## Scattering Amplitudes and Feynman integrals

Feynman integrals



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# Outline

- 1. Scattering amplitudes, an formal overview
- 2. Feynman integral representation and reduction
- 3. Feynman integral evaluation

## 1. Scattering amplitudes

Quantum transit rate for particle scattering



calculable by perturbation theory in quantum field theory

comparable with the measured cross sections from experiments



## How can scattering amplitude become a branch of theoretical physics ?

A. Surprisingly simple structures

Britto-Cachazo-Feng-Witten (BCFW) Kawai-Lewellen-Tye (KLT) Bern-Carassco-Johannson (BCJ) ....

B. Brave exploration of amplitudes in formal theories

amplitudes in N=4 super-Yang-Mills amplitudes in N=8 supergravity

C. Precision frontier of the LHC physics

multi-loop amplitudes in QCD and the standard model

## Surprisingly simple structures in amplitudes

Britto-Cachazo-Feng-Witten (BCFW)

Nucl.Phys. B715 (2005) 499-522 Phys.Rev.Lett. 94 (2005) 181602



Traditionally scattering amplitudes are calculated by Feynman diagrams

Even for the tree amplitudes, internal off-shell parts exist.

It is not clear how a high-multiplicity tree amplitude can be constructed from low-multiplicity **on-shell** tree amplitudes.

(BCFW) A high-multiplicity tree amplitude can be constructed from low-multiplicity COMPLEX on-shell tree amplitudes.



## Surprisingly simple structures in amplitudes

## Kawai-Lewellen-Tye (KLT)

Nucl.Phys. B269 (1986) 1-23



(closed string tree amplitude) = (open string tree amplitude) × (open string tree amplitude)

$$A_{\text{closed}}^{(4)}(\text{tachyon}) = -\pi\kappa^{2} \sin(\pi k_{2} \cdot k_{3}) A_{\text{open}}^{(4)}(s, t | \overline{A}_{\text{open}}^{(4)}(t, u), \qquad (3.11)$$
  
For the four-point amplitude, this simply means (3.11) can be rewritten as
$$A_{\text{closed}}^{(4)} = -\pi\kappa^{2} \sin(\pi k_{1} \cdot k_{2}) A_{\text{open}}^{(4)}(s, t) \overline{A}_{\text{open}}^{(4)}(s, u). \qquad (3.29)$$

tree-level graviton amplitude is the "square" of gluon amplitude in Yang-Mills theory

 $\sin(\pi k_2 \cdot k_3) A_{\text{open}}(t, u) = \sin(\pi k_1 \cdot k_2) A_{\text{open}}(s, u)$ 

Color-stripped tree amplitudes in Yang-Mills theory are linearly related

## Surprisingly simple structures in amplitudes

### From KLT to BCJ

 $\alpha' \to 0,$ 

 $\bar{A}^{(4)}_{\text{open}}(s,u) \rightarrow -\frac{n_s}{s} + \frac{n_u}{u}, \quad \bar{A}^{(4)}_{\text{open}}(t,u) \rightarrow -\frac{n_u}{u} + \frac{n_t}{t}$ 

Therefore  $n_s + n_t + n_u = 0$  (BCJ, tree-level 4-point).

### Bern-Carrasco-Johansson



Physical Review D, 78, 2008, 085011

Tree-level  $A_{\text{YM}} = \sum_{i} \frac{c_{i}n_{i}}{P_{i}}$  Loop-level  $A_{\text{YM}}^{L\text{-loop}} = \int d^{D}l_{1} \dots d^{D}l_{L} \sum_{i} \frac{c_{i}n_{i}}{P_{i}}$ BCJ:

- 1. We can re-arrange the kinematic terms such that if  $c_i + c_j + c_k = 0$ , then  $n_i + n_j + n_k = 0$  (BCJ numerators).
- 2. For BCJ numerators, the gravity amplitude is,

Tree-level 
$$A_{\text{grav}} = \sum_{i} \frac{n_i n_i}{P_i}$$
 Loop-level  $A_{\text{grav}}^{L\text{-loop}} = \int d^D l_1 \dots d^D l_L \sum_{i} \frac{n_i n_i}{P_i}$ 

