



LLRF Activities at IMP

Xianwu Wang, IMPCAS

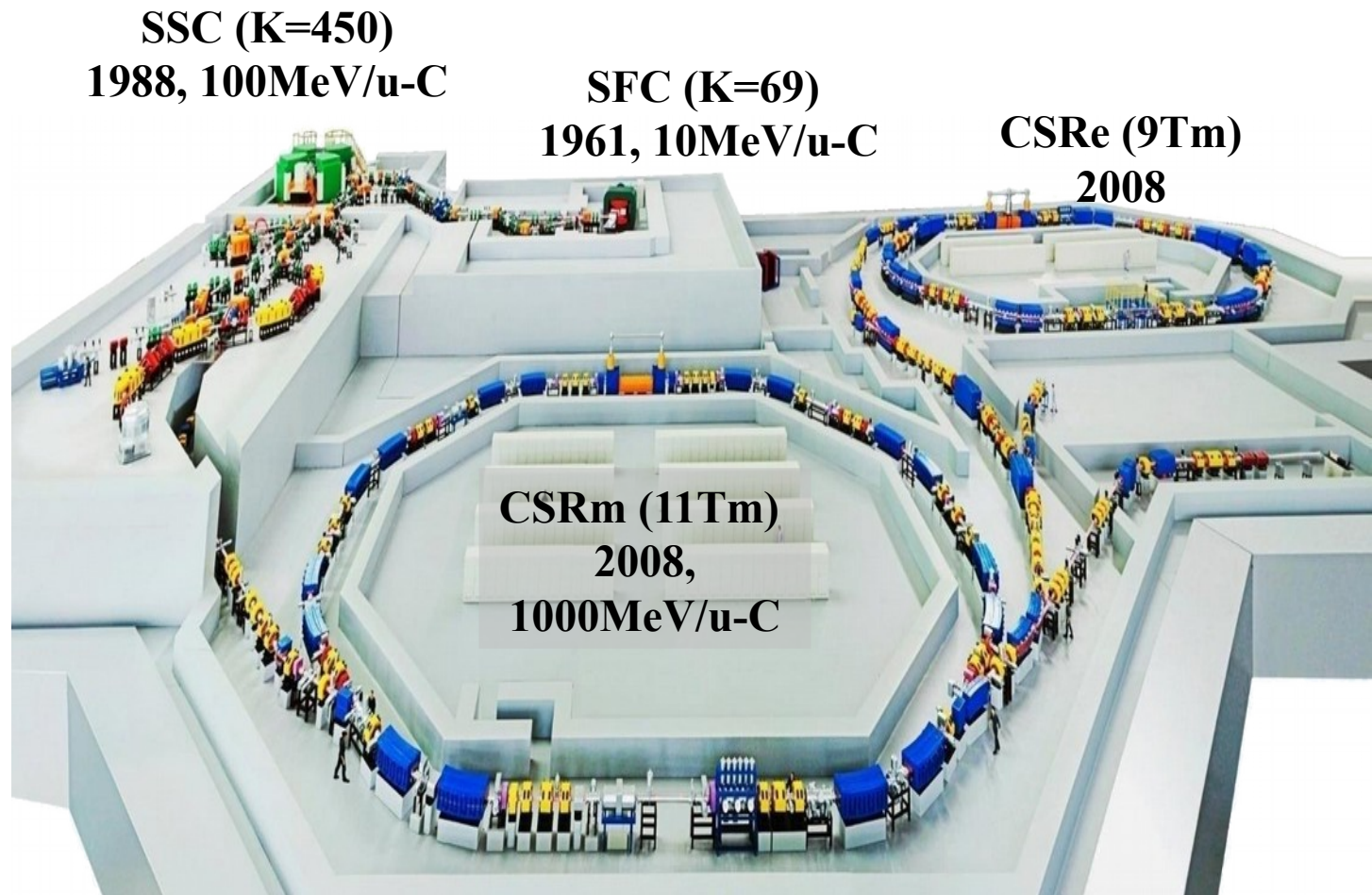
- IMP Facilities Introduction
- LLRF Systems in IMP
 - Cyclotrons LLRF
 - Synchrotrons LLRF
 - ADS Linac LLRF
 - Prototype LLRF
- Future Projects
 - HIAF
 - CiADS
 - ...

- IMP Facilities Introduction
- LLRF Systems in IMP
 - Cyclotrons LLRF
 - Synchrotrons LLRF
 - ADS Linac LLRF
 - Prototype LLRF
- Future Projects
 - HIAF
 - CiADS
 - ...

Overview of HIRFL



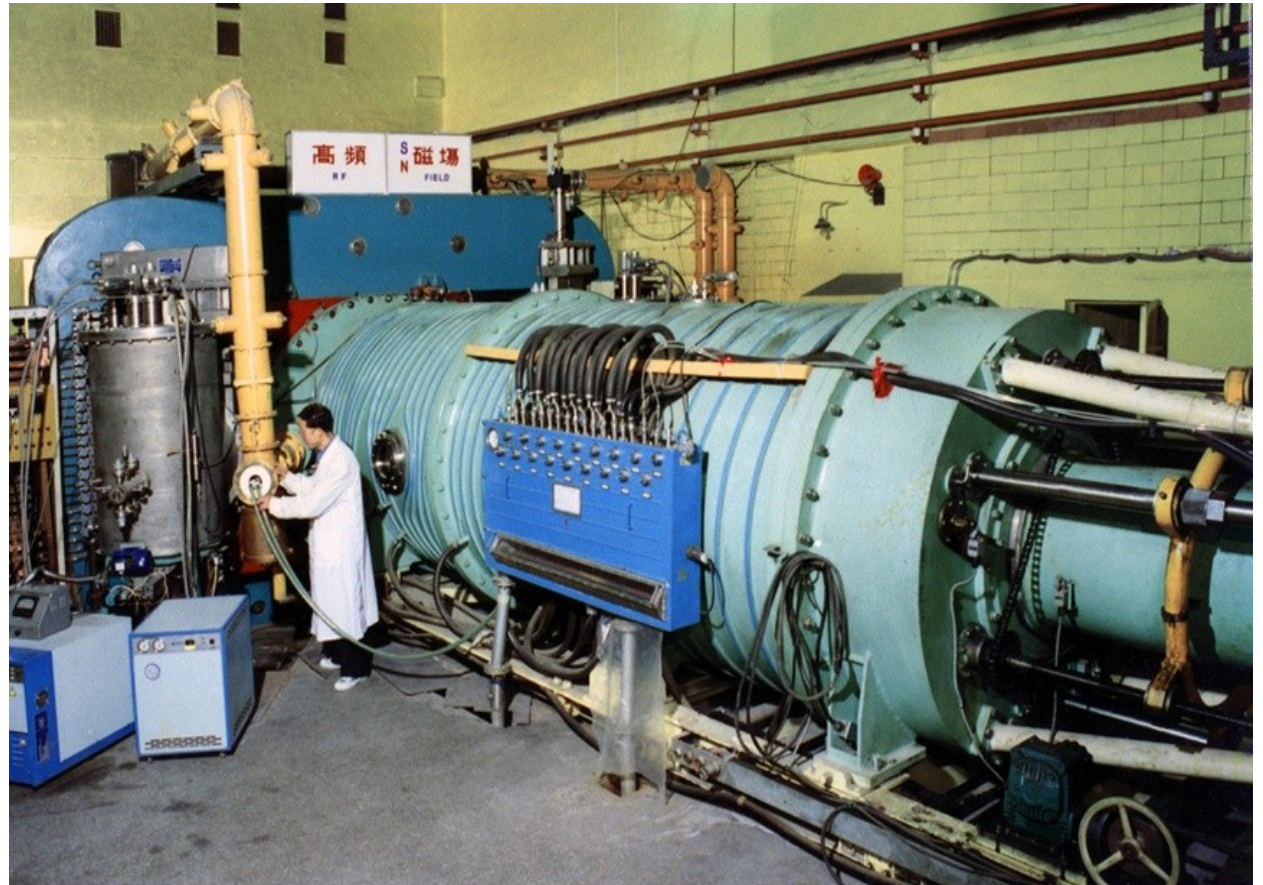
- Heavy Ion Research Facility in Lanzhou (HIRFL)
 - The largest ion-accelerator complex in China



The Injector SFC



- Built in 1961 with the assistance of the Soviet Union
- H&He 1970s, upgraded, Carbon~Uranium
 - $K \sim 69$
 - $R \sim 0.75$ m
 - $E \sim 10$ MeV(C)
 - 1 MeV/u(U)



The Main Cyclotron SSC



- 1988
 - $K \sim 450$
 - $R \sim 3.203 \text{ m}$
 - $\alpha \sim U$
 - $E : 100 \text{ MeV/u(C)}$
 - 10 MeV/u (U)



- Synchrotron and Storage Rings (CSR)

