

Progress of global tracking

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Reminder of problems of the global tracking

- Test with the pipiJpsi events
- Good track: $|V_{xy}| < 1\text{cm}$, $|V_z| < 10\text{cm}$, $|\cos \theta| < 0.93$, $Q_{rec} = Q_{truth}$

	Boss665p01 (IDC)	HoughV12 (CGEM-IT)	HoughV13 (CGEM-IT)
4 good tracks events (%)	63.25	60.16	62.68
$(\chi^2_{4c} < 200)$ events (%)	57.36	51.37	50.14
$(\chi^2_{4c} < 60)$ events (%)	38.70	30.14	25.36

- Check the Kalman filter results of event tracks in the pipiJpsi events

	Boss665p01 (IDC)	CgemBoss665b (CGEM-IT)	HoughV12 (CGEM-IT)	HoughV13 (CGEM-IT)
Kalman filter failure rate (%)	1.3	3.0	4.1	15.4

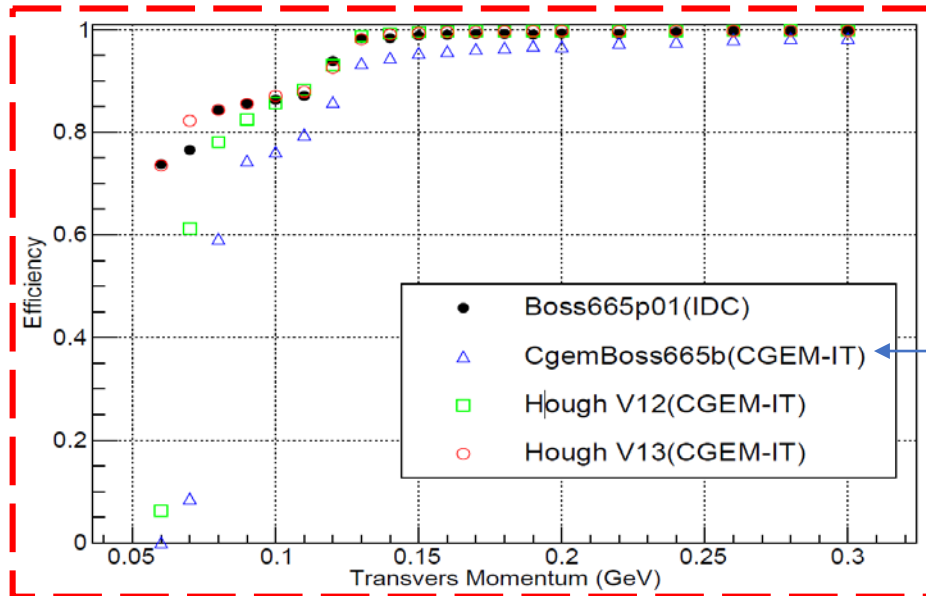
- Kalman filter take initial track parameters of global fitting and hits as input. Failure may cause by:
 - ① Bad initial parameters ? \rightarrow Check the resolution of global fitting result
 - ② Bad hits ? \rightarrow Need to find out the common features of bad hits to drop them

