

Two-loop triangle integrals with 4 scales for the HZV vertex

Based on :

Yuxuan Wang, Xiaofeng Xu, Li Lin Yang. arXiv : 1905.11463

Yuxuan Wang, Xiaofeng Xu, Li Lin Yang. arXiv : 1907.xxxxx

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Outline

- Motivation
- Solve the Integrals
- One loop example
- Result
- Summary

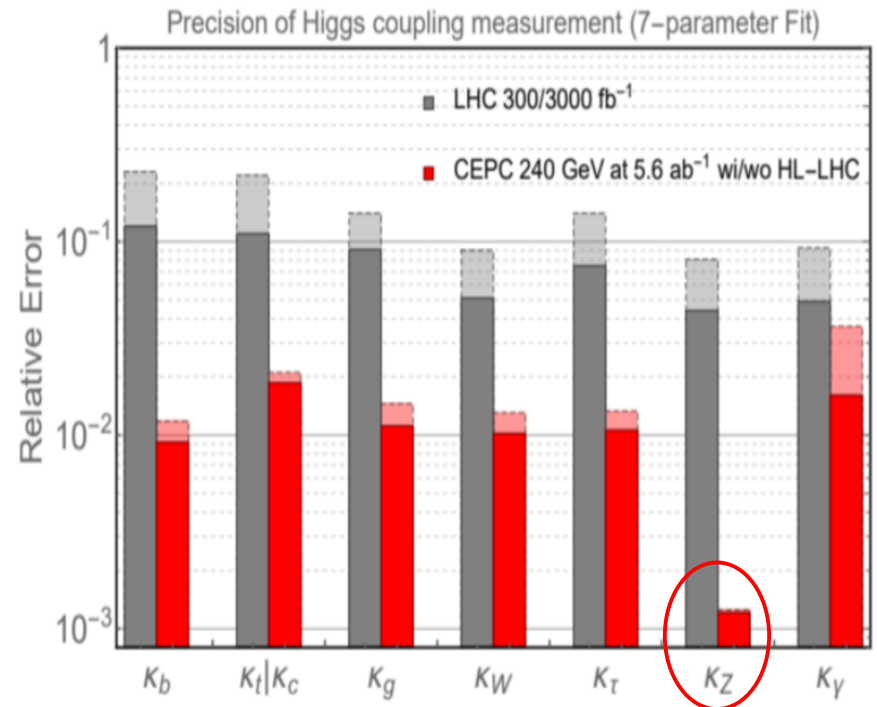
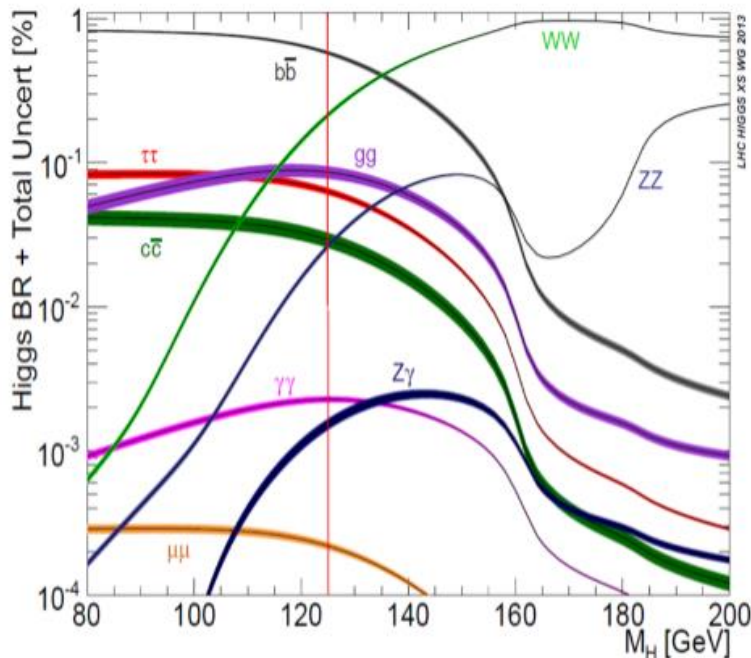
Motivation

- **Higgs**

- Found at LHC in 2012, H(125) is a Spin-0 SM-like particle
- Indirect probe to New Physics

- **HZV vertex** ($V = Z^*$ or γ^*)

