



LLRF Solutions of MicroTCA Technology Lab

Cagil Gumus
24/06/2019

Outlook

1. Our background in LLRF
2. Generic LLRF Control System Overview
 - Hardware
 - Firmware
 - Software + User Interfaces
3. Current LLRF Projects
 - Turkish Accelerator and Radiation Laboratory (TARLA)
 - Nuclotron-based Ion Collider Facility (NICA)



MicroTCA Technology Lab

- Close collaboration with largest LLRF Control Group in the world
 - >60 FTE (~25 FTE for LLRF)
- MSK Responsibilities;
 - LLRF Control Systems for Accelerator Structures
 - Special Diagnostic Devices
 - Beam Stabilization Systems (transversal/longitudinal) in storage rings & linacs
 - Timing for pre-accelerator systems



RF Control

- Amplitude (rms) stability of **0.01%**
- Phase (rms) stability of **0.01°**
- Any arbitrary pulse shape to CW RF operation
- Low latency (<2us) control loop on FPGAs
- MIMO + P controller for fast RF Feedback
- Realtime Q_i and detuning calculation
- Fast RF gating with external or internally generated interlock
- Single cavity or multicavity (vector sum) regulation options
- External timing synchronization available (**Whiterabbit & MRF possibilities**)

Resonance Control Specs

- Motor controller/driver FMC solutions available
- Piezo control/sensor on DRTM-PZT4
- Fast feedback on Piezo actuation using cavity information
- Advanced microphonic compensation techniques