## Brave exploration of amplitudes in formal theories

N=4 super-Yang-Mills

Pro



- maximally supersymmetric gauge theory in 4D
- conformal symmetry
- dual conformal symmetry for the planar N=4 SYM (large N limit)
- Usually its loop integrand is much simpler than the corresponding pure Yang-Mills integrand
- Compass for loop amplitude computation

#### Con

• N=4 SYM is too far away from the world

### N=4 super-Yang-Mills



### N=8 supergravity

Is there a UV-finite quantum gravity theory in the framework of field theory? N=8 supergravity?

"UV-finiteness is not a philosophy question, but an amplitude question"

Loop-level 
$$A_{\text{grav}}^{L\text{-loop}} = \int d^D l_1 \dots d^D l_L \sum_i \frac{n_i n_i}{P_i}$$
 BCJ

$$D_c = \frac{6}{L} + 4,$$
  $(2 \le L \le 4)$ 

1804.09311 Zvi Bern et al

5-loop N = 8 supergravity is UV divergent at D = 24/5 which corresponds to a counter term  $D^8 R^4$ ...... 7 loop D=4 UV divergent ?

## Multi-loop amplitudes for the LHC physics



Cross section

## Multi-loop amplitudes for the LHC physics

Integrand



## 2. Feynman integral representation and reduction

### Feynman integral representation

$$I[\alpha_1,\ldots,\alpha_m] = \int \frac{d^D l_1}{i\pi^{D/2}} \ldots \int \frac{d^D l_L}{i\pi^{D/2}} \frac{1}{D_1^{\alpha_1} \ldots D_m^{\alpha_m}}$$

Feynman parametric representation

$$I[\alpha_1, \dots, \alpha_m] = \frac{(-1)^{|\alpha|} \Gamma(|\alpha| - \frac{DL}{2})}{\Gamma(\alpha_1) \dots \Gamma(\alpha_m)} \int_0^1 \prod_{i=1}^m dz_i \, \delta(1 - \sum_j z_j) z_1^{\alpha_1 - 1} \dots z_m^{\alpha_m - 1} \frac{F^{LD/2 - |\alpha|}}{U^{(L+1)D/2 - |\alpha|}}$$

parametric representation

Roman Lee 1405.5616

$$I[\alpha_1, \dots, \alpha_m] = \frac{(-1)^{|\alpha|} \Gamma(D/2)}{\Gamma((L+1)D/2 - |\alpha|) \Gamma(\alpha_1) \dots \Gamma(\alpha_m)} \int_0^\infty \prod_{i=1}^m dz_i \, z_1^{\alpha_1 - 1} \dots z_m^{\alpha_m - 1} G^{-D/2}$$

G = F + U

useful for eduction problems

#### Baikov representation

#### Phys.Lett. B385 (1996) 404-410

When k = LE + L(L + 1)/2, (E is the number of independent legs), the Baikov rep. is

$$\int \frac{d^{D}l_{1}}{i\pi^{D/2}} \dots \int \frac{d^{D}l_{L}}{i\pi^{D/2}} \frac{1}{D_{1}^{\alpha_{1}} \dots D_{k}^{\alpha_{k}}} \propto \prod_{1 \le i \le L+E, \max\{i, E+1\} \le j \le L+E} \left(\int dx_{ij}\right) \det(S)^{\frac{D-L-E-1}{2}} \frac{1}{D_{1}^{\alpha_{1}} \dots D_{k}^{\alpha_{k}}}$$
$$\propto \prod_{i=1}^{k} \left(\int dz_{i}\right) \det(S)^{\frac{D-L-E-1}{2}} \frac{1}{z_{1}^{\alpha_{1}} \dots z_{k}^{\alpha_{k}}} \qquad z_{i} \equiv D_{i}$$
where  $\{v_{1}, \dots, v_{L+E}\} \equiv \{k_{1}, \dots, k_{E}, l_{1}, \dots, l_{L}\}$  and  $x_{ii} \equiv v_{i} \cdot v_{i}$ . *S* is a  $(L+E) \times (L+E)$  Baikov representation

where  $\{v_1, ..., v_{L+E}\} \equiv \{k_1, ..., k_E, l_1, ..., l_L\}$  and  $x_{ij} \equiv v_i \cdot v_j$ . *S* is a  $(L+E) \times (L+E)$ matrix with  $S_{ij} = x_{ij}$  (Gram matrix).

