
Progress of LHAASO Software Framework

Wenhao Huang, Xingtao Huang

Shandong University

2019.04.13-15 Nanjing



Outline

- ◆ Overview of LHAASO Offline Software System
- ◆ Optimization of Simulations
- ◆ Implementation of Reconstructions
- ◆ Current Status of Data Flow of raw data
- ◆ Summary & Plan

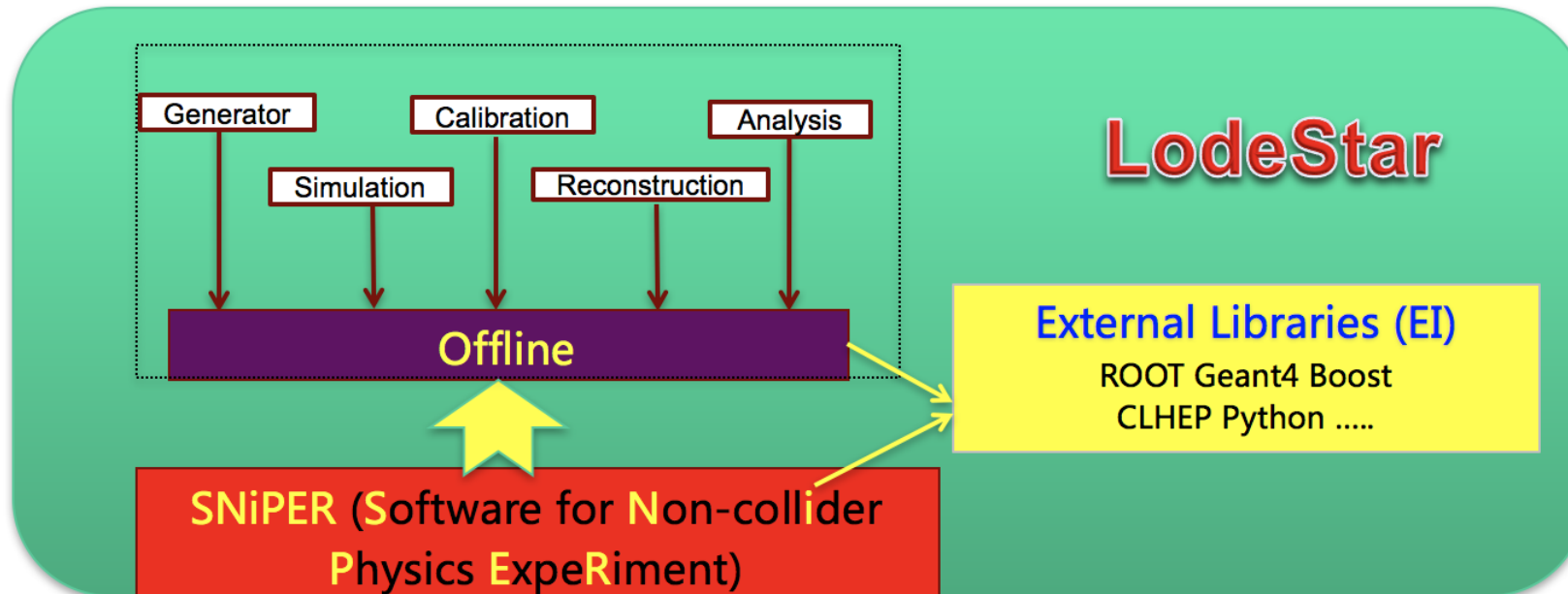
Overview of LHAASO Offline Software

◆ LodeStar

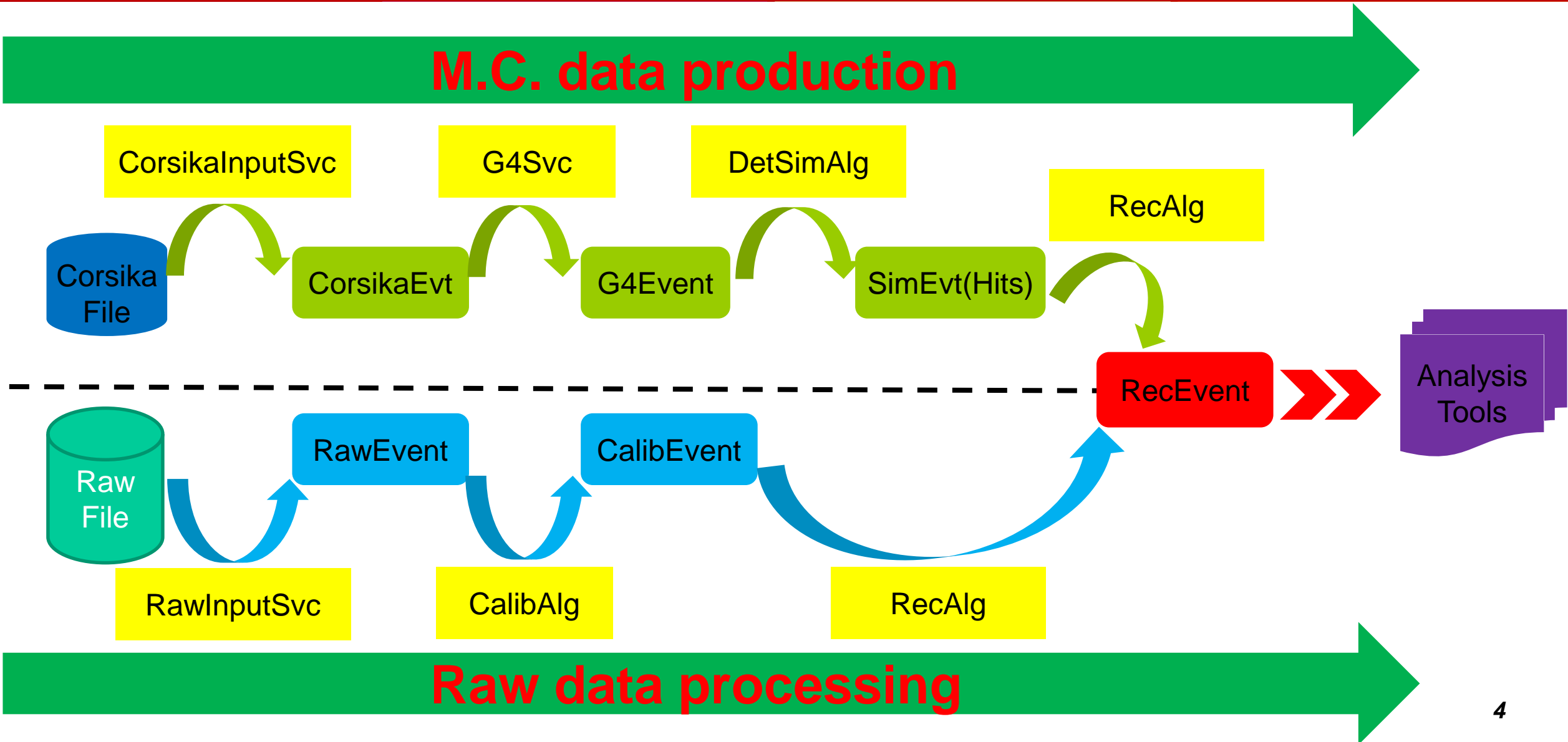
- LHAASO Offline Data Processing Software Framework