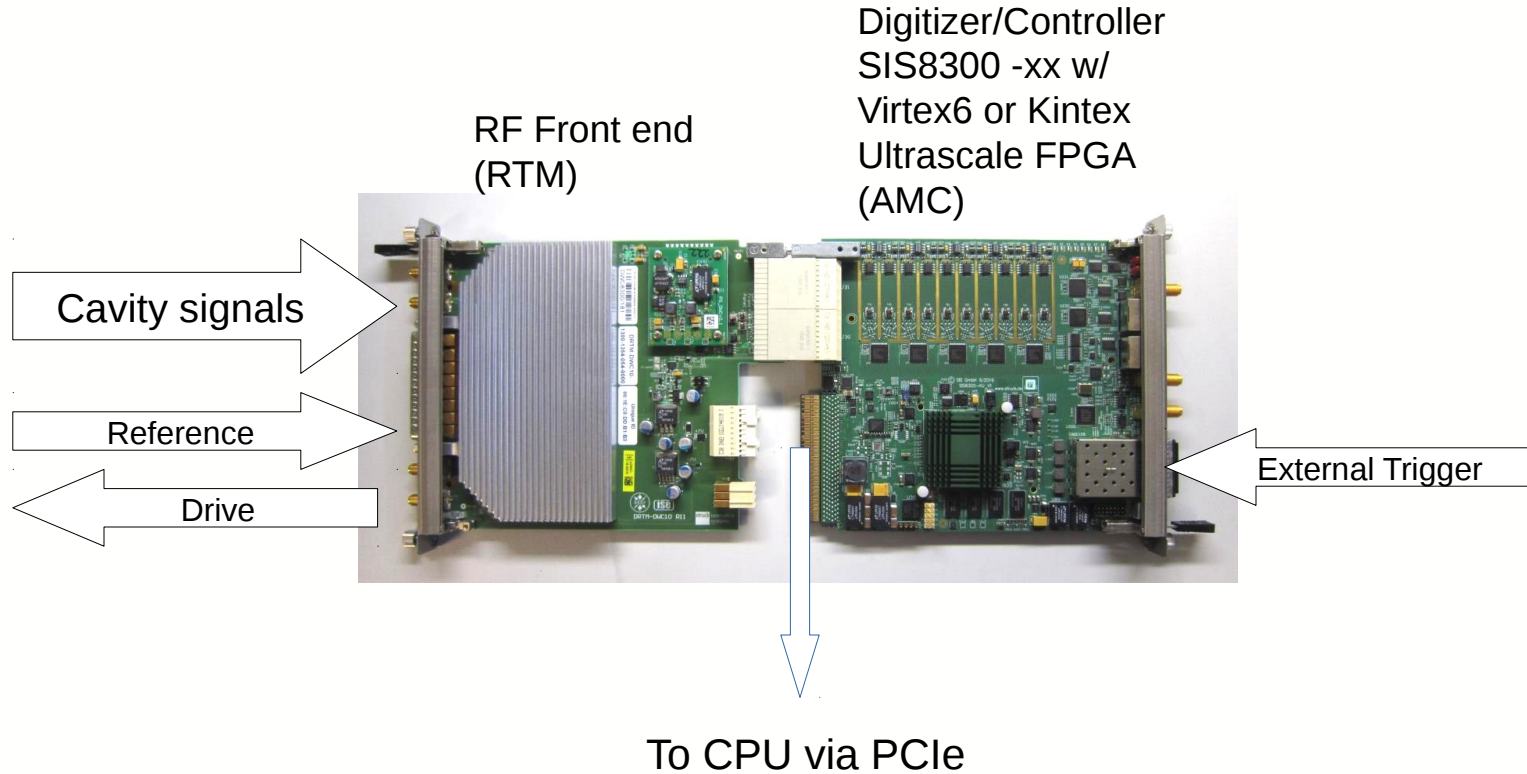


Starter LLRF Setups are now available!

[1] Picture taken from: vadatech.com

[2] Picture taken from: schroff.nvent.com

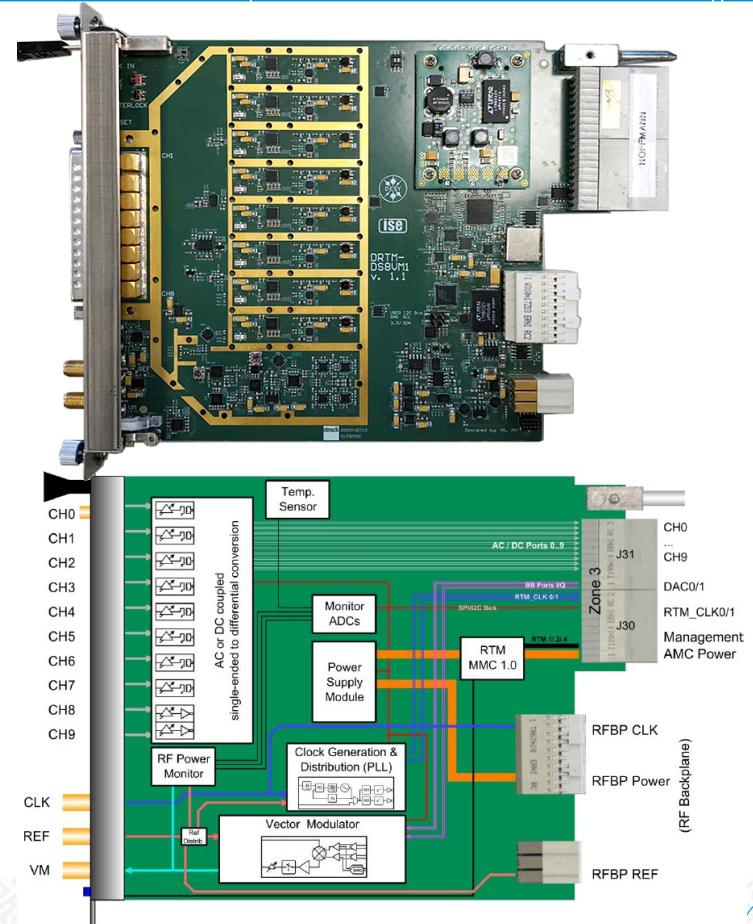
Example LLRF Control using MicroTCA.4



DRTM-DS8VM1

RF Front-end:

- 8 analog input channels (5 to 700 MHz) with phase resolution of 0.05° at 700MHz
- 2 analog input channels (DC to 400 MHz) with phase resolution of 0.05° at 400MHz
- One high frequency vector modulator channel (0.05 to 1.0 GHz) with modulation bandwidth from DC to 50 MHz
- Ultra-low jitter clock generation using on-board PLL
- Board was designed by DESY and is licensed to and produced by Struck