- CSRm 161.0m
- $G_{\max} = 11.3\text{Tm}$



- CSRe 122.8m
- $G_{\max} = 9.0\text{ Tm}$



Contents

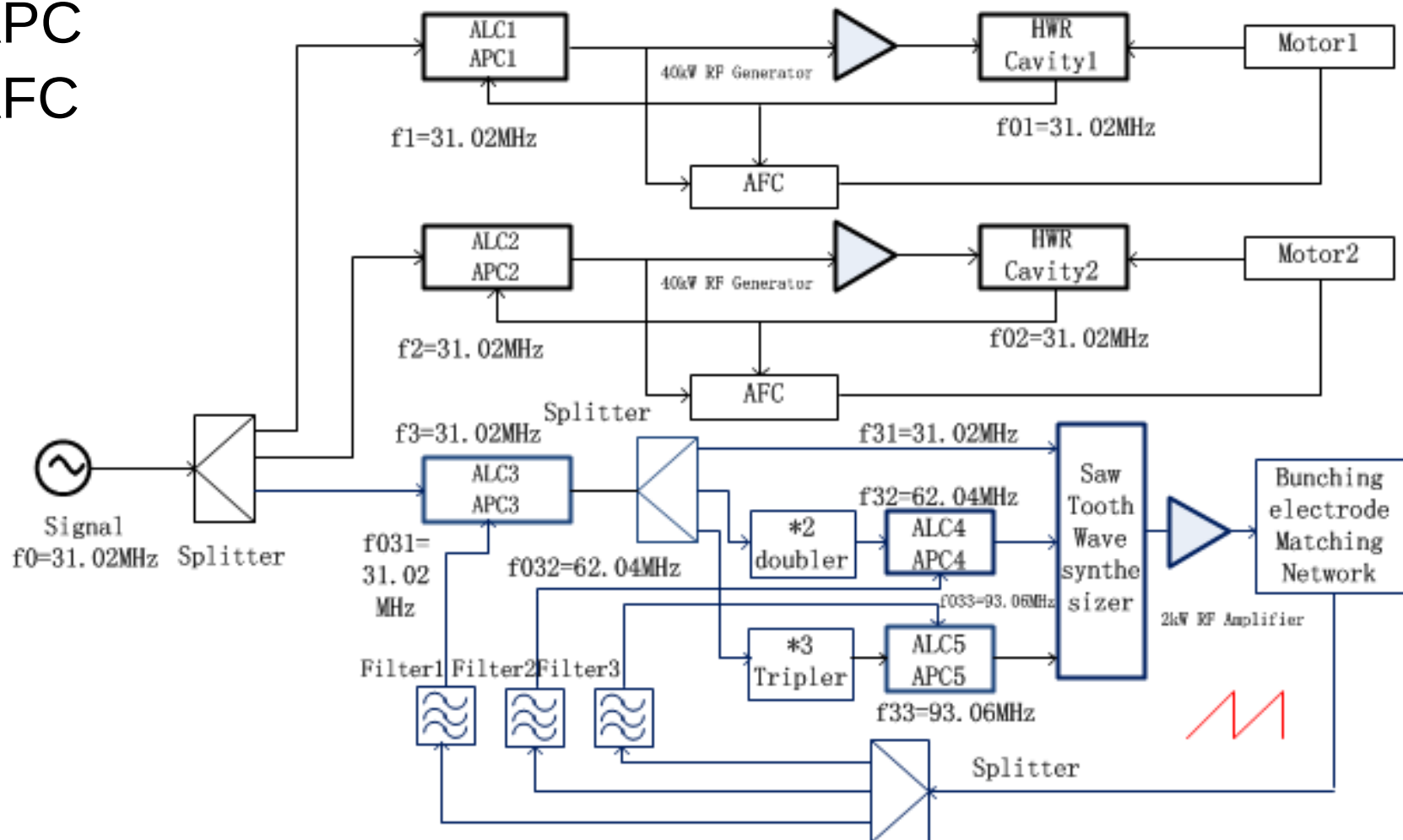


- IMP Facilities Introduction
- **LLRF Systems in IMP**
 - Cyclotrons LLRF
 - Synchrotrons LLRF
 - ADS Linac LLRF
- Future Projects
 - HIAF
 - CiADS

LLRF System for Cyclotrons



- Analog system
 - ALC
 - APC
 - AFC

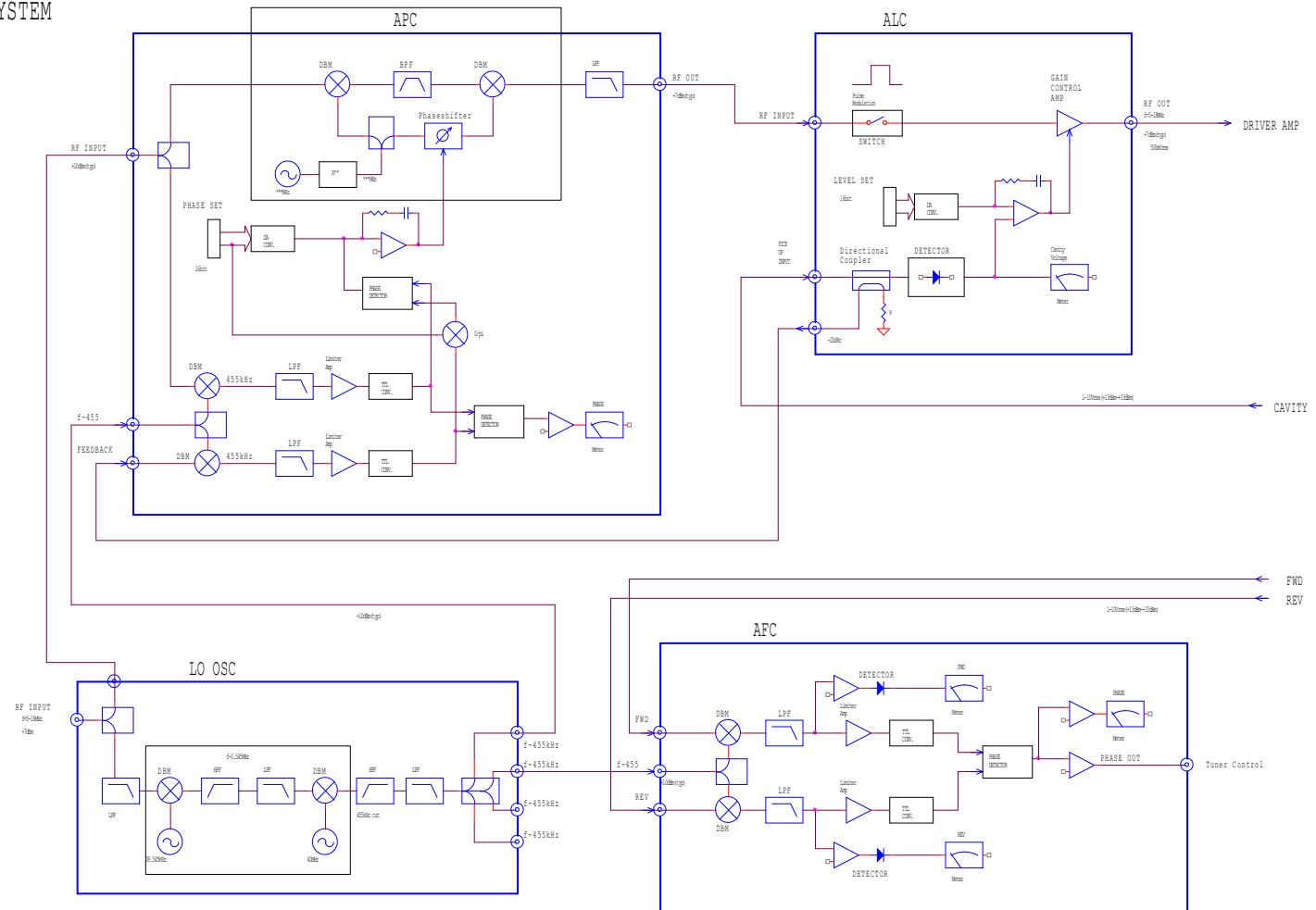


LLRF System for Cyclotrons



- Details

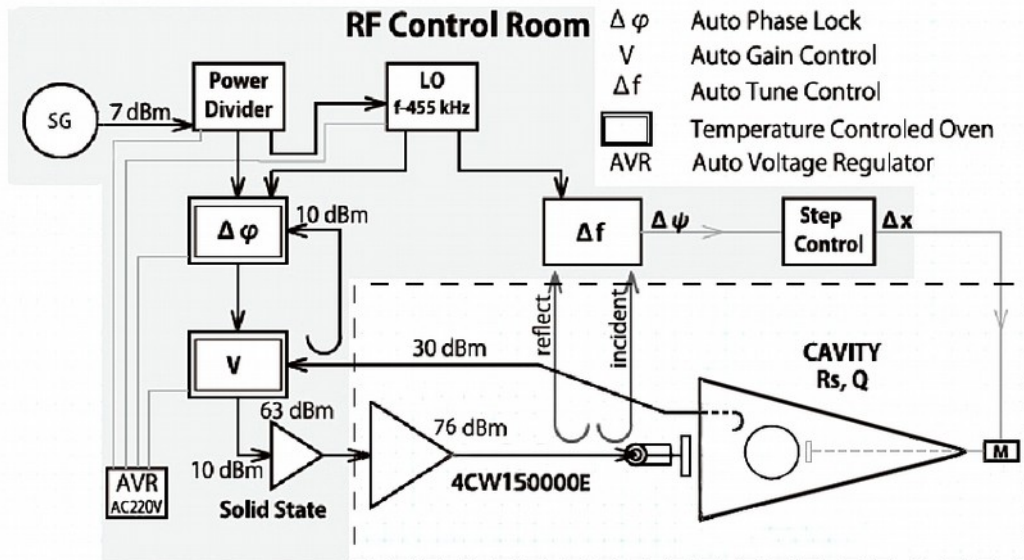
LOW LEVEL SYSTEM



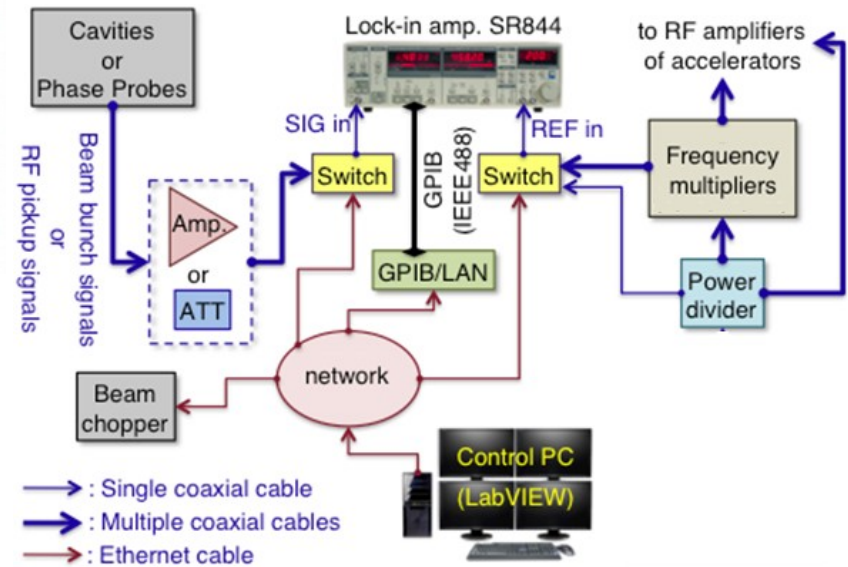
LLRF System for Cyclotrons



- One master oscillator for all cavities
- Analogue feed back
- Temperature controled oven