◆ Main Components:

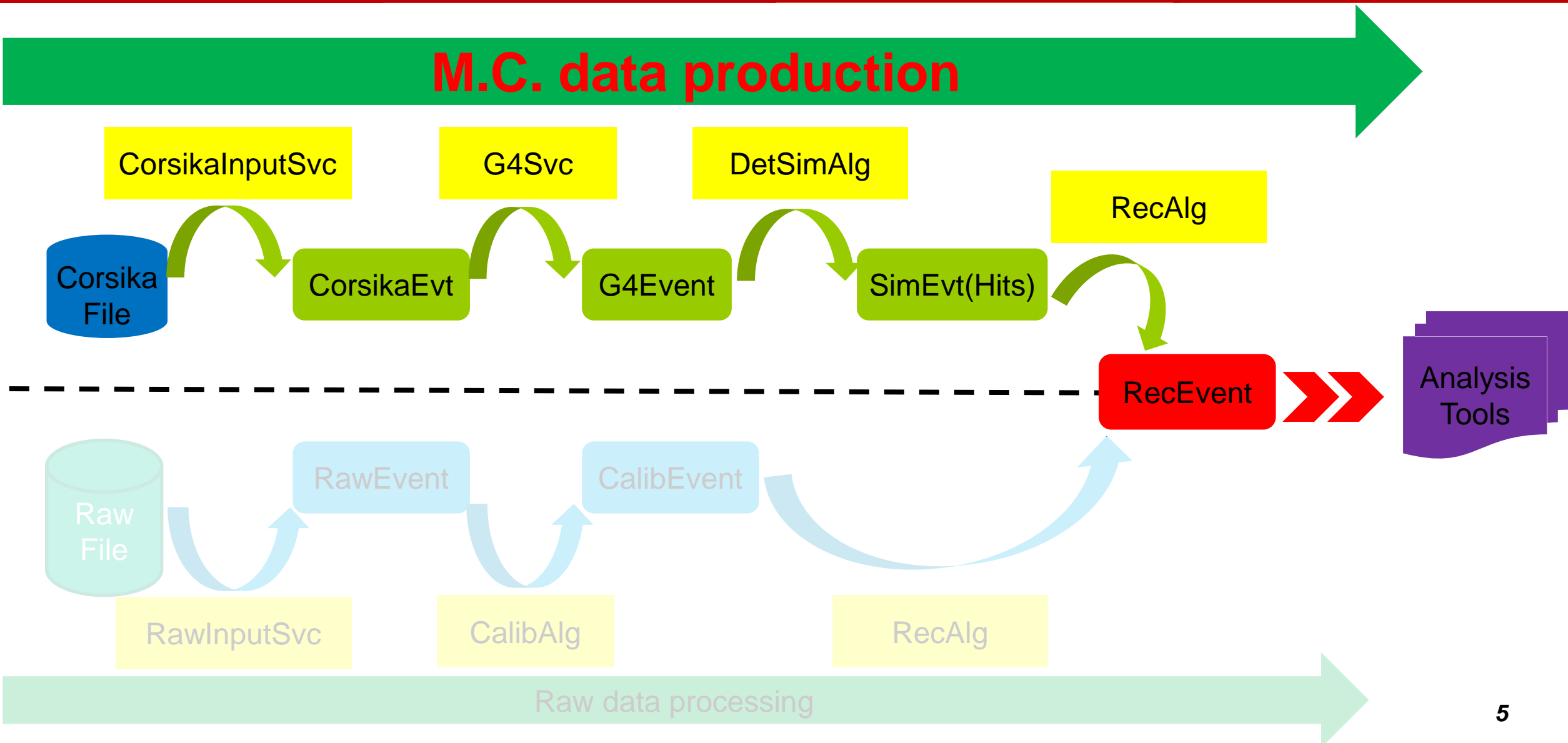
- **Offline**: specific to LHAASO Experiments
- **SNiPER**: underlying framework
- **External Libraries**: frequently used third-party software or tools