- decay and production *

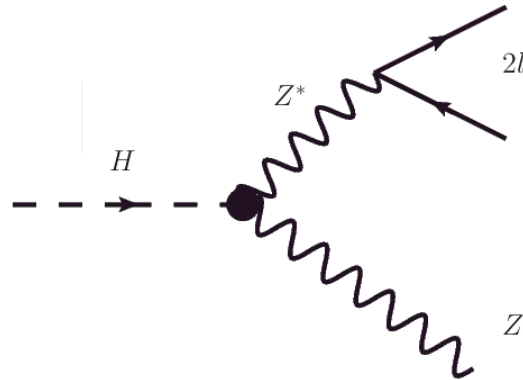


* The CEPC Study Group.... arXiv: 1809.00285

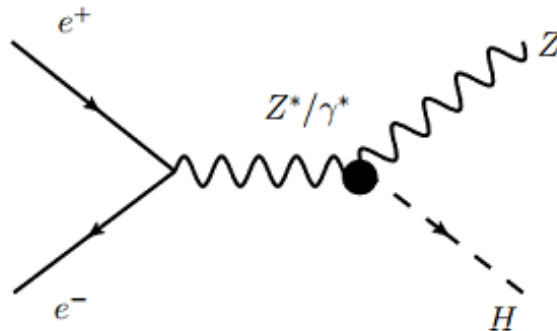
Motivation

- HZV vertex ($V = Z^*$ or γ^*)

- Decay : $H \rightarrow Z Z^* \rightarrow Z + 2l$



- Production : $e^+ + e^- \rightarrow V \rightarrow Z + H$



Motivation

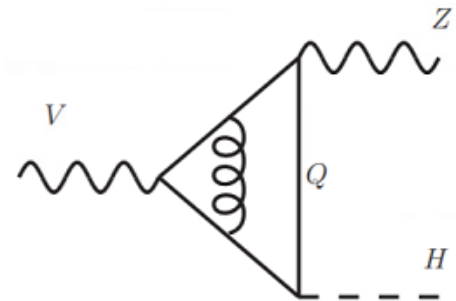
- **NNLO $\mathcal{O}(\alpha\alpha_s)$ corrections (EW-QCD)**

- Two-Loop (quark loop and gluon loop)
- Four Scales (V , Z, H and Q)
 - Three independent dimensionless variables

$$x = -\frac{q^2}{4m_Q^2}, \quad y = -\frac{p_Z^2}{4m_Q^2}, \quad z = -\frac{p_H^2}{4m_Q^2}.$$

- Hard to calculate, in both analytic and numerical way.

- We first give the fully analytic results up to weight-3 in terms of multiple polylogarithms, by using the Differential Equations method.



Solve the Integrals

- **Workflow**

- IBP to a set of master integrals
- Canonical-form Differential Equations

$$\begin{aligned}d\vec{f}(x, y, z, \epsilon) &= \epsilon dA(x, y, z) \vec{f}(x, y, z; \epsilon) \\ &= \epsilon \sum_i A_i d \log(\alpha_i) \vec{f}(x, y, z, \epsilon)\end{aligned}$$

- Solution

$$\vec{f}(x, y, z; \epsilon) = \mathcal{P} \exp \left(\epsilon \int_{\vec{r}_0}^{\vec{r}} dA \right) \vec{f}(x_0, y_0, z_0; \epsilon)$$

- Power series at ϵ

$$\vec{f}(x, y, z; \epsilon) = \sum_{n=0}^{\infty} \vec{f}^{(n)}(x, y, z) \epsilon^n$$

Integration By Parts (IBP)

- Process include huge amounts of integrals
- IBP give a set of linear relations of integrals in a given family.

$$\int \left(\prod_i d^d k_i \right) \frac{\partial}{\partial k_j^\mu} \left(q_\mu \prod_l \frac{1}{(k_l - p_n)^{a_l}} \right) = 0$$

- where q_μ can be any internal momentum k_i^μ or external momentum p_n^μ .
- A max set of independent Integrals are called Master Integrals(MIs).
- Auto-computer algebra program : FIRE5 *
- Huge amounts of integrals → much less MIs

Differential Equations

- Given a set of MIs $\vec{f}(\vec{x}, \epsilon)$ where \vec{x} are the kinematic variables, we have

$$\frac{\partial}{\partial x_i} \vec{f}(\vec{x}, \epsilon) = \bar{A}_i(\vec{x}, \epsilon) \vec{f}(\vec{x}, \epsilon)$$

- By choosing another appropriate MIs $\vec{f}_0(\vec{x}, \epsilon)$

$$\frac{\partial}{\partial x_i} \vec{f}_0(\vec{x}, \epsilon) = \left[\epsilon \tilde{A}_i(\vec{x}) + \tilde{B}_i(\vec{x}) \right] \vec{f}_0(\vec{x}, \epsilon)$$