on

$$L = 2, E = 3, m = 7 \text{ and } k = 9. \{v_1, \dots, v_5\} \equiv \{k_1, k_2, k_4, l_1, l_2\}.$$

$$S = \begin{pmatrix} 0 & \frac{s}{2} & \frac{t}{2} & x_{11} & x_{21} \\ \frac{s}{2} & 0 & \frac{1}{2}(-s-t) & x_{12} & x_{22} \\ \frac{t}{2} & \frac{1}{2}(-s-t) & 0 & x_{13} & x_{23} \\ x_{11} & x_{12} & x_{13} & x_{44} & x_{45} \\ x_{21} & x_{22} & x_{23} & x_{45} & x_{55} \end{pmatrix}$$

$$= \begin{pmatrix} 0 & \frac{s}{2} & \frac{t}{2} & \frac{z_{1}}{2} - \frac{z_{2}}{2} & \frac{z_{0}}{2} - \frac{z_{0}}{2} \\ \frac{s}{2} & 0 & \frac{1}{2}(-s-t) & \frac{1}{2}(s-z_{3}) + \frac{z_{2}}{2} & \frac{1}{2}(z_{4}-s) - \frac{z_{9}}{2} \\ \frac{t}{2} & \frac{1}{2}(-s-t) & 0 & \frac{z_{8}}{2} - \frac{z_{1}}{2} & \frac{z_{6}}{2} - \frac{z_{5}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{1}{2}(z_{4}-s) - \frac{z_{9}}{2} & \frac{z_{6}}{2} - \frac{z_{5}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{1}{2}(z_{4}-s) - \frac{z_{9}}{2} & \frac{z_{6}}{2} - \frac{z_{5}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{1}{2}(z_{4}-s) - \frac{z_{9}}{2} & \frac{z_{6}}{2} - \frac{z_{5}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{1}{2}(z_{4}-s) - \frac{z_{9}}{2} & \frac{z_{6}}{2} - \frac{z_{5}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{1}{2}(z_{4}-s) - \frac{z_{9}}{2} & \frac{z_{6}}{2} - \frac{z_{5}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{1}{2}(z_{4}-s) - \frac{z_{9}}{2} & \frac{z_{6}}{2} - \frac{z_{5}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{1}{2}(z_{4}-s) - \frac{z_{9}}{2} & \frac{z_{6}}{2} - \frac{z_{5}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{z_{9}}{2} & \frac{z_{6}}{2} - \frac{z_{5}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{z_{9}}{2} & \frac{z_{9}}{2} - \frac{z_{6}}{2} + \frac{z_{7}}{2} \\ \frac{z_{9}}{2} - \frac{z_{6}}{2} & \frac{z_{9}}{2} & \frac{z_{9}}{2} & \frac{z_{9}}{2} - \frac{z_{9}}{2} \\ \frac{z_{9}}{2} - \frac{z_{9}}{2} & \frac{z_{9}}{2} & \frac{z_{9}}{2} - \frac{z_{9}}{2} \\ \frac{z_{9}}{2} - \frac{z_{9}}{2} & \frac{z_{9}}{2} & \frac{z_{9}}{2} \\ \frac{z_{9}}{2} - \frac{z_{9}}{2} & \frac{z_{9}}{2} \\ \frac{z_{9}}{2} & \frac{z_{9}}{2} \\ \frac{z_{9}}{2} & \frac{z_{9}}{$$

#### Feynman integral reduction

Integration-by-parts identities

$$0 = \int \frac{d^D \ell_1}{\mathrm{i}\pi^{D/2}} \dots \frac{d^D \ell_L}{\mathrm{i}\pi^{D/2}} \sum_{j=1}^L \frac{\partial}{\partial \ell_j^{\mu}} \frac{v_j^{\mu}}{D_1^{\nu_1} \dots D_m^{\nu_m}}$$