Tracking Efficiency

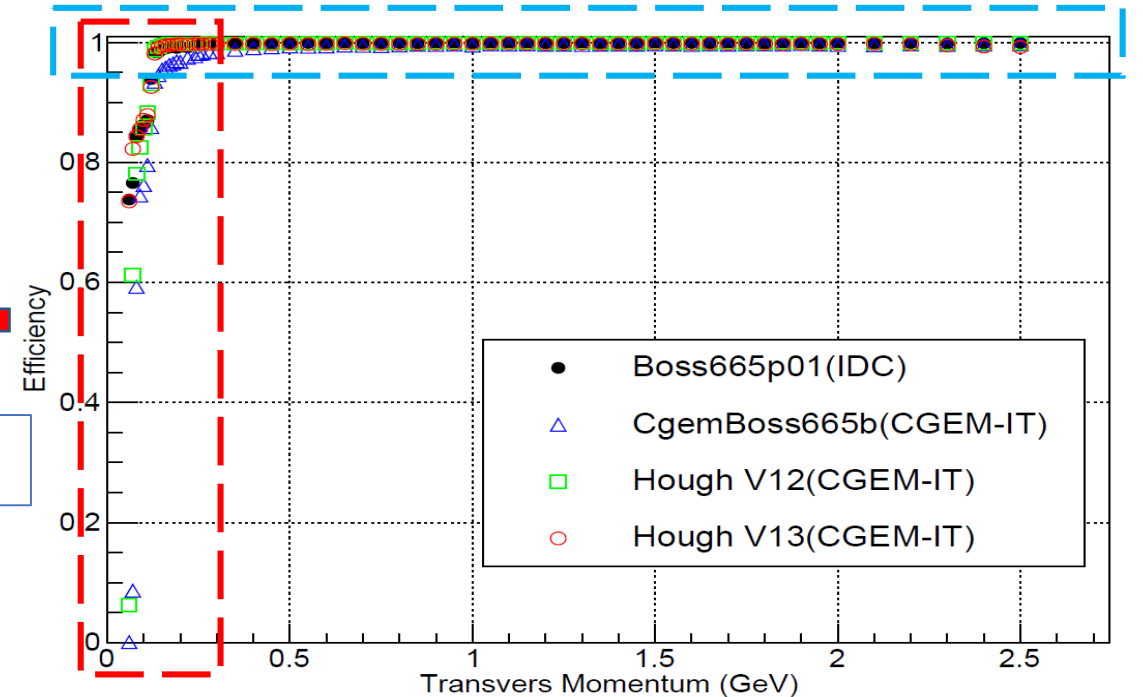
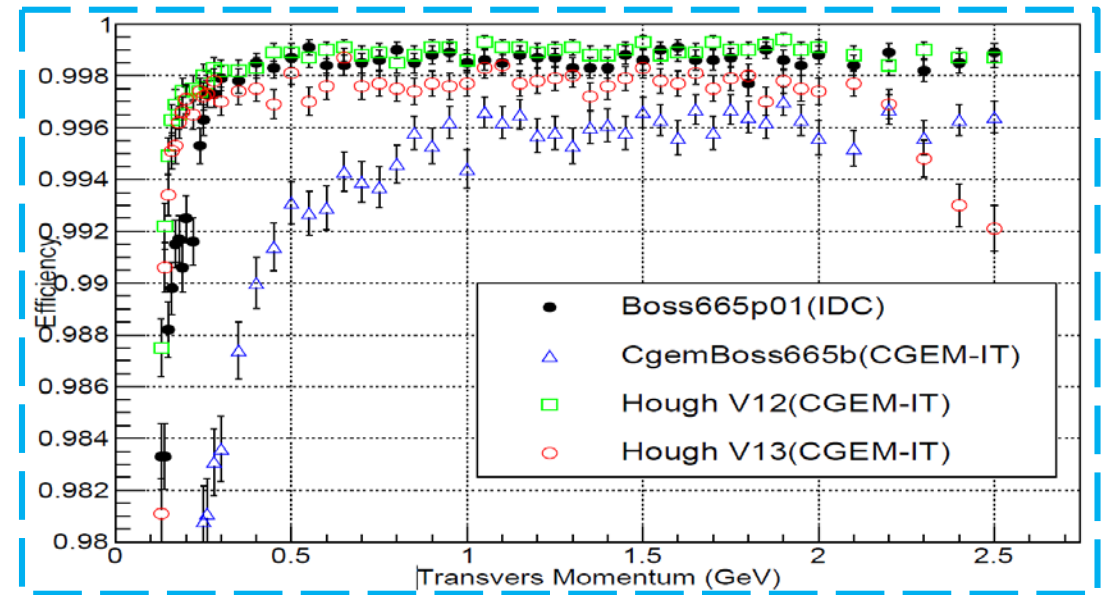
- Sample: fix transvers momentum of single-track μ^- (60MeV~2.5GeV)

$$\text{efficiency} = \frac{\text{reconstructed good track number}}{\text{total simulated track number}}$$

- count only once for tracks that reconstructed twice or more
- Good tracks:
 - $|V_{xy}| < 1\text{cm}$, $|V_z| < 10\text{cm}$,
 - $|\cos \theta| < 0.93$, $Q_{\text{rec}} = Q_{\text{truth}}$



