### **CEPCSW Prototype and Future Plan**

Zou Jiaheng

On behalf of the CEPCSW working group

#### 2019.11.18

## Introduction of CEPC Software

- CEPC software originally started from the iLCSoft (many thanks)
  - LCIO, Marlin, tracking and flavor-tagging
  - New components for CEPC: simulation, reconstruction...
  - Used for the CDR study, which is released in Nov, 2018
- A new framework for TDR is considered at the Oxford workshop, April 2019
  - to demonstrate the capabilities to meet future requirements
  - to support continuous integrations of new software components
- The common view at the Bolognia workshop, June 2019
  - A Common Software Stack (KEY4hep) for future collider experiments
    CEPC, CLIC, FCC, ILC, SCTF
  - Maximize the sharing of software components between experiments

### A typical HEP Software Stack

[Ref]: André Sailer, etc., CHEP2019

https://indico.cern.ch/event/773049/contributions/3474763/attachments/1938664/3213633/191105\_sailer\_key4hep.pdf

Applications usually rely on large number of libraries, where some depend on others



## The Goal of CEPCSW Prototype

- Based on KEY4hep (Common Software Stack for HEP)
- Reuse existing components
  - EDM4hep/PODIO, DD4hep, Gaudi, ROOT ...
- Implement the specific components for CEPC
- Provide a ready-to-work environment to algorithm developers and physicists
  - Migrate tracking algorithms from Marlin to CEPCSW
  - Integrate more algorithms and features
- Move from Marlin to the new software system

## Tasks of CEPCSW Prototype

Components	Tasks	Status
General	Software infrastructure Core modules	$\checkmark$
EDM & I/O	PLCIO data model and I/O LCIO compatible reader	$\checkmark$
Geometry and Simulation	DD4hep integration Simulation framework	$\checkmark$
	SiliconTracking	$\checkmark$
Reconstruction	More reconstruction algorithms	In progress
Build and release	Git, CMake, CVMFS	Ready

## Gaudi: the Underlying Framework

- The core part of the framework is small
- key components:
  - Application Manager
  - Services
  - Algorithms
  - Tools



- Data is separated from algorithms physicists can concentrate on the algorithms
- Originally developed for LHCb, also used by BESIII and DYB in China

### The Gaudi Framework

- Application manager: the job controller
  - Creation, configuration and management of services and algorithms
  - Algorithm scheduling during the event loop
  - Terminating the job properly
- User components
  - Algorithm: the concrete calculations to the event
  - Service: the common functions which can be invoked by users
  - Tool: subroutines belong to an algorithm
- High Performance Computing
  - Multithreading computing is supported since v29
  - Parallelized functional and reentrant algorithms
  - Transparent data management in memory

## PODIO: an Event-Data Model toolkit

#### [Ref]: F. Gaede, etc. , CHEP2019

https://indico.cern.ch/event/773049/contributions/3473254/attachments/1939721/3215730/gaede\_podio\_chep19.pdf

PODIO is originally developed in context of the FCC study

- user layer (API):
  - handles to EDM objects (e.g. Hit)
  - collections of EDM object handles (e.g. HitCollection).
- object layer
  - transient objects (e.g. HitObject) handling references to other objects and vector members
- POD layer
  - the actual POD data structures holding the persistent information (e.g. HitData)



direct access to POD also possible - if needed for performance reason

## EDM4hep

The EDM4hep project is being constructed in the context of CSS

- Based on LCIO and FCC-edm
- Provide a common event data model
  - Common core classes described in a yaml file
  - C++ Code is generated by PODIO
  - The persistency layer (ROOT, HDF5, ...) can be changed easily
  - Each experiment can implement their own extensions
- A project followed by HEP Software Foundation
  - Regular meeting in every 2 weeks (CERN, DESY, IHEP ... )
  - <u>https://github.com/HSF/EDM4hep</u>
- But, it is not ready yet : (

## Current EDM in CEPCSW Prototype

- CEPCSW will use PLCIO before EDM4hep is ready
- PLCIO is an implementation of the LCIO event data model in PODIO



- EDM4hep
  - The migration from PLCIO to EDM4hep should be easy
- CEPC is the first user of PLCIO
  - Missing classes, potential problems ...

