

三体体系在有限体积内的能移

The Energy Shift of 3-body System in the Finite Volume

吴佳俊 (中国科学院大学)

Collaborators: M. Doring, H.-W. Hammer, M. Mai, Ulf
-G. Meißner, J.-Y. Pang, and A. Rusetsky

Phys.Rev. D97 (2018) no.11, 114508

Phys.Rev. D99 (2019) no.07, 074513

第18届全国中高能核物理大会 2019.6.22 湖南师范大学, 长沙, 湖南



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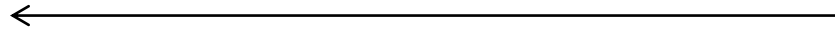
Outline

- Motivation
- 3-body system in the infinite volume
- 3-body quantization condition in the finite volume
- The energy shift in the finite volume
- Summary and Outlook



Motivation

**Experimental
Observations**



QCD theory



Motivation

Experimental
Observations

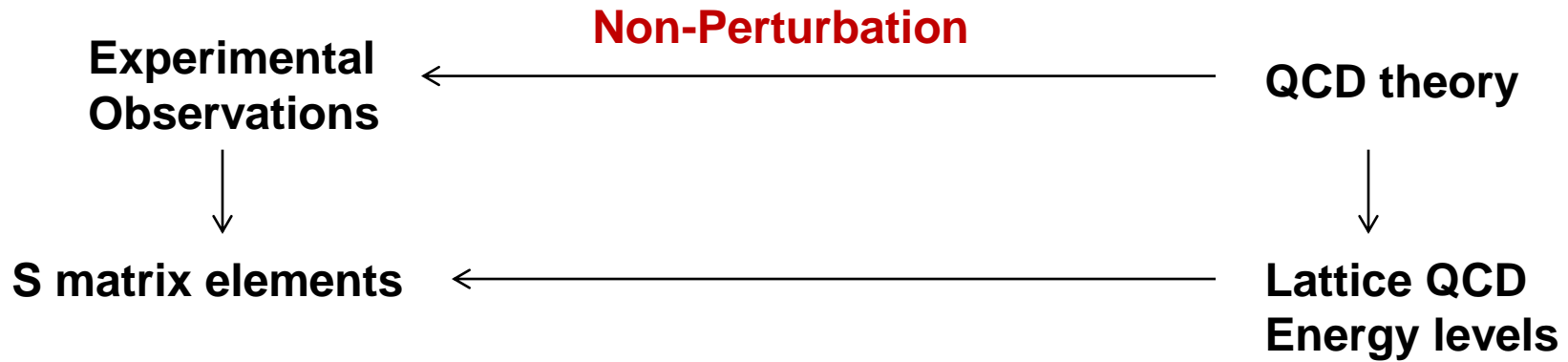
Non-Perturbation



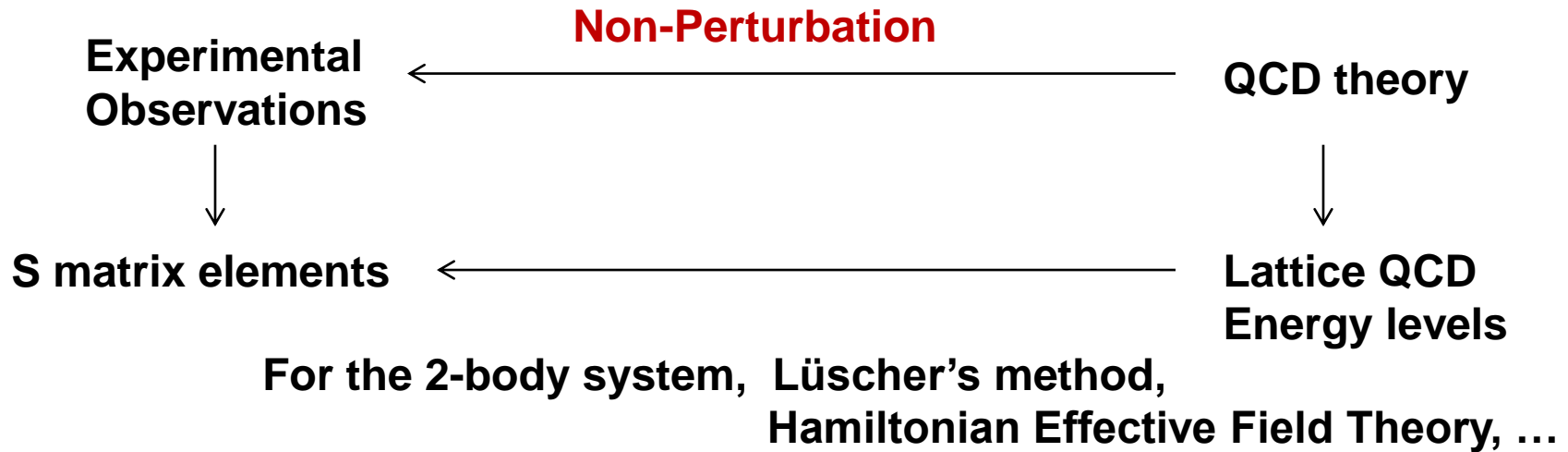
QCD theory



Motivation



Motivation



Motivation

Non-Perturbation

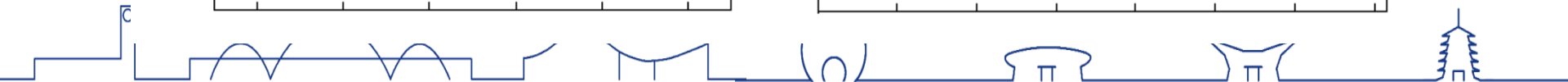
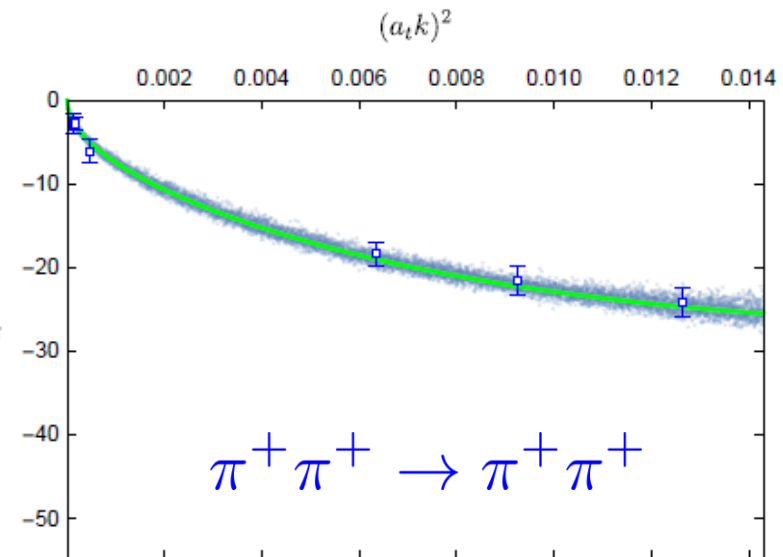
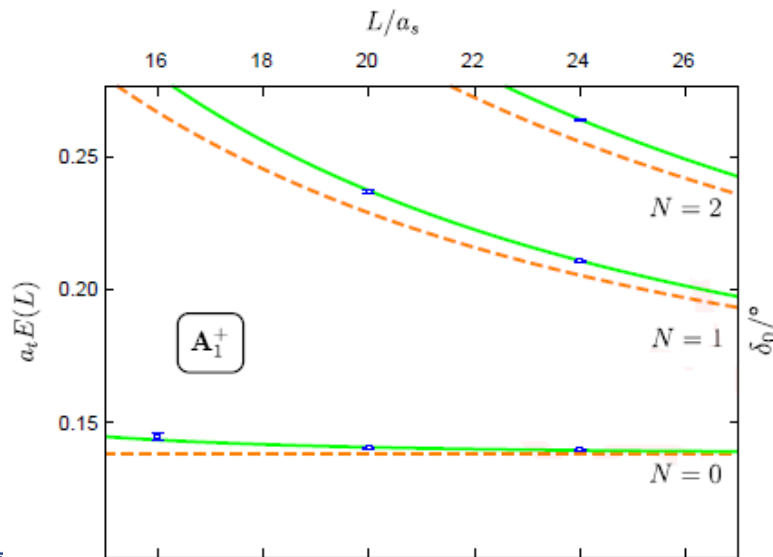
Experimental
Observations

QCD theory

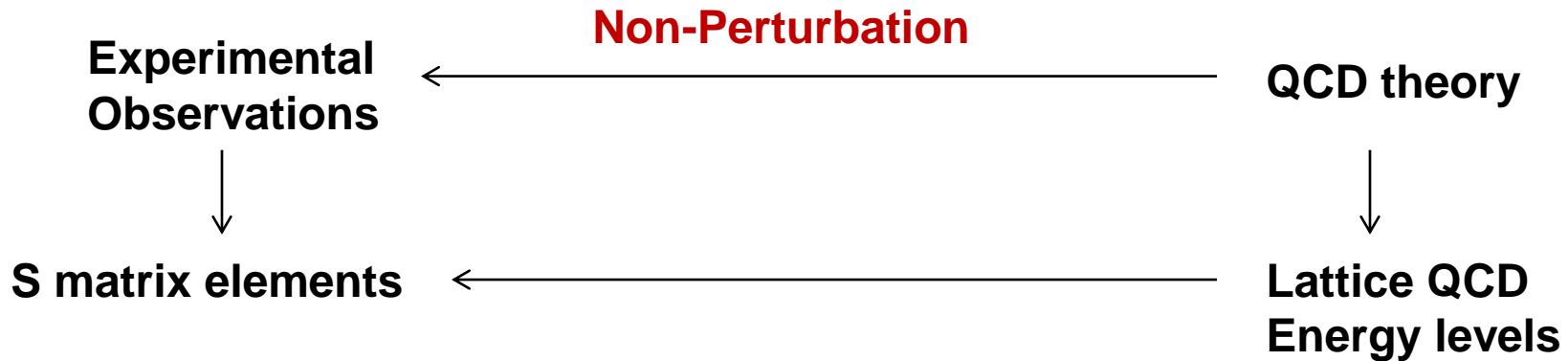
S matrix elements

Lattice QCD
Energy levels

For the 2-body system, Lüscher's method,
Hamiltonian Effective Field Theory, ...