Functional Diagram of Analog LLRF system



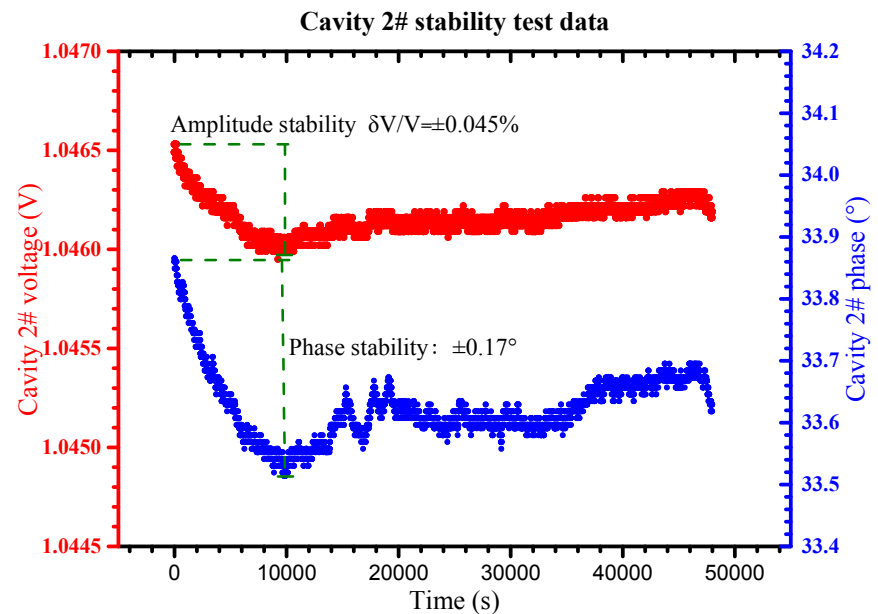
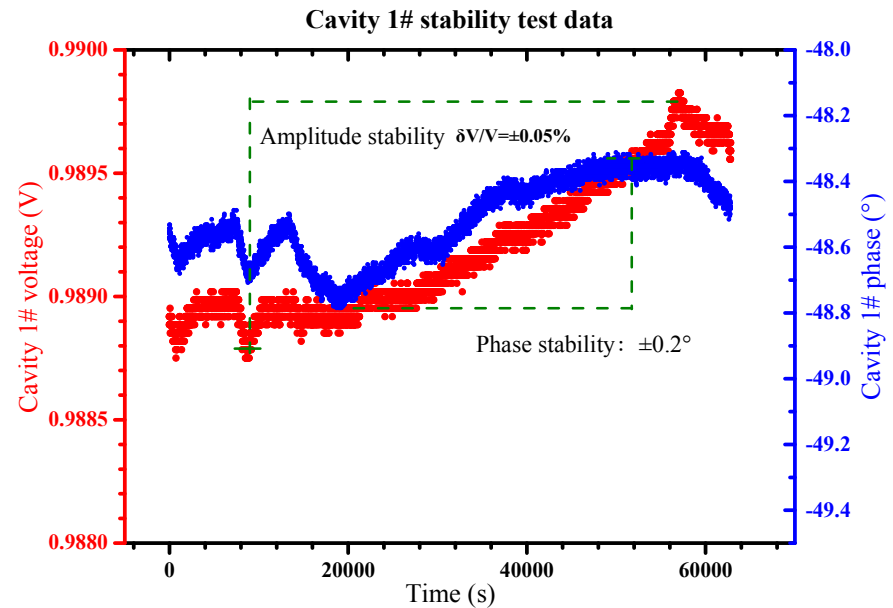
Monitoring system of rf and beam stability based on Lock-in Amp.

LLRF System for Cyclotrons



RF system parameter

Resonant Frequency	31.02MHz
Dee Voltage	60-80KV
Dee Angle	33°
Extraction Radius	750mm
Injection Radius	35mm
Phase Stability	$\leq \pm 0.5^\circ$
Amplitude Stability	$\leq 1 \times 10^{-4}$
Frequency Stability	$\leq 1 \times 10^{-6}$
Magnet	
Magnet Coil	~300kAT
Maximum magnetic field	2.75T
Magnet Weight	~90 tons



LLRF System for Synchrotrons



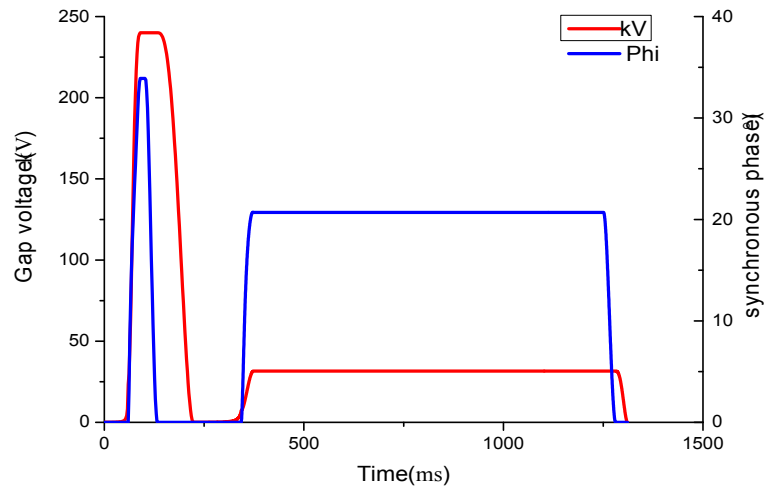
Requirements of the LLRF System

- Regulate the amplitude and phase
- Beam Loading Compensation
- Adjust phase between different cavities
- Synchronous phase control
- Adjust the working frequency according to BPM signal
- All digital system
- Base cPCI Bus