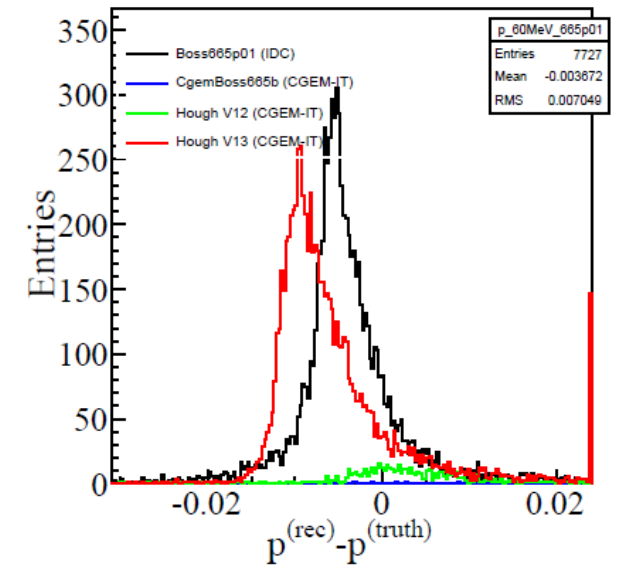
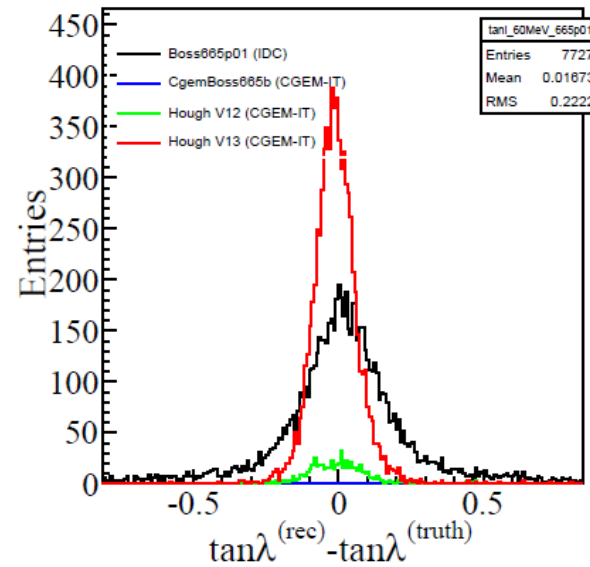
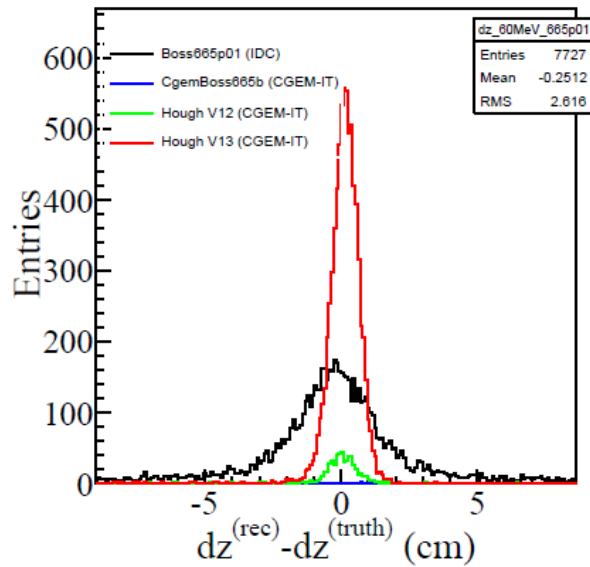
