

Optimization of VXD layout

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Impact Parameter Resolution:

$$\sigma_{r\phi} = a \oplus \frac{b}{p(\text{ GeV}) \sin^{3/2} \theta}$$

p the track momentum

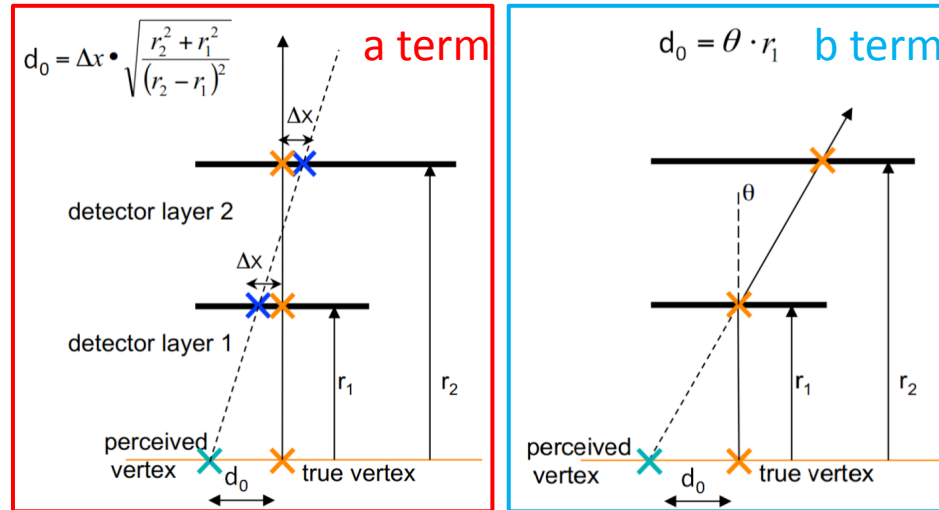
θ the polar track angle

The '**a**' term describes the intrinsic resolution of the vertex detector in the absence of multiple scattering and is independent of the track parameters.

The '**b**' term reflects the effects of multiple scattering.

The parameters $a = 5 \mu\text{m}$ and $b = 10 \mu\text{m} \cdot \text{GeV}$ are taken as the design values for the CEPC vertex detector.

three concentric cylinders of double-layer pixelated vertex detector.



	R (mm)	$ z $ (mm)	$ \cos \theta $	σ (μm)
Layer 1	16	62.5	0.97	2.8
Layer 2	18	62.5	0.96	6
Layer 3	37	125.0	0.96	4
Layer 4	39	125.0	0.95	4
Layer 5	58	125.0	0.91	4
Layer 6	60	125.0	0.90	4

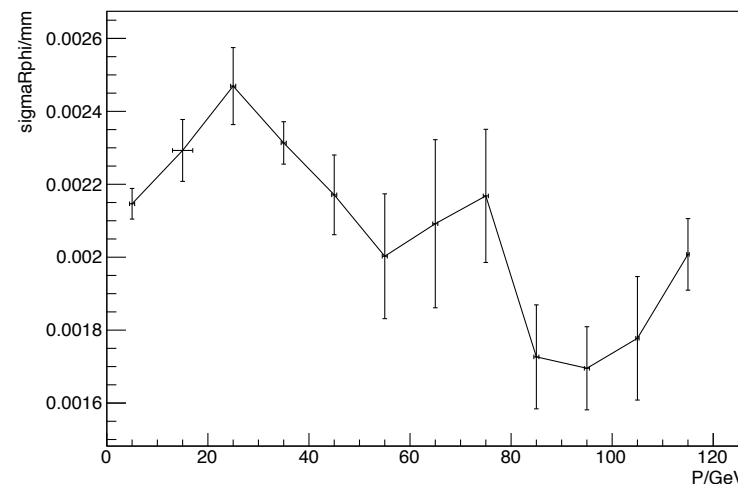
Simulation Method

Get in different energy and same angle(85°)