DRTM-DWC8VM1

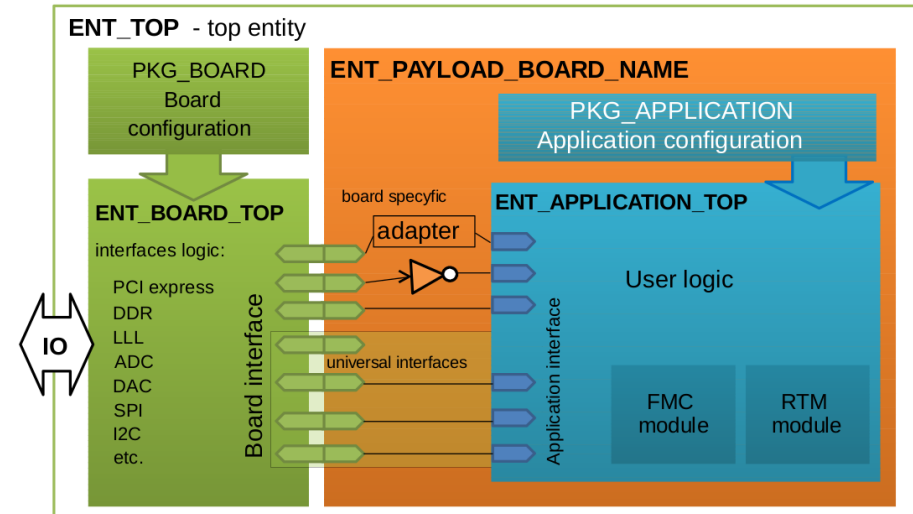
RF Front-end:

- Input frequency range: L and S Band
- Output frequency range: L, S and C Band
- Short term amplitude stability 0.003% in the range 10 Hz – 10 MHz at 1.3 GHz
- Short term phase stability 4 fs in the range 10 Hz – 10 MHz at 1.3 GHz
- Board was designed by DESY and is licensed to and produced by Struck



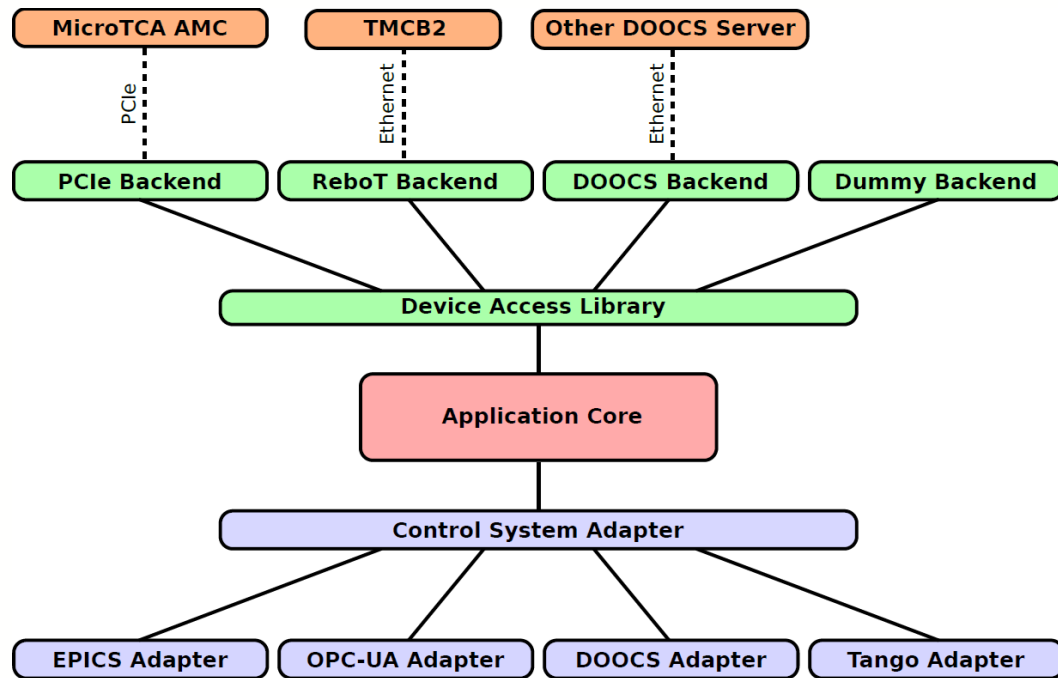
FPGA Firmware Framework

- **547,769** Lines of VHDL code accumulated over 15 years
- Maintained by DESY + other Helmholtz Labs
- Abstraction between board and application level + modular approach
 - >90% of similar code across different projects
- IP-core approach → Easy integration to your custom solution





- Abstraction layer between specifics of underlying system
- Same code for all facilities
- Hooking the server to many different control systems
 - EPICS,
 - OPC-UA,
 - DOOCS,
 - TANGO
 - <insert_your_control_system>