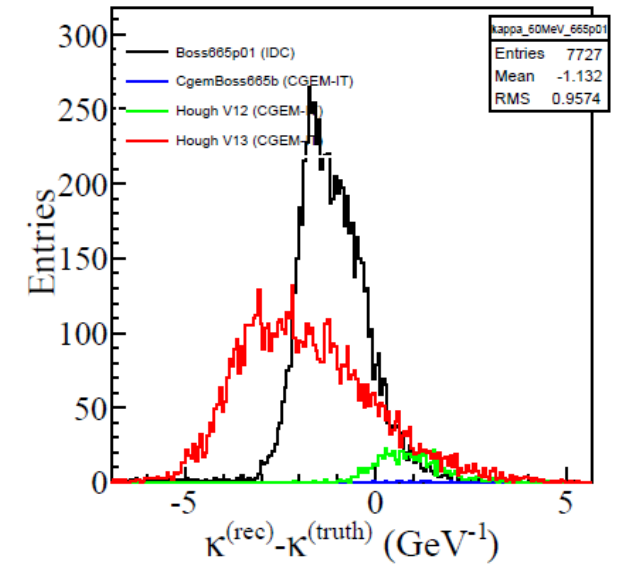
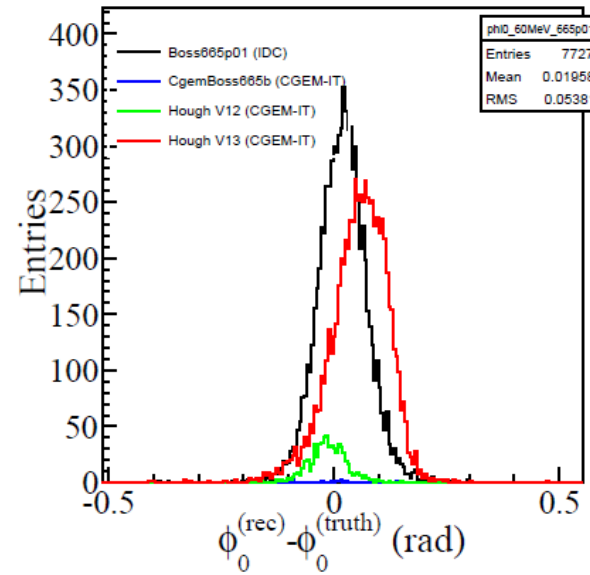
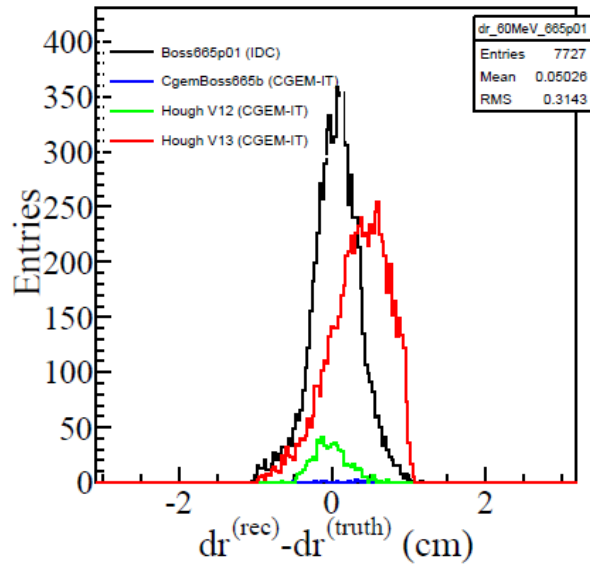
CGEM segment
+ ODC segment



