

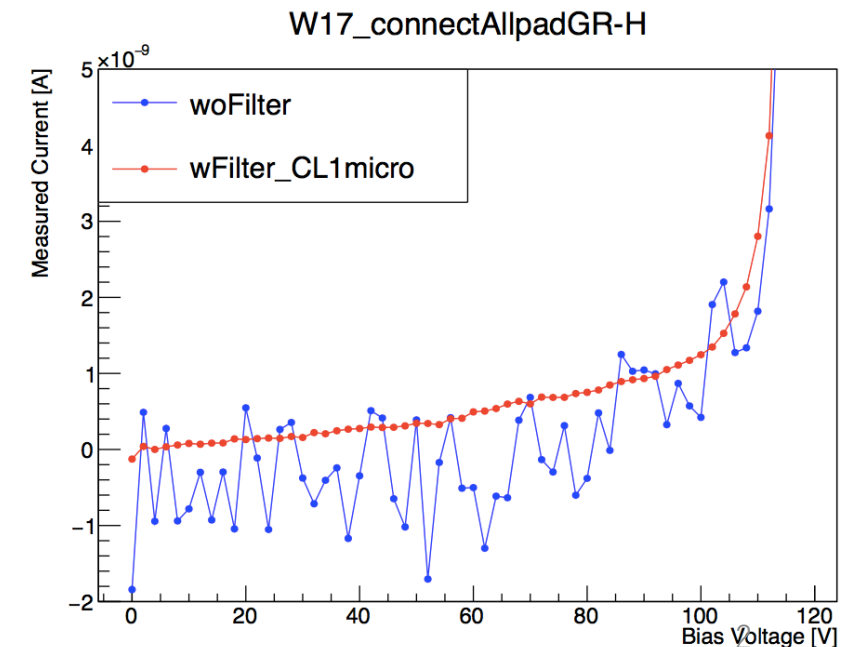
Update on the sensor test etc.

03/07/2019

IV measurement settings

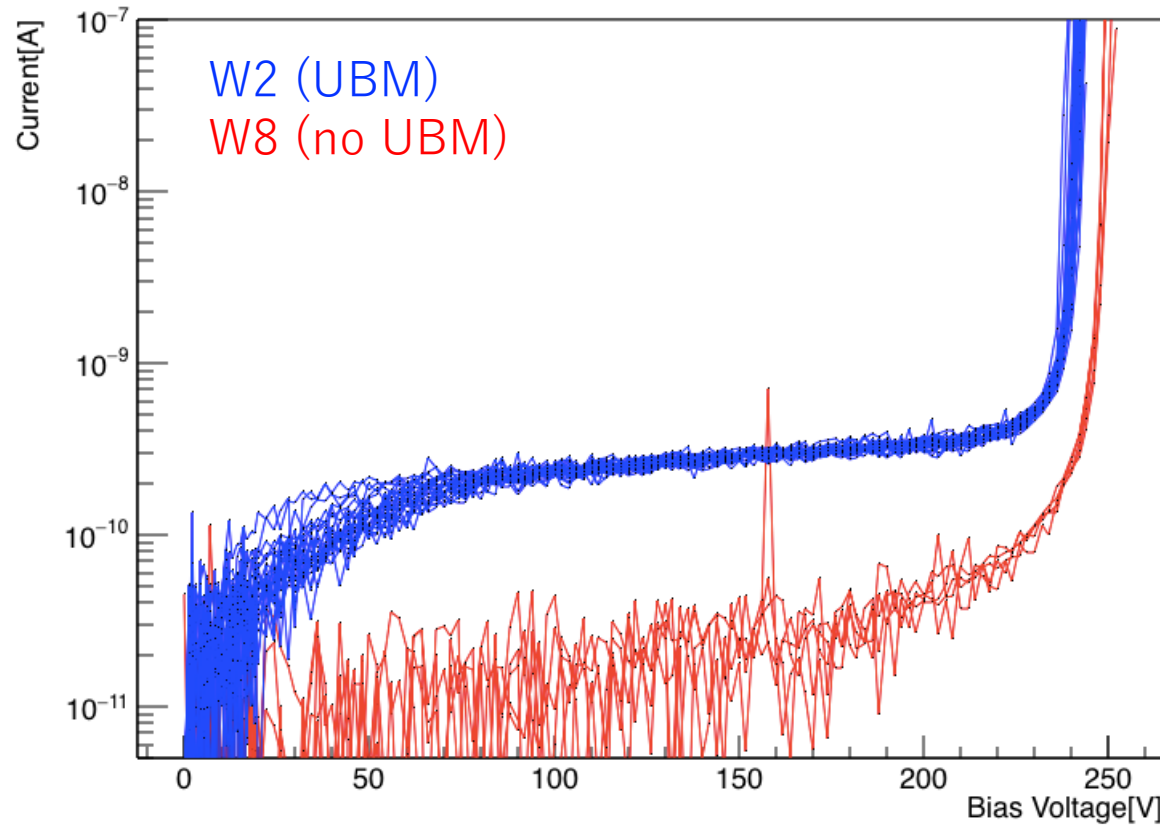
- Measurements done with all pads and the guard ring (GR) connected.
 - 24 neighbor pads and GR are connected to ground.
 - Keithley 2410 provides HV applied to the back of the sensor.
 - Keithley 2400 measures the pad current.
 - Current compliance and limit: $1\mu\text{A}$
 - Filter enabled.