SC2_2 LLRF Expert Panel

Overall Status: ■

Detailed View

Server Status:
Manual Mode

Exit Manual Mode

MicroDAQ: Off

Cavity and Pulse Parameters

RAW ADC

Forward ■

Reflected ■

Probe ■

CH3 ■

CH4 ■

CH5 ■

Reference ■

VMMonitor ■

SetPoint

Amplitude: $\uparrow \downarrow$ 1 0 0 0 0

Phase: $\uparrow \downarrow$ 0 0 0 0 0

VectorSum

FeedBack OFF

Feedback

MIMO Parameters enable

P Controller Gain: 0.002

Feedback Limit: 1000 digits

Feedforward

FeedForward ON

Controller Output Limit: 200 MV

Amplitude Scaling: $\uparrow \downarrow$ 1

Phase Rotation: $\uparrow \downarrow$ 0

via Amplifier and Cavity → **Vector Modulator**

XLLRF_RF-station_expert.xml XFEL_RF/LLRF.CONTROLLER/A25.L3/

Module 1

c1 c2 c3 c4 c5 c6 c7 c8

185.3
8.93

PVS

Module 2

c1 c2 c3 c4 c5 c6 c7 c8

190.2
13.06

PVS

Module 3

c1 c2 c3 c4 c5 c6 c7 c8

184.7
12.97

PVS

Module 4

c1 c2 c3 c4 c5 c6 c7 c8

0.00
0.00

PVS

560.0 MV
0.00 deg

VS

ERR

Beam based Feedback

FF

FFC

LFF

BLC

DAC offset

COUT

OVC

Mlystron

Toroid

Legend

- Status Ena
- Signal flow
- Monitor tap
- Plot/Panel

FF	SP	FB	LFF	BLC
OVC	VS	Out	VM	MBLS
KLM	Statistic		Limiter	PIP
Master		Slave		
Board	Info	Board	Info	
DCM	u.LOG	DCM	u.LOG	
<input checked="" type="checkbox"/> Quench	PZ16M	<input checked="" type="checkbox"/> Quench	PZ16M	
Module 1	Module 2	Module 3	Module 4	
Detuning	Detuning	Detuning	Detuning	
Ref	Ref	Ref	Ref	
ADC Delays	ADC Delays	ADC Delays	ADC Delays	

Feed Forward + Learning FF

- Feed Forward On
- Correction tables
- LFF Enable

Output Vector Correction

- On
- Ampl: $\uparrow \downarrow$ 0.0102
- Phase: $\uparrow \downarrow$ -154.19
- Ratio: $\uparrow \downarrow$ 0.418

Feedback

- FB
- MIMO

Output limiter

- Enable
- Ampl err: 0.000
- Phase err: 0.006

Pulse settings

- Delay: 20 us
- Filling: $\uparrow \downarrow$ 750
- Flattop: $\uparrow \downarrow$ 650

Beam loading comp

- Ena
- T. corr.

Close FB?

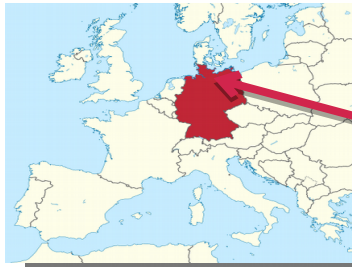
intra-pulse

- dA/A: 0.0061 %
- dP: 0.0062 deg

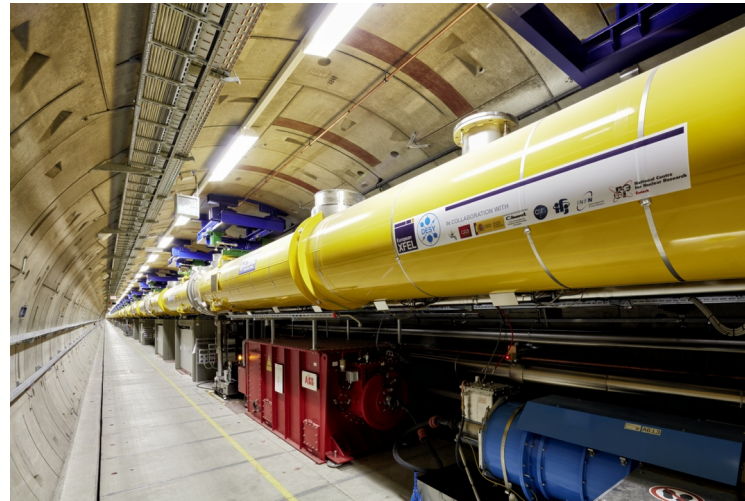
pulse to pulse

- dA/A: 0.0020 %
- dP: 0.0048 deg

MicroTCA in European XFEL



- Biggest success story of MicroTCA
- 800 Superconducting Cavities
- Over 200 MicroTCA Crates (> 2000 components)
 - LLRF
 - Synchronization
 - Timing
 - Beam Diagnostics
 - ...