- Canonical Form by further making a linear transformation $T(\vec{x}, \epsilon)$

$$\frac{\partial}{\partial x_i} \vec{f}(\vec{x}, \epsilon) = \epsilon A_i(\vec{x}) \vec{f}(\vec{x}, \epsilon)$$

where $\vec{f}(\vec{x}, \epsilon) = T(\vec{x}, \epsilon) \vec{f}_0(\vec{x}, \epsilon)$ are called canonical-basis of MIs

Canonical form of DE

- Canonical form

$$d\vec{f}(\vec{x}, \epsilon) = \epsilon dA(\vec{x}) \vec{f}(\vec{x}, \epsilon)$$

- Chen iterated integrals*

$$\vec{f}(\vec{x}, \epsilon) = \mathbb{P} \exp \left(\epsilon \int_{\gamma} dA(\vec{x}) \right) \vec{f}(\vec{x}_0, \epsilon)$$

- Multiple polylogarithms(GPLs)**

$$G(a_1, \dots, a_n; x) \equiv \int_0^x \frac{dx'}{x' - a_1} G(a_2, \dots, a_n; x'),$$

with $G(; \beta) \equiv 1$ and $G(\underbrace{0, \dots, 0}_{n \text{ times}}; x) \equiv \log^n(x)/n!$, weight is n

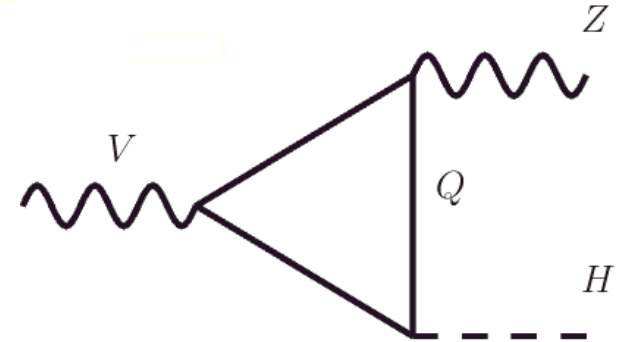
$$G(\vec{0}_{n-1}, 1; x) \equiv -Li_n(x)$$

* Kuo-Tsai Chen. Iterated path integrals. <https://projecteuclid.org:443/euclid.bams/1183539443>

** A. B. Goncharov, Math. Res. Lett. 5, 497 (1998) arXiv:1105.2076

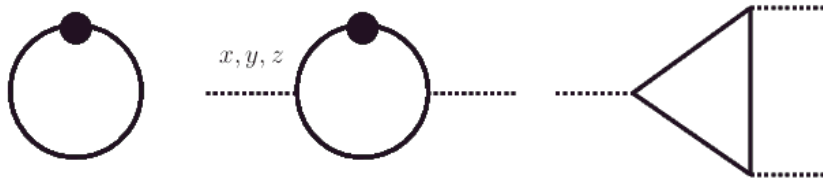
Example : One-loop triangle integrals

- IBP to only 5 master integrals
- Canonical basis for differential equation



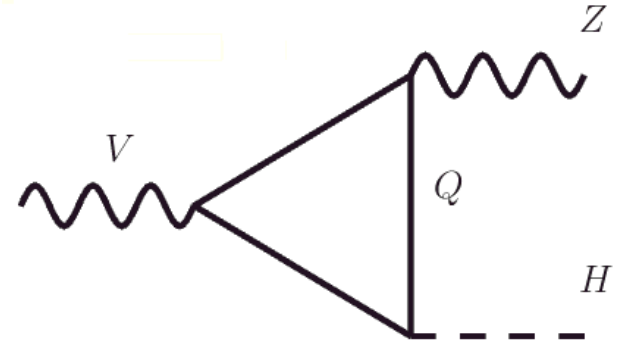
$$x = -\frac{q^2}{4m_Q^2}, \quad y = -\frac{p_Z^2}{4m_Q^2}, \quad z = -\frac{p_H^2}{4m_Q^2}$$

$$\begin{aligned} d\vec{f}(x, y, z, \epsilon) &= \epsilon dA(x, y, z) \vec{f}(x, y, z; \epsilon) \\ &= \epsilon \sum_i A_i d \log(\alpha_i) \vec{f}(x, y, z, \epsilon) \end{aligned}$$



Example : One-loop triangle integrals

$$\begin{aligned}
 d\vec{f}(x, y, z, \epsilon) &= \epsilon dA(x, y, z) \vec{f}(x, y, z; \epsilon) \\
 &= \epsilon \sum_i A_i d \log(\alpha_i) \vec{f}(x, y, z, \epsilon)
 \end{aligned}$$



- Four square roots $R_1(x) \equiv \sqrt{x(x+1)}$, $R_1(y)$, $R_1(z)$,
 $R_2 \equiv R_2(x, y, z) \equiv \sqrt{\lambda(x, y, z)}$.

