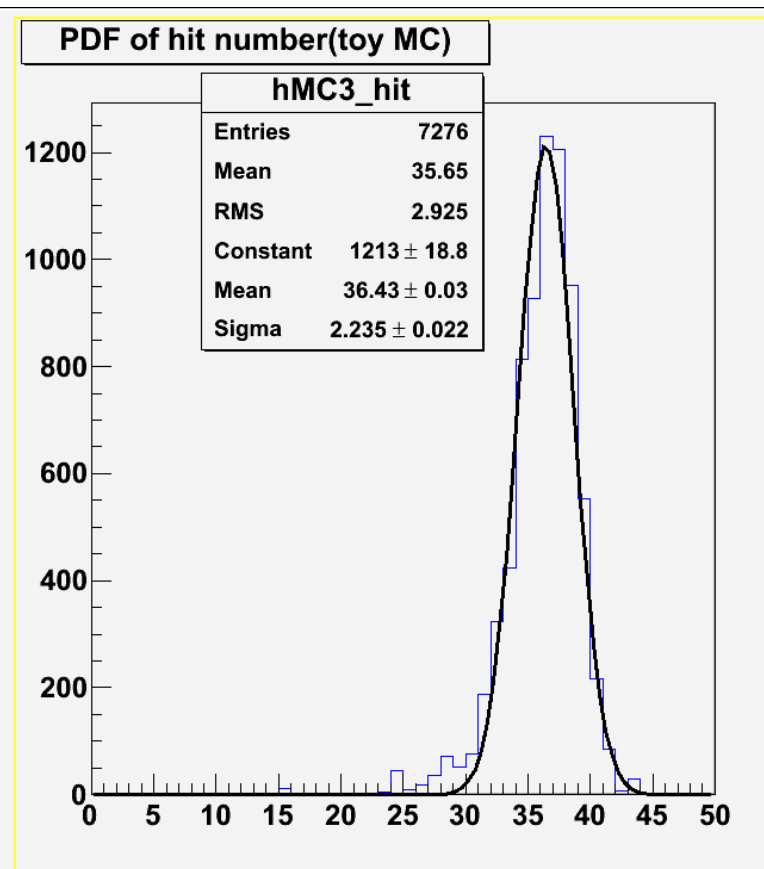
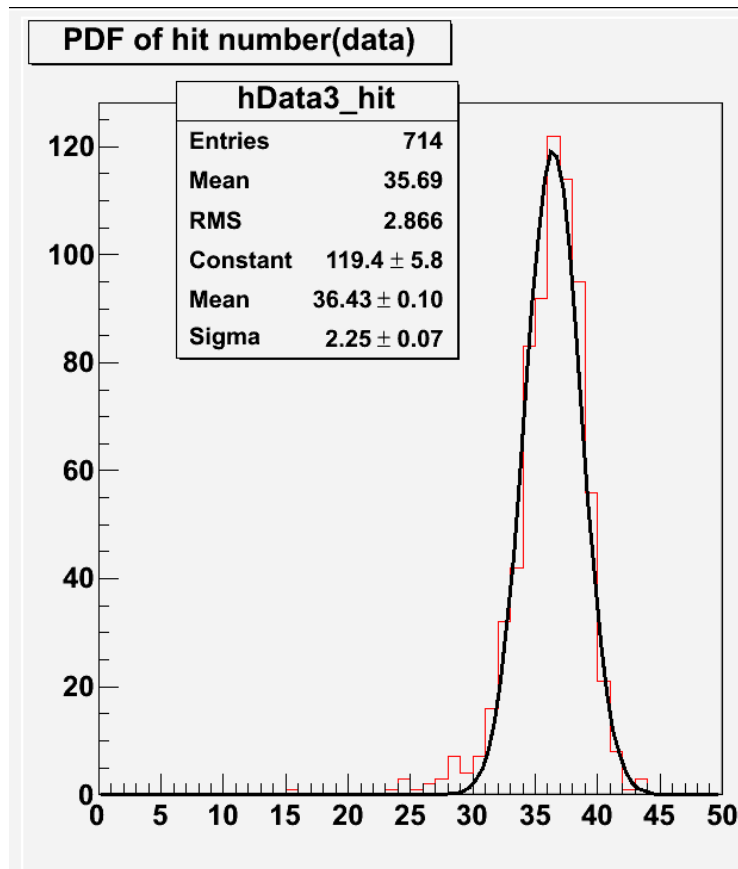
(2) loss of info. in sim.