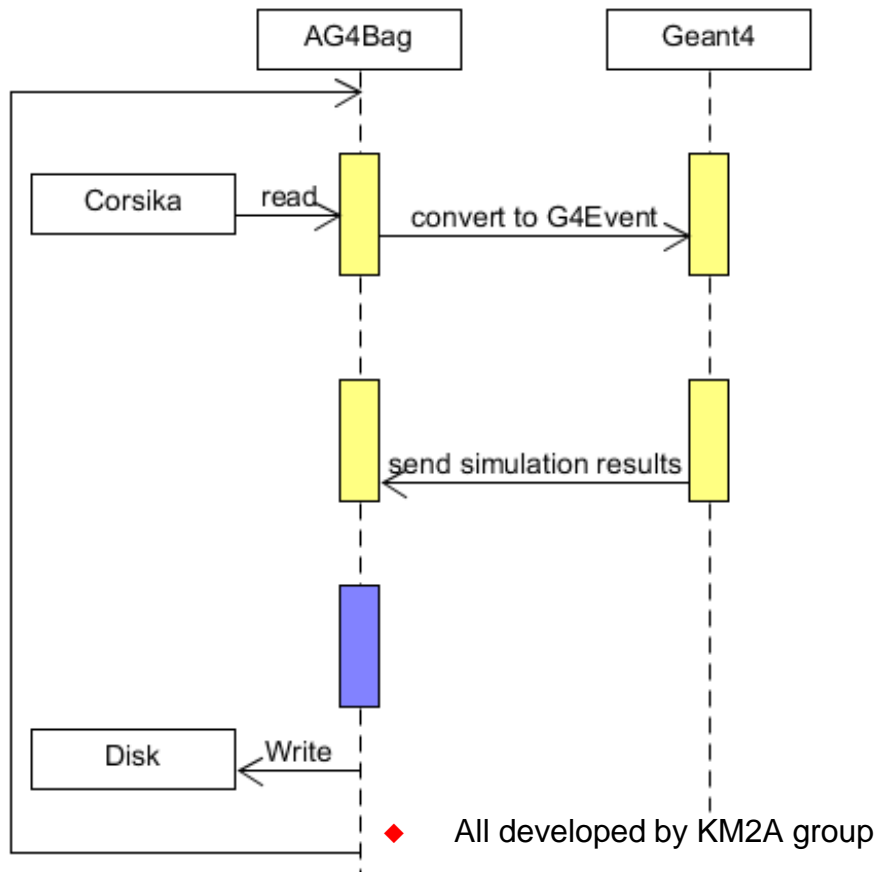
Two Data Flows in Framework



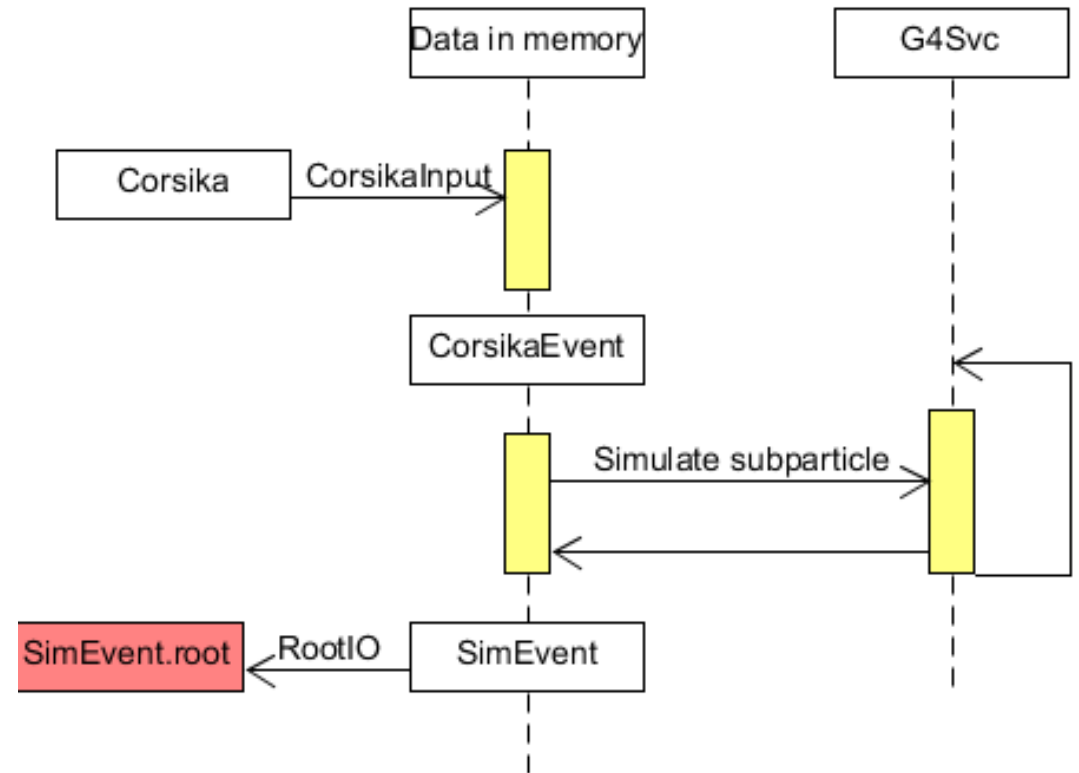
Two Data Flows in Framework



Optimizations in KM2A Simulation



- ◆ All developed by KM2A group
 - Reading corsika
 - Event loop
 - Writing into file
- ◆ Codes are used theirselves



- ◆ Implemented in framework way
 - Corsika input
 - G4Svc
 - RootIO
- ◆ Codes can be used in other applications

KM2A Simulation Script

```
import CorsikaIO
iSvc = task.createSvc("CorsikaInputSvc/InputSvc")
iSvc.property("InputStream").set({"/Event/CorsikaEvent" : "DAT000002"})
iSvc.property("Thining").set(False)
iSvc.property("ParticleBufferSize").set(10)
iSvc.property("FileType").set("particle")

import RootIOSvc
oSvc = task.createSvc("RootOutputSvc/OutputSvc")
oSvc.property("OutputStream").set({"/Event/KM2AEventV3" : "KM2AEventV3.root"})

import KM2AG4Svc
g4svc = task.createSvc("KM2AG4Svc/G4Svc")

import KM2ASimV2
factory = task.createSvc("KM2ASimV2Factory/Km2aFacory")
factory.property("AnaMgrList").set(["KM2AAnaMgr"])
factory.property("Mode").set(1)
factory.property("Wid").set(0)
```

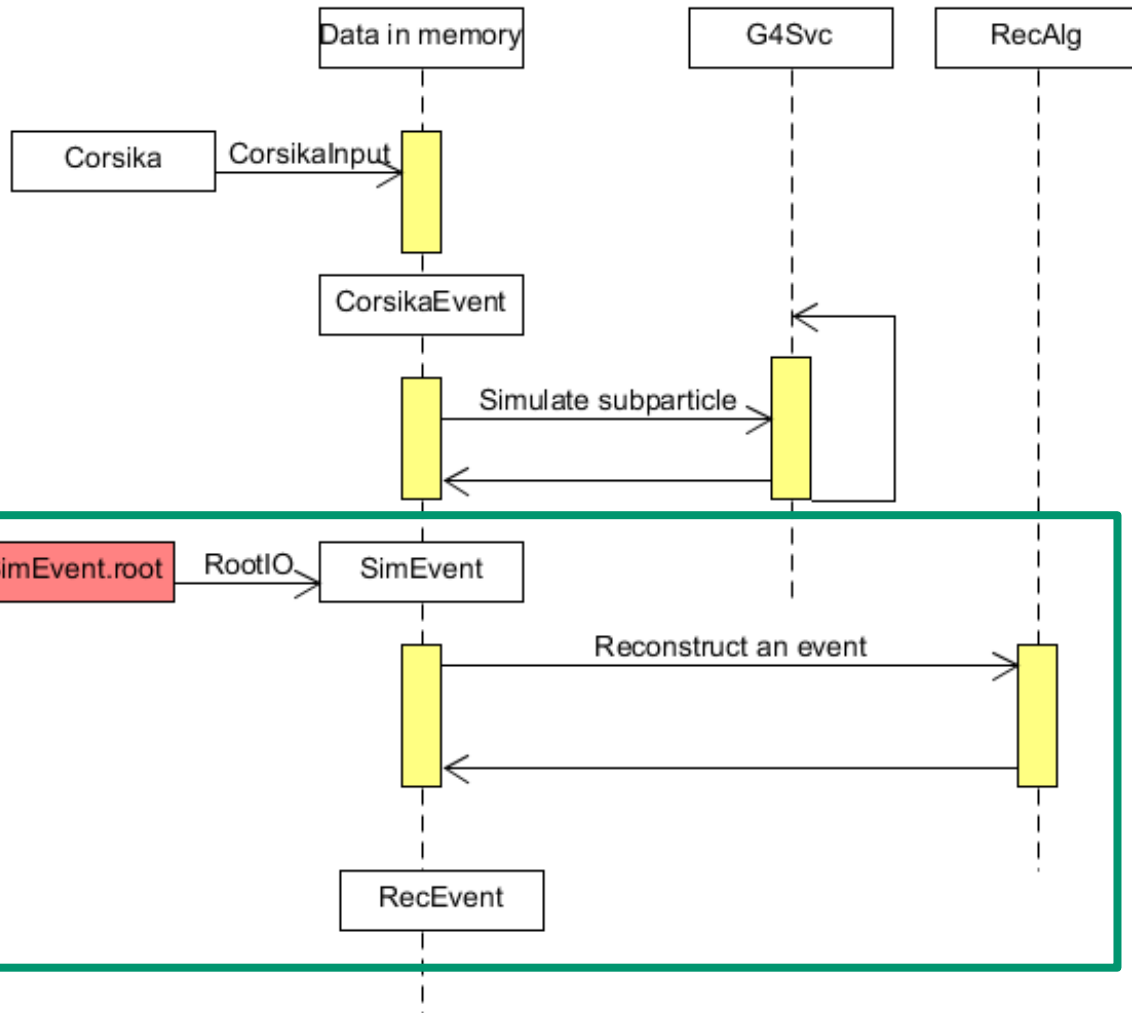
→ Input Service

→ Output Service

→ Simulation Parameters

\$python DetSim_KM2A.py

KM2A(Reconstruction)