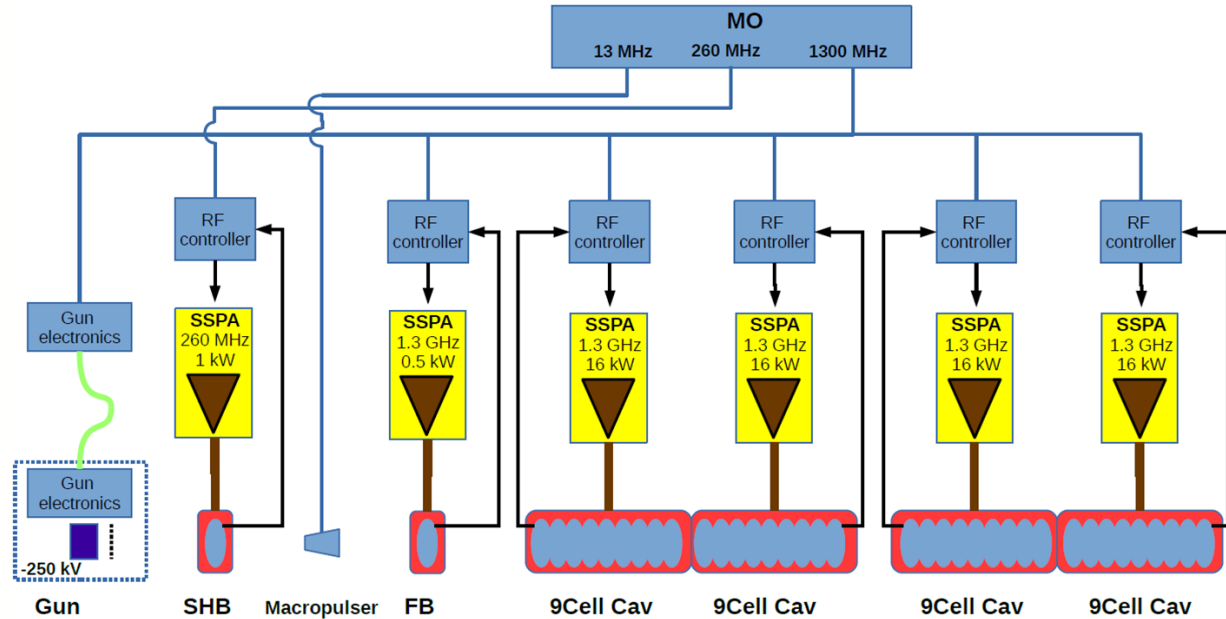




LLRF Project Examples

Turn-key LLRF System for the entire LINAC [1].

- Turkey's First Particle Accelerator
- 40MeV Free Electron Laser + Bremsstrahlung Radiation line
- Overall design is similar to ELBE accelerator in Dresden/Germany (HZDR)
- EPICS as Control System
- CW RF operation
- SSPA's for amplification

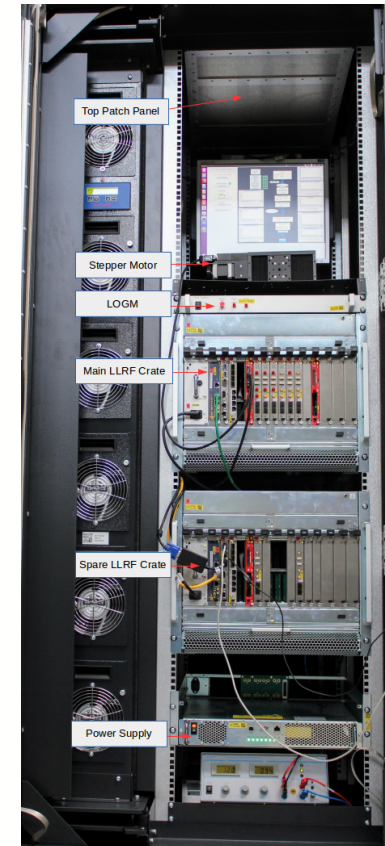


[1] C. Gumus et al., "Design and Status of the MicroTCA.4 Based LLRF System for TARLA" in IPAC'18, Vancouver, Canada