Much improved resolution with the new settings →

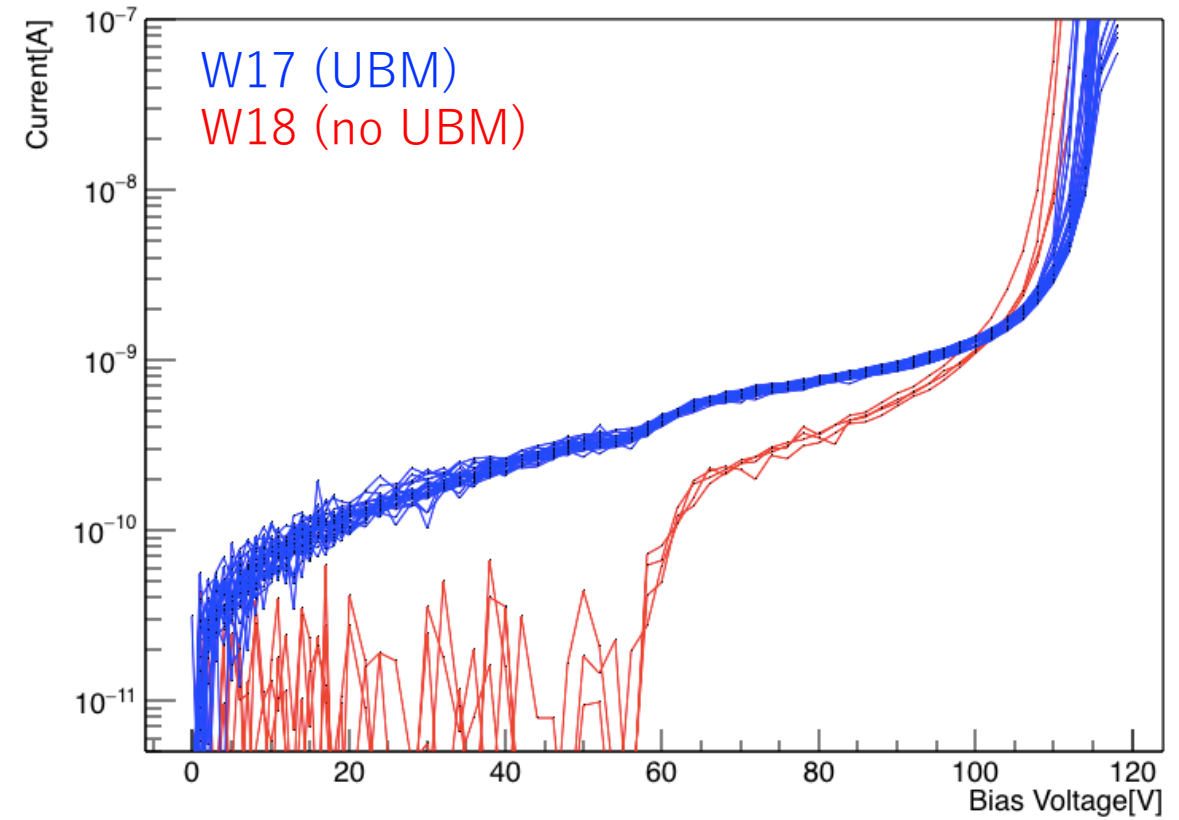


HPK 5x5 sensors : comparison with and w/o UBM

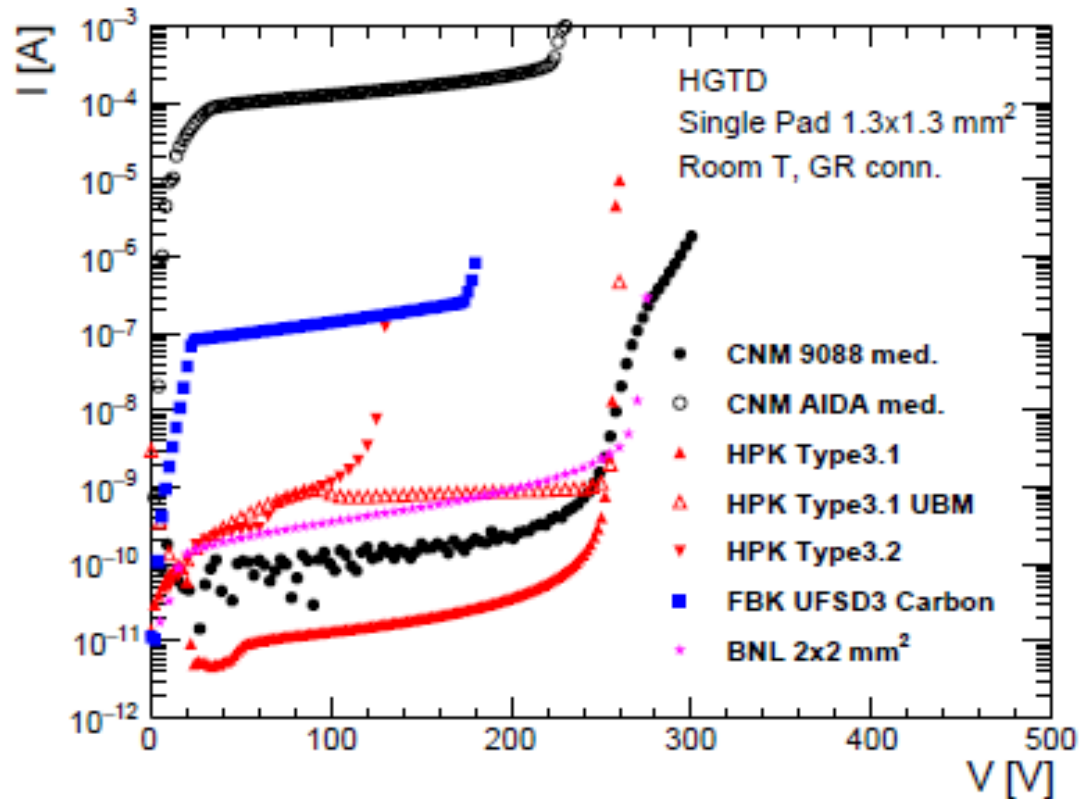
Type 3.1



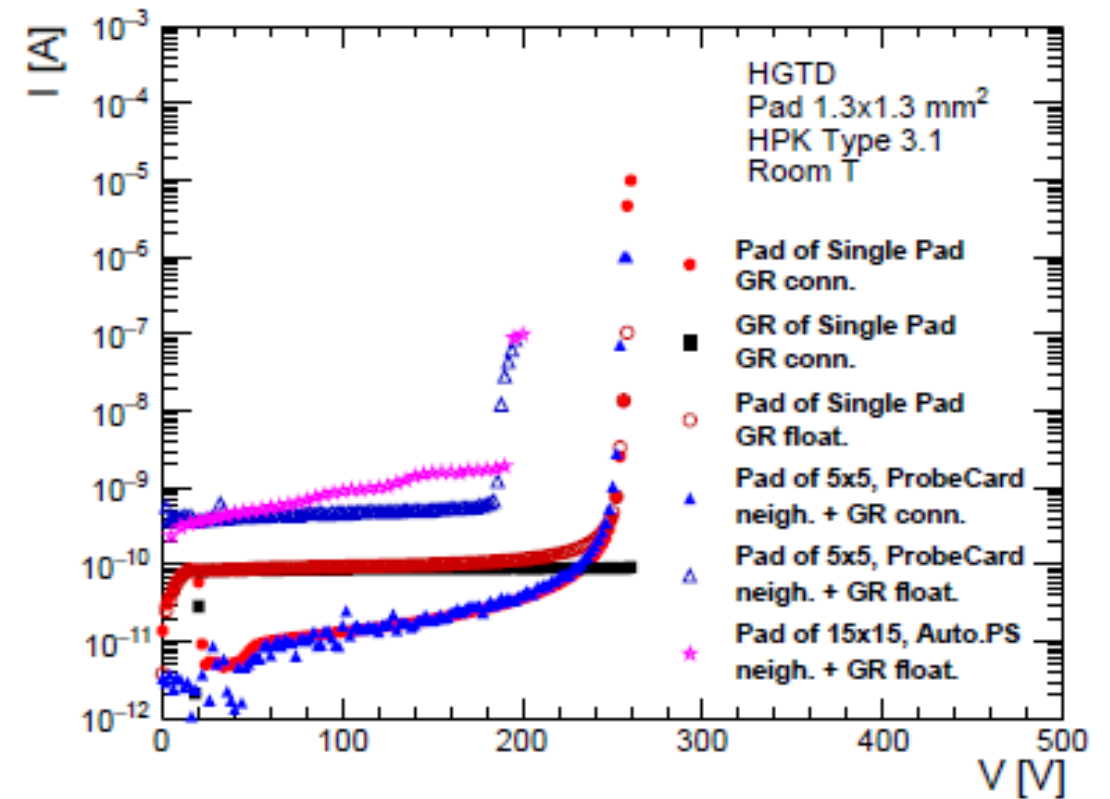
Type 3.2



Reference : Figure 5.4, TDR (pre. ver.)



(a) I-V for different runs.



(c) I-V for different types and conditions.

Our result looks similar to those. (Type3.2 UBM is not shown)