◆ Easily adding the reconstruction algorithms

- Direction reconstruction
- core position reconstruction

KM2A(Reconstruct of direction and core position)

```
import KM2Arec

task.property("algs").append("Km2aRecAlg/Km2aRec")

rec = task.find("Km2aRec")
print "Before setting properties"
rec.show()

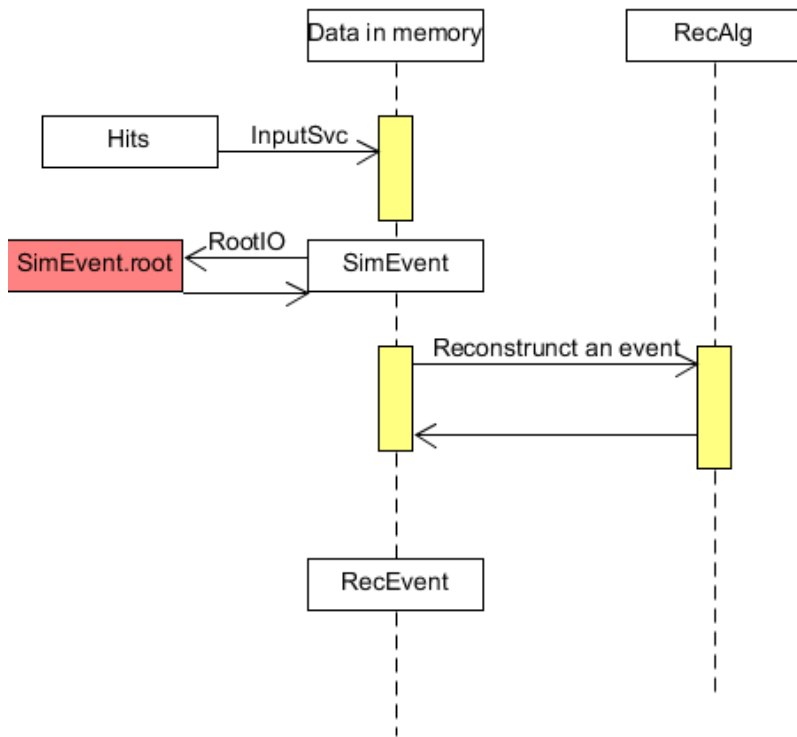
print

rec.property("Mode").set(2)
rec.property("Tresolution").set(0)
rec.property("InfileName").set("../ioput/DAT000001.root")
rec.property("OutfileName").set("../ioput/cszfit.root")
```

```
$python Rec_KM2A.py
```

Several lines in the **job configurations**, the **reconstruction algorithms** will be **automatically** called and write the reconstructed results into the root files

WCDA(Simulation & Reconstruction)



```
$python DetSim_WCDA_1(2).py inputfile outputfile --settingfile ...  
$python wcdaHitsConv.py
```

```
import WCDArec  
alg = task.createAlg("WcdaRecAlg/hAlg")  
  
import DataStoreMgr  
task.createSvc("DataStoreMgr")  
  
import RootIOSvc  
isvc = task.createSvc("RootInputSvc/InputSvc")  
isvc.property("InputStream").set({"Event/wcdaSimEvent" : "wcdaSimEvent_test.root"})  
  
osvc = task.createSvc("RootOutputSvc/OutputSvc")  
osvc.property("OutputStream").set({"Event/wcdaRecEvent" : "wcdaRecEvent.root"})  
  
task.setEvtMax(4)  
task.show()  
task.run()
```

```
$python Rec_WCDA.py
```

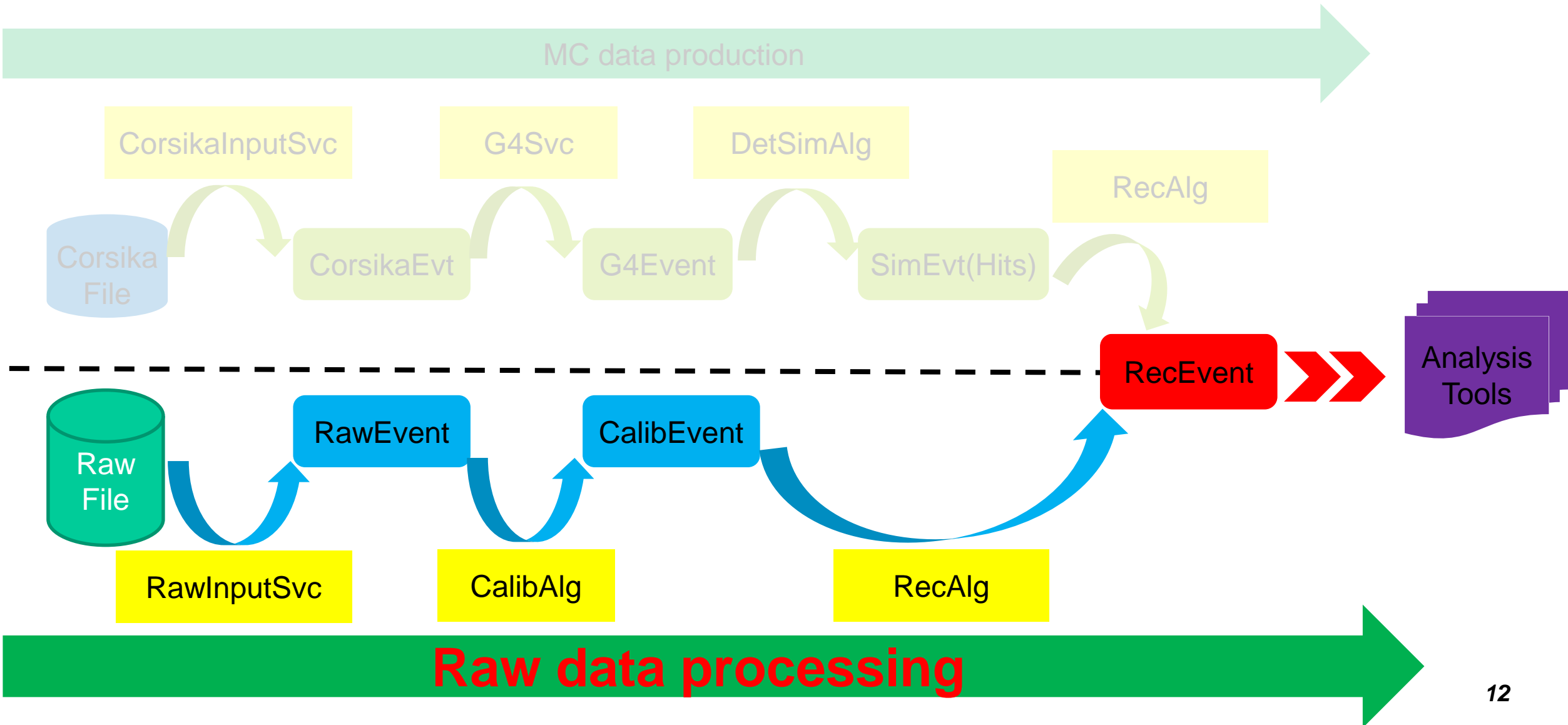
- ◆ Framework reads simulated hits into the data store
 - Write them into the root files as KM2A
 - Also can be used by the Reconstruction algorithms
- ◆ WCDA simulation can be run with the unified way.
 - No much changes on the WCDA detector simulation