Resolutions of global tracking

• 60MeV

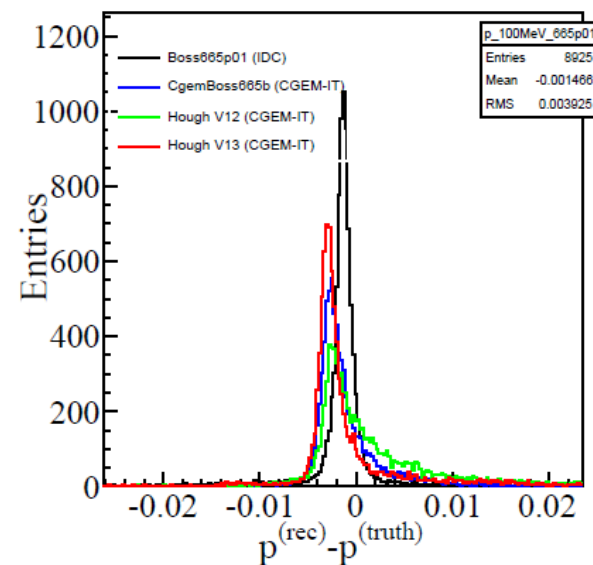
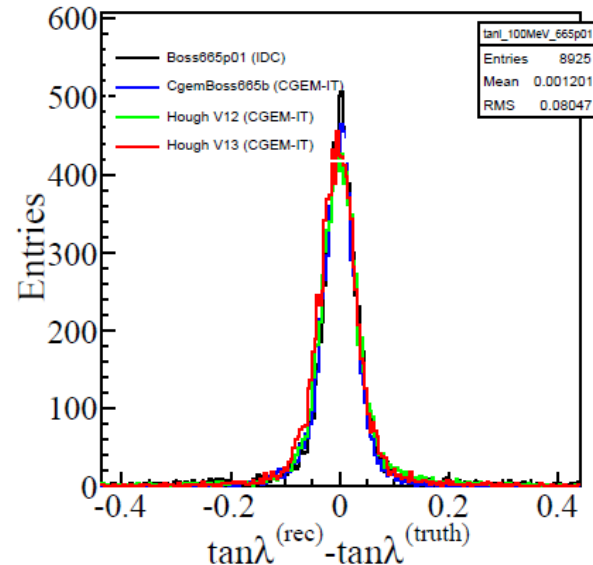
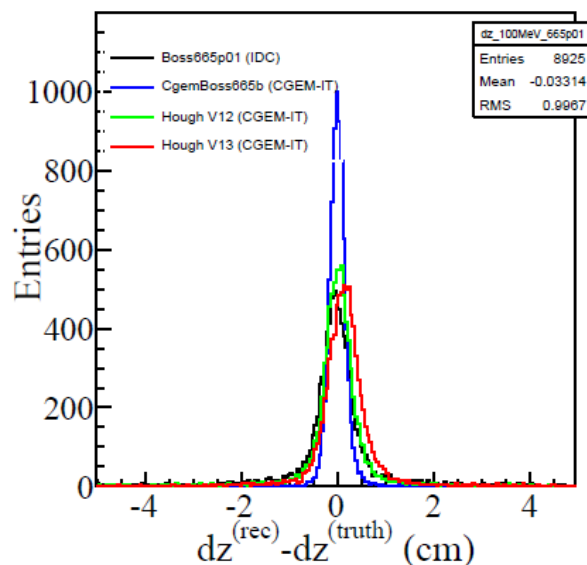
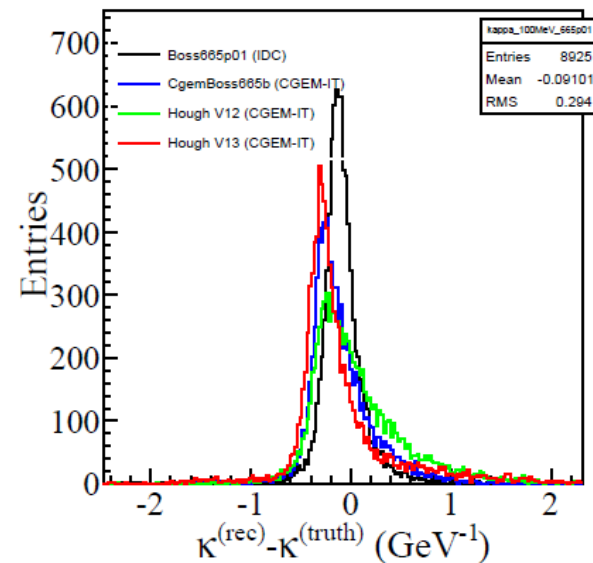
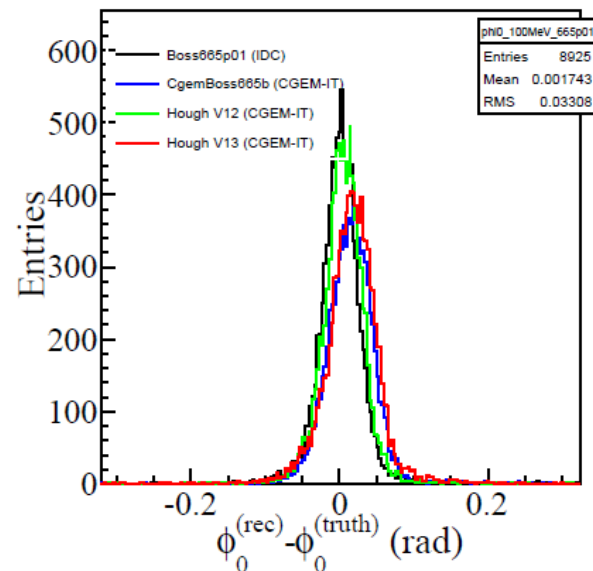
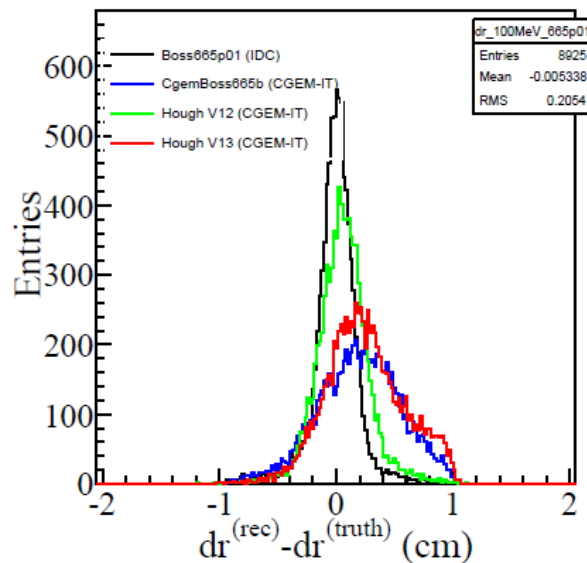
- $|V_{xy}| < 1\text{cm}$,
- $|V_z| < 10\text{cm}$,
- $|\cos \theta| < 0.93$,
- $Q_{rec} = Q_{truth}$