Motivation



For the 3-body system, it becomes very complicated,

1. There are two free momenta
2. How to define the S matrix of three body
3. How to deal with the divergent of three body re-scattering

But the 3-body system is extremely important to describe low energy resonances, such as $\eta \rightarrow 3\pi$, $\omega \rightarrow 3\pi$, $N^*(1440) \rightarrow N\pi\pi$.



Motivation

- History

K. Ploejaeva and A. Rusetsky, EPJA 48(2012) 67 “Three particles in a finite volume”

By S matrix

M. Hansen and S. Sharpe, PRD 90(2014) 116003

Relativistic, model independent, three-particle quantization condition

PRD 92(2015) 114509

Expressing the three-particle finite-volume spectrum in terms of the three-to-three scattering amplitude

Quantization Condition

R. Briceno and Z. Davoudi, PRD 87 (2013) 094507

Three-particle scattering amplitudes from a finite volume formalism

Dimer formalism

Quantization Condition

P. Guo, PRD 95 (2017) 054508

One spatial dimensional finite volume three-body interaction for a short-range potential

**Quantization Condition
In 1+1 dimensional case**

S. Kreuzer and H.-W. Hammer, PLB 694(2011) 424; The triton in a finite volume

EPJA 43(2010) 229; Three-boson bound states in finite volume with EFT

Dimer formalism

S. Kreuzer and H.-W. Griesshammer, PLB 673 (2009) 260 Efimov physics in a finite volume

EPJA 48 (2012) 93 Three-boson bound states in finite volume with Eft

Numerical solution

The quantization condition complicated, not well suited for the analysis of the lattice data.



Motivation

- For the large boxes (small momentum step), the energy spectrum can be calculated, using non-relativistic EFT in a finite volume.

**Infinite Volume
Observations**

**Finite Volume
Spectrum**

Dimer formalism

non-relativistic EFT



3-body System in the infinite volume

- Non-Relativistic Effective Field Theory (NREFT)

$$\mathcal{L} = \mathcal{L}_1 + \mathcal{L}_2 + \mathcal{L}_3$$

$$\mathcal{L}_1 = \psi^\dagger \left(i\partial_0 - \frac{\nabla^2}{2m} \right) \psi$$

$$p \cot \delta_0 = -\frac{1}{a_0} + \frac{r_0}{2} p^2$$

$$p^5 \cot \delta_2 = -\frac{1}{a_2}$$

$$\begin{aligned} \mathcal{L}_2 = & -\frac{C_0}{2} \psi^\dagger \psi^\dagger \psi \psi - \frac{C_2}{4} (\psi^\dagger \nabla^2 \psi^\dagger \psi \psi + h.c.) + \dots \\ & -\frac{C'_2}{4} \left(\vec{\nabla} \psi^\dagger \cdot \vec{\nabla} \psi \vec{\nabla} \psi^\dagger \cdot \vec{\nabla} \psi - 3\psi^\dagger \nabla^2 \psi^\dagger \nabla^2 \psi \psi + h.c. \right) + \dots \end{aligned}$$

$$\begin{aligned} \mathcal{L}_3 = & -\frac{D_0}{6} \psi^\dagger \psi^\dagger \psi^\dagger \psi \psi \psi - \frac{D_2}{12} (\psi^\dagger \psi^\dagger \nabla^2 \psi^\dagger \psi \psi \psi + h.c.) + \dots \\ & -\frac{D'_2}{4} \left(\psi^\dagger \vec{\nabla} \psi^\dagger \cdot \vec{\nabla} \psi \vec{\nabla} \psi^\dagger \cdot \vec{\nabla} \psi \psi - 3\psi^\dagger \psi^\dagger \nabla^2 \psi^\dagger \nabla^2 \psi \psi \psi + h.c. \right) + \dots \end{aligned}$$



3-body System in the infinite volume

S-wave

$$\mathcal{L}_1 = \psi^\dagger \left(i\partial_0 - \frac{\nabla^2}{2m} \right) \psi$$

$$\mathcal{L}_2 = -\frac{C_0}{2} \psi^\dagger \psi^\dagger \psi \psi - \frac{C_2}{4} (\psi^\dagger \nabla^2 \psi^\dagger \psi \psi + h.c.) + \dots$$

$$\mathcal{L}_3 = -\frac{D_0}{6} \psi^\dagger \psi^\dagger \psi^\dagger \psi \psi \psi - \frac{D_2}{12} (\psi^\dagger \psi^\dagger \nabla^2 \psi^\dagger \psi \psi \psi + h.c.) + \dots$$

Dimer picture

(C_0, C_2, D_0, D_2)

$$\mathcal{L}_1 = \psi^\dagger \left(i\partial_0 - \frac{\nabla^2}{2m} \right) \psi$$

$\sim (\sigma, f_1, h_0, h_2)$

$$\mathcal{L}_2 = \sigma T^\dagger T + \frac{1}{2} [T^\dagger (\psi \psi + f_1 \psi \nabla^2 \psi + \dots) + h.c.]$$

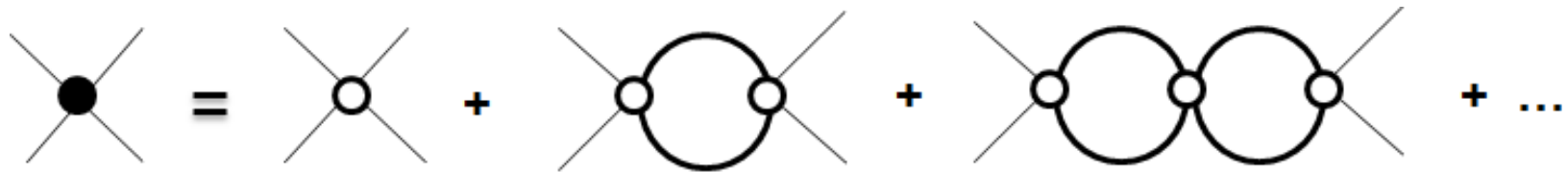
$$\mathcal{L}_3 = h_0 T^\dagger T \psi^\dagger \psi + h_2 T^\dagger T (\psi^\dagger \nabla^2 \psi + h.c.) + \dots$$



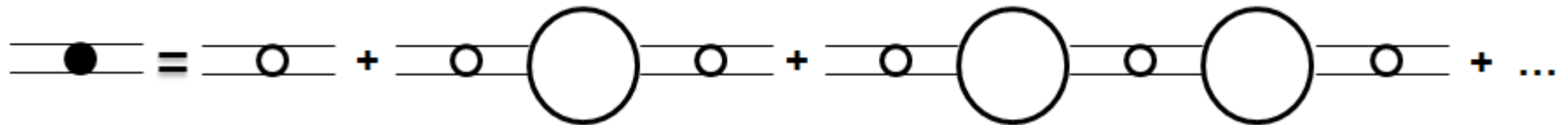
3-body System in the infinite volume

Dimer picture

$$\mathcal{L}_2 = -\frac{C_0}{2}\psi^\dagger\psi^\dagger\psi\psi - \frac{C_2}{4}(\psi^\dagger\nabla^2\psi^\dagger\psi\psi + h.c.) + \dots$$



$$\mathcal{L}_2 = \sigma T^\dagger T + [T^\dagger (\psi\psi + f_1\psi\nabla\psi + \dots) + h.c.]$$