$$\lambda(x, y, z) \equiv x^2 + y^2 + z^2 - 2xy - 2yz - 2zx.$$

$$\beta(t) \equiv \frac{R_1(t) - t}{R_1(t) + t}.$$

$$dA = \begin{pmatrix}
 0 & 0 & 0 & 0 & 0 \\
 d \log(\beta(x)) / 4 & -d \log(1+x) & 0 & 0 & 0 \\
 d \log(\beta(y)) / 4 & 0 & -d \log(1+y) & 0 & 0 \\
 d \log(\beta(z)) / 4 & 0 & 0 & -d \log(1+z) & 0 \\
 0 & -d \log\left(\frac{x(x-y-z) - R_1(x)R_2}{x(x-y-z) + R_1(x)R_2}\right) & \dots & \dots & \dots
 \end{pmatrix}$$

Example : One-loop triangle integrals

- Iterated integrals solution

$$\vec{f}^{(i)}(\vec{x}) = \int_{\gamma} dA(\vec{x}) \vec{f}^{(i-1)}(\vec{x}) + \vec{f}^{(i)}(\vec{x}_0)$$

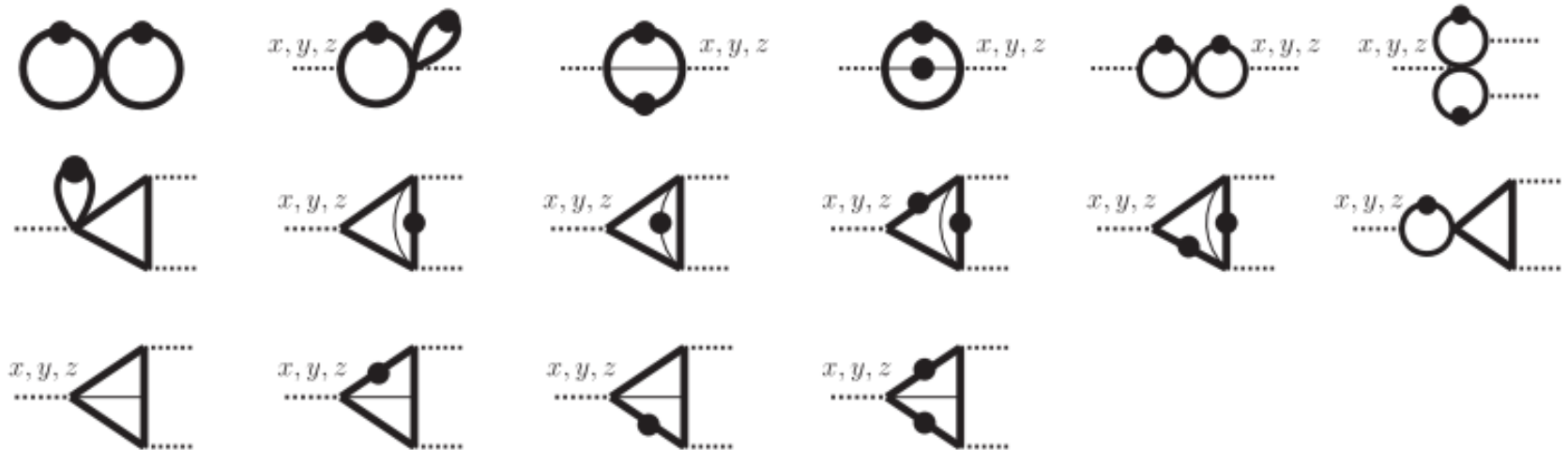
- Boundary Conditions

$$\lim_{x,y,z \rightarrow 0} f_i(x, y, z, \epsilon) = \delta_{i,1}$$

- Only need to be solved up to weight 2

Solve the Integrals (Two-loop)

- IBP to **41** master integrals
- The canonical basis of MIs



- Need to be solved up to weight 4
 - Using the Symbol *

Symbol representation

- Maps the iterated integrals to their integration kernels

$$\vec{f}^{(i)}(\vec{x}) = \int_{\gamma} dA(\vec{x}) \vec{f}^{(i-1)}(\vec{x}) + \vec{f}^{(i)}(\vec{x}_0)$$

$$\mathcal{S}(f_n^{(i)}(\vec{x})) = \sum_m \mathcal{S}(f_m^{(i-1)}(\vec{x})) \otimes \mathcal{S}(A_{nm}(\vec{x}))$$