Resolutions of global tracking

- 100MeV

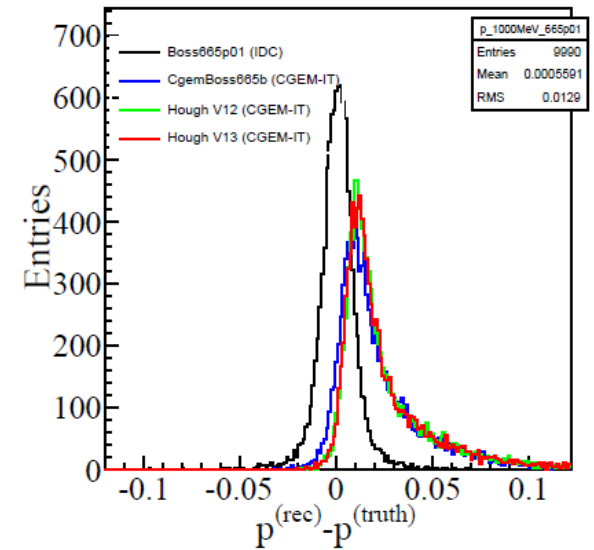
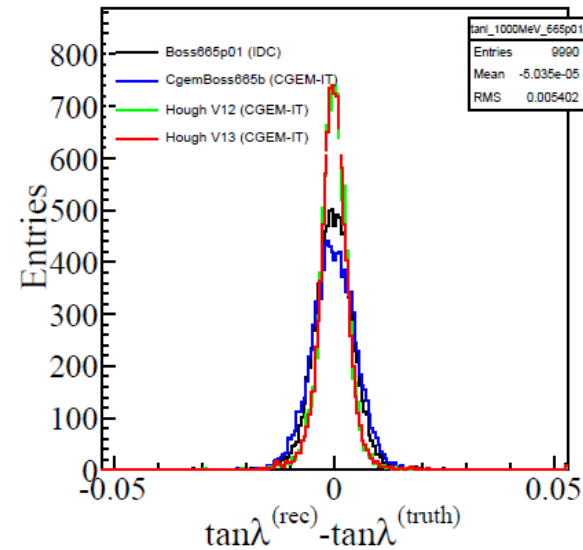
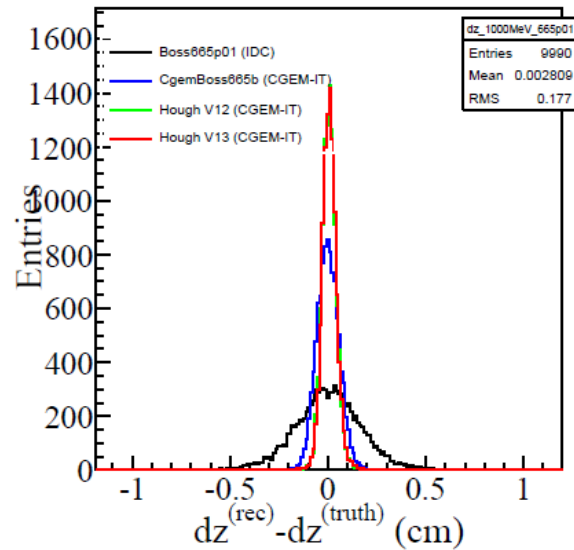
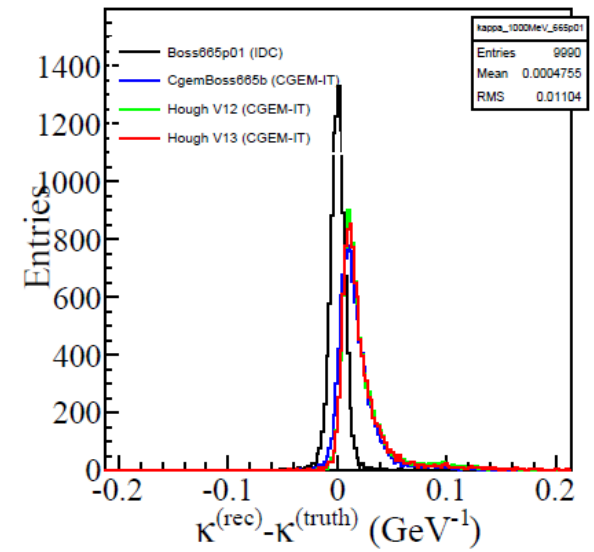
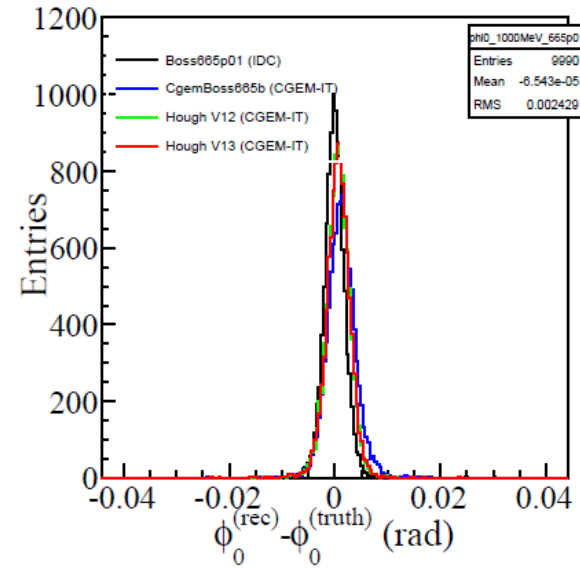
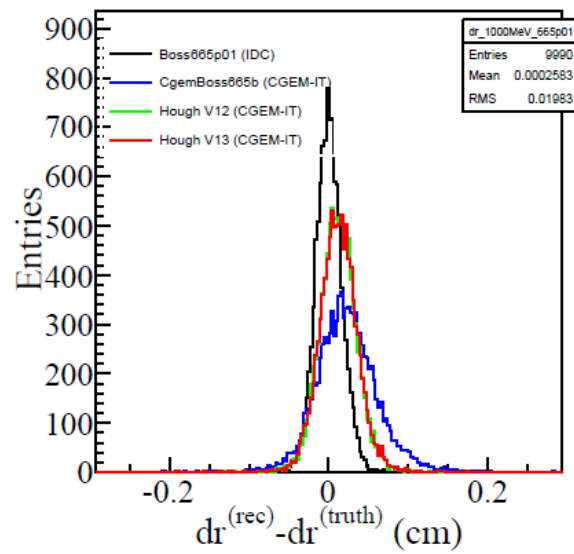
- $|V_{xy}| < 1\text{cm}$,
- $|V_z| < 10\text{cm}$,
- $|\cos\theta| < 0.93$,
- $Q_{rec} = Q_{truth}$



Resolutions of global tracking

- 1000 MeV

- $|V_{xy}| < 1\text{cm}$,
- $|V_z| < 10\text{cm}$,
- $|\cos \theta| < 0.93$,
- $Q_{rec} = Q_{truth}$



Further study plan

- Resolution may not be the reason of Kalman filter failure. But need further test
 - plan to replace the initial parameters with the truth value to test.
- Maybe need to find out the common features of bad hits of the track
 - find out the bad hits of the track
 - analyze their features (flight length, fake cluster, drift distance ...)
 - find out the common features