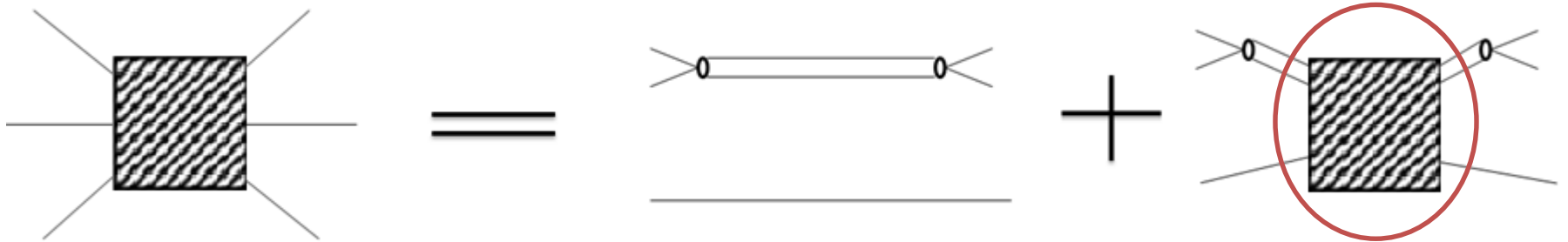


$$\tau(\vec{k}, E) = \frac{1}{k^* \cot \delta_0(k^*) + ik^*}$$



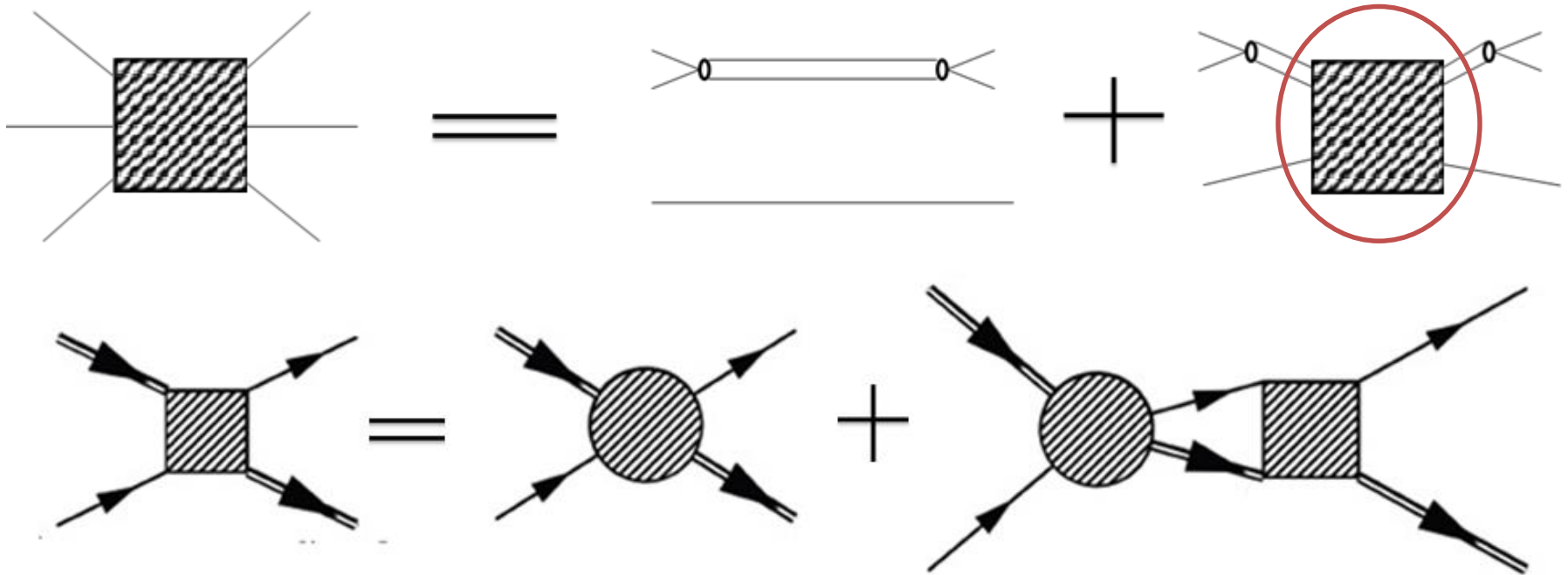
3-body System in the infinite volume

Dimer Particle scattering VS 3 Particles scattering



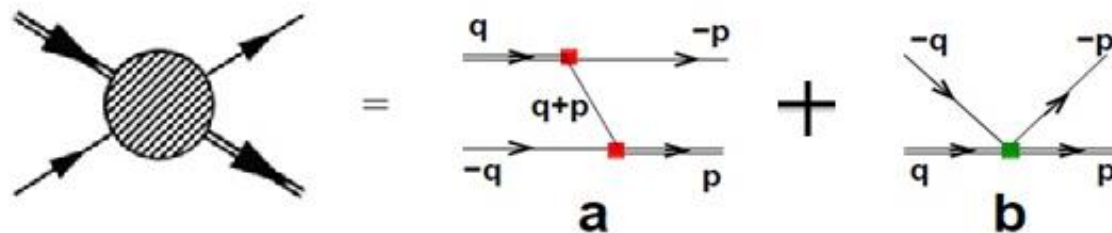
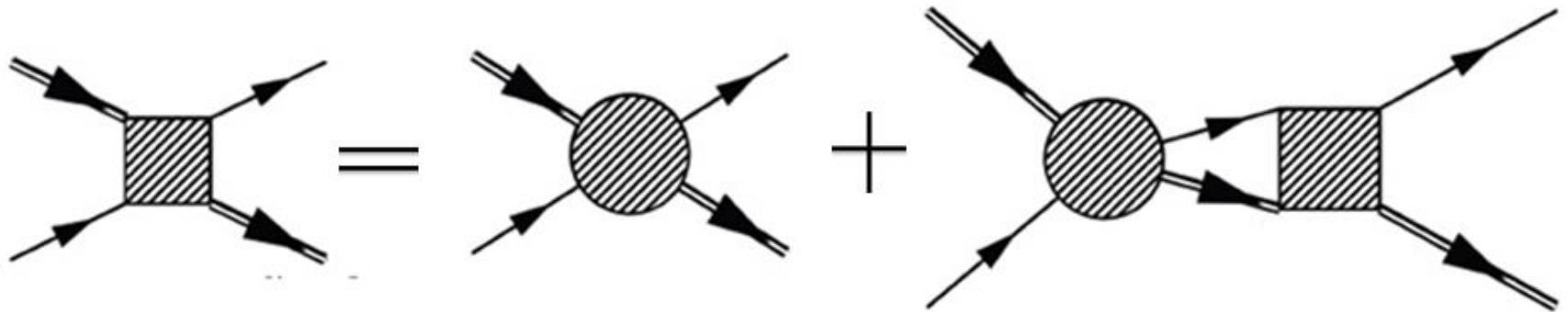
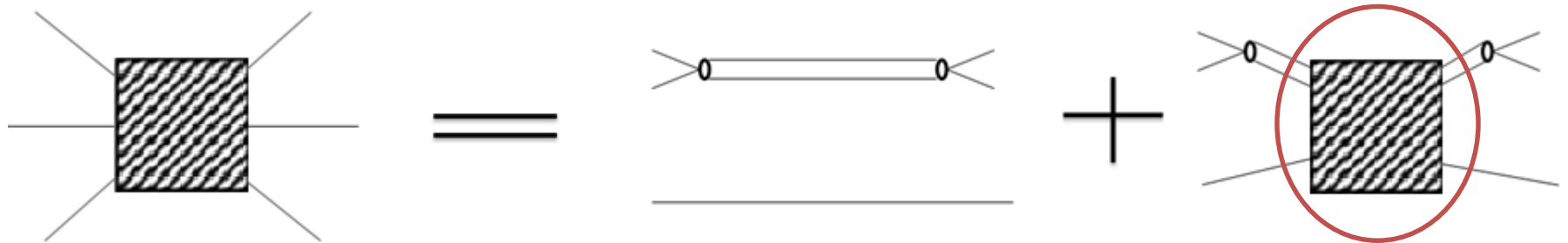
3-body System in the infinite volume

Dimer Particle scattering VS 3 Particles scattering



3-body System in the infinite volume

Dimer Particle scattering VS 3 Particles scattering



A toy Model

S-wave & O(p) & Non-Relativistic

$$\mathcal{L}_1 = \psi^\dagger \left(i\partial_0 - \frac{\nabla^2}{2m} \right) \psi \quad \mathcal{L}_2 = \sigma T^\dagger T + [T^\dagger \psi \psi + h.c.] \quad \mathcal{L}_3 = h_0 T^\dagger T \psi^\dagger \psi$$



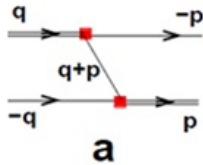
A toy Model

S-wave & O(p) & Non-Relativistic

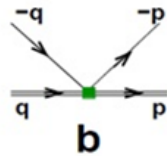
$$\mathcal{L}_1 = \psi^\dagger \left(i\partial_0 - \frac{\nabla^2}{2m} \right) \psi \quad \mathcal{L}_2 = \sigma T^\dagger T + [T^\dagger \psi \psi + h.c.] \quad \mathcal{L}_3 = h_0 T^\dagger T \psi^\dagger \psi$$

Scattering equation

$$\mathcal{M}(\vec{p}, \vec{q}, E) = Z(\vec{p}, \vec{q}, E) + 8\pi \int_0^\Lambda \frac{d^3 \vec{k}}{8\pi^3} Z(\vec{p}, \vec{k}, E) \tau(\vec{k}, E) \mathcal{M}(\vec{k}, \vec{q}, E)$$



+



$$\tau(\vec{k}, E) = \frac{1}{-\frac{1}{a_0} + \sqrt{\frac{3}{4}k^2 - mE}}$$



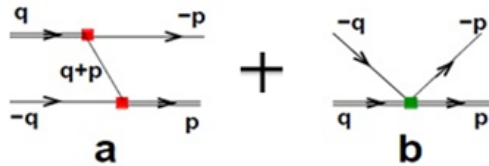
A toy Model

S-wave & O(p) & Non-Relativistic

$$\mathcal{L}_1 = \psi^\dagger \left(i\partial_0 - \frac{\nabla^2}{2m} \right) \psi \quad \mathcal{L}_2 = \sigma T^\dagger T + [T^\dagger \psi \psi + h.c.] \quad \mathcal{L}_3 = h_0 T^\dagger T \psi^\dagger \psi$$

Scattering equation

$$\mathcal{M}(\vec{p}, \vec{q}, E) = Z(\vec{p}, \vec{q}, E) + 8\pi \int_0^\Lambda \frac{d^3 \vec{k}}{8\pi^3} Z(\vec{p}, \vec{k}, E) \tau(\vec{k}, E) \mathcal{M}(\vec{k}, \vec{q}, E)$$



$$\tau(\vec{k}, E) = \frac{1}{-\frac{1}{a_0} + \sqrt{\frac{3}{4}k^2 - mE}}$$

Physical Input

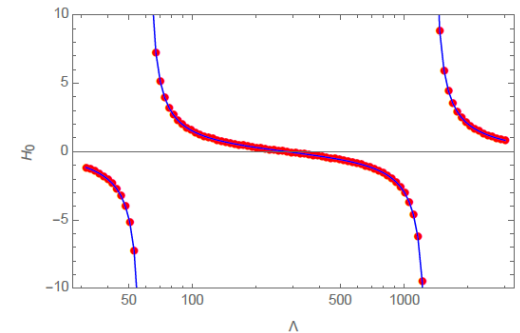
$$a_0 = m = 1$$

$$B_3(3p) = 10$$



$H_0(\Lambda)$ vs Λ

$$\mathcal{F}(\vec{p}, B_3) = \int_0^\Lambda d^3 \vec{k} Z(\vec{p}, \vec{k}, B_3) \tau(\vec{k}, B_3) \mathcal{F}(\vec{k}, B_3)$$



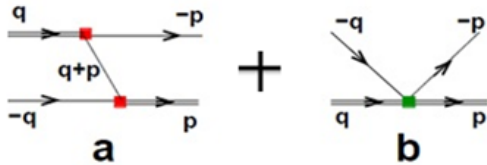
A toy Model

S-wave & O(p) & Non-Relativistic

$$\mathcal{L}_1 = \psi^\dagger \left(i\partial_0 - \frac{\nabla^2}{2m} \right) \psi \quad \mathcal{L}_2 = \sigma T^\dagger T + [T^\dagger \psi \psi + h.c.] \quad \mathcal{L}_3 = h_0 T^\dagger T \psi^\dagger \psi$$