- Algebraic properties

$$\begin{aligned} \alpha_1(\vec{x}) \otimes \cdots \otimes (\alpha_i(\vec{x})\alpha_{i'}(\vec{x})) \otimes \cdots \otimes \alpha_n(\vec{x}) &= \alpha_1(\vec{x}) \otimes \cdots \otimes \alpha_i(\vec{x}) \otimes \cdots \otimes \alpha_n(\vec{x}) \\ &\quad + \alpha_1(\vec{x}) \otimes \cdots \otimes \alpha_{i'}(\vec{x}) \otimes \cdots \otimes \alpha_n(\vec{x}) \end{aligned}$$

$$\alpha_1(\vec{x}) \otimes \cdots \otimes (c\alpha_i(\vec{x})) \otimes \cdots \otimes \alpha_n(\vec{x}) = \alpha_1(\vec{x}) \otimes \cdots \otimes \alpha_i(\vec{x}) \otimes \cdots \otimes \alpha_n(\vec{x})$$

- Shuffle product

$$a \text{ III } b = a \otimes b + b \otimes a.$$

$$(a_1 \otimes \cdots \otimes a_{n_1}) \text{ III } (a_{n_1+1} \otimes \cdots \otimes a_{n_1+n_2}) = \sum_{\sigma \in \Sigma(n_1, n_2)} a_{\sigma^{-1}(1)} \otimes \cdots \otimes a_{\sigma^{-1}(n_1+n_2)}$$

where $\Sigma(n_1, n_2)$ denotes the set of all shuffles of $n_1 + n_2$ elements

Weight 2 solution

$$R_1(x) \equiv \sqrt{x(x+1)} \quad \beta(t) \equiv \frac{R_1(t) - t}{R_1(t) + t}$$

$$R_2 \equiv R_2(x, y, z) \equiv \sqrt{\lambda(x, y, z)}$$

- Integrable symbols

$$\beta_i \otimes \beta_i, \quad \beta_i \otimes \beta_j + \beta_j \otimes \beta_i, \quad \beta_i \otimes r_i, \quad \beta_i \otimes (1 + r_i),$$

$$\frac{\beta_i \beta_j}{\beta_k} \otimes \left(1 - \frac{\beta_i \beta_j}{\beta_k}\right), \quad (\beta_i \beta_j \beta_k) \otimes (1 - \beta_i \beta_j \beta_k), \quad i \neq j \neq k = x, y, z$$

$$\beta(x) \otimes \frac{x(x - y - z) - R_1(x)R_2}{x(x - y - z) + R_1(x)R_2} + (x \leftrightarrow y) + (x \leftrightarrow z),$$

- Simple example

$$\mathcal{S}(G(0, 0; u)) = \mathcal{S}\left(\frac{1}{2} \log^2(u)\right) = u \otimes u,$$

$$\mathcal{S}(G(0; u)G(0; v)) = \mathcal{S}(\log(u) \log(v)) = u \otimes v + v \otimes u,$$

$$\mathcal{S}(G(0, 1; u)) = -\mathcal{S}(\text{Li}_2(u)) = (1 - u) \otimes u.$$

Weight 2 solution

$$\begin{aligned}
 R_1(x) &\equiv \sqrt{x(x+1)} & \beta(t) &\equiv \frac{R_1(t) - t}{R_1(t) + t} \\
 R_2 &\equiv R_2(x, y, z) \equiv \sqrt{\lambda(x, y, z)} \\
 \lambda(x, y, z) &\equiv x^2 + y^2 + z^2 - 2xy - 2yz - 2zx.
 \end{aligned}$$

- **complex symbol**

$$\beta(x) \otimes \frac{x(x-y-z) - R_1(x)R_2}{x(x-y-z) + R_1(x)R_2} + (x \leftrightarrow y) + (x \leftrightarrow z)$$

- **parametrize the path** : $t \vec{x}$ $R_2(tx, ty, tz) = tR_2(x, y, z) = tR_2$

$$\begin{aligned}
 I_1 &= \int_{t=0}^{t=1} \log(\beta(tx)) d \log \frac{tx(x-y-z) - R_1(tx)R_2}{tx(x-y-z) + R_1(tx)R_2} \\
 &= \int_{u=0}^{u=1-\beta(x)} G(1; u) d \log \frac{u(x-y-z+R_2) - 2R_2}{u(x-y-z-R_2) + 2R_2} \\
 &= G\left(\frac{2R_2}{R_2+x-y-z}, 1; 1-\beta(x)\right) - G\left(\frac{2R_2}{R_2-x+y+z}, 1; 1-\beta(x)\right)
 \end{aligned}$$