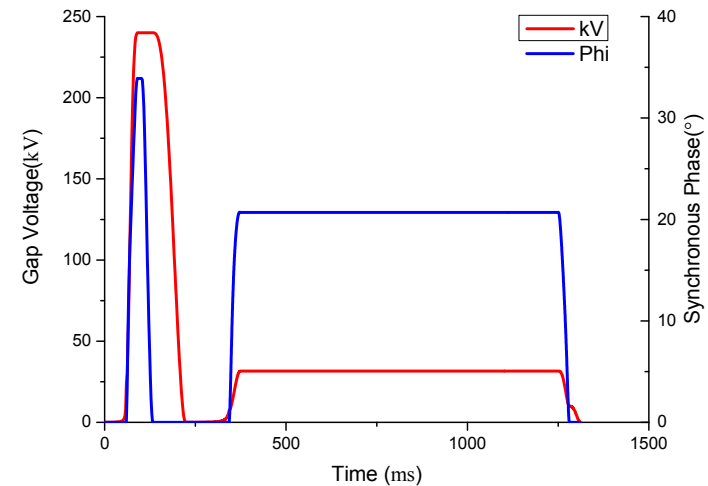
LLRF System for Synchrotrons



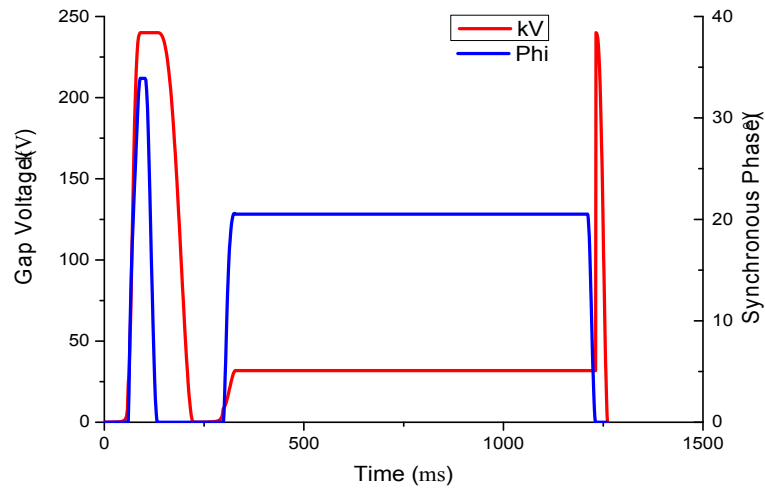
● BRing-gap voltage waveform



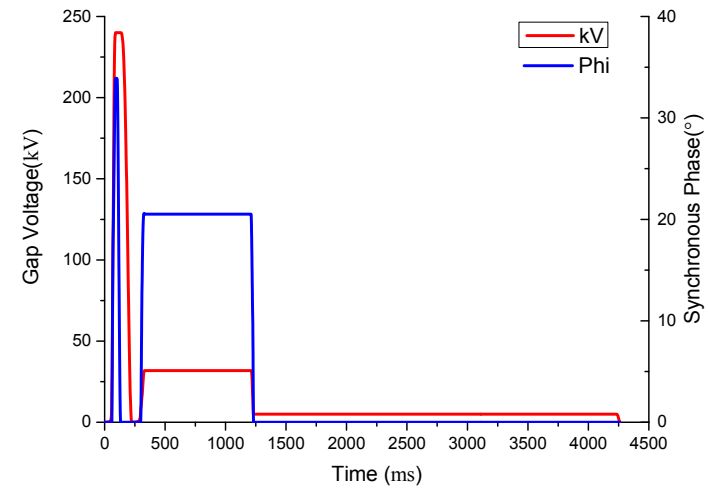
Conventional beam acceleration



Momentum spread adjustment



Bunch rotation



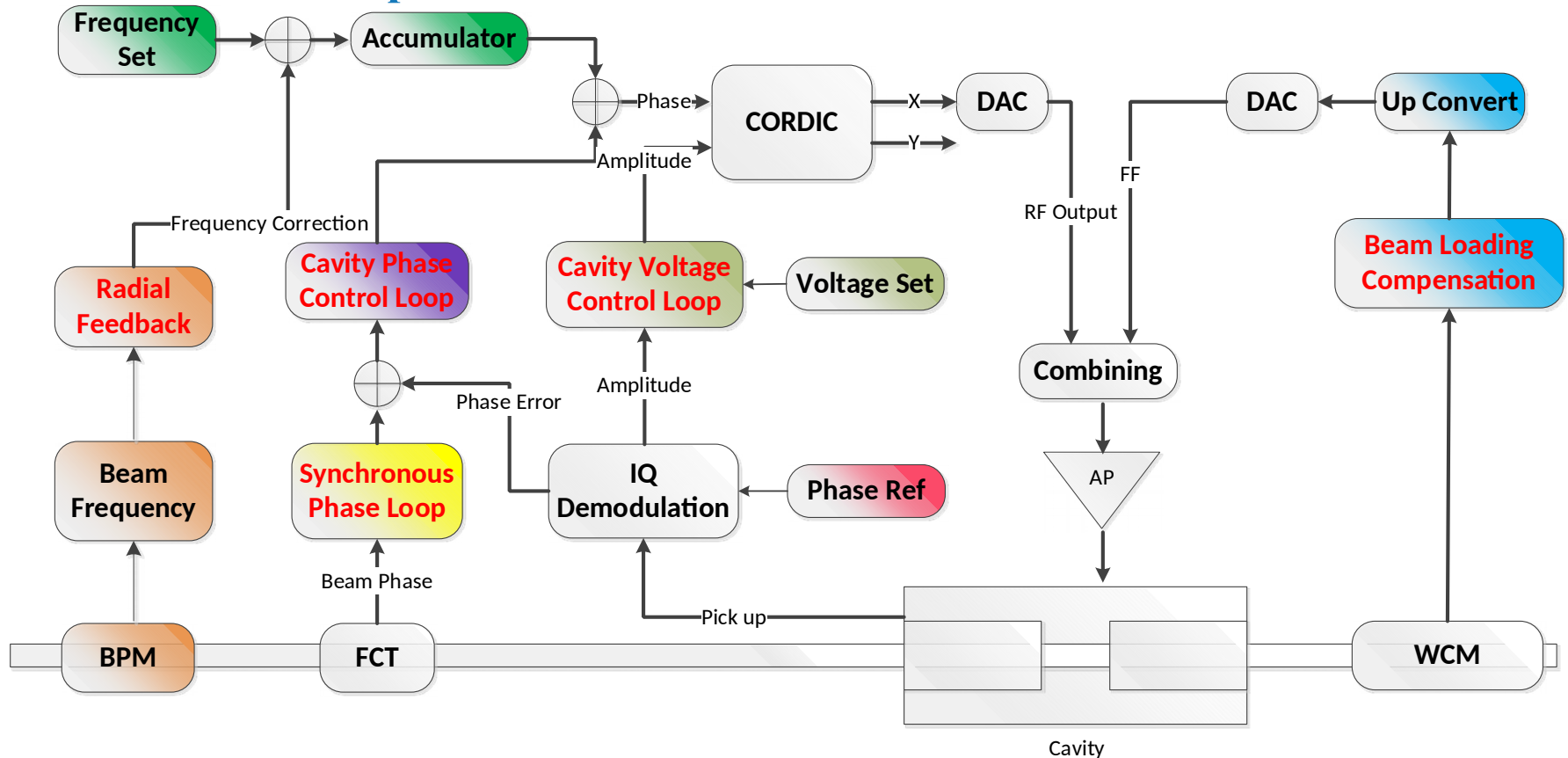
Bunch length manipulation

LLRF System for Synchrotrons



- LLRF System of Spring and Bring

Multi-control loops of the LLRF

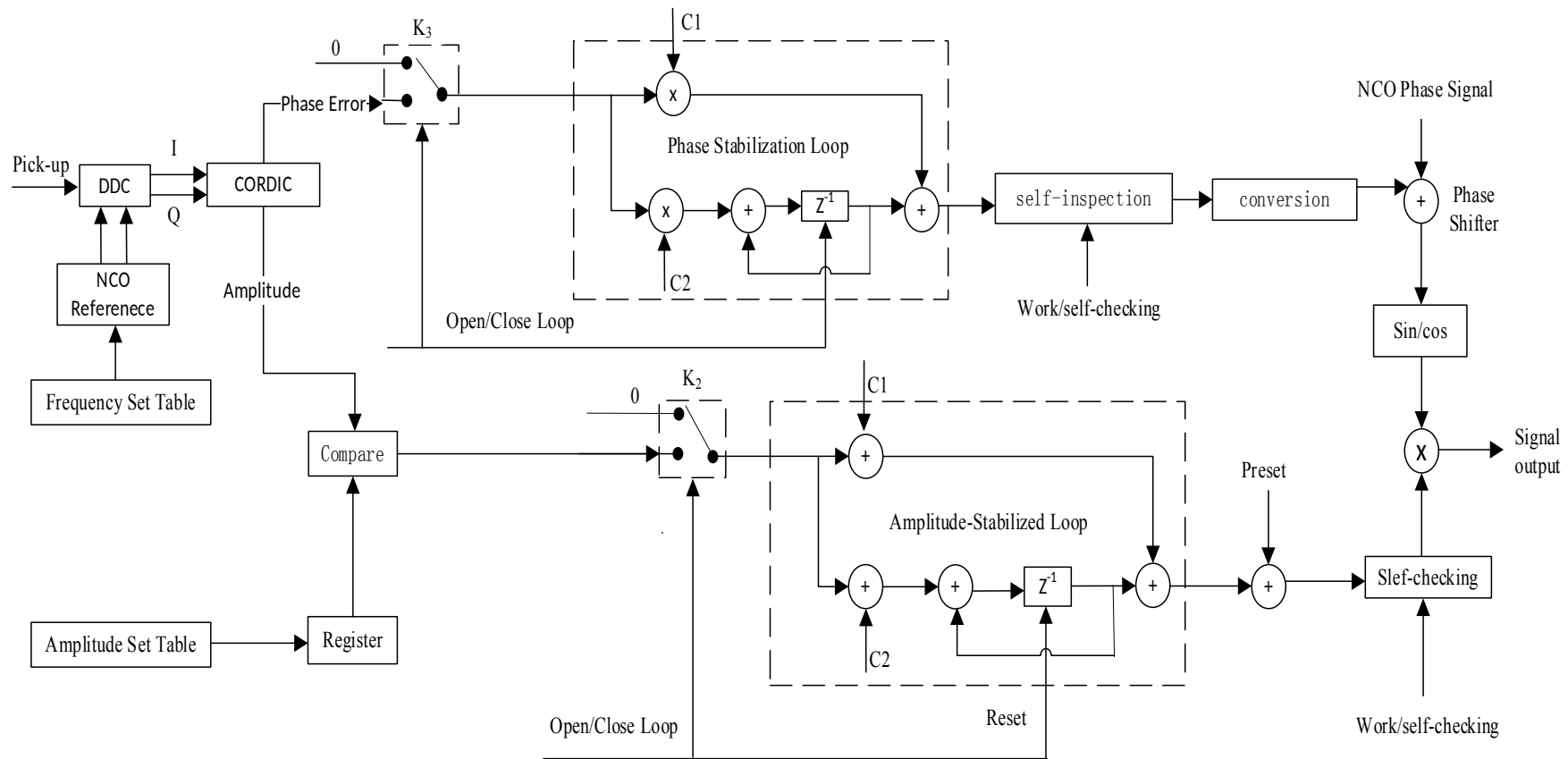


Principle Diagram of the Multi-Control Loops

LLRF System for Synchrotrons



● LLRF System of Sring and Bring

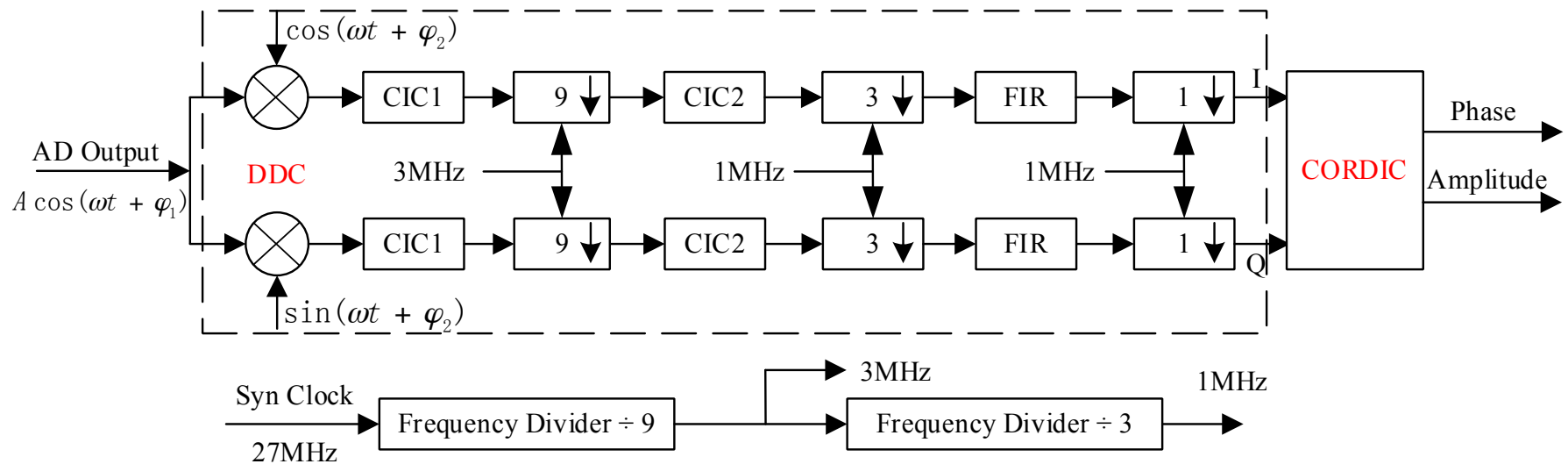


Principle Diagram of Phase/Amplitude stabilization Loop

LLRF System for Synchrotrons



- LLRF System of Spring and Bring



Principle Diagram of Demodulation and Digital Down Convert

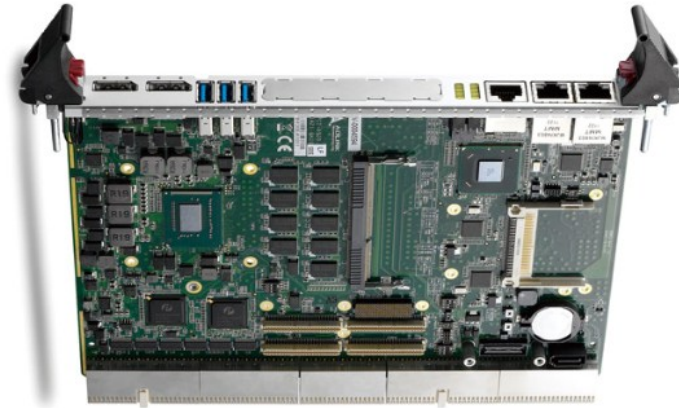
LLRF System for Synchrotrons



● LLRF System of Spring and Bring

Hardware

- 6U 8-slot CompactPCI
- PICMG2.5 H.110 CT Bus
- PICMG2.1 Hot Swap compliant 64-bit
- backplane with P3 & P5 rear I/O
- Dual AC power inlets



cPCI-6520



cPCIS-6418U

- The 3rd generation Intel Core i7
- Dual channel DDR3 ECC memory
- Three independent displays
- USB 3.0 and PCI Express Gen3 support
- Remote management and optional TPM support

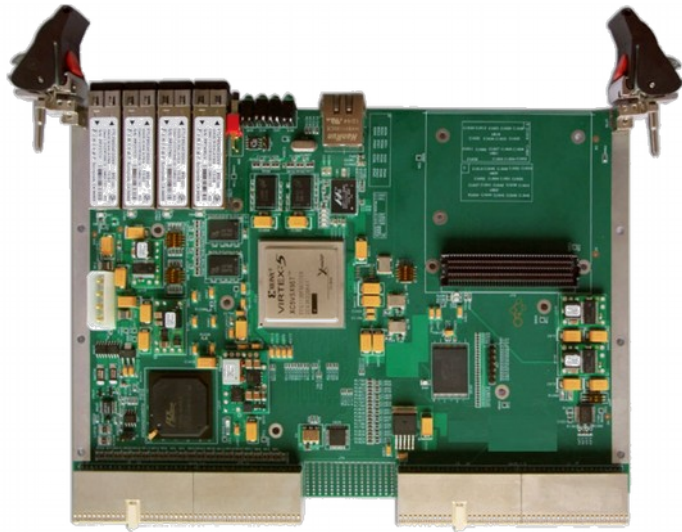
LLRF System for Synchrotrons



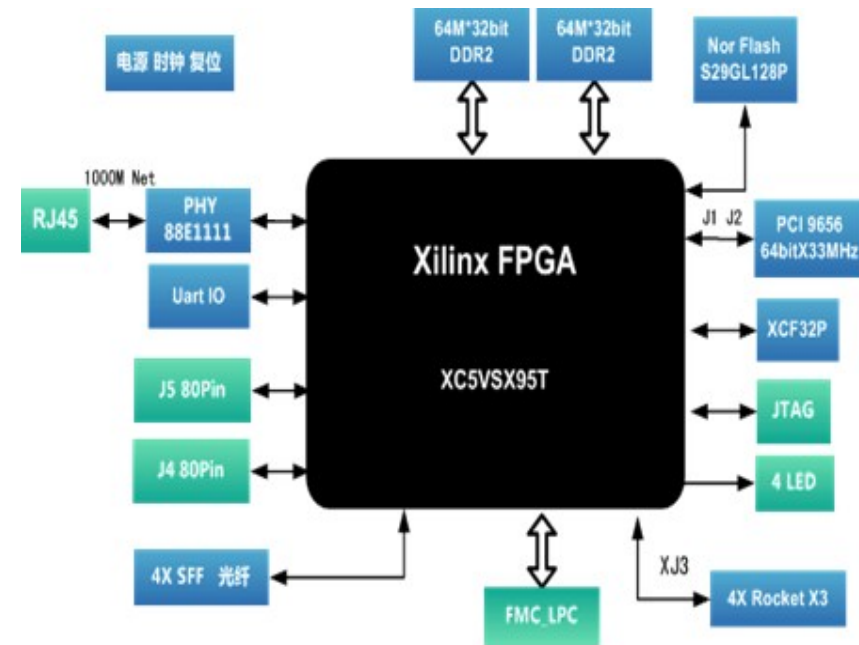
● LLRF System of Sring and Bring

Hardware

- Xilinx XC5VSX95T-1FF1136
- Configurable Logic Blocks 160 x 46
- Max Distributed RAM 1,520Kb
- DSP48E 640, CMT 6, IObank 20