Scattering equation

$$\mathcal{M}(\vec{p}, \vec{q}, E) = Z(\vec{p}, \vec{q}, E) + 8\pi \int_0^\Lambda \frac{d^3 \vec{k}}{8\pi^3} Z(\vec{p}, \vec{k}, E) \tau(\vec{k}, E) \mathcal{M}(\vec{k}, \vec{q}, E)$$



$$\tau(\vec{k}, E) = \frac{1}{-\frac{1}{a_0} + \sqrt{\frac{3}{4}k^2 - mE}}$$

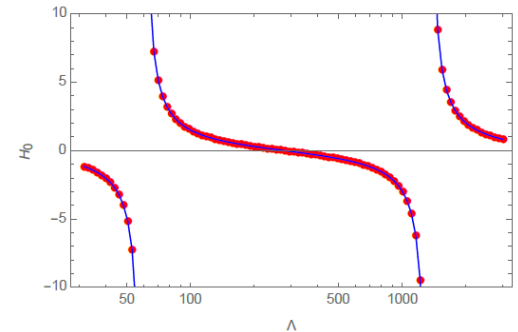
Physical Input

$$a_0 = m = 1$$

$$B_3(3p) = 10$$



$H_0(\Lambda)$ vs Λ



$\mathcal{M}(\vec{p}, \vec{q}, E)$ is Λ independent



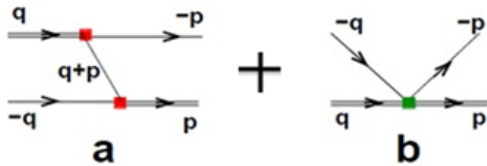
A toy Model

S-wave & O(p) & Non-Relativistic

$$\mathcal{L}_1 = \psi^\dagger \left(i\partial_0 - \frac{\nabla^2}{2m} \right) \psi \quad \mathcal{L}_2 = \sigma T^\dagger T + [T^\dagger \psi \psi + h.c.] \quad \mathcal{L}_3 = h_0 T^\dagger T \psi^\dagger \psi$$

Scattering equation

$$\mathcal{M}(\vec{p}, \vec{q}, E) = Z(\vec{p}, \vec{q}, E) + 8\pi \int_0^\Lambda \frac{d^3 \vec{k}}{8\pi^3} Z(\vec{p}, \vec{k}, E) \tau(\vec{k}, E) \mathcal{M}(\vec{k}, \vec{q}, E)$$



$$\tau(\vec{k}, E) = \frac{1}{-\frac{1}{a_0} + \sqrt{\frac{3}{4}k^2 - mE}}$$

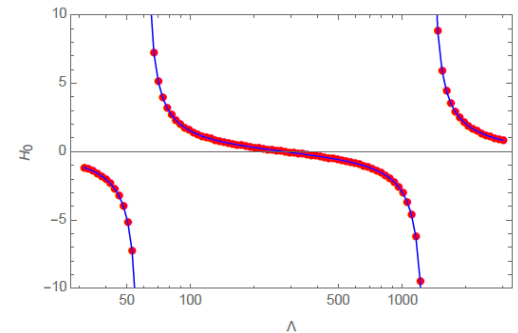
Physical Input

$$a_0 = m = 1$$

$$B_3(3p) = 10$$



$H_0(\Lambda)$ vs Λ



$\mathcal{M}(\vec{p}, \vec{q}, E)$ is Λ independent

P.F. Bedaque, H.-W. Hammer, and U. van Kolck NPA 646 444 (1999)

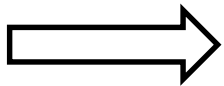
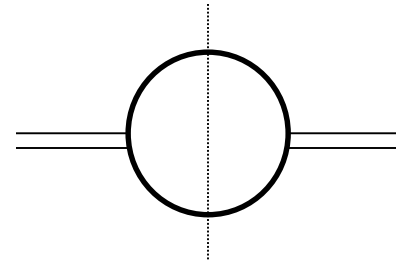
The three-boson system with short-range interactions



3-body System in the finite volume

- Infinite Volume \rightarrow Box
- Momentum space,
continuum \rightarrow discrete $(2\pi/L) \vec{n}$, $\vec{n} = (n_1, n_2, n_3)$
- Propagator of dimer,

$$\tau(\vec{k}, E) = \frac{1}{-\frac{1}{a_0} + \sqrt{\frac{3}{4}k^2 - mE}}$$



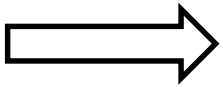
$$\tau_L(\vec{m}, E) = \frac{1}{-\frac{1}{a_0} - \frac{4\pi}{L^3} \sum_{\vec{l}} \frac{1}{\frac{4\pi^2}{L^2} (m^2 + l^2 + \vec{k} \cdot \vec{l}) - mE}}$$



3-body System in the finite volume

- Scattering equation,

$$\mathcal{M}(\vec{p}, \vec{q}, E) = Z(\vec{p}, \vec{q}, E) + 8\pi \int_0^\Lambda \frac{d^3 \vec{k}}{8\pi^3} Z(\vec{p}, \vec{k}, E) \tau(\vec{k}, E) \mathcal{M}(\vec{k}, \vec{q}, E)$$



$$\mathcal{M}\left(\frac{2\pi}{L}\vec{m}, \frac{2\pi}{L}\vec{n}, E\right) = Z\left(\frac{2\pi}{L}\vec{m}, \frac{2\pi}{L}\vec{n}, E\right) + \frac{8\pi}{L^3} \sum_{\vec{l} \in \mathbb{Z}^3}^{\frac{L\Lambda}{2\pi}} Z\left(\frac{2\pi}{L}\vec{m}, \frac{2\pi}{L}\vec{l}, E\right) \tau_L(\vec{l}, E) \mathcal{M}\left(\frac{2\pi}{L}\vec{l}, \frac{2\pi}{L}\vec{n}, E\right)$$

$$\mathcal{M}_L(\vec{m}, \vec{n}, E) = Z_L(\vec{m}, \vec{n}, E) + \frac{8\pi}{L^3} \sum_{\vec{l} \in \mathbb{Z}^3}^{\frac{L\Lambda}{2\pi}} Z_L(\vec{m}, \vec{l}, E) \tau_L(\vec{l}, E) \mathcal{M}_L(\vec{l}, \vec{n}, E)$$

- Quantization condition:

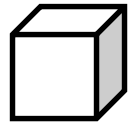
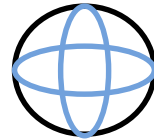
$$\det(\tau_L^{-1} - \frac{8\pi}{L^3} Z_L) = 0$$



3-body System in the finite volume

Symmetry

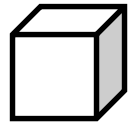
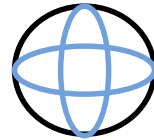
- Infinite Volume \rightarrow $SO(3)$ group
- Box Volume \rightarrow O_h group



3-body System in the finite volume

Symmetry

- Infinite Volume \rightarrow $SO(3)$ group
- Box Volume \rightarrow O_h group



Infinite Volume, $\mathcal{M}(\vec{p}, \vec{q}, E) = \mathcal{M}(\hat{R}\vec{p}, \hat{R}\vec{q}, E)$

In the finite Volume, $\hat{R}_{O_h} \in O_h$,

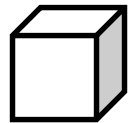
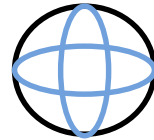
$$\mathcal{M}_L(\vec{n}, \vec{m}, E) = \mathcal{M}_L(\hat{R}_{O_h}\vec{n}, \hat{R}_{O_h}\vec{m}, E)$$



3-body System in the finite volume

Symmetry

- Infinite Volume \rightarrow $SO(3)$ group
- Box Volume \rightarrow O_h group

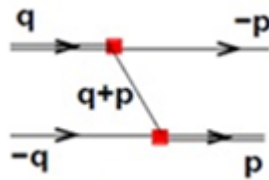


Infinite Volume, $\mathcal{M}(\vec{p}, \vec{q}, E) = \mathcal{M}(\hat{R}\vec{p}, \hat{R}\vec{q}, E)$

In the finite Volume, $\hat{R}_{O_h} \in O_h$,

$$\mathcal{M}_L(\vec{n}, \vec{m}, E) = \mathcal{M}_L(\hat{R}_{O_h}\vec{n}, \hat{R}_{O_h}\vec{m}, E)$$

$$\begin{aligned} 0^+ &= \mathbf{A}_1^+, \\ 1^- &= \mathbf{T}_1^-, \\ 2^+ &= \mathbf{E}^+ \oplus \mathbf{T}_2^+, \\ 3^- &= \mathbf{A}_2^- \oplus \mathbf{T}_1^- \oplus \mathbf{T}_2^-, \\ 4^+ &= \mathbf{A}_1^+ \oplus \mathbf{E}^+ \oplus \mathbf{T}_1^+ \oplus \mathbf{T}_2^+, \end{aligned}$$



$$\det(\tau_L^{-1} - \frac{8\pi}{L^3} Z_L) = 0$$



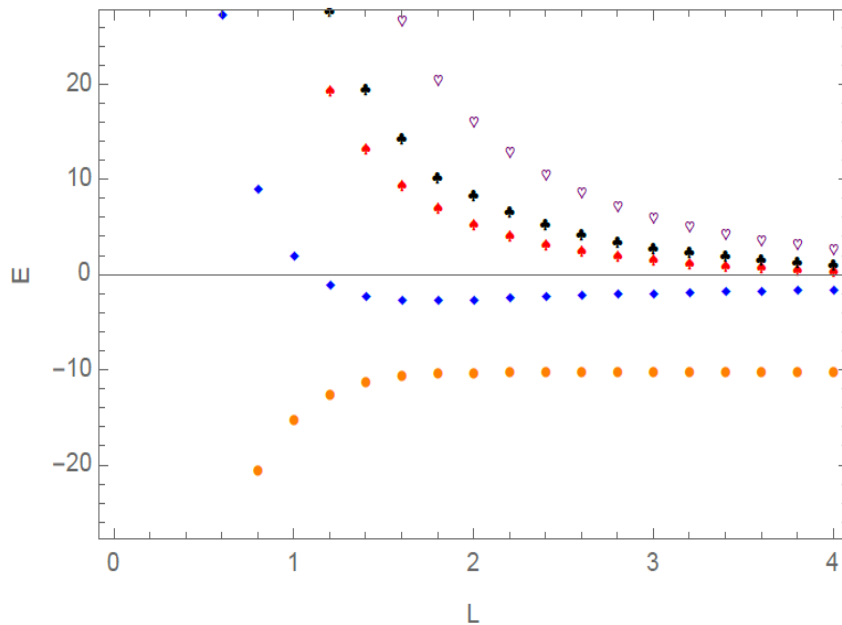
$$\det \left(\theta^{-1}(s) \tau_L^{-1}(r, E) \delta_{rs} - \frac{8\pi}{L^3} \frac{1}{G} Z_L^{A_1^+}(r, s, E) \right) = 0$$