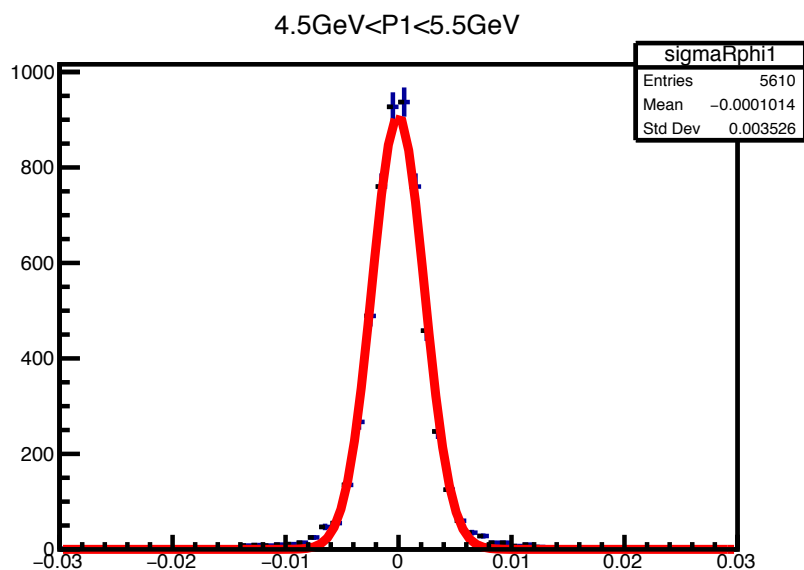
Event:

Simulation tools: Mokka & Marlin

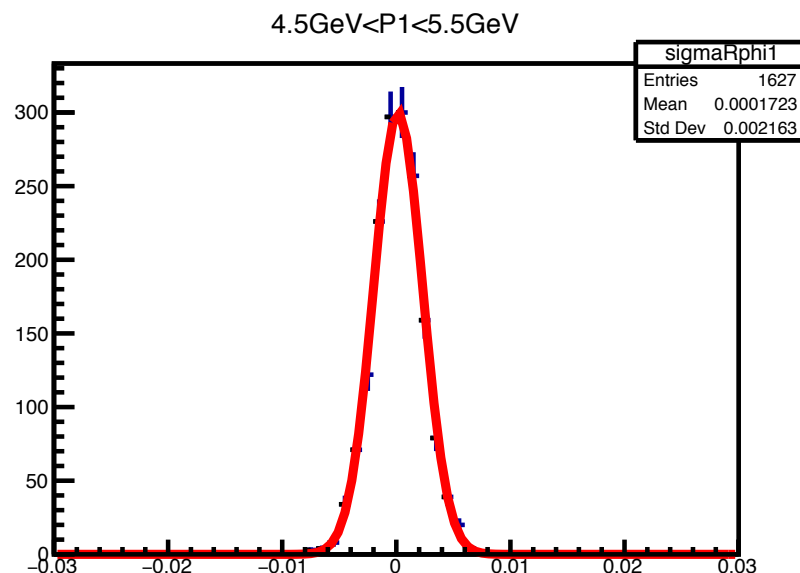
Impact Parameter Resolution



Energy = 5 ± 0.5 GeV & full angle



Energy = 5 ± 0.5 GeV & $\theta = 85^\circ$



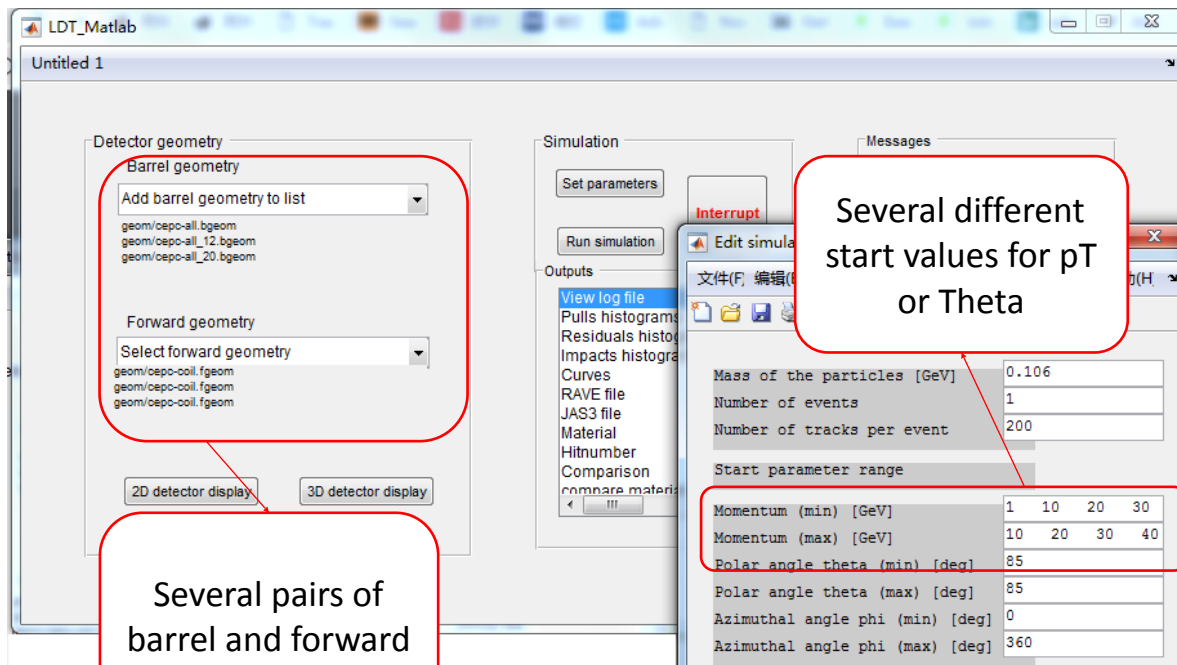
LDT for **fast** layout optimization

- A MATLAB based tool – easy to understand, handle and modify
- Compare track parameter resolutions of various detector setups
- Optimize size and position of the track sensitive devices, and of the detector material budgets
- Start parameters for simulated tracks are user-defined
 - VTX Geometry: Radius, Thickness..
 - Transverse momentum range, range of polar angle θ , number of tracks from the vertex.
- Weakness: Difficult to define new geometry parameters according to personal requests, e.g. rotation angle between two ladders