Main Board



Main Board Block Diagram

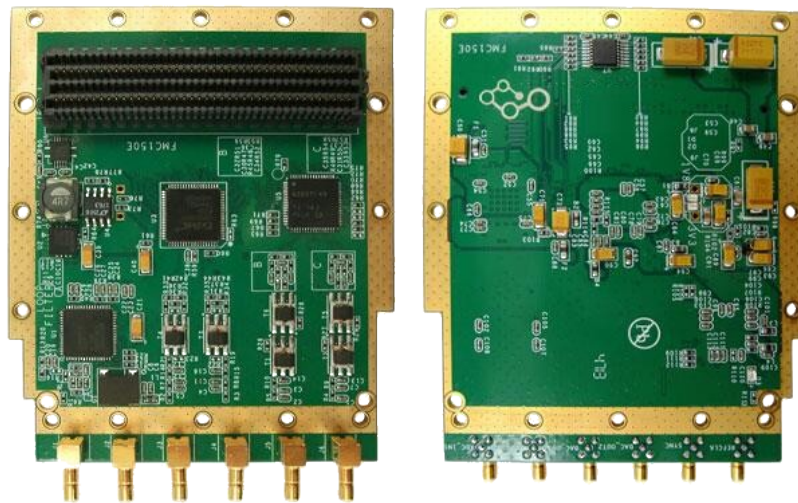
LLRF System for Synchrotrons



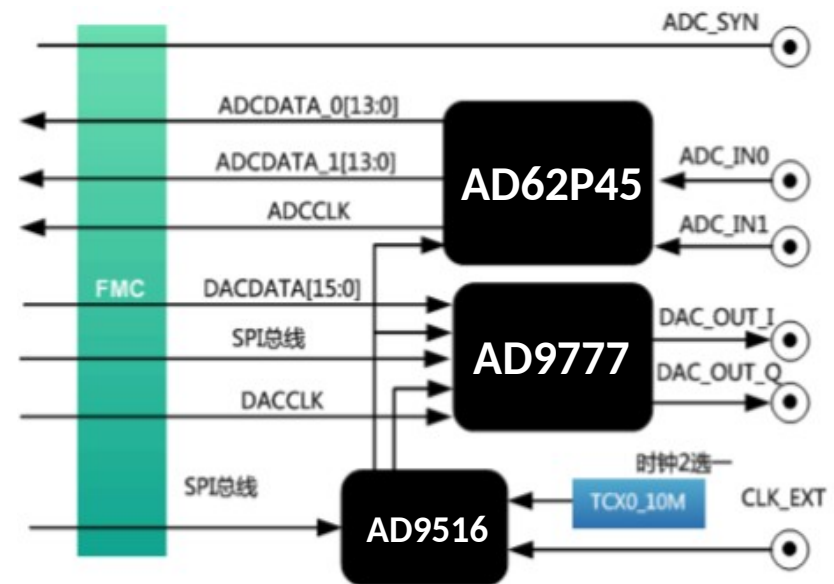
● LLRF System of Spring and Bring

Hardware

- FMC interface
- 2CH, 14bit, 125MSPS, AD62P45, ADC
- 2CH, 16bit, 160MSPS, AD9777, DAC
- AD9516 clock chip



ADC/DAC Board



ADC/DAC Block Diagram

LLRF System for Synchrotrons



● LLRF System of Spring and Bring

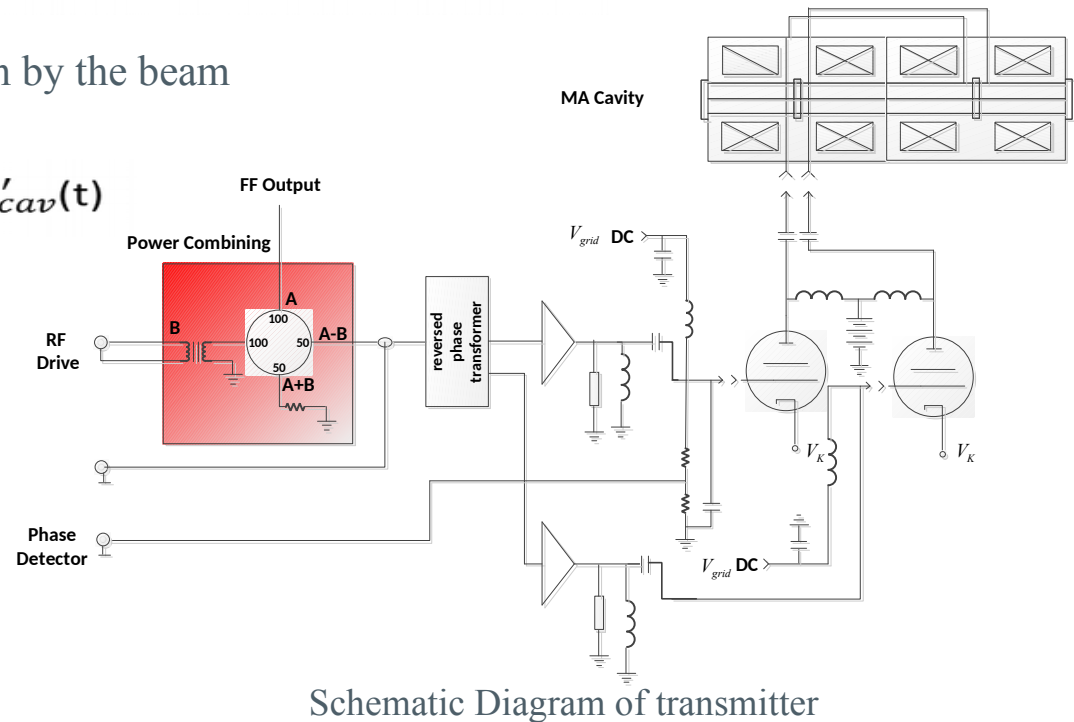
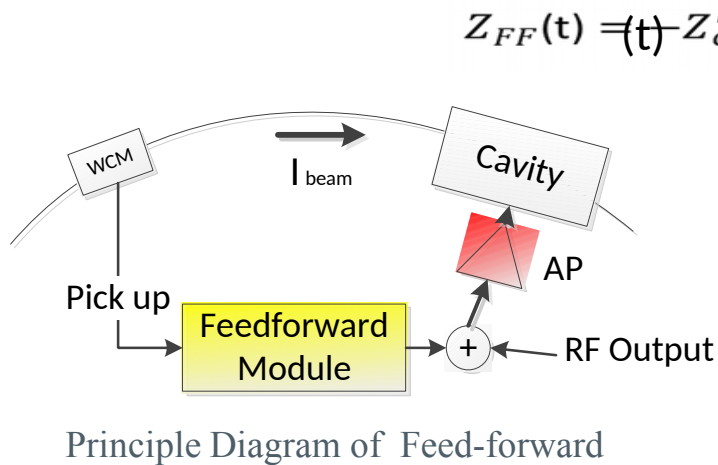
Challenge

- Beam loading compensation

$$V_{cav}(t) = V_{cav,dr}(t) + V_{cav,wake}(t) + V_{cav,FF}(t)$$
$$= H_{dr}^{cav}(t) \cdot V_{dr}(t) + Z'_{cav}(t) \cdot I_{beam}(t) + Z_{FF}(t) \cdot I_{beam}(t)$$

$Z'_{cav}(t)$ is the impedance seen by the beam

- Feed-forward

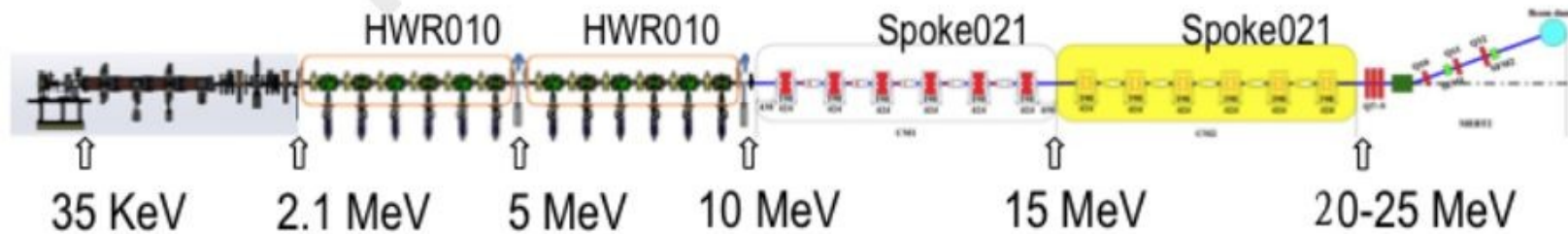
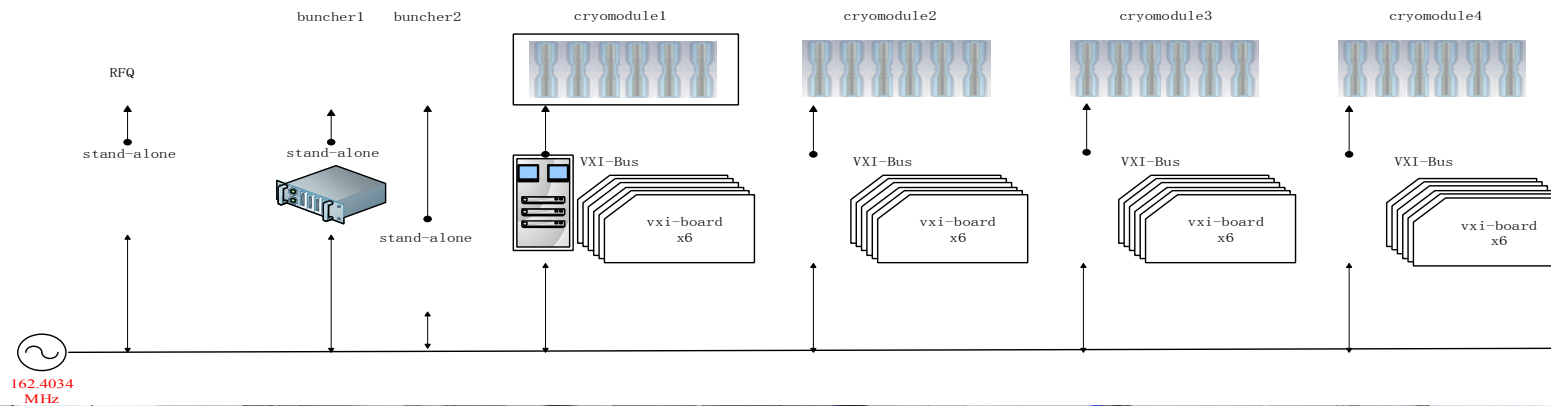