3-body System in the finite volume

- Results of Toy model and discussion

$$\det \left(\theta^{-1}(s) \tau_L^{-1}(r, E) \delta_{rs} - \frac{8\pi}{L^3} \frac{1}{G} Z_L^{A_1^+}(r, s, E) \right) = 0$$



Purple: excited state of dimer-particle

Black: ground state of three particle

Red: ground state of dimer-particle scattering state

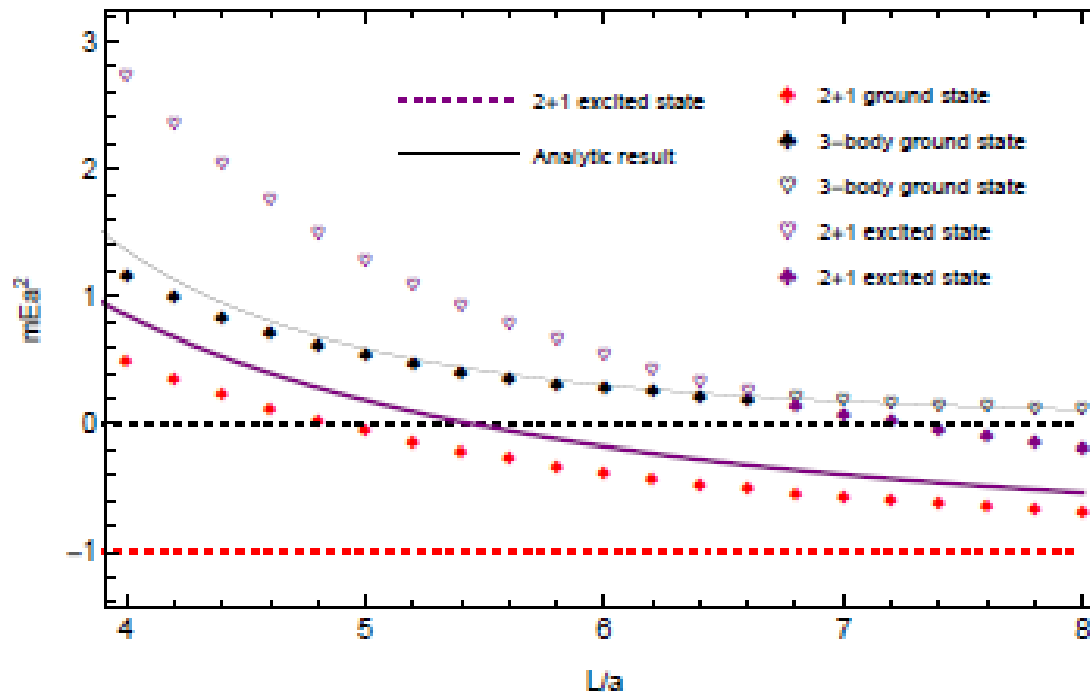
Blue: dimer – particle bound state

Orange: three body bound state



3-body System in the finite volume

- A interesting crossing between black and purple lines at larger size.



Purple: excite state of dimer-particle

Black: ground state of three particle

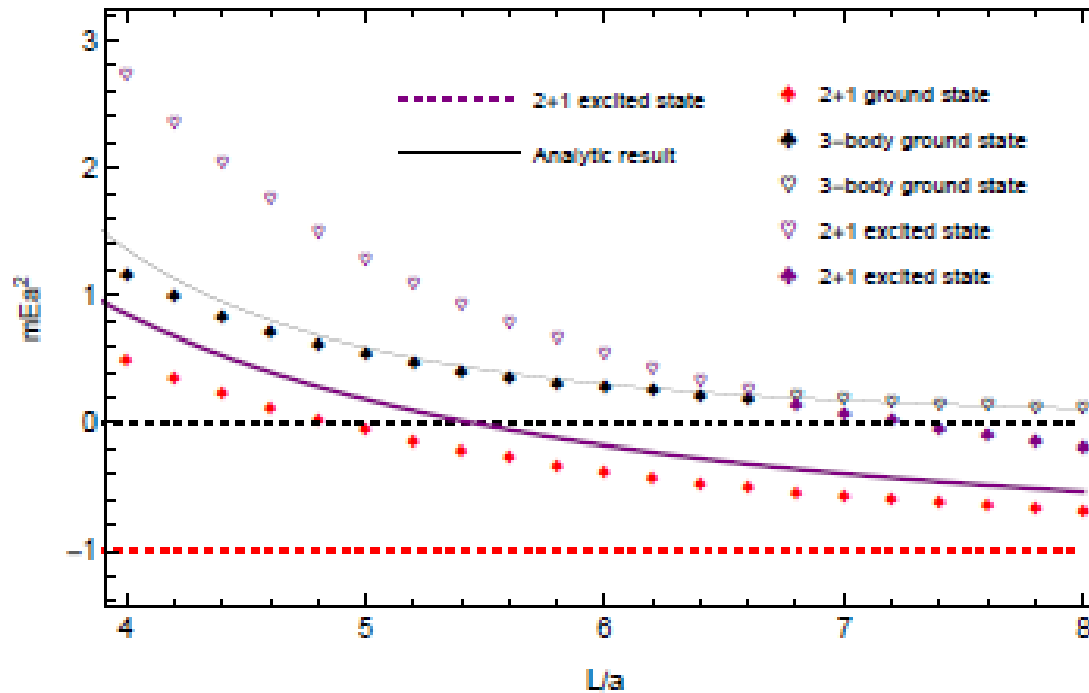
Red: ground state of dimer-particle scattering state

$$\Delta E = c_1 \frac{a}{L^3} + c_2 \frac{a^2}{L^4} + c_3 \frac{a^3}{L^5} + \mathcal{O}(L^{-6})$$

c_1, c_2, c_3 are all fixed parameters as shown later.



Energy shifts in the finite volume



In this section, we will discuss this thin line and try to give the **analytical expression** of this line up to $O(L^{-6})$.

$$\Delta E = c_1 \frac{a}{L^3} + c_2 \frac{a^2}{L^4} + c_3 \frac{a^3}{L^5} + c_4 \frac{a^4}{L^6} + \mathcal{O}(L^{-7})$$



Energy shifts in the finite volume

- Previous work :

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Testing the threshold expansion for three-particle energies
at fourth order in ϕ^4 theory

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$$N_{\text{cut}} = mL/(2\pi), \quad c_L = 16\pi^3(\sqrt{3} - 4\pi/3)$$

$$\begin{aligned} \Delta E_{3,\text{thr}} = & \frac{12\pi a}{mL^3} \left\{ 1 - \left(\frac{a}{\pi L} \right) \mathcal{I} + \left(\frac{a}{\pi L} \right)^2 (\mathcal{I}^2 + \mathcal{J}) \right. \\ & + \frac{64\pi^2 a^2 \mathcal{C}_3}{mL^3} + \frac{3\pi a}{m^2 L^3} + \frac{6\pi r a^2}{L^3} \\ & + \left(\frac{a}{\pi L} \right)^3 [-\mathcal{I}^3 + \mathcal{I}\mathcal{J} + 15\mathcal{K} + c_L \log(N_{\text{cut}}) \\ & \left. + \mathcal{C}_F + \mathcal{C}_4 + \mathcal{C}_5] \right\} - \frac{\mathcal{M}_{3,\text{thr}}}{48m^3 L^6} + \mathcal{O}(L^{-7}), \quad (16) \end{aligned}$$

and evaluated in Ref. [8]. The new amplitude entering at $\mathcal{O}(1/L^6)$ is the divergence-free three-to-three threshold amplitude $\mathcal{M}_{3,\text{thr}}$, which begins at $\mathcal{O}(\lambda^2)$ in perturbation theory. The numerical values of \mathcal{C}_3 , \mathcal{C}_4 , and \mathcal{C}_5 depend on the choice of UV cutoff, but this dependence cancels with that of $\mathcal{M}_{3,\text{thr}}$. This cancellation is necessary because $\Delta E_{3,\text{thr}}$ is a physical quantity.



Ground State of three body scattering, i.e., $0 < mE < L^{-2}$

$$\det \left(\theta^{-1}(s) \tau_L^{-1}(r, E) \delta_{rs} - \frac{8\pi}{L^3} \frac{1}{G} Z_L^{A_1^+}(r, s, E) \right) = 0$$

Analytical Method



$$mE = \left(\frac{2\pi}{L} \right)^2 \left(\frac{x_1}{L/a} + \frac{x_2}{(L/a)^2} + \frac{x_3}{(L/a)^3} + \frac{x_4}{(L/a)^4} \right)$$



Ground State of three body scattering, i.e., $0 < mE < L^{-2}$

$$\det \left(1 - \tilde{Z}_L(r, s) \tilde{\tau}(s) \right) = 0 \quad \left| \begin{array}{cccc} 1 - \tilde{Z}(1, 1) \tilde{\tau}(1) & -\tilde{Z}(1, 2) \tilde{\tau}(2) & \cdots & -\tilde{Z}(1, N) \tilde{\tau}(N) \\ -\tilde{Z}(2, 1) \tilde{\tau}(1) & 1 - \tilde{Z}(2, 2) \tilde{\tau}(2) & \cdots & -\tilde{Z}(2, N) \tilde{\tau}(N) \\ \vdots & \vdots & \ddots & \vdots \\ -\tilde{Z}(N, 1) \tilde{\tau}(1) & -\tilde{Z}(N, 2) \tilde{\tau}(2) & \cdots & 1 - \tilde{Z}(N, N) \tilde{\tau}(N) \end{array} \right| = 0$$