- By IBPs, for any Feynman diagram + sub diagrams, the number of master integrals is finite (Smirnov)
- IBP reduces the integrals to a basis of master integrals
- IBP reduction is difficult with multi-loop multi-scale diagrams (bottleneck)

Air Anastasiou, LazopoulosFIRE SmirnovKira Maierhoefer, Usovitsch, and UwerReduze von Manteuffel and C. Studerus

#### IBPs in Baikov representation

$$R = \mathbb{Q}(\text{parameters})[z_1, \dots z_k]$$

$$\int \frac{d^D l_1}{i\pi^{D/2}} \dots \int \frac{d^D l_L}{i\pi^{D/2}} \frac{1}{D_1^{\alpha_1} \dots D_m^{\alpha_m} D_{m+1}^{\alpha_{m+1}} \dots D_k^{\alpha_k}}, \quad \begin{cases} \alpha_i \le 1, & 1 \le i \le m \\ \alpha_i \le 0, & m < i \le k \end{cases}$$

Just consider IBPs 
$$0 = \left(\prod_{i=1}^{k} \int dz_i\right) \sum_{j=1}^{k} \frac{\partial}{\partial z_j} \left(a_j(z) \det(S)^{\frac{D-L-E-1}{2}} \frac{1}{z_1 \dots z_m}\right)$$
Polynomials!

Further require  $F \equiv \det(S)$  "Affine varieties and Lie algebras of vector fields" Hauser, Müller 1993

1. no shifted exponent: 
$$\sum_{j=1}^{k} a_j(z) \frac{\partial F}{\partial z_j} + \beta(z)F = 0$$
 These  $(a_1(z), \dots, a_k(z))$  form a module  $M_1 \subset \mathbb{R}^k$ .

2. no doubled propagator(z)  $\in \langle z_i \rangle$ ,  $1 \leq i \leq m$  These  $(a_1(z), \dots, a_k(z))$  form a module  $M_2 \subset \mathbb{R}^k$ .

Both  $M_1$  and  $M_2$  are pretty simple ...

 $M_1 \cap M_2$  Intersection of two modules

#### Computation of the first module $M_1$

In principle, the syzygy can be computed by Schreyer's theorem but the computation is heavy ...

• syzygy for the 
$$\{\frac{\partial F}{\partial z_1}, \dots, \frac{\partial F}{\partial z_k}, F\}$$

•  $\operatorname{Ann}(F^{s})$ , annihilator of  $F^{s}$  in Weyl algebra.

If *F* is a determinant matrix whose elements are free variables, this kind of syzygy module is simple.

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$
 Roman Lee's idea  
No computation is needed

syzygy generators (Laplace expansion)

 $\sum_{j=1}^{\kappa} a_j(z) \frac{\partial F}{\partial z_j} + \beta(z)F = 0$ 

 $\sum_{j} a_{k,j} \frac{\partial(\det A)}{\partial a_{i,j}} - \delta_{k,i} \cdot \det A = 0 \text{ provides all syzygy generators}$ The Gram matrix in Baikov rep. is symmetric and not all entries are free variables "weighted" Laplace expansion

## Example, massless double box



 $M_1 \cap M_2$  (even without cut) is found in ~4 seconds, with Singular 4.1.0,

#### intersect(M1,M2,"std")

## nonplanar hexagon-box (3,6,7) cut 10 different cuts needed ( 8 triple cuts, 2 quadr

 $\mathbb{Q}(s_{12}, s_{13}, s_{14}, s_{23}, s_{24})[z_1, z_2, z_4, z_5, z_8, z_9, z_{10}, z_{11}]$ : 5 parameters, 11-3=8 variables  $z_3 \rightarrow 0, z_6 \rightarrow 0, z_7 \rightarrow 0$ 



Numerically (and over finite field) the intersection can be found in sever Analytically the intersection seems very difficult

## A trick for computational algebraic geometry

Janko Boehm, Hans Schoeneman, University of Kaisers

Analytic Mandelstam variables (parameters) slow down the computation,

Treat parameters as variables, and compute in a particular monomial ordering

Module intersection for (1,4,6,7)