Weight 3 solution

$$R_1(x) \equiv \sqrt{x(x+1)}$$

$$R_2 \equiv R_2(x, y, z) \equiv \sqrt{\lambda(x, y, z)}$$

$$\beta(t) \equiv \frac{R_1(t) - t}{R_1(t) + t}$$

- The shuffle algebra (without R_2)

$$\beta(y) \otimes \beta(x) \otimes (1+x) + \beta(x) \otimes \beta(y) \otimes (1+x) + \beta(x) \otimes (1+x) \otimes \beta(y)$$

$$\begin{aligned} & G(1; 1 - \beta(y)) * (\beta(x) \otimes (1+x)) \\ &= G(1; 1 - \beta(y)) * \left(\beta(x) \otimes \frac{(1 + \beta(x))^2}{4\beta(x)} \right) \\ &= G(1; u(y)) * \left(2G(2, 1; u(x)) - G(1, 1; u(x)) \right) \quad u=1-\beta \end{aligned}$$

Weight 3 solution

$$R_1(x) \equiv \sqrt{x(x+1)}$$

$$R_2 \equiv R_2(x, y, z) \equiv \sqrt{\lambda(x, y, z)}$$

$$\beta(t) \equiv \frac{R_1(t) - t}{R_1(t) + t}$$

- Most symbols contain two R_1 with R_2
 - For example $R_1(x), R_1(y), R_2(x, y, z)$
- choose a path parameterized by $t \vec{x}$, $R_2(tx, ty, tz) = t * R_2(x, y, z)$
- rationalize $R_1(tx)$ and $R_1(ty)$ simultaneously :

$$t = \frac{v^2(2+v)^2}{4(1+v)((1+v)\sqrt{x} + \sqrt{y})((1+v)\sqrt{y} + \sqrt{x})}$$

$$\beta(tx) = \frac{(1+v)\sqrt{y} + \sqrt{x}}{(1+v)((1+v)\sqrt{x} + \sqrt{y})}$$

$$\beta(ty) = \frac{(1+v)\sqrt{x} + \sqrt{y}}{(1+v)((1+v)\sqrt{y} + \sqrt{x})}$$

Weight 4 solution

$$R_1(x) \equiv \sqrt{x(x+1)}$$

$$R_2 \equiv R_2(x, y, z) \equiv \sqrt{\lambda(x, y, z)}$$

- Symbols contain all 4 square roots
 - Cannot be rationalized simultaneously and solved analytically
- One-fold numerical integration
 - Parameterize integration path γ with $t \vec{x}$, $t \in [0,1]$

$$\vec{f}^{(i)}(\vec{x}) = \int_{\gamma} dA(\vec{x}) \vec{f}^{(i-1)}(\vec{x}) + \vec{f}^{(i)}(\vec{x}_0)$$

$$\vec{f}^{(4)}(\vec{x}) = \int_0^1 \partial_t A(t) \vec{f}^{(3)}(t) dt$$

Result

- **Why analytic result ???**

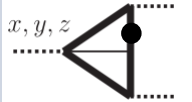
- Accurate and fast

- Apply to any phase-point

- Investigate the behaviors in various asymptotic limit (to be done)

Result

- Accurate and fast

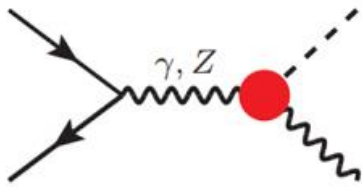
	$\sqrt{s} = 300 \text{ GeV}$		$\sqrt{s} = 500 \text{ GeV}$	
	ϵ^0	ϵ^1	ϵ^0	ϵ^1
Analytic result	0.329941	0.081257	0.410898 + 0.114525 i	0.103284 + 0.399126 i
pySecDec *	0.329(9)	0.081(2)	0.410(9) + 0.114(5) i	0.103(2) + 0.399(1) i
Time for all 41 MIs	12 s		19 s	
	556 s		517 s	

* S. Borowka et al. pySecDec... arXiv:1703.09692

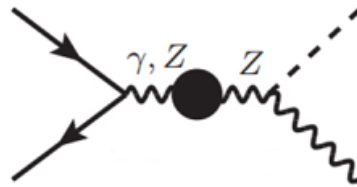
Result

- $e^+ + e^- \rightarrow V \rightarrow Z + H$

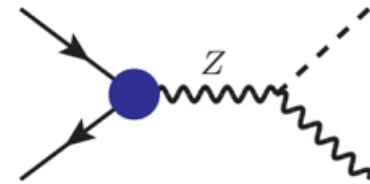
$$\sigma^{\alpha\alpha_s} = \sigma_Z^{\alpha\alpha_s} + \sigma_\gamma^{\alpha\alpha_s} + \sigma_{eeZ}^{\alpha\alpha_s}$$