Analytical Method



$$mE = \left(\frac{2\pi}{L}\right)^2 \left(\frac{x_1}{L/a} + \frac{x_2}{(L/a)^2} + \frac{x_3}{(L/a)^3} + \frac{x_4}{(L/a)^4}\right)$$



Ground State of three body scattering, i.e., $0 < mE < L^{-2}$

$$\det \left(1 - \tilde{Z}_L(r, s) \tilde{\tau}(s) \right) = 0 \quad \left| \begin{array}{cccc} 1 - \tilde{Z}(1, 1) \tilde{\tau}(1) & -\tilde{Z}(1, 2) \tilde{\tau}(2) & \cdots & -\tilde{Z}(1, N) \tilde{\tau}(N) \\ -\tilde{Z}(2, 1) \tilde{\tau}(1) & 1 - \tilde{Z}(2, 2) \tilde{\tau}(2) & \cdots & -\tilde{Z}(2, N) \tilde{\tau}(N) \\ \vdots & \vdots & \ddots & \vdots \\ -\tilde{Z}(N, 1) \tilde{\tau}(1) & -\tilde{Z}(N, 2) \tilde{\tau}(2) & \cdots & 1 - \tilde{Z}(N, N) \tilde{\tau}(N) \end{array} \right| = 0$$

Analytical Method

Perturbative analysis of each elements of matrix for “L” is unavailable

$$N \propto \frac{L\Lambda}{2\pi}$$

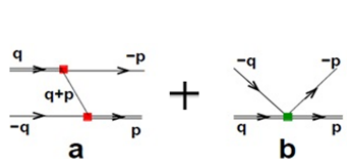
$$mE = \left(\frac{2\pi}{L}\right)^2 \left(\frac{x_1}{L/a} + \frac{x_2}{(L/a)^2} + \frac{x_3}{(L/a)^3} + \frac{x_4}{(L/a)^4}\right)$$



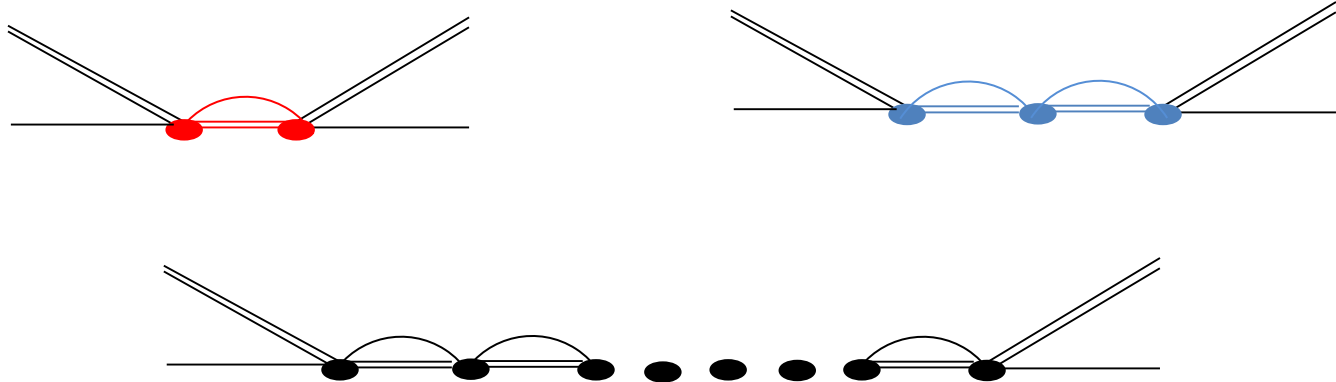
$$\begin{vmatrix}
 1 - \tilde{Z}(1,1)\tilde{\tau}(1) & -\tilde{Z}(1,2)\tilde{\tau}(2) & \cdots & -\tilde{Z}(1,N)\tilde{\tau}(N) \\
 -\tilde{Z}(2,1)\tilde{\tau}(1) & 1 - \tilde{Z}(2,2)\tilde{\tau}(2) & \cdots & -\tilde{Z}(2,N)\tilde{\tau}(N) \\
 \vdots & \vdots & \ddots & \vdots \\
 -\tilde{Z}(N,1)\tilde{\tau}(1) & -\tilde{Z}(N,2)\tilde{\tau}(2) & \cdots & 1 - \tilde{Z}(N,N)\tilde{\tau}(N)
 \end{vmatrix} = 0$$

$$\begin{aligned}
 &= 1 - \frac{3a_0}{\pi x_1} + \mathcal{O}(L^{-1}) \\
 &\implies x_1 = \frac{3a_0}{\pi}
 \end{aligned}$$

$$\tilde{\tau}^{-1}(1) - \tilde{Z}(1,1) = \sum_{j_1 \neq 1} \tilde{Z}(1, j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1, 1) + \sum_{j_1, j_2 \neq 1} \tilde{Z}(1, j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1, j_2) \tilde{\tau}(j_2) \tilde{Z}(j_2, 1)$$



$$+ \sum_{j_1, j_2, j_3 \neq 1} \tilde{Z}(1, j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1, j_2) \tilde{\tau}(j_2) \tilde{Z}(j_2, j_3) \tilde{\tau}(j_3) \tilde{Z}(j_3, 1) + \cdots$$



$$x_1 = \frac{3a_0}{\pi} \implies mE = \frac{12\pi a}{L^3} \left(1 + \frac{x_1}{L/a} + \frac{x_2}{(L/a)^2} + \frac{x'_3 Log[L/a]}{(L/a)^3} + \frac{x_3}{(L/a)^3} \right)$$


$$\begin{aligned} \tilde{\tau}^{-1}(1) - \tilde{Z}(1,1) = & \sum_{j_1 \neq 1} \tilde{Z}(1,j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1,1) + \sum_{j_1,j_2 \neq 1} \tilde{Z}(1,j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1,j_2) \tilde{\tau}(j_2) \tilde{Z}(j_2,1) \\ & + \sum_{j_1,j_2,j_3 \neq 1} \tilde{Z}(1,j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1,j_2) \tilde{\tau}(j_2) \tilde{Z}(j_2,j_3) \tilde{\tau}(j_3) \tilde{Z}(j_3,1) + \cdots \end{aligned}$$



$$x_1 = \frac{3a_0}{\pi} \implies mE = \frac{12\pi a}{L^3} \left(1 + \frac{x_1}{L/a} + \frac{x_2}{(L/a)^2} + \frac{x'_3 \text{Log}[L/a]}{(L/a)^3} + \frac{x_3}{(L/a)^3} \right)$$

$$\begin{aligned} \tilde{\tau}^{-1}(1) - \tilde{Z}(1, 1) &= \sum_{j_1 \neq 1} \tilde{Z}(1, j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1, 1) + \sum_{j_1, j_2 \neq 1} \tilde{Z}(1, j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1, j_2) \tilde{\tau}(j_2) \tilde{Z}(j_2, 1) \\ &\quad + \sum_{j_1, j_2, j_3 \neq 1} \tilde{Z}(1, j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1, j_2) \tilde{\tau}(j_2) \tilde{Z}(j_2, j_3) \tilde{\tau}(j_3) \tilde{Z}(j_3, 1) + \cdots \end{aligned}$$

$$\begin{aligned} \tilde{\tau}^{-1}(1) - \tilde{Z}(1, 1) &= \frac{1}{L/a} \left(-x_1 - \frac{\mathbb{I}(\vec{0})}{\pi} \right) + \frac{1}{(L/a)^2} \left(-x_2 + x_1^2 - \frac{3\mathbb{J}(\vec{0})}{\pi^2} \right) + \frac{-x'_3 \log[L/a]}{(L/a)^3} \\ &\quad + \frac{1}{(L/a)^3} \left(-x_3 + 2x_1x_2 - x_1^3 + \frac{6\pi r}{a} - \frac{1}{\pi^3} \left(3x_1\pi\mathbb{J}(\vec{0}) + 9\mathbb{K}(\vec{0}) \right) \right) - \frac{1}{(L/a)^3} \left(\frac{8\pi H_0(\Lambda)}{a^2\Lambda^2} \right) + \mathcal{O}(L^{-3-\epsilon}) \\ &= -\frac{4\mathbb{J}(\vec{0})}{(\pi L/a)^2} - \frac{16\sqrt{3}\log(L/a)}{(L/a)^3} + \frac{1}{(\pi L/a)^3} (X_0(\Lambda) + C_2 - 24\mathbb{K}(0)) + \mathcal{O}(L^{-3-\epsilon}) \end{aligned}$$



$$= \frac{64\pi \log(L/a)}{3(L/a)^3} + \frac{1}{(\pi L/a)^3} X_1(\Lambda) + \mathcal{O}(L^{-3-\epsilon})$$

$$= X_2(\Lambda) \frac{1}{(\pi L/a)^3} + \mathcal{O}(L^{-3-\epsilon})$$



$$x_1 = \frac{3a_0}{\pi} \implies mE = \frac{12\pi a}{L^3} \left(1 + \frac{x_1}{L/a} + \frac{x_2}{(L/a)^2} + \frac{x'_3 \text{Log}[L/a]}{(L/a)^3} + \frac{x_3}{(L/a)^3} \right)$$

$$\begin{aligned} \tilde{\tau}^{-1}(1)-\tilde{Z}(1,1) &= \sum_{j_1 \neq 1} \tilde{Z}(1,j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1,1) + \sum_{j_1,j_2 \neq 1} \tilde{Z}(1,j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1,j_2) \tilde{\tau}(j_2) \tilde{Z}(j_2,1) \\ &\quad + \sum_{j_1,j_2,j_3 \neq 1} \tilde{Z}(1,j_1) \tilde{\tau}(j_1) \tilde{Z}(j_1,j_2) \tilde{\tau}(j_2) \tilde{Z}(j_2,j_3) \tilde{\tau}(j_3) \tilde{Z}(j_3,1) + \cdots \end{aligned}$$