Order of 10^{-12} (pA) would be needed for Type3.1 to see structures

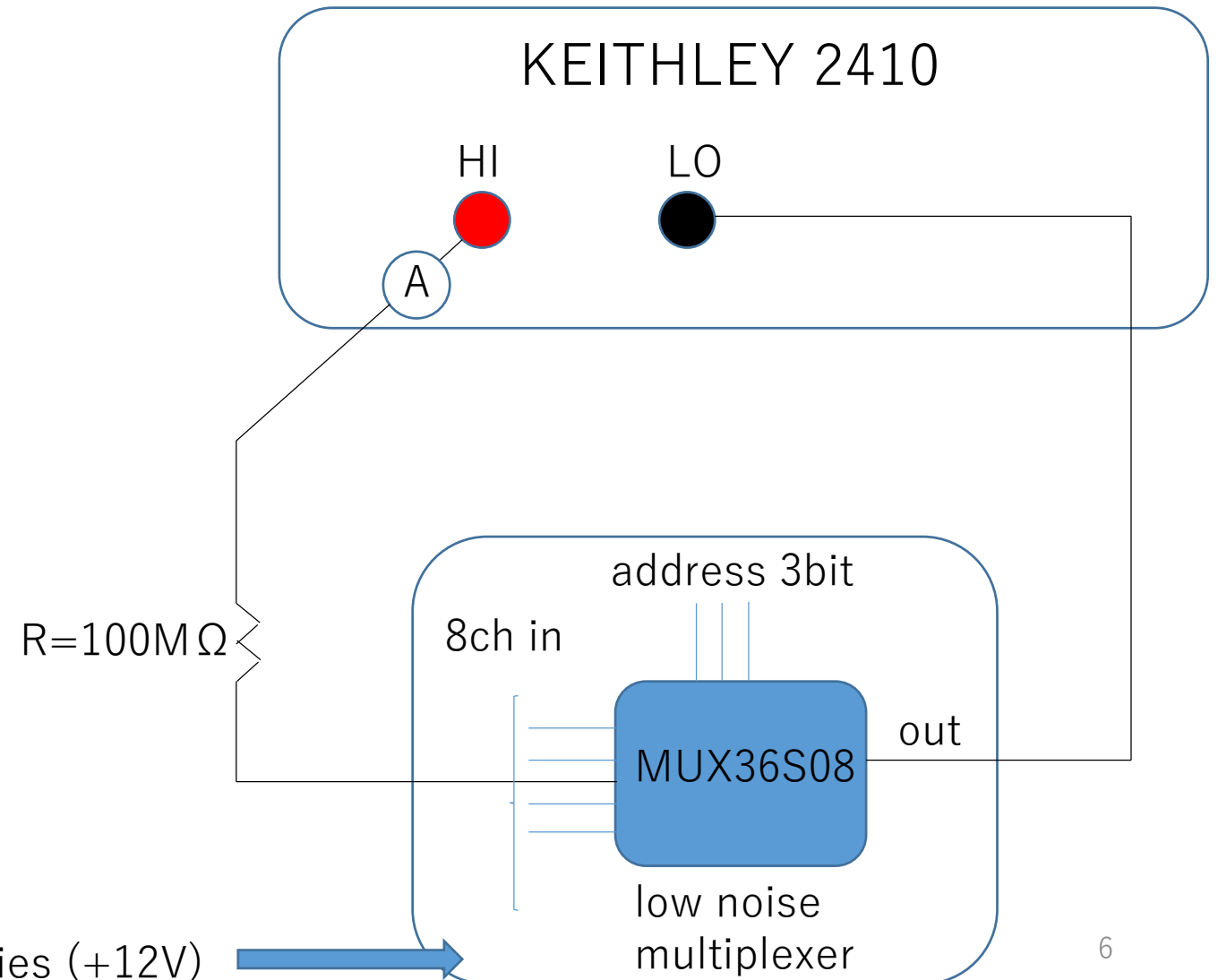