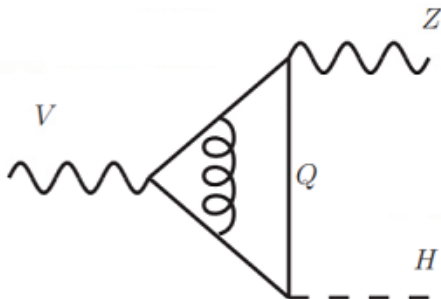
VZH vertex



self-energy



eeZ vertex



Result

- $e^+ + e^- \rightarrow V \rightarrow Z + H$
- Top

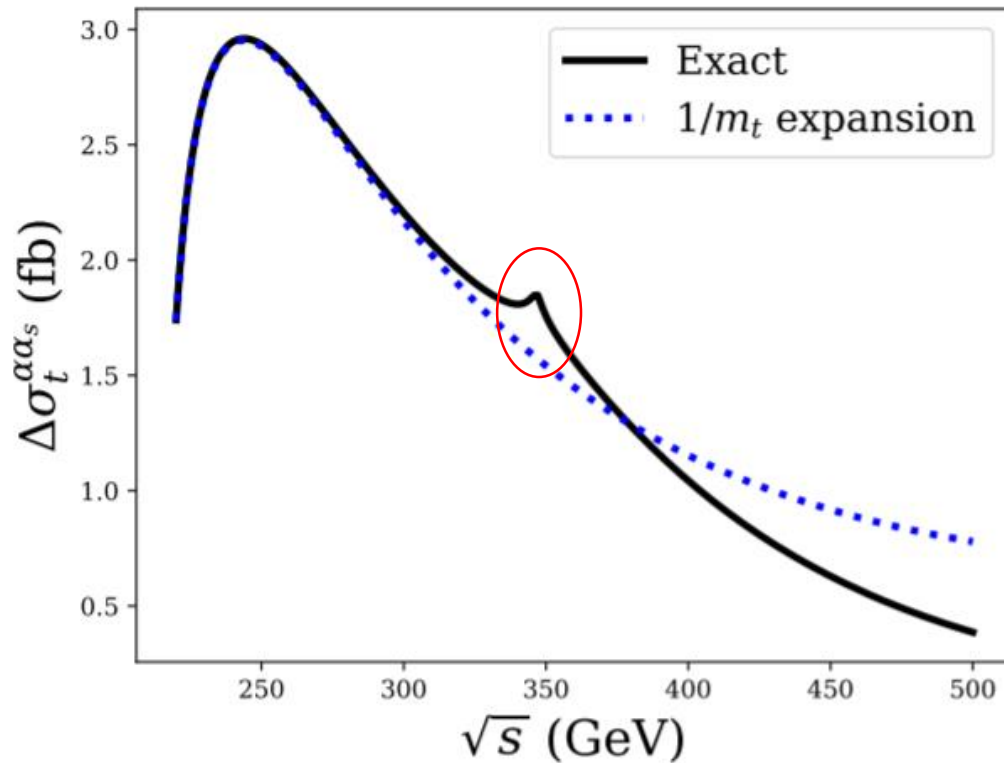


Fig1 : NNLO $\mathcal{O}(\alpha\alpha_s)$ corrections from top quark loops to the $e^+e^- \rightarrow ZH$ production cross sections.