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$$\begin{aligned} \dots &= -\frac{4\mathbb{J}(\vec{0})}{(\pi L/a)^2} - \frac{16\sqrt{3}\log(L/a)}{(L/a)^3} + \frac{1}{(\pi L/a)^3} (X_0(\Lambda) + C_2 - 24\mathbb{K}(0)) + \mathcal{O}(L^{-3-\epsilon}) \end{aligned}$$

$$\begin{aligned} \dots &= \frac{64\pi \log(L/a)}{3(L/a)^3} + \frac{1}{(\pi L/a)^3} X_1(\Lambda) + \mathcal{O}(L^{-3-\epsilon}) \end{aligned}$$

$$\begin{aligned} \dots &= X_2(\Lambda) \frac{1}{(\pi L/a)^3} + \mathcal{O}(L^{-3-\epsilon}) \end{aligned}$$

Non-perturbation

Energy shift of Ground state of 3-body scattering state

$$mE = \frac{12\pi a}{L^3} \left(1 + \frac{x_1}{L/a} + \frac{x_2}{(L/a)^2} + \frac{x'_3 \log[L/a]}{(L/a)^3} + \frac{x_3}{(L/a)^3} + \dots \right)$$

$$x_3 = \mathbf{Q} X(\Lambda) + \mathbf{R}$$

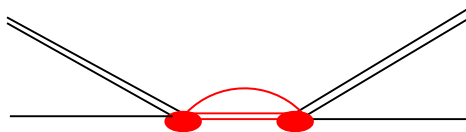
Cutoff Dependence

$$X(\Lambda) = \frac{H_0(\Lambda)}{\Lambda^2} + \sum_{\vec{i} \in \mathbb{Z}^3}^{[1,N]} \frac{8\pi}{L^3} z(\vec{0}, \vec{i}, 0) \tau(\vec{i}, 0) M^L(\vec{i}, \vec{0}),$$

$$M^L(\vec{j}, \vec{0}) = z(\vec{j}, \vec{0}, 0) + \sum_{\vec{i} \in \mathbb{Z}^3}^{[1,N]} \frac{8\pi}{L^3} z(\vec{j}, \vec{i}, 0) \tau(\vec{i}, 0) M^L(\vec{i}, \vec{0}).$$

$$z(\vec{i}, \vec{j}, n) = \frac{L^2}{4\pi^2} \frac{1}{\vec{i}^2 + \vec{j}^2 + \vec{i} \cdot \vec{j} - n} + \frac{H_0}{\Lambda^2}$$

$$\tau(\vec{i}, n) = -\frac{1}{a} + \frac{\pi}{L} \sqrt{3\vec{i}^2 - 4n}$$

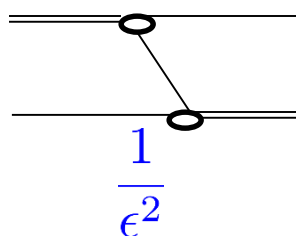


X_3 : Λ independence

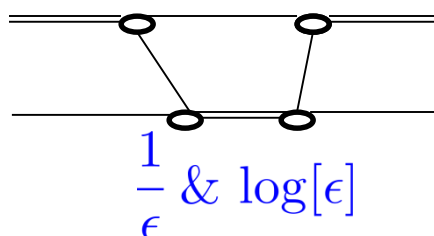
$$X(\Lambda) = \frac{H_0(\Lambda)}{\Lambda^2} + \sum_{\vec{i} \in \mathbb{Z}^3}^{[1,N]} \frac{8\pi}{L^3} z(\vec{0}, \vec{i}, 0) \tau(\vec{i}, 0) M^L(\vec{i}, \vec{0}), \quad \sim M(\vec{0}, \vec{0}, 0)$$

$$M^L(\vec{j}, \vec{0}) = z(\vec{j}, \vec{0}, 0) + \sum_{\vec{i} \in \mathbb{Z}^3}^{[1,N]} \frac{8\pi}{L^3} z(\vec{j}, \vec{i}, 0) \tau(\vec{i}, 0) M^L(\vec{i}, \vec{0}).$$

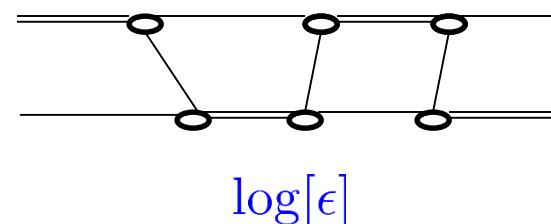
Divergent From



Tree Diagram



One loop Diagram,



Two loops Diagram.

$$\mathcal{A}_b = \lim_{\epsilon \rightarrow 0^+} \left(M_\epsilon(\vec{0}, \vec{0}, 0) + \frac{4a}{\pi\epsilon} + \left(\frac{8}{3} - \frac{2\sqrt{3}}{\pi} \right) a^2 \log \left(\frac{a\epsilon}{2\pi} \right) \right) - a^2 \frac{112\zeta(3)}{9}$$

$$M_\epsilon(\vec{0}, \vec{0}, 0) \equiv \frac{H_0(\Lambda)}{\Lambda^2} + 8\pi \int_\epsilon^\Lambda \frac{d^3 \vec{k}}{(2\pi)^3} Z(\vec{0}, \vec{k}, 0) \tau(\vec{k}, 0) M(\vec{k}, \vec{0}, 0)$$

$$X(\Lambda) = \mathbf{Q}' \mathcal{A} + \mathbf{R}'$$



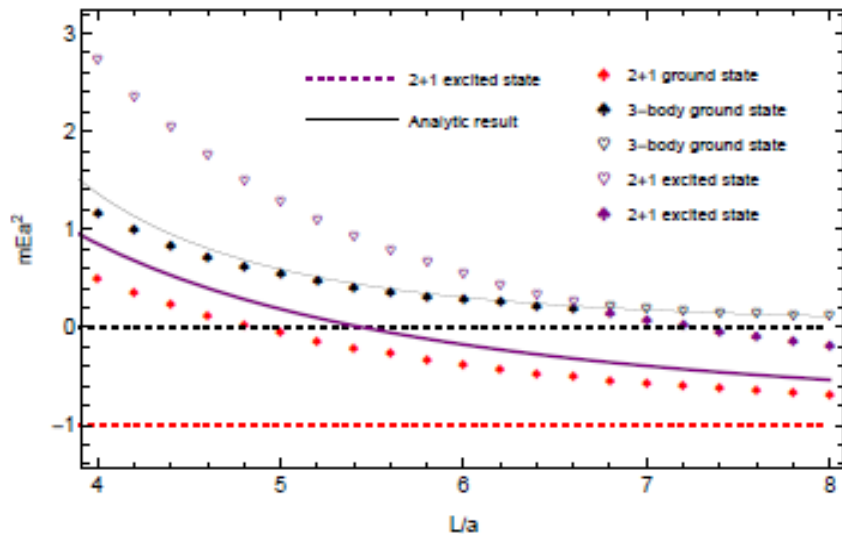
X_3 : Λ independence

$$x_3 = +\frac{1}{\pi^3} \left(-\mathbb{I}^3(0) + \mathbb{I}(0)\mathbb{J}(\vec{0}) + 15\mathbb{K}(\vec{0}) + C_2 \right) - \frac{8\pi}{a^2} \mathcal{A} - 8\pi \left(X_1 - \frac{\sqrt{3}\mathbb{I}_3}{2\pi^2} \right)$$

amplitude $\mathcal{M}_{3,\text{thr}}$, which begins at $\mathcal{O}(\lambda^2)$ in perturbation theory. The numerical values of \mathcal{C}_3 , \mathcal{C}_4 , and \mathcal{C}_5 depend on the choice of UV cutoff, but this dependence cancels with that of $\mathcal{M}_{3,\text{thr}}$. This cancellation is necessary because $\Delta E_{3\text{thr}}$ is a physical quantity.



Energy Shift of 3-body Ground state

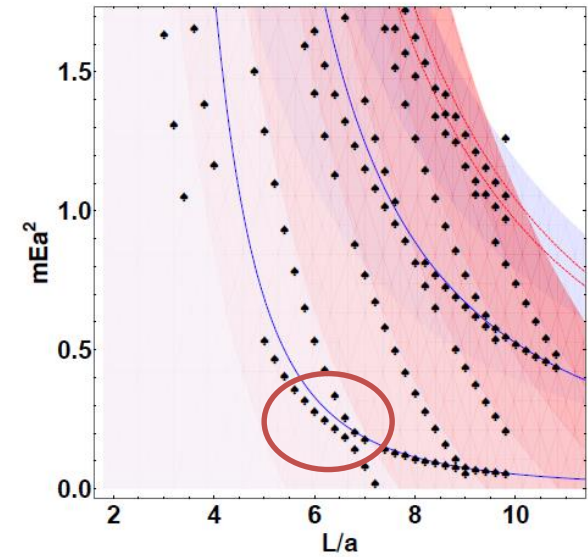
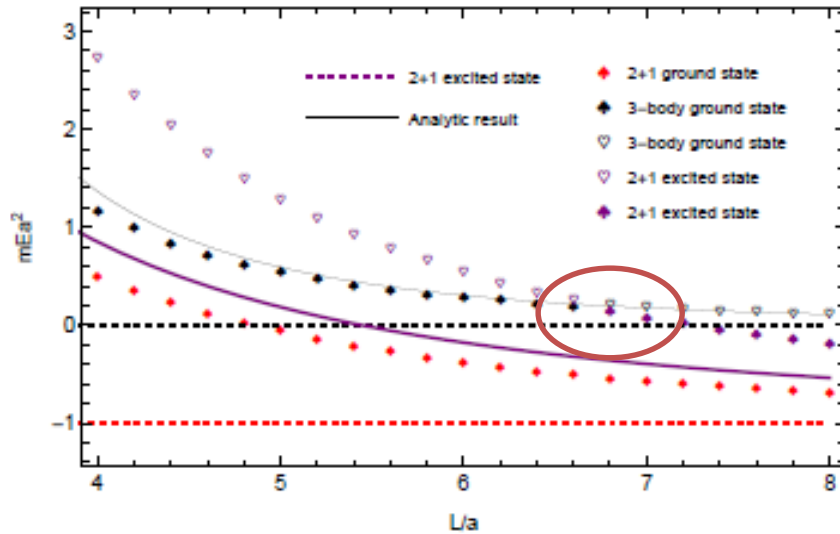


$$\text{Ground State: } \kappa^2 = \frac{g_0}{L} \left(1 + \frac{g_1}{L} + \frac{g_2}{L^2} + \frac{g_3}{L^3} \ln \frac{mL}{2\pi} + \frac{g_4}{L^3} + \dots \right)$$

$$\text{where } g_4 = \left(-5.159159617 + 6\pi \left(\frac{r}{a} \right) - 8\pi \left(\frac{\mathcal{M}}{a^2} \right) \right) a^3$$