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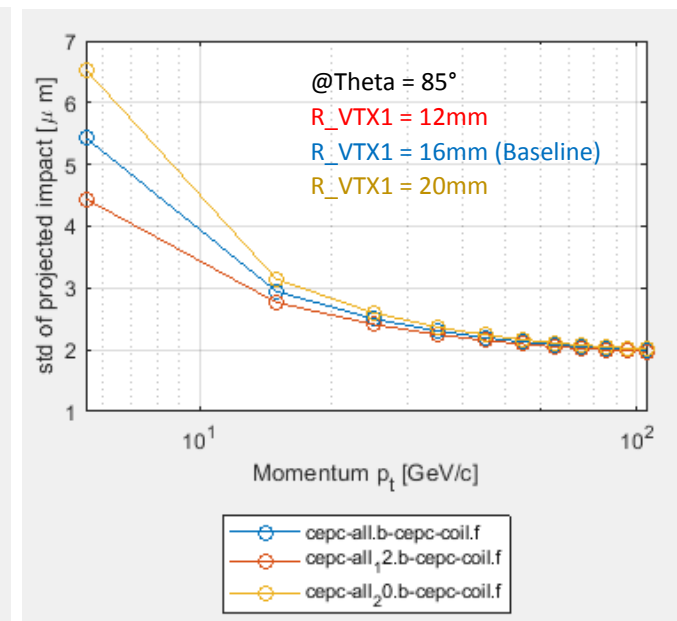
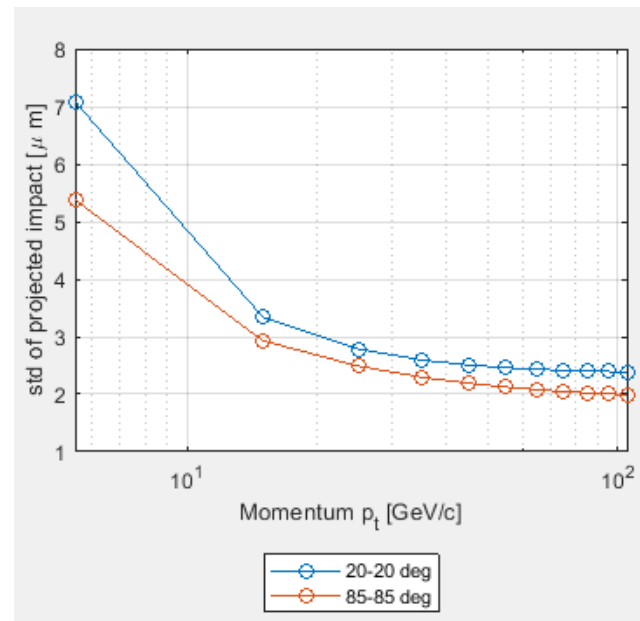
01 LiC Detector-Toy (barrel)
02 LDC-basic-Japan
03 Version: 120208
04 Vertex Detector (VTX)
05
06 Number of layers : 14
07 Description (optional) : |-Beamt.-|-----Vertex detector-----|
08 Names of the layers (opt.) : XBT, VTX1, XVTX1, XVTX2, VTX2, VTX3, XVTX3, XVTX4, VTX4, VTX5, XVTX5, VTX6, XVTX6, XVTXSHELL
09 Radii [mm] : 14.5, 15.95, 16, 17, 18, 36.95, 37, 38, 39, 57.95, 58, 59, 60, 65
10 Upper limit in z [mm] : 4225, 62.5, 62.5, 62.5, 62.5, 125, 125, 125, 125, 125, 125, 125, 125, 145
11 Lower limit in z [mm] : -4225, -62.5, -62.5, -62.5, -62.5, -125, -125, -125, -125, -125, -125, -125, -125, -145
12 Efficiency RPhi : 0, 0.99, 0, 0, 0.99, 0.99, 0, 0, 0.99, 0.99, 0, 0, 0.99, 0
13 Efficiency 2nd coord. (eg. z): -1
14 Stereo angle alpha [Rad] : -pi/2
15 Thickness [rad. lengths] : 0.0014, 0.00053, 0.00098, 0.00098, 0.00053, 0.00053, 0.00098, 0.00098, 0.00053, 0.00053, 0.00098, 0.00053, 0.00098, 0.0014
16 error distribution : 0
17 0 normal-sigma(RPhi) [1e-6m] : 2.8, 6, 4, 4, 4, 4
18 sigma(z) [1e-6m] : 2.8, 6, 4, 4, 4, 4
19 1 uniform-d(RPhi) [1e-6m] :
20 d(z) [1e-6m] :