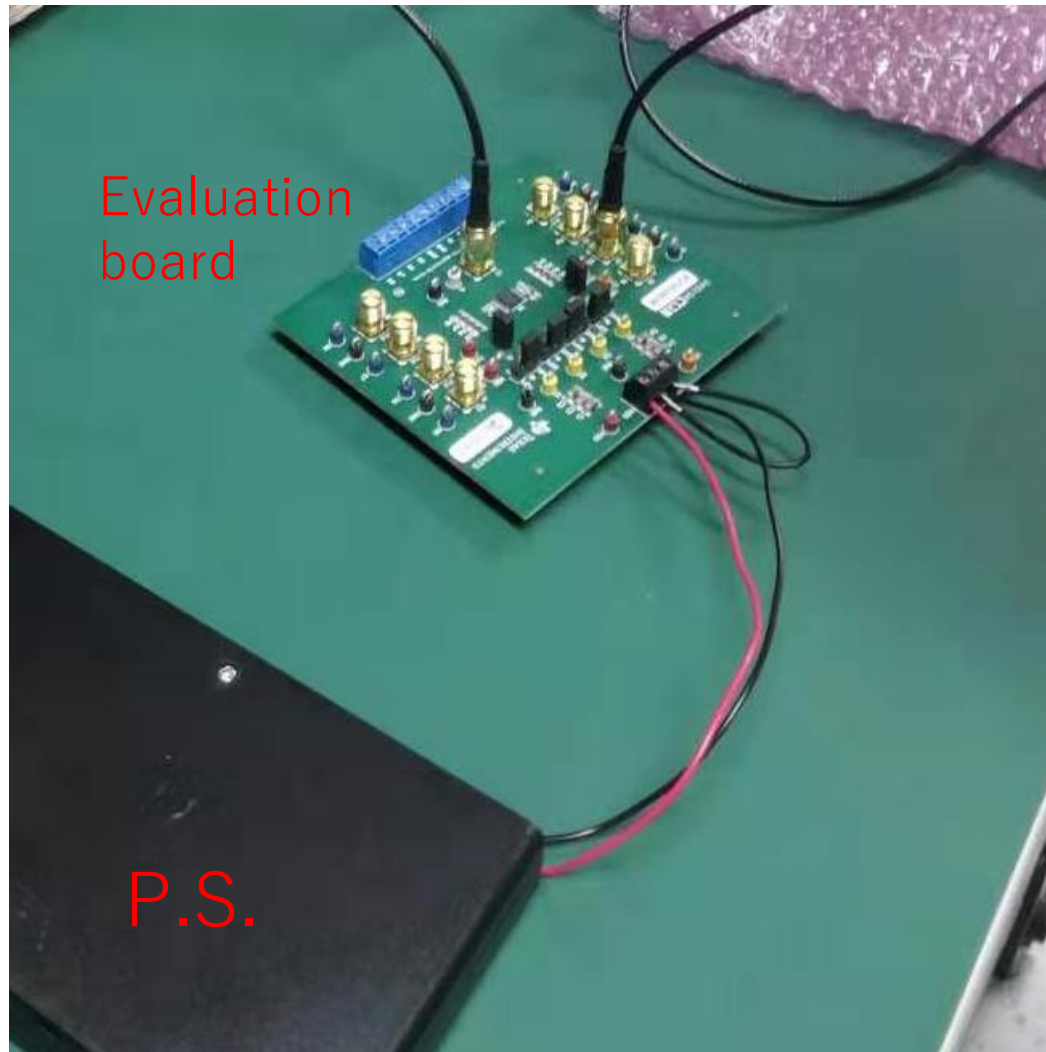
Array test table : (final call just before this meeting ...)