More Energy Shift



$$\text{Ground State: } \kappa^2 = \frac{g_0}{L} \left(1 + \frac{g_1}{L} + \frac{g_2}{L^2} + \frac{g_3}{L^3} \ln \frac{mL}{2\pi} + \frac{g_4}{L^3} + \dots \right)$$

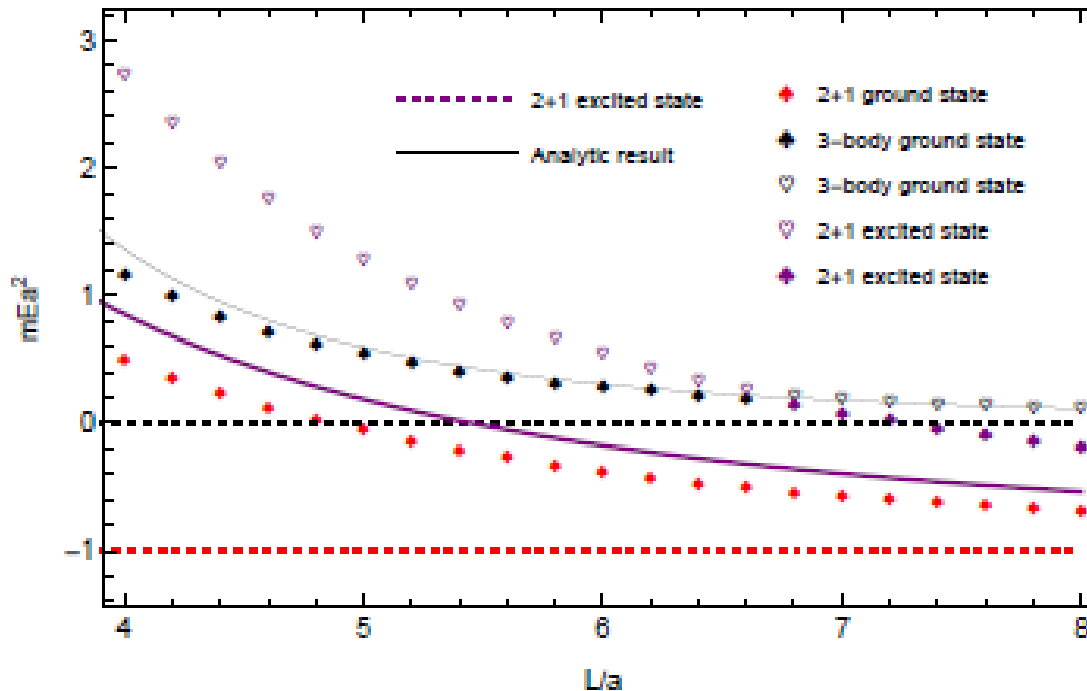
$$\text{Excited State: } \kappa^2 - 1 = \frac{h_0}{L} \left(1 + \frac{h_1}{L} + \frac{h_2}{L^2} + \frac{h_3}{L^3} \ln \frac{mL}{2\pi} + \frac{h_4}{L^3} + \dots \right),$$

$$\text{where } g_4 = \left(-5.159159617 + 6\pi \left(\frac{r}{a} \right) - 8\pi \left(\frac{\hat{\mathcal{M}}}{a^2} \right) \right) a^3$$

$$h_4 = \left(-172.001650 + 83.745841 \left(\frac{r}{a} \right) - \frac{27}{5} \times 8\pi \left(\frac{\hat{\mathcal{M}}}{a^2} \right) \right) a^3$$



More Energy Shift



Purple: excite state
of dimer-particle

Black: ground state
of three particle

Red: ground state
of dimer-particle
scattering state

$$E_{1d}(L) - E_{1d}^{\text{free}}(L) = \frac{\mathcal{A}_d}{L^3} + O(L^{-4})$$

\mathcal{A}_d denotes the particle-dimer
scattering amplitude at threshold



Summary

- In the infinite volume, we build the scattering equation of dimer particle amplitude to describe the 3-body system based on the non-relativistic effective field theory.
- By considering the symmetry and the discrete momentum in the box, the quantization condition for the energy level of 3-body system is derived.
- Through this quantization condition, we derived the lowest energy shift of the 3-body scattering state, and prove it is cutoff independence.



Outlook

- Non-relativistic \rightarrow relativistic
- S-wave dimer \rightarrow high partial wave dimer
- To apply this method to study real 3-body system, such as 3- pions, it still needs more efforts.





THANKS VERY MUCH



3-body System in the finite volume

There are 48 rotation operators $\hat{g} \in O_h$,

$(x,y,z) \Rightarrow (x,y,z), (x,y,-z), (x,-y,z), (x,-y,-z), (-x,y,z), (-x,y,-z),$
 $(-x,-y,z), (-x,-y,-z)$

$(y,x,z), (y,x,-z), (y,-x,z), (y,-x,-z), (-y,x,z), (-y,x,-z),$
 $(-y,-x,z), (-y,-x,-z)$

..... $\Rightarrow 8 \times 6 = 48$ vectors

Irreducible Representation Γ , $A_1^\pm, A_2^\pm, E^\pm, T_1^\pm, T_2^\pm$

\vec{n} is on the shell
 s , and \vec{n}_0 is the
special vector
on the shell s

$$f(\vec{n}) = f(\hat{g}\vec{n}_0) = \sum_{\Gamma} \sum_j T_{ij}^{\Gamma}(\hat{g}) f_j^{\Gamma,i}(\vec{n}_0(s))$$

$$\frac{G}{D_{\Gamma}} f_j^{\Gamma,i}(\vec{n}_0(s)) = \sum_{g \in O_h} T_{ij}^{\Gamma*}(\hat{g}) f(\hat{g}\vec{n}_0)$$



3-body System in the finite volume

$$Z_L(\vec{n}, \vec{m}, E) = Z_L(\hat{g}\vec{n}, \hat{g}\vec{m}, E)$$

$$Z_{L\,ij}^\Gamma(r, s, E) = \sum_{g \in O_h} T_{ji}^{\Gamma*}(\hat{g}) Z_L(\hat{g}\vec{n}_0(r), \vec{m}_0(s), E)$$

- Quantization condition: $\det(\tau_L^{-1} - \frac{8\pi}{L^3} Z_L) = 0$

$$\det \left(\theta^{-1}(s) \tau_L^{-1}(r, E) \delta_{rs} \delta_{ij} - \frac{8\pi}{L^3} \frac{1}{G} Z_{L\,ij}^\Gamma(r, s, E) \right) = 0$$

$$\sum_{\vec{n} \in \mathbb{Z}^3} f(\vec{n}) = \sum_s \sum_{g \in O_h} \frac{\theta(s)}{G} f(\hat{g}\vec{n}_0(s))$$



3-body System in the finite volume

- Results of Toy model && $\Gamma = A_1^+$

$$\det \left(\theta^{-1}(s) \tau_L^{-1}(r, E) \delta_{rs} \delta_{ij} - \frac{8\pi}{L^3} \frac{1}{G} Z_L^\Gamma(r, s, E) \right) = 0$$



$$\det \left(\theta^{-1}(s) \tau_L^{-1}(r, E) \delta_{rs} - \frac{8\pi}{L^3} \frac{1}{G} Z_L^{A_1^+}(r, s, E) \right) = 0$$

$$\tau_L^{-1}(r, E) = -\frac{1}{a_0} - \frac{4\pi}{L^3} \sum_{\vec{l}} \frac{1}{\frac{4\pi^2}{L^2} \left(\vec{n}_0^2(r) + \vec{l}^2 + \vec{n}_0(r) \cdot \vec{l} \right) - mE}$$

$$Z_L^{A_1^+}(r, s, E) = \sum_{g \in O_h} Z_L(\hat{g} \vec{n}_0(r), \vec{n}_0(s), E)$$



Energy shift of Ground state of 3-body scattering state

$$mE = \frac{12\pi a}{L^3} \left(1 + \frac{x_1}{L/a} + \frac{x_2}{(L/a)^2} + \frac{x'_3 \log[L/a]}{(L/a)^3} + \frac{x_3}{(L/a)^3} + \dots \right)$$

$$x_1 = -\frac{\mathbb{I}(0)}{\pi} \quad x_2 = \frac{\mathbb{I}^2(0) + \mathbb{J}^2(0)}{\pi^2} \quad x'_3 = 16\sqrt{3} - 64\pi/3$$

$$x_3 = +\frac{6\pi r}{a} + \frac{1}{\pi^3} \left(-\mathbb{I}^3(0) + \mathbb{I}(0)\mathbb{J}(\vec{0}) + 15\mathbb{K}(\vec{0}) + C_2 \right)$$

$$-\frac{1}{\pi^3} (X_0(\Lambda) + X_1(\Lambda) + X_2(\Lambda)) - \frac{8\pi H_0(\Lambda)}{a^2 \Lambda^2}$$

$$-(L/a)^3 \left(X(\Lambda) \frac{8\pi a}{L^3} + \frac{4\mathbb{J}(\vec{0})}{(\pi L/a)^2} + \frac{(16\sqrt{3} - 64\pi/3) \log(L/a)}{(L/a)^3} \right)$$

$$X(\Lambda) = \frac{H_0(\Lambda)}{\Lambda^2} + \sum_{\vec{i} \in \mathbb{Z}^3}^{[1,N]} \frac{8\pi}{L^3} z(\vec{0}, \vec{i}, 0) \tau(\vec{i}, 0) M^L(\vec{i}, \vec{0}),$$

**Cutoff
dependence**

$$M^L(\vec{j}, \vec{0}) = z(\vec{j}, \vec{0}, 0) + \sum_{\vec{i} \in \mathbb{Z}^3}^{[1,N]} \frac{8\pi}{L^3} z(\vec{j}, \vec{i}, 0) \tau(\vec{i}, 0) M^L(\vec{i}, \vec{0}).$$