LLRF System for ADS



Injector Parameter

Extract energy :25MeV Beam intensity 10mA@CW



LLRF System for ADS



Required functions:

- Cavity field control
- Cavity resonance control
- RF reference generation and distribution
- HPRF protection

Table 1 : LLRF specifications

Frequency	162.5MHz
Operation mode	CW/Pulse
Amplitude stability	0.3%
Phase stability	0.3°
Tuning	$\pm 1^\circ$

- **work mode:**

normal mode: On the startup, work in Pulse mode to train the cavity, then switch to CW mode

commissioning mode: To avoid high radiation levels, during the commissioning of the machine, work in pulse mode

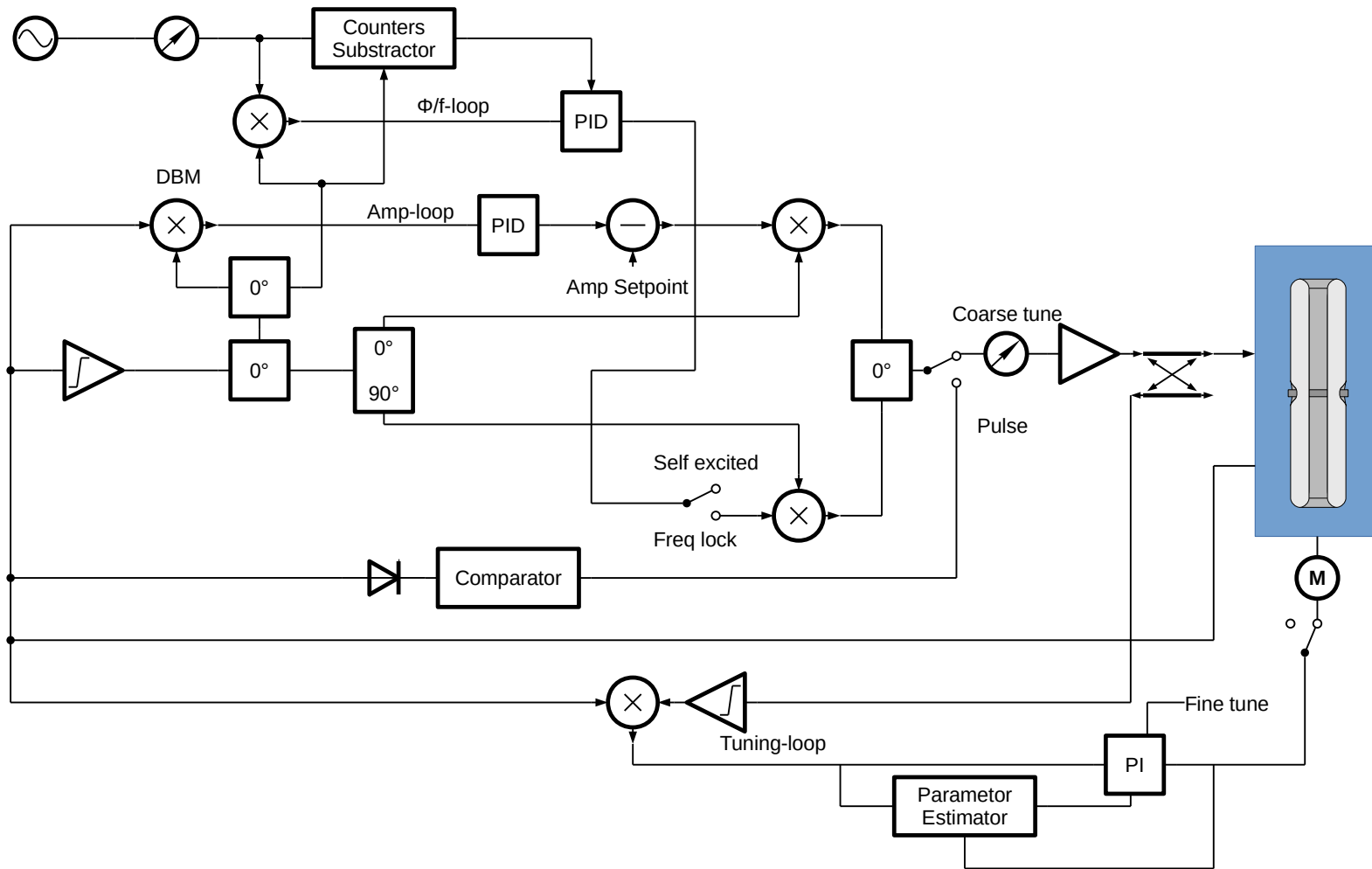
Self-Exited Loop

- **special for RFQ:**

Due to poor cooling system, heat detunes the cavity, On the startup LLRF takes self-exited loop to follow the resonance frequency of the cavity

Once the RFQ has achieved steady operation, frequency change to MO (GDR)

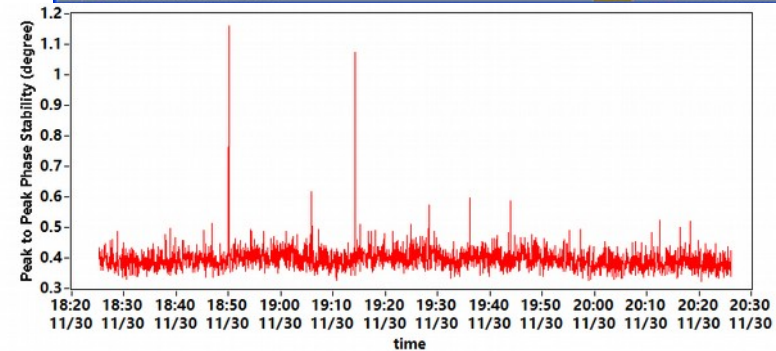
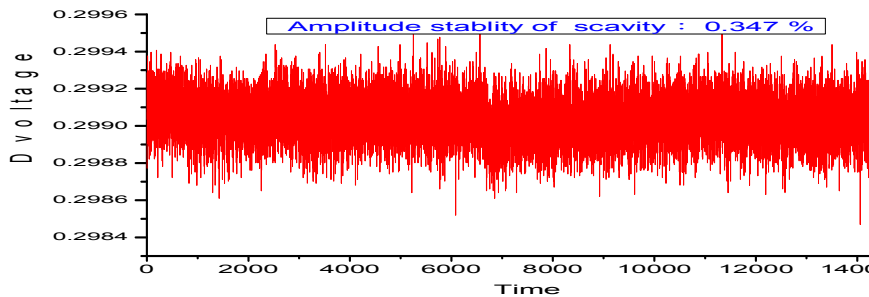
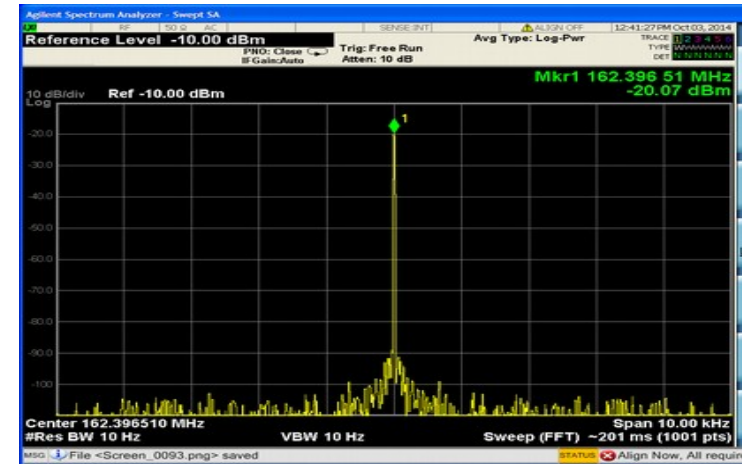
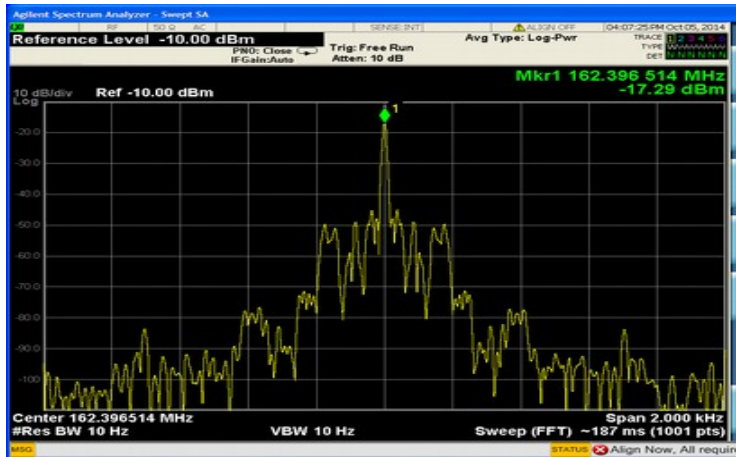
LLRF System for ADS



LLRF System for ADS

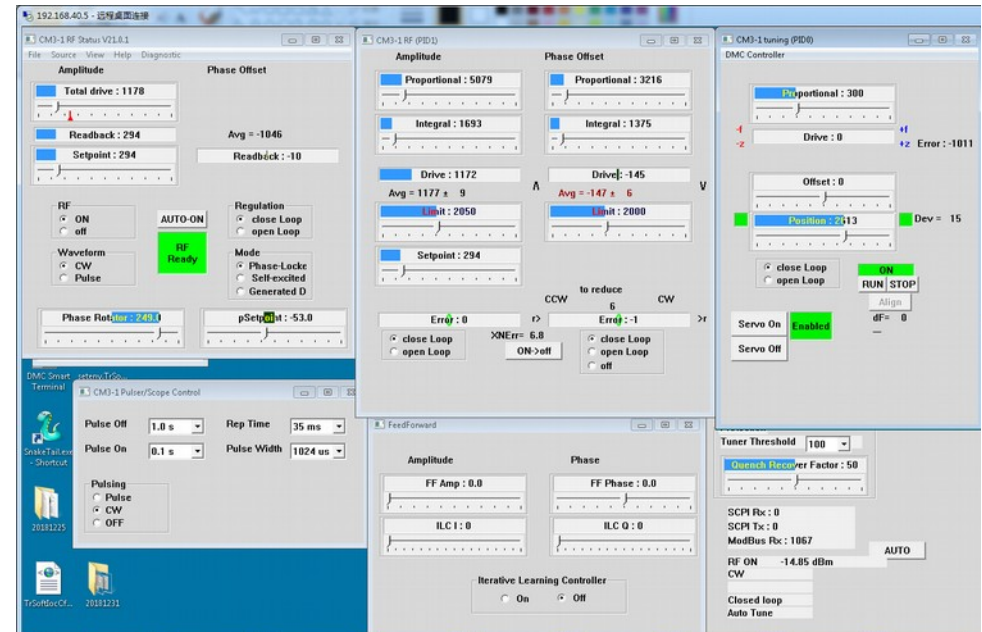


10MeV with beam test result:



Test Results : Amplitude stability 3.5% , Phase stability: $\pm 0.4^\circ$. ADS LLRF operating over 5000 Hs

LLRF System for ADS



射频超导系统运行监测界面 2019/06/21 19:58:05.359

Channel	环流状态&RF开关	联锁准加	Epk(MV/m)	相位*	腔体幅度误差	腔体相位误差	CM1	环流状态&RF开关	联锁准加	Epk(MV/m)	相位*	腔体幅度误差	腔体相位误差
CM1-1	🟢	🟢	7.8	20.1	0	2	CM1-4	🟢	🟢	20.5	138.0	-1	0
CM1-2	🟢	🟢	17.4	-3.3	0	24	CM1-5	🟢	🟢	16.9	-41.2	-1	0
CM1-3	🟢	🟢	9.6	-107.2	0	0	CM1-6	🟢	🟢	19.5	105.7	0	-3
CM2-1	🟢	🟢	25.0	70.3	0	22	CM2-4	🟢	🟢	27.9	81.3	-1	2
CM2-2	🟢	🟢	27.5	-86.7	-1	0	CM2-5	🟢	🟢	22.9	-59.0	-13	42
CM2-3	🟢	🟢	32.5	105.6	2	-1	CM2-6	🟢	🟢	34.0	21.8	8	-79
CM3-1	🟢	🟢	13.0	-53.0	0	2	CM3-4	🟢	🟢	28.2	-176.7	0	6
CM3-2	🟢	🟢	25.9	-2.6	-1	6	CM3-5	🟢	🟢	25.4	13.2	2	6
CM3-3	🟢	🟢	28.5	-130.1	2	8							
CM4-1	🔴	🔴	0.0	90.0	100.0	-17.1	CM4-4	🔴	🔴	0.0	119.6	100.0	-48.9
CM4-2	🔴	🔴	0.0	-105.9	100.0	-139.4	CM4-5	🔴	🔴	0.0	-180.0	100.0	-40.6
CM4-3	🔴	🔴	0.0	-90.0	100.0	-137.7	CM4-6	🔴	🟢	0.0	-153.8	99.8	-159.4

Buncher1

READY 🔴

AMP 22480.00

PHASE 44.17

VACC 104.54

PW_IN 3.69

PW_RE 0.67

AMP_SET 23900

PHASE_SET 51.3

Buncher2

READY 🟢

AMP 12806.00

PHASE 131.37

VACC 114.54

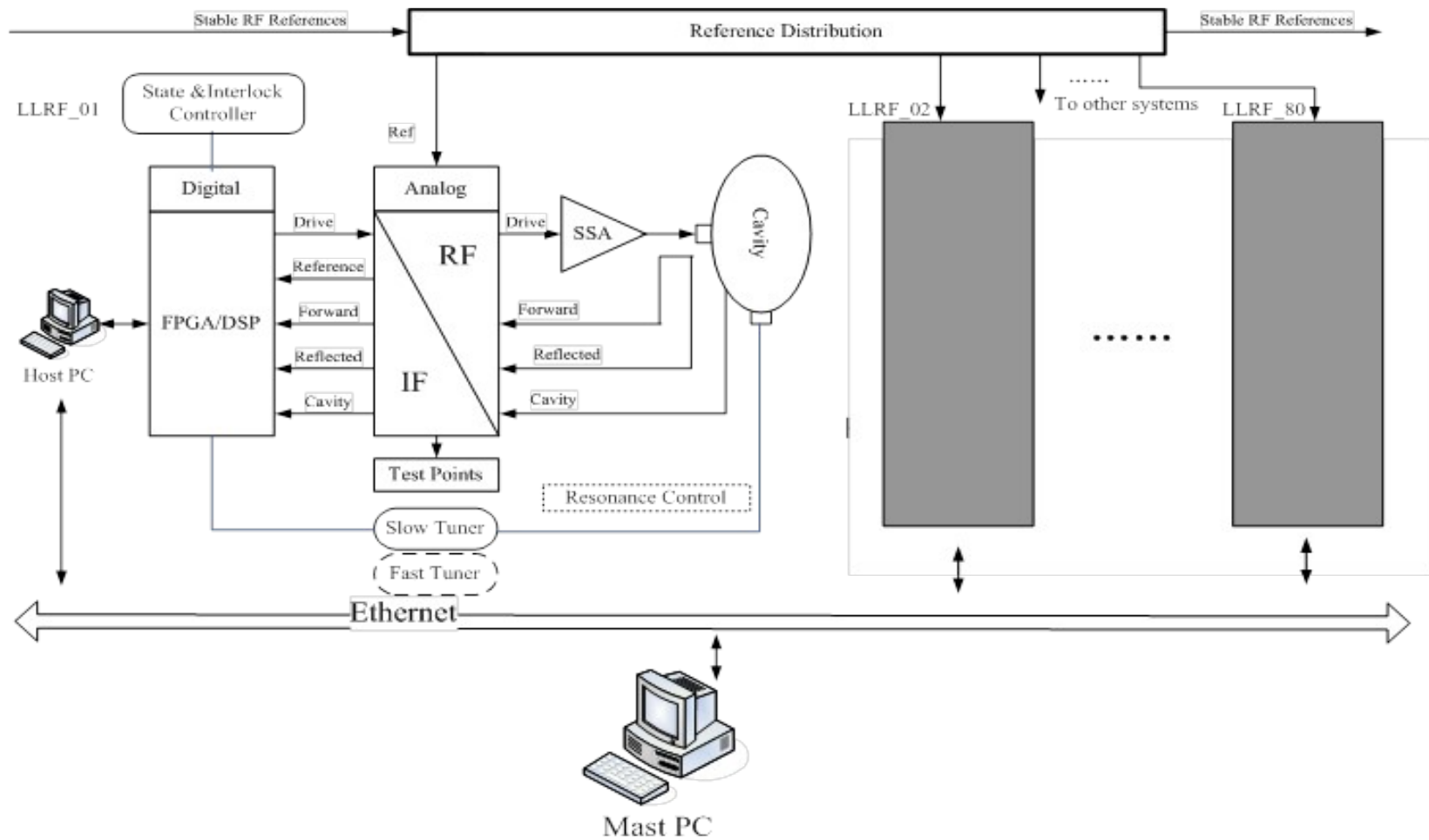
PW_IN 4.78

PW_RE 0.21

AMP_SET 12738

PHASE_SET 133.4

Prototype LLRF System



LLRF System for ADS



clocks distribution

RF 162.5MHz

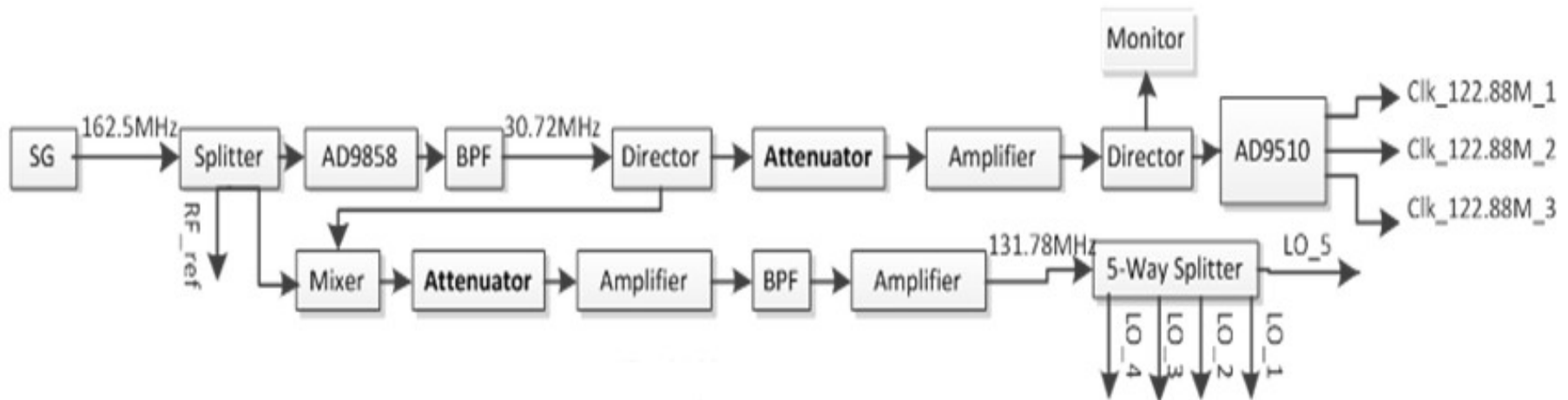
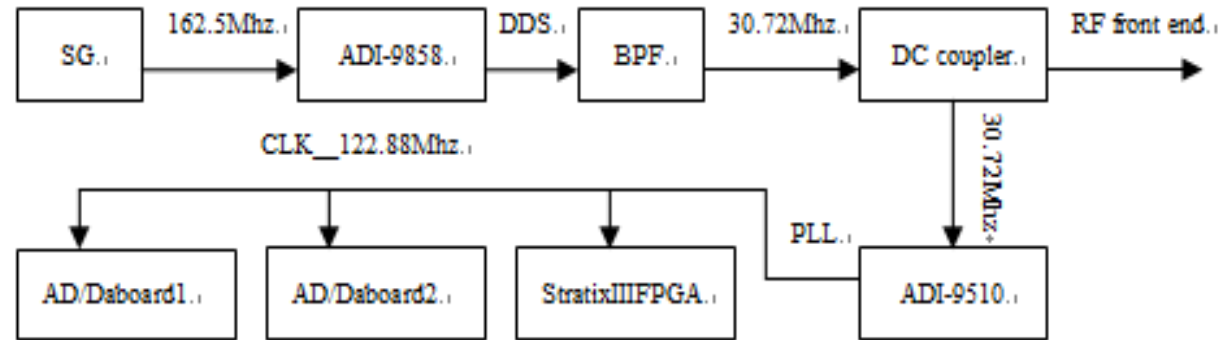
IF: 30.72MHz