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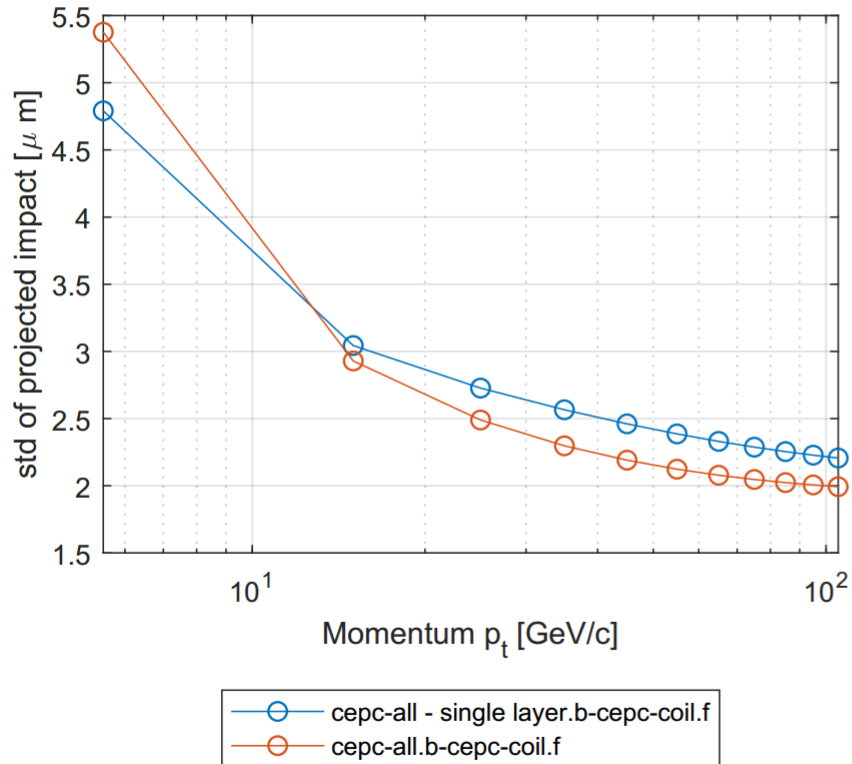
Compare detector setups
as function of –
momentum – polar angle

Output:
Impact parameter
resolution as a function
of pT with different
Theta/different R of
innermost layer

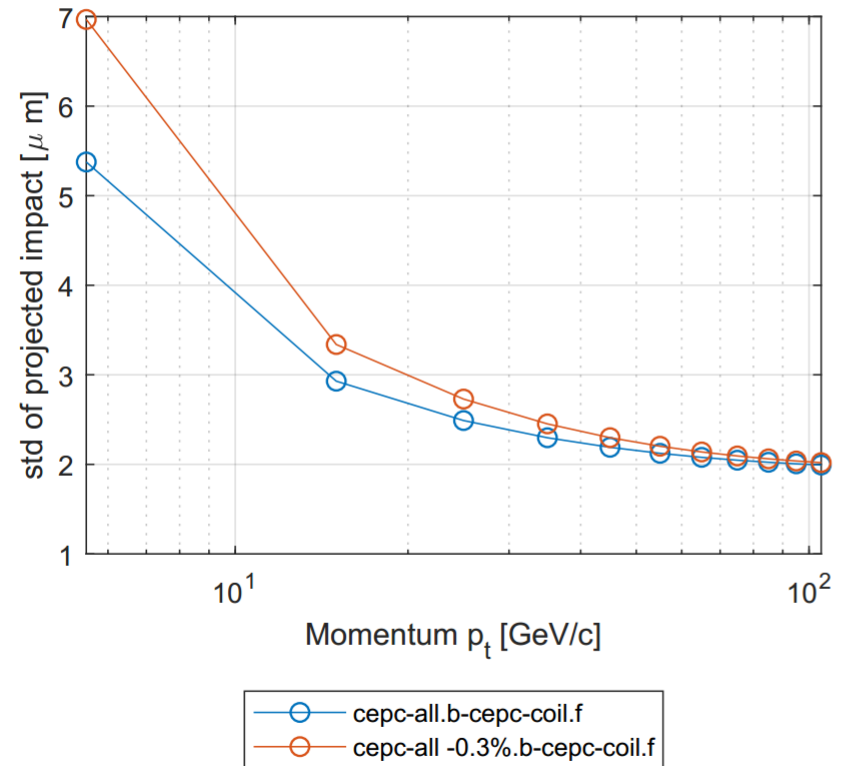


Comparison of different geometries

Double layers vs Single layers



material budget $0.15\% X_0$ vs $0.3\% X_0$



Optimization

— — Next Step

- LDT:
 - Test more detector geometry parameters
 - Communicate with mechanic engineer for their requests
- Full simulation used to validate the fast results
- TkLayout as alternative way also for cross check, but some technical problems ...