Result

- $e^+ + e^- \rightarrow V \rightarrow Z + H$
 - Top + Bottom

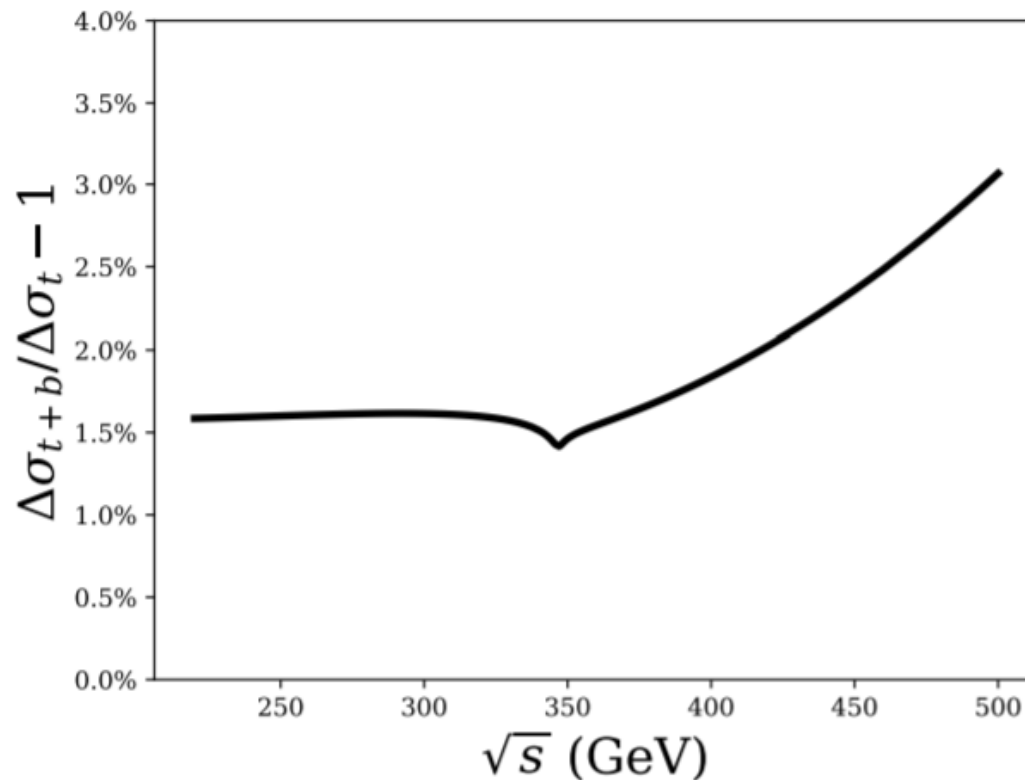


Fig2 : Relative corrections from **bottom** quark loops

Result

- $H \rightarrow Z Z^* \rightarrow Z + 2l$
 - Top + Bottom

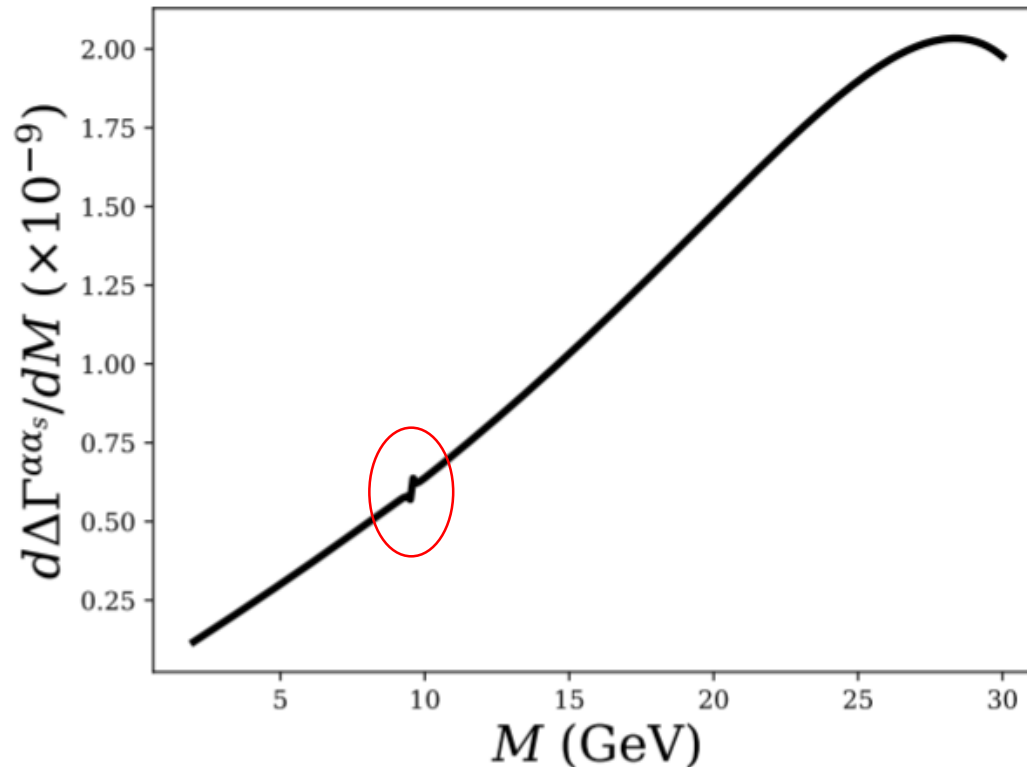


Fig3 : NNLO $\mathcal{O}(\alpha\alpha_s)$ corrections differential decay rate as a function of the lepton pair invariant mass M , including **both top and bottom** quark contributions

Summary

- We give the fully **analytic result** up to weight-3 of Two-loop triangle integrals with 4 scales for the HZV vertex .
- The analytic result we get is **accurate and fast**
- We use our analytic result to calculate the $e^+e^- \rightarrow ZH$ production cross section and the $H \rightarrow Z Z^* \rightarrow Z + 2l$ decay width.



Thanks!

Yuxuan Wang