 $\mathbb{Q}(s_{12}, s_{13}, s_{14}, s_{23}, s_{24})[z_2, z_3, z_5, z_8, z_9, z_{10}, z_{11}]$  with

 $z_2 > z_3 > z_5 > z_8 > z_9 > z_{10} > z_{11}$ 

 $\mathbb{Q}[z_2, z_3, z_5, z_8, z_9, z_{10}, z_{11}, s_{12}, s_{13}, s_{14}, s_{23}, s_{24}] \text{ with } \\ [z_2, z_3, z_5, z_8, z_9, z_{10}, z_{11}] > [s_{12}, s_{13}, s_{14}, s_{23}, s_{24}]$ 

[variables] > [parameters]

this trick makes all polynomials homogeneous

? (does not finish)

4 seconds with Singu

All module intersections for 10 necessary cuts found analyt



## Complete integration-by-parts reductions of the non-planar hexagon-box via module intersections

#### Janko Böhm,<sup>a</sup> Alessandro Georgoudis,<sup>b</sup> Kasper J. Larsen,<sup>c</sup> Hans Schönemann,<sup>a</sup> Yang Zhang<sup>d,e,f</sup>

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ABSTRACT: We present the powerful module-intersection integration-by-parts (IBP) method, suitable for multi-loop and multi-scale Feynman integral reduction. Utilizing modern computational algebraic geometry techniques, this new method successfully trims traditional IBP systems dramatically to much simpler integral-relation systems on unitarity cuts. We demonstrate the power of this method by explicitly carrying out the complete analytic reduction of two-loop five-point non-planar hexagon-box integrals, with degree-four numerators, to a basis of 73 master integrals.

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## 3. Feynman Integral evaluation

## Differential equation (DE)

*I*: a list of *N* master integrals in dimensional regularization (DimReg)

 $\frac{\neg}{\partial x_i}I = M_i(\epsilon)I$ 

Kotikov 1991 Bern, Dixon and Kosower 1994 Gehrmann and Remiddi 2000

 $x_i$ 's are kinematic variables

Matrices can be generated by IBPs

Gauge Transformation  $I \mapsto TI, \quad M_i \mapsto TM_iT^{-1} + (\partial_iT)T^{-1}$ 

 $M_i$ 's form the connection of the N-dim vector bundle

Integrability  $\partial_i M_j - \partial_j M_i + [M_i, M_j] = 0$ 

The connection has zero curvature

$$dI = \omega I, \quad \omega \equiv \sum_{i} M_{i} dx_{i}$$
  
flat meromorphic connection

A smart basis choice, Henn, Phys.Rev.Lett. 110 (2013) 251601

## Canonical basis I

- In general, only first several orders in  $\epsilon$  are needed.
- Some integrals are known to have constant leading singularities or *dlog*.
- In differential geometry, zero curvature ⇒ constant metric after a change of coordinates. Here for flat connection ...

$\tilde{I} = T(\epsilon)I,$	$\frac{\partial}{\partial x_i}\tilde{I} = \epsilon A_i\tilde{I}$
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Henn 2013

$$\partial_i A_j = \partial_j A_i, \quad [A_i, A_j] = 0, \quad \omega = dA$$

connection trivialized

Boundary condition given by kinematic limit/ traditional Feynman parameterization

Feynman integrals become iterated integral  $\tilde{I}(x) = P \exp\left(\epsilon \int_{\mathcal{C}} dA\right) \tilde{I}(x_0)$ 

> path ordered integral, expressible as Chen's (陳國才) iterated integrals

# Canonical basis II $\tilde{I}(x) = P \exp\left(\epsilon \int_{\mathcal{C}} dA\right) \tilde{I}(x_0)$ Henn 2013

When *dA* has the d-logarithm form,

$$A = \sum_{k} C_k \log \alpha_k(x) \longrightarrow alphabets,$$
  
indicate the special  
functions in amplitudes

it is clear that  $\tilde{I}(x)$  has uniform transcendentality.