TARLA – LLRF System Overview

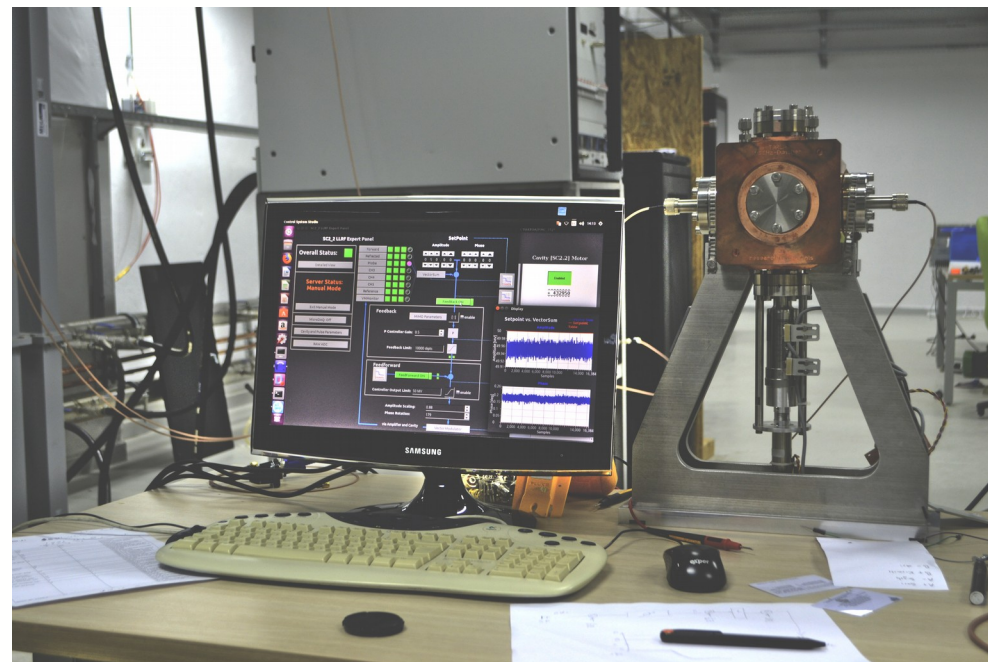
Turn-key LLRF System for the entire LINAC.

- 6 Cavity RF Regulation
 - 4x Superconducting 1.3 GHz Tesla type cavities
 - 1x Normalconducting 1.3 GHz Buncher cavity
 - 1x Normalconducting 260 Mhz Subharmonic Buncher Cavity
- Resonance Control
 - Stepper Motor control on all cavities
 - Piezo Actuator/Sensor control on SC cavities
- Drift Compansation Module for CW RF Operation



TARLA – Latest Status

- Main construction finished including clean room
- Cryogenic system commissioning done
- First ever high power RF operation on close loop of 1.3 GHz Buncher Cavity (September 2018)
- Next months → Cryomodule acceptance tests
- Q3 2019 → Main LLRF Rack will be shipped to Ankara after inner rack cabling
- First accelerated beam in end of 2020