2. (2) loss of info. in sim.

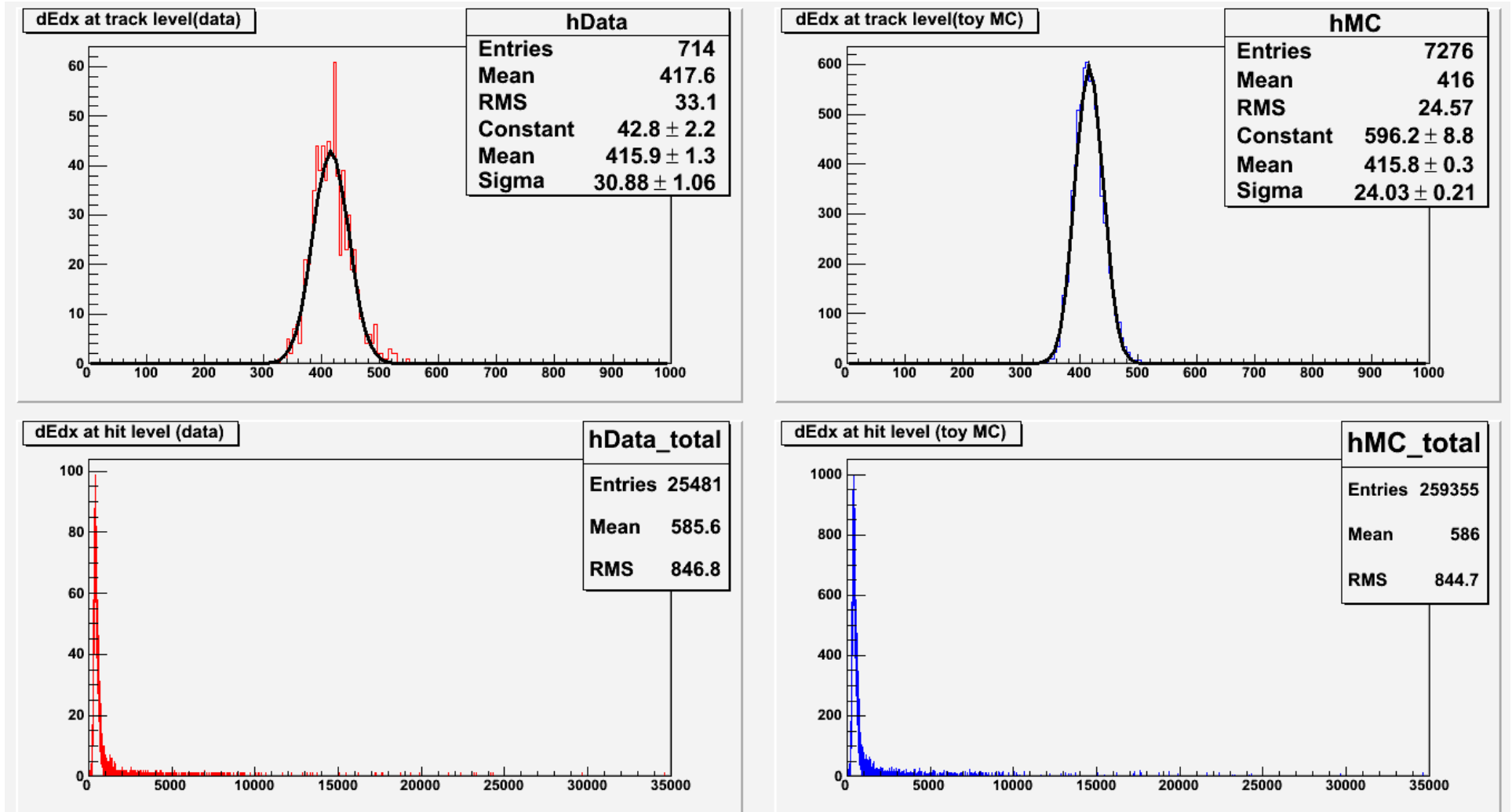
(a) Sampling from a single hist.

- 以下toy MC 的dEdx只从单个直方图抽取.(排除动量、角度、击中数分布不一致的影响)
- Momentum: $0.8\text{GeV}/c < p < 0.85\text{GeV}/c$, angle: $0 < \cos\theta < 0.1$



2. (2) loss of info. in sim.