WFCTA Simulation

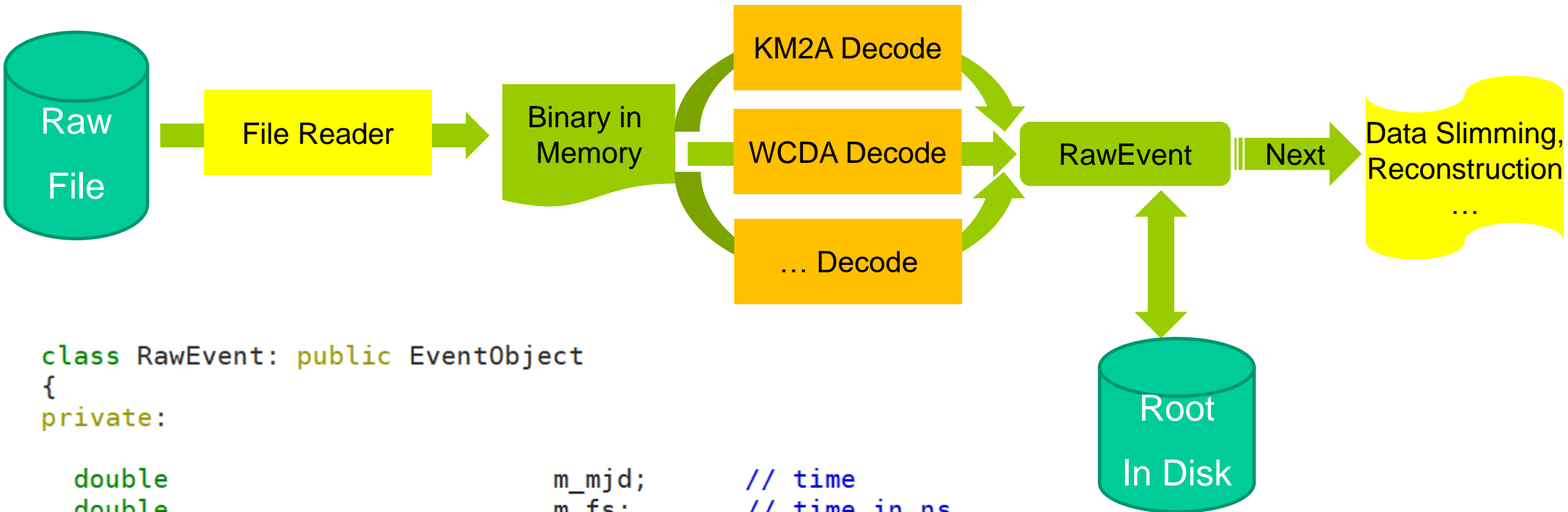
- ◆ We updated data model of WFCTA(WFCTASimEvent).



Two Data Flows in Framework



Raw Data Input Module



```
class RawEvent: public EventObject
{
private:
```

```
double          m_mjd;          // time
double          m_fs;          // time in ns
int             m_nedhit;       // number of ed hits
int             m_nmdhit;       // number of md hits
std::vector<LHAAS0::KM2AHit*> m_KM2Ahits; // List of KM2A hits
```