| B | C | D | E | F | G | H | I | J | K | L | M | N | O | P |
|-------------------------------|----------------|-------------|---------------------------|---------------------|---------------------------------|---------------------------|---|-------------------------------|----------------|-------------|---------------------------|---------------------|---------------------------------|---------------------------|
| Type 3.1 | | | | | | | | Type 3.2 | | | | | | |
| Sensor | Sensors tested | Pads tested | Number of Perfect Sensors | Number of Good Pads | Fraction of Perfect Sensors [%] | Fraction of Good Pads [%] | | Sensor | Sensors tested | Pads tested | Number of Perfect Sensors | Number of Good Pads | Fraction of Perfect Sensors [%] | Fraction of Good Pads [%] |
| Type | | | | | | | | Type | | | | | | |
| Single (based on HPK probing) | 648 | 648 | 648 | 648 | 100 | 100 | | Single (based on HPK probing) | 216 | 216 | 216 | 216 | 100 | 100 |
| Single SE5 | 360 | 360 | 360 | 360 | 100 | 100 | | Single SE5 | 120 | 120 | 120 | 120 | 100 | 100 |
| Single SE5 | 144 | 144 | 144 | 144 | 100 | 100 | | Single SE5 | 48 | 48 | 48 | 48 | 100 | 100 |
| Single SE5 | 144 | 144 | 144 | 144 | 100 | 100 | | Single SE5 | 48 | 48 | 48 | 48 | 100 | 100 |
| 5x5 All groups | 17 | 425 | 17 | 425 | 100 | 100 | | 5x5 All groups | 5 | 125 | 5 | 125 | 100 | 100 |
| 15x15 All groups | 8 | 1800 | 7 | 1799 | 87.5 | 99.94444444 | | 15x15 All groups | 3 | 675 | 2 | 673 | 66.66666667 | 99.7037037 |
| Göttingen: | | | | | | | | Göttingen: | | | | | | |
| 5x5 | 6 | 150 | 6 | 150 | 100 | 100 | | 5x5 | 1 | 25 | 1 | 25 | 100 | 100 |
| 15x15 | 7 | 1575 | 6 | 1574 | 85.71428571 | 99.93650794 | | 15x15 | 3 | 675 | 2 | 673 | 66.66666667 | 99.7037037 |
| UCSC: | | | | | | | | UCSC: | | | | | | |
| 5x5 | 10 | 250 | 10 | 250 | 100 | 100 | | 5x5 | 2 | 50 | 2 | 50 | 100 | 100 |
| 15x15 | 1 | 225 | 1 | 225 | 0 | 1 | | 15x15 | 0 | 0 | | | | |
| IHEP: | | | | | | | | IHEP: | | | | | | |
| 5x5 | 1 | 25 | 1 | 25 | 100 | 100 | | 5x5 | 2 | 50 | 2 | 50 | 100 | 100 |
| 15x15 | | | | | | | | 15x15 | | | | | | |
| BNL: | | | | | | | | BNL: | | | | | | |
| 5x5 | | | | | | | | 5x5 | | | | | | |
| 15x15 | | | | | | | | 15x15 | | | | | | |
| JSI: | | | | | | | | JSI: | | | | | | |
| 5x5 | | | | | | | | 5x5 | | | | | | |
| 15x15 | | | | | | | | 15x15 | | | | | | |