LO: 131.78MHz

ADC: 122.88MHz

DAC: 122.88MHz

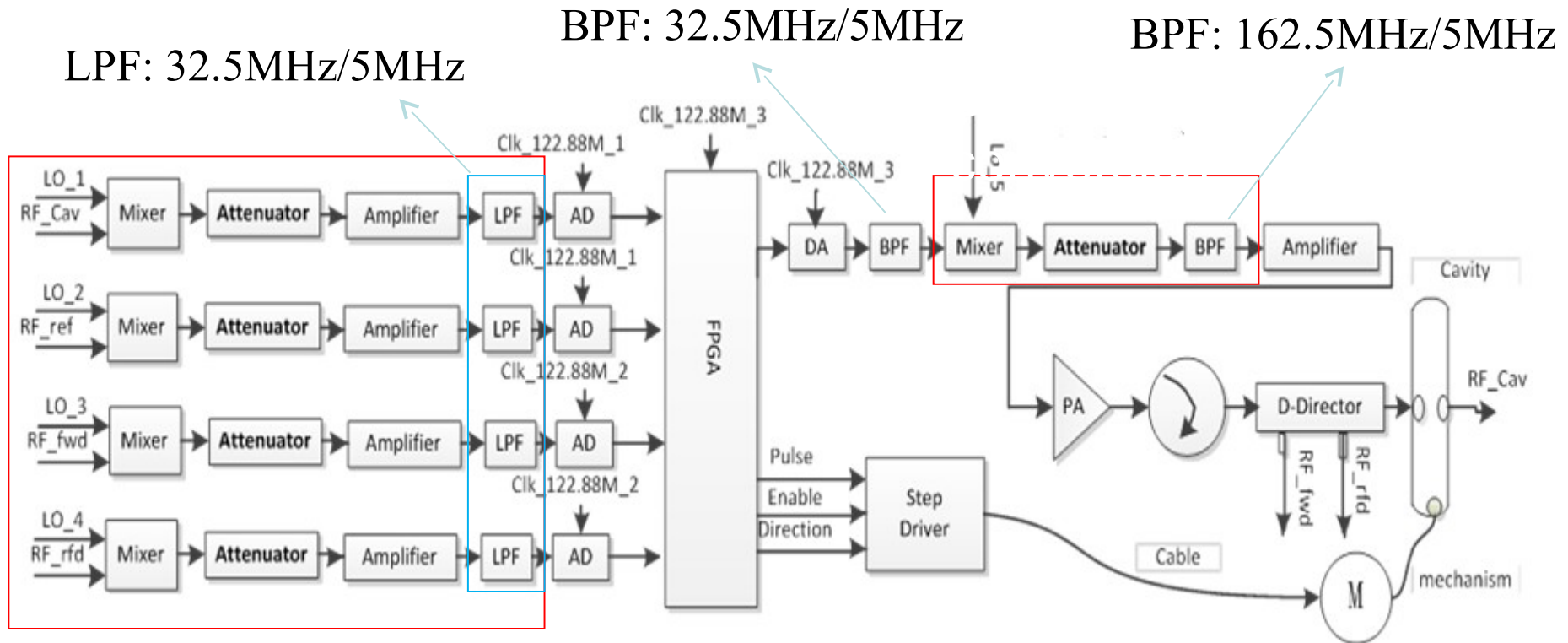
FPGA: 122.88MHz



LLRF System for ADS

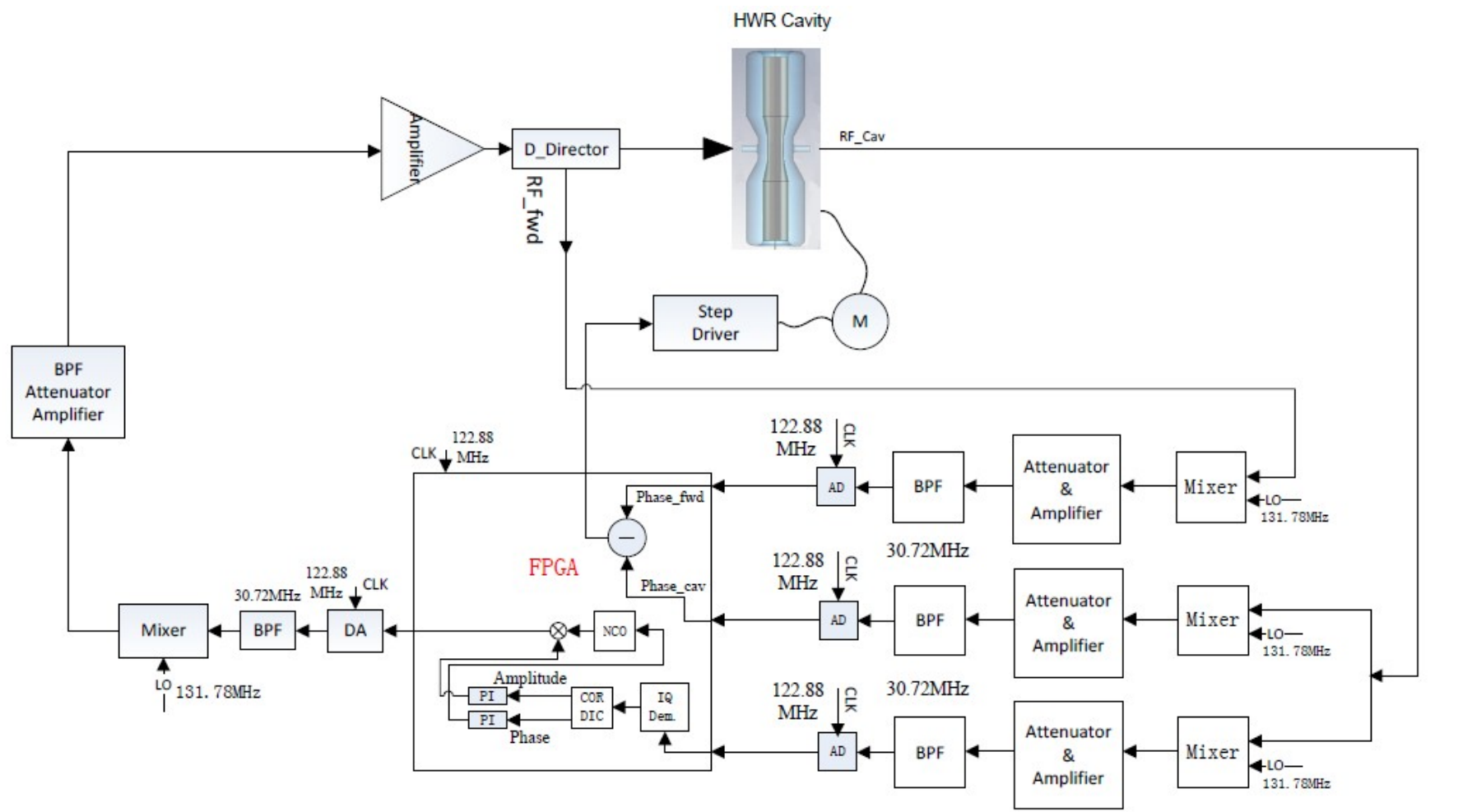


Frequency Conversion



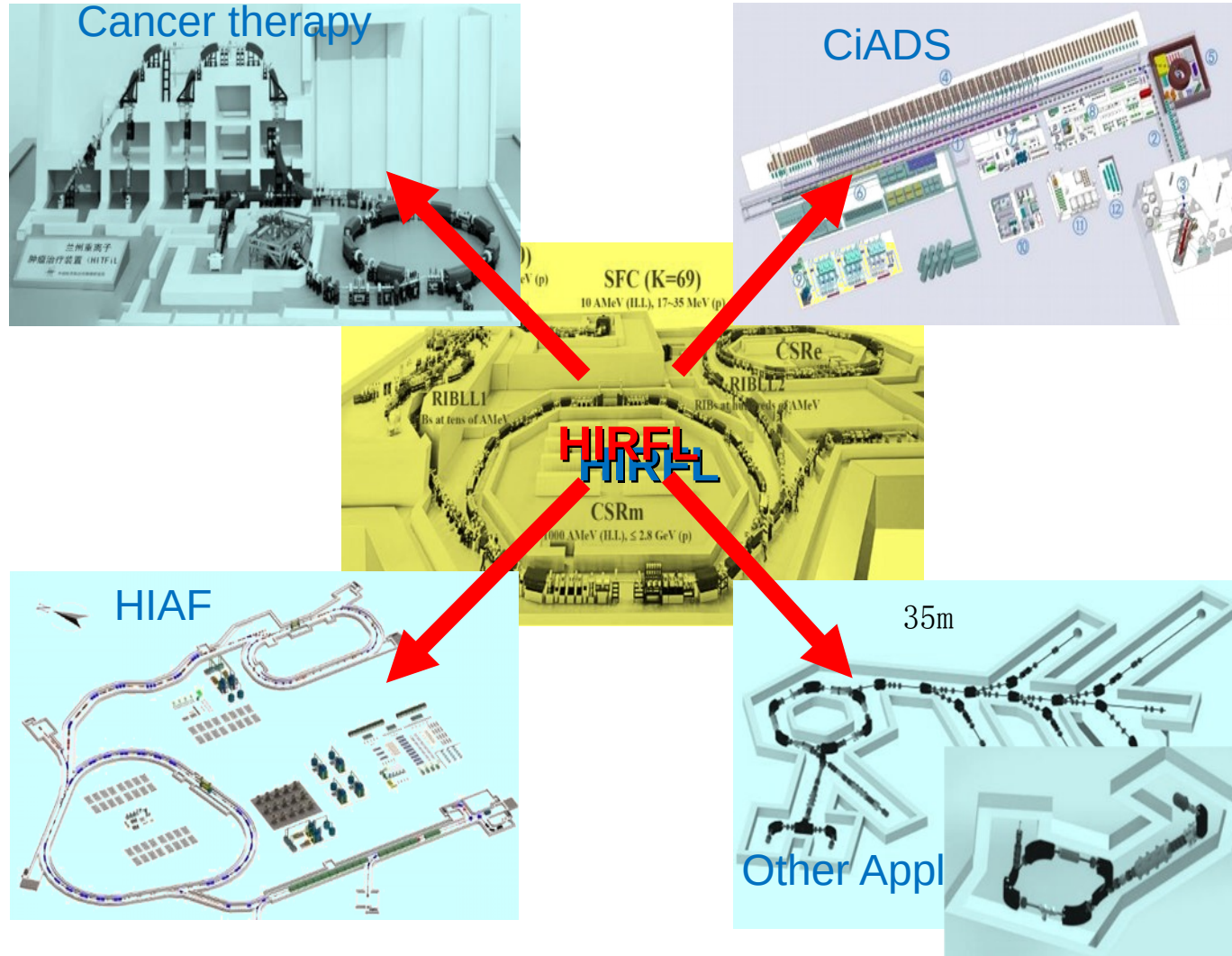
Mixer: **ZMY-2+** Mini-Circuit

LLRF System for ADS



- IMP Facilities Introduction
- LLRF Systems in IMP
 - Cyclotrons LLRF
 - Synchrotrons LLRF
 - ADS Linac LLRF
 - Prototype LLRF
- Future Projects
 - HIAF
 - CiADS
 - ...

Recent and future projects based on HIRFL



- Universal Hardware
 - LLRF
 - Timing system
 - Beam diagnostic system
 - Data acquisition system
 - ...
- Backplane bus standard
 - mTCA
 - PCIe
 - ...

- LLRF Activities in IMP:
- Cyclotrons LLRF (SFC, SSC)
 - Adopted analog circuit
 - consists of Phase stabilizer, amplitude controller and tuning controller.
- Synchrotrons LLRF (CSRm, CSRe)
 - The low level control system aims to realize the adjustment and stability of rf acceleration voltage, synchronization of acceleration voltage and beam phase, rf frequency correction, beam load feedforward and feedback and other control functions to ensure the stable operation of rf system in accordance with physical requirements.
- ADS linac LLRF
 - To control the cavity to work in the resonance state under the condition of large beam load and strong Lorentz force detuning to reducing the rolling fluctuation. The effects of temperature, cavity deformation and noise on the tuning process.



Thanks for your attention!