Raw Data Input Module

```
#!/usr/bin/env python
import Sniper

Algtask = Sniper.Task("Algtask")

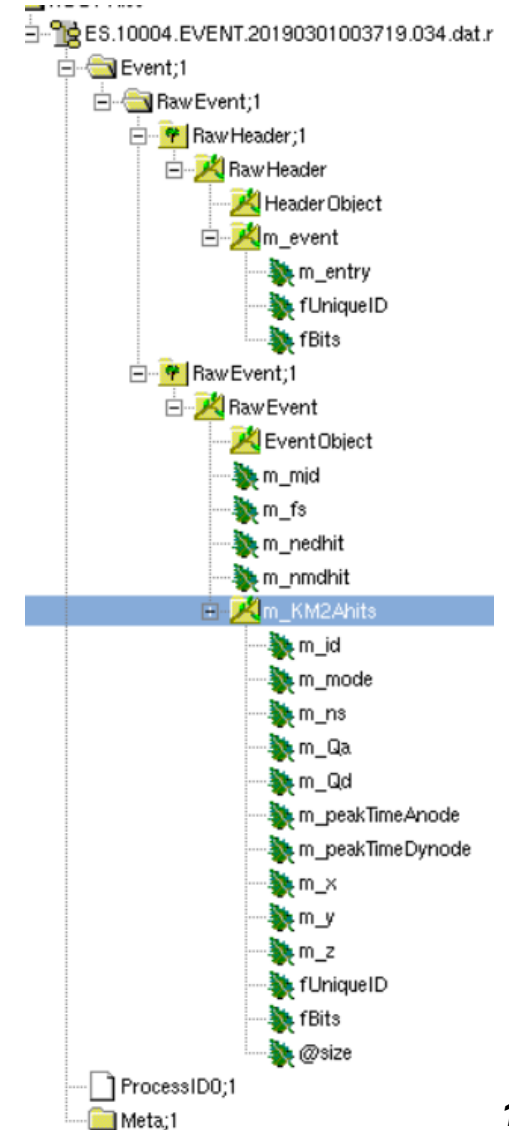
import IOTestAlg
datalg = Algtask.createAlg("IOTestAlg/myalg")

import RawIO
iSvc = Algtask.createSvc("RawInputSvc/InputSvc")
iSvc.property("InputStream").set({"Event/RawEvent" : "/scratchfs/ybj/zhanghy/LodeStar/ES.10003.EVENT.20190226015650.013.dat"})