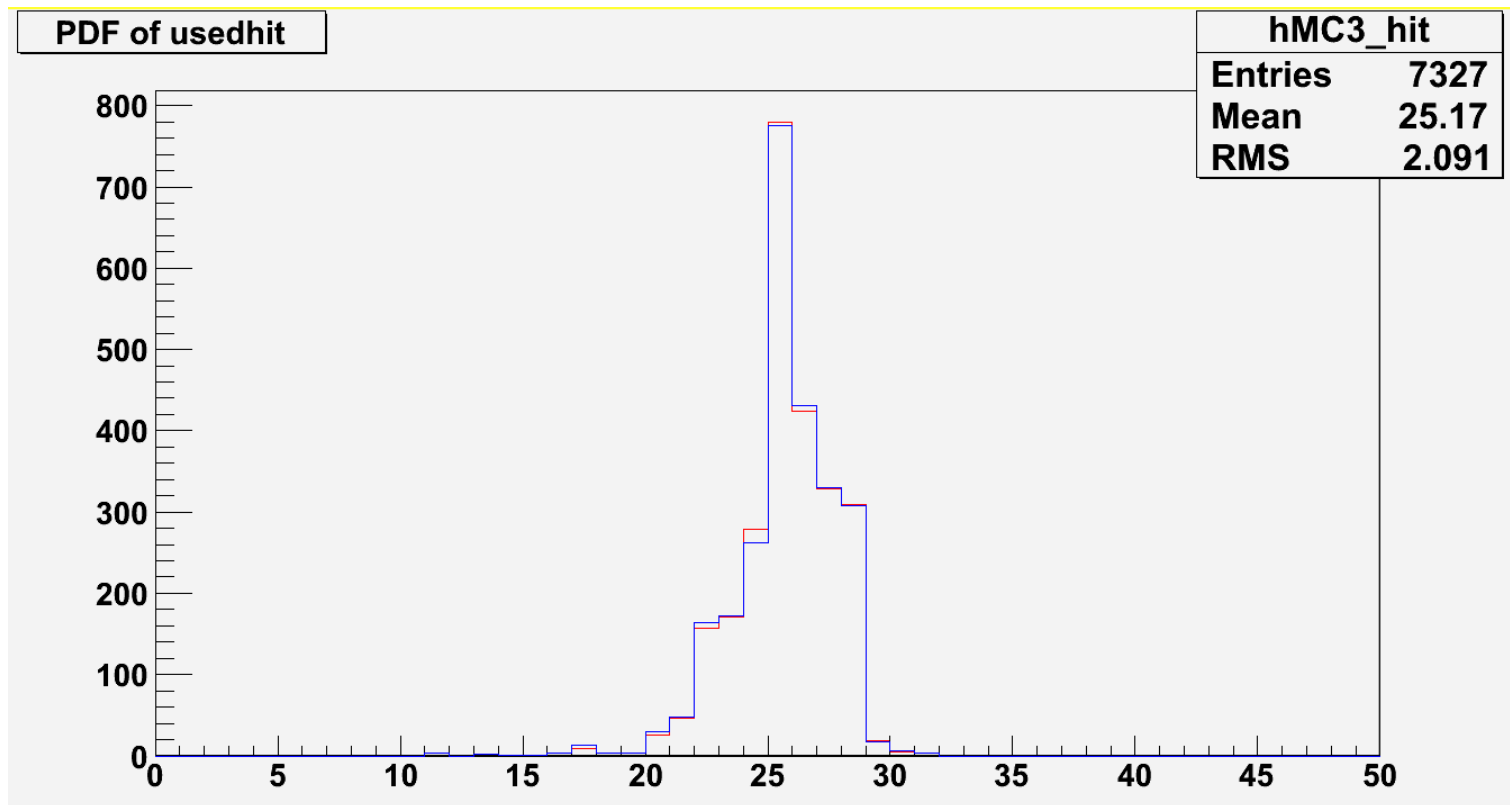
(a) Sampling from a single hist.



2. (2) loss of info. in sim.

(b) Sampling from a single hist. (take n_{hit} into account when sampling)

➤ Momentum: $0.8\text{GeV}/c < p < 1.0\text{GeV}/c$, angle: $0 < \cos\theta < 0.1$



2. (2) loss of info. in sim.

(b) Sampling from a single hist.(take n_{hit} into account when sampling)