 $\mathcal{T}(\log) = 1, \mathcal{T}(\pi) = 1, \mathcal{T}(\zeta_n) = n, \mathcal{T}(\mathrm{Li}_n) = n, \dots, \mathcal{T}(f_1 f_2) = \mathcal{T}(f_1) + \mathcal{T}(f_2)$ 

- makes the DE solving simple
- the canonical basis integrals have simple expression (UT)
- also makes numeric integration much easier

#### Find canonical basis

- Leading singularity/ d-log integrand form (Henn 2013)
- Feynman parametrization (Henn 2013, 2014)
- Eigenvalue analysis for residue matrix and balance transformation One-variable case (Lee 2014)
- Packages: Fuchsia (Gituliar, Magerya), epsilon (Prausa)

Elliptic case, transformation using modular form (Adam, Weinzierl 2017)

## dbox example

#### Henn 2013

HPLs



$$f_{1} = -\epsilon^{2} (-s)^{2\epsilon} t I_{0,2,0,0,0,0,0,1,2},$$

$$f_{2} = \epsilon^{2} (-s)^{1+2\epsilon} I_{0,0,2,0,1,0,0,0,2},$$

$$f_{3} = \epsilon^{3} (-s)^{1+2\epsilon} I_{0,1,0,0,1,0,1,0,2},$$

$$f_{4} = -\epsilon^{2} (-s)^{2+2\epsilon} I_{2,0,1,0,2,0,1,0,0},$$

$$f_{5} = \epsilon^{3} (-s)^{1+2\epsilon} t I_{1,1,1,0,0,0,0,1,2},$$

$$f_{6} = -\epsilon^{4} (-s)^{2\epsilon} (s+t) I_{0,1,1,0,1,0,0,1,1},$$

$$f_{7} = -\epsilon^{4} (-s)^{2+2\epsilon} t I_{1,1,1,0,1,0,1,1,1},$$

$$f_{8} = -\epsilon^{4} (-s)^{2+2\epsilon} I_{1,1,1,0,1,-1,1,1,1},$$

Simple known integrals ... Integrate out the bubble ...

Feynman parametrization d-log form

$$f_{1} = -\epsilon^{2} (-s)^{2\epsilon} t I_{0,2,0,0,0,0,0,1,2},$$

$$f_{2} = \epsilon^{2} (-s)^{1+2\epsilon} I_{0,0,2,0,1,0,0,0,2},$$

$$f_{3} = \epsilon^{3} (-s)^{1+2\epsilon} I_{0,1,0,0,1,0,1,0,2},$$

$$f_{4} = -\epsilon^{2} (-s)^{2+2\epsilon} I_{2,0,1,0,2,0,1,0,0},$$

$$f_{5} = \epsilon^{3} (-s)^{1+2\epsilon} t I_{1,1,1,0,0,0,0,1,2},$$

$$f_{6} = -\epsilon^{4} (-s)^{2\epsilon} (s+t) I_{0,1,1,0,1,0,0,1,1},$$

$$f_{7} = -\epsilon^{4} (-s)^{2+2\epsilon} t I_{1,1,1,0,1,0,1,1,1},$$

$$f_{8} = -\epsilon^{4} (-s)^{2+2\epsilon} I_{1,1,1,0,1,-1,1,1,1}.$$
and

$$\partial_x f = \epsilon \left[ \frac{a}{x} + \frac{b}{1+x} \right] f, \qquad b =$$

Henn 2013

,

## Roman Lee's algorithm

JHEP 1504 (2015) 108



works very well for ODEs

## Other modern differential equation techniques

SDE



Papadopoulos, JHEP 1604 (2016) 078

DE from vacuum

$$I(D; \{\nu_{\alpha}\}; \eta) \equiv \int \prod_{i=1}^{L} \frac{\mathrm{d}^{D} \ell_{i}}{\mathrm{i}\pi^{D/2}} \prod_{\alpha=1}^{N} \frac{1}{(\mathcal{D}_{\alpha} + \mathrm{i}\eta)^{\nu_{\alpha}}},$$

Xiao Liu, Yan-Qing Ma and Chen-Yu Wang Phys.Lett. B779 (2018) 353-357