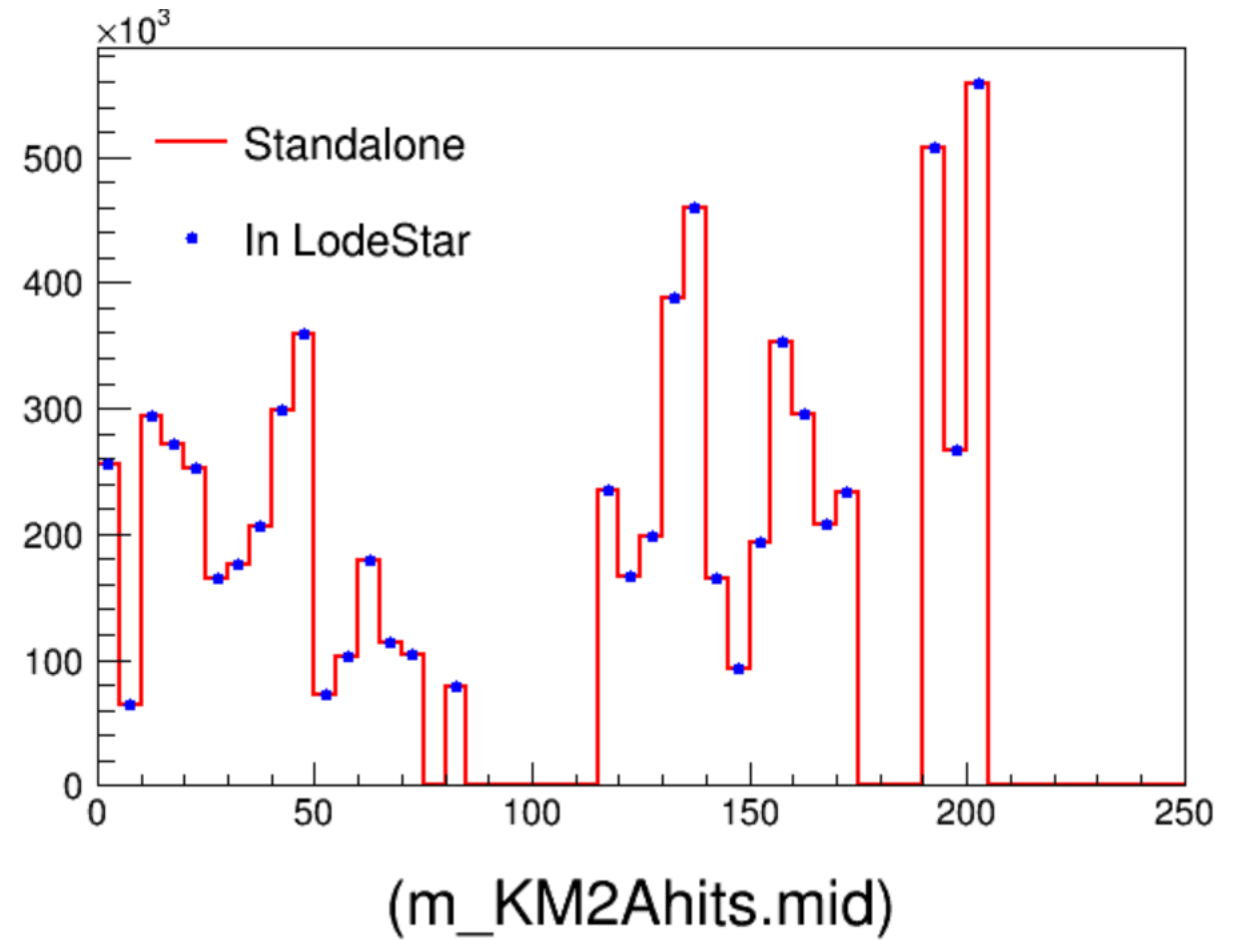
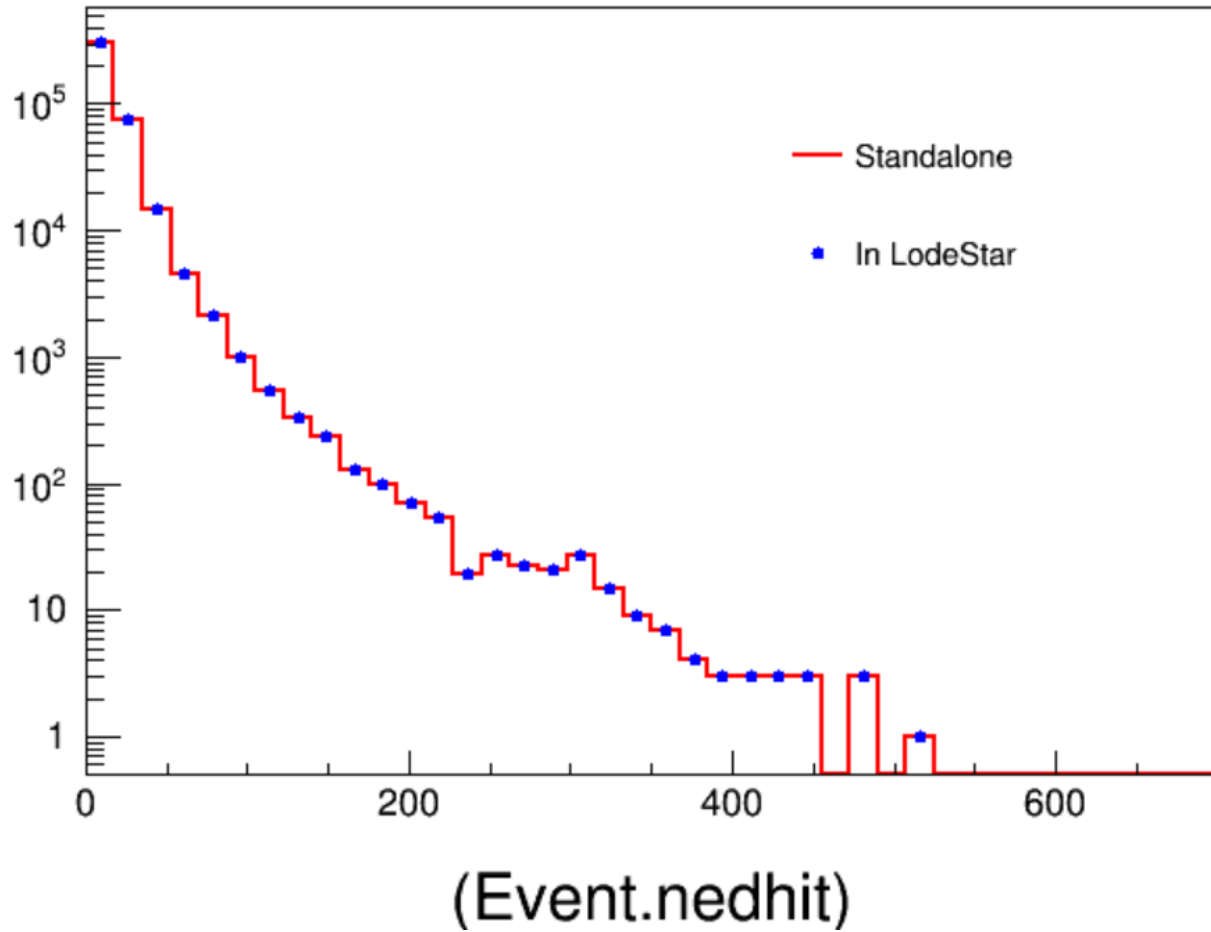
import DataStoreMgr
Algtask.createSvc("DataStoreMgr")

import RootIOSvc
oSvc = Algtask.createSvc("RootOutputSvc/OutputSvc")
oSvc.property("OutputStream").set({"Event/RawEvent" : "test.root"})

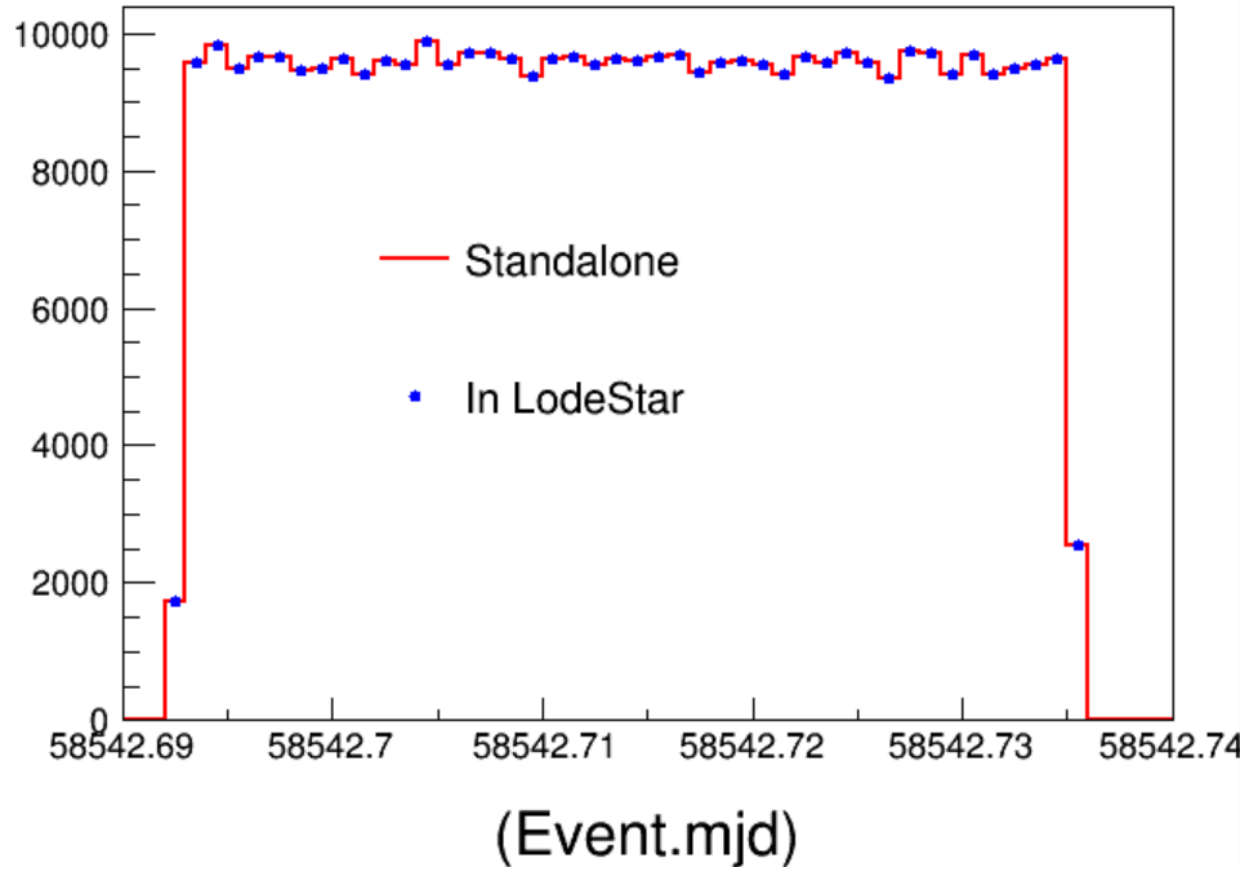
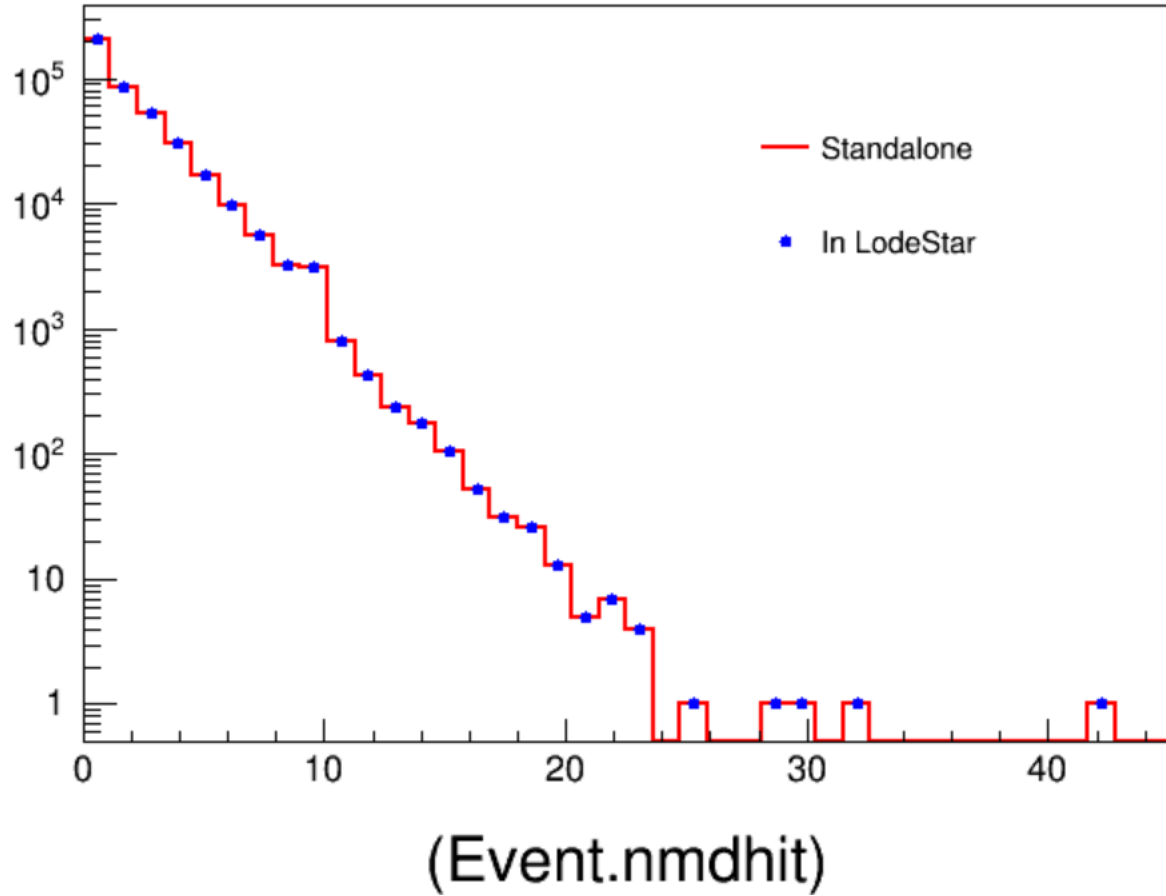
Algtask.setEvtMax(-1)
Algtask.show()
Algtask.run()
```