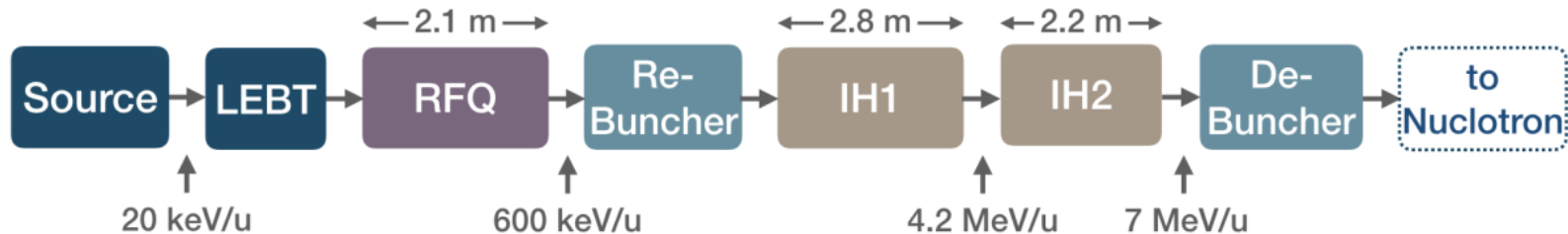
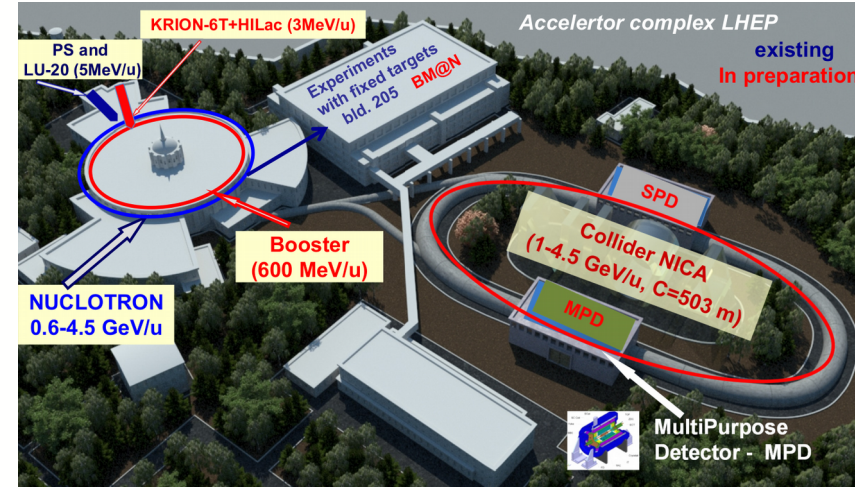


LLRF Project Examples



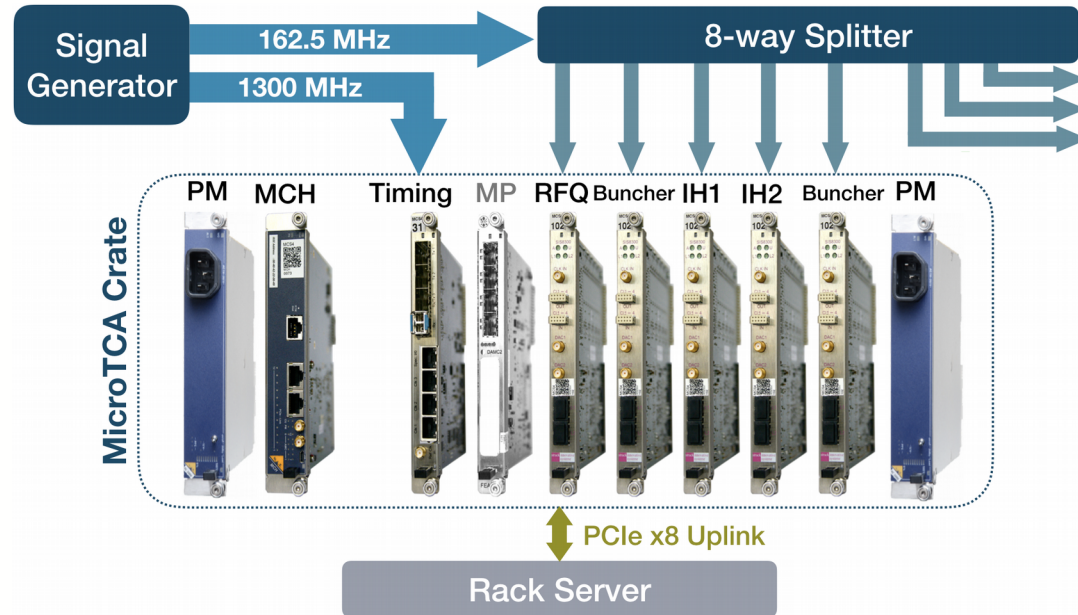
Nuclotron-based Ion Collider Facility at JINR
Dubna/ Russia

- For ion collider upgrade: Light ion frontend Linac (LILac) for polarised particles
- LLRF Control of 6 cavities
- DOOCS as Control System
- 5 Hz rep. Rate with 1 – 300 us pulse length
- 5 mA beam current



LLRF Project Examples

NICA LiLAC LLRF Overview



Cooperation with



LLRF Project Examples

NICA LiLAC LLRF Status

- Currently ongoing system integration:
- Board tests are finished
- Firmware + Software ready.
- Q3 2019 → Crate will be shipped to Bevatech
– Frankfurt Germany

LLRF Crate

External Server

Signal Generator as MO





感谢您的关注