### FWCore

#### FCCSW FWCore

- DataWrapper: PLCIO data collection -> DataObject in Gaudi
- DataHandle: user interface to register/retrieve data to/from Gaudi TES (Transient Event Store)
- PODIO data service: read/write PODIO data objects

#### CEPCSW FWCore

- Mainly taken from FCCSW FWCore (many thanks)
- Extension to read LCIO data generated by Marlin

### Read the Existing LCIO Data

- LCIODataSvc
  - Read LCIO files via the LCIO library
  - Convert LCIO data objects to PLCIO data objects
  - Register PLCIO data objects to Gaudi Event Data Store



- Current Status
  - Data converters for reconstructed data types
  - Some of the data relations are not fully recovered (there are some limits to data analysis now)

### **Detector Description and Simulation**

Unified Geometry Service

Interfaced to DD4HEP

\*



Reconstruction

Simulation

## **Reconstruction:** SiliconTracking

As a first step, the SiliconTracking algorithm is migrated from Marlin to CEPCSW The results are intelligible same as Marlin's. See Chengdong's report later



## Software Infrastructure and Building

- Common tools
  - CMake: Build & deployment
    - Gaudi cmake macros
  - Git: version control
    - <u>http://cepcgit.ihep.ac.cn/cepc-prototype</u>
  - CVMFS: software distribution
    CEPC specific: /cvmfs/cepcsw.ihep.ac.cn/prototype
- Software building
  - Based on FCCSW & LCG software stack now (many thanks)
  - Move to KEY4hep in the in the future



## A Preliminary Testing

- A digitization algorithm migrated from Marlin
- Geometry: GearSvc migrated from Marlin
- Data and I/O
  - Read .slcio (LCIO) format files with LCIODataSvc
  - Write .podio (PLCIO) format files with PodioDataSvc

Compare the results with Marlin

### **Physics Results**

#### The results of CEPCSW and Marlin are exactly the same

Attaching file PlanarDigi\_marlin.root (TFile \*) 0x7fc1ef93ea70 root [1] planarDigi->Show(13000) =====> EVENT:13000 side = 0laver = 3 module = 8 = 0 sensor theta\_xcar = 1.5708phi\_xcar

theta\_ycar

phi\_ycar

edep

= 1.428

= 8.65927e - 17

= 4.89194e - 05

= -2.49899



A	ttaching file P	Lar	narDigi_gaudi.root		
(	TFile *) 0x7f9b3	390	1043d0		
r	oot [1] planarD	igi	L—>Show <b>(</b> 13000)		
=====> EVENT:13000					
	side	=	0		
	layer	=	3		
	module	=	8		
	sensor	=	0		
	theta_xcar	=	1.5708		
	phi_xcar	=	1.428		
	theta_ycar	=	8.65927e-17		
	phi_ycar	=	-2.49899		
	edep	=	4.89194e-05		







### **Future Plans**

- Software migration from Marlin to CEPCSW
  - Existing algorithms (reconstruction)
  - Geometry management: GEAR -> DD4hep
  - Recover the relations between PLCIO data object
  - Common services, such as database accessing
- Parallel Computing
  - Use the latest version of Gaudi
  - Writing functional and reentrant algorithms
  - EDM & I/O performance analysis and optimization
- Integration with Deep Learning algorithms
- Package management with SPACK, fewer external libs

### Summary

- CEPCSW prototype has been developed using Gaudi, DD4hep, Geant4 and PLCIO, etc.
- In the prototype
  - Both detector simulation and tracking algs can be run successfully
  - By implementing data conversion, previously produced MC data can be reused
- It is ready to add more algorithms to the prototype by following given examples
- Future development will be based on KEY4hep collaborating with CERN

# Thank You! 谢谢