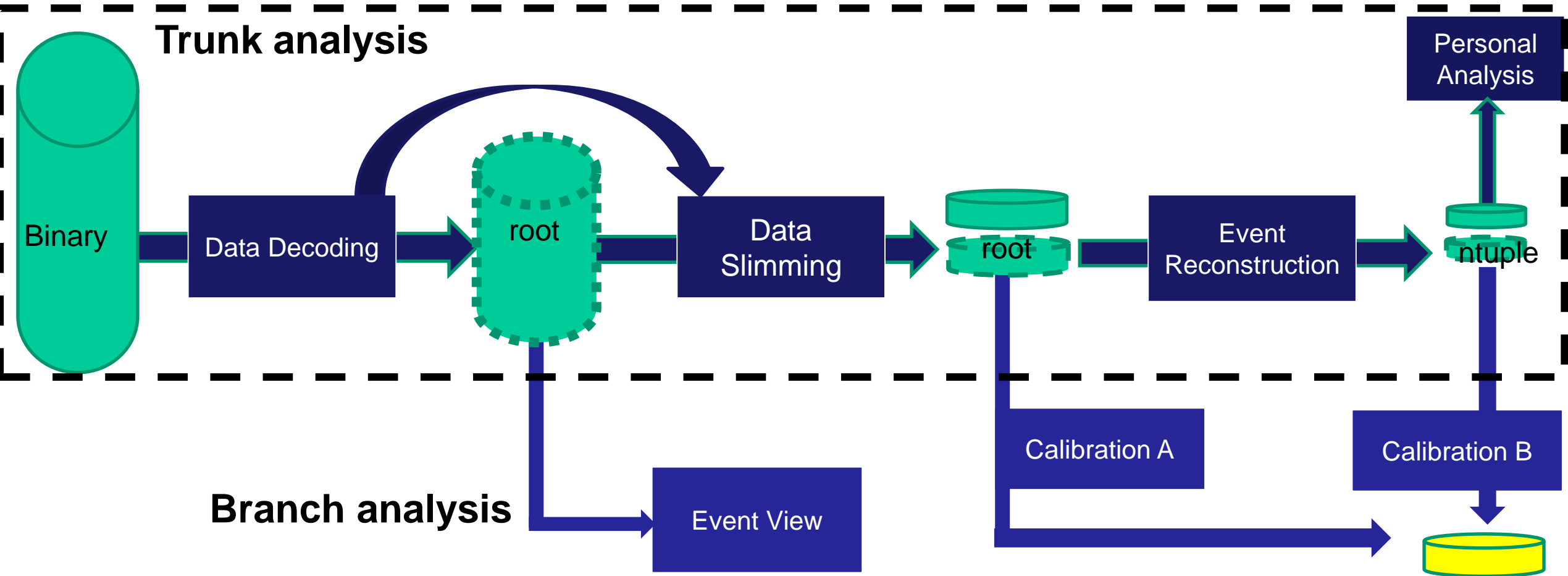
Raw Data Results Validation



Raw Data Results Validation



Data Flow of Raw Data



More details from Zhu's, the whole chain basically has been set up from the raw data to analysis.

Latest version and documentation

- ◆ The latest version of LodeStar has been installed at ihep.
 - [/afs/ihep.ac.cn/soft/LHAASO/LodeStar-SLC6/Pre-Release/L18-Pre1](https://afs.ihep.ac.cn/soft/LHAASO/LodeStar-SLC6/Pre-Release/L18-Pre1)

```
-bash-4.1$ ls /afs/ihep.ac.cn/soft/LHAASO/LodeStar-SLC6/Pre-Release/L18-Pre1
bashrc.sh      ExternalLibs  offline      setup.sh      sniper
ExternalInterface  lhaasoenvironment  setup.csh  setup-trunk.sh  tcshrc.csh
-bash-4.1$ █
```

- ◆ Doc-Db
581-v3

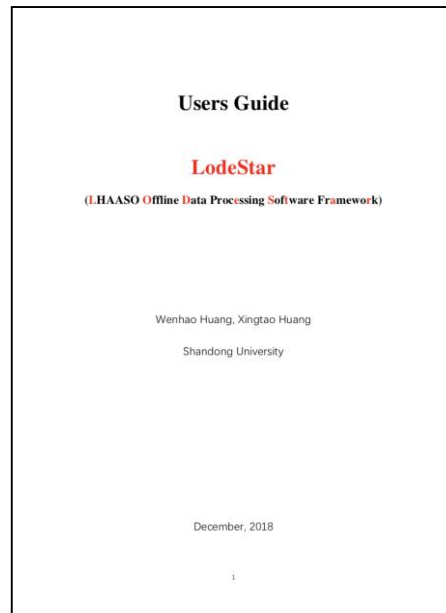


Table of Contents	
1. INTRODUCTION	5
2. ARCHITECTURE	6
3. STATUS AND RELEASE	8
SVN REPOSITORY	8
CURRENT VERSION	9
4. GETTING STARTED	10
HOW TO SETUP ENVIRONMENTS	10
HOW TO USE CMT	11
HOW TO USE SVN	12
HOW TO RUN HELLOWORLD	12
HOW TO DEVELOP DETECTOR SIMULATION	15
A Class to get access to G4	15
Run/Event/Stacking/Tracking/Stepping Actions	15
DetSimFactory	16
Example KM4Sim	17
HOW TO DEFINE EVENT DATA	18
Event Data Header and Object	18
XOD Tool	19
EDIM Book	22
Config and make	22
HOW TO READ EVENT DATA	22
HOW TO WRITE EVENT DATA	23
HOW TO GENERATE MC DATA	23
5. MAIN COMPONENTS	24
DATA PROCESSING PROCEDURE	24
ALGORITHM	25
What' s the Algorithm?	25
How to create an Algorithm	25
SERVICE	28

What' s the Service?	28
How to create a Service	28
How to use a Service	28
TASK	29
What' s the Task?	29
How to configure a Task	29
How to use a Task	29
TOOL	30
What' s the Tool?	30
How to create a Tool	30
How to use a Tool	30
PROPERTY	32
What' s the Property?	32
How to use Properties	32
6. DATA MODEL	33
7. INPUT/OUTPUT SYSTEM	34
8. GENERATORS	35
9. SIMULATION	36
10. CALIBRATION	37
11. RECONSTRUCTION	38
12. PHYSICS ANALYSIS TOOLS	39
13. APPENDIX	40
INSTALLATION	40
CODING CONVENTIONS	41

Summary & Plan

- ◆ Optimized data flow in framework
 - M.C. Data
 - Raw Data
- ◆ KM2A, WCDA and WFCTA have been integrated with LodeStar
 - More people and imputes are needed
- ◆ Raw Data Input Service has been integrated with LodeStar
- ◆ Develop calibration and event select algorithm.
- ◆ Setup the whole chain from Corsica (Raw) data to physics analysis

Thank you

Advantage

◆ Modularity

- common modules
- specific modules
- share

◆ Independent

- Low coupling between different modules

◆ Easy to access

- Modules are easy to combine in python scripts.