From "Development of monolithic pixel detector with SOI technology for the ILC vertex detector"

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Several Introduction slides about the SOI detector from Prof. Arai (@OIST 2017Dec)

Features of SOI Pixel Detector

- Monolithic device. No mechanical bonding. Small pixel size.
- Fabricated with semiconductor process only.
 → High reliability and Low Cost.
- High Resistive fully depleted sensor (50um~700um thick) with Low sense node capacitance. → Large S/N.
- On Pixel processing with CMOS circuits.
- No Latch up and very low Single Event cross section.
- Can be operated in wide temperature (1K-570K) range.
- Based on Industry Standard Technology.



Charge affects the circuit (transistor) operation

Main issues in SOI Pixel





 Transistors does not work when highvoltage is applied to handle wafer.
 (Back-Gate Effect)

• Circuit signal and sense node couples. (Signal Cross Talk)

 Oxide trapped hole induced by radiation will shift transistor threshold voltage. (Radiation Tolerance)

1st refinement: Buried p-Well (BPW) keyword in the paper

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- Shrink pixel size without loosing sensitive area.
- Increase break down voltage with low dose region.
- With biasing middle Si layer, radiation hardness is improved.

"The BPW is a p+ layer implanted underneath the BOX layer, which reduces the electric field in the BOX layer by utilizing the p+-n junction. " (from M. Kochiyama et al., NIMA (2010))

Tracking Resolution: High-Energy Beam test @Fermi National Accelerator Lab.





Proton Beam (120 GeV/c)

Two kinds of SOIPIX-DSOI detectors are used:

- FPIX2 x 4: 8 μm square pixel detector
- SOFIST1 x 2: 20 μm square pixel detector

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I (Ryuta) have shortly introduced this page & next page in the past JC.

Tracking Resolution (cont.)



Today's paper is about the other (SOFIST) SOI pixel detector

Return to the paper ...

Requirements for the ILC vertex detector -- from the paper --

• Single point resolution of better than 3 μ m

• Time resolution to identify a single bunch crossing every 554 ns for 1300 bunches.

one comment : FPCCD (for ILC vertex) has no timing information

• Low detector occupancy of less than 2%

 \cdot Low material budget of less than 0.1-0.2% of radiation length X $_{\rm 0}$.

SOI sensor for Fine measurement of Space and Time (= SOFIST)

• A prototype pixel sensor for the ILC

- monolithic pixel sensor with silicon-on-insulator technology (SOIPIX), 0.2 μm fully depleted SOI CMOS process

- Pixel size : $20 \times 20 \ \mu m^2$
- Number of pixels : 3125×500 (\Leftrightarrow 50 x 50, proto ver.1)
- Sensor thickness: 50 μ m (\Leftrightarrow 500 μ m proto ver.1)

<u>Overview</u>

Circuit within a pixel



SOFIST prototype ver.1



taken from a slide by T. Mori "operation test of SOFIST:SOI sensor of ILC"



taken from a slide by T. Mori "operation test of SOFIST:SOI sensor of ILC"

Pixel Layout

Different BPW size

16x16, 14x14, 12x12

• Different Gain

Gain ~ 1/C



Beam Test

- 120 GeV proton beam
- Fermilab Test Beam Facility
- FPIX(2), another SOI
 pixel detector with 8x8 µm² fine position resolution
- trigger is made by coincidence of he scintillation counter and ATLAS pixel detector FE-I4



Figure 4. Setup (not to scale)

• 148 hours beam time (but they claimed "low" statistics for tracking ...)

Analysis I. Noise distribution

[Step]

1) noise of one pixel is extracted by fitting a Gaussian to the pedestal distribution

2) mean of Gaussian sigma of all pixels as the noise of the sensor



Figure 5. Pixel noise distribution. Left shows high-gain pixels and right shows low-gain pixels. The signal readout was done with an external 12-bit ADC.

Analysis II. Clustering

[Step]

1) calculate S/N for each pixel

2) extract a pixel with S/N>64 as a seed

3) extract a pixel with S/N>16 from 5x5 pixels around the seed, then add a pixel to the cluster

"N" would be the Gaussian sigma of the pixel or the "sensor" noise ?



Figure 6. Cluster signal distributions. Left shows high-gain pixels and right shows low-gain pixels (BPW = $12 \times 12 \,\mu m^2$). The signal readout was external 12-bit ADC.

Signal-to-Noise Ratio

Comments (question) from Tao about the definition of the S/N

Table 1. Summary of signal-to-noise ratio.

| | High-gain | low-gain | low-gain | low-gain |
|-----|------------------------|-------------------------------|-------------------------------|-------------------------------|
| | $16 \times 16 \mu m^2$ | $12 \times 12 \mu \text{m}^2$ | $14 \times 14 \mu \text{m}^2$ | $16 \times 16 \mu \text{m}^2$ |
| S/N | 409 ± 45 | 315 ± 30 | 296 ± 27 | 285 ± 20 |

- S: Most Probable value of the fitted Landau function
- N: Noise of a single pixel ("sensor" noise)

However, though it is not explicitly written, the cluster size might be close to 1 due to

- -- full depletion with high bias voltage => charge will be collected mainly by drift not diffusion
- -- it is possible that the beam track is almost perpendicular to the sensor
- -- relatively high cut threshold, owing to the 500 μm thickness

Analysis III. Spatial Resolution

-- (in offline) X, Y position adjustment between the sensors.

-- (in offline) rotation angle around z direction adjustment

Iterative alignment

obtain residual distribution after this fine-tuning



Subtracting the position resolution of the reference detector (FPIX2), the position resolution of SOFIST is \sim 1.2 μ m.

Conclusion and future prospect

memories, and on-chip column ADCs. Its pixel size is $20 \times 20 \,\mu m^2$. Using a 120 GeV proton beam at Fermilab Test Beam Facility, we obtained a residual resolution of approximately 1.5 μ m. The effect of Coulomb multiple scattering is negligible. If we subtract the tracking resolution, the spatial resolution of SOFIST ver.1 is estimated to be close to $1.2 \,\mu\text{m}$ under the used readout and depletion conditions. The second prototype sensor SOFIST ver.2 ($25 \times 25 \,\mu m^2$ pixel size) has a time stamp circuit and on-chip Zero-suppression logic. We plan to perform a beam test in January 2018 to study these functions. Our next challenge is implementing the full pixel circuit in the $20 \times 20 \,\mu \text{m}^2$. The next prototype sensor SOFIST ver.4 is a 3D integrated SOI sensor. We will adopt the 3D integration technology of Au cone bump method by T-Micro [12] that allows connection between upper and lower chip with $5 \,\mu m \times 5 \,\mu m$ spacing. The lower chip for the analog part has an amplifier and comparator, and the upper chip for the digital part has a shift register, and analog and time stamp memories up to three hits. SOFIST ver.4 was submitted in June 2017, and it will be delivered in December 2017.