+ 2 Type3.1 sensors (Wo.1/Wo.2)

+ 1 Type3.2 sensors (Wo.17)

Test of the MUX evaluation board



Power Supply (P.S.) : Now with batteries (+12V)

Test of the MUX evaluation board

- Current fluctuation was $O(10)\mu\text{A}$ (including precision of SMU itself)



As expected from spec. sheet

- Address is controlled with shunts, therefore, the current fluctuation by using digital level from Raspberry Pi is the next issue. (personally, expecting the necessity of isolators)



Fig : $1\text{V}/1\text{M}\Omega = 0.01\mu\text{A}$ with fluctuation

Technical document on MUX36xxx (Texas Inst.)

| | | | | | |
|---------------------|-----------------------|---|--|-------------------------|-------------------------|
| | | $T_A = -40^\circ\text{C to } +125^\circ\text{C}$ | | 58 | |
| | On-resistance drift | $V_S = 0\text{ V}$ | | 0.62 | $\Omega/^\circ\text{C}$ |
| $I_{S(\text{OFF})}$ | Input leakage current | Switch state is off, $V_S = \pm 10\text{ V}$, $V_D = \pm 10\text{ V}^{(1)}$ | | -0.04 <u>0.001</u> 0.04 | nA |
| | | | $T_A = -40^\circ\text{C to } +85^\circ\text{C}$ | -0.15 0.15 | |
| | | | $T_A = -40^\circ\text{C to } +125^\circ\text{C}$ | -1.2 1.2 | |
| | Output off leakage | Switch state is off, | | -0.15 0.01 0.15 | |

Next

(from my side)

- Setup Raspberry PI
- IV on 5x5 arrays with KEITHLEY 6487
(depending on the schedule)